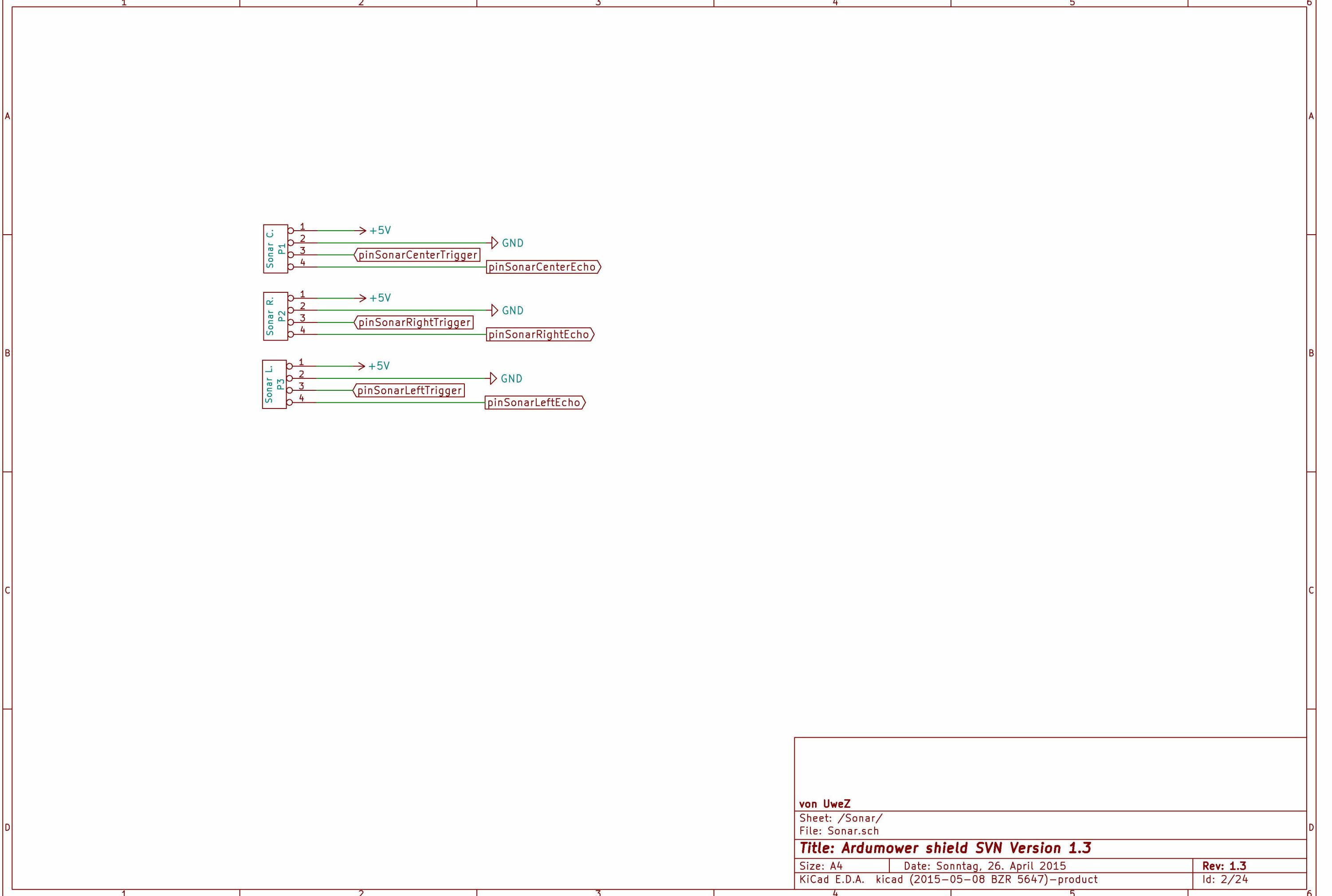


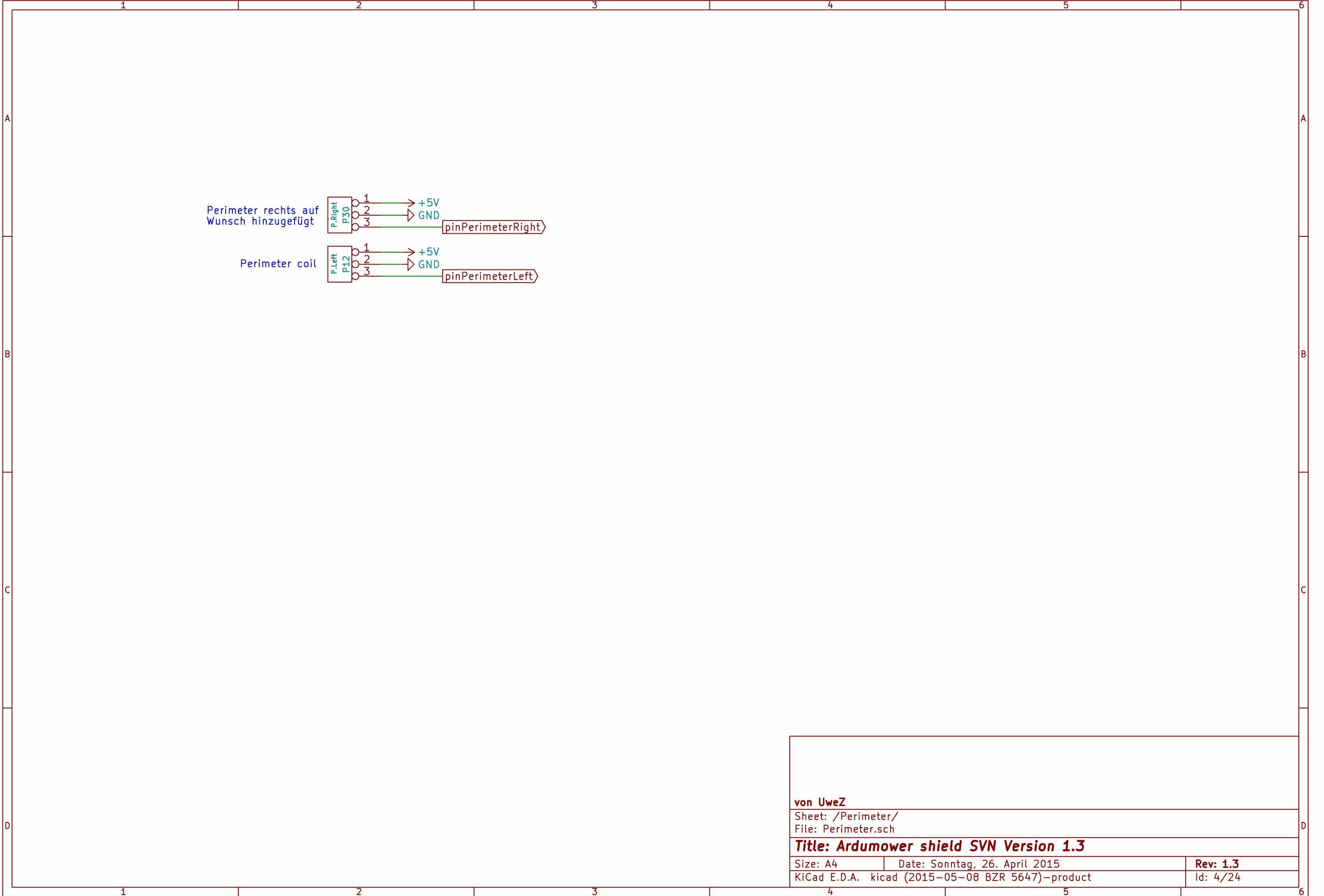
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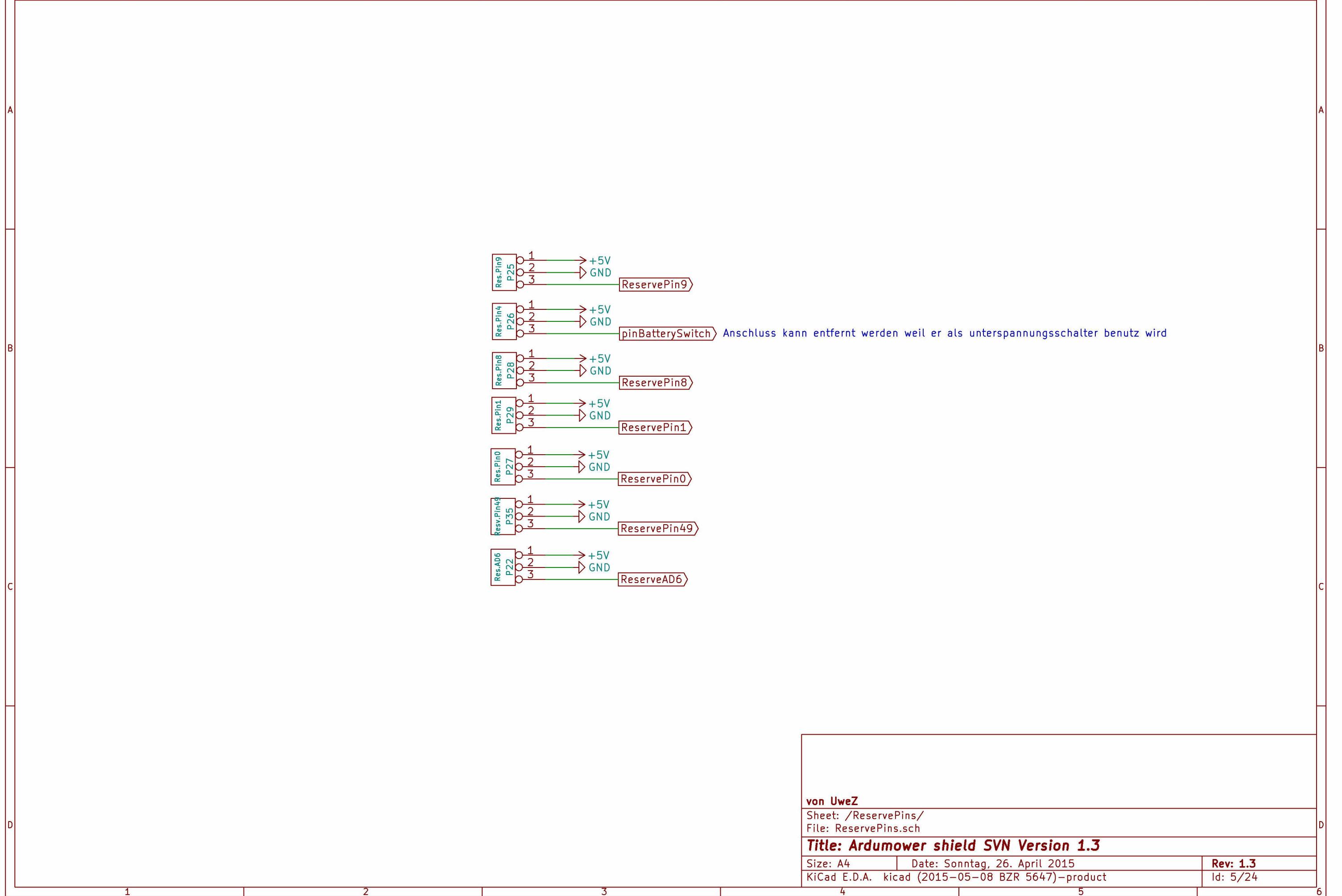


