

Package ‘rgl’

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rgl-package	<i>3D visualization device system</i>
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Description

3D real-time rendering system.

Usage

```
# Low level rgl.* interface
rgl.open()      # open new device
rgl.close()     # close current device
rgl.cur()       # returns active device ID
rgl.set(which, silent=FALSE) # set device as active
rgl.quit()      # shutdown rgl device system
rgl.init(initValue=0) # re-initialize rgl
```

Arguments

<code>which</code>	device ID
<code>silent</code>	whether to suppress update of window titles
<code>initValue</code>	value for internal use only

Details

RGL is a 3D real-time rendering device driver system for R. Multiple devices are managed at a time, where one has the current focus that receives instructions from the R command-line. The device design is oriented towards the R device metaphor. If you send scene management instructions, and there's no device open, it will be opened automatically. Opened devices automatically get the current device focus. The focus may be changed by using `rgl.set()`. `rgl.quit()` shuts down the rgl subsystem and all open devices, detaches the package including the shared library and additional system libraries.

If `rgl.open()` fails (e.g. because X windows is not running, or its `DISPLAY` variable is not set properly), then you can retry the initialization by calling `rgl.init()`. Do not do this when windows have already been successfully opened: they will be orphaned, with no way to remove them other than closing R. In fact, it's probably a good idea not to do this at all: quitting R and restarting it is a better solution.

This package also includes a higher level interface which is described in the [r3d](#) help topic. That interface is designed to act more like classic 2D R graphics. We recommend that you avoid mixing `rgl.*` and `*3d` calls.

See the first example below to display the ChangeLog.

See Also

[r3d](#), [rgl.clear](#), [rgl.pop](#), [rgl.viewpoint](#), [rgl.light](#), [rgl.bg](#), [rgl.bbox](#), [rgl.points](#), [rgl.lines](#), [rgl.triangles](#), [rgl.quads](#), [rgl.texts](#), [rgl.surface](#), [rgl.spheres](#), [rgl.sprites](#), [rgl.snapshot](#)

Examples

```
file.show(system.file("NEWS", package="rgl"))
example(surface3d)
example(plot3d)
```

addNormals

Add normal vectors to objects so they render more smoothly.

Description

This generic function adds normals at each of the vertices of a polyhedron by averaging the normals of each incident face. This has the effect of making the surface of the object appear smooth rather than faceted when rendered.

Usage

```
addNormals(x, ...)
```

Arguments

`x` An object to which to add normals.

`...` Additional parameters which will be passed to the methods. Currently unused.

Details

Currently methods are supplied for `"mesh3d"` and `"shapelist3d"` classes.

Value

A new object of the same class as `x`, with normals added.

Author(s)

Duncan Murdoch

Examples

```
open3d()
y <- subdivision3d(tetrahedron3d(col="red"), depth=3)
shade3d(y) # No normals
y <- addNormals(y)
shade3d(translate3d(y, x=1, y=0, z=0)) # With normals
```

aspect3d

Set the aspect ratios of the current plot

Description

This function sets the apparent ratios of the x, y, and z axes of the current bounding box.

Usage

```
aspect3d(x, y = NULL, z = NULL)
```

Arguments

`x` The ratio for the x axis, or all three ratios, or `"iso"`

`y` The ratio for the y axis

`z` The ratio for the z axis

Details

If the ratios are all 1, the bounding box will be displayed as a cube approximately filling the display. Values may be set larger or smaller as desired. Aspect "iso" signifies that the coordinates should all be displayed at the same scale, i.e. the bounding box should not be rescaled. (This corresponds to the default display before `aspect3d` has been called.) Partial matches to "iso" are allowed.

`aspect3d` works by modifying `par3d("scale")`.

Value

The previous value of the scale is returned invisibly.

Author(s)

Duncan Murdoch

See Also

[plot3d](#), [par3d](#)

Examples

```
x <- rnorm(100)
y <- rnorm(100)*2
z <- rnorm(100)*3

open3d()
plot3d(x, y, z)
aspect3d(1,1,0.5)
open3d()
plot3d(x, y, z)
aspect3d("iso")
```

axes3d

Draw boxes, axes and other text outside the data

Description

These functions draw axes, boxes and text outside the range of the data. `axes3d`, `box3d` and `title3d` are the higher level functions; normally the others need not be called directly by users.

Usage

```
axes3d(edges = "bbox", labels = TRUE, tick = TRUE, nticks = 5, ...)
box3d(...)
title3d(main = NULL, sub = NULL, xlab = NULL, ylab = NULL,
        zlab = NULL, line = NA, ...)
axis3d(edge, at = NULL, labels = TRUE, tick = TRUE, line = 0,
        pos = NULL, nticks = 5, ...)
mtext3d(text, edge, line = 0, at = NULL, pos = NA, ...)
```

Arguments

<code>edges</code>	a code to describe which edge(s) of the box to use; see Details below
<code>labels</code>	whether to label the axes, or (for <code>axis3d</code>) the labels to use
<code>tick</code>	whether to use tick marks
<code>nticks</code>	suggested number of ticks
<code>main</code>	the main title for the plot
<code>sub</code>	the subtitle for the plot
<code>xlab, ylab, zlab</code>	the axis labels for the plot
<code>line</code>	the “line” of the plot margin to draw the label on
<code>edge, pos</code>	the position at which to draw the axis or text
<code>text</code>	the text to draw
<code>at</code>	the value of a coordinate at which to draw the axis
<code>...</code>	additional parameters which are passed to <code>bbox3d</code> or <code>material3d</code>

Details

The rectangular prism holding the 3D plot has 12 edges. They are identified using 3 character strings. The first character ('x', 'y', or 'z') selects the direction of the axis. The next two characters are each '-' or '+', selecting the lower or upper end of one of the other coordinates. If only one or two characters are given, the remaining characters default to '-'. For example `edge = 'x+'` draws an x-axis at the high level of y and the low level of z.

By default, `axes3d` uses the `bbox3d` function to draw the axes. The labels will move so that they do not obscure the data. Alternatively, a vector of arguments as described above may be used, in which case fixed axes are drawn using `axis3d`.

If `pos` is a numeric vector of length 3, `edge` determines the direction of the axis and the tick marks, and the values of the other two coordinates in `pos` determine the position. See the examples.

Value

These functions are called for their side effects. They return the object IDs of objects added to the scene.

Author(s)

Duncan Murdoch

See Also

[axis](#), [box](#), [title](#), [mtext](#), [bbox3d](#)

Examples

```

open3d()
points3d(rnorm(10),rnorm(10),rnorm(10))

# First add standard axes
axes3d()

# and one in the middle (the NA will be ignored, a number would
# do as well)
axis3d('x',pos=c(NA, 0, 0))

# add titles
title3d('main','sub','xlab','ylab','zlab')

rgl.bringtotop()

open3d()
points3d(rnorm(10),rnorm(10),rnorm(10))

# Use fixed axes
axes3d(c('x','y','z'))

# Put 4 x-axes on the plot
axes3d(c('x--','x-+','x+-','x++'))

axis3d('x',pos=c(NA, 0, 0))
title3d('main','sub','xlab','ylab','zlab')

```

 bg

Set up Background

Description

Setup the background environment of the scene.

Usage

```

bg3d(...)
rgl.bg( sphere = FALSE, fogtype = "none", color=c("black","white"),
        back="lines", ...)

```

Arguments

fogtype	fog type: "none" no fog "linear" linear fog function
---------	--

	"exp" exponential fog function
	"exp2" squared exponential fog function
sphere	logical, if true, an environmental sphere geometry is used for the background decoration.
color	Primary color is used for background clearing and as fog color. Secondary color is used for background sphere geometry. See rgl.material for details.
back	Specifies the fill style of the sphere geometry. See rgl.material for details.
...	Material properties. See rgl.material for details.

Details

If sphere is set to TRUE, an environmental sphere enclosing the whole scene is drawn.

See Also

[rgl.material](#)

Examples

```
rgl.open()

# a simple white background

bg3d("white")

# the holo-globe (inspired by star trek):

rgl.bg(sphere=TRUE, color=c("black","green"), lit=FALSE, back="lines" )

# an environmental sphere with a nice texture.

rgl.bg(sphere=TRUE, texture=system.file("textures/sunsleep.png", package="rgl"),
      back="filled" )
```

cylinder3d

Create cylindrical or "tube" plots.

Description

This function converts a description of a space curve into a ["mesh3d"](#) object forming a cylindrical tube around the curve.

Usage

```
cylinder3d(center, radius = 1, twist = 0, e1 = NULL, e2 = NULL, e3 = NULL,
           sides = 8, closed = 0, debug = FALSE)
```


Arguments

<code>center</code>	An n by 3 matrix whose columns are the x , y and z coordinates of the space curve.
<code>radius</code>	The radius of the cross-section of the tube at each point in the center.
<code>twist</code>	The amount by which the polygon forming the tube is twisted at each point.
<code>e1</code> , <code>e2</code> , <code>e3</code>	The Frenet coordinates to use at each point on the space curve.
<code>sides</code>	The number of sides in the polygon cross section.
<code>closed</code>	Whether to treat the first and last points of the space curve as identical, and close the curve. If <code>closed > 0</code> , it represents the number of points of overlap in the coordinates.
<code>debug</code>	If TRUE, display the local Frenet coordinates at each point.

Details

The number of points in the space curve is determined by the vector lengths in `center`, after using `xyz.coords` to convert it to a list. The other arguments `radius`, `twist`, `e1`, `e2`, and `e3` are extended to the same length.

The three optional arguments `e1`, `e2`, and `e3` determine the local coordinate system used to create the vertices at each point in `center`. If missing, they are computed by simple numerical approximations. `e1` should be the tangent coordinate, giving the direction of the curve at the point. The cross-section of the polygon will be orthogonal to `e1`. `e2` defaults to an approximation to the normal or curvature vector; it is used as the image of the y axis of the polygon cross-section. `e3` defaults to an approximation to the binormal vector, to which the x axis of the polygon maps. The vectors are orthogonalized and normalized at each point.

Value

A "mesh3d" object holding the cylinder.

Author(s)

Duncan Murdoch

Examples

```
# A trefoil knot
open3d()
theta <- seq(0, 2*pi, len=25)
knot <- cylinder3d(cbind(sin(theta)+2*sin(2*theta), 2*sin(3*theta), cos(theta)-2*cos(2*theta)),
                  e1=cbind(cos(theta)+4*cos(2*theta), 6*cos(3*theta), sin(theta)+4*sin(2*theta)),
                  radius=0.8, closed=TRUE)

shade3d(addNormals(subdivision3d(knot, depth=2)), col="green")
```

ellipse3d

*Make an ellipsoid***Description**

A generic function and several methods returning an ellipsoid or other outline of a confidence region for three parameters.

