

# **MATHEMATICS EXTENSION 2**

# **4 UNIT MATHEMATICS**

**TOPIC 5: VOLUMES** 

# 5.3 SOLIDS OF REVOLUTION

In Topic 5.2, the volume V of a solid aligned along the X-axis was given by the equation

$$V = \int_{x_a}^{x_b} A(x) dx$$

Solid figures can also be produced by rotating bounded regions in the XY plane in space through  $360^{\circ}$ . The solid generated by the rotation is called a **solid of revolution**.

We will only consider solids of revolution that are generated by rotations about axes that are parallel to the **X-axis** or the **Y-axis** (coordinates axes).

#### **DISK METHOD**

#### ROTATIONS ABOUT THE X-AXIS $(y_R = 0)$

Let y=f(x) be a single-valued continuous function where  $f(x) \ge 0$  in the interval  $x_a \le x \le x_b$ . Consider the region  $\mathbf R$  bounded by the function y=f(x) and the X-axis  $(y_R=0)$  for the interval  $x_a \le x \le x_b$ . When this region  $\mathbf R$  is rotated about X-axis through the  $360^{\circ}$  rotation, a solid of revolution is generated. The volume V of the solid of revolution is given by

$$V = \int_{x_a}^{x_b} A(x) dx$$
 rotation about X-axis

The solid generated by the rotation must have a circular cross-section with radius R(x). Therefore, the cross-sectional area A(x) is given by

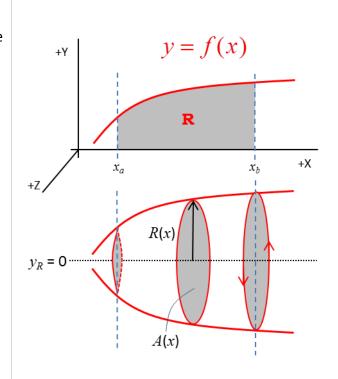
$$A(x) = \pi R(x)^{2}$$
  $R(x) = y$   $A(x) = \pi y^{2}$ 

The volume *V* of the solid of revolution is

$$V = \pi \int_{x_a}^{x_b} R(x)^2 dx = \pi \int_{x_a}^{x_b} y^2 dx$$
 disk method – rotation about X-axis

This is called the disk method.

In the disk method, we sum up the volumes of an infinite number of infinitesimally thin circular disks to find the total volume of a solid. The solid has been decomposed into stacked circular disks, and by integrating the disk volumes we obtain the total volume.



### ROTATIONS ABOUT THE Y-AXIS ( $x_R = 0$ )

Let x = g(y) be a single-valued continuous function where  $g(y) \ge 0$  in the interval  $y_a \le y \le y_b$ . Consider the region  $\mathbf{R}$  bounded by the function x = g(y) and the Y-axis ( $x_R = 0$ ) for the interval  $y_a \le y \le y_b$ . When this region  $\mathbf{R}$  is rotated about Y-axis through the 360° rotation, a solid of revolution is generated. The volume V of the solid of revolution is given by

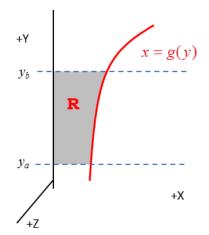
$$V = \int_{y_a}^{y_b} A(y) dy$$
 rotation about Y-axis

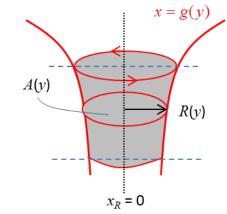
The solid generated by the rotation must have a circular cross-section with radius R(y). Therefore, the cross-sectional area A(y) is given by

$$A(y) = \pi R(y)^2$$
  $R(y) = x$   $A(x) = \pi x^2$ 

The volume V of the solid of revolution is

$$V = \pi \int_{y_a}^{y_b} R(y)^2 dy = \pi \int_{y_a}^{y_b} x^2 dy$$
 disk method – rotation about Y-axis





### CYLINDRICAL SHELL METHOD

In another approach to find the volume V, we decompose the solid into hollow concentric shells or rings which are infinitesimally thin. For a rotation about the X-axis ( $y_R = 0$ )

The area of each ring is  $A(x_k) = 2\pi y_k \Delta y$  (circumference x width)

The volume of each the cylindrical shell is

$$V(x_k) = (2\pi y \Delta y) x_k$$
 (area x height)

