### **NAME**

"IO::Async::Process" - start and manage a child process

### **SYNOPSIS**

```
use IO::Async::Process;
 use IO::Async::Loop;
my $loop = IO::Async::Loop->new;
 my $process = IO::Async::Process->new(
    command => [ "tr", "a-z", "n-za-m" ],
    stdin => {
       from => "hello world\n",
    },
    stdout => {
       on_read => sub {
          my (\$stream, \$buffref) = @\_;
          while ( \$buffref = s/^(.*) \n// ) {
             print "Rot13 of 'hello world' is '$1'\n";
          return 0;
       },
    } ,
    on_finish => sub {
      $loop->stop;
    },
 );
 $loop->add( $process );
 $loop->run;
Also accessible via the "open_process" in IO::Async::Loop method:
 $loop->open_process(
    command => [ "/bin/ping", "-c4", "some.host" ],
    stdout => {
       on_read => sub {
         my ( $stream, $buffref, $eof ) = @_;
          while (\$$buffref = s/^(.*)\n//) {
             print "PING wrote: $1\n";
          }
          return 0;
       },
    },
    on_finish => sub {
       my $process = shift;
       my ( \$exitcode ) = @_;
       my \$status = ( \$exitcode >> 8 );
       . . .
    },
 );
```

#### IO::Async::Process(3pm)

### **DESCRIPTION**

This subclass of IO::Async::Notifier starts a child process, and invokes a callback when it exits. The child process can either execute a given block of code (via fork (2)), or a command.

#### **EVENTS**

The following events are invoked, either using subclass methods or CODE references in parameters:

#### on finish \$exitcode

Invoked after the process has exited by normal means (i.e. an exit(2) syscall from a process, or returning from the code block), and has closed all its file descriptors.

```
on_exception $exception, $errno, $exitcode
```

Invoked when the process exits by an exception from code, or by failing to exec(2) the given command. \$errno will be a dualvar, containing both number and string values. After a successful exec() call, this condition can no longer happen.

Note that this has a different name and a different argument order from Loop->open\_process's on\_error.

If this is not provided and the process exits with an exception, then on\_finish is invoked instead, being passed just the exit code.

Since this is just the results of the underlying \$loop->spawn\_child on\_exit handler in a different order it is possible that the \$exception field will be an empty string. It will however always be defined. This can be used to distinguish the two cases:

### **CONSTRUCTOR**

new

```
$process = IO::Async::Process->new( %args )
```

Constructs a new IO::Async::Process object and returns it.

Once constructed, the Process will need to be added to the Loop before the child process is started.

### **PARAMETERS**

The following named parameters may be passed to new or configure:

```
on_finish => CODE
```

#### on exception => CODE

CODE reference for the event handlers.

Once the on\_finish continuation has been invoked, the IO::Async::Process object is removed from the containing IO::Async::Loop object.

The following parameters may be passed to new, or to configure before the process has been started (i.e. before it has been added to the Loop). Once the process is running these cannot be changed.

# IO::Async::Process(3pm)

#### command => ARRAY or STRING

Either a reference to an array containing the command and its arguments, or a plain string containing the command. This value is passed into perl's exec (2) function.

#### code => CODE

A block of code to execute in the child process. It will be called in scalar context inside an eval block.

#### setup => ARRAY

Optional reference to an array to pass to the underlying Loop spawn\_child method.

#### fdn => HASH

A hash describing how to set up file descriptor n. The hash may contain the following keys:

## via => STRING

Configures how this file descriptor will be configured for the child process. Must be given one of the following mode names:

#### pipe read

The child will be given the writing end of a pipe (2); the parent may read from the other.

### pipe\_write

The child will be given the reading end of a pipe (2); the parent may write to the other. Since an EOF condition of this kind of handle cannot reliably be detected, on\_finish will not wait for this type of pipe to be closed.

#### pipe\_rdwr

Only valid on the stdio filehandle. The child will be given the reading end of one pipe (2) on STDIN and the writing end of another on STDOUT. A single Stream object will be created in the parent configured for both filehandles.

#### socketpair

The child will be given one end of a <code>socketpair(2)</code>; the parent will be given the other. The family of this socket may be given by the extra key called <code>family</code>; defaulting to <code>unix</code>. The socktype of this socket may be given by the extra key called <code>socktype</code>; defaulting to <code>stream</code>. If the type is not <code>SOCK\_STREAM</code> then a IO::Async::Socket object will be constructed for the parent side of the handle, rather than IO::Async::Stream.

Once the filehandle is set up, the fd method (or its shortcuts of stdin, stdout or stderr) may be used to access the IO::Async::Handle-subclassed object wrapped around it.

The value of this argument is implied by any of the following alternatives.

### on read => CODE

The child will be given the writing end of a pipe. The reading end will be wrapped by an IO::Async::Stream using this on\_read callback function.

#### into => SCALAR

The child will be given the writing end of a pipe. The referenced scalar will be filled by data read from the child process. This data may not be available until the pipe has been closed by the child.

#### from => STRING

The child will be given the reading end of a pipe. The string given by the from parameter will be written to the child. When all of the data has been written the pipe will be closed.

## prefork => CODE

Only valid for handles with a via of socketpair. The code block runs after the socketpair(2) is created, but before the child is forked. This is handy for when you adjust both ends of the created socket (for example, to use setsockopt(3)) from the controlling parent, before the child code runs. The arguments passed in are the IO::Socket objects for the parent and child ends of the socket.

```
$prefork->( $localfd, $childfd )
```

```
stdin => ...
stdout => ...
stderr => ...
     Shortcuts for fd0, fd1 and fd2 respectively.
```

#### stdio => ...

Special filehandle to affect STDIN and STDOUT at the same time. This filehandle supports being configured for both reading and writing at the same time.