Usage

```
ellipse3d(x, ...)
## Default S3 method:
ellipse3d(x, scale = c(1, 1, 1), centre = c(0, 0, 0), level = 0.95,
          t = sqrt(qchisq(level, 3)), which = 1:3, subdivide = 3, smooth = TRUE,
## S3 method for class 'lm':
ellipse3d(x, which = 1:3, level = 0.95, t = sqrt(3 * qf(level,
                                                    3, x$df.residual)), ...)

## S3 method for class 'glm':
ellipse3d(x, which = 1:3, level = 0.95, t, dispersion, ...)
## S3 method for class 'nls':
ellipse3d(x, which = 1:3, level = 0.95, t = sqrt(3 * qf(level,
                                                    3, s$df[2])), ...)
```

Arguments

<code>x</code>	An object. In the default method the parameter <code>x</code> should be a square positive definite matrix at least 3x3 in size. It will be treated as the correlation or covariance of a multivariate normal distribution.
<code>...</code>	Additional parameters to pass to the default method or to qmesh3d .
<code>scale</code>	If <code>x</code> is a correlation matrix, then the standard deviations of each parameter can be given in the scale parameter. This defaults to <code>c(1, 1, 1)</code> , so no rescaling will be done.
<code>centre</code>	The centre of the ellipse will be at this position.
<code>level</code>	The confidence level of a simultaneous confidence region. The default is 0.95, for a 95% region. This is used to control the size of the ellipsoid.
<code>t</code>	The size of the ellipse may also be controlled by specifying the value of a t-statistic on its boundary. This defaults to the appropriate value for the confidence region.
<code>which</code>	This parameter selects which variables from the object will be plotted. The default is the first 3.
<code>subdivide</code>	This controls the number of subdivisions (see subdivision3d) used in constructing the ellipsoid. Higher numbers give a smoother shape.
<code>smooth</code>	If <code>TRUE</code> , smooth interpolation of normals is used; if <code>FALSE</code> , a faceted ellipsoid will be displayed.
<code>dispersion</code>	The value of dispersion to use. If specified, it is treated as fixed, and chi-square limits for <code>t</code> are used. If missing, it is taken from <code>summary(x)</code> .

Value

A `mesh3d` object representing the ellipsoid.

Examples

```
# Plot a random sample and an ellipsoid of concentration corresponding to a 95%
# probability region for a
# trivariate normal distribution with mean 0, unit variances and
# correlation 0.8.
if (require(MASS)) {
  Sigma <- matrix(c(10,3,0,3,2,0,0,0,1), 3,3)
  Mean <- 1:3
  x <- mvrnorm(1000, Mean, Sigma)

  open3d()

  plot3d(x, box=FALSE)

  plot3d(ellipse3d(Sigma, centre=Mean), col="green", alpha=0.5, add = TRUE)
}

# Plot the estimate and joint 90% confidence region for the displacement and cylinder
# count linear coefficients in the mtcars dataset

data(mtcars)
fit <- lm(mpg ~ disp + cyl , mtcars)

open3d()
plot3d(ellipse3d(fit, level = 0.90), col="blue", alpha=0.5, aspect=TRUE)
```

grid3d

Add a grid to a 3D plot

Description

This function adds a reference grid to an RGL plot.

Usage

```
grid3d(side, at = NULL, col = "gray", lwd = 1, lty = 1, n = 5)
```

Arguments

<code>side</code>	Where to put the grid; see the Details section.
<code>at</code>	How to draw the grid; see the Details section.
<code>col</code>	The color of the grid lines.
<code>lwd</code>	The line width of the grid lines.
<code>lty</code>	The line type of the grid lines.
<code>n</code>	Suggested number of grid lines; see the Details section.

Details

This function is similar to `grid` in classic graphics, except that it draws a 3D grid in the plot.

The grid is drawn in a plane perpendicular to the coordinate axes. The first letter of the `side` argument specifies the direction of the plane: "x", "y" or "z" (or uppercase versions) to specify the coordinate which is constant on the plane.

If `at = NULL` (the default), the grid is drawn at the limit of the box around the data. If the second letter of the `side` argument is "-" or is not present, it is the lower limit; if "+" then at the upper limit. The grid lines are drawn at values chosen by `pretty` with `n` suggested locations. The default locations should match those chosen by `axis3d` with `nticks = n`.

If `at` is a numeric vector, the grid lines are drawn at those values.

If `at` is a list, then the "x" component is used to specify the x location, the "y" component specifies the y location, and the "z" component specifies the z location. Missing components are handled using the default as for `at = NULL`.

Multiple grids may be drawn by specifying multiple values for `side` or for the component of `at` that specifies the grid location.

Value

A vector or matrix of object ids is returned invisibly.

Author(s)

Ben Bolker and Duncan Murdoch

See Also

`axis3d`

Examples

```
x <- 1:10
y <- 1:10
z <- matrix(outer(x-5,y-5) + rnorm(100), 10, 10)
open3d()
persp3d(x, y, z, col="red", alpha=0.7, aspect=c(1,1,0.5))
grid3d(c("x", "y+", "z"))
```

light

add light source

Description

add a light source to the scene.

Usage

```
light3d(theta = 0, phi = 15, ...)
rgl.light( theta = 0, phi = 0, viewpoint.rel = TRUE, ambient = "#FFFFFF",
          diffuse = "#FFFFFF", specular = "#FFFFFF")
```

Arguments

theta, phi	polar coordinates
viewpoint.rel	logical, if TRUE light is a viewpoint light that is positioned relative to the current viewpoint
ambient, diffuse, specular	light color values used for lighting calculation
...	generic arguments passed through to RGL-specific (or other) functions

Details

Up to 8 light sources are supported. They are positioned either in world space or relative to the camera using polar coordinates. Light sources are directional.

Value

This function is called for the side effect of adding a light. A light ID is returned to allow `rgl.pop` to remove it.

See Also

`rgl.clear` `rgl.pop`

matrices

Work with homogeneous coordinates

Description

These functions construct 4x4 matrices for transformations in the homogeneous coordinate system used by OpenGL, and translate vectors between homogeneous and Euclidean coordinates.

Usage

```
identityMatrix()
scaleMatrix(x, y, z)
translationMatrix(x, y, z)
rotationMatrix(angle, x, y, z, matrix)
asHomogeneous(x)
asEuclidean(x)

scale3d(obj, x, y, z, ...)
```

```

translate3d(obj, x, y, z, ...)
rotate3d(obj, angle, x, y, z, matrix, ...)

transform3d(obj, matrix, ...)

```

Arguments

<code>x, y, z, angle, matrix</code>	See details
<code>obj</code>	An object to be transformed
<code>...</code>	Additional parameters to be passed to methods

Details

OpenGL uses homogeneous coordinates to handle perspective and affine transformations. The homogeneous point (x, y, z, w) corresponds to the Euclidean point $(x/w, y/w, z/w)$. The matrices produced by the functions `scaleMatrix`, `translationMatrix`, and `rotationMatrix` are to be left-multiplied by a row vector of homogeneous coordinates; alternatively, the transpose of the result can be right-multiplied by a column vector. The generic functions `scale3d`, `translate3d` and `rotate3d` apply these transformations to the `obj` argument. The `transform3d` function is a synonym for `rotate3d(obj, matrix=matrix)`.

By default, it is assumed that `obj` is a row vector (or a matrix of row vectors) which will be multiplied on the right by the corresponding matrix, but users may write methods for these generics which operate differently. Methods are supplied for `mesh3d` objects.

To compose transformations, use matrix multiplication. The effect is to apply the matrix on the left first, followed by the one on the right.

`identityMatrix` returns an identity matrix.

`scaleMatrix` scales each coordinate by the given factor. In Euclidean coordinates, (u, v, w) is transformed to $(x*u, y*v, z*w)$.

`translationMatrix` translates each coordinate by the given translation, i.e. (u, v, w) is transformed to $(u+x, v+y, w+z)$.

`rotationMatrix` can be called in three ways. With arguments `angle, x, y, z` it represents a rotation of `angle` radians about the axis `x, y, z`. If `matrix` is a 3x3 rotation matrix, it will be converted into the corresponding matrix in 4x4 homogeneous coordinates. Finally, if a 4x4 matrix is given, it will be returned unchanged. (The latter behaviour is used to allow `transform3d` to act like a generic function, even though it is not.)

Use `asHomogeneous(x)` to convert the Euclidean vector `x` to homogeneous coordinates, and `asEuclidean(x)` for the reverse transformation.

Value

`identityMatrix`, `scaleMatrix`, `translationMatrix`, and `rotationMatrix` produce a 4x4 matrix representing the requested transformation in homogeneous coordinates.

`scale3d`, `translate3d` and `rotate3d` transform the object and produce a new object of the same class.

Author(s)

Duncan Murdoch

See Also[par3d](#) for a description of how rgl uses matrices in rendering.**Examples**

```
# A 90 degree rotation about the x axis:

rotationMatrix(pi/2, 1, 0, 0)

# Find what happens when you rotate (2,0,0) by 45 degrees about the y axis:

x <- asHomogeneous(c(2,0,0))
y <- x
asEuclidean(y)

# or more simply...

rotate3d(c(2,0,0), pi/4, 0, 1, 0)
```

 mesh3d

3D Mesh objects

Description

3D triangle and quadrangle mesh object creation and a collection of sample objects.

Usage

```
qmesh3d(vertices, indices, homogeneous = TRUE, material = NULL, normals = NULL)
tmesh3d(vertices, indices, homogeneous = TRUE, material = NULL, normals = NULL)

cube3d(trans = identityMatrix(), ...)
tetrahedron3d(trans = identityMatrix(), ...)
octahedron3d(trans = identityMatrix(), ...)
icosahedron3d(trans = identityMatrix(), ...)
dodecahedron3d(trans = identityMatrix(), ...)
cuboctahedron3d(trans = identityMatrix(), ...)

oh3d(trans = identityMatrix(), ...)    # an 'o' object

dot3d(x, ...)    # draw dots at the vertices of an object
## S3 method for class 'mesh3d':
dot3d(x, override = TRUE, ...)
```

```
wire3d(x, ...) # draw a wireframe object
## S3 method for class 'mesh3d':
wire3d(x, override = TRUE, ...)
shade3d(x, ...) # draw a shaded object
## S3 method for class 'mesh3d':
shade3d(x, override = TRUE, ...)
```

Arguments

<code>x</code>	a mesh3d object (class <code>qmesh3d</code> or <code>tmesh3d</code>)
<code>vertices</code>	3- or 4-component vector of coordinates
<code>indices</code>	4-component vector of vertex indices
<code>homogeneous</code>	logical indicating if homogeneous (four component) coordinates are used.
<code>material</code>	material properties for later rendering
<code>normals</code>	normals at each vertex
<code>trans</code>	transformation to apply to objects; see below for defaults
<code>...</code>	additional rendering parameters
<code>override</code>	should the parameters specified here override those stored in the object?

Details

These functions create and work with `mesh3d` objects, which consist of a matrix of vertex coordinates together with a matrix of indices indicating which vertex is part of which face. Such objects may have triangular faces, planar quadrilateral faces, or both.

The sample objects optionally take a matrix transformation `trans` as an argument. This transformation is applied to all vertices of the default shape. The default is an identity transformation.

The `"shape3d"` class is a general class for shapes that can be plotted by `dot3d`, `wire3d` or `shade3d`.

The `"mesh3d"` class is a class of objects that form meshes: the vertices are in member `vb`, as a 3 or 4 by `n` matrix. Meshes with triangular faces will contain `it`, a $3 \times n$ matrix giving the indices of the vertices in each face. Quad meshes will have vertex indices in `ib`, a $4 \times n$ matrix.

