

# Logic for Multiagent Systems

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# Propositional logic



#### Language

#### Definition 1.1

The language of propositional logic PL consists of:

- ▶ a countable set  $V = \{v_n \mid n \in \mathbb{N}\}$  of variables;
- ▶ the logic connectives  $\neg$  (non),  $\rightarrow$  (implies)
- parantheses: ( , ).
- The set *Sym* of symbols of *PL* is

$$Sym := V \cup \{\neg, \rightarrow, (,)\}.$$

• We denote variables by  $u, v, x, y, z \dots$ 



#### Language

# Definition 1.2

The set Expr of expressions of PL is the set of all finite sequences of symbols of PL.

#### Definition 1.3

Let  $\theta = \theta_0 \theta_1 \dots \theta_{k-1}$  be an expression, where  $\theta_i \in Sym$  for all  $i = 0, \dots, k-1$ .

- ▶ If  $0 \le i \le j \le k-1$ , then the expression  $\theta_i \dots \theta_j$  is called the (i,j)-subexpression of  $\theta$ .
- We say that an expression  $\psi$  appears in  $\theta$  if there exists  $0 \le i \le j \le k-1$  such that  $\psi$  is the (i,j)-subexpression of  $\theta$ .
- We denote by  $Var(\theta)$  the set of variables appearing in  $\theta$ .

The definition of formulas is an example of an inductive definition.

#### Definition 1.4

The formulas of PL are the expressions of PL defined as follows:

- (F0) Any variable is a formula.
- (F1) If  $\varphi$  is a formula, then  $(\neg \varphi)$  is a formula.
- (F2) If  $\varphi$  and  $\psi$  are formulas, then  $(\varphi \to \psi)$  is a formula.
- (F3) Only the expressions obtained by applying rules (F0), (F1), (F2) are formulas.

#### **Notations**

The set of formulas is denoted by *Form*. Formulas are denoted by  $\varphi, \psi, \chi, \ldots$ 

# Proposition 1.5

The set Form is countable.

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#### Language

# Proposition 1.7 (Induction principle on formulas)

Let  $\Gamma$  be a set of formulas satisfying the following properties:

- V ⊂ Γ.
- ▶ Γ is closed to ¬, that is:  $\varphi \in \Gamma$  implies  $(\neg \varphi) \in \Gamma$ .
- ightharpoonup Γ is closed to  $\rightarrow$ , that is:  $\varphi, \psi ∈ \Gamma$  implies  $(\varphi → \psi) ∈ \Gamma$ .

Then  $\Gamma = Form$ .

It is used to prove that all formulas have a property  $\mathcal{P}$ : we define  $\Gamma$  as the set of all formulas satisfying  $\mathcal{P}$  and apply induction on formulas to obtain that  $\Gamma = Form$ .



# Language

#### Unique readability

If  $\varphi$  is a formula, then exactly one of the following hold:

- $\triangleright \varphi = v$ , where  $v \in V$ .
- $ightharpoonup \varphi = (\neg \psi)$ , where  $\psi$  is a formula.
- $ightharpoonup \varphi = (\psi \to \chi)$ , where  $\psi, \chi$  are formulas.

Furthermore,  $\varphi$  can be written in a unique way in one of these forms.

#### Definition 1.6

Let  $\varphi$  be a formula. A subformula of  $\varphi$  is any formula  $\psi$  that appears in  $\varphi$ .



#### Language

The derived connectives  $\vee$  (or),  $\wedge$  (and),  $\leftrightarrow$  (if and only if) are introduced by the following abbreviations:

$$\varphi \lor \psi := ((\neg \varphi) \to \psi) 
\varphi \land \psi := \neg(\varphi \to (\neg \psi))) 
\varphi \leftrightarrow \psi := ((\varphi \to \psi) \land (\psi \to \varphi))$$

#### Conventions and notations

- ► The external parantheses are omitted, we put them only when necessary. We write  $\neg \varphi$ ,  $\varphi \rightarrow \psi$ , but we write  $(\varphi \rightarrow \psi) \rightarrow \chi$ .
- ▶ To reduce the use of parentheses, we assume that
  - ightharpoonup has higher precedence than  $\rightarrow$ ,  $\land$ ,  $\lor$ ,  $\leftrightarrow$ ;
  - $\wedge$ ,  $\vee$  have higher precedence than  $\rightarrow$ ,  $\leftrightarrow$ .
- ▶ Hence, the formula  $(((\varphi \to (\psi \lor \chi)) \land ((\neg \psi) \leftrightarrow (\psi \lor \chi)))$  is written as  $(\varphi \to \psi \lor \chi) \land (\neg \psi \leftrightarrow \psi \lor \chi)$ .



#### Truth values

We use the following notations for the truth values:

1 for true and 0 for false.

Hence, the set of truth values is  $\{0,1\}$ .

Define the following operations on  $\{0,1\}$  using truth tables.

$$abla : \{0,1\} \to \{0,1\}, \qquad \begin{array}{c|c}
p & \neg p \\
\hline
0 & 1 \\
1 & 0
\end{array}$$



#### Semantics



#### Semantics

#### Definition 1.8

An evaluation (or interpretation) is a function  $e: V \to \{0,1\}$ .

#### Theorem 1.9

For any evaluation  $e: V \to \{0,1\}$  there exists a unique function  $e^+: Form \to \{0,1\}$ 

satisfying the following properties:

- $ightharpoonup e^+(v) = e(v)$  for all  $v \in V$ .
- $e^+(\neg \varphi) = \neg e^+(\varphi)$  for any formula  $\varphi$ .
- $e^+(\varphi \to \psi) = e^+(\varphi) \to e^+(\psi)$  for any formulas  $\varphi$ ,  $\psi$ .

# Proposition 1.10

For any formula  $\varphi$  and all evaluations  $e_1, e_2 : V \to \{0, 1\}$ , if  $e_1(v) = e_2(v)$  for all  $v \in Var(\varphi)$ , then  $e_1^+(\varphi) = e_2^+(\varphi)$ .



#### Semantics

Let  $\varphi$  be a formula.

#### Definition 1.11

- An evaluation  $e: V \to \{0,1\}$  is a model of  $\varphi$  if  $e^+(\varphi) = 1$ . Notation:  $e \models \varphi$ .
- $ightharpoonup \varphi$  is satisfiable if it has a model.
- ▶ If  $\varphi$  is not satisfiable, we also say that  $\varphi$  is unsatisfiable or contradictory.
- $ightharpoonup \varphi$  is a tautology if every evaluation is a model of  $\varphi$ . Notation:  $\models \varphi$ .

## Notation 1.12

The set of models of  $\varphi$  is denoted by  $Mod(\varphi)$ .



#### Semantics

#### Remark 1.13

- $\blacktriangleright \varphi$  is a tautology iff  $\neg \varphi$  is unsatisfiable.
- $\triangleright \varphi$  is unsatisfiable iff  $\neg \varphi$  is a tautology.

# Proposition 1.14

Let  $e: V \to \{0,1\}$  be an evaluation. Then for all formulas  $\varphi$ ,  $\psi$ ,

- $ightharpoonup e 
  vdash \neg \varphi \text{ iff } e 
  vdash \varphi.$
- $e \vDash \varphi \rightarrow \psi$  iff  $(e \vDash \varphi \text{ implies } e \vDash \psi)$  iff  $(e \nvDash \varphi \text{ or } e \vDash \psi)$ .
- $ightharpoonup e dash \varphi \lor \psi$  iff  $(e dash \varphi \text{ or } e dash \psi)$ .
- ightharpoonup  $e \vDash \varphi \land \psi$  iff  $(e \vDash \varphi \text{ and } e \vDash \psi)$ .



#### Semantics

#### Definition 1.15

Let  $\varphi, \psi$  be formulas. We say that

- $\varphi$  is a semantic consequence of  $\psi$  if  $Mod(\psi) \subseteq Mod(\varphi)$ . Notation:  $\psi \models \varphi$ .
- $\varphi$  and  $\psi$  are (logically) equivalent if  $Mod(\psi) = Mod(\varphi)$ .

  Notation:  $\varphi \sim \psi$ .

#### Remark 1.16

Let  $\varphi, \psi$  be formulas.

