

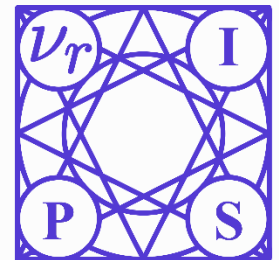
Deep Multi-State Dynamic Recurrent Neural Networks Operating on Wavelet Based Neural Features for Robust Brain Machine Interfaces

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Applications of BMI

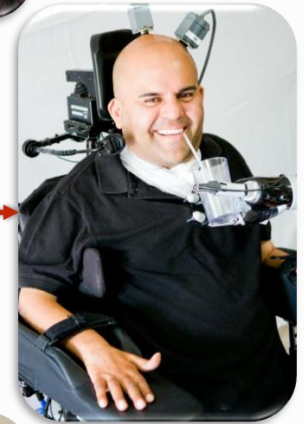
Controlling a prosthesis



Spelling



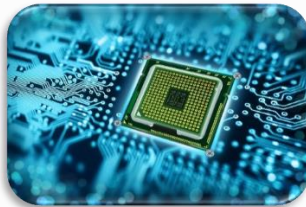
Controlling a Mechatronic Device



Brain Signal



Tiny Chip



Virtual Reality



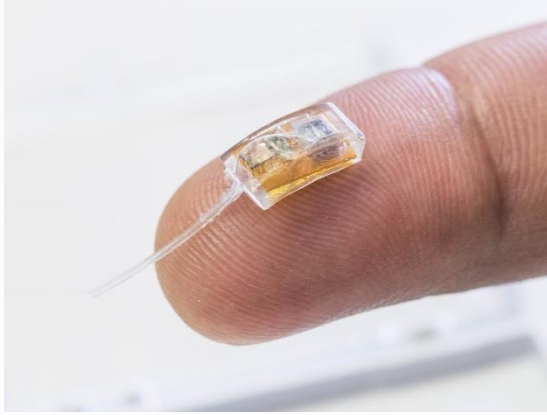
Gaming



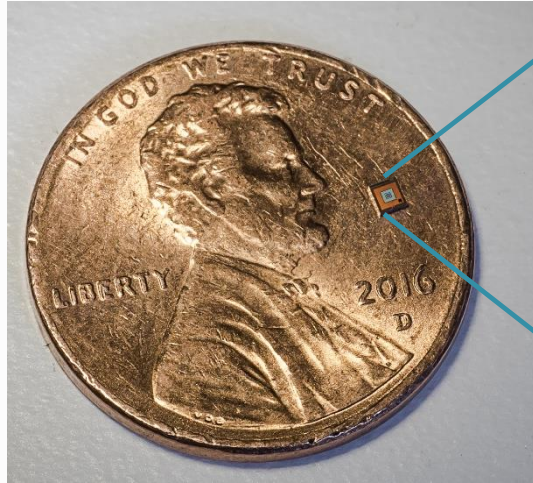
A Sci-Fi Becomes Reality



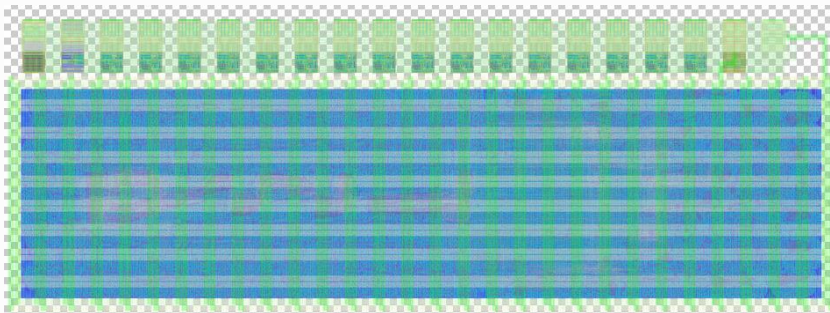
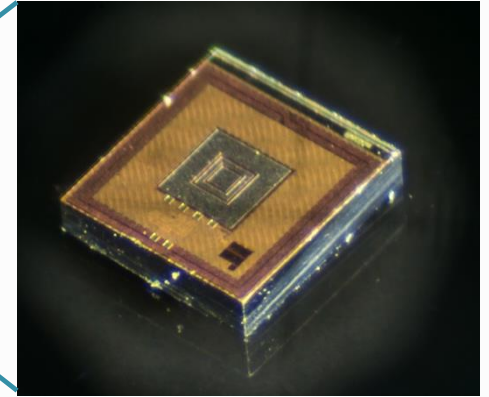
Implantable Wireless Medical Devices



