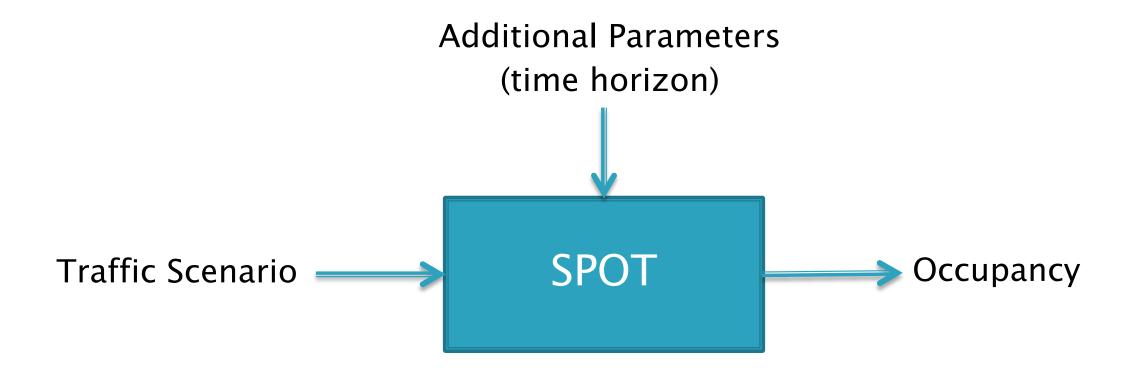
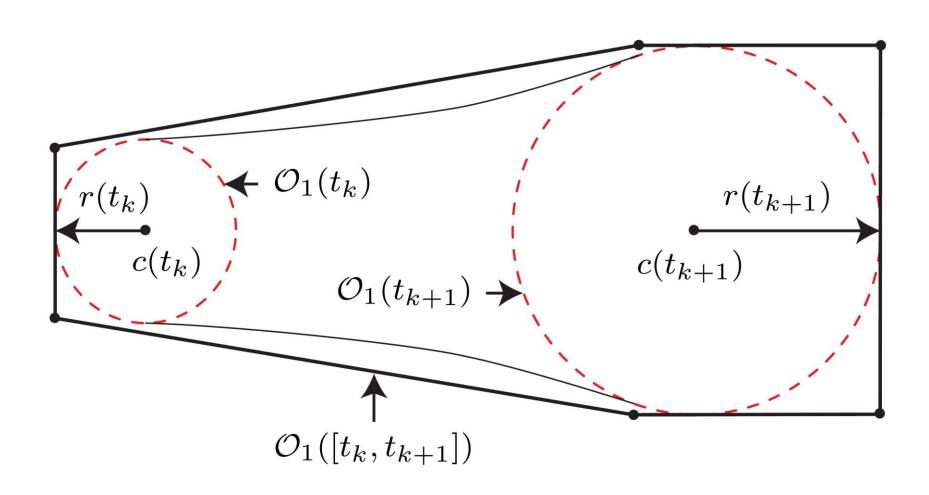
Lab Course Motion Planning

Sebastian Kaster Technical University Munich April 27, 2018

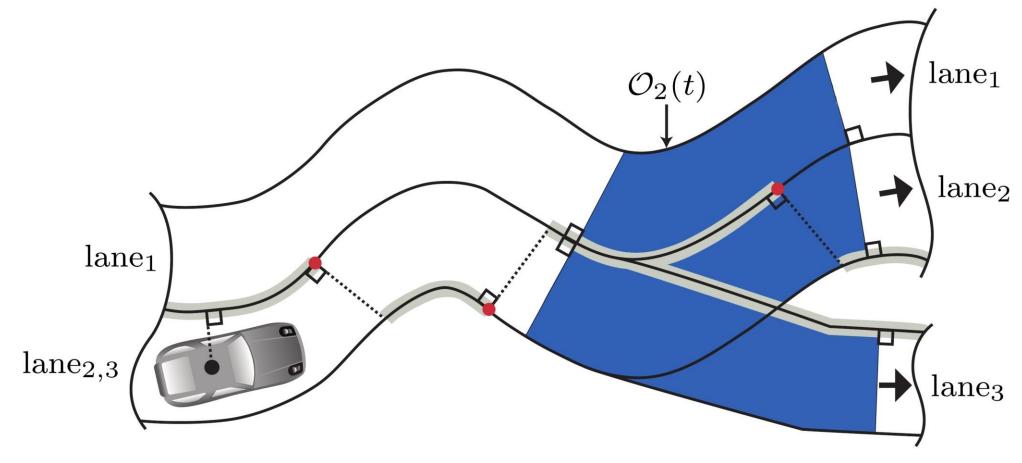
Overview Model



Acceleration-Based Occupancy (M1)

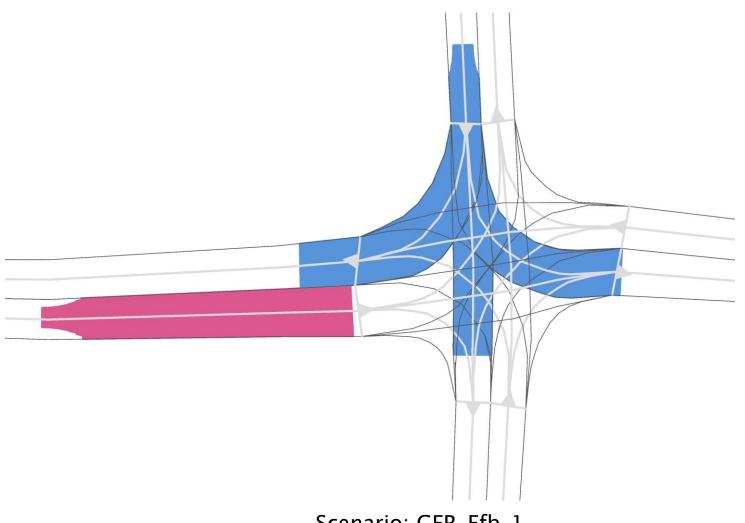


Lane-Following Occupancy (M2)



shortest path along inner lane bounds

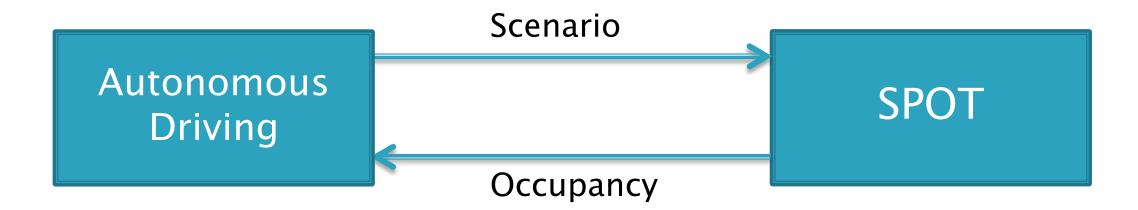
Overall Occupancy



Scenario: GER_Ffb_1

Agenda

> Connect spot with autonomous driving framework



Agenda

- Connect spot to autonomous driving framework
- Reduce velocity in curves
- Add further unit tests