Value

`qmesh3d`, `cube3d`, `oh3d`, `tmesh3d`, `tetrahedron3d`, `octahedron3d`, `icosahedron3d` and `dodecahedron3d` return objects of class `c("mesh3d", "shape3d")`. The first three of these are quad meshes, the rest are triangle meshes.

`dot3d`, `wire3d`, and `shade3d` are called for their side effect of drawing an object into the scene; they return an object ID (or vector of IDs, for some classes) invisibly.

See Also

[r3d](#), [par3d](#), [shapelist3d](#) for multiple shapes

Examples

```
# generate a quad mesh object

vertices <- c(
  -1.0, -1.0, 0, 1.0,
   1.0, -1.0, 0, 1.0,
   1.0,  1.0, 0, 1.0,
  -1.0,  1.0, 0, 1.0
)
indices <- c( 1, 2, 3, 4 )

open3d()
wire3d( qmesh3d(vertices,indices) )

# render 4 meshes vertically in the current view

open3d()
bg3d("gray")
l0 <- oh3d(tran = par3d("userMatrix"), color = "green" )
shade3d( translate3d( l0, -6, 0, 0 ) )
l1 <- subdivision3d( l0 )
shade3d( translate3d( l1, -2, 0, 0 ), color="red", override = FALSE )
l2 <- subdivision3d( l1 )
shade3d( translate3d( l2,  2, 0, 0 ), color="red", override = TRUE )
l3 <- subdivision3d( l2 )
shade3d( translate3d( l3,  6, 0, 0 ), color="red" )

# render all of the Platonic solids
open3d()
shade3d( translate3d( tetrahedron3d(col="red"), 0, 0, 0) )
shade3d( translate3d( cube3d(col="green"), 3, 0, 0) )
shade3d( translate3d( octahedron3d(col="blue"), 6, 0, 0) )
shade3d( translate3d( dodecahedron3d(col="cyan"), 9, 0, 0) )
shade3d( translate3d( icosahedron3d(col="magenta"), 12, 0, 0) )
```

par3d

Set or Query RGL Parameters

Description

par3d can be used to set or query graphical parameters in rgl. Parameters can be set by specifying them as arguments to par3d in tag = value form, or by passing them as a list of tagged values.

Usage

```
par3d(..., no.readonly = FALSE)

open3d(..., params=get("r3dDefaults", envir=.GlobalEnv))
```

Arguments

<code>...</code>	arguments in <code>tag = value</code> form, or a list of tagged values. The tags must come from the graphical parameters described below.
<code>no.readonly</code>	logical; if <code>TRUE</code> and there are no other arguments, only those parameters which can be set by a subsequent <code>par3d()</code> call are returned.
<code>params</code>	a list of graphical parameters

Details

Parameters are queried by giving one or more character vectors to `par3d`.

`par3d()` (no arguments) or `par3d(no.readonly=TRUE)` is used to get *all* the graphical parameters (as a named list).

R.O. indicates *read-only arguments*: These may only be used in queries, i.e., they do *not* set anything.

`open3d` opens a new `rgl` device, and sets the parameters as requested. The `r3dDefaults` list will be used as default values for parameters. As installed this sets the point of view to 'world coordinates' (i.e. x running from left to right, y from front to back, z from bottom to top), the `mouseMode` to (`zAxis`, `zoom`, `fov`), and the field of view to 30 degrees. Users may create their own variable of that name in the global environment and it will override the installed one. If there is a `bg` element in the list or the arguments, it should be a list of arguments to pass to the `bg3d` function to set the background.

The arguments to `open3d` may include `material`, a list of material properties as in `r3dDefaults`, but note that high level functions such as `plot3d` normally use the `r3dDefaults` values in preference to this setting.

Value

When parameters are set, their former values are returned in an invisible named list. Such a list can be passed as an argument to `par3d` to restore the parameter values. Use `par3d(no.readonly = TRUE)` for the full list of parameters that can be restored.

When just one parameter is queried, its value is returned directly. When two or more parameters are queried, the result is a list of values, with the list names giving the parameters.

Note the inconsistency: setting one parameter returns a list, but querying one parameter returns an object.

Parameters

cex real. The default size for text.

family character. The default device independent family name; see `text3d`.

font integer. The default font number (from 1 to 5; see `text3d`).

useFreeType logical. Should FreeType fonts be used?

fontname *R.O.*; the system-dependent name of the current font.

FOV real. The field of view, from 1 to 179 degrees. This controls the degree of parallax in the perspective view. Isometric perspective (which would correspond to `FOV=0`) is not currently possible, but one can approximate it by specifying `par3d(FOV=1)`.

ignoreExtent logical. Set to TRUE so that subsequently plotted objects will be ignored in calculating the bounding box of the scene.

modelMatrix *R.O.*; a 4 by 4 matrix describing the position of the user data.

mouseMode character. A vector of 3 strings describing what the 3 mouse buttons do. Partial matching is used. Possible values for mouseMode are

"none" No action for this button.

"trackball" Mouse acts as a virtual trackball, rotating the scene.

"xAxis" Similar to "trackball", but restricted to X axis rotation.

"yAxis" Y axis rotation.

"zAxis" Z axis rotation.

"polar" Mouse rotates the scene by moving in polar coordinates.

"selecting" Mouse is used for selection. This is not normally set by the user, but is used internally by the `select3d` function.

"zoom" Mouse is used to zoom the display.

"fov" Mouse changes the field of view of the display.

projMatrix *R.O.*; a 4 by 4 matrix describing the current projection of the scene.

scale real. A vector of 3 values indicating the amount by which to rescale each axis before display. Set by `aspect3d`.

skipRedraw whether to update the display. Set to TRUE to suspend updating while making multiple changes to the scene. See `demo(hist3d)` for an example.

userMatrix a 4 by 4 matrix describing user actions to display the scene.

viewport *R.O.*; real. A vector giving the dimensions of the window in pixels.

zoom real. A positive value indicating the current magnification of the scene.

bbox *R.O.*; real. A vector of six values indicating the current values of the bounding box of the scene (xmin, xmax, ymin, ymax, zmin, zmax)

windowRect integer. A vector of four values indicating the left, top, right and bottom of the displayed window (in pixels).

note

The "xAxis", "yAxis" and "zAxis" mouse modes rotate relative to the coordinate system of the data, regardless of the current orientation of the scene.

Rendering

The parameters returned by `par3d` are sufficient to determine where `rgl` would render a point on the screen. Given a column vector (x, y, z) , it performs the equivalent of the following operations:

1. It converts the point to homogeneous coordinates by appending $w=1$, giving the vector $v = (x, y, z, 1)$.
2. It calculates the $M = \text{par3d}(\text{"modelMatrix"})$ as a product from right to left of the following matrices:
 - A matrix to translate the centre of the bounding box to the origin.
 - A matrix to rescale according to `par3d("scale")`.

- The `par3d("userMatrix")` as set by the user.
 - A matrix which may be set by mouse movements.
 - A matrix to translate the origin to the centre of the viewing region.
3. It multiplies the point by `M` giving `u = M %*% v`. Using this location and information on the normals (which have been similarly transformed), it performs lighting calculations.
 4. It obtains the projection matrix `P = par3d("projMatrix")` and multiplies the point by it giving `P %*% u = (x2, y2, z2, w2)`.
 5. It converts back to Euclidean coordinates by dividing the first 3 coordinates by `w2`.
 6. The new value `z2/w2` represents the depth into the scene of the point. Depending on what has already been plotted, this depth might be obscured, in which case nothing more is plotted.
 7. If the point is not culled due to depth, the `x2` and `y2` values are used to determine the point in the image. The `par3d("viewport")` values are used to translate from the range `(-1, 1)` to pixel locations, and the point is plotted.

See [?matrices](#) for more information on homogeneous and Euclidean coordinates.

References

OpenGL Architecture Review Board (1997). OpenGL Programming Guide. Addison-Wesley.

See Also

[rgl.viewpoint](#) to set FOV and zoom.

Examples

```
r3dDefaults
open3d()
shade3d(cube3d(color=rep(rainbow(6),rep(4,6))))
save <- par3d(userMatrix = rotationMatrix(90*pi/180, 1,0,0))
save
par3d("userMatrix")
par3d(save)
par3d("userMatrix")
```

par3dinterp

Interpolator for par3d parameters

Description

Returns a function which interpolates `par3d` parameter values, suitable for use in animations.

Usage

```
par3dinterp(times = NULL, userMatrix, scale, zoom, FOV,
            method = c("spline", "linear"),
            extrapolate = c("oscillate", "cycle", "constant", "natural"))
```

Arguments

<code>times</code>	Times at which values are recorded or a list; see below
<code>userMatrix</code>	Values of <code>par3d("userMatrix")</code>
<code>scale</code>	Values of <code>par3d("scale")</code>
<code>zoom</code>	Values of <code>par3d("zoom")</code>
<code>FOV</code>	Values of <code>par3d("FOV")</code>
<code>method</code>	Method of interpolation
<code>extrapolate</code>	How to extrapolate outside the time range

Details

This function is intended to be used in constructing animations. It produces a function that returns a list suitable to pass to `par3d`, to set the viewpoint at a given point in time.

All of the parameters are optional. Only those `par3d` parameters that are specified will be returned.

The input values other than `times` may each be specified as lists, giving the parameter value settings at a fixed time, or as matrices or arrays. If not lists, the following formats should be used: `userMatrix` can be a $4 \times 4 \times n$ array, or a $4 \times 4n$ matrix; `scale` should be an $n \times 3$ matrix; `zoom` and `FOV` should be length n vectors.

An alternative form of input is to put all of the above arguments into a list (i.e. a list of lists, or a list of arrays/matrices/vectors), and pass it as the first argument. This is the most convenient way to use this function with the `tkrgl` function `par3dsave`.

Interpolation is by cubic spline or linear interpolation in an appropriate coordinate-wise fashion. Extrapolation may oscillate (repeat the sequence forward, backward, forward, etc.), cycle (repeat it forward), be constant (no repetition outside the specified time range), or be natural (linear on an appropriate scale). In the case of cycling, the first and last specified values should be equal, or the last one will be dropped. Natural extrapolation is only supported with spline interpolation.

Value

A function is returned. The function takes one argument, and returns a list of `par3d` settings interpolated to that time.

Note

Due to a bug in R (fixed in R 2.6.0), using `extrapolate` equal to "oscillate" will sometimes fail when only two points are given.

Author(s)

Duncan Murdoch

See Also

`play3d` to play the animation.

Examples

```
f <- par3dinterp( zoom = c(1,2,3,1) )
f(0)
f(1)
f(0.5)
## Not run:
play3d(f)
## End(Not run)
```

persp3d

Surface plots

Description

This function draws plots of surfaces over the x-y plane. `persp3d` is a generic function.

