

PythonRobotics: a Python code collection of robotics algorithms

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Abstract

This paper describes an Open Source Software(OSS): PythonRobotics[[1](#)]. This OSS is a Python code collection of robotics algorithms, especially focusing on autonomous navigation. It aims for beginners of robotics to understand basic ideas of each algorithm. The algorithms which is widely used in academia and industry and practical are selected. Each sample code only depends some standard modules on Python 3.x. In this paper, related works of this project, some key ideas about this OSS project, and brief structure of this repository are introduced. I also discuss future works of this project.

1 Introduction

2 Related works

3 Philosophy

In this section, the philosophy of this project is described.

This project aims for beginners of robotics to understand basic ideas of each algorithm. Therefore, the code have to be easy to read and understand the algorithm. Programming language, Python[[2](#)] is adopted in this project because it has good code readability and it allows us to focus on algorithm itself.

The algorithms which is widely used in academia and industry and practical are selected. For example, Kalman filters and particle filter for localization, grid mapping for mapping, dynamic programming based approaches and sampling based approaches for path planning, and optimal control based approach for path tracking.

Each sample code only depends some standard modules on Python 3.x

- Python 3.6.x
- numpy
- scipy
- matplotlib
- pandas

- cvxpy 0.4.x

Easy to read for understanding each algorithm's basic idea.

4 Repository structure

4.1 Localization

4.2 Mapping

4.3 SLAM

4.4 Path planning

4.5 Path tracking

5 Conclusion and future work

In this paper, I introduced an OSS which is a Python code collection of robotics algorithms, especially for autonomous navigation. Related works of this project, some key ideas about this OSS project, and brief structure of this repository were described.

The future works of this project is as followed:

- Technical and mathematical documentation with Jupyter notebook[[1](#)].
- Simple image processing samples for autonomous navigation only using OpenCV[[2](#)].
- Simple multi-robots simulations.

If readers were interested in these future projects, contributions are welcome.

6 Acknowledgments

I appreciate all contributors: Daniel Ingram[[3](#)], Joe Dinius[[5](#)], Karan Chala[[4](#)], Antonin RAFFIN[[6](#)], and Alexis Paques[[8](#)]. This is my GitHub account[[10](#)]

References

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