



# Introduction to Optimization Modeling in Python



Juan Javaloyes & Daniel Vázquez  
February 2020

# Contents

- ▶ **Install PYOMO and solvers**
- ▶ **Mathematical Programming Background**
- ▶ **Introduction to Python**
- ▶ **PYOMO Components**
- ▶ **Case Studies**

<https://github.com/CAChemE/>

# Install PYOMO and Solvers

## PYOMO

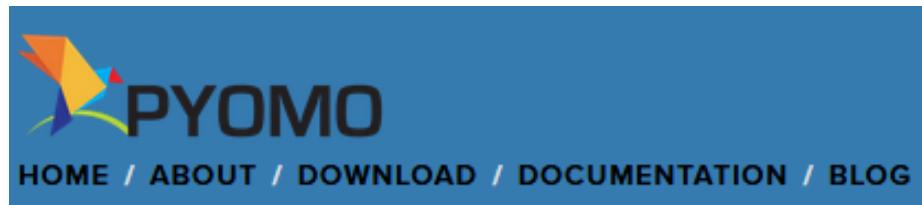
- conda install -c conda-forge pyomo
- conda install -c conda-forge pyomo.extras  
<http://www.pyomo.org/installation/>

## SOLVERS

- glpk [LP, MILP] >> conda install -c conda-forge glpk  
<http://ftp.gnu.org/gnu/glpk/>
- gurobi [LP, MILP] >> download and install. Free university license  
<http://www.gurobi.com/>
- IPOPT [NLP] >> conda install -c conda-forge ipopt  
<https://www.coin-or.org/download/binary/>
- SCIP [MINLP] >> download and add the solver installation to the path environment variable  
<http://scip.zib.de/#download>

# PYOMO Sources

## Homepage:



<http://www.pyomo.org/>



<https://software.sandia.gov/trac/pyomo>

## Book Reference

Springer Optimization and Its Applications 67

William E. Hart  
Carl D. Laird  
Jean-Paul Watson  
David L. Woodruff  
Gabriel A. Hackebeil  
Bethany L. Nicholson  
John D. Siirola

Pyomo —  
Optimization  
Modeling  
in Python

*Second Edition*

Springer

# PYOMO Sources

## GitHub

<https://github.com/Pyomo>

## Help Forums

<https://groups.google.com/forum/#!forum/pyomo-forum>

## Stack Overflow

<https://stackoverflow.com/questions/tagged/pyomo>

# Mathematical Programming Background

# Mathematical Programming

## Classes of Optimization Problems

$$\min \quad f_0(x) \quad \leftarrow \text{Objective Function}$$

$$s.t \quad f_i(x) \leq b_i \quad i = 1, \dots, m. \quad \leftarrow \text{Constraints}$$

$$x \in \mathbb{R}^n$$

$$f_0(x) : \mathbb{R}^n \rightarrow \mathbb{R}, f_i(x) : \mathbb{R}^n \rightarrow \mathbb{R}$$

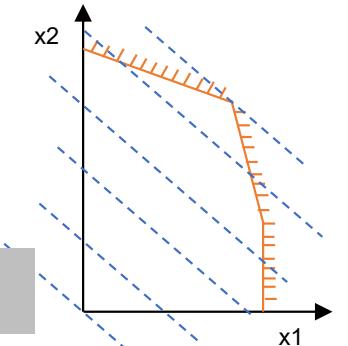
$$f_i(\alpha x_1 + \beta x_2) = xf_i(x_1) + \beta f_i(x_2) \quad x_1, x_2 \in \mathbb{R}^n$$

$\alpha, \beta \in \mathbb{R}$

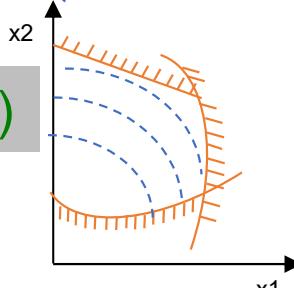
$$f_i(\alpha x_1 + \beta x_2) \neq xf_i(x_1) + \beta f_i(x_2) \quad x_1, x_2 \in \mathbb{R}^n$$

$\alpha, \beta \in \mathbb{R}$

**← Linear Program (LP)**



**← Nonlinear Program (NLP)**



---


$$f_i(\alpha x_1 + \beta x_2) \leq xf_i(x_1) + \beta f_i(x_2) \quad x_1, x_2 \in \mathbb{R}^n$$

$\alpha, \beta \in \mathbb{R}$  with  $\alpha + \beta = 1, \alpha, \beta \geq 0$

**← Convex Optimization**

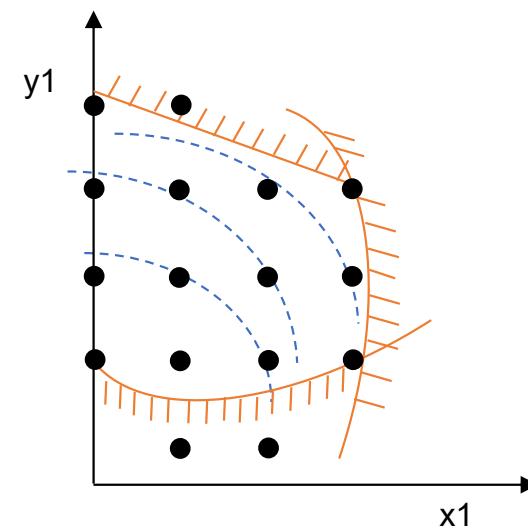
# Mathematical Programming

## Classes of Optimization Problems

$$\begin{array}{ll} \min & f_0(x, y) \\ s.t & f_i(x, y) \leq b_i \quad i = 1, \dots, m. \\ & x \in R^n, \quad y \in \{0,1\}^q \end{array}$$