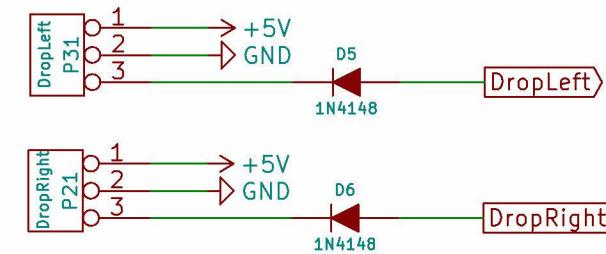
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1 2 3 4 5 6





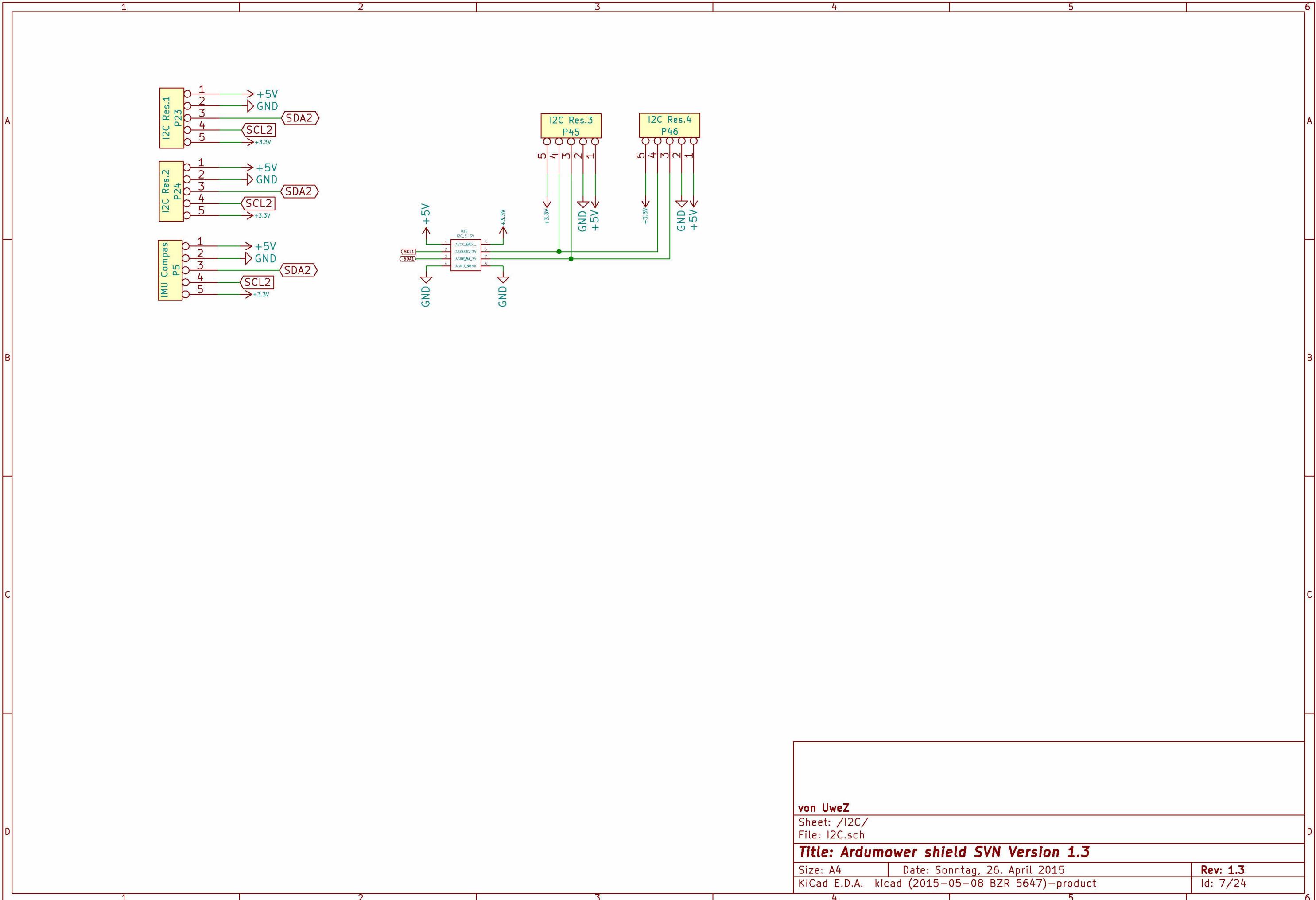


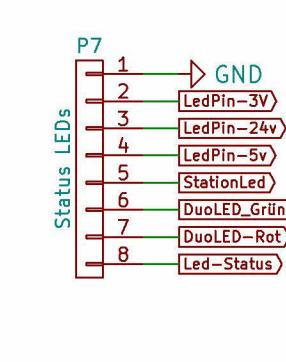
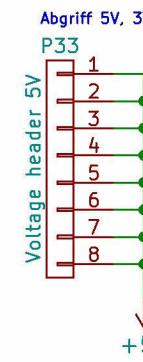
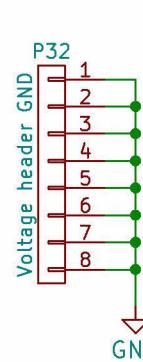
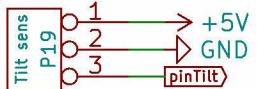
Dropsensoren
von UweZ