- $\blacktriangleright \psi \vDash \varphi \text{ iff } \vDash \psi \rightarrow \varphi.$
- $\blacktriangleright \ \psi \sim \varphi \ \text{iff } (\psi \vDash \varphi \ \text{and} \ \varphi \vDash \psi) \ \text{iff} \ \vDash \psi \leftrightarrow \varphi.$



#### Semantics

For all formulas  $\varphi, \psi, \chi$ ,

$$\models \varphi \vee \neg \varphi$$

$$\models \neg(\varphi \land \neg\varphi)$$

$$\models \varphi \wedge \psi \to \varphi$$

$$\models \varphi \rightarrow \varphi \lor \psi$$

$$\models \varphi \rightarrow (\psi \rightarrow \varphi)$$

$$\models (\varphi \to (\psi \to \chi)) \to ((\varphi \to \psi) \to (\varphi \to \chi))$$

$$\models (\varphi \to \psi) \to ((\psi \to \chi) \to (\varphi \to \chi))$$

$$\models (\varphi \to \psi) \lor (\neg \varphi \to \psi)$$

$$\models (\varphi \to \psi) \lor (\varphi \to \neg \psi)$$

$$\models \neg \varphi \rightarrow (\neg \psi \leftrightarrow (\psi \rightarrow \varphi))$$

$$\models (\varphi \to \psi) \to (((\varphi \to \chi) \to \psi) \to \psi)$$

$$\vdash \neg \psi \rightarrow (\psi \rightarrow \varphi)$$



#### Semantics



$$\varphi \sim \neg \neg \varphi$$

$$\varphi \rightarrow \psi \sim \neg \psi \rightarrow \neg \varphi$$

$$\varphi \lor \psi \sim \neg (\neg \varphi \land \neg \psi)$$

$$\varphi \land \psi \sim \neg (\neg \varphi \lor \neg \psi)$$

$$\varphi \rightarrow (\psi \rightarrow \chi) \sim \varphi \land \psi \rightarrow \chi$$

$$\varphi \sim \varphi \land \varphi \sim \varphi \lor \varphi$$

$$\varphi \land \psi \sim \psi \land \varphi$$

$$\varphi \lor \psi \sim \psi \lor \varphi$$

$$\varphi \land (\psi \land \chi) \sim (\varphi \land \psi) \land \chi$$

$$\varphi \lor (\psi \lor \chi) \sim (\varphi \lor \psi) \lor \chi$$

$$\varphi \lor (\varphi \land \psi) \sim \varphi$$

$$\varphi \land (\varphi \lor \psi) \sim \varphi$$



#### Semantics

$$\varphi \wedge (\psi \vee \chi) \sim (\varphi \wedge \psi) \vee (\varphi \wedge \chi)$$

$$\varphi \vee (\psi \wedge \chi) \sim (\varphi \vee \psi) \wedge (\varphi \vee \chi)$$

$$\varphi \rightarrow \psi \wedge \chi \sim (\varphi \rightarrow \psi) \wedge (\varphi \rightarrow \chi)$$

$$\varphi \rightarrow \psi \vee \chi \sim (\varphi \rightarrow \psi) \vee (\varphi \rightarrow \chi)$$

$$\varphi \wedge \psi \rightarrow \chi \sim (\varphi \rightarrow \chi) \vee (\psi \rightarrow \chi)$$

$$\varphi \vee \psi \rightarrow \chi \sim (\varphi \rightarrow \chi) \wedge (\psi \rightarrow \chi)$$

$$\varphi \rightarrow (\psi \rightarrow \chi) \sim \psi \rightarrow (\varphi \rightarrow \chi)$$

$$\sim (\varphi \rightarrow \psi) \rightarrow (\varphi \rightarrow \chi)$$

$$\sim (\varphi \rightarrow \psi) \rightarrow (\varphi \rightarrow \chi)$$

$$\neg \varphi \sim \varphi \rightarrow \neg \varphi \sim (\varphi \rightarrow \psi) \wedge (\varphi \rightarrow \neg \psi)$$

$$\varphi \rightarrow \psi \sim \neg \varphi \vee \psi \sim \neg (\varphi \wedge \neg \psi)$$

$$\varphi \vee \psi \sim \varphi \vee (\neg \varphi \wedge \psi) \sim (\varphi \rightarrow \psi) \rightarrow \psi$$

$$\varphi \leftrightarrow (\psi \leftrightarrow \chi) \sim (\varphi \leftrightarrow \psi) \leftrightarrow \chi$$



#### Semantics

It is often useful to have a canonical tautology and a canonical unsatisfiable formula.

#### Remark 1.17

 $v_0 \rightarrow v_0$  is a tautology and  $\neg (v_0 \rightarrow v_0)$  is unsatisfiable.

#### Notation 1.18

Denote  $v_0 \rightarrow v_0$  by  $\top$  and call it the truth. Denote  $\neg(v_0 \rightarrow v_0)$  by  $\bot$  and call it the false.

#### Remark 1.19

- $ightharpoonup \varphi$  is a tautology iff  $\varphi \sim \top$ .
- $ightharpoonup \varphi$  is unsatisfiable iff  $\varphi \sim \bot$ .



#### Semantics

Let  $\Gamma$  be a set of formulas.

#### Definition 1.20

An evaluation  $e:V\to\{0,1\}$  is a model of  $\Gamma$  if it is a model of every formula from  $\Gamma$ .

*Notation:*  $e \models \Gamma$ .

#### Notation 1.21

The set of models of  $\Gamma$  is denoted by  $Mod(\Gamma)$ .

#### Definition 1.22

A formula  $\varphi$  is a semantic consequence of  $\Gamma$  if  $Mod(\Gamma) \subseteq Mod(\varphi)$ . Notation:  $\Gamma \vDash \varphi$ .



#### Definition 1.23

- **Γ** is satisfiable if it has a model.
- ightharpoonup  $\Gamma$  is finitely satisfiable if every finite subset of  $\Gamma$  is satisfiable.
- ▶ If  $\Gamma$  is not satisfiable, we say also that  $\Gamma$  is unsatisfiable or contradictory.

# Proposition 1.24

The following are equivalent:

- Γ is unsatisfiable.
- Γ ⊨ ⊥.

# Theorem 1.25 (Compactness Theorem)

 $\Gamma$  is satisfiable iff  $\Gamma$  is finitely satisfiable.



# Syntax

We use a deductive system of Hilbert type for LP.

# Logical axioms

The set Axm of (logical) axioms of LP consists of:

- (A1)  $\varphi \rightarrow (\psi \rightarrow \varphi)$
- (A2)  $(\varphi \to (\psi \to \chi)) \to ((\varphi \to \psi) \to (\varphi \to \chi))$
- (A3)  $(\neg \psi \rightarrow \neg \varphi) \rightarrow (\varphi \rightarrow \psi)$ ,

where  $\varphi$ ,  $\psi$  and  $\chi$  are formulas.

#### The deduction rule

For any formulas  $\varphi$ ,  $\psi$ , from  $\varphi$  and  $\varphi \to \psi$  infer  $\psi$  (modus ponens or (MP)):

$$\frac{\varphi, \ \varphi \to \psi}{\psi}$$

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#### Syntax

Let  $\Gamma$  be a set of formulas. The definition of  $\Gamma$ -theorems is another example of an inductive definition.

#### Definition 1.26

The  $\Gamma$ -theorems of PL are the formulas defined as follows:

- (T0) Every logical axiom is a  $\Gamma$ -theorem.
- (T1) Every formula of  $\Gamma$  is a  $\Gamma$ -theorem.
- (T2) If  $\varphi$  and  $\varphi \to \psi$  are  $\Gamma$ -theorems, then  $\psi$  is a  $\Gamma$ -theorem.
- (T3) Only the formulas obtained by applying rules (T0), (T1), (T2) are  $\Gamma$ -theorems.

If  $\varphi$  is a  $\Gamma$ -theorem, then we also say that  $\varphi$  is deduced from the hypotheses  $\Gamma$ .



# Syntax

#### **Notations**

 $\Gamma \vdash \varphi : \Leftrightarrow \varphi \text{ is a } \Gamma\text{-theorem}$  $\vdash \varphi : \Leftrightarrow \emptyset \vdash \varphi.$ 

# Definition 1.27

A formula  $\varphi$  is called a theorem of LP if  $\vdash \varphi$ .

By a reformulation of the conditions (T0), (T1), (T2) using the notation  $\vdash$ , we get

#### Remark 1.28

- ▶ If  $\varphi$  is an axiom, then  $\Gamma \vdash \varphi$ .
- ▶ If  $\varphi \in \Gamma$ , then  $\Gamma \vdash \varphi$ .
- ▶ If  $\Gamma \vdash \varphi$  and  $\Gamma \vdash \varphi \rightarrow \psi$ , then  $\Gamma \vdash \psi$ .



#### Definition 1.29

A  $\Gamma$ -proof (or proof from the hypotheses  $\Gamma$ ) is a sequence of formulas  $\theta_1, \ldots, \theta_n$  such that for all  $i \in \{1, \ldots, n\}$ , one of the following holds:

- $\triangleright \theta_i$  is an axiom.
- $\bullet$   $\theta_i \in \Gamma$ .
- there exist k, j < i such that  $\theta_k = \theta_i \rightarrow \theta_i$ .

