


Enable communication timeout on the GoPiGo

 dexterindustries.com/GoPiGo/programming__trashed/python-programming-for-the-raspberry-pi-gopigo__trashed/enable_com_timeout/

Enable the communication timeout on the GoPiGo. The GoPiGo automatically stops if it does not get a command from the GoPiGo in the time period specified. This could be helpful in automatically stopping a run away robot.

Syntax

```
enable_com_timeout(time)
```

Parameter:

time: timeout in ms (0-65536)

Return:

1 on success

-1 on failure

Example

```
from gopigo import *  
enable_com_timeout(1000)  #Stops motors after 1s  
fwd()
```