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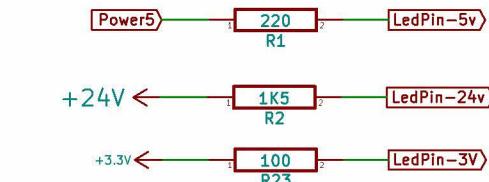


LED Rechner:
<http://www.elektronik-kompendium.de/sites/bau/1109111.htm>

Z-Dioden Rechner:
<http://www.dieelektronikerseite.de/Tools/Zenerdiode.htm>

LED Anzeigen – Hardware:

Led 3V grün – Betriebsanzeige Versorgungsspannung
LED 24V grün – Betriebsanzeige Versorgungsspannung R2 für 12 V anpassen
LED 5V grün – Betriebsanzeige Versorgungsspannung
LED Station – gelb – Statusanzeige ob Mover in Ladestation

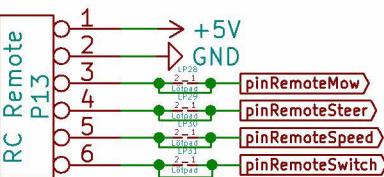
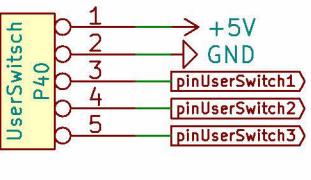


LED Anzeigen – Software:

Dual LED z.B:
Dual LED grün. Dauerlicht – Mover innerhalb Perimeter
Dual LED grün+rot = Orange – Dauerlicht Mover außerhalb Perimeter
Dual LED grün+rot = Orange – Blinkt Mover findet Perimeter nicht oder sucht danach
Dual LED rot = Blinkt Fehler kurzzeitig Überlast Antriebmotor Treibe oder Mähmotor.
Dual LED rot – Dauerlicht – Fehler muss für weiterfahren durch drücken von Button zurückgesetzt werden

LED Status – Software:

Led 3V grün Dauerlicht – warte auf Eingabe
LED Status – grün blinken 1 bis 5 mal hintereinander mit länger Pause dazwischen für Anzeige in welchen Betriebsmodi sich der Mover befindet



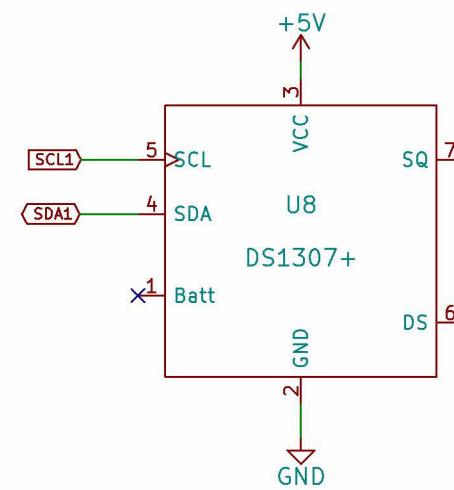
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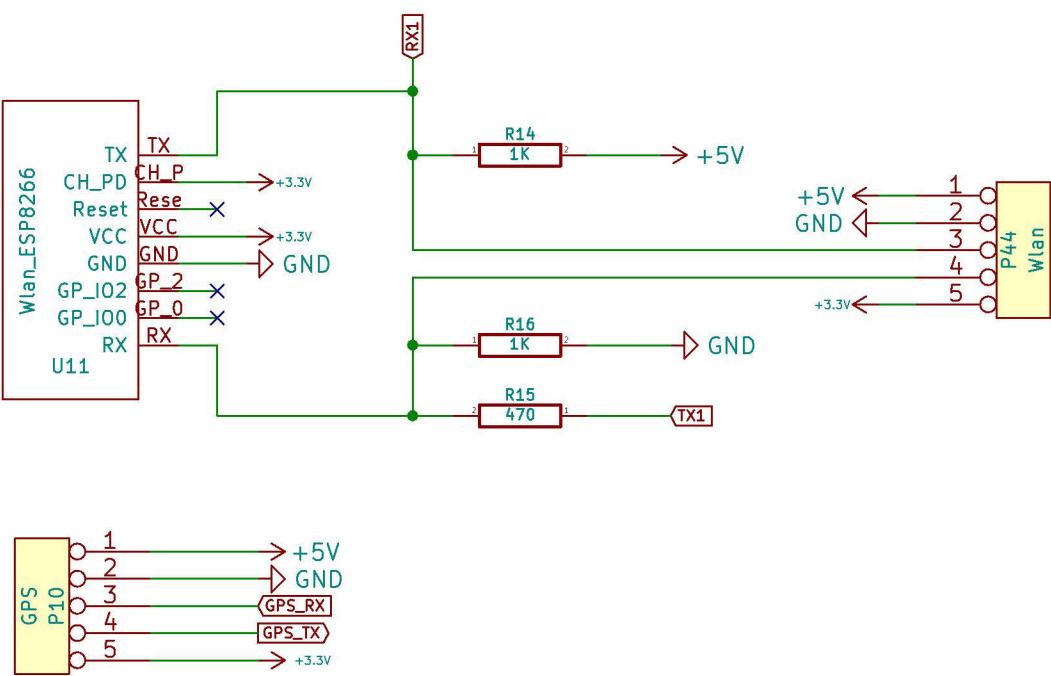
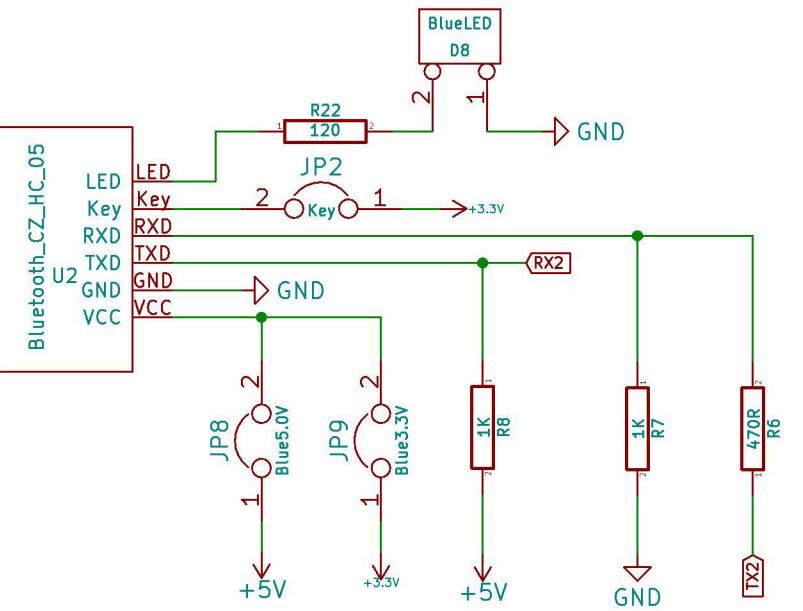


