

Homework 6

Particle Swarm Optimization using Schwefel Benchmark Function

Daniel Carpenter

April 2022

Contents

1	Question 1: Particle Swarm Optimization	2
1.1	Schwefel Function	3
1.2	Functions for the Global and Local Best Logic (<i>using Ring Structure</i>)	3
1.3	Function to Initialize the Swarm	5
1.4	Function to Update Velocity and Position	6
1.5	Function to Calculate Particle Historical Best Fitness Value and Position	8
1.6	2 Functions to Display Best Solution and Write to CSV	9
1.7	Driver Funtion to Compile and Loop through a PSO Problem	11
1.8	Part 1 (b) & (c) - Global Best Method	13
1.8.1	1(b) 2D Global Swarm	13
1.8.2	1(b) i. - iii. Iteration Table & Plot	14
1.8.3	1(c) 200D Global Swarm w/Variious Param	17
1.9	Part 1 (d) & (e) - Local Best Method	19
1.9.1	Reference: Local Swarm Calculation and Logic	19
1.9.2	1(d) 2D Local Swarm	20
1.9.3	1(e) 200D Local Swarm w/Variious Params.	21

Global Variables

Input variables like the *random seed*, and the *lower and upper bound of solution space*
Please assume these are referenced by following code chunks

```
import math
from random import Random
import numpy as np

# Random seed
seed = 12345
randNumGenerator = Random(seed)

# bounds for Schwefel Function search space
lowerBound = -500
upperBound = 500
```

1 Question 1: Particle Swarm Optimization

Find the global optimum of the Schwefel function below

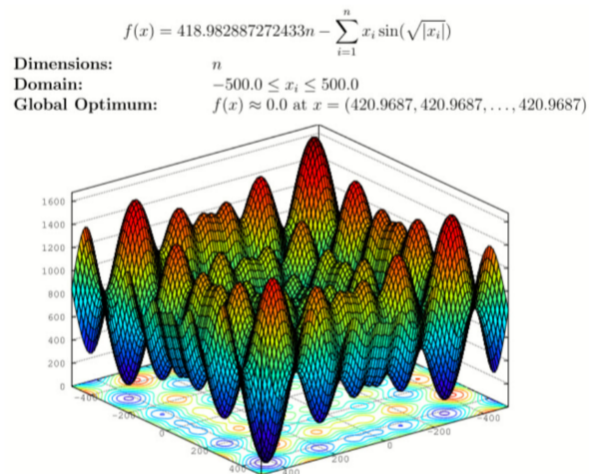


Figure 1: 2D Schwefel Function

The Following Functions Satisfy Problem 1(a)

1.1 Schwefel Function

```
# =====
# SCHWEFEL FUNCTION
# Schwefel function to evaluate a real-valued solution x
# note: the feasible space is an n-dimensional hypercube centered at the origin with side length = 2 * .
# =====
def evalFitnessVal(x):
    fitnessValue = 0
    numParticles = len(x)

    # For every particle particle, calculate the fitness value based on Schwefel function
    for particle in range(numParticles):
        fitnessValue = fitnessValue + x[particle]*math.sin(math.sqrt(abs(x[particle])))

    fitnessValue = 418.9829*numParticles - fitnessValue

    return fitnessValue
```