#### **METHODS**

#### pid

```
$pid = $process->pid
```

Returns the process ID of the process, if it has been started, or undef if not. Its value is preserved after the process exits, so it may be inspected during the on\_finish or on\_exception events.

### kill

```
$process->kill( $signal )
```

Sends a signal to the process

### is\_running

```
$running = $process->is_running
```

Returns true if the Process has been started, and has not yet finished.

#### is\_exited

```
$exited = $process->is_exited
```

Returns true if the Process has finished running, and finished due to normal exit (2).

#### exitstatus

```
$status = $process->exitstatus
```

If the process exited due to normal exit (2), returns the value that was passed to exit (2). Otherwise, returns undef.

#### exception

```
$exception = $process->exception
```

If the process exited due to an exception, returns the exception that was thrown. Otherwise, returns undef.

#### errno

```
$errno = $process->errno
```

If the process exited due to an exception, returns the numerical value of \$! at the time the exception was thrown. Otherwise, returns undef.

## errstr

```
$errstr = $process->errstr
```

If the process exited due to an exception, returns the string value of \$! at the time the exception was thrown. Otherwise, returns undef.

#### fd

```
$stream = $process->fd( $fd )
```

Returns the IO::Async::Stream or IO::Async::Socket associated with the given FD number. This must have been set up by a configure argument prior to adding the Process object to the Loop.

The returned object have its read or write handle set to the other end of a pipe or socket connected to that FD number in the child process. Typically, this will be used to call the write method on, to write more data into the child, or to set an on\_read handler to read data out of the child.

The on\_closed event for these streams must not be changed, or it will break the close detection used by the Process object and the on\_finish event will not be invoked.

```
stdin
stdout
stderr
stdio

$stream = $process->stdin

$stream = $process->stdout

$stream = $process->stderr

$stream = $process->stdio
```

Shortcuts for calling fd with 0, 1, 2 or io respectively, to obtain the IO::Async::Stream representing the standard input, output, error, or combined input/output streams of the child process.

### **EXAMPLES**

### Capturing the STDOUT stream of a process

By configuring the stdout filehandle of the process using the into key, data written by the process can be captured.

```
my $stdout;
my $process = IO::Async::Process->new(
   command => [ "writing-program", "arguments" ],
   stdout => { into => \$stdout },
   on_finish => sub {
      my $process = shift;
      my ( $exitcode ) = @_;
      print "Process has exited with code $exitcode, and wrote:\n";
      print $stdout;
   }
);
$loop->add( $process );
```

Note that until on\_finish is invoked, no guarantees are made about how much of the data actually written by the process is yet in the \$stdout scalar.

See also the run\_child method of IO::Async::Loop.

To handle data more interactively as it arrives, the on\_read key can instead be used, to provide a callback function to invoke whenever more data is available from the process.

```
my $process = IO::Async::Process->new(
   command => [ "writing-program", "arguments" ],
   stdout => {
      on_read => sub {
         my ( $stream, $buffref ) = @_;
         while( $$buffref =~ s/^(.*)\n// ) {
            print "The process wrote a line: $1\n";
         }
        return 0;
      },
      on_finish => sub {
        print "The process has finished\n";
      }
);
```

```
$loop->add( $process );
```

If the code to handle data read from the process isn't available yet when the object is constructed, it can be supplied later by using the configure method on the stdout filestream at some point before it gets added to the Loop. In this case, stdin should be configured using pipe\_read in the via key.

```
my $process = IO::Async::Process->new(
   command => [ "writing-program", "arguments" ],
   stdout => { via => "pipe_read" },
   on_finish => sub {
      print "The process has finished\n";
);
$process->stdout->configure(
   on_read => sub {
      my ( $stream, $buffref ) = @_;
      while ( \$buffref = s/^(.*) \n// ) {
         print "The process wrote a line: $1\n";
      }
      return 0;
   },
);
$loop->add( $process );
```

### Sending data to STDIN of a process

By configuring the stdin filehandle of the process using the from key, data can be written into the STDIN stream of the process.

```
my $process = IO::Async::Process->new(
   command => [ "reading-program", "arguments" ],
   stdin => { from => "Here is the data to send\n" },
   on_finish => sub {
      print "The process has finished\n";
   }
);

$loop->add( $process );
```

The data in this scalar will be written until it is all consumed, then the handle will be closed. This may be useful if the program waits for EOF on STDIN before it exits.

To have the ability to write more data into the process once it has started. the write method on the stdin stream can be used, when it is configured using the pipe\_write value for via:

```
my $process = IO::Async::Process->new(
   command => [ "reading-program", "arguments" ],
   stdin => { via => "pipe_write" },
   on_finish => sub {
      print "The process has finished\n";
   }
);

$loop->add( $process );

$process->stdin->write( "Here is some more data\n" );
```

### **Setting socket options**

By using the prefork code block you can change the socket receive buffer size at both ends of the socket before the child is forked (at which point it would be too late for the parent to be able to change the child end of the socket).

```
use Socket qw( SOL_SOCKET SO_RCVBUF );

my $process = IO::Async::Process->new(
    command => [ "command-to-read-from-and-write-to", "arguments" ],
    stdio => {
        via => "socketpair",
        prefork => sub {
            my ( $parentfd, $childfd ) = @_;

            # Set parent end of socket receive buffer to 3 MB
            $parentfd->setsockopt(SOL_SOCKET, SO_RCVBUF, 3 * 1024 * 1024);
            # Set child end of socket receive buffer to 3 MB
            $childfd ->setsockopt(SOL_SOCKET, SO_RCVBUF, 3 * 1024 * 1024);
        },
    },
},
};
$loop->add( $process );
```

### **AUTHOR**

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