

motor_bwd()

 dexterindustries.com/GoPiGo/programming__trashed/python-programming-for-the-raspberry-pi-gopigo__trashed/motor_bwd/

Turn the motors on in the backward direction.

Both the motors are turned on to move back. This does not take much processing power but the GoPiGo may wiggle around and deviate from its course.

Syntax

```
motor_bwd()
```

Parameter:

None

Return:

1 on success

-1 on error

Example

```
from gopigo import * motor_bwd()
```