


# servo()

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 [dexterindustries.com/GoPiGo/programming\\_\\_trashed/python-programming-for-the-raspberry-pi-gopigo\\_\\_trashed/servo/](https://dexterindustries.com/GoPiGo/programming__trashed/python-programming-for-the-raspberry-pi-gopigo__trashed/servo/)

## Move servo to the position

This function moves the servo to the position that is given. You will have to manually add a very small delay when trying to do a servo sweep or when moving the servo because the servo moves much slower than the code so you will have to account for the delay.

The servo angle can be between 0 and 180

## Syntax

```
servo(angle)
```

## Parameter:

angle: Final servo position between 0 and 180

## Return:

None

## Example

```
from gopigo import *
import time
enable_servo()
for i in range(180):
    servo(i)
    time.sleep(100)
```