RTC Uhr
von UweZ

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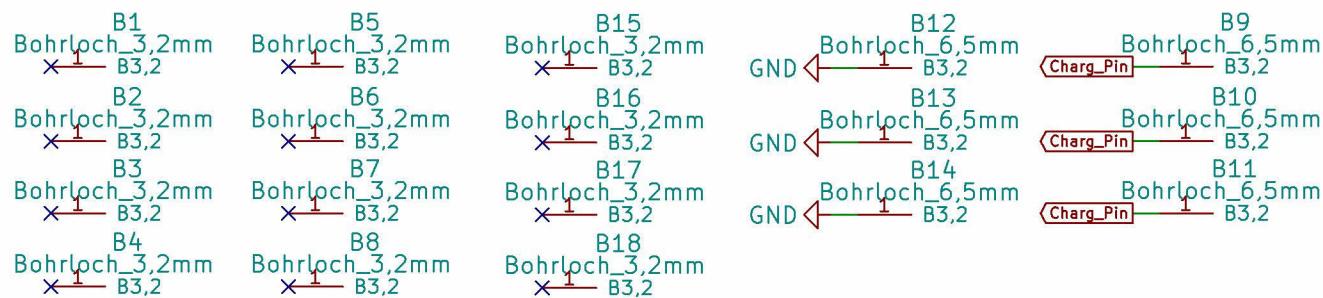
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1 2 3 4 5 6



A

A

B

B

C

C

D

D

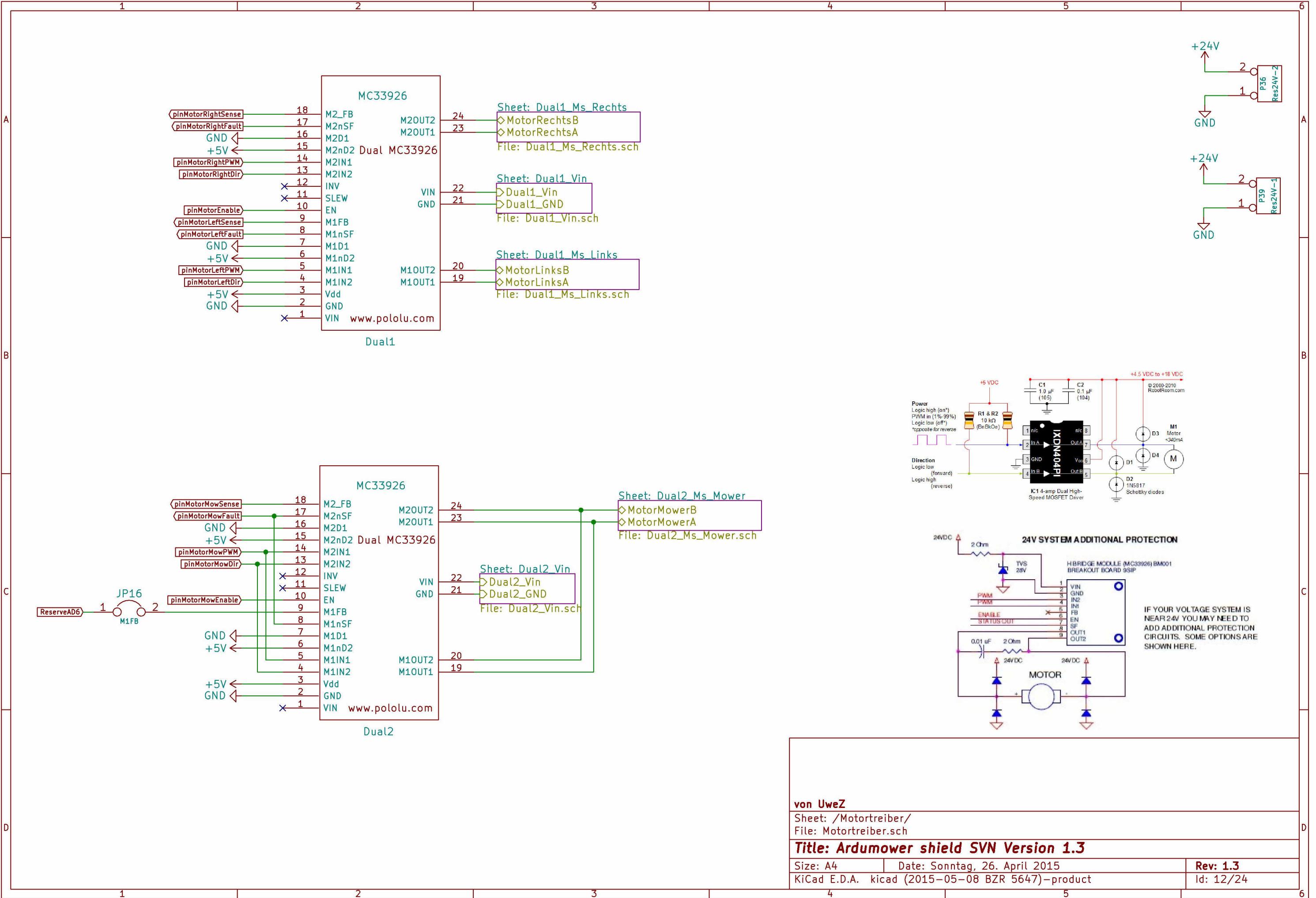
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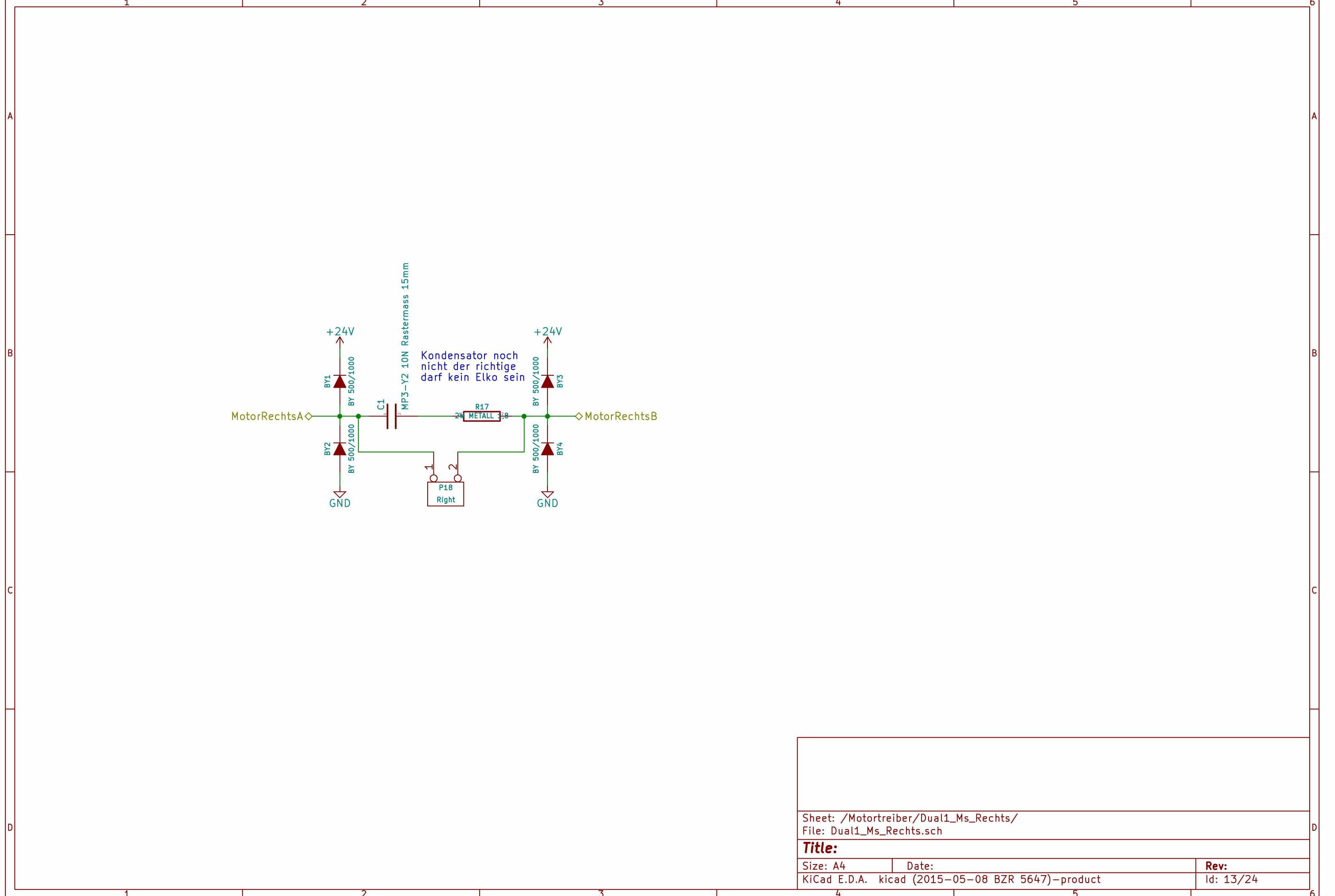
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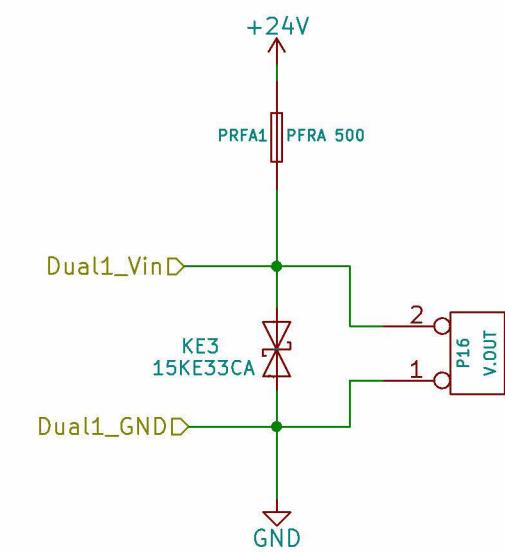