← Objective Function  
← Constraints  
← Mixed-Integer (Non) Linear Programming (MI(N)LP)

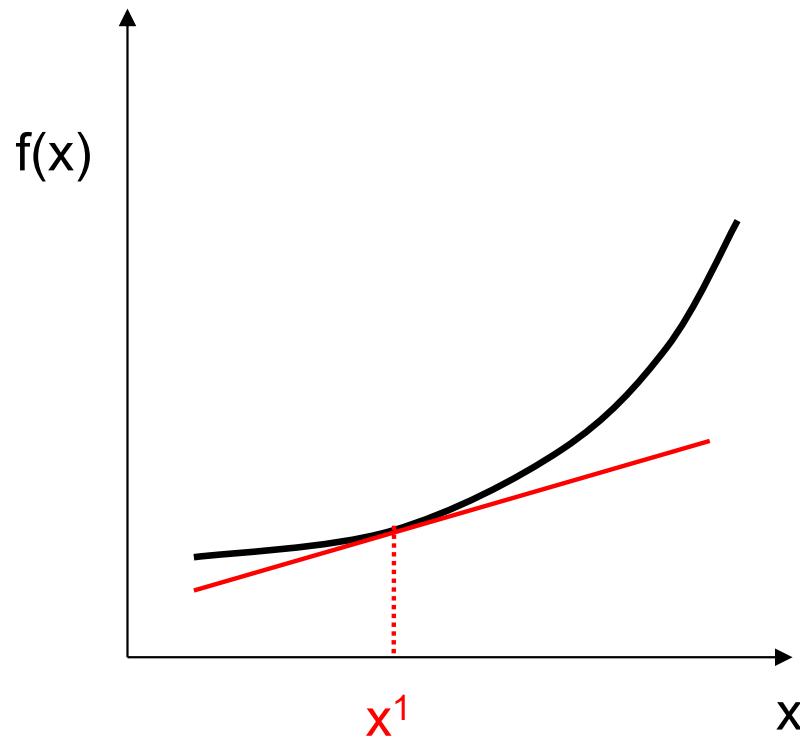
$$f_0(x, y) : R^n \rightarrow R, \quad f_i(x, y) : R^n \rightarrow R$$



# Mathematical Programming

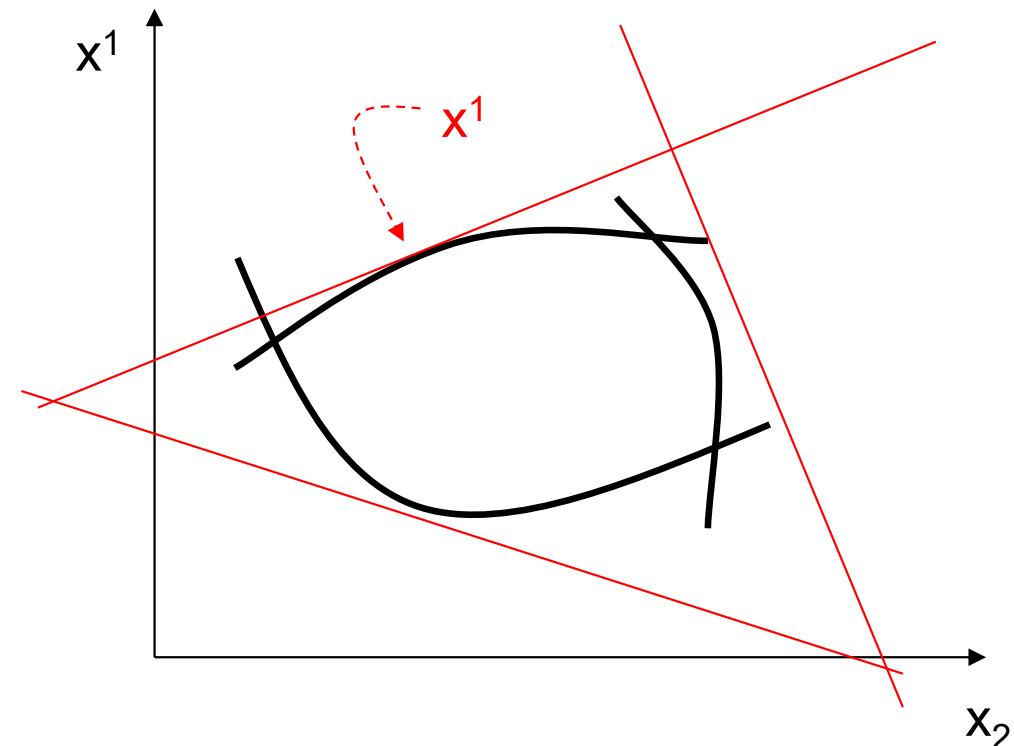
## Classes of Optimization Problems – Convex Problems