Usage

```
persp3d(x, ...)
```

```
## Default S3 method:
```

```
persp3d(x = seq(0, 1, len = nrow(z)), y = seq(0, 1, len = ncol(z)), z,
        xlim = range(x, na.rm = TRUE), ylim = range(y, na.rm = TRUE), zlim = range(z, na.rm = TRUE),
        xlab = NULL, ylab = NULL, zlab = NULL, add = FALSE, aspect = !add, ...)
```

Arguments

<code>x, y</code>	locations of grid lines at which the values in <code>z</code> are measured. These may be given as vectors or matrices. If vectors, they must be in ascending order. Either one or both may matrices. If <code>x</code> is a <code>list</code> , its components <code>x\$x</code> and <code>x\$y</code> are used for <code>x</code> and <code>y</code> , respectively.
<code>z</code>	a matrix containing the values to be plotted. Note that <code>x</code> can be used instead of <code>z</code> for convenience.
<code>xlim, ylim, zlim</code>	x-, y- and z-limits. The plot is produced so that the rectangular volume defined by these limits is visible.
<code>xlab, ylab, zlab</code>	titles for the axes. N.B. These must be character strings; expressions are not accepted. Numbers will be coerced to character strings.
<code>add</code>	whether to add the points to an existing plot.
<code>aspect</code>	either a logical indicating whether to adjust the aspect ratio, or a new ratio
<code>...</code>	additional material parameters to be passed to surface3d and decorate3d .

Details

This is similar to `persp` with user interaction. See `plot3d` for more general details.

One difference from `persp` is that colors are specified on each vertex, rather than on each facet of the surface. To emulate the `persp` color handling, you need to do the following. First, convert the color vector to an $(nx-1)$ by $(ny-1)$ matrix; then add an extra row before row 1, and an extra column after the last column, to convert it to nx by ny . (These extra colors will not be used). For example, `col <- rbind(0, cbind(matrix(col, nx-1, ny-1), 0))`. Finally, call `persp3d` with material property `smooth = FALSE`.

If the `x` or `y` argument is a matrix, then it must be of the same dimension as `z`, and the values in the matrix will be used for the corresponding coordinates. This is used to plot shapes such as spheres or cylinders where `z` is not a function of `x` and `y`. See the fourth and fifth examples below.

Value

This function is called for the side effect of drawing the plot. A vector of shape IDs is returned.

Author(s)

Duncan Murdoch

See Also

`plot3d`, `persp`. The `curve3d` function in the `emdbook` package draws surface plots of functions.

Examples

```
# (1) The Obligatory Mathematical surface.
#       Rotated sinc function.

x <- seq(-10, 10, length= 30)
y <- x
f <- function(x,y) { r <- sqrt(x^2+y^2); 10 * sin(r)/r }
z <- outer(x, y, f)
z[is.na(z)] <- 1
open3d()
bg3d("white")
material3d(col="black")
persp3d(x, y, z, aspect=c(1, 1, 0.5), col = "lightblue",
        xlab = "X", ylab = "Y", zlab = "Sinc( r )")

# (2) Add to existing persp plot:

xE <- c(-10,10); xy <- expand.grid(xE, xE)
points3d(xy[,1], xy[,2], 6, col = "red")
lines3d(x, y=10, z= 6 + sin(x), col = "green")

phi <- seq(0, 2*pi, len = 201)
r1 <- 7.725 # radius of 2nd maximum
```

```

xr <- r1 * cos(phi)
yr <- r1 * sin(phi)
lines3d(xr,yr, f(xr,yr), col = "pink", lwd = 2)

# (3) Visualizing a simple DEM model

z <- 2 * volcano      # Exaggerate the relief
x <- 10 * (1:nrow(z)) # 10 meter spacing (S to N)
y <- 10 * (1:ncol(z)) # 10 meter spacing (E to W)

open3d()
bg3d("slategray")
material3d(col="black")
persp3d(x, y, z, col = "green3", aspect="iso",
        axes = FALSE, box = FALSE)

# (4) A cylindrical plot

z <- matrix(seq(0, 1, len=50), 50, 50)
theta <- t(z)
r <- 1 + exp( -pmin( (z - theta)^2, (z - theta - 1)^2, (z - theta + 1)^2 )/0.01 )
x <- r*cos(theta*2*pi)
y <- r*sin(theta*2*pi)

open3d()
persp3d(x, y, z, col="red")

# (5) A globe

lat <- matrix(seq(90,-90, len=50)*pi/180, 50, 50, byrow=TRUE)
long <- matrix(seq(-180, 180, len=50)*pi/180, 50, 50)

r <- 6378.1 # radius of Earth in km
x <- r*cos(lat)*cos(long)
y <- r*cos(lat)*sin(long)
z <- r*sin(lat)

open3d()
persp3d(x, y, z, col="white",
        texture=system.file("textures/worldsmall.png",package="rgl"),
        specular="black", axes=FALSE, box=FALSE, xlab="", ylab="", zlab="",
        normal_x=x, normal_y=y, normal_z=z)
play3d(spin3d(axis=c(0,0,1), rpm=8), duration=5)

## Not run:
# This looks much better, but is slow because the texture is very big
persp3d(x, y, z, col="white",
        texture=system.file("textures/world.png",package="rgl"),
        specular="black", axes=FALSE, box=FALSE, xlab="", ylab="", zlab="",
        normal_x=x, normal_y=y, normal_z=z)
## End(Not run)

```


play3d

*Play animation of rgl scene***Description**

play3d calls a function repeatedly, passing it the elapsed time in seconds, and using the result of the function to reset the viewpoint. movie3d does the same, but records each frame to a file to make a movie.

Usage

```
play3d(f, duration = Inf, dev = rgl.cur(), ...)
movie3d(f, duration, dev = rgl.cur(), ..., fps = 10,
        movie = "movie", frames = movie, dir = tempdir(),
        convert = TRUE, clean = TRUE, verbose=TRUE,
        top = TRUE, type = "gif")
```

Arguments

f	A function returning a list that may be passed to par3d
duration	The duration of the animation
dev	Which rgl device to select
...	Additional parameters to pass to f.
fps	Number of frames per second
movie	The base of the output filename, not including .gif
frames	The base of the name for each frame
dir	A directory in which to create temporary files for each frame of the movie
convert	Whether to try to convert the frames to a single GIF movie, or a command to do so
clean	If convert is TRUE, whether to delete the individual frames
verbose	Whether to report the convert command and the output filename
top	Whether to call rgl.bringtotop before each frame
type	What type of movie to create. See Details.

Details

The function f will be called in a loop with the first argument being the time in seconds since the start (where the start is measured after all arguments have been evaluated).

play3d is likely to place a high load on the CPU; if this is a problem, calls to [Sys.sleep](#) should be made within the function to release time to other processes.

movie3d saves each frame to disk in a filename of the form "framesXXX.png", where XXX is the frame number, starting from 0. If convert is TRUE, it uses ImageMagick to convert them to a

single file, by default an animated GIF. The `type` argument will be passed to ImageMagick to use as a file extension to choose the file type.

Alternatively, `convert` can be a template for a command to execute in the standard shell (wild-cards are allowed). The template is converted to a command using `sprintf(convert, fps, frames, movie, type, dir, duration)`. For example, `code=TRUE` uses the template `"convert -delay 1x%d %s*.png %s.%s"`. All work is done in the directory `dir`, so paths should not be needed in the command. (Note that `sprintf` does not require all arguments to be used, and supports formats that use them in an arbitrary order.)

The `top=TRUE` default is designed to work around an OpenGL limitation: in some implementations, `rgl.snapshot` will fail if the window is not topmost.

Value

This function is called for the side effect of its repeated calls to `f`. It returns `NULL` invisibly.

Author(s)

Duncan Murdoch, based on code by Michael Friendly

See Also

`spin3d` and `par3dinterp` return functions suitable to use as `f`. See `demo(flag)` for an example that modifies the scene in `f`.

Examples

```
open3d()
plot3d( cube3d(col="green") )
M <- par3d("userMatrix")
play3d( par3dinterp( userMatrix=list(M,
                                     rotate3d(M, pi/2, 1, 0, 0),
                                     rotate3d(M, pi/2, 0, 1, 0) ) ),
        duration=4 )
## Not run:
movie3d( spin3d(), duration=5 )
## End(Not run)
```

plot3d

3D Scatterplot

Description

Draws a 3D scatterplot.

Usage

```

plot3d(x, ...)
## Default S3 method:
plot3d(x, y, z,
       xlab, ylab, zlab, type = "p", col,
       size, lwd, radius,
       add = FALSE, aspect = !add, ...)
## S3 method for class 'mesh3d':
plot3d(x, xlab = "x", ylab = "y", zlab = "z", type = c("shade", "wire", "dots"),
       add = FALSE, ...)
decorate3d(xlim, ylim, zlim,
           xlab = "x", ylab = "y", zlab = "z",
           box = TRUE, axes = TRUE, main = NULL, sub = NULL,
           top = TRUE, aspect = FALSE, ...)

```

Arguments

<code>x, y, z</code>	vectors of points to be plotted. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>xlab, ylab, zlab</code>	labels for the coordinates.
<code>type</code>	For the default method, a single character indicating the type of item to plot. Supported types are: 'p' for points, 's' for spheres, 'l' for lines, 'h' for line segments from z=0, and 'n' for nothing. For the <code>mesh3d</code> method, one of 'shade', 'wire', or 'dots'. Partial matching is used.
<code>col</code>	the colour to be used for plotted items.
<code>size</code>	the size for plotted points.
<code>lwd</code>	the line width for plotted items.
<code>radius</code>	the radius of spheres: see Details below.
<code>add</code>	whether to add the points to an existing plot.
<code>aspect</code>	either a logical indicating whether to adjust the aspect ratio, or a new ratio.
<code>...</code>	additional parameters which will be passed to par3d , material3d or decorate3d .
<code>xlim, ylim, zlim</code>	limits to use for the coordinates.
<code>box, axes</code>	whether to draw a box and axes.
<code>main, sub</code>	main title and subtitle.
<code>top</code>	whether to bring the window to the top when done.

Details

`plot3d` is a partial 3D analogue of `plot.default`.

Note that since `rgl` does not currently support clipping, all points will be plotted, and `xlim`, `ylim`, and `zlim` will only be used to increase the respective ranges.

Missing values in the data are skipped, as in standard graphics.

If `aspect` is `TRUE`, aspect ratios of `c(1, 1, 1)` are passed to [aspect3d](#). If `FALSE`, no aspect adjustment is done. In other cases, the value is passed to [aspect3d](#).

With `type = "s"`, spheres are drawn centered at the specified locations. The radius may be controlled by `size` (specifying the size relative to the plot display, with the default `size=3` giving a radius about 1/20 of the plot region) or `radius` (specifying it on the data scale if an isometric aspect ratio is chosen, or on an average scale if not).

Value

`plot3d` is called for the side effect of drawing the plot; a vector of object IDs is returned.

`decorate3d` adds the usual decorations to a plot: labels, axes, etc.

Author(s)

Duncan Murdoch

See Also

[plot.default](#), [open3d](#), [par3d](#).

Examples

```
open3d()
x <- sort(rnorm(1000))
y <- rnorm(1000)
z <- rnorm(1000) + atan2(x,y)
plot3d(x, y, z, col=rainbow(1000))
```

points3d

add primitive set shape

Description

Adds a shape node to the current scene

Usage

```
points3d(x, y = NULL, z = NULL, ...)
lines3d(x, y = NULL, z = NULL, ...)
segments3d(x, y = NULL, z = NULL, ...)
triangles3d(x, y = NULL, z = NULL, ...)
quads3d(x, y = NULL, z = NULL, ...)
```

Arguments

<code>x, y, z</code>	coordinates. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>...</code>	Material properties (see rgl.material), normals and texture coordinates (see rgl.primitive).