1.2 Functions for the Global and Local Best Logic (*using Ring Structure*)

- Local best topology method: Ring structure
- The driver function takes in a string called local or global
- This parameter switches between these two methods for the driver
- For example, if I chose local, then it would use the local best method
- See inline comments for detailed logic

```
# =====
# GLOBAL MIN VALUE AND POSITION SEARCH FUNCTION
# Returns the 2 element list (each containing a single value) with the global best particle's:
# ---- [0] min value and
# ---- [1] associate position of
# =====
def getGlobalBest(fitnessValues, positions, swarmSize):
    minValue = np.min(fitnessValues) # Find the Minimum fitness value of all particles
    minIndex = fitnessValues.index(minValue) # Find the index of the position for the min. fit. value

    minPosition = positions[minIndex][:] # Now get a copy of the particle's position with min index

    # Returns: the global best particle's minimum fitness value and its position
    return [minValue, minPosition]

# =====
# LOCAL MIN VALUE AND POSITION SEARCH FUNCTION
# Topology: Ring structure with n neighbors (default 2)
# Returns the 2 element list of lists with the each particle's local best within neighborhood
# ---- [0] min value and
# ---- [1] associate position of
```

```

# Can change numParticlesInNbrhood to consider more or less in particle's neighborhood
# =====
def getLocalBest(fitnessValues, positions, swarmSize,
                 numParticlesInNbrhood = 2): # Number of particles to compare to for local best

    lBestFitValue = [] # will hold the best VALUE of the n surrounding particles, for each particle
    lBestPosition = [] # will hold the best POSITION of the n surrounding particles, for each particle

    # For every particle in the swarm, (starting at n less than index 0)
    for particle in range(-numParticlesInNbrhood, swarmSize - numParticlesInNbrhood):

        # Identify the two neighbors fitness value of this particle,
        # which are the two preceding particles
        personalBestNeighbor1 = fitnessValues[particle]
        personalBestNeighbor2 = fitnessValues[particle + 1]

        # Identify the lowest fitness value of this particle's the two preceding neighbors
        minNeighValue = min(personalBestNeighbor1, personalBestNeighbor2)

        # Store the index of the particle
        minNeighIndex = fitnessValues.index(minNeighValue)

        # Store the particle's best neighbors fitness value and position
        lBestFitValue.append(fitnessValues[minNeighIndex])
        lBestPosition.append(positions[minNeighIndex])

    # Returns a list of particles and the min of their n best fit. valued neighbors
    return[lBestFitValue, lBestPosition]

# If you needed to index the list just returned for global or local best
VALUE_IDX = 0
POSITION_IDX = 1

```

1.3 Function to Initialize the Swarm

- Allows you to easily change the swarm size, dimensions, and the local or global best method

```
# =====
# STEP 1 - SWARM INITIALIZATION / EVALUATION
# Randomly initialize a swarm instance
# Set the particle's best to it's starting position
# =====
def initializeSwarm(swarmSize, numDimensions, functionToGetBest):

    # In the current time period, position[particle] and velocity[particle] of each particle i,
    # Each particle contains n-dimensional list of the coordinate position & velocity
    position = [[] for _ in range(swarmSize)] # X[particle]: position (2D: x, y) of particle i
    velocity = [[] for _ in range(swarmSize)] # V[particle]: velocity (2D: x, y) of particle i

    # Lists containing info related to each particle in swarm
    pCurrFitValue = [] # X[particle] The current position of particle i

    # For each particle and dimension, randomly initialize the...
    for particle in range(swarmSize):
        for theDimension in range(numDimensions):

            # Position: give random value between lower/upper bounds (-500, 500 for schwefel)
            position[particle].append(randNumGenerator.uniform(lowerBound, upperBound))

            # Velocity: give random value between -1 and 1 --- maybe these are good bounds? maybe not
            velocity[particle].append(randNumGenerator.uniform(-1, 1))

        # 1.1 - Evaluate fitness value
        pCurrFitValue.append(evalFitnessVal(position[:, particle])) # evaluate the current position's fitness

    # 1.2 - Log the individual and global bests
    pBestPosition = position[:, 0] # initialize pBestPosition to the starting position
    pBestFitValue = pCurrFitValue[0] # initialize pBestPosition to the starting position's value

    # 1.3 - Log the Global or local best (depends on chosen method) fitness value and position
    glBestFitValue, glBestPosition = functionToGetBest(pBestFitValue, pBestPosition, swarmSize)

    return [position, velocity, pCurrFitValue,
            pBestPosition, pBestFitValue,
            glBestFitValue, glBestPosition]
```