Convex objective function



Sub-estimation of the  
Objective function

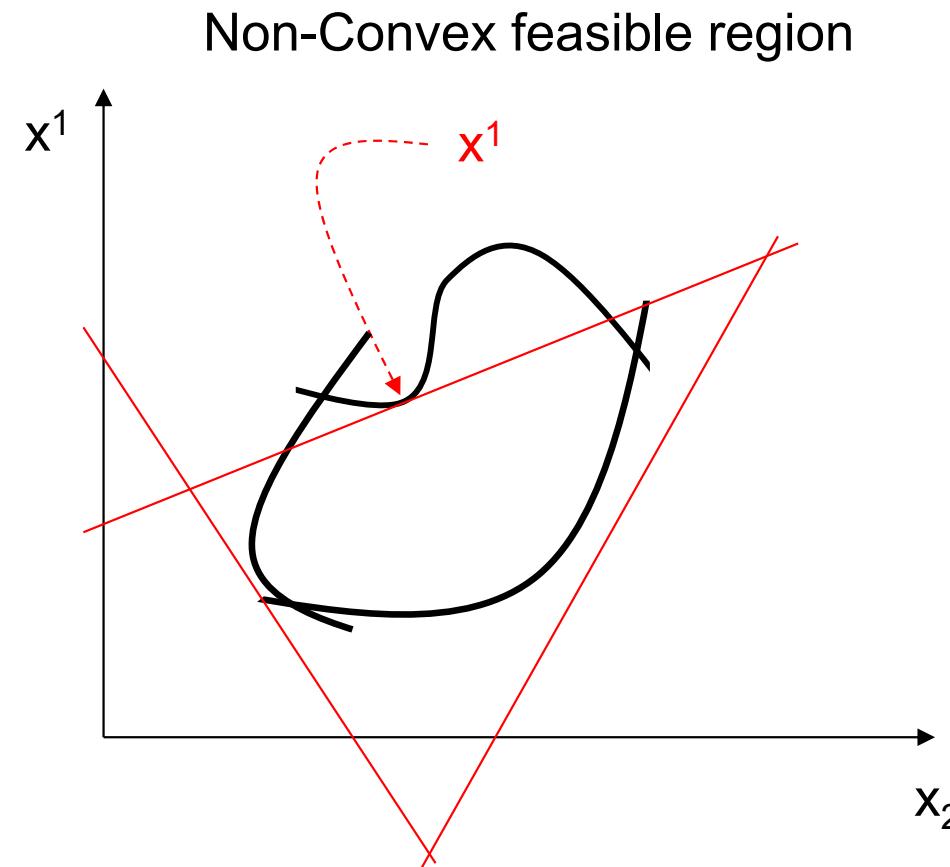
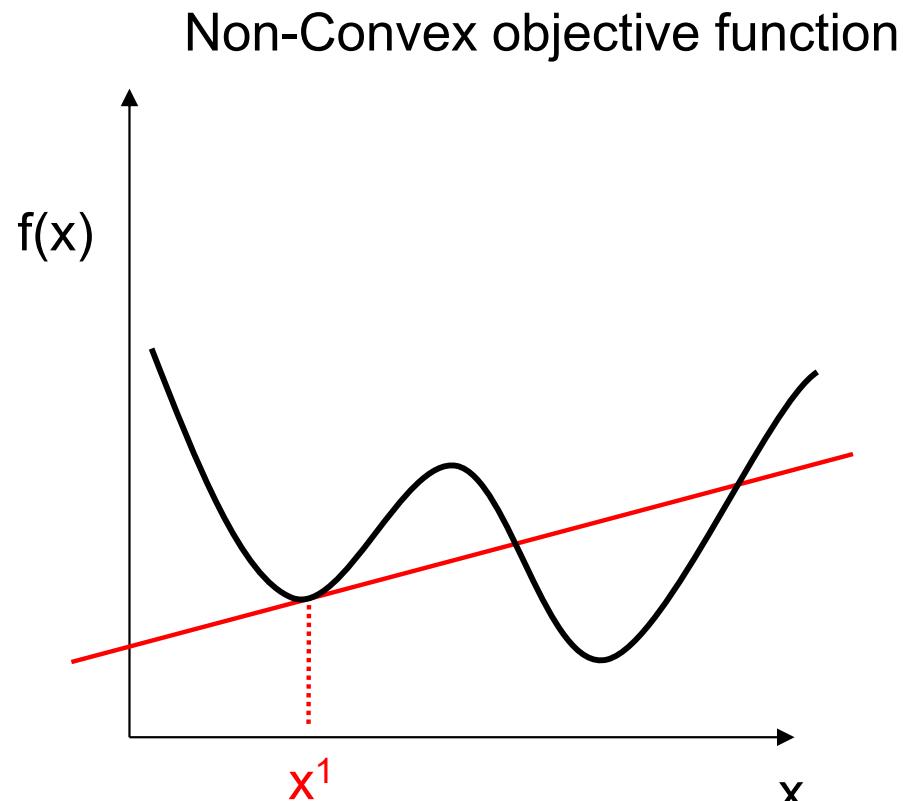
Convex feasible region



