The following equations were employed in the development of PlateVib in reference to a letter on the vibration analysis of rectangular clamped plates written by J. P. Arenas for the editor of Journal of Sound and Vibration (2003).

Let consider an isotropic, un-damped, rectangular, thin plate with dimension of a (m) by b (m) and h (m) thick. Based on the principle of virtual work, the steady state transverse displacement,  $\xi_0(x,y)$ , of a full clamped plate subjected to harmonic point excitation at (x',y'), is

$$\xi_0(x,y) = F_0 \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \frac{\Psi_{mn}(x,y)\Psi_{mn}(x',y')}{B(I_1I_2 + 2I_3I_4 + I_5I_6) - \rho_s\omega^2 I_2I_6}$$

Here,

 $F_0$ : force amplitude,

 $B = Eh^3/12(1-v^2)$ : bending stiffness,

E: Young's modulus,

v: Poisson ratio,

 $ho_{\scriptscriptstyle S}$  : plate surface density, and

 $\omega$ : angular frequency.

The shape function is given as,

$$\Psi_{mn}(x,y) = \vartheta_m(x)\zeta_n(y)$$

where

$$\vartheta_m(x) = \mathcal{J}(\beta_m x/a) - \frac{\mathcal{J}(\beta_m)}{\mathcal{H}(\beta_m)} \mathcal{H}\left(\frac{\beta_m x}{a}\right); \ \mathcal{J}(s) = \cosh(s) - \cos(s); \ \mathcal{H}(s) = \sinh(s) - \sin(s)$$

and

$$\zeta_n(y) = \mathcal{J}(\beta_n y/b) - \frac{\mathcal{J}(\beta_n)}{\mathcal{H}(\beta_n)} \mathcal{H}(\beta_n y/b)$$

Note that  $\beta_i$  is the i -th root of  $\cosh(\beta) \cos(\beta) = 0$ .

The denominator can be calculated using

$$I_{2}I_{6} = \frac{ab}{\beta_{m}\beta_{n}}\mathcal{L}_{m}\mathcal{L}_{n}; \ I_{3}I_{4} = \frac{\beta_{m}\beta_{n}}{ab}\mathcal{R}_{m}\mathcal{R}_{n}; \ I_{1} = I_{6}(\beta_{m}/a)^{4}; \ I_{5} = I_{2}(\beta_{n}/b)^{4}$$

where

$$\begin{split} \mathcal{L}_{i} &= \frac{\left(1 + \mathcal{D}_{i}^{2}\right)sinh(2\beta_{i})}{4} + sinh(\beta_{i})\left[2\mathcal{D}_{i}\sin(\beta_{i}) - \left(1 - \mathcal{D}_{i}^{2}\right)\cos(\beta_{i})\right] - \left(1 + \mathcal{D}_{i}^{2}\right)sin(\beta_{i})cosh(\beta_{i}) \\ &+ \left(1 - \mathcal{D}_{i}^{2}\right)sin(\beta_{i})cos(\beta_{i}) + \beta_{i} - \frac{\mathcal{D}_{i}[1 + cosh(2\beta_{i})]}{2} + \mathcal{D}_{i}\cos^{2}(\beta_{i}); \; \mathcal{D}_{i} = \frac{\mathcal{J}(\beta_{i})}{\mathcal{H}(\beta_{i})} \end{split}$$

and

$$\mathcal{R}_{i} = \frac{\left(1 + \mathcal{D}_{i}^{2}\right)sinh(2\beta_{i})}{4} - \frac{\mathcal{D}_{i}cosh(2\beta_{i})}{2} - \frac{\left(1 - \mathcal{D}_{i}^{2}\right)sin(\beta_{i})cos(\beta_{i})}{2} - \mathcal{D}_{i}\cos^{2}(\beta_{i}) - \mathcal{D}_{i}^{2}\beta_{i} + \frac{3\mathcal{D}_{i}}{2}$$