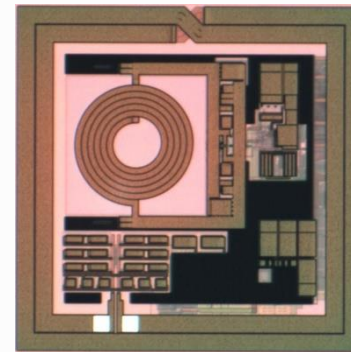
Intra-Ocular Pressure Sensor



Injectable Glucose Sensor



1mm x 0.5mm classifier CMOS chip for seizure prediction



ATOMS, Smart Pill



External Reader

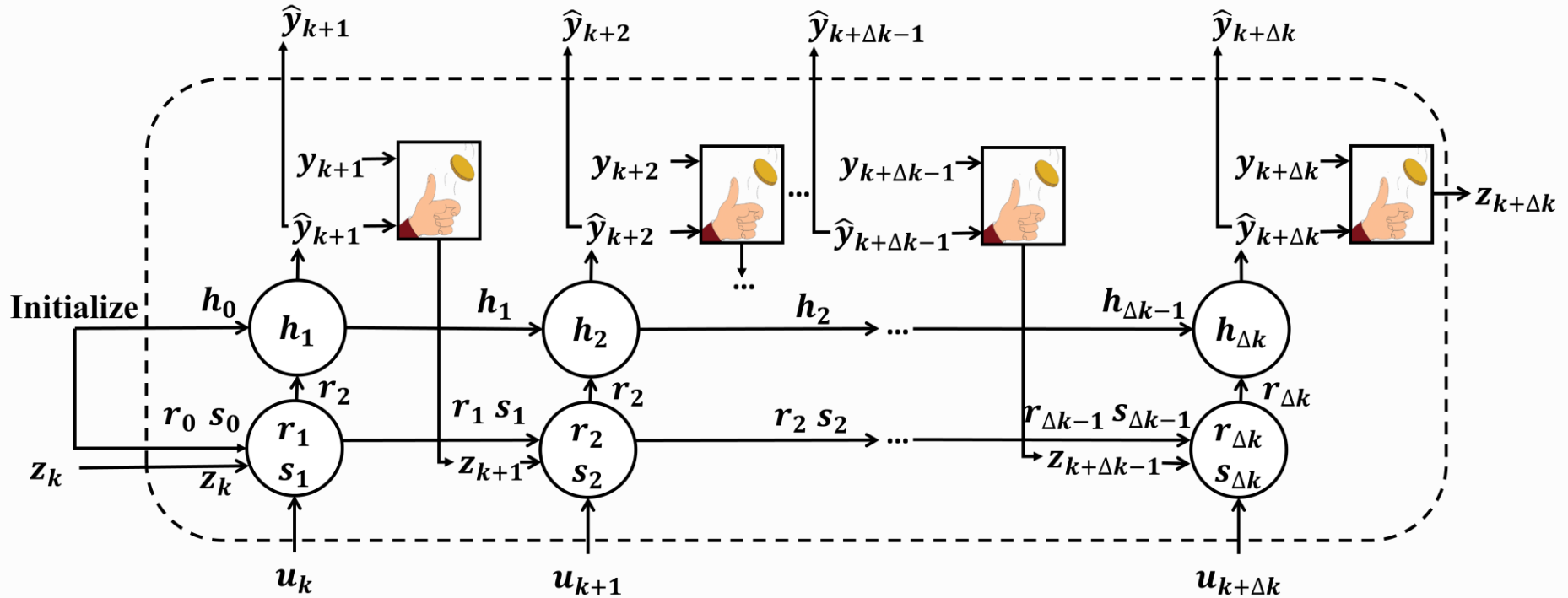
Goals

- Minimize Treatment Cost
- Low Power/Area Chip
- Robustness
- High Performance

Challenges

- Achieving High Speed Design
- Non-Stationarity of Neural Data
- Noise
- Limited Data