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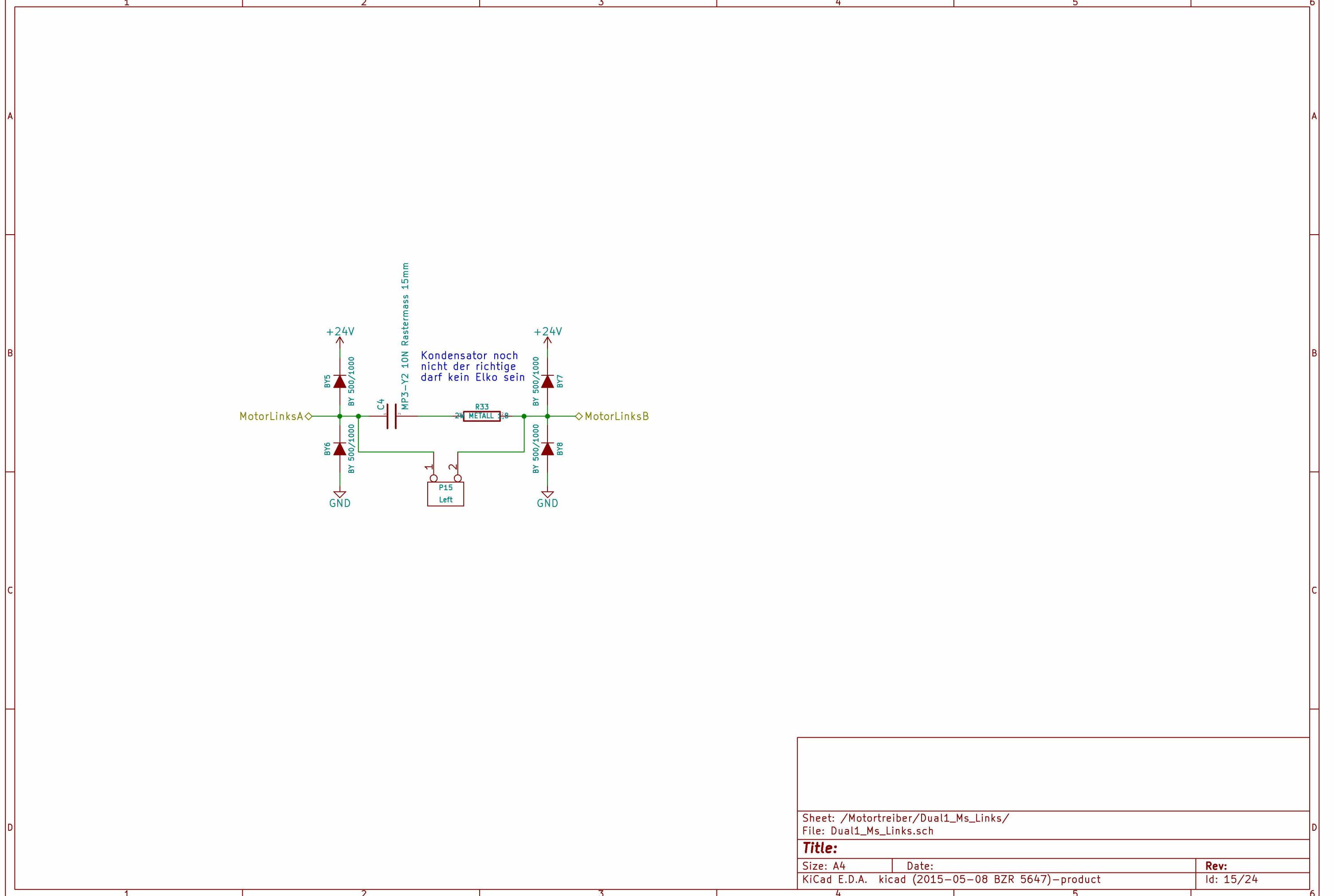
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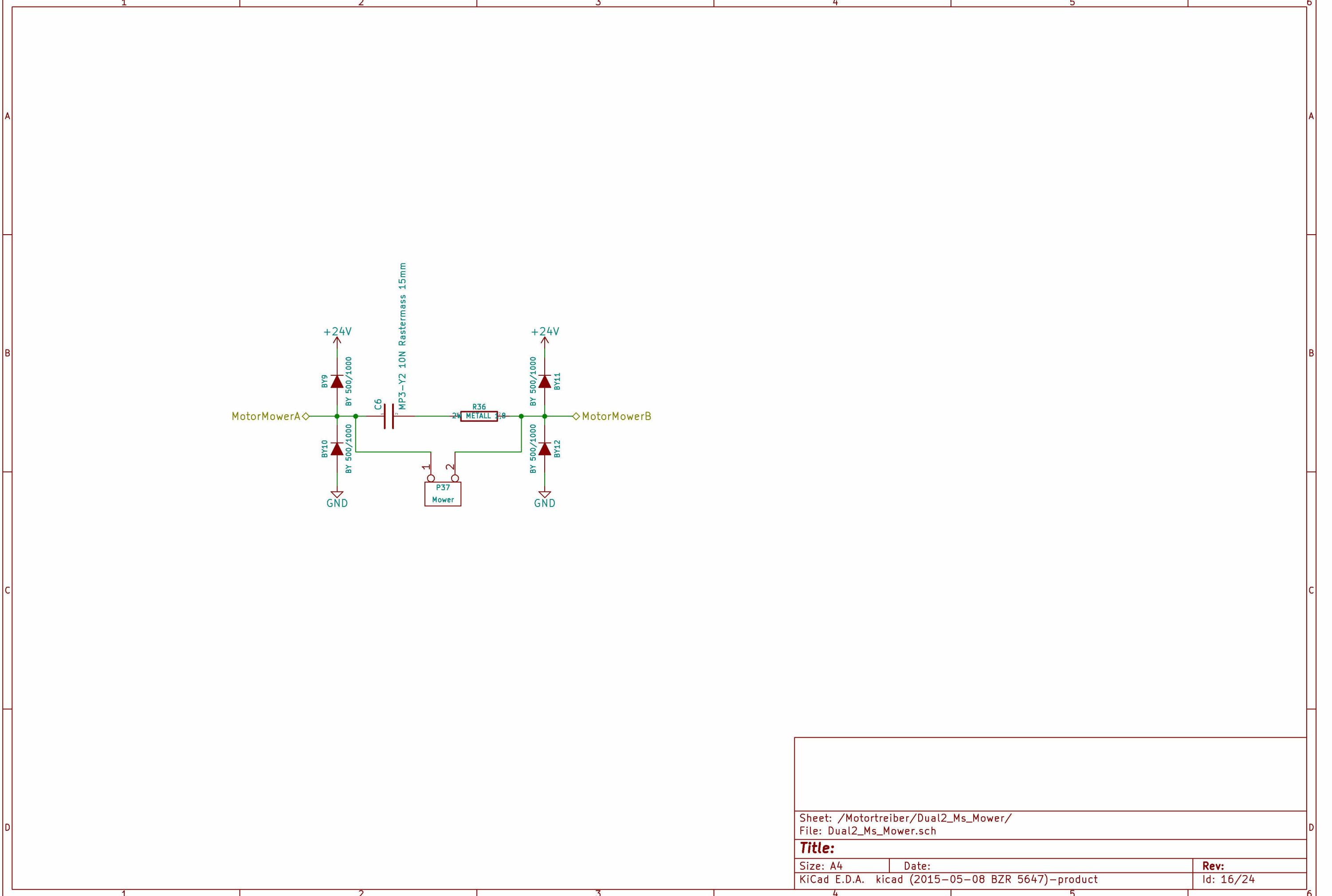