Overestimation of  
the feasible region

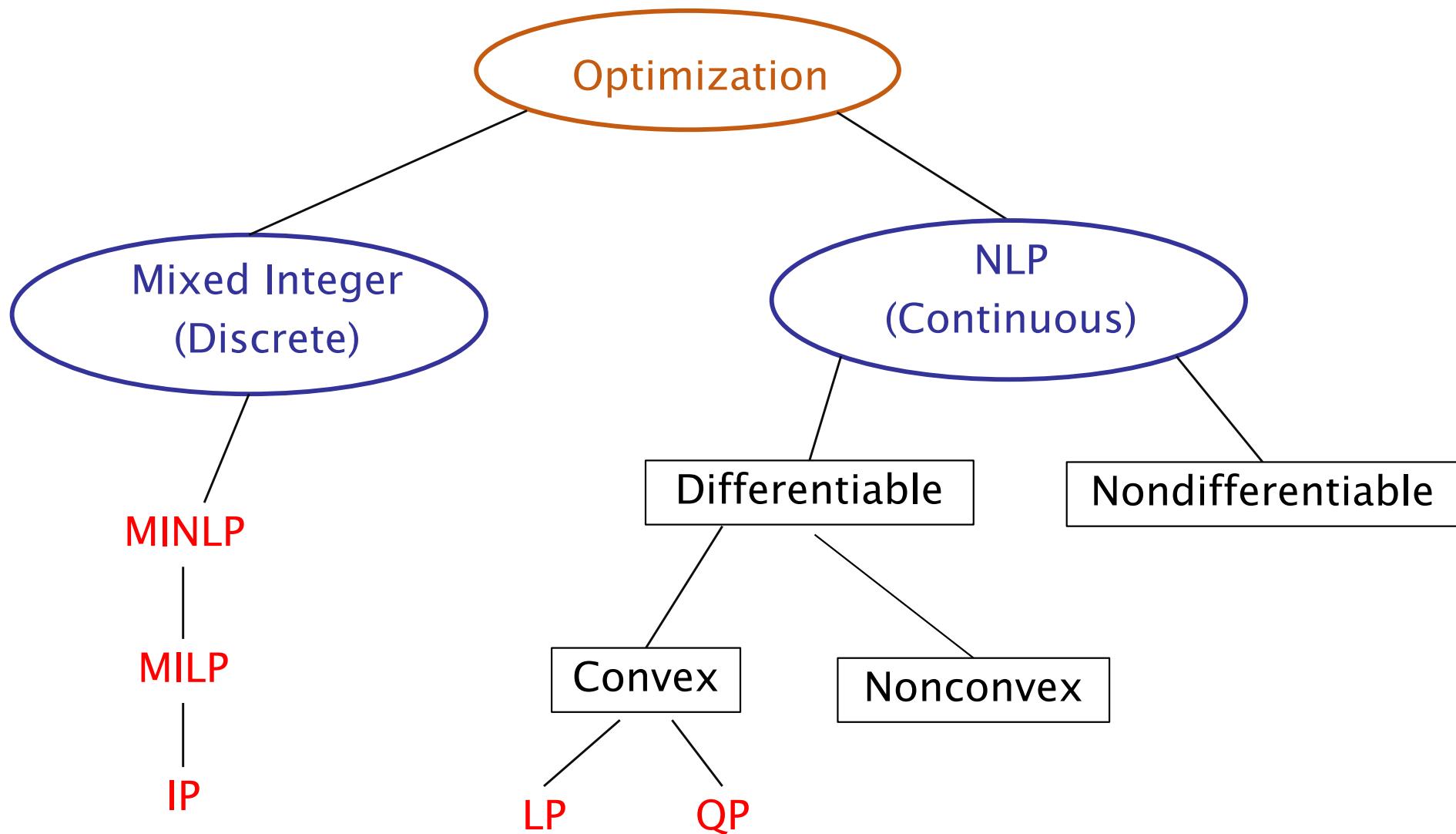
# Mathematical Programming

## Classes of Optimization Problems – Non-Convex Problems



# Mathematical Programming

## Classes of Optimization Problems



# Mathematical Programming

## Classes of Optimization Problems - Solvers

Solver	Problem Class			
	LP	MILP	NLP	MINLP
ALPHAEC				X
ANTIGONE			X	X
BARON	X	X	X	X
CONOPT4	X		X	
CPLEX	X	X		
DICOPT				X
GUROBI	X	X		
GLPK	X	X		
IPOPT	X		X	
SCIP		X	X	X

# Mathematical Programming

## Modeling of Discrete-Continuous Optimization Problems

Motivation Example (Grossmann & Trespalacios (2013), [doi.org/10.1002/aic.14088](https://doi.org/10.1002/aic.14088))

*“A company has to decide whether to produce either product A or product B in order to maximize its profit. The profit of product A is 3, and the profit of product B is 2. The limit on production of A is 4, and the limit in production of B is 5.”*

# Mathematical Programming

## Modeling of Discrete-Continuous Optimization Problems

Motivation Example (Grossmann & Trespalacios (2013), [doi.org/10.1002/aic.14088](https://doi.org/10.1002/aic.14088))

$$\max \quad 3A + 2B$$

$$s.t \quad A y_2 = 0$$

$$B y_1 = 0$$

$$y_1 y_2 = 0$$

$$y_1 + y_2 = 1$$

$$0 \leq A \leq 4$$

$$0 \leq B \leq 5$$

$$0 \leq y_1, y_2 \leq 1$$

$$A, B, y_1, y_2 \in \mathbb{R}^n$$

$$\max \quad 3A + 2B$$

$$s.t \quad A \leq 10 (1 - y_2)$$

$$B \leq 10 (1 - y_1)$$

$$y_1 + y_2 = 1$$

$$0 \leq A \leq 4$$

$$0 \leq B \leq 5$$

$$A, B \in \mathbb{R}$$

$$y_1, y_2 \in \{0, 1\}$$

$$\max \quad 3A + 2B$$

$$s.t \quad 0 \leq A \leq 4 y_1$$

$$0 \leq B \leq 5 y_2$$

$$y_1 + y_2 = 1$$

$$A, B \in \mathbb{R}$$

$$y_1, y_2 \in \{0, 1\}$$

# Mathematical Programming

## Generalized Disjunctive Programming (GDP) Formulation

$$\min : z = f(x)$$

$$s.t. \quad g(x) \leq 0$$

$$h(x) = 0$$

$$\bigvee_{i \in D_k} \left[ \begin{array}{c} Y_{k,i} \\ r_{i,k}(x) \leq 0 \end{array} \right] \quad k \in K$$

$$\bigvee_{i \in D_k} Y_{k,i} \quad k \in K$$

$$\Omega(Y) = True$$

$$x^{lo} \leq x \leq x^{up}$$

$$x \in \mathbb{R}^n;$$

$$Y \in \{True, False\} \quad k \in K, i \in D_k$$

Objective function  
and  
global constraints

Balas (1979)



Disjunctions

Logic propositions

Raman and  
Grossmann (1994)