Deep Multi-state DRNN Architecture



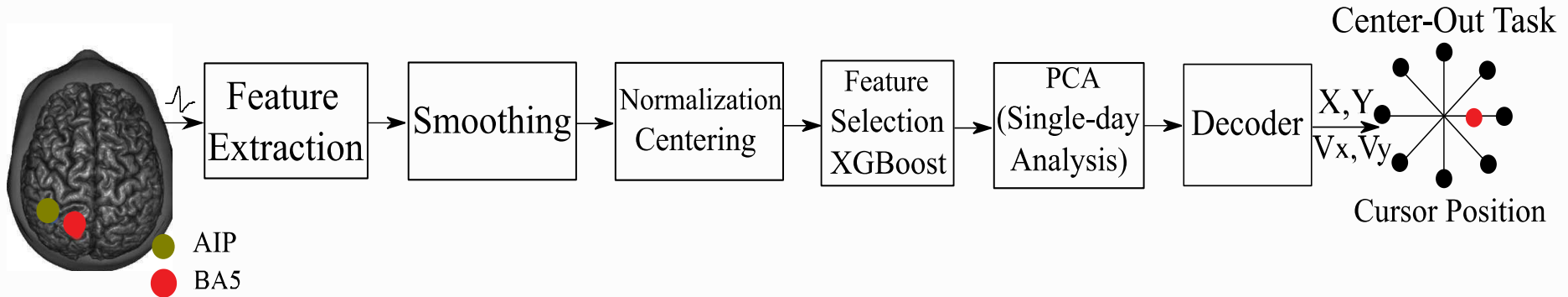
$$\begin{cases} s_k = W_{ss}s_{k-1} + W_{sr}r_{k-1} + W_{si}u_k + W_{sf}z_k + b_s \\ r_k = \tanh(s_k) \\ h_k^{(1)} = \tanh(W_{h^{(1)}h^{(1)}}h_{k-1}^{(1)} + W_{h^{(1)}r}r_k + b_{h^{(1)}}) \\ h_k^{(i)} = \tanh(W_{h^{(i)}h^{(i)}}h_{k-1}^{(i)} + W_{h^{(i)}h^{(i-1)}}h_k^{(i-1)} + b_{h^{(i)}}) \\ \hat{y}_k = W_{yh^{(l)}}h_k^{(l)} + b_y \\ \hat{y}_k = \tanh(\hat{y}_k) \quad |\hat{y}_k| > 1 \\ z_k \leftarrow \hat{y}_k \text{ or } y_k \text{ (Scheduled Sampling)} \end{cases}$$

Architecture of BMI System

- 32 year-old tetraplegic (C5-C6) human
- FDA- and IRB-approved

- Sampling Rate: 30 KHz
- Utah electrode arrays

192 Channels



AIP: Anterior Intraparietal
BA5: Broadman's Area 5

Features	Frequency Range
HWT, HFT, HPF	> 3.75KHz
TCs, LFADS	250Hz – 5KHz
MWT, MFT, MUA	234Hz – 3.75KHz
LWT, LFT, LPF	< 234HZ