Details

The functions `points3d`, `lines3d`, `segments3d`, `triangles3d` and `quads3d` add points, joined lines, line segments, filled triangles or quadrilaterals to the plots. They correspond to the OpenGL types `GL_POINTS`, `GL_LINE_STRIP`, `GL_LINES`, `GL_TRIANGLES` and `GL_QUADS` respectively.

Points are taken in pairs by `segments3d`, triplets as the vertices of the triangles, and quadruplets for the quadrilaterals. Colours are applied vertex by vertex; if different at each end of a line segment, or each vertex of a polygon, the colours are blended over the extent of the object. Quadrilaterals must be entirely in one plane and convex, or the results are undefined.

These functions call the lower level functions `rgl.points`, `rgl.linestrips`, and so on, and are provided for convenience.

The appearance of the new objects are defined by the material properties. See `rgl.material` for details.

The two principal differences between the `rgl.*` functions and the `*3d` functions are that the former set all unspecified material properties to defaults, whereas the latter use current values as defaults; the former make persistent changes to material properties with each call, whereas the latter make temporary changes only for the duration of the call.

Value

Each function returns the integer object ID of the shape that was added to the scene. These can be passed to `rgl.pop` to remove the object from the scene.

Author(s)

Ming Chen and Duncan Murdoch

Examples

```
# Show 12 random vertices in various ways.

M <- matrix(rnorm(36), 3, 12, dimnames=list(c('x','y','z'),
                                             rep(LETTERS[1:4], 3)))

# Force 4-tuples to be convex in planes so that quads3d works.

for (i in c(1,5,9)) {
  quad <- as.data.frame(M[,i+0:3])
  coeffs <- runif(2,0,3)
  if (mean(coeffs) < 1) coeffs <- coeffs + 1 - mean(coeffs)
  quad$C <- with(quad, coeffs[1]*(B-A) + coeffs[2]*(D-A) + A)
  M[,i+0:3] <- as.matrix(quad)
}

open3d()

# Rows of M are x, y, z coords; transpose to plot

M <- t(M)
```

```

shift <- matrix(c(-3,3,0), 12, 3, byrow=TRUE)

points3d(M)
lines3d(M + shift)
segments3d(M + 2*shift)
triangles3d(M + 3*shift, col='red')
quads3d(M + 4*shift, col='green')
text3d(M + 5*shift, texts=1:12)

# Add labels

shift <- outer(0:5, shift[1,])
shift[,1] <- shift[,1] + 3
text3d(shift,
        texts = c('points3d','lines3d','segments3d',
                  'triangles3d', 'quads3d','text3d'),
        adj = 0)
rgl.bringtotop()

```

r3d

Generic 3D interface

Description

Generic 3D interface for 3D rendering and computational geometry.

Details

R3d is a design for an interface for 3d rendering and computation without dependency on a specific rendering implementation. R3d includes a collection of 3D objects and geometry algorithms. All r3d interface functions are named `*3d`. They represent generic functions that delegate to implementation functions.

The interface can be grouped into 8 categories: Scene Management, Primitive Shapes, High-level Shapes, Geometry Objects, Visualization, Interaction, Transformation, Subdivision.

The rendering interface gives an abstraction to the underlying rendering model. It can be grouped into four categories:

Scene Management: A 3D scene consists of shapes, lights and background environment.

Primitive Shapes: Generic primitive 3D graphics shapes such as points, lines, triangles, quadrangles and texts.

High-level Shapes: Generic high-level 3D graphics shapes such as spheres, sprites and terrain.

Interaction: Generic interface to select points in 3D space using the pointer device.

In this package we include an implementation of r3d using the underlying `rgl.*` functions.

3D computation is supported through the use of object structures that live entirely in R.

Geometry Objects: Geometry and mesh objects allow to define high-level geometry for computational purpose such as triangle or quadrangle meshes (see [mesh3d](#)).

Transformation: Generic interface to transform 3d objects.

Visualization: Generic rendering of 3d objects such as dotted, wired or shaded.

Computation: Generic subdivision of 3d objects.

At present, there are two main practical differences between the `r3d` functions and the `rgl.*` functions is that the `r3d` functions call `open3d` if there is no device open, and the `rgl.*` functions call `rgl.open`. By default `open3d` sets the initial orientation of the coordinate system in 'world coordinates', i.e. a right-handed coordinate system in which the x-axis increases from left to right, the y-axis increases with depth into the scene, and the z-axis increases from bottom to top of the screen. `rgl.*` functions, on the other hand, use a right-handed coordinate system similar to that used in OpenGL. The x-axis matches that of `r3d`, but the y-axis increases from bottom to top, and the z-axis decreases with depth into the scene. Since the user can manipulate the scene, either system can be rotated into the other one.

The `r3d` functions also preserve the `rgl.material` setting across calls (except for texture elements, in the current implementation), whereas the `rgl.*` functions leave it as set by the last call.

The example code below illustrates the two coordinate systems.

See Also

`points3d` `lines3d` `segments3d` `triangles3d` `quads3d` `text3d` `spheres3d` `sprites3d`
`terrain3d` `select3d` `dot3d` `wire3d` `shade3d` `transform3d` `rotate3d` `subdivision3d`
`mesh3d` `cube3d` `rgl`

Examples

```
x <- c(0,1,0,0)
y <- c(0,0,1,0)
z <- c(0,0,0,1)
labels <- c("Origin", "X", "Y", "Z")
i <- c(1,2,1,3,1,4)

# rgl.* interface

rgl.open()
rgl.texts(x,y,z,labels)
rgl.texts(1,1,1,"rgl.* coordinates")
rgl.lines(x[i],y[i],z[i])

# *3d interface

open3d()
text3d(x,y,z,labels)
text3d(1,1,1,"*3d coordinates")
segments3d(x[i],y[i],z[i])
```

rgl.bbox

Set up Bounding Box decoration

Description

Set up the bounding box decoration.

Usage

```
rgl.bbox(
  xat=NULL, xlab=NULL, xunit=0, xlen=5,
  yat=NULL, ylab=NULL, yunit=0, ylen=5,
  zat=NULL, zlab=NULL, zunit=0, zlen=5,
  marklen=15.0, marklen.rel=TRUE, expand=1, ...)
bbox3d(xat, yat, zat, expand=1.03, nticks=5, ...)
```

Arguments

xat,yat,zat	vector specifying the tickmark positions
xlab,ylab,zlab	character vector specifying the tickmark labeling
xunit,yunit,zunit	value specifying the tick mark base for uniform tick mark layout
xlen,ylen,zlen	value specifying the number of tickmarks
marklen	value specifying the length of the tickmarks
marklen.rel	logical, if TRUE tick mark length is calculated using $1/\text{marklen} \times \text{axis length}$, otherwise tick mark length is <code>marklen</code> in coordinate space
expand	value specifying how much to expand the bounding box around the data
nticks	suggested number of ticks to use on axes
...	Material properties (or other <code>rgl.bbox</code> parameters in the case of <code>bbox3d</code>). See rgl.material for details.

Details

Three different types of tick mark layouts are possible. If `at` is not `NULL`, the ticks are set up at custom positions. If `unit` is not zero, it defines the tick mark base. If `length` is not zero, it specifies the number of ticks that are automatically specified. The first colour specifies the bounding box, while the second one specifies the tick mark and font colour.

`bbox3d` defaults to [pretty](#) locations for the axis labels and a slightly larger box, whereas `rgl.bbox` covers the exact range.

[axes3d](#) offers more flexibility in the specification of the axes, but they are static, unlike those drawn by [rgl.bbox](#) and [bbox3d](#).

Value

This function is called for the side effect of setting the bounding box decoration. A shape ID is returned to allow `rgl.pop` to delete it.

See Also

`rgl.material`, `axes3d`

Examples

```
rgl.open()
rgl.points(rnorm(100), rnorm(100), rnorm(100))
rgl.bbox(color=c("#333377", "white"), emission="#333377",
         specular="#3333FF", shininess=5, alpha=0.8 )

open3d()
points3d(rnorm(100), rnorm(100), rnorm(100))
bbox3d(color=c("#333377", "black"), emission="#333377",
       specular="#3333FF", shininess=5, alpha=0.8)
```

<code>rgl.bringtotop</code>	<i>Assign focus to an RGL window</i>
-----------------------------	--------------------------------------

Description

'`rgl.bringtotop`' brings the current RGL window to the front of the window stack (and gives it focus).

Usage

```
rgl.bringtotop(stay = FALSE)
```

Arguments

<code>stay</code>	whether to make the window stay on top.
-------------------	---

Details

If `stay` is `TRUE`, then the window will stay on top of normal windows.

Note

not completely implemented for X11 graphics (`stay` not implemented; window managers such as KDE may block this action (set "Focus stealing prevention level" to None in Control Center/Window Behavior/Advanced)). Not currently implemented under OS/X.

Author(s)

Ming Chen/Duncan Murdoch

Examples

```
rgl.open()
rgl.points(rnorm(1000), rnorm(1000), rnorm(1000), color=heat.colors(1000))
rgl.bringtotop(stay = TRUE)
```

rgl.material	<i>Generic Appearance setup</i>
--------------	---------------------------------

Description

Set material properties for geometry appearance.

Usage

```
rgl.material(
  color      = c("white"),
  alpha      = c(1.0),
  lit        = TRUE,
  ambient    = "black",
  specular   = "white",
  emission   = "black",
  shininess  = 50.0,
  smooth     = TRUE,
  texture    = NULL,
  textype    = "rgb",
  texmipmap  = FALSE,
  texminfilter = "linear",
  texmagfilter = "linear",
  texenvmap  = FALSE,
  front      = "fill",
  back       = "fill",
  size       = 3.0,
  lwd        = 1.0,
  fog        = TRUE,
  point_antialias = FALSE,
  line_antialias = FALSE,
  ...
)
```

material3d(...)

Arguments

color	vector of R color characters. Represents the diffuse component in case of lighting calculation (lit = TRUE), otherwise it describes the solid color characteristics.
lit	logical, specifying if lighting calculation should take place on geometry

ambient, specular, emission, shininess	properties for lighting calculation. ambient, specular, emission are R color character string values; shininess represents a numerical.
alpha	vector of alpha values between 0.0 (fully transparent) .. 1.0 (opaque).
smooth	logical, specifying whether Gouraud shading (smooth) or flat shading should be used.
texture	path to a texture image file. Supported formats: png.
texturetype	specifies what is defined with the pixmap "alpha" alpha values "luminance" luminance "luminance.alpha" luminance and alpha "rgb" color "rgba" color and alpha texture
texmipmap	Logical, specifies if the texture should be mipmapped.
texmagfilter	specifies the magnification filtering type (sorted by ascending quality): "nearest" texel nearest to the center of the pixel "linear" weighted linear average of a 2x2 array of texels
texminfilter	specifies the minification filtering type (sorted by ascending quality): "nearest" texel nearest to the center of the pixel "linear" weighted linear average of a 2x2 array of texels "nearest.mipmap.nearest" low quality mipmapping "nearest.mipmap.linear" medium quality mipmapping "linear.mipmap.nearest" medium quality mipmapping "linear.mipmap.linear" high quality mipmapping
texenvmap	logical, specifies if auto-generated texture coordinates for environment-mapping should be performed on geometry.
front, back	Determines the polygon mode for the specified side: "fill" filled polygon "line" wireframed polygon "points" point polygon "cull" culled (hidden) polygon
size	numeric, specifying the size of points in pixels
lwd	numeric, specifying the line width in pixels
fog	logical, specifying if fog effect should be applied on the corresponding shape
point_antialias, line_antialias	logical, specifying if points and lines should be antialiased
...	Any of the arguments above; see Details below.