# Mathematical Programming

## Generalized Disjunctive Programming (GDP) Formulation

GDP Reformulation (Grossmann & Trespalacios (2013), [doi.org/10.1002/aic.14088](https://doi.org/10.1002/aic.14088))

### GDP

$$\begin{aligned} \min : \quad & z = f(x) \\ \text{s.t.} \quad & g(x) \leq 0 \\ & h(x) = 0 \end{aligned}$$

$$\begin{aligned} \bigvee_{i \in D_k} \left[ \begin{array}{l} Y_{k,i} \\ r_{i,k}(x) \leq 0 \end{array} \right] \quad & k \in K \\ \bigvee_{i \in D_k} Y_{k,i} \quad & k \in K \end{aligned}$$

$$\Omega(Y) = \text{True}$$

$$x^{lo} \leq x \leq x^{up}, \quad x \in \mathbb{R}^n$$

$$Y \in \{\text{True}, \text{False}\} \quad k \in K, i \in D_k$$

### Big-M (BM)

$$\begin{aligned} \min : \quad & z = f(x) \\ \text{s.t.} \quad & g(x) \leq 0 \\ & h(x) = 0 \end{aligned}$$

$$r_{ki}(x) \leq M^{ki} (1 - y_{ki}) \quad k \in K, i \in D_k$$

$$\sum_{i \in D_k} y_{ki} = 1 \quad k \in K$$

$$x^{lo} \leq x \leq x^{up}, \quad x \in \mathbb{R}^n$$

$$y_{ki} \in \{0,1\} \quad k \in K, i \in D_k$$

### Hull Reformulation (HR) [Linear]

$$\begin{aligned} \min : \quad & z = f(x) \\ \text{s.t.} \quad & g(x) \leq 0 \\ & h(x) = 0 \end{aligned}$$

$$\begin{aligned} x = \sum_{i \in D_k} v^{ki} \quad & k \in K \\ y_{ki} r_{ki} \left( v^{ki} / y_{ki} \right) \leq 0 \quad & k \in K, i \in D_k \\ x^{lo} y_{ki} \leq v^{ki} \leq x^{up} y_{ki} \quad & k \in K, i \in D_k \\ \sum_{i \in D_k} y_{ki} = 1 \quad & k \in K \end{aligned}$$

$$Hx \geq h$$

$$x \in \mathbb{R}^n$$

$$y_{ki} \in \{0,1\} \quad k \in K, i \in D_k$$

# Mathematical Programming

## Generalized Disjunctive Programming (GDP) Formulation

Systematic procedure to derive MILP constraints for Logic Propositions (Grossmann & Trespalacios (2013), [doi.org/10.1002/aic.14088](https://doi.org/10.1002/aic.14088))

Proposition: set of literals  $Y_i$ , separated by OR, AND, IMPLICATION

OR 
$$Y_1 \vee Y_2 \vee \dots \vee Y_r \rightarrow y_1 + y_2 + \dots + y_r \geq 1$$

AND 
$$Y_1 \wedge Y_2 \wedge \dots \wedge Y_r \rightarrow y_1 \geq 1, y_2 \geq 1, \dots, y_r \geq 1$$

IMPLICATION 
$$Y_1 \Rightarrow Y_2 \text{ equivalent to } \neg Y_1 \vee Y_2 \rightarrow 1 - y_1 + y_2 \geq 1 \quad (y_2 \geq y_1)$$

# Mathematical Programming

## Generalized Disjunctive Programming (GDP) Formulation

Systematic procedure to derive MILP constraints for Logic Propositions (Grossmann & Trespalacios (2013), [doi.org/10.1002/aic.14088](https://doi.org/10.1002/aic.14088))

The goal is to convert logical expressions into **Conjunctive Normal Form**:

$$Q_1 \wedge Q_2 \wedge \dots \wedge Q_s \quad (\text{all AND}) \quad \text{where clause} \quad Q_i : Y_1 \vee Y_2 \vee \dots \vee Y_i \quad (\text{all OR})$$

### Basic Steps

(1) Replace implication by disjunction

$$Y_1 \Rightarrow Y_2 \Leftrightarrow \neg Y_1 \vee Y_2$$

(2) Move negation inward

applying De Morgan's law

$$\neg(Y_1 \vee Y_2) \Leftrightarrow (\neg Y_1) \wedge (\neg Y_2)$$

(3) Recursively distribute OR over AND

$$(Y_1 \wedge Y_2) \vee Y_3 \Leftrightarrow (Y_1 \vee Y_3) \wedge (Y_2 \vee Y_3)$$

# PYOMO Components

# PYOMO Components

## Example: Machinery Problem

A company manufacture four types of machinery. The factory is divided in three sections. The first section has available 960 h/week, the second 1110 h/week and the third 400 h/week. Each machinery unit requires the following time at each section

Plants	hours per machinery			Profit [units/machinery]
	Machining	Painting	Assembly	
Machinery 1	6	3	2	12
Machinery 2	4	3	1	8
Machinery 3	4	6	2	12
Machinery 4	8	9	1	17

Determine the number of units of machinery for each type that should be manufacture per week to maximize the profit.

