


# Disable communication timeout on the GoPiGo

---

 [dexterindustries.com/GoPiGo/learning-2/python-programming-for-the-raspberry-pi-gopigo/disable\\_com\\_timeout/](https://dexterindustries.com/GoPiGo/learning-2/python-programming-for-the-raspberry-pi-gopigo/disable_com_timeout/)

Enable the communication timeout on the GoPiGo. The GoPiGo automatically stops if it does not get a command from the GoPiGo in the time period specified. This could be helpful in automatically stopping a run away robot.

## Syntax

```
disable_com_timeout(time)
```

## Parameter:

None

## Return:

1 on success

-1 on failure

## Example

```
from gopigo import *
enable_com_timeout(1000) #Stops motors after 1s
fwd()
disable_com_timeout()
fwd()                    #This will not stop
```