



- ① Raw angle data
- ② Processed angle data
- ③ Belt speed
- ④ PWM signal
- ⑤ Motor control signal
- ⑥ Desired speed
- ⑦ Angle/servo control signal
- ⑧ Position and time
- ⑨ Time received
- ⑩ Ultra sound
- ⑪ Hall sensor pulses
- ⑫ Time send
- ⑬ Route
- ⑭ Map edge

### Tracked Vehicle