# PYOMO Components

## Example: Machinery Problem

### Nomenclature

- m → machinery type (set)  
s → factory section (set)  
 $\text{profit}_m$  → profit per machinery type (parameter)  
 $b_s$  → time availability in each section per week (parameter)  
 $T_{m,s}$  → time required for each machinery type in each section (parameter)  
 $x_m$  → number of units of machinery for each type (variable)

$$\begin{aligned} \max_x : & \sum_m \text{profit}_m x_m && \text{Objective function} \\ s.t. & \sum_m T_{m,s} x_m \leq b_i & \forall s & \text{Factory section time limit} \\ & x_m \in \mathbb{Z} \end{aligned}$$

# Model Structure

```
from pyomo.environ import *
```

Import packages

```
m = ConcreteModel()
```

Create model object

```
M = m.M = Set(initialize = ['m1', 'm2', 'm3', 'm4'])
S = m.S = Set(initialize = ['s1', 's2', 's3'])
```

Sets declarations

```
profit = {'m1':12, 'm2':8, 'm3':12, 'm4':17}
max_time = {'s1': 960, 's2': 1110, 's3': 400}
time_x_section = {
    ('m1','s1'): 6 , ('m1','s2'): 3 , ('m1','s3'): 2 ,
    ('m2','s1'): 4 , ('m2','s2'): 3 , ('m2','s3'): 1 ,
    ('m3','s1'): 4 , ('m3','s2'): 6 , ('m3','s3'): 2 ,
    ('m4','s1'): 8 , ('m4','s2'): 9 , ('m4','s3'): 1 }
```

Specify/import problem data

```
x = m.x = Var( M, within = PositiveIntegers)
```

Variable declarations

```
m.value = Objective(
    expr = sum( profit[i] * m.x[i] for i in M),
    sense = maximize )
```

Objective function declaration

```
def constraint_rule(m, j):
    return sum(time_x_section[i,j] * x[i] for i in M)
        <= max_time[j]
m.constraint = Constraint(S, rule = constraint_rule)
```

Constraint functions declaration

```
opt = SolverFactory('glpk').solve(m)
```

Solver call

# Case Studies

# Knap-Sack Problem

In this problem, we are adventurous thieves. We want to loot all of the treasures that we can before the guards arrive. Since it will not be possible to come back to loot whatever we leave behind, we must ensure that we maximize the benefit of what we steal. Our horse can handle up until 2500 g of weight (It's a tiny pony) and a volume of 2000 cm<sup>3</sup>. Considering the loot table, what should we carry out there to sell?

Item	Market Price	Volume (cm <sup>3</sup> )	Unit Weight (g)	Units available
Chest	50	1000	2000	1
Ring	5	2	20	10
Necklace	3	10	300	1
Mirror	20	500	1000	1
Bracelet	16	15	300	15
Ruby	5	3	75	1
Parfum	1	100	100	1
Diamond	30	5	50	1
Gold goblet	12	250	500	1
Spice	40	100	100	1

# Knap-Sack Problem

## Mathematical Model

$$\max\left(\sum_i MP_i n_i\right) \quad \text{Maximize Profit}$$

s.t.

$$\sum_i V_i n_i \leq 2000 \quad \text{Volume constraint}$$

$$\sum_i W_i n_i \leq 2500 \quad \text{Weight constraint}$$

$$n_i \leq N_i \quad \forall i \quad \text{Amount constraint}$$

# Sudoku problem

## Nomenclature

**r** → rows | **c** → columns | **k** → value

**y<sub>r,c,k</sub>** → binary variable.  $y_{r,c,k} = 1$  means cell [r, c] is assigned number k

Every position in the Sudoku is filled

$$\sum_k y_{r,c,k} = 1 \quad \forall r, c$$

Cells in the same column must be assigned distinct numbers

$$\sum_r y_{r,c,k} = 1 \quad \forall c, k$$

Cells in the same row must be assigned distinct numbers

$$\sum_c y_{r,c,k} = 1 \quad \forall r, k$$

	c1	c2	c3	c4	c5	c6	c7	c8	c9
r1	5	3			7				
r2	6			1	9	5			
r3		9	8					6	
r4	8				6				3
r5	4			8					1
r6	7				2				6
r7		6					2	8	
r8				4	1				5
r9					8		7	9	

Cells in the same 3x3 grid must be assigned distinct numbers

$$\sum_{r=3p-2}^{3p} \sum_{c=3q-2}^{3q} y_{r,c,k} = 1 \quad \forall k, p, q = \{1, 2, 3\}$$

