

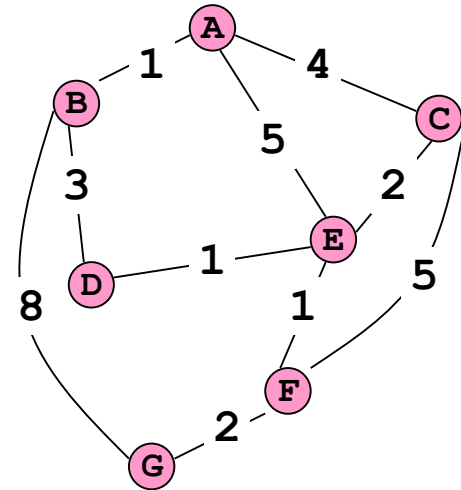
# Shortest Path Algorithm

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# Shortest Path Problem

For weighted graphs it is often useful to find the shortest path between two vertices

- Here, the “shortest path” is the path that has the smallest sum of its edge weights



The shortest path between B and G is:  
B-D-E-F-G and not  
B-G (or B-A-E-F-G)

# MST Vs Shortest Path

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Consider the triangle graph with unit weights - it has three vertices  $x, y, z$ , and all three edges  $\{x, y\}, \{x, z\}, \{y, z\}$  have weight 1.

The shortest path between any two vertices is the direct path, but if you put all of them together you get a triangle rather than a tree. E

very collection of two edges forms a minimum spanning tree in this graph, yet if (for example) you choose  $\{x, y\}, \{y, z\}$ , then you miss the shortest path  $\{x, z\}$

.

In conclusion, if you put all shortest paths together, you don't necessarily get a tree.

# Dijkstra's Algorithm

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- Solution to the single-source shortest path problem in graph theory
- Both directed and undirected graphs
- All edges must have nonnegative weights
- Graph must be connected

# Dijkstra's Algorithm

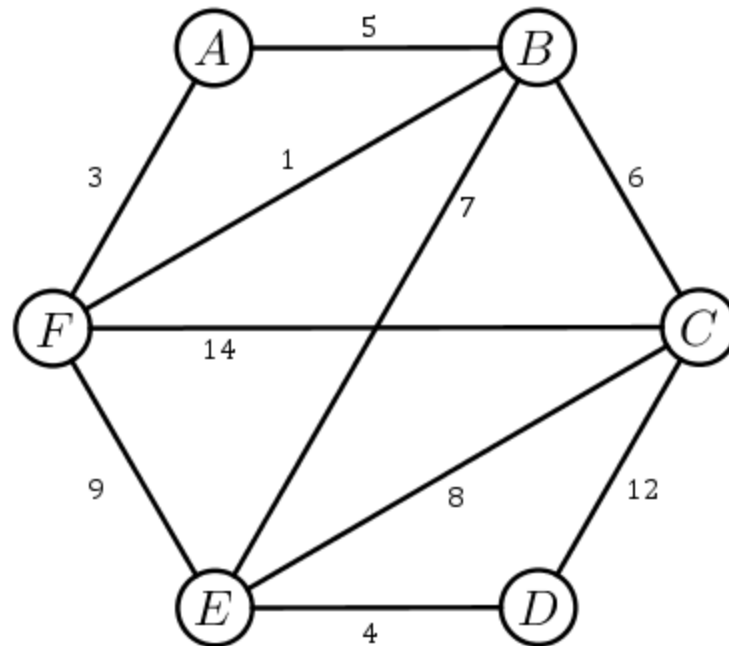
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dist[s] ← 0                                (distance to source vertex is zero)
for all v ∈ V - {s}
    do dist[v] ← ∞                          (set all other distances to infinity)
S ← ∅                                        (S, the set of visited vertices is initially empty)
Q ← V                                       (Q, the queue initially contains all vertices)
while Q ≠ ∅                                (while the queue is not empty)
do u ← mindistance(Q, dist)                (select the element of Q with the min. distance)
    S ← S ∪ {u}, Q = Q - {u}               (add u to list of visited vertices)
    for all v ∈ neighbors[u]
        do if dist[v] > dist[u] + w(u, v)   (if new shortest path found)
            then d[v] ← d[u] + w(u, v)     (set new value of shortest path)
                                            (if desired, add traceback code)