Details

Only one side at a time can be culled.

`material3d` is an alternate interface to the material properties, modelled after `par3d`: rather than setting defaults for parameters that are not specified, they will be left unchanged. `material3d` may also be used to query the material properties; see the examples below.

The current implementation does not return parameters for textures.

If `point_antialias` is `TRUE`, points will be drawn as circles; otherwise, they will be drawn as squares. Lines tend to appear heavier with `line_antialias==TRUE`.

The `material` member of the `r3dDefaults` list may be used to set default values for material properties.

The `...` parameter to `rgl.material` is ignored.

Value

`rgl.material()` is called for the side effect of setting the material properties. It returns a value invisibly which is not intended for use by the user.

Users should use `material3d()` to query material properties. It returns values similarly to `par3d` as follows: When setting properties, it returns the previous values in a named list. A named list is also returned when more than one value is queried. When a single value is queried it is returned directly.

See Also

`rgl.primitive`, `rgl.bbox`, `rgl.bg`, `rgl.light`

Examples

```
save <- material3d("color")
material3d(color="red")
material3d("color")
material3d(color=save)
```

`rgl.pixels`

Extract pixel information from window

Description

This function extracts single components of the pixel information from the topmost window.

Usage

```
rgl.pixels(component = c("red", "green", "blue"), viewport=par3d("viewport"), top =
```

Arguments

<code>component</code>	Which component(s)?
<code>viewport</code>	Lower left corner and size of desired region.
<code>top</code>	Whether to bring window to top before reading.

Details

The possible components are "red", "green", "blue", "alpha", "depth", and "luminance" (the sum of the three colours). All are scaled from 0 to 1.

Note that the luminance is kept below 1 by truncating the sum; this is the definition used for the `GL_LUMINANCE` component in OpenGL.

Value

A vector, matrix or array containing the desired components. If one component is requested, a vector or matrix will be returned depending on the size of block requested (length 1 dimensions are dropped); if more, an array, whose last dimension is the list of components.

Author(s)

Duncan Murdoch

See Also

`rgl.snapshot` to write a copy to a file, `demo("stereo")` for functions that make use of this to draw a random dot stereogram and an anaglyph.

Examples

```
example(surface3d)
depth <- rgl.pixels(component="depth")
if (is.matrix(depth)) # Protect against single pixel windows
  contour(depth)
```

<code>rgl.postscript</code>	<i>export screenshot</i>
-----------------------------	--------------------------

Description

Saves the screenshot to a file in PostScript or other vector graphics format.

Usage

```
rgl.postscript( filename, fmt="eps", drawText=TRUE )
```

Arguments

filename	full path to filename.
fmt	export format, currently supported: ps, eps, tex, pdf, svg, pgf
drawText	logical, whether to draw text

Details

Animations can be created in a loop modifying the scene and saving a screenshot to a file. (See example below)

This function is a wrapper for the GL2PS library by Christophe Geuzaine, and has the same limitations as that library: not all OpenGL features are supported, and some are only supported in some formats. See the reference for full details.

Author(s)

Christophe Geuzaine / Albrecht Gebhardt

References

GL2PS: an OpenGL to PostScript printing library by Christophe Geuzaine, <http://www.geuz.org/gl2ps/>, version 1.3.2.

See Also

[rgl.viewpoint](#), [rgl.snapshot](#)

Examples

```
x <- y <- seq(-10,10,length=20)
z <- outer(x,y,function(x,y) x^2 + y^2)
persp3d(x,y,z, col='lightblue')

title3d("Using LaTeX text", col='red', line=3)
rgl.postscript("persp3da.ps","ps",drawText=FALSE)
rgl.postscript("persp3da.pdf","pdf",drawText=FALSE)
rgl.postscript("persp3da.tex","tex")
rgl.pop()
title3d("Using ps/pdf text", col='red', line=3)
rgl.postscript("persp3db.ps","ps")
rgl.postscript("persp3db.pdf","pdf")
rgl.postscript("persp3db.tex","tex",drawText=FALSE)

## Not run:

#
# create a series of frames for an animation
#

rgl.open()
```

```

shade3d(oh3d(), color="red")
rgl.viewpoint(0,20)

for (i in 1:45) {
  rgl.viewpoint(i,20)
  filename <- paste("pic",formatC(i,digits=1,flag="0"),".eps",sep="")
  rgl.postscript(filename, fmt="eps")
}

## End(Not run)

```

rgl.primitive	<i>add primitive set shape</i>
---------------	--------------------------------

Description

Adds a shape node to the current scene

Usage

```

rgl.points(x, y = NULL, z = NULL, ... )
rgl.lines(x, y = NULL, z = NULL, ... )
rgl.linestrips(x, y = NULL, z = NULL, ...)
rgl.triangles(x, y = NULL, z = NULL, normals=NULL, texcoords=NULL, ... )
rgl.quads(x, y = NULL, z = NULL, normals=NULL, texcoords=NULL, ... )

```

Arguments

<code>x, y, z</code>	coordinates. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>normals</code>	Normals at each point.
<code>texcoords</code>	Texture coordinates at each point.
<code>...</code>	Material properties. See rgl.material for details.

Details

Adds a shape node to the scene. The appearance is defined by the material properties. See [rgl.material](#) for details.

For triangles and quads, the normals at each vertex may be specified using `normals`. These may be given in any way that would be acceptable as a single argument to [xyz.coords](#). These need not match the actual normals to the polygon: curved surfaces can be simulated by using other choices of normals.

Texture coordinates may also be specified. These may be given in any way that would be acceptable as a single argument to [xy.coords](#), and are interpreted in terms of the bitmap specified as the material texture, with $(0, 0)$ at the lower left, $(1, 1)$ at the upper right. The texture is used to modulate the colour of the polygon.

These are the lower level functions called by `points3d`, `lines3d`, etc. The two principal differences between the `rgl.*` functions and the `*3d` functions are that the former set all unspecified material properties to defaults, whereas the latter use current values as defaults; the former make persistent changes to material properties with each call, whereas the latter make temporary changes only for the duration of the call.

Value

Each primitive function returns the integer object ID of the shape that was added to the scene. These can be passed to `rgl.pop` to remove the object from the scene.

See Also

`rgl.material`, `rgl.spheres`, `rgl.texts`, `rgl.surface`, `rgl.sprites`

Examples

```
rgl.open()
rgl.points(rnorm(1000), rnorm(1000), rnorm(1000), color=heat.colors(1000))
```

```
rgl.setMouseCallbacks
```

User callbacks on mouse events

Description

This function sets user callbacks on mouse events.

Usage

```
rgl.setMouseCallbacks(button, begin = NULL, update = NULL, end = NULL)
```

Arguments

<code>button</code>	Which button?
<code>begin</code>	Called when mouse down event occurs
<code>update</code>	Called when mouse moves
<code>end</code>	Called when mouse is released

Details

This function sets an event handler on mouse events that occur within the current rgl window. The `begin` and `update` events should be functions taking two arguments; these will be the mouse coordinates when the event occurs. The `end` event handler takes no arguments.

Alternatively, the handlers may be set to `NULL`, the default value, in which case no action will occur.

Value

This function is called for the side effect of setting the mouse event handlers.

Author(s)

Duncan Murdoch

See Also

[par3d](#) to set built-in handlers

Examples

```
## Not quite right --- this doesn't play well with rescaling

pan3d <- function(button) {
  start <- list()

  begin <- function(x, y) {
    start$userMatrix <- par3d("userMatrix")
    start$viewport <- par3d("viewport")
    start$scale <- par3d("scale")
    start$projection <- rgl.projection()
    start$pos <- rgl.window2user( x/start$viewport[3], 1 - y/start$viewport[4], 0.5,
                                projection=start$projection)
  }

  update <- function(x, y) {
    xlat <- (rgl.window2user( x/start$viewport[3], 1 - y/start$viewport[4], 0.5,
                            projection = start$projection) - start$pos)*start$scale
    mouseMatrix <- translationMatrix(xlat[1], xlat[2], xlat[3])
    par3d(userMatrix = start$userMatrix %*% t(mouseMatrix) )
  }
  rgl.setMouseCallbacks(button, begin, update)
  cat("Callbacks set on button", button, "of rgl device", rgl.cur(), "\n")
}
pan3d(3)
```

rgl.snapshot

export screenshot

Description

Saves the screenshot as png file.

Usage

```
rgl.snapshot( filename, fmt="png", top=TRUE )
snapshot3d( ... )
```

Arguments

filename	full path to filename.
fmt	image export format, currently supported: png
top	whether to call <code>rgl.bringtotop</code>
...	arguments to pass to <code>rgl.snapshot</code>

Details

Animations can be created in a loop modifying the scene and saving each screenshot to a file. Various graphics programs (e.g. ImageMagick) can put these together into a single animation. (See [movie3d](#) or the example below.)

Note

On some systems, the snapshot will include content from other windows if they cover the active rgl window. Setting `top=TRUE` (the default) will use `rgl.bringtotop` before the snapshot to avoid this. (See <http://www.opengl.org/resources/faq/technical/rasterization.htm#rast0070> for more details.)

See Also

[movie3d](#), [rgl.viewpoint](#)

Examples

```
## Not run:

#
# create animation
#

shade3d(oh3d(), color="red")
rgl.bringtotop()
rgl.viewpoint(0,20)

setwd(tempdir())
for (i in 1:45) {
  rgl.viewpoint(i,20)
  filename <- paste("pic", formatC(i, digits=1, flag="0"), ".png", sep="")
  rgl.snapshot(filename)
}
## Now run ImageMagick command:
##   convert -delay 10 *.png -loop 0 pic.gif
## End(Not run)
```

rgl.surface	<i>add height-field surface shape</i>
-------------	---------------------------------------

Description

Adds a surface to the current scene. The surface is defined by a matrix defining the height of each grid point and two vectors defining the grid.

Usage

```
rgl.surface(x, z, y, coords=1:3, ...,
            normal_x=NULL, normal_y=NULL, normal_z=NULL,
            texture_s=NULL, texture_t=NULL)
```

Arguments

<code>x</code>	values corresponding to rows of <code>y</code> , or matrix of <code>x</code> coordinates
<code>y</code>	matrix of height values
<code>z</code>	values corresponding to columns of <code>y</code> , or matrix of <code>z</code> coordinates
<code>coords</code>	See details
<code>...</code>	Material and texture properties. See rgl.material for details.
<code>normal_x, normal_y, normal_z</code>	matrices of the same dimension as <code>y</code> giving the coordinates of normals at each grid point
<code>texture_s, texture_t</code>	matrices of the same dimension as <code>z</code> giving the coordinates within the current texture of each grid point

Details

Adds a surface mesh to the current scene. The surface is defined by the matrix of height values in `y`, with rows corresponding to the values in `x` and columns corresponding to the values in `z`.

