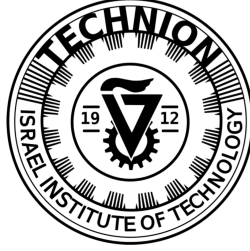


# TECHNION - ISRAEL INSTITUTE OF TECHNOLOGY

## Numerical Methods in Aeronautical Engineering (086172)

### Theoretical Part - Daniel Engelsman, 300546173



## 1

Suppose we want to solve the following linear algebraic system using Jacobi's method:

$$\sum_{j=1}^N a_{ij}x_j = b_i, \quad i = 1, 2, \dots, N$$

Prove that if  $\sum_{j=1, j \neq i}^N |a_{ij}| \leq |a_{ii}|$ ,  $i = 1, 2, \dots, N$  iterative convergence is assured. (This condition is known as Diagonal Dominance).

Let us decompose matrix  $A$  into 3 components (L - Lower, D - Diagonal, U - Upper) :

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1N} \\ a_{21} & a_{22} & \cdots & a_{2N} \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ a_{N1} & a_{N2} & \cdots & a_{NN} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ \vdots \\ x_N \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ \vdots \\ b_N \end{bmatrix} \rightarrow \underline{A}\bar{x} = \bar{b} \Leftrightarrow (\underline{L} + \underline{D} + \underline{U})\bar{x} = \bar{b} \quad (1.1)$$

Isolating the diagonal, and express as Jacobi method :

$$\underline{D}\bar{x}^{(n+1)} = \bar{b} - (\underline{L} + \underline{U})\bar{x}^{(n)} \rightarrow \bar{x}^{(n+1)} = \underline{D}^{-1}(\bar{b} - (\underline{L} + \underline{U})\bar{x}^{(n)})$$

$$\text{Equivalently, } x_i^{(n+1)} = \frac{1}{a_{ii}}(b_i - \sum_{j=1, j \neq i}^N a_{ij}x_j^{(n)}) = \frac{b_i}{a_{ii}} - \sum_{j=1, j \neq i}^N \frac{a_{ij}}{a_{ii}}x_j^{(n)}, \quad i = 1, 2, \dots, N \quad (1.2)$$

Constant elements ( $b_i/a_{ii}$ ) are subtracted between iterations, so we're interested in :

$$\underline{C} = \sum_{j=1 \neq i}^N \frac{a_{ij}}{a_{ii}}, \quad i = 1, 2, \dots, N \quad (1.3)$$

Using Gershgorin theorem to asses  $C$ 's eigenvalues :

$$\rho(\underline{C}) = \max_{1 \leq s \leq N} |\lambda_s| \leq S = \max_{1 \leq i \leq N} S_i = \max_{1 \leq i \leq N} \sum_{j=1 \neq i}^N \left| \frac{a_{ij}}{a_{ii}} \right|$$

Let  $a_{ii}$  satisfy:  $\sum_{j=1 \neq i}^N |a_{ij}| \leq |a_{ii}|$  such that :  $\sum_{j=1 \neq i}^N \left| \frac{a_{ij}}{a_{ii}} \right| \leq 1$  (1.4)

$$\text{here : } \rho(\underline{C}) = \max_{1 \leq i \leq N} \sum_{j=1 \neq i}^N \left| \frac{a_{ij}}{a_{ii}} \right| = \sum_{j=1 \neq i}^N \left| \frac{a_{ij}}{a_{ii}} \right| \leq 1 \quad (1.5)$$

Since  $a_{ii}$  is diagonally dominant, the spectral radius is less than or equal to 1, at every row.

## 2

Use Brauer's theorem to investigate how boundary conditions influence the stability of Crank-Nicholson's method for the numerical solution of the following problem:

$$0 \leq x \leq 1 : \quad \frac{\partial^2 U}{\partial x^2} = \frac{\partial U}{\partial t}$$

subject to the initial and boundary conditions:

$$U(x, 0) = U_0(x) \text{ where } U_0(x) \text{ is a given function}$$

$$x = 0, t \geq 0, \quad \frac{\partial U}{\partial x} = K_1(U - v_1)$$

$$x = 1, t \geq 0, \quad \frac{\partial U}{\partial x} = -K_2(U - v_2)$$

where  $K_1 > 0, K_2 > 0, v_1, v_2$  are constants.