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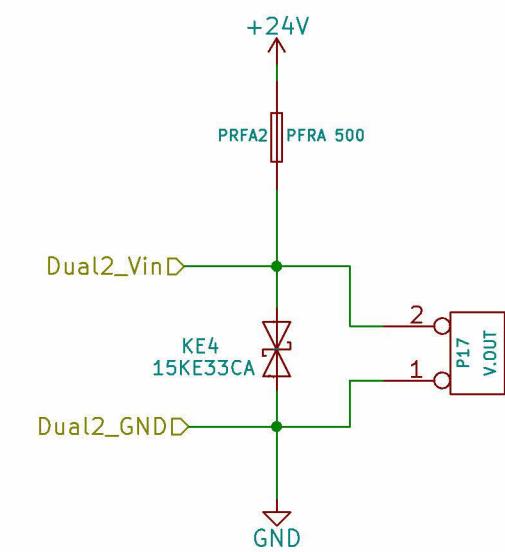
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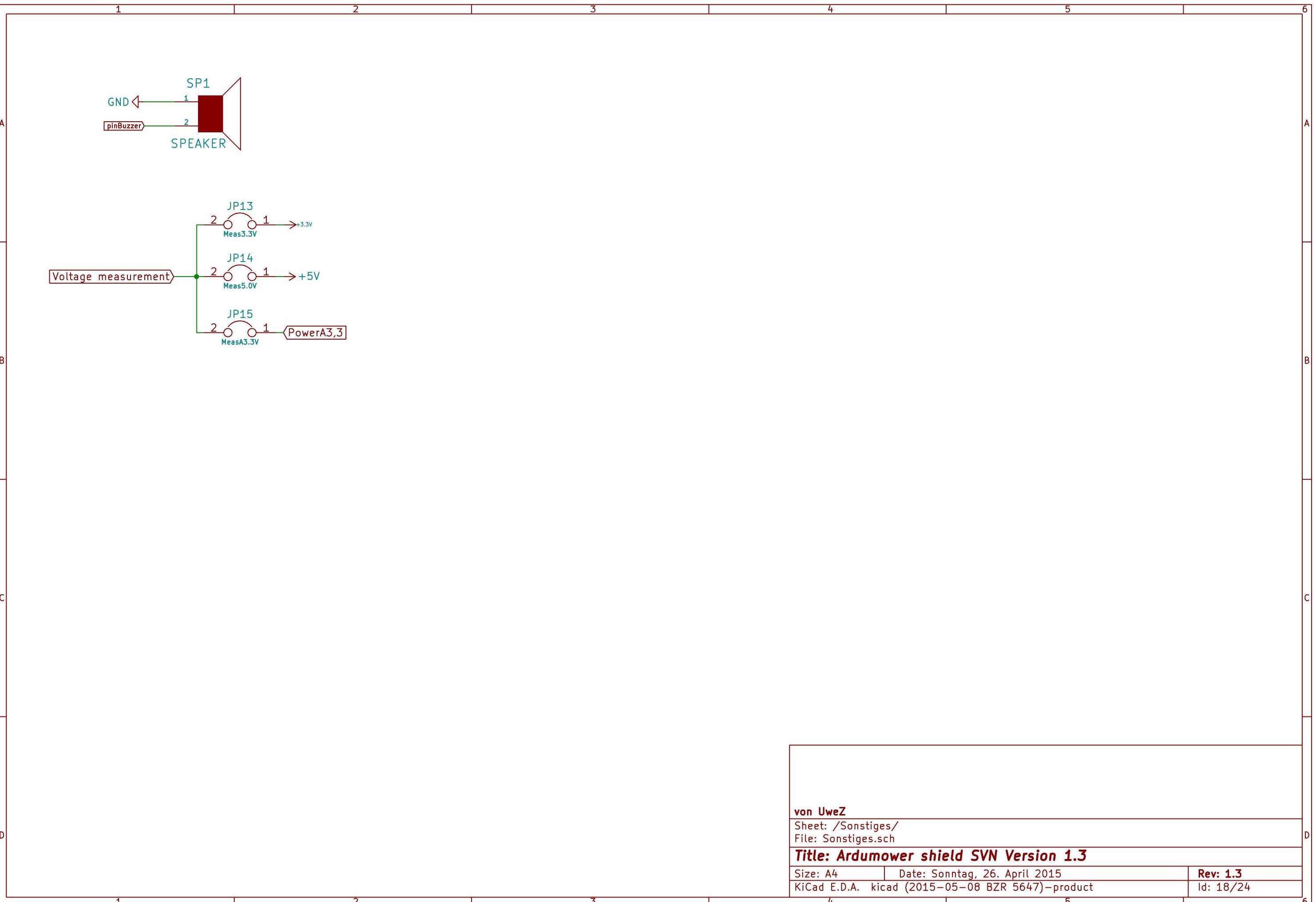
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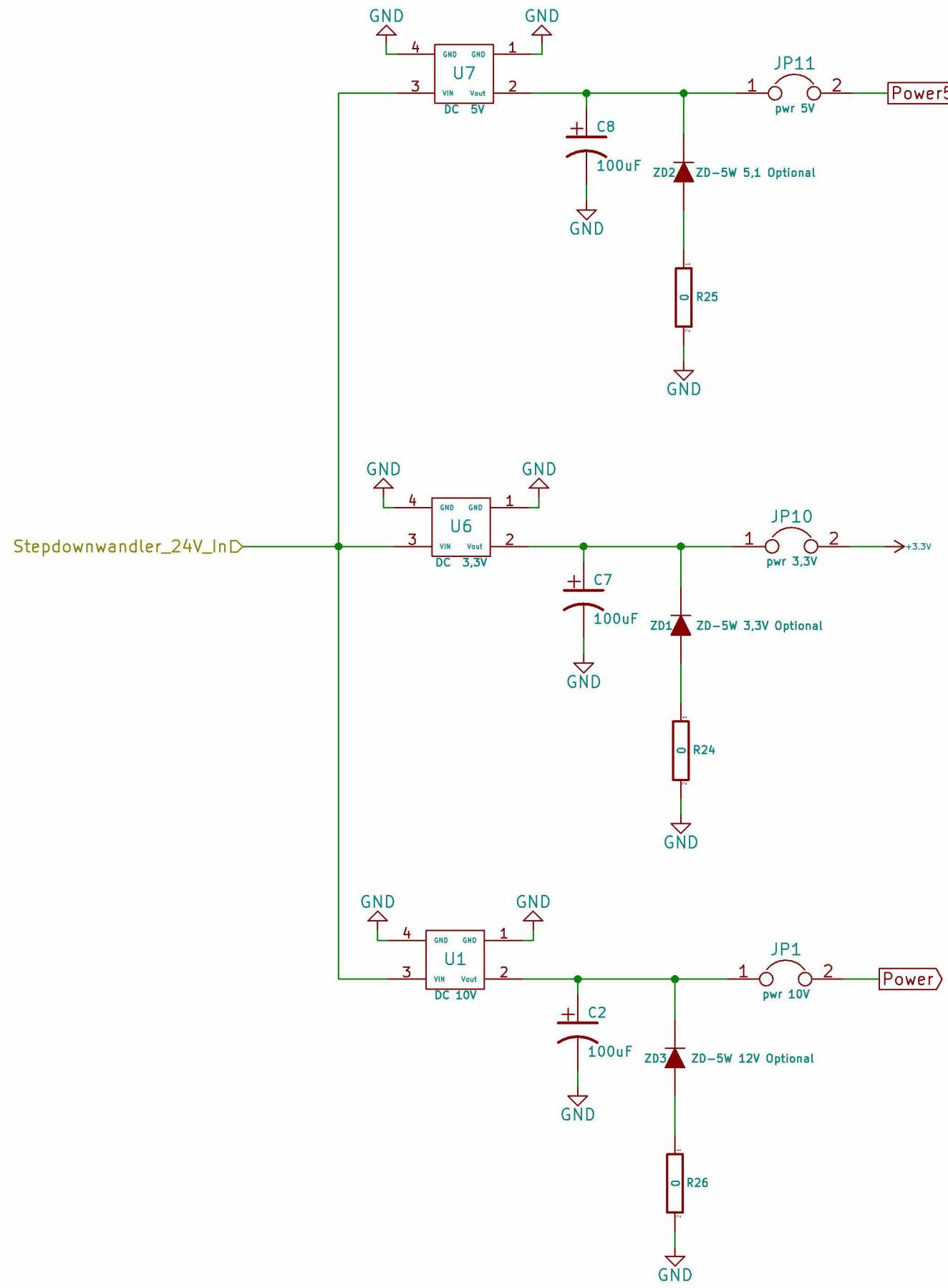