The `coords` parameter can be used to change the geometric interpretation of `x`, `y`, and `z`. The first entry of `coords` indicates which coordinate (1=X, 2=Y, 3=Z) corresponds to the `x` parameter. Similarly the second entry corresponds to the `y` parameter, and the third entry to the `z` parameter. In this way surfaces may be defined over any coordinate plane.

If the normals are not supplied, they will be calculated automatically based on neighbouring points.

Texture coordinates run from 0 to 1 over each dimension of the texture bitmap. If texture coordinates are not supplied, they will be calculated to render the texture exactly once over the grid. Values greater than 1 can be used to repeat the texture over the surface.

`rgl.surface` always draws the surface with the ‘front’ upwards (i.e. towards higher `y` values). This can be used to render the top and bottom differently; see [rgl.material](#) and the example below.

If the `x` or `z` argument is a matrix, then it must be of the same dimension as `y`, and the values in the matrix will be used for the corresponding coordinates. This is used to plot shapes such as cylinders where `y` is not a function of `x` and `z`.

NA values in the height matrix are not drawn.

Value

The object ID of the displayed surface is returned invisibly.

See Also

[rgl.material](#), [surface3d](#), [terrain3d](#). See [persp3d](#) for a higher level interface.

Examples

```
#
# volcano example taken from "persp"
#

data(volcano)

y <- 2 * volcano      # Exaggerate the relief

x <- 10 * (1:nrow(y)) # 10 meter spacing (S to N)
z <- 10 * (1:ncol(y)) # 10 meter spacing (E to W)

ylim <- range(y)
ylen <- ylim[2] - ylim[1] + 1

colorlut <- terrain.colors(ylen) # height color lookup table

col <- colorlut[ y-ylim[1]+1 ] # assign colors to heights for each point

rgl.open()
rgl.surface(x, z, y, color=col, back="lines")
```

rgl.user2window	<i>Convert between rgl user and window coordinates</i>
-----------------	--

Description

This function converts from 3-dimensional user coordinates to 3-dimensional window coordinates.

Usage

```
rgl.user2window(x, y = NULL, z = NULL, projection = rgl.projection())
rgl.window2user(x, y = NULL, z = 0, projection = rgl.projection())
rgl.projection()
```

Arguments

<code>x, y, z</code>	Input coordinates. Any reasonable way of defining the coordinates is acceptable. See the function <code>xyz.coords</code> for details.
<code>projection</code>	The rgl projection to use

Details

These functions convert between user coordinates and window coordinates.

Window coordinates run from 0 to 1 in X, Y, and Z. X runs from 0 on the left to 1 on the right; Y runs from 0 at the bottom to 1 at the top; Z runs from 0 foremost to 1 in the background. `rgl` does not currently display vertices plotted outside of this range, but in normal circumstances will automatically resize the display to show them. In the example below this has been suppressed.

Value

The coordinate conversion functions produce a matrix with columns corresponding to the X, Y, and Z coordinates.

`rgl.projection()` returns a list containing the model matrix, projection matrix and viewport. See [par3d](#) for more details.

Author(s)

Ming Chen / Duncan Murdoch

See Also

[select3d](#)

Examples

```
open3d()
points3d(rnorm(100), rnorm(100), rnorm(100))
if (interactive() || !.Platform$OS=="unix") {
  # Calculate a square in the middle of the display and plot it
  square <- rgl.window2user(c(0.25, 0.25, 0.75, 0.75, 0.25),
                           c(0.25, 0.75, 0.75, 0.25, 0.25), 0.5)
  par3d(ignoreExtent = TRUE)
  lines3d(square)
  par3d(ignoreExtent = FALSE)
}
```

scene

scene management

Description

Clear shapes, lights, bbox

Usage

```

clear3d( type = c("shapes", "bboxdeco", "material"), defaults )
rgl.clear( type = "shapes" )
pop3d( ... )
rgl.pop( type = "shapes", id = 0 )
rgl.ids( type = "shapes" )

```

Arguments

<code>type</code>	Select subtype(s): "shapes" shape stack "lights" light stack "bboxdeco" bounding box "viewpoint" viewpoint "material" material properties "all" all of the above
<code>defaults</code>	default values to use after clearing
<code>id</code>	vector of ID numbers of items to remove
<code>...</code>	generic arguments passed through to RGL-specific (or other) functions

Details

RGL holds two stacks. One is for shapes and the other is for lights. `clear3d` and `rgl.clear` clear the specified stack, or restore the defaults for the bounding box (not visible) or viewpoint. By default with `id=0` `rgl.pop` removes the top-most (last added) node on the shape stack. The `id` argument may be used to specify arbitrary item(s) to remove from the specified stack.

`rgl.clear` and `clear3d` may also be used to clear material properties back to their defaults.

`clear3d` has an optional `defaults` argument, which defaults to `r3dDefaults`. Only the materials component of this argument is currently used by `clear3d`.

`rgl.ids` returns a dataframe containing the IDs in the currently active rgl window, along with an indicator of their type.

For convenience, `type="shapes"` and `id=1` signifies the bounding box.

Note that clearing the light stack leaves the scene in darkness; it should normally be followed by a call to `rgl.light` or `light3d`.

See Also

[rgl](#), [rgl.bbox](#), [rgl.light](#), [open3d](#) to open a new window.

Examples

```
x <- rnorm(100)
y <- rnorm(100)
z <- rnorm(100)
p <- plot3d(x, y, z, type='s')
rgl.ids()
lines3d(x, y, z)
rgl.ids()
if (interactive()) {
  readline("Hit enter to change spheres")
  rgl.pop(id = p[c("data", "box.lines")])
  spheres3d(x, y, z, col="red", radius=1/5)
  box3d()
}
```

select3d

Select a rectangle in an RGL scene

Description

This function allows the user to use the mouse to select a region in an RGL scene.

Usage

```
rgl.select3d(button = c("left", "middle", "right"))
select3d(...)
```

Arguments

button	Which button to use for selection.
...	Button argument to pass to <code>rgl.select3d</code>

Details

This function selects 3-dimensional regions by allowing the user to use a mouse to draw a rectangle showing the projection of the region onto the screen. It returns a function which tests points for inclusion in the selected region.

If the scene is later moved or rotated, the selected region will remain the same, no longer corresponding to a rectangle on the screen.

Value

Returns a function $f(x, y, z)$ which tests whether each of the points (x, y, z) is in the selected region, returning a logical vector. This function accepts input in a wide variety of formats as it uses [xyz.coords](#) to interpret its parameters.

Author(s)

Ming Chen / Duncan Murdoch

See Also[locator](#)**Examples**

```
# Allow the user to select some points, and then redraw them
# in a different color

if (interactive()) {
  x <- rnorm(1000)
  y <- rnorm(1000)
  z <- rnorm(1000)
  open3d()
  points3d(x,y,z)
  f <- select3d()
  keep <- f(x,y,z)
  rgl.pop()
  points3d(x[keep],y[keep],z[keep],color='red')
  points3d(x[!keep],y[!keep],z[!keep])
}
```

shapelist3d

*Create and plot a list of shapes***Description**

These functions create and plot a list of shapes.

Usage

```
shapelist3d(shapes, x = 0, y = NULL, z = NULL, size = 1, matrix = NULL, override =
..., plot = TRUE)
```

Arguments

shapes	A single shape3d object, or a list of them.
x, y, z	Translation(s) to apply
size	Scaling(s) to apply
matrix	A single matrix transformation, or a list of them.
override	Whether the material properties should override the ones in the shapes.
...	Material properties to apply.
plot	Whether to plot the result.

Details

`shapelist3d` is a quick way to create a complex object made up of simpler ones. Each of the arguments `shapes` through `override` may be a vector of values (a list in the case of `shapes` or `matrix`). All values will be recycled to produce a list of shapes as long as the longest of them.

The `xyz.coords` function will be used to process the `x`, `y` and `z` arguments, so a matrix may be used as `x` to specify all three. If a vector is used for `x` but `y` or `z` is missing, default values of 0 will be used.

The "shapelist3d" class is simply a list of "shape3d" objects.

Methods for `dot3d`, `wire3d`, `shade3d`, `translate3d`, `scale3d`, and `rotate3d` are defined for these objects.

Value

An object of class `c("shapelist3d", "shape3d")`.

Author(s)

Duncan Murdoch

See Also

[mesh3d](#)

Examples

```
shapelist3d(icosahedron3d(), x=rnorm(10), y=rnorm(10), z=rnorm(10), col=1:5, size=0.3)
```

spheres	<i>add sphere set shape</i>
---------	-----------------------------

Description

Adds a sphere set shape node to the scene

Usage

```
spheres3d(x, y = NULL, z = NULL, radius = 1, ...)
rgl.spheres(x, y = NULL, z = NULL, radius, ...)
```

Arguments

<code>x</code> , <code>y</code> , <code>z</code>	Numeric vector of point coordinates corresponding to the center of each sphere. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>radius</code>	Vector or single value defining the sphere radius/radii
<code>...</code>	Material properties. See rgl.material for details.

Details

If a non-isometric aspect ratio is chosen, these functions will still draw objects that appear to the viewer to be spheres. Use `ellipse3d` to draw shapes that are spherical in the data scale.

When the scale is not isometric, the radius is measured in an average scale. Note that the bounding box calculation is always done assuming an isometric scale, so in this case it is inaccurate: the extent of axes with `scale < 1` is underestimated, and that of axes with `scale > 1` is overestimated.

If any coordinate or radius is NA, the sphere is not plotted.

Value

A shape ID of the spheres object is returned.

See Also

`rgl.material`, `aspect3d` for setting non-isometric scales

Examples

```
open3d()
spheres3d(rnorm(10), rnorm(10), rnorm(10), radius=runif(10), color=rainbow(10))
```

spin3d

Create a function to spin a scene at a fixed rate

Description

This creates a function to use with `play3d` to spin an rgl scene at a fixed rate.

Usage

```
spin3d(axis = c(0, 0, 1), rpm = 5)
```

Arguments

<code>axis</code>	The desired axis of rotation
<code>rpm</code>	The rotation speed in rotations per minute

Value

A function with header `function(time)`. This function calculates and returns a list containing `userMatrix` updated by spinning it for `time` seconds at `rpm` revolutions per minute about the specified `axis`.

Author(s)

Duncan Murdoch

See Also

[play3d](#) to play the animation

Examples

```
open3d()
plot3d(oh3d(col="lightblue", alpha=0.5))
play3d(spin3d(axis=c(1,0,0), rpm=20), duration=3)
```

sprites	<i>add sprite set shape</i>
---------	-----------------------------

Description

Adds a sprite set shape node to the scene.

Usage

```
sprites3d(x, y = NULL, z = NULL, radius = 1, ...)
particles3d(x, y = NULL, z = NULL, radius = 1, ...)
rgl.sprites(x, y = NULL, z = NULL, radius = 1, ...)
```

Arguments

<code>x, y, z</code>	point coordinates. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>radius</code>	vector or single value defining the sphere radius
<code>...</code>	material properties, texture mapping is supported

Details

Sprites are rectangle planes that are directed towards the viewpoint. Their primary use is for fast (and faked) atmospherical effects, e.g. particles and clouds using alpha blended textures. Particles are Sprites using an alpha-blended particle texture giving the illusion of clouds and gasses.

If any coordinate is NA, the sprite is not plotted.

