


# enable\_encoders()

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 [dexterindustries.com/GoPiGo/programming\\_\\_trashed/python-programming-for-the-raspberry-pi-gopigo\\_\\_trashed/enable\\_encoders/](https://dexterindustries.com/GoPiGo/programming__trashed/python-programming-for-the-raspberry-pi-gopigo__trashed/enable_encoders/)

## Enable the GoPiGo encoders(default setting)

Enable the encoder ISR on the GoPiGo. This is the default setup on runtime. If the encoders are enabled, the GoPiGo firmware will always be calculating the pulse count for the encoder rotations as the wheels move.

### Syntax

```
enable_encoders()
```

### Parameter:

None

### Return:

1 on success

-1 on error

### Example

```
from gopigo import *  
enable_encoders()  
enc_tgt(1,1,72)  
fwd()
```