return dist
```

# Class Exercise 1

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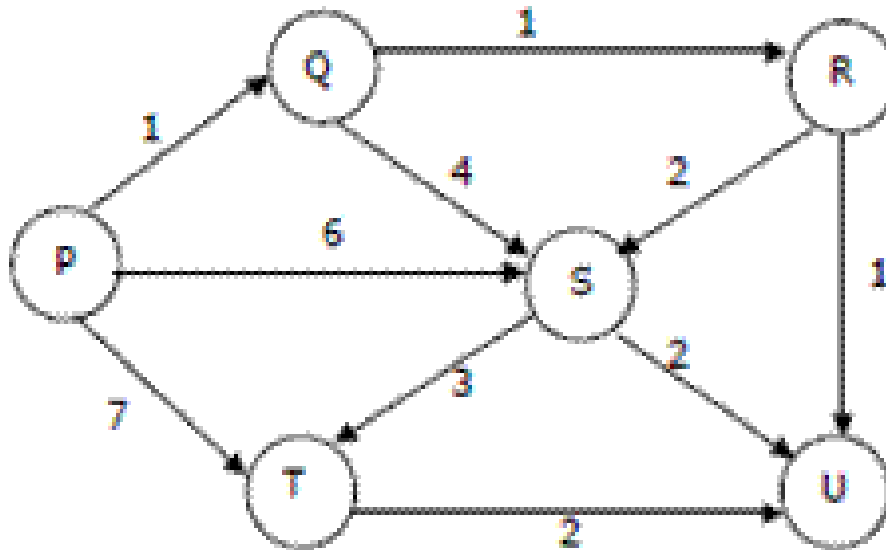
Apply the Dijkstra's algorithm to find the shortest path between the vertex A and each of the other vertices.



# Class Exercise 2

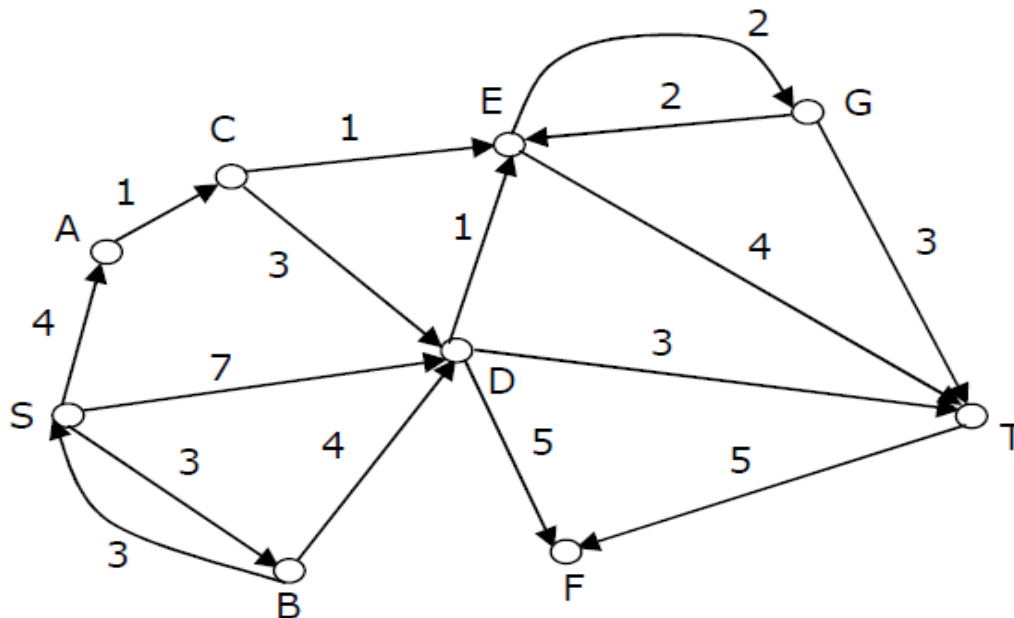
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Suppose we run Dijkstra's single source shortest-path algorithm on the following edge weighted directed graph with vertex P as the source. In what order do the nodes get included into the set of vertices for which the shortest path distances are finalized?



# Class Exercise 3

Consider the directed graph shown in the figure below. There are multiple shortest paths between vertices S and T. Which one will be reported by Dijkstra's shortest path algorithm? Assume that, in any iteration, the shortest path to a vertex  $v$  is updated only when a strictly shorter path to  $v$  is discovered.



- i. SACDT
- ii. SBDT
- iii. SDT
- iv. SACET