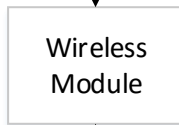


- ① Raw angle data
- ② Change in forward angle
- ③ Change in angle and angular position
- ④ PWM
- ⑤ Motor control signal
- ⑥ Desired speed
- ⑦ Angle/servo control signal
- ⑧ Position
- ⑨ Time received and distance
- ⑩ Ultra sound
- ⑪ Position and time
- ⑫ Time send
- ⑬ Route



Tracked Vehicle