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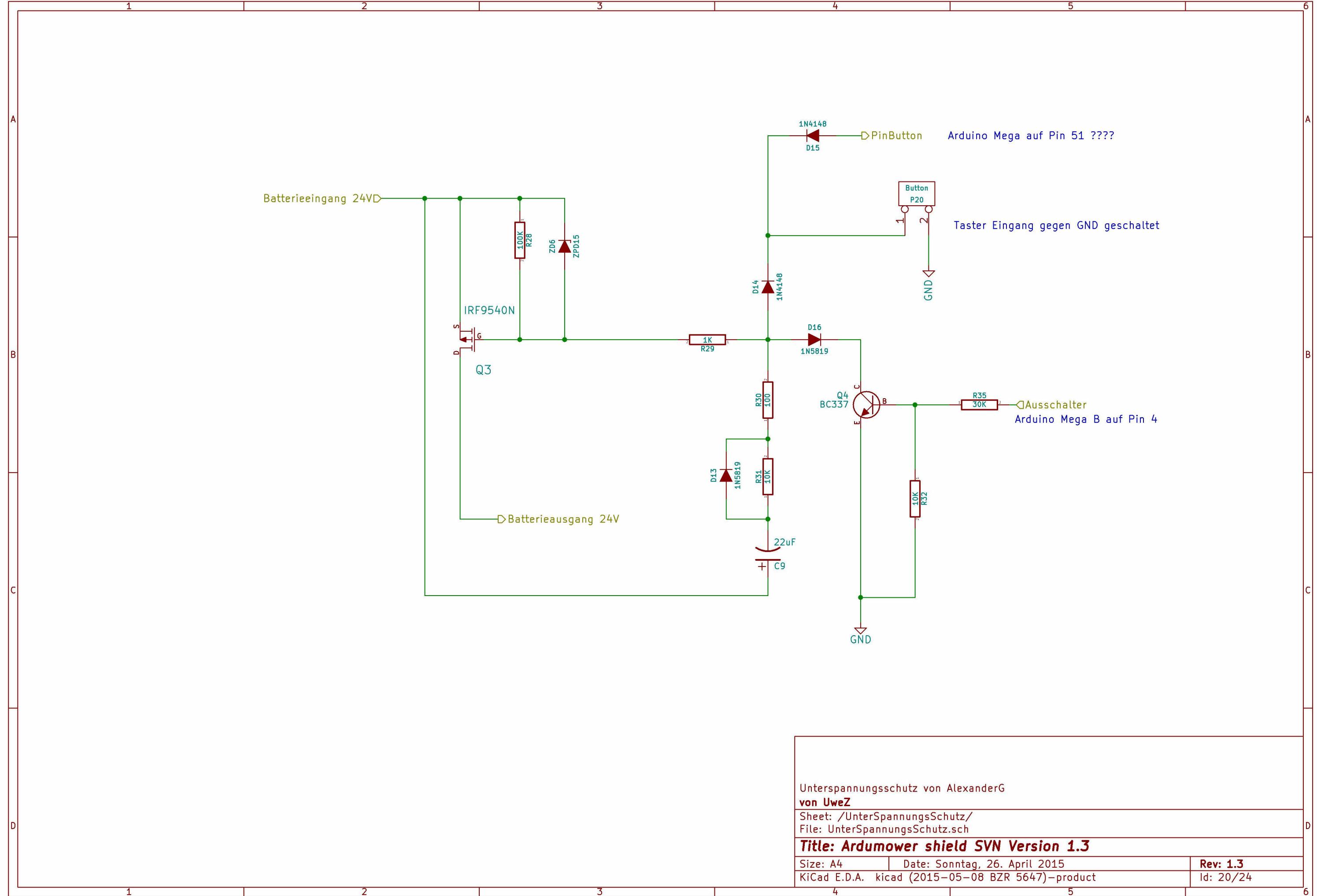