Single-day Analysis with Mid-Wavelet Feature

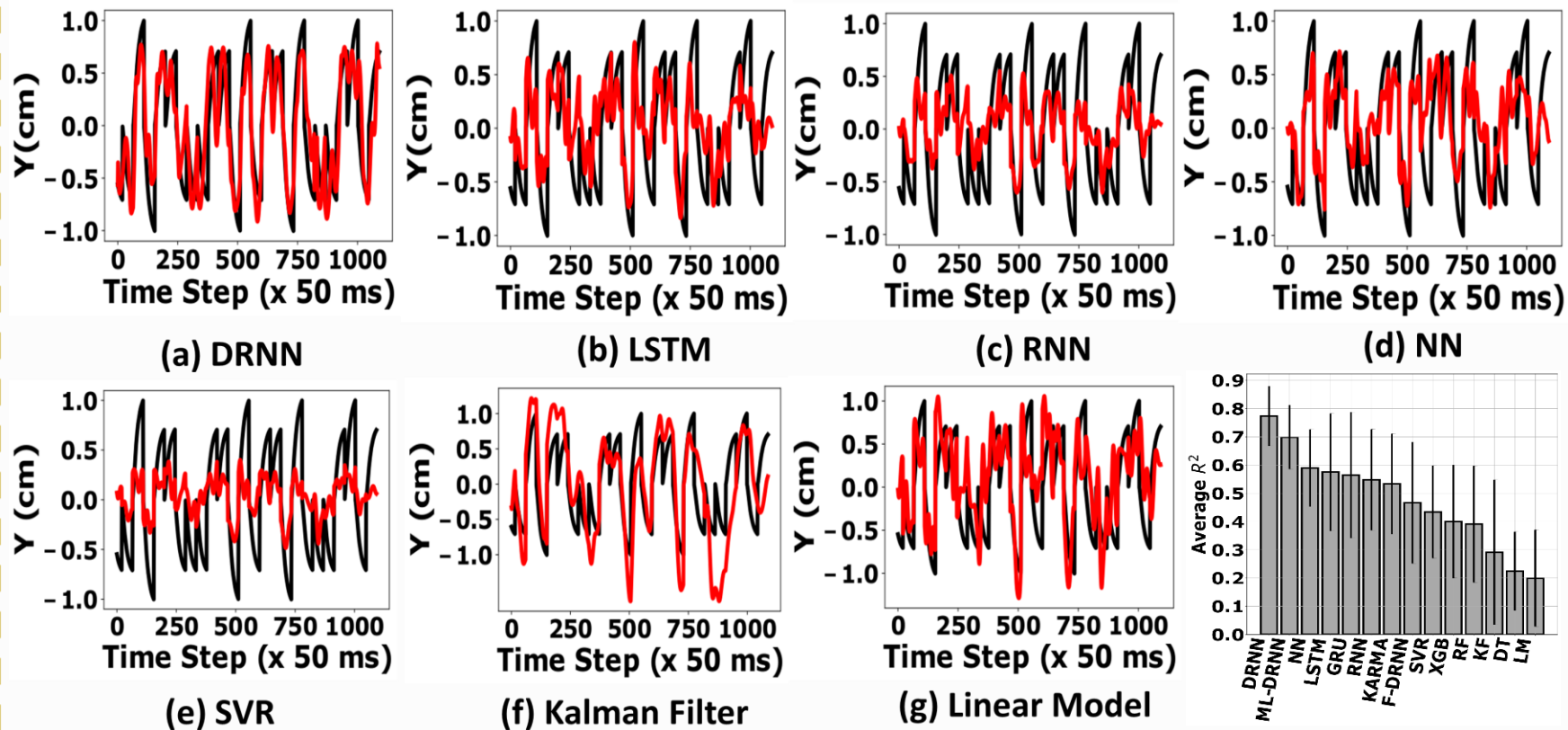


Fig.1. Regression of different algorithms on test data from the same day 2018-04-23: true target motion (black) and reconstruction (red)