1.4 Function to Update Velocity and Position

- Uses the velocity calculation to update the position.
- Function is dynamic and can use the local or global best methods
- Also handles:
 - *Infeasibility of Velocity*: pushes the position back into the lower or upper bound solution space (see logic below)
 - *Infeasibility of Position*: Randomly moves above the solution space until the position has found a feasible solution

```
# =====
# UPDATE VELOCITY AND POSITION
# =====
def updateVelocityAndPosition(inertiaWeight, velocity, position, phi1, phi2, pBestPosition, glBestPosition,
                              swarmSize, numDimensions):
    # Velocity -----

    ## random weights of r for random velocity adjustment
    r1, r2 = randNumGenerator.random(), randNumGenerator.random()

    ## Calculations of updating velocity, separated by
    ## inertia + cognitive + social (for simplicity)
    vInertia = np.multiply(inertiaWeight, velocity[:]) # Inertia component
    vCognitive = np.multiply(phi1*r1, np.subtract(pBestPosition[:], position[:])) # Cognitive component
    vSocial = np.multiply(phi2*r2, np.subtract(glBestPosition[:], position[:])) # Social component

    ## Update the new velocity to the summation of inertia, cognitive, and social
    newVelocity = vInertia[:] + vCognitive[:] + vSocial[:]

    ## Limit the velocity between the upper and lower bound limits
    for particle in range(swarmSize):
        for theDimension in range(numDimensions):

            # If the new velocity of particle i is > the limit, then reduce to the limit
            if newVelocity[particle][theDimension] > upperBound:
                newVelocity[particle][theDimension] = upperBound

            # If the new velocity of particle i is < the limit, then increase to the limit
            if newVelocity[particle][theDimension] < lowerBound:
                newVelocity[particle][theDimension] = lowerBound

    # Position -----

    ## Update new position based on the updated velocity
    newPosition = position[:] + newVelocity[:]

    ## Make sure that the position is within the bounds -----
    for particle in range(swarmSize):
        for theDimension in range(numDimensions):

            # Check to see if position in bounds
            while (newPosition[particle][theDimension] > upperBound) or (newPosition[particle][theDimension] < lowerBound):
                # Randomly move the position to a new location within the bounds
                newPosition[particle][theDimension] = lowerBound + (upperBound - lowerBound) * randNumGenerator.random()
```

```
        # Stochastically put the position in bounds
        newPosition[particle][theDimension] = randNumGenerator.uniform(lowerBound, upperBound)

# Convert position and velocity back to list -----
newPosition = newPosition.tolist()
newVelocity = newVelocity.tolist()

return [newPosition, newVelocity]
```

1.5 Function to Calculate Particle Historical Best Fitness Value and Position

```
# =====  
# Compare current position fitness value to the current best (for each particle)  
# =====  
def calculateParticleBests(position, swarmSize, numDimensions,  
                           pCurrFitValue, pBestPosition, pBestFitValue):  
    # Calculate the fitness of the new positions  
    for particle in range(swarmSize):  
        for theDimension in range(numDimensions):  
  
            # Get the current fitness value of the new positions  
            pCurrFitValue[particle] = evalFitnessVal(position[:, particle])  
  
            # Compare the current positions' value to their person best  
            if pCurrFitValue[particle] < pBestFitValue[particle]:  
  
                # If better, then set the best VALUE to the current value (as a copy [:])  
                pBestFitValue[particle] = pCurrFitValue[:, particle]  
  
                # If better, then set the best POSITION to the current position (as a copy [:])  
                pBestPosition[particle] = position[:, particle]  
  
    return [pCurrFitValue, pBestPosition, pBestFitValue]
```