Let us write the PDE under C-N using central finite differences :

$$\frac{\partial u}{\partial t} = \frac{1}{2} \left[ \left( \frac{\partial^2 u}{\partial x^2} \right)_j + \left( \frac{\partial^2 u}{\partial x^2} \right)_{j+1} \right] \quad (2.1)$$

$$\frac{u_{i,j+1} - u_{i,j}}{k} = \frac{1}{2} \left( \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} + \frac{u_{i+1,j+1} - 2u_{i,j+1} + u_{i-1,j+1}}{h^2} \right) \quad (2.2)$$

Define  $R \equiv \frac{k}{h^2}$ , we get :

$$-\frac{R}{2}u_{i-1,j+1} + u_{i,j+1}(1+R) - \frac{R}{2}u_{i+1,j+1} = \frac{R}{2}u_{i-1,j} + u_{i,j}(1-R) + \frac{R}{2}u_{i+1,j} \quad (2.3)$$

Both sides' conditions are defined by derivatives, such that index becomes -  $i \in [0, N+1]$  :

$$\begin{aligned} \left. \frac{\partial u}{\partial x} \right|_{x=0}^{t \geq 0} &= \frac{u_{1,j} - u_{-1,j}}{2h} = K_1(u_{0,j} - v_1), \quad \Rightarrow \quad \begin{cases} u_{-1,j} = u_{1,j} - 2hK_1(u_{0,j} - v_1) \\ u_{-1,j+1} = u_{1,j+1} - 2hK_1(u_{0,j+1} - v_1) \end{cases} \\ \left. \frac{\partial u}{\partial x} \right|_{x=1}^{t \geq 0} &= \frac{u_{N+2,j} - u_{N,j}}{2h} = -K_2(u_{N+1,j} - v_2), \quad \Rightarrow \quad \begin{cases} u_{N+2,j} = u_{N,j} - 2hK_2(u_{N+1,j} - v_2) \\ u_{N+2,j+1} = u_{N,j+1} - 2hK_2(u_{N+1,j+1} - v_2) \end{cases} \end{aligned}$$

Check the first and last rows :

$$\begin{aligned} i = 0 : \quad & -\frac{R}{2}u_{-1,j+1} + (1+R)u_{0,j+1} - \frac{R}{2}u_{1,j+1} = \frac{R}{2}u_{-1,j} + (1-R)u_{0,j} + \frac{R}{2}u_{1,j} \\ \text{LHS :} \quad & -\frac{R}{2}(u_{1,j+1} - 2hK_1(u_{0,j+1} - v_1)) + (1+R)u_{0,j+1} - \frac{R}{2}u_{1,j+1} \\ \text{LHS :} \quad & \Rightarrow (1+R(1+hK_1))u_{0,j+1} - Ru_{1,j+1} - (RhK_1v_1) \\ \text{RHS :} \quad & \frac{R}{2}(u_{1,j} - 2hK_1(u_{0,j} - v_1)) + (1-R)u_{0,j} + \frac{R}{2}u_{1,j} \\ \text{RHS :} \quad & \Rightarrow (1-R(1+hK_1))u_{0,j} + Ru_{1,j} + (RhK_1v_1) \\ i = N+1 : \quad & -\frac{R}{2}u_{N,j+1} + (1+R)u_{N+1,j+1} - \frac{R}{2}u_{N+2,j+1} = \frac{R}{2}u_{N,j} + (1-R)u_{N+1,j} + \frac{R}{2}u_{N+2,j} \\ \text{LHS :} \quad & -\frac{R}{2}u_{N,j+1} + (1+R)u_{N+1,j+1} - \frac{R}{2}(u_{N,j+1} - 2hK_2(u_{N+1,j+1} - v_2)) \\ \text{LHS :} \quad & -Ru_{N,j+1} + (1+R(1+hK_2))u_{N+1,j+1} - (RhK_2v_2) \\ \text{RHS :} \quad & \frac{R}{2}u_{N,j} + (1-R)u_{N+1,j+1} + \frac{R}{2}(u_{N,j} - 2hK_2(u_{N+1,j} - v_2)) \\ \text{RHS :} \quad & Ru_{N,j} + (1-R(1+hK_2))u_{N+1,j} + (RhK_2v_2) \end{aligned}$$

