TECHNION - ISRAEL INSTITUTE OF TECHNOLOGY

Numerical Methods in Aeronautical Engineering (086172)

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1

1.1 a

Develop the completely implicit for the numerical solution of the PDE : $\frac{\partial u}{\partial t} = \frac{\partial u^2}{\partial x^2}$:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} \quad \Rightarrow \quad \frac{\partial}{\partial t} u(x, t) = \frac{\partial^2}{\partial x^2} u(x, t) \tag{1.1}$$

Express u(x,t) via Taylor series w.r.t time:

$$u(x,t+\delta t) = u(x,t) + \delta t \frac{\partial u}{\partial t} + \frac{\delta t^2}{2!} \frac{\partial^2 u}{\partial t^2} + \frac{\delta t^3}{3!} \frac{\partial^3 u}{\partial t^3} + \dots$$
$$u(x,t+\delta t) = (1 + \delta t \frac{\partial}{\partial t} + \frac{\delta t^2}{2!} \frac{\partial^2}{\partial t^2} + \frac{\delta t^3}{3!} \frac{\partial^3}{\partial t^3} + \dots) u(x,t)$$
(1.2)

Exponent series identity:

$$u(x,t+\delta t) = u(x,t) \sum_{n=1}^{\infty} \left(\frac{\delta t}{n!} \cdot \frac{\partial}{\partial t}\right)^n = \exp(\delta t \frac{\partial}{\partial t}) u(x,t)$$
 (1.3)

Substitute with 1.1 inside:

$$u(x,t+\delta t) = u(x,t) \sum_{n=1}^{\infty} \left(\frac{\delta t}{n!} \cdot \frac{\partial^2}{\partial x^2}\right)^n = \exp(\delta t \frac{\partial}{\partial x^2}) u(x,t)$$
 (1.4)

In order to gain a linear operator <u>instead</u> of the derivative term, we'll develop:

$$hD_x[\delta] = 2sinh^{-1}(\frac{\delta_x}{2}) \quad \Rightarrow \quad \frac{\partial}{\partial x} = \frac{2}{h}sinh^{-1}(\frac{\delta_x}{2}) \quad \Rightarrow \quad (\frac{\partial}{\partial x})^n = (\frac{2}{h}sinh^{-1}(\frac{\delta x}{2}))^n \quad (1.5)$$

Here:

$$u(x,t+\delta t) = \exp(\delta t D_x^2) = \exp\left(\frac{4\delta t}{h^2} \cdot \left(\sinh^{-1}\left(\frac{\delta x}{2}\right)\right)^2\right) u(x,t) \tag{1.6}$$

 $Sinh^{-1}$ series identity :

$$sinh^{-1}(\frac{\delta x}{2}) = (\frac{\delta x}{2}) - \frac{1}{6}(\frac{\delta x}{2})^3 + \frac{3}{40}(\frac{\delta x}{2})^5 + \dots$$
 (1.7)

Re-open as exponential identity:

$$u(x, t + \delta t) = \exp(\delta t D_x^2) = \exp(\frac{4\delta t}{h^2} \cdot ((\frac{\delta x}{2}) - \frac{1}{6}(\frac{\delta x}{2})^3 + \dots)^2) u(x, t)$$
$$u(x, t + \delta t) = \left[\sum_{n=0}^{\infty} \frac{1}{n!} (\frac{4\delta t}{h^2} \left((\frac{\delta x}{2}) - \frac{1}{6}(\frac{\delta x}{2})^3 + \dots\right)^2)^n\right] u(x, t)$$
(1.8)

Neglecting higher terms from 2nd order, we get:

$$(x,t+\delta t) = \left[\sum_{n=0}^{1} \frac{1}{n!} \left(\frac{4\delta t}{h^2} \left(\frac{\delta x}{2}\right) + O(h^2)\right)^2\right]^n u(x,t)$$

$$u(x,t+\delta t) \approx \left[1 + \frac{4\delta t}{h^2} \left(\frac{\delta x}{2}\right)^2\right] u(x,t)$$

$$u(x,t+\delta t) = u(x,t) + \frac{\delta t}{h^2} \cdot \delta_x^2 \left(u(x,t)\right)$$
(1.10)

Recall relations from the linear operators table:

$$\delta_x^2 \Big[f(x) \Big] = \delta_x \Big[f(x) \Big] \quad \Rightarrow \quad \delta_x [\delta_x] = \delta_x^2 = \delta_x$$
(1.11)

Central F.D development:

$$\delta^{2} \left[f(x + \frac{h}{2}) - f(x - \frac{h}{2}) \right] = \delta \left[f(x + \frac{h}{2}) - f(x - \frac{h}{2}) \right]$$

$$= \delta \left[f(x + \frac{h}{2}) \right] - \delta \left[f(x - \frac{h}{2}) \right] = f(x + h) - 2f(x) + f(x - h)$$
(1.12)

And implement on 1.10:

$$u(x,t+\delta t) = u(x,t) + \frac{4\delta t}{h^2} \cdot (\frac{\delta_x}{2})^2 \left(u(x,t) \right) = u(x,t) + \frac{\delta t}{h^2} (\delta_x^2 \left[u(x,t) \right])$$
 (1.13)

General term for the θ method :

$$\frac{\partial u}{\partial t} = \left[\theta(\frac{\partial^2 u}{\partial x^2})_{j+1} + (1-\theta)(\frac{\partial^2 u}{\partial x^2})_j\right] \tag{1.14}$$

Set it for the completely implicit method $(\theta = 1)$:

$$\left(\frac{\partial u}{\partial t}\right)_{j+1} = \left(\frac{\partial^2 u}{\partial x^2}\right)_{j+1} \tag{1.15}$$

Finally, denote $R = \frac{\delta t}{h^2}$ and we get the method :

$$u(x, t + \delta t) = u(x, t) + R[u(x - h, t + \delta t) - 2u(x, t + \delta t) + u(x + h, t + \delta t)]$$
(1.16)

Which can be written numerically as:

$$\underline{u_{i,j+1}} = u_{i,j} + R[u_{i-1,j+1} - 2u_{i,j+1} + u_{i+1,j+1}]$$

1.2 b

Consider the nonlinear PDE: $\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left[F(u) \frac{\partial u}{\partial x} \right]$.