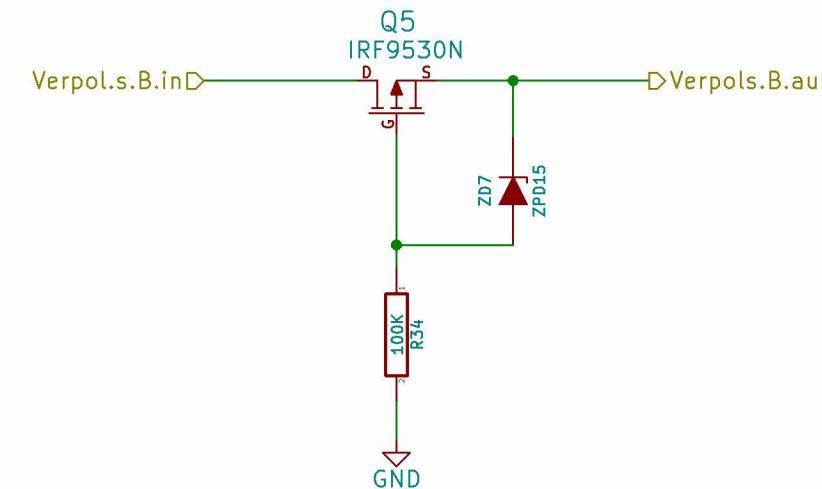
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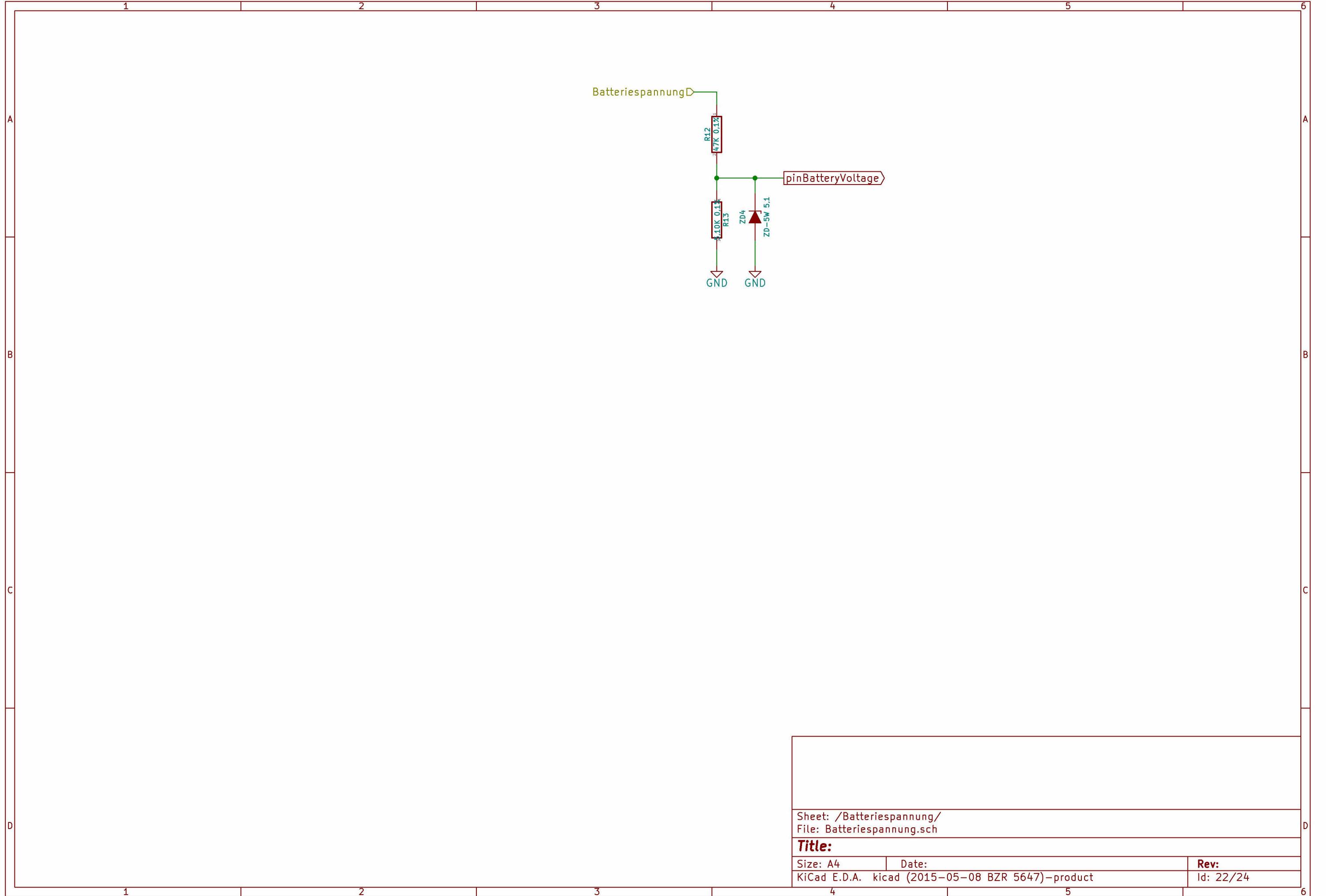


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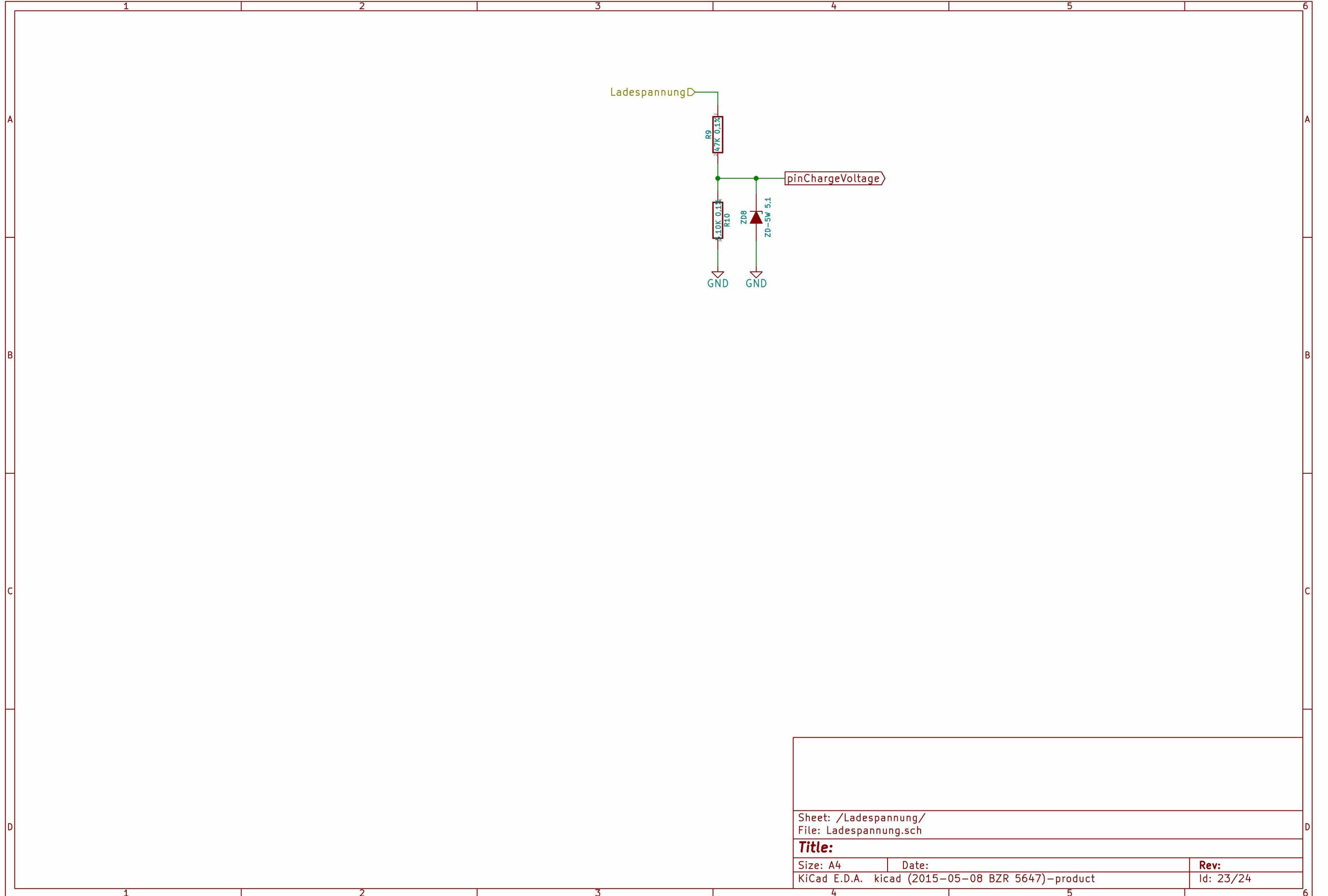
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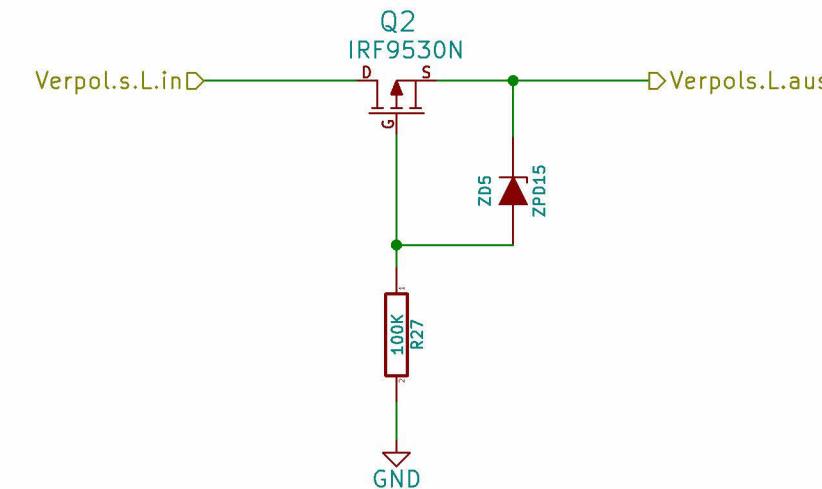
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von UweZ

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