Matrix presentation :

$$\begin{aligned}
\text{LHS : } & \begin{bmatrix} 1 + R(1 + hK_1) & -R & 0 & \cdots & \cdots & 0 \\ -\frac{R}{2} & 1 + R & -\frac{R}{2} & \ddots & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & -\frac{R}{2} & 1 + R & -\frac{R}{2} \\ 0 & \cdots & \cdots & 0 & -R & 1 + R(1 + hK_2) \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ \vdots \\ \vdots \\ u_{N+1} \end{bmatrix}_{j+1} - \begin{bmatrix} RhK_1 v_1 \\ 0 \\ \vdots \\ \vdots \\ 0 \\ RhK_2 v_2 \end{bmatrix} \\
\text{RHS : } & \begin{bmatrix} 1 - R(1 + hK_1) & R & 0 & \cdots & \cdots & 0 \\ \frac{R}{2} & 1 - R & \frac{R}{2} & \ddots & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & \frac{R}{2} & 1 - R & \frac{R}{2} \\ 0 & \cdots & \cdots & 0 & R & 1 - R(1 + hK_2) \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ \vdots \\ \vdots \\ u_{N+1} \end{bmatrix}_j + \begin{bmatrix} RhK_1 v_1 \\ 0 \\ \vdots \\ \vdots \\ 0 \\ RhK_2 v_2 \end{bmatrix} \\
\text{Define : } \Lambda = & \begin{bmatrix} -R(1 + hK_1) & R & 0 & \cdots & \cdots & 0 \\ \frac{R}{2} & -R & \frac{R}{2} & \ddots & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \frac{R}{2} & -R & \frac{R}{2} & \\ 0 & \cdots & 0 & R & -R(1 + hK_2) \end{bmatrix} \Rightarrow \begin{cases} A_{LHS} = I - M \\ A_{RHS} = I + M \end{cases}
\end{aligned}$$

$$\text{Extract : } \quad \bar{\mathbf{u}}_{j+1} = A_{LHS}^{-1} A_{RHS} \mathbf{u}_j + A_{LHS}^{-1} 2\bar{b}$$

Given derivative initial conditions, our matrix is not a **c-a-b** matrix, and thus no analytic expression can be used. We shall therefore look for  $A_{LHS}^{-1}$  and  $A_{RHS}$  eigenvalues :

$$\text{Similar to : } \quad f_k(\underline{A})\bar{v} = f_k(\lambda)\bar{v} \quad \rightarrow \quad \bar{v} = f_k(\underline{A})^{-1} f_k(\lambda)\bar{v}$$

$$\text{Polynomial matrices : } \quad f(A_{LHS})^{-1} f(A_{RHS}) \bar{v} = f(\lambda_{LHS})^{-1} f(\lambda_{RHS}) \bar{v} = \frac{f(\lambda_{RHS})}{f(\lambda_{LHS})} \bar{v}$$

$$\text{Extract } (A_{LHS}^{-1} A_{RHS}) \text{ eigenvalues : } \quad \mu_i(\lambda) = \left| \frac{I_i - \Lambda_i}{I_i + \Lambda_i} \right| \leq 1 \quad \forall \quad i$$

$$|1 - \Lambda_i| \leq |1 + \Lambda_i| \quad \rightarrow \quad 1 - \Lambda_i \leq \pm(1 + \Lambda_i) \quad \Rightarrow \quad \Lambda_i \geq 0 \quad \forall \quad i$$

Using Brauer's theorem, each  $A$  matrix produces 3 circles from rows  $[1, 1 < i < N, N]$  :

$$\begin{aligned}
(i = 1) \quad & |\lambda + R(1 + hK_1)| \leq R \rightarrow -R \leq \lambda + R(1 + hK_1) \leq R \\
& -R(2 + hK_1) \leq \lambda \leq RhK_1 \Rightarrow \{h, K_1, R\} > 0, |\lambda| > 0 \\
(1 < i < N) \quad & |\lambda + R| \leq R \rightarrow -R \leq \lambda + R \leq R \\
& -2R \leq \lambda \leq 0 \Rightarrow R > 0, |\lambda| \geq 0 \\
(i = N) \quad & |\lambda + R(1 + hK_2)| \leq R \rightarrow -R \leq \lambda + R(1 + hK_2) \leq R \\
& -R(2 + hK_2) \leq \lambda \leq RhK_2 \Rightarrow \{h, K_2, R\} > 0, |\lambda| > 0
\end{aligned}$$

All  $\lambda_i$  are greater than zero, and thus satisfy stability criterion of eigenvalues  $\mu_i \leq 1$ . Thus the *Crank-Nicolson* method is unconditionally stable, and is variables independent.