Multi-Day Performance of the Decoders

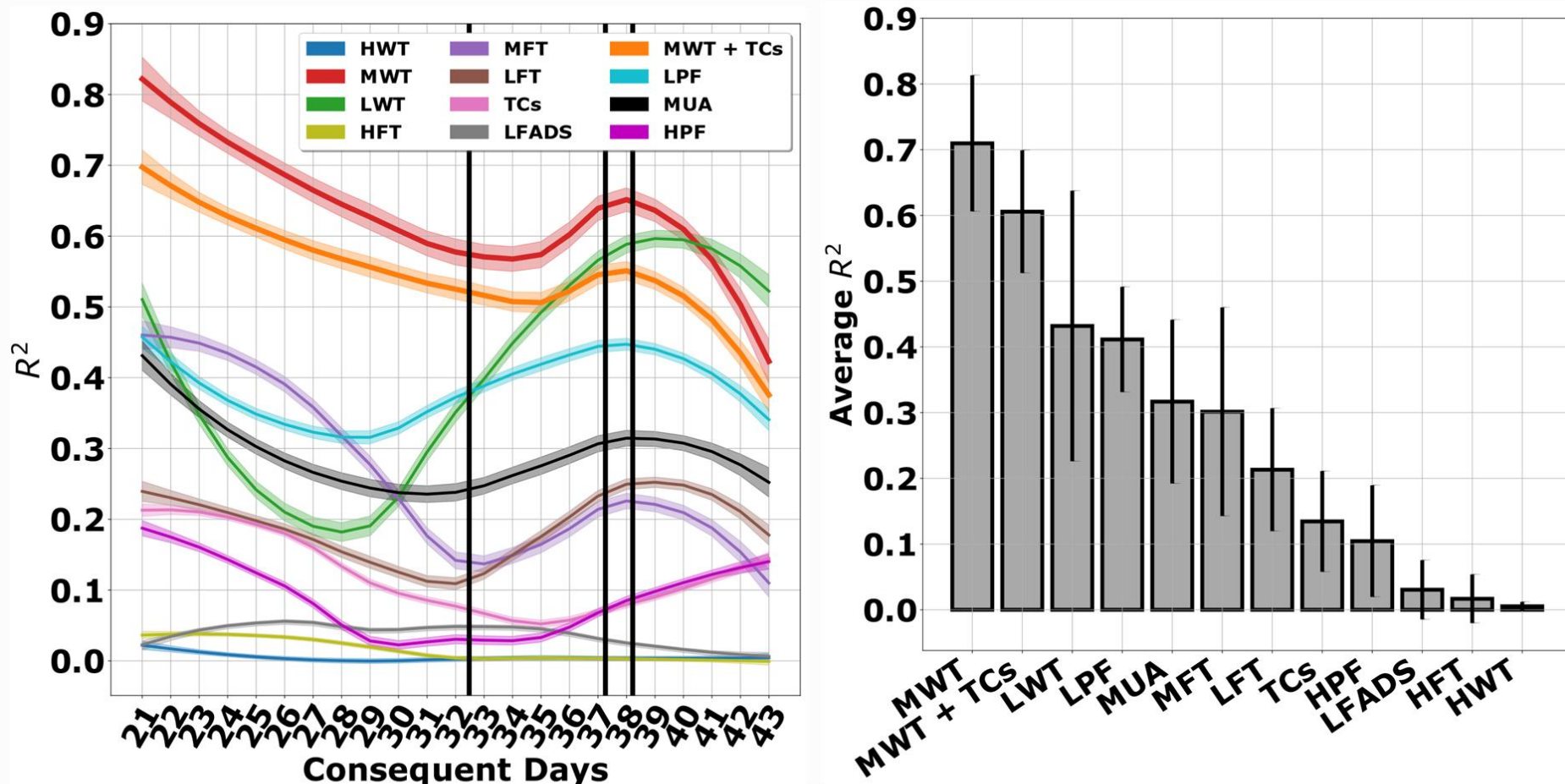


Fig.2. The DRNN operating on different features.

