# 编译原理作业 15

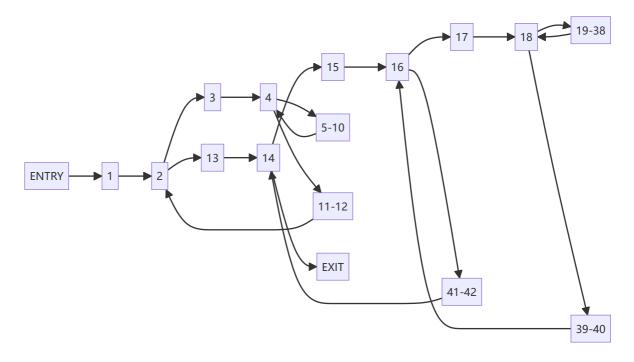
23.12.18

### 8.4.1

(1)

下面的三地址代码假定三个矩阵的第二维都含有 n 个元素.

```
1 \mid i = 0
2 | if i >= n goto (13)
3 j = 0
4 if j >= n goto (11)
5
   t1 = n * i
6 | t2 = t1 + j
   t3 = t2 * 8
8
   c[t3] = 0.0
9
   j = j + 1
10 goto (4)
11 | i = i + 1
12 goto (2)
13
   i = 0
14 | if i >= n goto (43)
15
   j = 0
16 | if j >= n goto (41)
17
   k = 0
18 | if k >= n \text{ goto } (39)
19
   t4 = n * i
20 | t5 = t4 + j
21 t6 = t5 * 8
22 t7 = c[t6]
23
   t8 = n * i
24 t9 = t8 + k
25 | t10 = t9 * 8
26 t11 = a[t10]
27
   t12 = n * k
28 | t13 = t12 + j
29 t14 = t13 * 8
30 | t15 = b[t14]
31 t16 = t11 * t15
32 t17 = t7 + t16
33 t18 = n * i
34 t18 = t18 + j
35
   t20 = t19 * 8
36 c[t20] = t16
37
   k = k + 1
38 goto (18)
39
   j = j + 1
40 goto (16)
41 | i = i + 1
42 goto (14)
43 EXIT
```



(3)

### 循环有:

- {4, 5-10}.
- {2, 3, 4, 5-10, 11-12}.
- {18, 19-38}.
- {16, 17, 18, 19-38, 39-40}.
- {14, 15, 16, 17, 18, 19-38, 39-40, 41-42}.

# 另一道作业题

(1)

### 冲突情况:

- R1: R2, R3, R4, R5, R6, R7, R8.
- R2: R1, R3, R4, R5, R6, R7.
- R3: R1, R2, R4, R5.
- R4: R1, R2, R3.
- R5: R1, R2, R3, R6.
- R6: R1, R2, R5.
- R7: R1, R2, R8.
- R8: R1, R7.

(2)

一种可能的方案为溢出 R2, 将 BB1 和 BB4 分别修改为

```
1 // BB1
2 LD R1, a
3 LD R2, b
4 ST 4(SP), R2
5
6 // BB4
7 LD R9, 4(SP)
8 MUL R7, R9, R4
9 ST g, R7
10 LD R8, #5
11 SUB R10, R2, R7
12 ST 4(SP), R10
```

#### 然后就可以指派如下:

- 物理寄存器 1: R3, R6, R7, R9.
- 物理寄存器 2: R4, R5, R8, R10.
- 物理寄存器 3: R1.

(3)

至少要 4 个. R1 与所有其它符号寄存器冲突,必须单独放在一个物理寄存器中, R2, R3, R4 互相冲突,必须分别放在三个物理寄存器中,因此至少要 4 个物理寄存器.一种可能的方案为四个物理寄存器分别存放 {R3, R6, R7}, {R4, R5, R8}, {R2}, {R1}.