### 3

For the solution of the convection-diffusion equation:

$$-u \frac{\partial w}{\partial x} + D \frac{\partial^2 w}{\partial x^2} = 0 \quad (I)$$

(where  $u$  is the velocity and  $D$  is the diffusion coefficient, both of which are constant) the following numerical method is proposed:

$$w_{i+1} - (I + e^{uh/D})w_i + e^{uh/D}w_{i-1} = 0 \quad (II)$$

which can be solved iteratively using

$$w_i^{(n+1)} = \frac{I}{(I + e^{uh/D})} [w_{i+1}^{(n)} + e^{uh/D}w_{i-1}^{(n)}] \quad i = 0, 1, 2, \dots \quad (III)$$

- Show that under certain conditions equation (II) reduces to the finite difference equation that would be obtained by writing (I) using central differences.
- Prove that the iterative procedure (III) will not diverge.

(a) We'll express the exponent by using first order approximation of power series :

$$e^{\frac{uh}{D}} = \sum_{n=0}^{\infty} \left(\frac{uh}{D}\right)^n = \sum_{n=0}^1 \left(\frac{uh}{D}\right)^n + \text{H.O.T} = 1 + \frac{uh}{D}$$

$$\text{Equation (II) : } w_{i+1} - (1 + e^{\frac{uh}{D}})w_i + e^{\frac{uh}{D}}w_{i-1} = 0 \quad (3.1)$$

$$\text{Plug inside : } w_{i+1} - (2 + \frac{uh}{D})w_i + (1 + \frac{uh}{D})w_{i-1} = 0 \quad (3.2)$$

$$\backslash \cdot D \rightarrow Dw_{i+1} - (2D + uh)w_i + (D + uh)w_{i-1} = 0$$

$$\text{Sort by coefficients : } -uh(w_i - w_{i-1}) + D(w_{i+1} - 2w_i + w_{i-1}) = 0 \quad \backslash \cdot \frac{1}{h^2}$$

$$\text{We get : } -u \cdot \left(\frac{w_i - w_{i-1}}{h}\right) + D \cdot \left(\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2}\right) = 0 \quad (3.3)$$

The final equation is comprised of 2nd central F.Ds and 1st order backward F.Ds. To ensure reduction into central F.Ds of both derivatives, we must nullify  $u$  such as :

$$\begin{aligned} -\cancel{u} \cdot \left(\frac{w_i - w_{i-1}}{h}\right) + D \cdot \left(\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2}\right) &= 0 \\ -\cancel{u} \cdot \frac{\partial u}{\partial x} + D \frac{\partial^2 u}{\partial x^2} &= 0 \Rightarrow D \frac{\partial^2 u}{\partial x^2} = 0 \end{aligned} \quad (3.4)$$

(b) Using (Eqn. 3.2) in its iterative form (III) :

$$\begin{aligned} w_i^{(n+1)} &= \frac{1}{(1 + e^{\frac{uh}{D}})} [w_{i+1}^{(n)} + e^{\frac{uh}{D}} w_{i-1}^{(n)}] \\ w_i^{(n+1)} &= \frac{e^{\frac{uh}{D}}}{(1 + e^{\frac{uh}{D}})} w_{i-1}^{(n)} + \frac{1}{(1 + e^{\frac{uh}{D}})} w_{i+1}^{(n)} \\ \text{as vector : } w_i^{(n+1)} &= \mathbf{c} \cdot w_{i-1}^{(n)} + \mathbf{b} \cdot w_{i+1}^{(n)} \end{aligned}$$

For convenience, let us nullify constant i.c. and b.c such that :

$$\begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ \vdots \\ w_N \end{bmatrix}^{(n+1)} = \begin{bmatrix} 0 & b & 0 & \cdots & 0 \\ c & 0 & b & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & b \\ 0 & \cdots & \cdots & c & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ \vdots \\ w_N \end{bmatrix}^{(n)} + \begin{bmatrix} c \cancel{w_0} \\ 0 \\ \vdots \\ 0 \\ b \cancel{w_{N+1}} \end{bmatrix}^0$$

Using Gershgorin theorem ( $A \equiv$  matrix  $\uparrow$ ), and asking :

$$\rho(\underline{A}) = \max_{1 \leq s \leq N} |\lambda_s| \leq S = \max_{1 \leq i \leq N} S_i = \max \{ b, c, b + c \}$$

$$(i) \quad |\lambda - 0| \leq b \quad \rightarrow \quad |\lambda| \leq \frac{1}{(1 + e^{\frac{uh}{D}})} \rightarrow \leq 1$$

$$(ii) \quad |\lambda - 0| \leq c \quad \rightarrow \quad |\lambda| \leq \frac{1}{(1 + e^{-\frac{uh}{D}})} \rightarrow \leq 1$$

$$(iii) \quad |\lambda - 0| \leq b + c \quad \rightarrow \quad |\lambda| \leq \frac{1}{(1 + e^{\frac{uh}{D}})} + \frac{e^{\frac{uh}{D}}}{(1 + e^{\frac{uh}{D}})} \rightarrow = 1$$

Maximal eigenvalue is not greater than 1, and thus  $\rho(A) \leq 1$  is fulfilled without constraints on any of the parameters.

