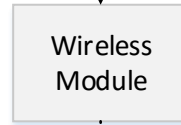


- ① Raw angle data
- ② Angle
- ③ Belt speed
- ④ PWM signal
- ⑤ Motor control signal
- ⑥ Desired speed
- ⑦ Angle/servo control signal
- ⑧ Position
- ⑨ Time received
- ⑩ Ultra sound
- ⑪ Hall sensor pulses
- ⑫ Time send
- ⑬ Route coordinates
- ⑭ Time send and received



Tracked Vehicle