Multi-Day Performance of the Decoders

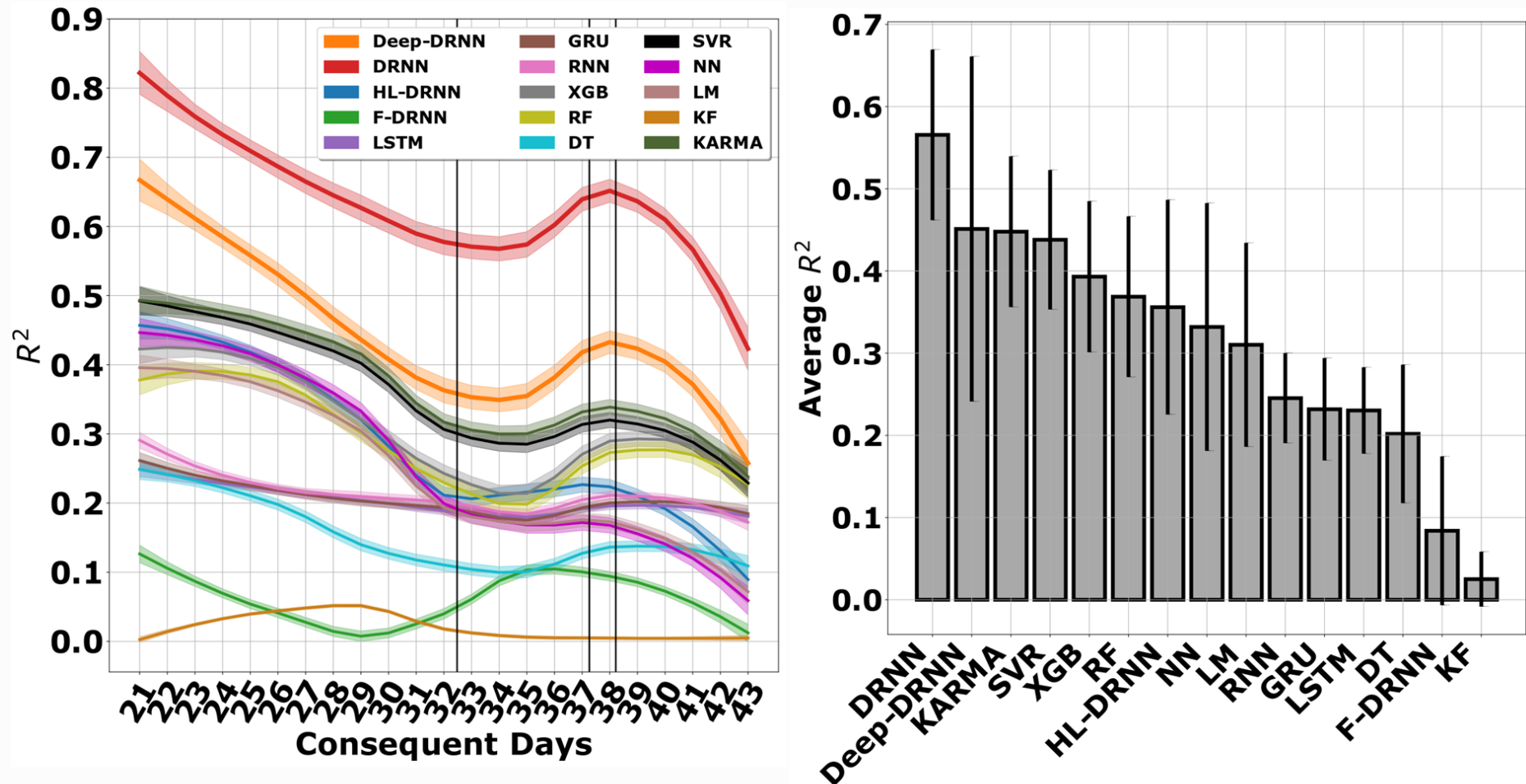


Fig.3. Multi-day performance of the decoders.

