right()

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Turn GoPiGo Right slowly

The right motor is turned off and the left motor is kept on. This slowly banks the GoPiGo to turn right.

Syntax

right()

Parameter:

None

Return:

1 on success

-1 on error

Example

```
from gopigo import *
right()
```

Specifications

- Difficulty
- Ages 10+
- Tech Raspberry Pi & Windows 10
- Languages Python, Scratch, Java, NodeJS, C/C++

GoPiGo

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