#### Definition 1.30

Let  $\varphi$  be a formula. A  $\Gamma$ -proof of  $\varphi$  or a proof of  $\varphi$  from the hypotheses  $\Gamma$  is a  $\Gamma$ -proof  $\theta_1, \ldots, \theta_n$  such that  $\theta_n = \varphi$ .

# Proposition 1.31

For any formula  $\varphi$ ,

 $\Gamma \vdash \varphi$  iff there exists a  $\Gamma$ -proof of  $\varphi$ .



# Syntax

# Theorem 1.32 (Deduction Theorem)

Let  $\Gamma \cup \{\varphi, \psi\}$  be a set of formulas. Then

$$\Gamma \cup \{\varphi\} \vdash \psi \quad \textit{iff} \quad \Gamma \vdash \varphi \rightarrow \psi.$$

# Proposition 1.33

For any formulas  $\varphi, \psi, \chi$ ,

$$\vdash (\varphi \to \psi) \to ((\psi \to \chi) \to (\varphi \to \chi))$$
$$\vdash (\varphi \to (\psi \to \chi)) \to (\psi \to (\varphi \to \chi))$$

# Proposition 1.34

Let  $\Gamma \cup \{\varphi, \psi, \chi\}$  be a set of formulas.

$$\begin{array}{ccc} \Gamma \vdash \varphi \rightarrow \psi \ \textit{and} \ \Gamma \vdash \psi \rightarrow \chi & \Rightarrow & \Gamma \vdash \varphi \rightarrow \chi \\ \Gamma \cup \{\neg \psi\} \vdash \neg(\varphi \rightarrow \varphi) & \Rightarrow & \Gamma \vdash \psi \\ \Gamma \cup \{\psi\} \vdash \varphi \ \textit{and} \ \Gamma \cup \{\neg \psi\} \vdash \varphi & \Rightarrow & \Gamma \vdash \varphi. \end{array}$$



#### Consistent sets

Let  $\Gamma$  be a set of formulas.

#### Definition 1.35

 $\Gamma$  is called <u>consistent</u> if there exists a formula  $\varphi$  such that  $\Gamma \not\vdash \varphi$ .  $\Gamma$  is said to be inconsistent if it is not consistent, that is  $\Gamma \vdash \varphi$  for any formula  $\varphi$ .

#### Proposition 1.36

- ▶ ∅ is consistent.
- ▶ The set of theorems is consistent.

# Proposition 1.37

The following are equivalent:

- Γ is inconsistent.
- **▶** Γ ⊢ ⊥.



# Completeness Theorem

# Theorem 1.38 (Completeness Theorem (version 1))

Let  $\Gamma$  be a set of formulas. Then

 $\Gamma$  is consistent  $\iff$   $\Gamma$  is satisfiable.

# Theorem 1.39 (Completeness Theorem (version 2))

Let  $\Gamma$  be a set of formulas. For any formula  $\varphi$ ,

$$\Gamma \vdash \varphi \iff \Gamma \vDash \varphi.$$



# First-order logic



# First-order languages

#### Definition 2.1

A first-order language  $\mathcal{L}$  consists of:

- ▶ a countable set  $V = \{v_n \mid n \in \mathbb{N}\}$  of variables;
- $\blacktriangleright$  the connectives  $\neg$  and  $\rightarrow$ ;
- parantheses ( , );
- ► the equality symbol =;
- **▶** the universal quantifier ∀;
- $\triangleright$  a set  $\mathcal{R}$  of relation symbols;
- ► a set F of function symbols;
- ► a set C of constant symbols;
- $\blacktriangleright$  an arity function ari :  $\mathcal{F} \cup \mathcal{R} \to \mathbb{N}^*$ .
- $ightharpoonup \mathcal{L}$  is uniquely determined by the quadruple  $\tau := (\mathcal{R}, \mathcal{F}, \mathcal{C}, \operatorname{ari})$ .
- ightharpoonup au is called the signature of  $\mathcal{L}$  or the similaritaty type of  $\mathcal{L}$ .



# First-order languages

Let  $\mathcal{L}$  be a first-order language.

• The set  $Sym_{\mathcal{L}}$  of symbols of  $\mathcal{L}$  is

$$Sym_{\mathcal{L}} := V \cup \{\neg, \rightarrow, (,), =, \forall\} \cup \mathcal{R} \cup \mathcal{F} \cup \mathcal{C}$$

- The elements of  $\mathcal{R} \cup \mathcal{F} \cup \mathcal{C}$  are called non-logical symbols.
- The elements of  $V \cup \{\neg, \rightarrow, (,), =, \forall\}$  are called logical symbols.
- We denote variables by  $x, y, z, v, \ldots$ , relation symbols by  $P, Q, R \ldots$ , function symbols by  $f, g, h, \ldots$  and constant symbols by  $c, d, e, \ldots$
- For every  $m \in \mathbb{N}^*$  we denote:

 $\mathcal{F}_m$  := the set of function symbols of arity m;

 $\mathcal{R}_m$  := the set of relation symbols of arity m.



# First-order languages

#### Definition 2.2

The set  $\mathsf{Expr}_\mathcal{L}$  of expressions of  $\mathcal{L}$  is the set of all finite sequences of symbols of  $\mathcal{L}$ .

#### Definition 2.3

Let  $\theta = \theta_0 \theta_1 \dots \theta_{k-1}$  be an expression of  $\mathcal{L}$ , where  $\theta_i \in Sym_{\mathcal{L}}$  for all  $i = 0, \dots, k-1$ .

- ▶ If  $0 \le i \le j \le k-1$ , then the expression  $\theta_i \dots \theta_j$  is called the (i,j)-subexpression of  $\theta$ .
- We say that an expression  $\psi$  appears in  $\theta$  if there exists  $0 \le i \le j \le k-1$  such that  $\psi$  is the (i,j)-subexpression of  $\theta$ .
- We denote by  $Var(\theta)$  the set of variables appearing in  $\theta$ .

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# First-order languages

#### Definition 2.4

The terms of  $\mathcal{L}$  are the expressions defined as follows:

- (T0) Every variable is a term.
- (T1) Every constant symbol is a term.
- (T2) If  $m \ge 1$ ,  $f \in \mathcal{F}_m$  and  $t_1, \ldots, t_m$  are terms, then  $ft_1 \ldots t_m$  is a term.
- (T3) Only the expressions obtained by applying rules (T0), (T1), (T2) are terms.

#### Notations:

- ▶ The set of terms is denoted by  $Term_{\mathcal{L}}$ .
- ightharpoonup Terms are denoted by  $t, s, t_1, t_2, s_1, s_2, \dots$
- $\triangleright$  Var(t) is the set of variables that appear in the term t.

#### Definition 2.5

A term t is called closed if  $Var(t) = \emptyset$ .



# First-order languages

# Proposition 2.6 (Induction on terms)

Let  $\Gamma$  be a set of terms satisfying the following properties:

- **Γ** contains the variables and the constant symbols.
- ▶ If m > 1,  $f \in \mathcal{F}_m$  and  $t_1, \ldots, t_m \in \Gamma$ , then  $ft_1 \ldots t_m \in \Gamma$ .

Then  $\Gamma = Term_{\mathcal{L}}$ .

It is used to prove that all terms have a property  $\mathcal{P}$ : we define  $\Gamma$  as the set of all terms satisfying  $\mathcal{P}$  and apply induction on terms to obtain that  $\Gamma = \mathit{Term}_{\mathcal{L}}$ .



# First-order languages

#### Definition 2.7

The atomic formulas of  $\mathcal L$  are the expressions having one of the following forms:

- $\triangleright$  (s = t), where s, t are terms;
- $ightharpoonup (Rt_1 ... t_m)$ , where  $R \in \mathcal{R}_m$  and  $t_1, ..., t_m$  are terms.

#### Definition 2.8

The formulas of  $\mathcal{L}$  are the expressions defined as follows:

- (F0) Every atomic formula is a formula.
- (F1) If  $\varphi$  is a formula, then  $(\neg \varphi)$  is a formula.
- (F2) If  $\varphi$  and  $\psi$  are formulas, then  $(\varphi \to \psi)$  is a formula.
- (F3) If  $\varphi$  is a formula, then  $(\forall x \varphi)$  is a formula for every variable x.
- (F4) Only the expressions obtained by applying rules (F0), (F1), (F2), (F3) are formulas.



# First-order languages

#### **Notations**

- ▶ The set of formulas is denoted by  $Form_{\mathcal{L}}$ .
- Formulas are denoted by  $\varphi, \psi, \chi, \ldots$
- $ightharpoonup Var(\varphi)$  is the set of variables that appear in the formula  $\varphi$ .