1.6 2 Functions to Display Best Solution and Write to CSV

- writeIteratonsToCSV() is used to write a CSV with the top n iterations
- Using R, I plotted the first 5 iterations of swarmSize 5 (see related question below)

```
# =====
# DISPLAY GLOBAL BEST AND DIMENSIONS FUNCTION
# Function for displaying the global best and its dimensions
# =====
def displayGlobalBest(glBestFitValue, glBestPosition, numDimensions, printDims):
    # Print the global optima
    print('\nGlobal Best Value:\t % 0.4f' % glBestFitValue)

    # Print each dimension (if toggled)
    if printDims:
        print('For each [dimension], Global Best Position:')

        # Print the position of each dimension in markdown table format
        print('\n',
              '| Dimension | Global Best |', sep='')
        print('|-----|-----|')
        for theDimension in range(numDimensions):
            print('|| + str(theDimension).rjust(10, ' '),
                  '| + {:.4f}'.format(glBestPosition[theDimension]).rjust(12, ' ') + ' |'
                  )

# =====
# WRITE TOP n SWARM ITERATIONS TO A CSV FUNCTION
# Basic function for writing to file
# =====
def writeIteratonsToCSV(numDimensions, # Number of dimensions in the swarm
                        filename,
                        method,
                        velocityIterations,
                        positionIterations,
                        gBestPositionIterations,
                        swarmSize):

    iterBreak      = 1 # Display every n iterations
    maxIterToView = 5 # Top iteration to display

    # Write to file if the dimensions are 2D and using Global best.
    # (only global since list structure for each particle, not single value)
    if numDimensions == 2 and method == 'global':

        # Print the first 5 best positions of the swarm, while highlighting global best
        f = open(filename + '.csv', 'w') # Open CSV for writing

        # Column names
        f.write('iteration,particle,position1,position2,globalBest1,globalBest2,velocity1,velocity2\n')

        # Write the data to a CSV for plotting and summary table
```

```

for iteration in range(maxIterToView):
    thisIter = ''
    for particle in range(swarmSize):

        if iteration % iterBreak == 0:

            # Get the Iteration, Particle, position1/2 and velocity 1/2
            theVelocities = velocityIterations[iteration][particle]
            thePositions = positionIterations[iteration][particle]
            globalBest = gBestPositionIterations[iteration]

            # Convert the positions to flat text
            velDims = ','.join(['{: .4f}'.format(positionVal) for positionVal in theVelocities])
            posDims = ','.join(['{: .4f}'.format(positionVal) for positionVal in thePositions])
            globalDims = ','.join(['{: .4f}'.format(positionVal) for positionVal in globalBest])

            # Write tp the file
            f.write(str(iteration+1) + ',' + str(particle) + ',' + str(posDims) + ',' +
                    str(globalDims) + ',' + str(velDims) + '\n')

f.close() # close the file for saving output

```

1.7 Driver Function to Compile and Loop through a PSO Problem

```
# =====
# SWARM OPTIMIZATION FUNCTION
# Parameters:
# ---- numDimensions:   The number of dimension in the schwefel function
# ---- swarmSize:       The number of particles within the swarm
# ---- inertiaWeight:   The weight assigned to the inertia component of the velocity eq.
# ---- phi1:            Cognitive weight of the velocity equation. Note phi1 + phi2 <= 4
# ---- phi2:            Social weight of the velocity equation. Note phi1 + phi2 <= 4
# ---- totalIterations: The total number of iterations before stopping (Stopping criterion)
# ---- method:          Can use 'local' or 'global' best methods.
# ----                  'local' uses Ring Structure with 2 neighbors by default
# ---- filename:        Name of CSV file to export to working directory.
# ----                  If using 2D and 'global' best method, will export CSV.
# ----                  Reason for exporting is to read in data to R for plotting iterations
# ---- printDims:       Print the dimensions' value or not
# =====

def swarmOptimizationSchwefel( # ----- Defaults -----
    numDimensions = 2,      # number of dimensions of problem
    swarmSize     = 5,      # number of particles in swar
    phi1          = 2,      # Cognitive weight
    phi2          = 2,      # Social weight
    inertiaWeight = 0.1,    # Constant Inertia weighting value
    totalIterations = 100,  # Stopping criteria = the total number of iterations
    method        = 'local', # 'local' or 'global' best function name
    filename       = 'output', # Name of the ouput csv file to write first 5 iterations,
    printDims      = False   # Print the dimension's value or not
):

    # Initialize to global best function by default
    functionToGetBest = getGlobalBest

    # If not using the global best, then switch to the local best method
    if method != 'global':
        functionToGetBest = getLocalBest

    # -----
    # INITIALIZE POSITION AND VELOCITY, and INITIAL BESTS
    # the swarm will be represented as a list of positions, velocities, values,
    # pBestPosition, and pBestPosition values
    # Note: position[0] and velocity[0] provides the position and velocity of particle 0;
    # position[1] and velocity[1] provides the position and velocity of particle 1; and so on.
    # -----

    # Step 1: Initialize swarm and get the particles' and global best (and current position)
    position, velocity, pCurrFitValue, pBestPosition, pBestFitValue, glBestFitValue, glBestPosition = i

    # Create empty lists for holding the swarm iterations
    positionIterations = [] # Each particle's velocity
```

```

velocityIterations      = [] # Each particle's position
gBestPositionIterations = [] # The current Global Best Position

# -----
# Main Loop
# -----
for iteration in range(totalIterations):

    # Step 0: Keep track of each iterations/dimension for velocity, position, and current global best
    velocityIterations.append(velocity)
    positionIterations.append(position)
    gBestPositionIterations.append(gBestPosition)

    # Step 2: Update the velocity and position
    velocity, position = updateVelocityAndPosition(inertiaWeight, velocity, position,
                                                    phi1, phi2, pBestPosition, gBestPosition,
                                                    swarmSize, numDimensions)

    # Step 3: Recalculate the particle and global bests
    pCurrFitValue, pBestPosition, pBestFitValue = calculateParticleBests(position,
                                                                           swarmSize, numDimensions,
                                                                           pCurrFitValue,
                                                                           pBestPosition,
                                                                           pBestFitValue)

    # Step 4: Get the Global or local best (depends on chosen method) fitness value and position
    gBestFitValue, gBestPosition = functionToGetBest(pBestFitValue[:], pBestPosition[:], swarmSize)

# -----
# Global Best
# -----

# Finally, if using the local best method, get the absolute best from the local bests
if method == 'local':
    gBestFitValue, gBestPosition = getGlobalBest(gBestFitValue, gBestPosition, swarmSize)
else: # if not local best, then change the gl best is the global best
    gBestFitValue, gBestPosition = gBestFitValue, gBestPosition

# -----
# Print and Export
# -----

# Print the global (or local best) and each dimensions' position
displayGlobalBest(gBestFitValue, gBestPosition, numDimensions, printDims)

# If 2D, then write to a csv for plotting in R
writeIteratonsToCSV(numDimensions, filename, method, velocityIterations,
                   positionIterations, gBestPositionIterations, swarmSize)

