

set_right_speed()

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Set the speed of the right motor on GoPiGo

The speed of the GoPiGo can be between 0-255. The default speed is 200.

You can use `set_right_speed()` to set the speed of the of the right motor between 0 and 255. Any speed above 255 will be made as 255 and any speed below 0 will be made 0.

Syntax

```
set_right_speed(speed)
```

Parameter:

speed: valid speed value between 0-255

Return:

None

Example

```
from gopigo import *  
set_right_speed(150)
```