#### Unique readability

If  $\varphi$  is a formula, then exactly one of the following hold:

- $ightharpoonup \varphi = (s = t)$ , where s, t are terms.
- $ightharpoonup \varphi = (Rt_1 \dots t_m)$ , where  $R \in \mathcal{R}_m$  and  $t_1, \dots, t_m$  are terms.
- $ightharpoonup \varphi = (\neg \psi)$ , where  $\psi$  is a formula.
- $ightharpoonup \varphi = (\psi \to \chi)$ , where  $\psi, \chi$  are formulas.
- $ightharpoonup \varphi = (\forall x \psi)$ , where x is a variable and  $\psi$  is a formula.

Furthermore,  $\varphi$  can be written in a unique way in one of these forms.



# Proposition 2.9 (Induction principle on formulas)

Let  $\Gamma$  be a set of formulas satisfying the following properties:

- **Γ** contains all atomic formulas.
- ▶  $\Gamma$  is closed to  $\neg$ ,  $\rightarrow$  and  $\forall x$  (for any variable x), that is: if  $\varphi, \psi \in \Gamma$ , then  $(\neg \varphi), (\varphi \rightarrow \psi), (\forall x \varphi) \in \Gamma$ .

Then  $\Gamma = Form_{\mathcal{L}}$ .

It is used to prove that all formulas have a property  $\mathcal{P}$ : we define  $\Gamma$  as the set of all formulas satisfying  $\mathcal{P}$  and apply induction on formulas to obtain that  $\Gamma = Form_{\mathcal{L}}$ .



# First-order languages

#### Derived connectives

Connectives  $\lor$ ,  $\land$ ,  $\leftrightarrow$  and the existential quantifier  $\exists$  are introduced by the following abbreviations:

$$\varphi \lor \psi := ((\neg \varphi) \to \psi) 
\varphi \land \psi := \neg(\varphi \to (\neg \psi))) 
\varphi \leftrightarrow \psi := ((\varphi \to \psi) \land (\psi \to \varphi)) 
\exists x \varphi := (\neg \forall x (\neg \varphi))$$



# First-order languages

Usually the external parantheses are omitted, we write them only when necessary. We write  $s=t, Rt_1 \dots t_m, ft_1 \dots t_m, \neg \varphi, \varphi \to \psi, \forall x \varphi$ . On the other hand, we write  $(\varphi \to \psi) \to \chi$ .

To reduce the use of parentheses, we assume that

- ▶ ¬ has higher precedence than  $\rightarrow$ ,  $\land$ ,  $\lor$ ,  $\leftrightarrow$ ;
- $\blacktriangleright$   $\land$ ,  $\lor$  have higher precedence than  $\rightarrow$ ,  $\leftrightarrow$ ;
- ▶ quantifiers  $\forall$ ,  $\exists$  have higher precedence than the other connectives. Thus,  $\forall x \varphi \rightarrow \psi$  is  $(\forall x \varphi) \rightarrow \psi$  and not  $\forall x (\varphi \rightarrow \psi)$ .



# First-order languages

- We write sometimes  $f(t_1, ..., t_m)$  instead of  $ft_1 ... t_m$  and  $R(t_1, ..., t_m)$  instead of  $Rt_1 ... t_m$ .
- ► Function/relation symbols of arity 1 are called unary. Function/relation symbols of arity 2 are called binary.
- ▶ If f is a binary function symbol, we write  $t_1ft_2$  instead of  $ft_1t_2$ .
- ▶ If R is a binary relation symbol, we write  $t_1Rt_2$  instead of  $Rt_1t_2$ .

We identify often a language  $\mathcal{L}$  with the set of its non-logical symbols and write  $\mathcal{L} = (\mathcal{R}, \mathcal{F}, \mathcal{C})$ .



# First-order languages

#### Definition 2.10

Let  $\varphi = \varphi_0 \varphi_1 \dots \varphi_{n-1}$  be a formula of  $\mathcal{L}$  and x be a variable.

- We say that x occurs bound on position k in  $\varphi$  if  $x = \varphi_k$  and there exists  $0 \le i \le k \le j \le n-1$  such that the (i,j)-subexpression of  $\varphi$  has the form  $\forall x \psi$ .
- We say that x occurs free on position k in  $\varphi$  if  $x = \varphi_k$ , but x does not occur bound on position k in  $\varphi$ .
- ightharpoonup x is a bound variable of  $\varphi$  if there exists k such that x occurs bound on position k in  $\varphi$ .
- ightharpoonup x is a free variable of  $\varphi$  if there exists k such that x occurs free on position k in  $\varphi$ .

# Example

Let  $\varphi = \forall x(x = y) \rightarrow x = z$ . Free variables: x, y, z. Bound variables: x.



# First-order languages

Notation:  $FV(\varphi)$  := the set of free variables of  $\varphi$ .

#### Alternative definition

The set  $FV(\varphi)$  of free variables of a formula  $\varphi$  can be also defined by induction on formulas:

$$FV(\varphi)$$
 =  $Var(\varphi)$ , if  $\varphi$  is an atomic formula

$$FV(\neg \varphi) = FV(\varphi)$$

$$FV(\varphi \to \psi) = FV(\varphi) \cup FV(\psi)$$

$$FV(\forall x\varphi) = FV(\varphi) \setminus \{x\}.$$



#### *L*-structures

#### Definition 2.11

An  $\mathcal{L}$ -structure is a quadruple

$$\mathcal{A} = (\mathcal{A}, \mathcal{F}^{\mathcal{A}}, \mathcal{R}^{\mathcal{A}}, \mathcal{C}^{\mathcal{A}})$$

#### where

- A is a nonempty set.
- ▶  $\mathcal{F}^{\mathcal{A}} = \{ f^{\mathcal{A}} \mid f \in \mathcal{F} \}$  is a set of functions on A; if f has arity m, then  $f^{\mathcal{A}} : A^m \to A$ .
- $\mathcal{R}^{\mathcal{A}} = \{R^{\mathcal{A}} \mid R \in \mathcal{R}\}$  is a set of relations on A; if R has arity m, then  $R^{\mathcal{A}} \subset A^{m}$ .
- $\triangleright C^{\mathcal{A}} = \{ c^{\mathcal{A}} \in A \mid c \in \mathcal{C} \}.$
- ightharpoonup A is called the universe of the structure A. Notation: A = |A|
- ▶  $f^{\mathcal{A}}$  (  $R^{\mathcal{A}}$ ,  $c^{\mathcal{A}}$ , respectively) is called the interpretation of f (R, c, respectively) in  $\mathcal{A}$ .



# Examples - The language of equality $\mathcal{L}_{=}$

$$\mathcal{L}_{=}=(\mathcal{R},\mathcal{F},\mathcal{C})$$
, where

- $ightharpoonup \mathcal{R} = \mathcal{F} = \mathcal{C} = \emptyset;$
- this language is proper for expressing the properties of equality;
- $\triangleright$   $\mathcal{L}_{=}$ -structures are the nonempty sets.

# Examples of formulas:

• equality is symmetric:

$$\forall x \forall y (x = y \rightarrow y = x)$$

• the universe has at least three elements:

$$\exists x \exists y \exists z (\neg(x = y) \land \neg(y = z) \land \neg(z = x))$$



# Examples - The language of arithmetics $\mathcal{L}_{\mathsf{ar}}$

 $\mathcal{L}_{ar} = (\mathcal{R}, \mathcal{F}, \mathcal{C})$ , where

- $ightharpoonup \mathcal{R} = \{\dot{<}\}; \dot{<} \text{ is a binary relation symbol;}$
- $\mathcal{F} = \{\dot{+}, \dot{\times}, \dot{S}\}; \dot{+}, \dot{\times}$  are binary function symbols and  $\dot{S}$  is a unary function symbol;
- $ightharpoonup \mathcal{C} = \{\dot{0}\}.$

We write  $\mathcal{L}_{ar} = (\dot{\langle}; \dot{+}, \dot{\times}, \dot{S}; \dot{0})$  or  $\mathcal{L}_{ar} = (\dot{\langle}, \dot{+}, \dot{\times}, \dot{S}, \dot{0})$ .

The natural example of  $\mathcal{L}_{ar}$ -structure:

$$\mathcal{N} := (\mathbb{N}, <, +, \cdot, S, 0),$$

where  $S: \mathbb{N} \to \mathbb{N}$ , S(m) = m+1 is the successor function. Thus,

$$\dot{<}^{\mathcal{N}}=<,\ \dot{+}^{\mathcal{N}}=+,\ \dot{\times}^{\mathcal{N}}=\cdot,\ \dot{S}^{\mathcal{N}}=S,\ \dot{0}^{\mathcal{N}}=0.$$

• Another example of  $\mathcal{L}_{ar}$ -structure:  $\mathcal{A} = (\{0,1\},<,\vee,\wedge,\neg,1)$ .