The total volume V of the solid of revolution is

$$V = \sum_{k=1}^{N} V(x_k) = \sum_{k=1}^{N} (2 \pi x_k \ y) \Delta y$$

As the thickness of the shells becomes infinitely thin

$$N \to \infty \quad \Delta y \to 0 \quad \sum \quad \to \int$$

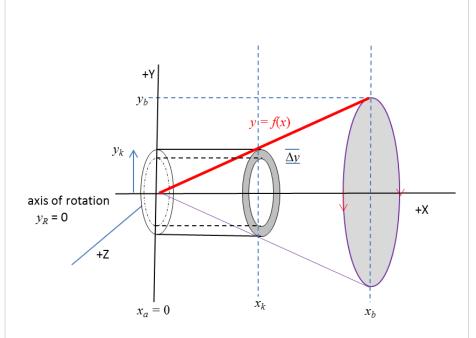
$$V = 2\pi \int_0^{y_b} x \, y \, dy$$

cylindrical shell method

$$V = 2\pi \int_0^{y_b} g(y) y \, dy$$

rotation about X-axis

$$x = g(y)$$



For a rotation about the Y-axis (  $x_R = 0$  )

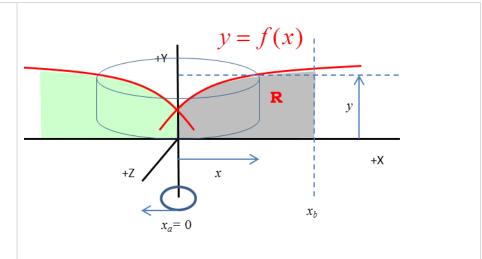
$$V = 2\pi \int_0^{x_b} y x \, dx$$

cylindrical shell method

$$V = 2\pi \int_0^{x_b} f(x) x \, dx$$

rotation about Y-axis

$$y = f(x)$$

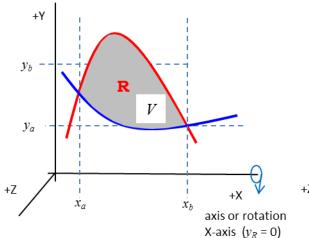


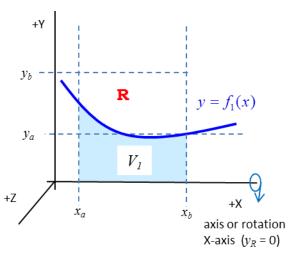
# Volumes generated by the rotation of bounded regions

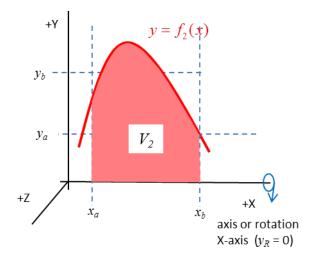
When the region  ${\bf R}$  between two functions defined in the XY plane is rotated, a solid of revolution can be produced. Let  $y=f_1(x)$  and  $y=f_2(x)$  be two functions such that  $0 \le f_1(x) \le f_2(x)$  in the interval  $x_a \le x \le x_b$ . The volume V of revolution of the region  ${\bf R}$  is the difference between the volume  $V_1$  of revolution of  $f_1(x)$  and volume  $V_2$  of revolution of  $f_2(x)$ .

$$V = V_2 - V_1$$

$$V_1 = \pi \int_{x_a}^{x_b} f_1(x)^2 dx \qquad V_2 = \pi \int_{x_a}^{x_b} f_2(x)^2 dx$$







## Solids of revolutions about lines parallel to a coordinate axis

We can also find the volume of revolution when the region is revolved about a line parallel to a coordinate axis. To do such calculations it is necessary to draw a "good quality" sketch of the region to be rotated and the axis of rotation  $y_R$  = constant.

The volume V of the solid of revolution for the region  $\mathbb{R}$  bounded by y = f(x), the X-axis (y = 0) and the vertical lines  $x_a$  and  $x_b$  about the line  $y_R$   $(y_R < 0)$  is

$$V = V_2 - V_1$$

$$V_1 = \pi \int_{x_a}^{x_b} R_1(x)^2 dx \qquad V_2 = \pi \int_{x_a}^{x_b} R_2(x)^2 dx$$

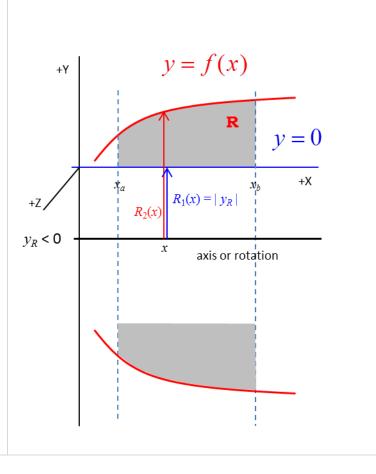
where

$$R_2(x) = f(x) - y_R = f(x) + |y_R|$$
  
 $R_1(x) = -y_R = |y_R| \quad y_R < 0$ 

For the rotation about an axis of rotation when  $y_R \ge f(x)$   $x_a \le x \le x_b$ 

$$R_2(x) = y_R \quad y_R \ge f(x)$$
  
$$R_1(x) = f(x)$$

For rotations about lines parallel to the Y-axis, then the x and y values are simply interchanged.



The best approach to mastering volume calculations for the HSC examination is to do lots of practice questions. Always start with a good diagram and work from first principles. Dot "blindly" apply an equation. Carefully choose the best method for the calculation.