Value

These functions are called for the side effect of displaying the sprites. The shape ID of the displayed object is returned.

See Also

[rgl.material](#)

Examples

```
open3d()
particles3d( rnorm(100), rnorm(100), rnorm(100), color=rainbow(100) )
# is the same as
sprites3d( rnorm(100), rnorm(100), rnorm(100), color=rainbow(100),
  lit=FALSE, alpha=.2,
  textype="alpha", texture=system.file("textures/particle.png", package="rgl") )
```

subdivision3d

generic subdivision surface method

Description

The Subdivision surface algorithm divide and refine (deform) a given mesh recursively to certain degree (depth). The mesh3d algorithm consists of two stages: divide and deform. The divide step generates for each triangle or quad four new triangles or quads, the deform step drags the points (refinement step).

Usage

```
subdivision3d( x, ...)
## S3 method for class 'mesh3d':
subdivision3d( x, depth=1, normalize=FALSE, deform=TRUE, ... )
divide.mesh3d(mesh, vb=mesh$vb, ib=mesh$ib, it=mesh$it )
normalize.mesh3d(mesh)
deform.mesh3d(mesh, vb=mesh$vb, ib=mesh$ib, it=mesh$it )
```

Arguments

x	3d geometry mesh
mesh	3d geometry mesh
depth	recursion depth
normalize	normalize mesh3d coordinates after division if deform is TRUE
deform	deform mesh
it	indices for triangular faces
ib	indices for quad faces
vb	matrix of vertices: 4xn matrix (rows x,y,z,h) or equivalent vector, where h indicates scaling of each plotted quad
...	other arguments (unused)

Details

Generic subdivision surface method. Currently there exists an algorithm that can be applied on mesh3d objects.

See Also[r3d.mesh3d](#)**Examples**

```
open3d()
shade3d( subdivision3d( cube3d(), depth=3 ), color="red", alpha=0.5 )
```

surface3d

add height-field surface shape

Description

Adds a surface to the current scene. The surface is defined by a matrix defining the height of each grid point and two vectors defining the grid.

Usage

```
surface3d(x, y, z, ..., normal_x=NULL, normal_y=NULL, normal_z=NULL)
terrain3d(x, y, z, ..., normal_x=NULL, normal_y=NULL, normal_z=NULL)
```

Arguments

<code>x</code>	values corresponding to rows of <code>z</code> , or matrix of <code>x</code> coordinates
<code>y</code>	values corresponding to the columns of <code>z</code> , or matrix of <code>y</code> coordinates
<code>z</code>	matrix of heights
<code>...</code>	Material and texture properties. See rgl.material for details.
<code>normal_x</code> , <code>normal_y</code> , <code>normal_z</code>	matrices of the same dimension as <code>z</code> giving the coordinates of normals at each grid point

Details

Adds a surface mesh to the current scene. The surface is defined by the matrix of height values in `z`, with rows corresponding to the values in `x` and columns corresponding to the values in `y`. This is the same parametrization as used in [persp](#).

If the `x` or `y` argument is a matrix, then it must be of the same dimension as `z`, and the values in the matrix will be used for the corresponding coordinates. This is used to plot shapes such as cylinders where `z` is not a function of `x` and `y`.

If the normals are not supplied, they will be calculated automatically based on neighbouring points.

`surface3d` always draws the surface with the ‘front’ upwards (i.e. towards higher `z` values). This can be used to render the top and bottom differently; see [rgl.material](#) and the example below.

For more flexibility in defining the surface, use [rgl.surface](#).

`surface3d` and `terrain3d` are synonyms.

See Also

[rgl.material](#), [rgl.surface](#). See [persp3d](#) for a higher level interface.

Examples

```
#
# volcano example taken from "persp"
#

data(volcano)

z <- 2 * volcano      # Exaggerate the relief

x <- 10 * (1:nrow(z)) # 10 meter spacing (S to N)
y <- 10 * (1:ncol(z)) # 10 meter spacing (E to W)

zlim <- range(y)
zlen <- zlim[2] - zlim[1] + 1

colorlut <- terrain.colors(zlen) # height color lookup table

col <- colorlut[ z-zlim[1]+1 ] # assign colors to heights for each point

open3d()
surface3d(x, y, z, color=col, back="lines")
```

texts

add text

Description

Adds text to the scene. The text is positioned in 3D space. Text is always oriented towards the camera.

Usage

```
rgl.texts(x, y = NULL, z = NULL, text, adj = 0.5, justify, family = par3d("family")
        cex = par3d("cex"), useFreeType=par3d("useFreeType"), ...)
text3d(x, y = NULL, z = NULL, texts, adj = 0.5, justify, ...)
texts3d(x, y = NULL, z = NULL, texts, adj = 0.5, justify, ...)
rglFonts(...)
```

Arguments

<code>x, y, z</code>	point coordinates. Any reasonable way of defining the coordinates is acceptable. See the function xyz.coords for details.
<code>text</code>	text character vector to draw

<code>texts</code>	text character vector to draw
<code>adj</code>	one value specifying the horizontal adjustment, or two, specifying horizontal and vertical adjustment respectively.
<code>justify</code>	(deprecated, please use <code>adj</code> instead) character string specifying the horizontal adjustment; options are "left", "right", "center".
<code>family</code>	A device-independent font family name, or ""
<code>font</code>	A numeric font number from 1 to 5
<code>cex</code>	A numeric character expansion value
<code>useFreeType</code>	logical. Should FreeType be used to draw text? (See details below.)
<code>...</code>	In <code>rgl.texts</code> , material properties; see rgl.material for details. In <code>rglFonts</code> , device dependent font definitions for use with FreeType. In the other functions, additional parameters to pass to <code>rgl.texts</code> .

Details

The `adj` parameter determines the position of the text relative to the specified coordinate. Use `adj = c(0,0)` to place the left bottom corner at (x, y, z) , `adj = c(0.5, 0.5)` to center the text there, and `adj = c(1,1)` to put the right top corner there. The optional second coordinate for vertical adjustment defaults to 0.5. Placement is done using the "advance" of the string and the "ascent" of the font relative to the baseline, when these metrics are known.

`text3d` and `texts3d` draw text using the [r3d](#) conventions. These are synonyms; the former is singular to be consistent with the classic 2-D graphics functions, and the latter is plural to be consistent with all the other graphics primitives. Take your choice!

If any coordinate or text is NA, that text is not plotted.

Value

The text drawing functions return the object ID of the text object `i` invisibly.

`rglFonts` returns the current set of font definitions.

Fonts

Fonts are specified using the `family`, `font`, `cex`, and `useFreeType` arguments. Defaults for the currently active device may be set using [par3d](#), or for future devices using [r3dDefaults](#).

The `family` specification is the same as for standard graphics, i.e. families `c("serif", "sans", "mono", "symbol")` are normally available, but users may add additional families. `font` numbers are restricted to the range 1 to 4 for standard, bold, italic and bold italic respectively; with font 5 recoded as family "symbol" font 1.

Using an unrecognized value for "family" will result in the system standard font as used in `rgl` up to version 0.76. That font is not resizable and `font` values are ignored.

If `useFreeType` is TRUE, then `rgl` will use the FreeType anti-aliased fonts for drawing. This is generally desirable, and it is the default if `rgl` was built to support FreeType.

FreeType fonts are specified using the `rglFonts` function. This function takes a vector of four filenames of TrueType font files which will be used for the four styles regular, bold, italic and bold

italic. The vector is passed with a name to be used as the family name, e.g. `rglFonts(sans = c("/path/to/FreeSans.ttf", ...`. In order to limit the file size, `rgl` ships with just 3 font files, for regular versions of the `serif`, `sans` and `mono` families. Additional free font files are available from the Amaya project at <http://dev.w3.org/cvsweb/Amaya/fonts/>. See the example below for how to specify a full set of fonts.

Full pathnames should normally be used to specify font files. If relative paths are used, they are interpreted differently by platform. Currently Windows fonts are looked for in the Windows fonts folder, while other platforms use the current working directory.

If FreeType fonts are not used, then bitmapped fonts will be used instead. On Windows these will be based on the fonts specified using the `windowsFonts` function, and are resizable. Other platforms will use the default bitmapped font which is not resizable. Currently MacOSX defaults to the bitmapped font, as our font library appears unable to read fonts properly on that platform.

See Also

[r3d](#)

Examples

```
open3d()
famnum <- rep(1:4, 8)
family <- c("serif", "sans", "mono", "symbol")[famnum]
font <- rep(rep(1:4, each=4), 2)
cex <- rep(1:2, each=16)
text3d(font, cex, famnum, text=paste(family, font), adj = 0.5,
        color="blue", family=family, font=font, cex=cex)
## Not run:
# These FreeType fonts are available from the Amaya project, and are not shipped
# with rgl. You would normally install them to the rgl/fonts directory
# and use fully qualified pathnames, e.g.
# system.file("fonts/FreeSerif.ttf", package= "rgl")

rglFonts(serif=c("FreeSerif.ttf", "FreeSerifBold.ttf", "FreeSerifItalic.ttf",
                "FreeSerifBoldItalic.ttf"),
        sans =c("FreeSans.ttf", "FreeSansBold.ttf", "FreeSansOblique.ttf",
                "FreeSansBoldOblique.ttf"),
        mono =c("FreeMono.ttf", "FreeMonoBold.ttf", "FreeMonoOblique.ttf",
                "FreeMonoBoldOblique.ttf"),
        symbol=c("ESSTIX10.TTF", "ESSTIX12.TTF", "ESSTIX9_.TTF",
                "ESSTIX11.TTF"))
## End(Not run)
```

viewpoint

Set up viewpoint

Description

Set the viewpoint orientation.

Usage

```
view3d( theta = 0, phi = 15, ...)
rgl.viewpoint( theta = 0, phi = 15, fov = 60, zoom = 1, scale = par3d("scale"),
              interactive = TRUE, userMatrix )
```

Arguments

<code>theta, phi</code>	polar coordinates
<code>...</code>	additional parameters to pass to <code>rgl.viewpoint</code>
<code>fov</code>	field-of-view angle in degrees
<code>zoom</code>	zoom factor
<code>scale</code>	real length 3 vector specifying the rescaling to apply to each axis
<code>interactive</code>	logical, specifying if interactive navigation is allowed
<code>userMatrix</code>	4x4 matrix specifying user point of view

Details

The viewpoint can be set in an orbit around the data model, using the polar coordinates `theta` and `phi`. Alternatively, it can be set in a completely general way using the 4x4 matrix `userMatrix`. If `userMatrix` is specified, `theta` and `phi` are ignored.

The pointing device of your graphics user-interface can also be used to set the viewpoint interactively. With the pointing device the buttons are by default set as follows:

left adjust viewpoint position
middle adjust field of view angle
right or wheel adjust zoom factor

If the `fov` angle is set to 0, a parallel or orthogonal projection is used. Small non-zero values (e.g. 0.01 or less, but not 0.0) are likely to lead to rendering errors due to OpenGL limitations.

See Also

[par3d](#)

Examples

```
## Not run:
# animated round trip tour for 10 seconds

rgl.open()
shade3d(oh3d(), color="red")

start <- proc.time()[3]
while ((i <- 36*(proc.time()[3]-start)) < 360) {
  rgl.viewpoint(i, i/4);
}
## End(Not run)
```

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