# Examples - The language with a binary relation symbol

 $\mathcal{L}_R = (\mathcal{R}, \mathcal{F}, \mathcal{C})$ , where

- $ightharpoonup \mathcal{R} = \{R\}; R \text{ is a binary relation symbol;}$
- $\triangleright$   $\mathcal{F} = \mathcal{C} = \emptyset$ :
- $\triangleright$   $\mathcal{L}$ -structures are nonempty sets together with a binary relation.
- ▶ If we are interested in partially ordered sets  $(A, \leq)$ , we use the symbol  $\leq$  instead of R and we denote the language by  $\mathcal{L}_{\leq}$ .
- ▶ If we are interested in strictly ordered sets (A, <), we use the symbol  $\dot{<}$  instead of R and we denote the language by  $\mathcal{L}_{<}$ .
- If we are interested in graphs G = (V, E), we use the symbol  $\dot{E}$  instead of R and we denote the language by  $\mathcal{L}_{Graf}$ .
- ▶ If we are interested in structures  $(A, \in)$ , we use the symbol  $\in$  instead of R and we denote the language by  $\mathcal{L}_{\in}$ .



#### Semantics

Let  $\mathcal{L}$  be a first-order language and  $\mathcal{A}$  be an  $\mathcal{L}$ -structure.

#### Definition 2.12

An A-assignment or A-evaluation is a function  $e: V \to A$ .

When the  $\mathcal{L}$ -structure  $\mathcal{A}$  is clear from the context, we also write simply e is an assignment.

In the following,  $e:V\to A$  is an  $\mathcal{A}$ -assignment.

# Definition 2.13 (Interpretation of terms)

The interpretation  $t^{\mathcal{A}}(e) \in A$  of a term t under the  $\mathcal{A}$ -assignment e is defined by induction on terms :

- ightharpoonup if  $t=x\in V$ , then  $t^{\mathcal{A}}(e):=e(x)$ ;
- ▶ if  $t = c \in C$ , then  $t^{A}(e) := c^{A}$ ;
- ightharpoonup if  $t=ft_1\ldots t_m$ , then  $t^{\mathcal{A}}(e):=f^{\mathcal{A}}(t_1^{\mathcal{A}}(e),\ldots,t_m^{\mathcal{A}}(e)).$



# Semantics

#### The interpretation

$$arphi^{\mathcal{A}}(e) \in \{0,1\}$$

of a formula  $\varphi$  under the A-assignment e is defined by induction on formulas.

$$(s = t)^{\mathcal{A}}(e) = \begin{cases} 1 & \text{if } s^{\mathcal{A}}(e) = t^{\mathcal{A}}(e) \\ 0 & \text{otherwise.} \end{cases}$$

$$(Rt_1 \dots t_m)^{\mathcal{A}}(e) = \begin{cases} 1 & \text{if } R^{\mathcal{A}}(t_1^{\mathcal{A}}(e), \dots, t_m^{\mathcal{A}}(e)) \\ 0 & \text{otherwise.} \end{cases}$$



#### Semantics

# Negation and implication

- $(\neg \varphi)^{\mathcal{A}}(e) = 1 \varphi^{\mathcal{A}}(e);$
- $\blacktriangleright$   $(\varphi \to \psi)^{\mathcal{A}}(e) = \varphi^{\mathcal{A}}(e) \to \psi^{\mathcal{A}}(e)$ , where,

Hence.

- $\blacktriangleright$   $(\neg \varphi)^{\mathcal{A}}(e) = 1$  iff  $\varphi^{\mathcal{A}}(e) = 0$ .
- $\blacktriangleright$   $(\varphi \to \psi)^{\mathcal{A}}(e) = 1$  iff  $(\varphi^{\mathcal{A}}(e) = 0 \text{ or } \psi^{\mathcal{A}}(e) = 1)$ .



#### Semantics

#### Notation

For any variable  $x \in V$  and any  $a \in A$ , we define a new  $\mathcal{A}$ -assignment  $e_{x \leftarrow a}: V \rightarrow A$  by

$$e_{x \leftarrow a}(v) = \left\{ \begin{array}{ll} e(v) & \text{if } v \neq x \\ a & \text{if } v = x. \end{array} \right.$$

# Universal quantifier

$$(\forall x \varphi)^{\mathcal{A}}(e) = \begin{cases} 1 & \text{if } \varphi^{\mathcal{A}}(e_{x \leftarrow a}) = 1 \text{ for all } a \in A \\ 0 & \text{otherwise.} \end{cases}$$



# Semantics

Let A be an  $\mathcal{L}$ -structure and  $e: V \to A$  be an A-assignment.

#### Definition 2.14

Let  $\varphi$  be a formula. We say that:

- ightharpoonup e satisfies  $\varphi$  in  $\mathcal{A}$  if  $\varphi^{\mathcal{A}}(e) = 1$ . Notation:  $\mathcal{A} \vDash \varphi[e]$ .
- e does not satisfy  $\varphi$  in  $\mathcal{A}$  if  $\varphi^{\mathcal{A}}(e) = 0$ . Notation:  $\mathcal{A} \not\models \varphi[e]$ .

# Proposition 2.15

For all formulas  $\varphi, \psi$  and any variable x,

- (i)  $\mathcal{A} \models \neg \varphi[e]$  iff  $\mathcal{A} \not\models \varphi[e]$ .
- (ii)  $A \vDash (\varphi \to \psi)[e]$  iff  $(A \vDash \varphi[e]$  implies  $A \vDash \psi[e])$  iff  $(A \nvDash \varphi[e]$  or  $A \vDash \psi[e])$ .
- (iii)  $A \models (\forall x \varphi)[e]$  iff for all  $a \in A$ ,  $A \models \varphi[e_{x \leftarrow a}]$ .



# Semantics

# Proposition 2.16

For all formulas  $\varphi, \psi$  and any variable x,

- (i)  $A \vDash (\varphi \land \psi)[e]$  iff  $(A \vDash \varphi[e])$  and  $A \vDash \psi[e]$ .
- (ii)  $A \vDash (\varphi \lor \psi)[e]$  iff  $(A \vDash \varphi[e]$  or  $A \vDash \psi[e])$ .
- (iii)  $A \vDash (\varphi \leftrightarrow \psi)[e]$  iff  $(A \vDash \varphi[e])$  iff  $A \vDash \psi[e]$ .
- (iv)  $A \models (\exists x \varphi)[e]$  iff there exists  $a \in A$  s.t.  $A \models \varphi[e_{x \leftarrow a}]$ .



Let arphi be a formula of  $\mathcal{L}.$ 

#### Definition 2.17

 $\varphi$  is satisfiable if there exists an  $\mathcal{L}$ -structure  $\mathcal{A}$  and an  $\mathcal{A}$ -assignment e such that  $\mathcal{A} \vDash \varphi[e]$ . We also say that  $(\mathcal{A}, e)$  is a model of  $\varphi$ .

#### Definition 2.18

 $\varphi$  is true in an  $\mathcal{L}$ -structure  $\mathcal{A}$  if  $\mathcal{A} \vDash \varphi[e]$  for all  $\mathcal{A}$ -assignments e. We also say that  $\mathcal{A}$  satisfies  $\varphi$  or that  $\mathcal{A}$  is a model of  $\varphi$ . Notation:  $\mathcal{A} \vDash \varphi$ 

#### Definition 2.19

 $\varphi$  is universally true (or logically valid or, simply, valid) if  $A \vDash \varphi$  for all  $\mathcal{L}$ -structures A.

*Notation:*  $\models \varphi$ 

# Semantics

Let  $\varphi, \psi$  be formulas of  $\mathcal{L}$ .

#### Definition 2.20

 $\psi$  is a logical consequence of  $\varphi$  if for all  $\mathcal{L}$ -structures  $\mathcal{A}$  and all  $\mathcal{A}$ -assignments e,

$$\mathcal{A} \vDash \varphi[e]$$
 implies  $\mathcal{A} \vDash \psi[e]$ .

