# motor\_fwd()

# dexterindustries.com/GoPiGo/learning-2/python-programming-for-the-raspberry-pi-gopigo/motor\_fwd/

## Turn the motors on in the forward direction.

Both the motors are turned on to move forward. This does not take much processing power but the GoPiGo may wiggle around and deviate from its course

## **Syntax**

```
motor_fwd()
```

#### Parameter:

None

#### Return:

1 on success

-1 on error

# **Example**

```
from gopigo import *
motor_fwd()
```