Multi-Day Performance of the Decoders

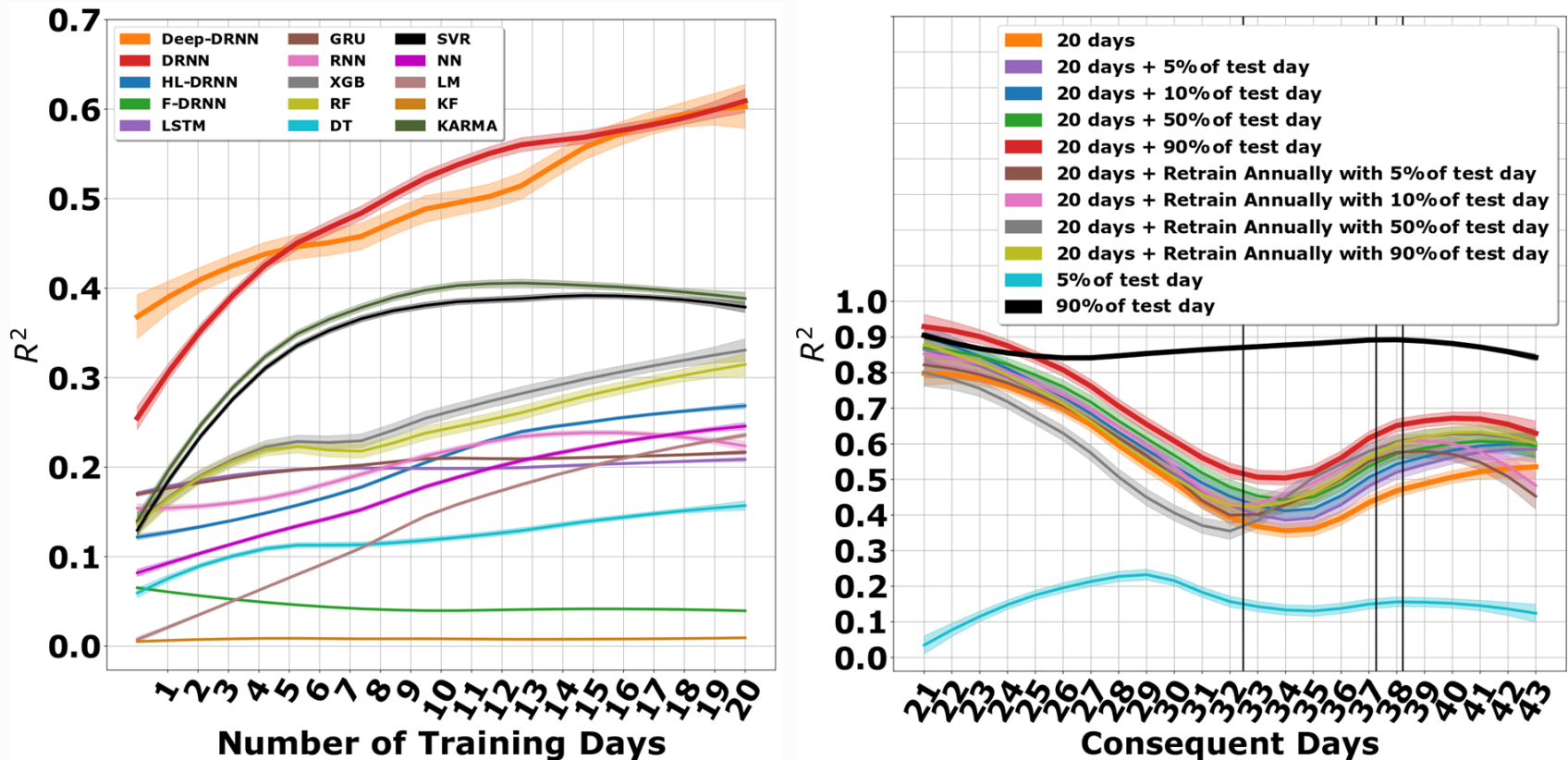
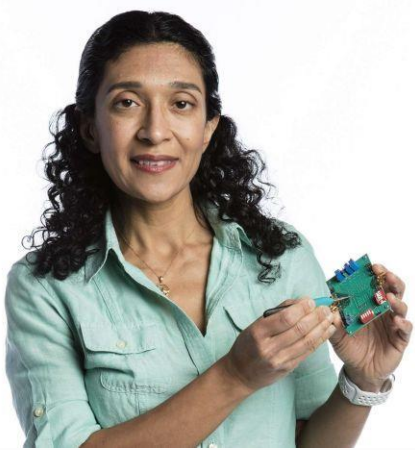


Fig.4. (Left) Effect of number of training days on the performance of the decoders. (Right) The DRNN operating in different training scenarios.

Summary

- Neural networks for BMI: promising
- Hardware requirements of NN: challenges toward implantable devices
- Algorithms that can translate to energy-efficient hardware
- Need to deal with significant variations and non-stationary conditions

Team Members



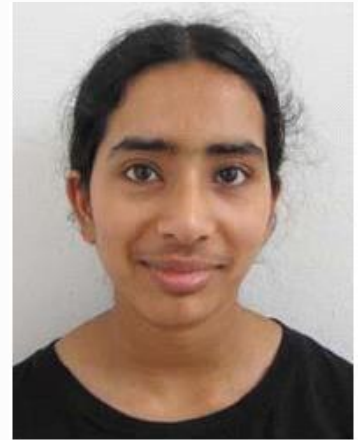
Azita Emami



Benyamin Haghi



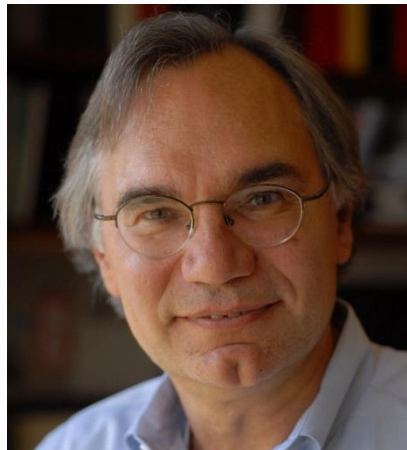
Sahil Shah



Maitreyi Ashok



Spencer Kellis



Richard Andersen



Luke Bashford

Thank you!

- **Paper:**

<https://www.biorxiv.org/content/biorxiv/early/2019/08/30/710327.full.pdf>

- **Codes, Poster, and Slides:**

<https://github.com/BenyaminHaghi/DRNN-NeurIPS2019>

