# left\_rot()

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### **Rotate GoPiGo Left**

The left motor starts rotating back and the right motor starts rotating forward. This makes the GoPiGo rotate towards left at the same spot.

## **Syntax**

```
left_rot()
```

## **Parameter:**

None

### Return:

1 on success

-1 on error

# **Example**

```
from gopigo import *
left_rot()
```