# Non Sharp Separation

## Nomenclature

### Sets

$$C := \{c : c \text{ is a column}\}$$

$$I := \{i : i \text{ is a component}\}$$

### Continuous Variables

$F_{c,i}$  : molar feed flow to column  $c$  of component  $i$

$D_{c,i}$  : molar distillate flow of column  $c$  and component  $i$

$B_{c,i}$  : molar bottoms flow of column  $c$  and component  $i$

$S1_i$  : Feed stream bypass to node  $A$ , component  $i$

$S2_i$  : Feed stream bypass to node  $B$ , component  $i$

$S3_i$  : Feed stream bypass to node  $C$ , component  $i$

$ProdA_i$  : molar product  $A$  flow of component  $i$

$ProdB_i$  : molar product  $B$  flow of component  $i$

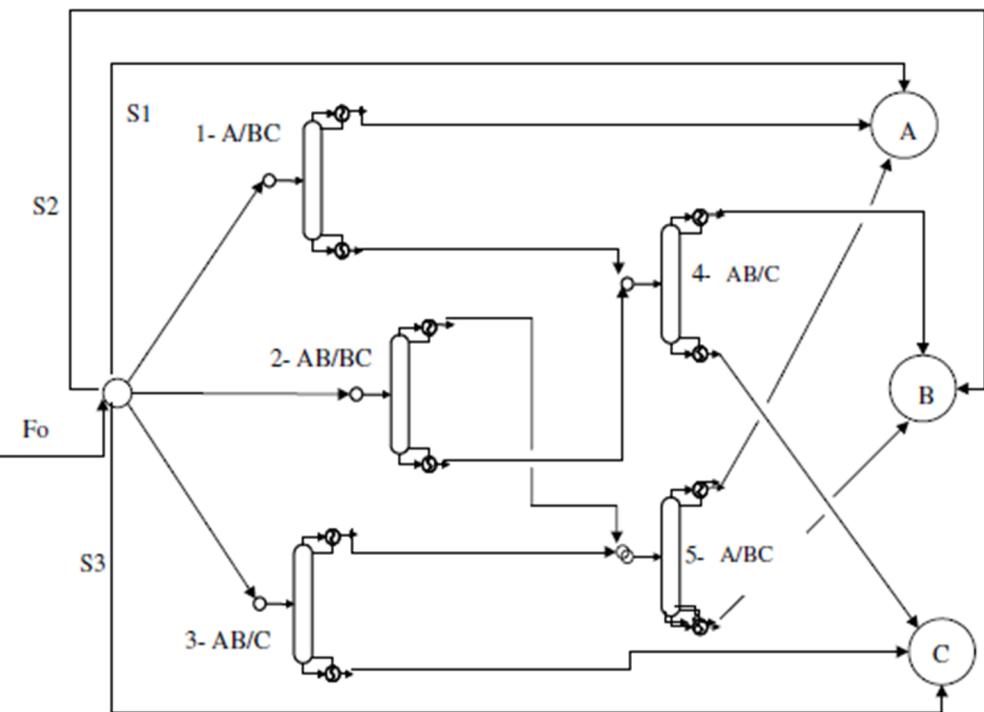
$ProdC_i$  : molar product  $C$  flow of component  $i$

$Cost_c$  : cost of distillation column  $c$

### Binary Variables

$y_c$  : 1 if column  $c$  is selected. 0 otherwise

## Distillation Sequence Superstructure



### Parameters

$F_{0i}$  : molar feed flow to distillation sequence of component  $i$

$FC_c$  : column  $c$  fixed cost

$FV_c$  : column  $c$  variable cost

$x_{c,i}$  : column  $c$  component  $i$  fraction in distillate

# Non Sharp Separation

## GDP Formulation

$$\min \sum_{c \in C} Cost_c$$

Objective function

$$s.t \quad F_{0i} = S1_i + S2_i + S3_i + F_{c1,i} + F_{c2,i} + F_{c3,i} \quad \forall i \in I$$

$$F_{c4,i} = B_{c1,i} + B_{c2,i} \quad \forall i \in I$$

$$F_{c5,i} = D_{c2,i} + D_{c3,i} \quad \forall i \in I$$

$$ProdA_i = S1_i + D_{c1,i} + D_{c5,i} \quad \forall i \in I$$

$$ProdB_i = S2_i + D_{c4,i} + B_{c5,i} \quad \forall i \in I$$

$$ProdC_i = S3_i + B_{c3,i} + B_{c4,i} \quad \forall i \in I$$

$$\sum_{i \in I} SX_i \ F_{0i} = \sum_{i \in I} F_{0i} \ SX_i \quad \forall i \in I, SX = \{S1, S2, S3\}$$

$$\sum_{i \in I} F_{c,i} \ F_{0i} = \sum_{i \in I} F_{0i} \ F_{c,i} \quad \forall i \in I, c = \{c1, c2, c3\}$$

$$F_{c,i} = D_{c,i} + B_{c,i} \quad \forall c \in C, i \in I$$

$$D_{c,i} = F_{c,i} x_{c,i} \quad \forall c \in C, i \in I$$

Global constraints

# Non Sharp Separation

## GDP Formulation

$$\left[ \begin{array}{l} Y_c \\ Cost_c = FC_c + FV_c \sum_{i \in I} D_{c,i} \\ F_{c,i} \leq F_{0i} \quad \forall i \in I \end{array} \right] \vee \left[ \begin{array}{l} \neg Y_c \\ Cost_c = 0 \\ F_{c,i} = 0 \quad \forall i \in I \end{array} \right] \quad \forall c \in C$$

Disjunctions

$$Y_1 \vee Y_2 \vee Y_3$$
$$\Omega(Y) = \text{True}$$

Logic propositions

$$F_{ci}, D_{ci}, D_{c,i}, S1_i, S2_i, S3_i, ProdA_i, ProdB_i, ProdC_i, Cost_c \in \mathbb{R}$$

$$Y_{i,j} \in \{\text{True}, \text{False}\}$$

# Strip packing 2D problem

## Nomenclature

$i \rightarrow$  rectangles,  $i = \{1, 2, \dots, n\}$

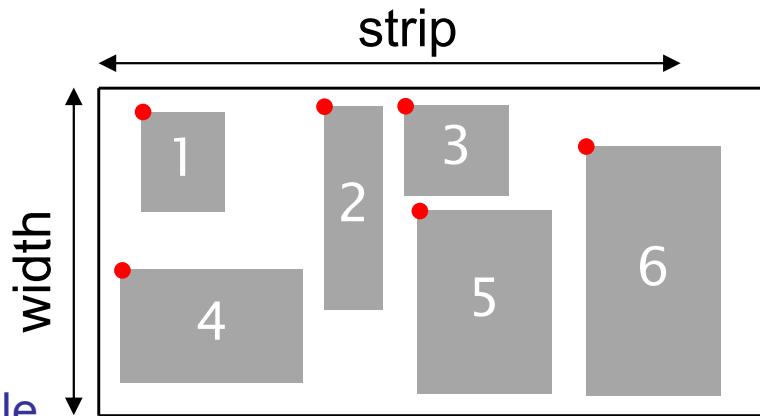
$l_t \rightarrow$  length of the strip

$(x_i, y_i) \rightarrow$  rectangle coordinates

$L_i, H_i \rightarrow$  Length and height of rectangle  $i$

$W \rightarrow$  Width of the strip

$UB_i \rightarrow$  Upper bound for the x-coordinate of every rectangle



## GDP Formulation

$$\min l_t$$

Source: Sawaya & Grossmann (2005),  
<https://doi.org/10.1016/j.compchemeng.2005.04.004>