*Notation:*  $\varphi \models \psi$ 

#### Definition 2.21

 $\varphi$  and  $\psi$  are logically equivalent or, simply, equivalent if for all  $\mathcal{L}$ -structures  $\mathcal{A}$  and all  $\mathcal{A}$ -assignments e,

$$\mathcal{A} \vDash \varphi[e] \text{ iff } \mathcal{A} \vDash \psi[e].$$

*Notation:*  $\varphi \bowtie \psi$ 

#### Remark

- $\triangleright \varphi \vDash \psi \text{ iff } \vDash \varphi \rightarrow \psi.$



#### Semantics

For all formulas  $\varphi$ ,  $\psi$  and all variables x, y,

$$\neg \exists x \varphi \quad \exists \quad \forall x \neg \varphi \tag{1}$$

$$\neg \forall x \varphi \quad \exists x \neg \varphi \tag{2}$$

$$\forall x (\varphi \wedge \psi) \quad \exists \quad \forall x \varphi \wedge \forall x \psi \tag{3}$$

$$\forall x \varphi \vee \forall x \psi \models \forall x (\varphi \vee \psi) \tag{4}$$

$$\exists x (\varphi \wedge \psi) \models \exists x \varphi \wedge \exists x \psi \tag{5}$$

$$\exists x (\varphi \lor \psi) \quad \exists x \varphi \lor \exists x \psi \tag{6}$$

$$\forall x(\varphi \to \psi) \models \forall x\varphi \to \forall x\psi \tag{7}$$

$$\forall x(\varphi \to \psi) \models \exists x \varphi \to \exists x \psi \tag{8}$$

$$\forall x \varphi \models \exists x \varphi \tag{9}$$



#### Semantics

$$\varphi \models \exists x \varphi \tag{10}$$

$$\forall x \varphi \models \varphi \tag{11}$$

$$\forall x \forall y \varphi \quad \exists \quad \forall y \forall x \varphi \tag{12}$$

$$\exists x \exists y \varphi \quad \exists \ y \exists x \varphi \tag{13}$$

$$\exists y \forall x \varphi \models \forall x \exists y \varphi. \tag{14}$$



# Proposition 2.22

For all terms s, t, u,

- (i)  $\models t = t$ ;
- (ii)  $\models s = t \rightarrow t = s$ ;
- (iii)  $\models s = t \land t = u \rightarrow s = u$ .

# Proposition 2.23

For all  $m \ge 1$ ,  $f \in \mathcal{F}_m, R \in \mathcal{R}_m$  and all terms  $t_i, u_i, i = 1, \dots, m$ ,

$$\exists (t_1 = u_1) \land \ldots \land (t_m = u_m) \to ft_1 \ldots t_m = fu_1 \ldots u_m 
\exists (t_1 = u_1) \land \ldots \land (t_m = u_m) \to (Rt_1 \ldots t_m \leftrightarrow Ru_1 \ldots u_m)$$



#### Semantics

# Proposition 2.24

For any  $\mathcal{L}$ -structure  $\mathcal{A}$  and any  $\mathcal{A}$ -assignments  $e_1, e_2$ ,

(i) for any term t,

if 
$$e_1(v) = e_2(v)$$
 for all variables  $v \in Var(t)$ , then  $t^{\mathcal{A}}(e_1) = t^{\mathcal{A}}(e_2)$ .

(ii) for any formula  $\varphi$ ,

if 
$$e_1(v) = e_2(v)$$
 for all variables  $v \in FV(\varphi)$ , then  $A \vDash \varphi[e_1]$  iff  $A \vDash \varphi[e_2]$ .



#### Semantics

#### Proposition 2.25

For all formulas  $\varphi$ ,  $\psi$  and any variable  $x \notin FV(\varphi)$ ,

$$\varphi \ \ \exists x \varphi$$
 (15)

$$\varphi \ \ \exists \ \ \forall x \varphi$$
 (16)

$$\forall x (\varphi \wedge \psi) \quad \exists \quad \varphi \wedge \forall x \psi \tag{17}$$

$$\forall x (\varphi \lor \psi) \quad \exists \quad \varphi \lor \forall x \psi \tag{18}$$

$$\exists x (\varphi \wedge \psi) \quad \exists \quad \varphi \wedge \exists x \psi \tag{19}$$

$$\exists x (\varphi \lor \psi) \quad \exists \quad \varphi \lor \exists x \psi \tag{20}$$

$$\forall x (\varphi \to \psi) \quad \exists \quad \varphi \to \forall x \psi$$
 (21)

$$\exists x (\varphi \to \psi) \quad \exists x \varphi$$
 (22)

$$\forall x(\psi \to \varphi) \quad \exists x\psi \to \varphi \tag{23}$$

$$\exists x(\psi \to \varphi) \quad \exists \quad \forall x\psi \to \varphi \tag{24}$$



#### Semantics

#### Definition 2.26

A formula  $\varphi$  is called a sentence if  $FV(\varphi) = \emptyset$ , that is  $\varphi$  does not have free variables.

*Notation:* Sent<sub>L</sub>:= the set of sentences of L.

# Proposition 2.27

Let  $\varphi$  be a sentence. For all  $\mathcal{A}$ -assignments  $e_1,e_2$ ,

$$\mathcal{A} \vDash \varphi[e_1] \Longleftrightarrow \mathcal{A} \vDash \varphi[e_2]$$

# Definition 2.28

Let  $\varphi$  be a sentence. An  $\mathcal{L}$ -structure  $\mathcal{A}$  is a model of  $\varphi$  if  $\mathcal{A} \models \varphi[e]$  for an (any)  $\mathcal{A}$ -assignment e. Notation:  $\mathcal{A} \models \varphi$ 



Let  $\varphi$  be a formula and  $\Gamma$  be a set of formulas of  $\mathcal{L}$ .

#### Definition 2.29

We say that  $\Gamma$  is satisfiable if there exists an  $\mathcal{L}$ -structure  $\mathcal{A}$  and an  $\mathcal{A}$ -assignment e such that

$$\mathcal{A} \vDash \gamma[e]$$
 for all  $\gamma \in \Gamma$ .

(A, e) is called a model of  $\Gamma$ .

#### Definition 2.30

We say that  $\varphi$  is a logical consequence of  $\Gamma$  if for all  $\mathcal{L}$ -structures  $\mathcal{A}$  and all  $\mathcal{A}$ -assignments  $e:V\to A$ ,

$$(A, e)$$
 model of  $\Gamma \implies (A, e)$  model of  $\varphi$ .

*Notation:*  $\Gamma \vDash \varphi$ 



Let  $\varphi$  be a sentence and  $\Gamma$  be a set of sentences of  $\mathcal{L}$ .

#### Definition 2.31

We say that  $\Gamma$  is satisfiable if there exists an  $\mathcal{L}$ -structure  $\mathcal{A}$  such that

$$A \vDash \gamma$$
 for all  $\gamma \in \Gamma$ .

A is called a model of  $\Gamma$ . Notation:  $A \models \Gamma$ 

#### Definition 2.32

We say that  $\varphi$  is a logical consequence of  $\Gamma$  if for all  $\mathcal{L}$ -structures  $\mathcal{A}$ ,

$$\mathcal{A} \models \Gamma \implies \mathcal{A} \models \varphi$$
.

*Notation*:  $\Gamma \vDash \varphi$ 



# **Tautologies**

The notions of tautology and tautological consequence from propositional logic can also be applied to a first-order language  $\mathcal{L}$ . Intuitively, a tautology is a formula which is "true" based only on the interpretations of the connectives  $\neg$ ,  $\rightarrow$ .

#### Definition 2.33

An  $\mathcal{L}$ -truth assignment is a function  $F : Form_{\mathcal{L}} \to \{0,1\}$  satisfying, for all formulas  $\varphi, \psi$ ,

$$ightharpoonup F(\neg \varphi) = 1 - F(\varphi);$$

$$ightharpoonup F(\varphi) o F(\psi).$$

#### Definition 2.34

 $\varphi$  is a tautology if  $F(\varphi) = 1$  for any  $\mathcal{L}$ -truth assignment F.

Examples of tautologies:  $\varphi \to (\psi \to \varphi)$ ,  $(\varphi \to \psi) \leftrightarrow (\neg \psi \to \neg \varphi)$ 



# **Tautologies**

# Proposition 2.35

If  $\varphi$  is a tautology, then  $\varphi$  is valid.

#### Example

x = x is valid, but x = x is not a tautology.

#### Definition 2.36

We say that the formulas  $\varphi$  and  $\psi$  are tautologically equivalent if  $F(\varphi) = F(\psi)$  for any  $\mathcal{L}$ -truth assignment F.

# Example 2.37

 $\varphi_1 \to (\varphi_2 \to \ldots \to (\varphi_n \to \psi) \ldots)$  and  $(\varphi_1 \land \ldots \land \varphi_n) \to \psi$  are tautologically equivalent.



#### Definition 2.38

Let  $\varphi$  be a formula and  $\Gamma$  be a set of formulas. We say that  $\varphi$  is a tautological consequence of  $\Gamma$  if for any  $\mathcal{L}$ -truth assignment F,

$$F(\gamma) = 1$$
 for all  $\gamma \in \Gamma$   $\Rightarrow$   $F(\varphi) = 1$ .

# Proposition 2.39

If  $\varphi$  is a tautological consequence of  $\Gamma$ , then  $\Gamma \vDash \varphi$ .



Let x be a variable of  $\mathcal{L}$  and u be a term of  $\mathcal{L}$ .

#### Definition 2.40

For any term t of  $\mathcal{L}$ , we define

 $t_x(u) := the expression obtained from t by replacing all$ occurences of x with u.