Develop the completely implicit method for this equation numerically:

$$\frac{\partial}{\partial x} = \frac{2}{h} \left(\sinh^{-1}(\frac{\delta_x}{2}) \right) = \frac{2}{h} \left((\frac{\delta_x}{2}) - \frac{1}{6} (\frac{\delta_x}{2})^3 + \frac{3}{40} (\frac{\delta_x}{2})^5 + \dots \right)$$
 (1.17)

neglecting H.O.T $O(h^2)$:

$$\frac{\partial}{\partial x} = \frac{2}{h} \left(\left(\frac{\delta_x}{2} \right) + O(h^2) \right) = \frac{\delta_x}{h} \tag{1.18}$$

Here, using cetral F.D for 1st derivative:

$$\begin{split} (\frac{\partial u}{\partial t})_{i,j+1} &= \frac{\delta_x}{h} \Big[F(u) \frac{\partial u}{\partial x} \Big]_{i,j+1} = \frac{\delta_x}{h} \Big[F_{i+\frac{1}{2},j+1} (\frac{\partial u}{\partial x})_{i+\frac{1}{2},j+1} - F_{i-\frac{1}{2},j+1} (\frac{\partial u}{\partial x})_{i-\frac{1}{2},j+1} \Big] \\ &= \frac{\delta_x}{h} \Big[F_{i+\frac{1}{2},j+1} (\frac{u_{i+1,j+1} - u_{i,j}}{\delta_x}) - F_{i-\frac{1}{2},j+1} (\frac{u_{i,j+1} - u_{i-1,j+1}}{\delta_x}) \Big] \\ &= \frac{1}{h} \Big[F_{i+\frac{1}{2},j+1} u_{i+1,j+1} - (F_{i+\frac{1}{2},j+1} u_{i,j} + F_{i-\frac{1}{2},j+1}) + F_{i-\frac{1}{2},j+1} u_{i-1,j+1} \Big] \end{split}$$

Finally, substituting indices and plug R ratio :

$$\underline{\underline{u_{i,j+1}}} = u_{i,j} + \left[F_{i+\frac{1}{2},j+1} u_{i+1,j+1} - \left(F_{i+\frac{1}{2},j+1} u_{i,j} + F_{i-\frac{1}{2},j+1} \right) + F_{i-\frac{1}{2},j+1} u_{i-1,j+1} \right]$$
(1.19)

Provide that we want to eliminate half h indices, we'll average F(u):

$$F\left[u_{i\pm\frac{1}{2},j+1}\right] = \frac{1}{2}\left[F(u_{i\pm1,j+1}) + F(u_{i,j+1})\right] = \frac{1}{2}F\left[u_{i\pm1,j+1} + u_{i,j+1}\right]$$
(1.20)

And plug back into the final solution:

$$\underline{\underline{u_{i,j+1}}} = u_{i,j} + \left[u_{i+1,j+1}^2 - 2u_{i,j}^2 + u_{i-1,j+1}^2\right]$$
(1.21)

1.3 c

Find the local truncation error for the fully implicit method when solving: $\frac{\partial u}{\partial t} = \frac{\partial u^2}{\partial x^2}$:

The PDE was brought into:

$$u(x,t+\delta t) = \exp(\delta t D_x^2) = \exp\left(\frac{4\delta t}{h^2} \cdot \left(\sinh^{-1}\left(\frac{\delta x}{2}\right)\right)^2\right) u(x,t)$$
 (1.22)

And the hyperbolic sinus expansion:

$$\sinh^{-1}\left(\frac{\delta x}{2}\right) = \left(\frac{\delta x}{2}\right) - \frac{1}{6}\left(\frac{\delta x}{2}\right)^3 + \frac{3}{40}\left(\frac{\delta x}{2}\right)^5 + \dots$$

$$\sinh^{-1}\left(\frac{\delta x}{2}\right) = \left[\sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{4\delta t}{h^2} \left(\left(\frac{\delta x}{2}\right) + O(h^2)\right)^2\right)^n\right] \tag{1.23}$$

Inevitably, a well thought out reduction had to be handled for a practical solution:

$$sinh^{-1}(\frac{\delta x}{2}) = \left[\sum_{n=0}^{1} \frac{1}{n!} \left(\frac{4\delta t}{h^2} \left(\left(\frac{\delta x}{2}\right) + O(h^2)\right)^2\right)^n\right] u(x,t)$$

Thus :

$$sinh^{-1}(\frac{\delta x}{2}) = \left[1 + \frac{4\delta t}{h^2}(\frac{\delta x}{2})\right] + \underline{\underline{O(h^2)^2}}$$
(1.24)

Add it to the time derivative local truncation, and we get:

$$u_{i,j+1} = u_{i,j} + R\left[u_{i-1,j+1} - 2u_{i,j+1} + u_{i+1,j+1}\right] + \underline{O(k) + O(h^2)^2}$$
(1.25)

$$-fin-$$