Suppose we want to solve the following problem using Crank-Nicholson's method:

$$0 \leq x \leq l: \quad \frac{\partial U}{\partial t} = \frac{\partial^2 U}{\partial x^2}$$

$$U(0, t) = U(l, t) = 0 \quad \text{and} \quad U(x, 0) = U_0(x)$$

Instead of using a tridiagonal solver for the set of algebraic equations we get, we will use the following iterative method:

$$u_{i,j+1}^{(n+1)} = \frac{R}{2} \left( u_{i-1,j+1}^{(n)} - 2u_{i,j+1}^{(n)} + u_{i+1,j+1}^{(n)} \right) + \frac{R}{2} \left( u_{i-1,j} + u_{i+1,j} \right) + (1-R)u_{i,j}$$

where  $R = k/h^2$ ,  $i = 1, 2, 3, \dots, N$ ,  $j = 0, 1, 2, 3, \dots$  and  $(n)$  represents the iterative index.

Prove (mathematically) that the unconditional stability of the Crank-Nicholson method is lost due to a restrictive condition on  $R$  for iterative convergence.

Let us write the PDE under C-N using central finite differences :

$$\frac{u_{i,j+1} - u_{i,j}}{k} = \frac{1}{2} \left( \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} + \frac{u_{i+1,j+1} - 2u_{i,j+1} + u_{i-1,j+1}}{h^2} \right)$$

Define  $R \equiv \frac{k}{h^2}$ , we get :

$$-\frac{R}{2}u_{i-1,j+1} + u_{i,j+1}(1+R) - \frac{R}{2}u_{i+1,j+1} = \frac{R}{2}u_{i-1,j} + u_{i,j}(1-R) + \frac{R}{2}u_{i+1,j}$$

Sort iteratively as required :

$$u_{i,j+1}^{(n+1)} = \frac{R}{2} \left( u_{i-1,j+1}^{(n)} - 2u_{i,j+1}^{(n)} + u_{i+1,j+1}^{(n)} \right) + \frac{R}{2}u_{i-1,j} + u_{i,j}(1-R) + \frac{R}{2}u_{i+1,j}$$

$$\text{i.c and b.c : } u(0, t) = u_{0,j} = 0, \quad u(x_f, t) = u_{N+1,j} = 0, \quad u(x, 0) = u_{i,0} = U_0$$

We get the following system where only the first matrix is iteration dependent :

$$\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ \vdots \\ u_N \end{bmatrix}^{(n+1)} = \begin{bmatrix} -R & \frac{R}{2} & 0 & \cdots & 0 \\ \frac{R}{2} & -R & \frac{R}{2} & 0 & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \frac{R}{2} \\ 0 & \cdots & 0 & \frac{R}{2} & -R \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ \vdots \\ u_N \end{bmatrix}^{(n)} + \begin{bmatrix} 1-R & \frac{R}{2} & 0 & \cdots & 0 \\ \frac{R}{2} & 1-R & \frac{R}{2} & 0 & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \frac{R}{2} \\ 0 & \cdots & 0 & \frac{R}{2} & 1-R \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ \vdots \\ u_N \end{bmatrix}^{(n=1)}$$



Using Brauer theorem to check stability criterion :

$$\begin{aligned}
\rho(\underline{A}) &= \max_{1 \leq s \leq N} |\lambda_s| \leq \max_{1 \leq i \leq N} S_i \leq 1 \\
(i=1) \quad |\lambda + R| &\leq \frac{R}{2} \quad \rightarrow \quad -\frac{R}{2} \leq \lambda + R \leq \frac{R}{2} \\
-\frac{3}{2}R &\leq \lambda \leq -\frac{R}{2} \quad \Rightarrow_{|\lambda| \leq 1} \quad R \leq \{\frac{2}{3}, 2\} \\
(1 < i < N) \quad |\lambda + R| &\leq R \quad \rightarrow \quad -R \leq \lambda + R \leq R \\
-2R &\leq \lambda \leq 0 \quad \Rightarrow_{|\lambda| \leq 1} \quad R \leq \{\frac{1}{2}\}
\end{aligned}$$

For stability analysis, one must take the strictest (=minimal) condition, here  $R \leq \frac{1}{2}$ .

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