# Proposition 2.41

For any term t of  $\mathcal{L}$ ,  $t_x(u)$  is a term of  $\mathcal{L}$ .



#### Substitution

- $\blacktriangleright$  We would like to define, similarly,  $\varphi_x(u)$  as the expression obtained from  $\varphi$  by replacing all free occurences of x in  $\varphi$ with u.
- ▶ We expect that the following natural properties of substitution are true:

$$\vDash \forall x \varphi \to \varphi_x(u) \text{ and } \vDash \varphi_x(u) \to \exists x \varphi.$$

As the following example shows, there are problems with this definition.

Let  $\varphi := \exists y \neg (x = y)$  and u := y. Then  $\varphi_x(u) = \exists y \neg (y = y)$ . Avem

- ▶ For any  $\mathcal{L}$ -structure  $\mathcal{A}$  with  $|A| \geq 2$ ,  $\mathcal{A} \models \forall x \varphi$ .
- $\triangleright \varphi_{x}(u)$  is not satisfiable.



# Substitution

Let x be a variable, u a term and  $\varphi$  a formula.

# Definition 2.42

We say that x is free for u in  $\varphi$  or that u is substitutable for x in  $\varphi$ if for any variable y that occurs in u, no subformula of  $\varphi$  of the form  $\forall y \psi$  contains free occurences of x.

#### Remark

x is free for u in  $\varphi$  in any of the following cases:

- u does not contain variables:
- $\triangleright \varphi$  does not contain variables that occur in u;
- $\blacktriangleright$  no variable from u occurs bound in  $\varphi$ ;
- $\triangleright$  x does not occur in  $\varphi$ ;
- $\triangleright \varphi$  does not contain free occurrences of x.



#### Substitution

Let x be a variable, u a term and  $\varphi$  be a formula such that x is free for u in  $\varphi$ .

#### Definition 2.43

 $\varphi_{x}(u) := \text{the expression obtained from } \varphi \text{ by replacing all }$ free occurences of x in  $\varphi$  with u.

We say that  $\varphi_{x}(u)$  is a free substitution.

## Proposition 2.44

 $\varphi_{\mathsf{x}}(\mathsf{u})$  is a formula of  $\mathcal{L}$ .

#### Substitution

Free substitution rules out the problems mentioned above, it behaves as expected.

# Proposition 2.45

Let  $\varphi$  be a formula and x be a variable.

(i) For any term u substitutable for x in  $\varphi$ ,

$$\vDash \forall x \varphi \rightarrow \varphi_x(u) \quad and \quad \vDash \varphi_x(u) \rightarrow \exists x \varphi.$$

- (ii)  $\models \forall x \varphi \rightarrow \varphi \text{ and } \models \varphi \rightarrow \exists x \varphi.$
- (iii) For any constant symbol c,

$$\vDash \forall x \varphi \rightarrow \varphi_x(c) \text{ and } \vDash \varphi_x(c) \rightarrow \exists x \varphi.$$



#### Substitution

# Proposition 2.46

For any formula  $\varphi$ , distinct variables x and y such that  $y \notin FV(\varphi)$ and y is substitutable for x in  $\varphi$ ,

$$\exists x \varphi \bowtie \exists y \varphi_x(y)$$
 and  $\forall x \varphi \bowtie \forall y \varphi_x(y)$ .

In particular, this holds if y is a new variable, that does not occur in  $\varphi$ .

We use Proposition 2.46 as follows: if  $\varphi_X(u)$  is not a free substitution (that is x is not free for u in  $\varphi$ ), then we replace  $\varphi$ with a logically equivalent formula  $\varphi'$  such that  $\varphi'_{\mathbf{r}}(u)$  is a free substitution.



# Substitution

#### Definition 2.47

For any formula  $\varphi$  and any variables  $y_1, \ldots, y_k$ , the  $y_1, \ldots, y_k$ -free variant  $\varphi'$  of  $\varphi$  is inductively defined as follows:

- $\blacktriangleright$  if  $\varphi$  is an atomic formula, then  $\varphi'$  is  $\varphi$ ;
- $\blacktriangleright$  if  $\varphi = \neg \psi$ , then  $\varphi'$  is  $\neg \psi'$ ;
- $\blacktriangleright$  if  $\varphi = \psi \rightarrow \chi$ , then  $\varphi'$  is  $\psi' \rightarrow \chi'$ ;
- if  $\varphi = \forall z \psi$ , then

$$\varphi' = \begin{cases} \forall w \psi_z'(w) & \text{if } z \in \{y_1, \dots, y_k\} \\ \forall z \psi' & \text{altfel;} \end{cases}$$

where w is the first variable in the sequence  $v_0, v_1, \ldots, which$ does not occur in  $\psi'$  and is not among  $y_1, \ldots, y_k$ .



#### Definition 2.48

 $\varphi'$  is a variant of  $\varphi$  if it is the  $y_1, \ldots, y_k$ -free variant of  $\varphi$  for some variables  $y_1, \ldots, y_k$ .

# Proposition 2.49

- (i) For any formulas  $\varphi$  and  $\varphi'$ , if  $\varphi'$  is a variant of  $\varphi$ , then  $\varphi \vDash \varphi'$ ;
- (ii) For any formula  $\varphi$  and any term u, if the variables of u are among  $y_1, \ldots, y_k$  and  $\varphi'$  is the  $y_1, \ldots, y_k$ -free variant of  $\varphi$ , then  $\varphi'_{\mathsf{v}}(u)$  is a free substitution.



#### Definition 2.50

The set  $LogAx_{\mathcal{L}} \subseteq Form_{\mathcal{L}}$  of logical axioms of  $\mathcal{L}$  consists of:

- (i) all tautologies.
- (ii) formulas of the form

$$t=t, \quad s=t \rightarrow t=s, \quad s=t \wedge t=u \rightarrow s=u,$$
 for any terms  $s,t,u.$ 

(iii) formulas of the form

$$t_1 = u_1 \wedge \ldots \wedge t_m = u_m \rightarrow ft_1 \ldots t_m = fu_1 \ldots u_m,$$
  $t_1 = u_1 \wedge \ldots \wedge t_m = u_m \rightarrow (Rt_1 \ldots t_m \leftrightarrow Ru_1 \ldots u_m),$  for any  $m \geq 1$ ,  $f \in \mathcal{F}_m$ ,  $R \in \mathcal{R}_m$  and any terms  $s_i$ ,  $t_i$   $(i = 1, \ldots, m)$ .

(iv) formulas of the form

$$\varphi_{\mathsf{x}}(t) \to \exists \mathsf{x} \varphi$$

where  $\varphi_x(t)$  is a free substitution ( $\exists$ -axioms).



# Syntax

#### Definition 2.51

The deduction rules (or inference rules) are the following: for any formulas  $\varphi$ ,  $\psi$ ,

(i) from  $\varphi$  and  $\varphi \to \psi$  infer  $\psi$  (modus ponens or (MP)):

$$\frac{\varphi, \ \varphi \to \psi}{\psi}$$

(ii) if  $x \notin FV(\psi)$ , then from  $\varphi \to \psi$  infer  $\exists x \varphi \to \psi$  ( $\exists$ -introduction):

$$\frac{\varphi \to \psi}{\exists x \varphi \to \psi} \quad \text{if } x \notin FV(\psi).$$



# Syntax

Let  $\Gamma$  be a set of formulas of  $\mathcal{L}$ .

#### Definition 2.52

The  $\Gamma$ -theorems of  $\mathcal L$  are the formulas defined as follows:

- ( $\Gamma$ 0) Every logical axiom is a  $\Gamma$ -theorem.
- (Γ1) Every formula of Γ is a Γ-theorem.
- ( $\Gamma$ 2) If  $\varphi$  and  $\varphi \to \psi$  are  $\Gamma$ -theorems, then  $\psi$  is a  $\Gamma$ -theorem.
- ( $\Gamma$ 3) If  $\varphi \to \psi$  is a  $\Gamma$ -theorem and  $x \notin FV(\psi)$ , then  $\exists x \varphi \to \psi$  is a  $\Gamma$ -theorem.
- ( $\Gamma$ 4) Only the formulas obtained by applying rules ( $\Gamma$ 0), ( $\Gamma$ 1), ( $\Gamma$ 2) and ( $\Gamma$ 3) are  $\Gamma$ -theorems.

If  $\varphi$  is a  $\Gamma$ -theorem, then we also say that  $\varphi$  is deduced from the hypotheses  $\Gamma$ .



#### **Notations**

 $\Gamma \vdash_{\mathcal{L}} \varphi := \varphi \text{ is a $\Gamma$-theorem}$ 

 $\vdash_{\mathcal{L}} \varphi := \emptyset \vdash_{\mathcal{L}} \varphi$ 

#### Definition 2.53

A formula  $\varphi$  is called a (logical) theorem of  $\mathcal{L}$  if  $\vdash_{\mathcal{L}} \varphi$ .