$$s.t \quad l_t \geq x_i + L_i \quad \forall i \in N$$

$$\left[ \begin{array}{c} Y_{i,j}^1 \\ y_j - H_j \geq y_i \end{array} \right] \vee \left[ \begin{array}{c} Y_{i,j}^2 \\ x_i + L_i \leq x_j \end{array} \right] \vee \left[ \begin{array}{c} Y_{i,j}^3 \\ y_i - H_i \geq y_j \end{array} \right] \vee \left[ \begin{array}{c} Y_{i,j}^4 \\ x_j + L_j \leq x_i \end{array} \right] \quad \forall i, j \in N, i < j$$

$$Y_{i,j}^1 \vee Y_{i,j}^2 \vee Y_{i,j}^3 \vee Y_{i,j}^4 \quad \forall i, j \in N, i < j$$

$$x_i \leq UB - L_i \quad \forall i \in N$$

$$H_i \leq y_i \leq W \quad \forall i \in N$$

$$l_t, x_i, y_i \in \mathbb{R}$$

$$Y_{i,j} \in \{True, False\}$$

# Strip packing 2D problem

## Nomenclature

$i \rightarrow$  rectangles,  $i = \{1, 2, \dots, n\}$

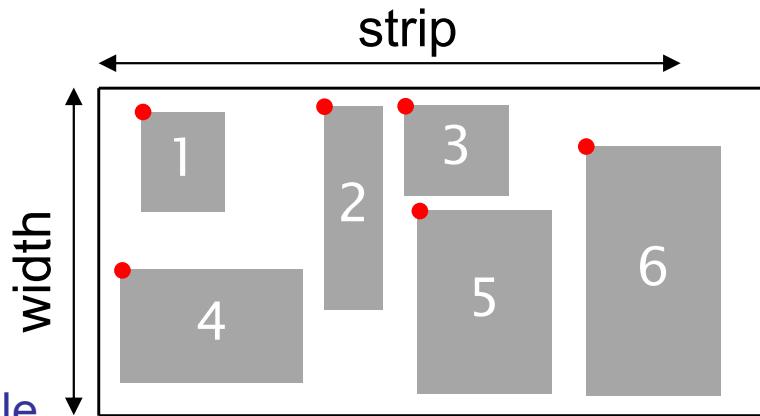
$l_t \rightarrow$  length of the strip

$(x_i, y_i) \rightarrow$  rectangle coordinates

$L_i, H_i \rightarrow$  Length and height of rectangle  $i$

$W \rightarrow$  Width of the strip

$UB_i \rightarrow$  Upper bound for the x-coordinate of every rectangle



## MILP Formulation [Big-M]

$$\begin{aligned}
 & \min l_t \\
 \text{s.t } & l_t \geq x_i + L_i \quad \forall i \in N \\
 & y_j - H_j \geq y_i - M_{ij}^1 (1 - w_{ij}^1) \quad \forall i, j \in N, i < j \\
 & x_i + L_i \leq x_j + M_{ij}^2 (1 - w_{ij}^2) \quad \forall i, j \in N, i < j \\
 & y_i - H_i \geq y_j - M_{ij}^3 (1 - w_{ij}^3) \quad \forall i, j \in N, i < j \\
 & x_j + L_j \leq x_i + M_{ij}^4 (1 - w_{ij}^4) \quad \forall i, j \in N, i < j \\
 & \sum_{d \in D} w_{ij}^d = 1 \quad \forall i, j \in N, i < j \\
 & x_i \leq UB - L_i \quad \forall i \in N \\
 & H_i \leq y_i \leq W \quad \forall i \in N \\
 & l_t, x_i, y_i \in \mathbb{R}, \quad w_{i,j} \in \{0,1\}
 \end{aligned}$$

# More Complex Constraints Examples

## The Expanded Transshipment Model (Papoulias & Grossmann, 1983.)

$$R_{i,k} + \sum_{j \in C_{jk}} Q_{ijk} + \sum_{n \in W_{nk}} Q_{ink} = R_{i,k-1} + Q_{ik}^H \quad \forall i, k \in HS_{i,k}$$

### GAMS

```
EQ_01_EB_A(HS(i,k))$(ord(k) eq 1).. R(i,k) + sum(j$C(j,k), Qijk(i,j,k)) +  
      sum(n$W(n,k), Qink(i,n,k)) =E= Q_H(i,k);  
  
EQ_02_EB_A(HS(i,k))$(ord(k) ne 1).. R(i,k) + sum(j$C(j,k), Qijk(i,j,k)) +  
      sum(n$W(n,k), Qink(i,n,k)) =E= Q_H(i,k) + R(i,k-1);
```

### PYOMO

```
def energy_balance_A_rule(model, i, k):  
    if (i,k) in model.HS:  
        if k == model.K[1]:  
            return (  
                model.R[i,k] + sum(model.Qijk[i,j,k] for j in model.J if (j,k) in model.C) +  
                sum(model.Qink[i,n,k] for n in model.N if (n,k) in model.W) ==  
                model.Q_H[i,k]  
            )  
        else:  
            return (  
                model.R[i,k] + sum(model.Qijk[i,j,k] for j in model.J if (j,k) in model.C) +  
                sum(model.Qink[i,n,k] for n in model.N if (n,k) in model.W) ==  
                model.R[i, model.K[model.K.ord(k)-1]] + model.Q_H[i,k]  
            )  
    else:  
        return Constraint.Skip  
model.energy_balance_A = Constraint(model.I, model.K, rule = energy_balance_A_rule)
```



# Introduction to Optimization Modeling in Python



Juan Javaloyes & Daniel Vázquez  
February 2020