$$\begin{array}{c|c} PWM(s) & K_s & \theta_{servo}(s) \\ \hline \end{array} \begin{array}{c|c} K_v & \omega_v(s) \\ \hline \end{array} \begin{array}{c|c} \frac{1}{s} & \theta_v(s) \\ \hline \end{array}$$