#### Convention

When  $\mathcal{L}$  is clear from the context, we write  $\Gamma \vdash \varphi$ ,  $\vdash \varphi$ , etc..



# **Syntax**

#### Definition 2.54

A  $\Gamma$ -proof (or proof from the hypotheses  $\Gamma$ ) of  $\mathcal L$  is a sequence of formulas  $\theta_1, \ldots, \theta_n$  such that for all  $i \in \{1, \ldots, n\}$ , one of the following holds:

- (i)  $\theta_i$  is an axiom;
- (ii)  $\theta_i \in \Gamma$ ;
- (iii) there exist k, j < i such that  $\theta_k = \theta_i \rightarrow \theta_i$ ;
- (iv) there exists j < i such that

$$\theta_i = \varphi \rightarrow \psi$$
 and  $\theta_i = \exists x \varphi \rightarrow \psi$ ,

where  $\varphi, \psi$  are formulas and  $x \notin FV(\psi)$ .

A  $\emptyset$ -proof is called simply a proof.



# Syntax

#### Definition 2.55

Let  $\varphi$  be a formula. A  $\Gamma$ -proof of  $\varphi$  or a proof of  $\varphi$  from the hypotheses  $\Gamma$  is a  $\Gamma$ -proof  $\theta_1, \ldots, \theta_n$  such that  $\theta_n = \varphi$ .

#### Proposition 2.56

Let  $\Gamma$  be a set of formulas. For any formula  $\varphi$ ,

 $\Gamma \vdash \varphi$  iff there exists a  $\Gamma$ -proof of  $\varphi$ .



#### Syntax

Let  $\Gamma$  be a set of formulas.

# Theorem 2.57 (Tautology Theorem (Post))

If  $\psi$  is a tautological consequence of  $\{\varphi_1, \ldots, \varphi_n\}$  and  $\Gamma \vdash \varphi_1, \ldots, \Gamma \vdash \varphi_n$ , then  $\Gamma \vdash \psi$ .

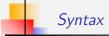
# Theorem 2.58 (Deduction Theorem)

Let  $\Gamma \cup \{\psi\}$  be a set of formulas and  $\varphi$  be a sentence. Then

$$\Gamma \cup \{\varphi\} \vdash \psi \quad \textit{iff} \quad \Gamma \vdash \varphi \rightarrow \psi.$$

#### Definition 2.59

 $\Gamma$  is called <u>consistent</u> if there exists a formula  $\varphi$  such that  $\Gamma \not\vdash \varphi$ .  $\Gamma$  is said to be <u>inconsistent</u> if it is not consistent, that is  $\Gamma \vdash \varphi$  for any formula  $\varphi$ .



# Proposition 2.60

For any formula  $\varphi$  and variable x,

$$\Gamma \vdash \varphi \iff \Gamma \vdash \forall x \varphi.$$

#### Definition 2.61

Let  $\varphi$  be a formula with  $FV(\varphi) = \{x_1, \dots, x_n\}$ . The universal closure of  $\varphi$  is the sentence

$$\overline{\forall \varphi} := \forall x_1 \dots \forall x_n \varphi.$$

#### Notation 2.62

 $\overline{\forall \Gamma} := \{ \overline{\forall \psi} \mid \psi \in \Gamma \}.$ 

#### Proposition 2.63

For any formula  $\varphi$ ,

$$\Gamma \vdash \varphi \quad \Longleftrightarrow \quad \Gamma \vdash \overline{\forall \varphi} \quad \Longleftrightarrow \quad \overline{\forall \Gamma} \vdash \varphi \quad \Longleftrightarrow \quad \overline{\forall \Gamma} \vdash \overline{\forall \varphi}.$$



# Completeness Theorem

# Theorem 2.64 (Completeness Theorem (version 1))

Let  $\Gamma$  be a set of sentences. Then

 $\Gamma$  is consistent  $\iff$   $\Gamma$  is satisfiable.

# Theorem 2.65 (Completeness Theorem (version 2))

For any set of sentences  $\Gamma$  and any sentence  $\varphi$ ,

$$\Gamma \vdash \varphi \iff \Gamma \vDash \varphi.$$

- ► The Completeness Theorem was proved by Gödel in 1929 in his PhD thesis.
- ► Henkin gave in 1949 a simplified proof.



#### Prenex normal form

## Definition 2.66

A formula that does not contain quantifiers is called quantifier-free.

#### Definition 2.67

A formula  $\varphi$  is in prenex normal form if

$$\varphi = Q_1 x_1 Q_2 x_2 \dots Q_n x_n \psi,$$

where  $n \in \mathbb{N}$ ,  $Q_1, \ldots, Q_n \in \{\forall, \exists\}$ ,  $x_1, \ldots, x_n$  are variables and  $\psi$  is a quantifier-free formula.  $Q_1x_1Q_2x_2\ldots Q_nx_n$  is the prefix of  $\varphi$  and  $\psi$  is called the matrix of  $\varphi$ .

Any quantifier-free formula is in prenex normal form, as one can take n=0 in the above definition.



# Prenex normal form

# Examples of formulas in prenex normal form:

- universal formulas:  $\varphi = \forall x_1 \forall x_2 \dots \forall x_n \psi$ , where  $\psi$  is quantifier-free
- existential formulas:  $\varphi = \exists x_1 \exists x_2 \dots \exists x_n \psi$ , where  $\psi$  is quantifier-free
- ▶  $\forall \exists$ -formulas:  $\varphi = \forall x_1 \forall x_2 \dots \forall x_n \exists y_1 \exists y_2 \dots \exists y_k \psi$ , where  $\psi$  is quantifier-free
- ▶  $\forall \exists \forall$ -formulas:  $\varphi = \forall x_1 \dots \forall x_n \exists y_1 \dots \exists y_k \forall z_1 \dots \forall z_p \psi$ , where  $\psi$  is quantifier-free

# Theorem 2.68 (Prenex normal form theorem)

For any formula  $\varphi$  there exists a formula  $\varphi^*$  in prenex normal form such that  $\varphi \vDash \varphi^*$  and  $FV(\varphi) = FV(\varphi^*)$ .  $\varphi^*$  is called a prenex normal form of  $\varphi$ .



Let  ${\mathcal L}$  be a first-order language containing

- ▶ two unary relation symbols R, S and two binary relation symbols P, Q;
- $\triangleright$  a unary function symbol f and a binary function symbol g;
- $\triangleright$  two constant symbols c, d.

# Example

Find a prenex normal form of the formula

$$\varphi := \exists y (g(y,z) = c) \land \neg \exists x (f(x) = d)$$

We have that

$$\varphi \quad \exists y (g(y,z) = c \land \neg \exists x (f(x) = d))$$

$$\exists y (g(y,z) = c \land \forall x \neg (f(x) = d))$$

$$\exists y \forall x (g(y,z) = c \land \neg (f(x) = d))$$

Thus,  $\varphi^* = \exists y \forall x (g(y,z) = c \land \neg (f(x) = d))$  is a prenex normal form of  $\varphi$ .



#### Prenex normal form

# Example

Find a prenex normal form of the formula

$$\varphi := \neg \forall y (S(y) \to \exists z R(z)) \land \forall x (\forall y P(x, y) \to f(x) = d).$$

$$\varphi \quad \exists y \neg (S(y) \rightarrow \exists z R(z)) \land \forall x (\forall y P(x, y) \rightarrow f(x) = d)$$

$$\exists y \neg \exists z (S(y) \rightarrow R(z)) \land \forall x (\forall y P(x, y) \rightarrow f(x) = d)$$

$$\exists y \neg \exists z (S(y) \rightarrow R(z)) \land \forall x \exists y (P(x,y) \rightarrow f(x) = d)$$

$$\exists y \forall z \neg (S(y) \rightarrow R(z)) \land \forall x \exists y (P(x,y) \rightarrow f(x) = d)$$

$$\exists y \forall z (\neg(S(y) \to R(z)) \land \forall x \exists y (P(x,y) \to f(x) = d))$$

$$\exists y \forall z \forall x \big( \neg (S(y) \to R(z)) \land \exists y (P(x,y) \to f(x) = d) \big)$$

$$\exists y \forall z \forall x (\neg (S(y) \to R(z)) \land \exists v (P(x, v) \to f(x) = d))$$

$$\exists y \forall z \forall x \exists v \big( \neg (S(y) \to R(z)) \land (P(x, v) \to f(x) = d) \big)$$

 $\varphi^* = \exists y \forall z \forall x \exists v (\neg(S(y) \to R(z)) \land (P(x, v) \to f(x) = d))$  is a prenex normal form of  $\varphi$ .