```

```
return gBestFitValue # return the best fit
```

1.8 Part 1 (b) & (c) - Global Best Method

1.8.1 1(b) 2D Global Swarm

Create a swarm of size 5 and solve the 2D Schwefel problem

```
# 1(b) Create a swarm of size 5 and solve the 2D Schwefel problem. -----
swarmOptimizationSchwefel(
    numDimensions    = 2,          # number of dimensions of problem
    swarmSize        = 5,          # number of particles in swar
    phi1              = 2,          # Cognitive weight
    phi2              = 2,          # Social weight
    inertiaWeight     = 0.1,        # Constant Inertia weighting value
    totalIterations   = 100000,     # Stopping criteria = the total number of iterations
    method            = 'global',   # 'local' or 'global' best function name
    filename          = 'output',   # Name of the ouput csv file to write first 5 iterations
    printDims         = True        # Print the dimension's value or not
)
```

```
##
## Global Best Value:      0.0005
## For each [dimension], Global Best Position:
##
## | Dimension | Global Best |
## |-----|-----|
## |          0 |    420.9120 |
## |          1 |    420.9941 |
## 0.0005125608778371316
```

1.8.2 1(b) i. - iii. Iteration Table & Plot

i. - ii. Record in table the first 5 positions and velocities of each particle. Highlight Global Best

```
library(tidyverse)
library(ggplot2)
library(readr)  # Read CSV
library(knitr)  # table printing

# Pull in the data from the swarm optimization (written in
# main loop)
swarmData <- read_csv("output.csv")

# Table holding the 5 iterations for the 5 particles
# Position and Velocity 1 & 2, as well indicator of global
# best
swarmDataTable <- swarmData %>%
  mutate(isGlobalBest = if_else(position1 == globalBest1 &
    position2 == globalBest2, "New Global Best!", "")) %>%

select(particle, iteration, starts_with("pos"), starts_with("vel"),
  isGlobalBest)

# Print the table
kable(swarmDataTable)
```

particle	iteration	position1	position2	velocity1	velocity2	isGlobalBest
0	1	-83.3801	325.2065	-0.9797	-0.4027	
1	1	-131.5883	66.0082	-0.6127	-0.6766	
2	1	-375.7331	62.0785	-0.1341	-0.6513	
3	1	53.2211	458.0648	-0.2902	-0.8174	New Global Best!
4	1	478.6400	3.9354	-0.1758	-0.7037	
0	2	51.8027	50.4383	-31.5775	375.6448	
1	2	70.1557	148.8914	-61.4326	214.8996	
2	2	162.9646	150.3870	-212.7685	212.4655	
3	2	-0.0290	-0.0817	53.1921	457.9830	
4	2	-161.6524	172.4728	316.9876	176.4082	
0	3	-3.0910	56.7402	48.7117	107.1785	
1	3	-144.7555	-20.5850	-74.5997	128.3064	
2	3	-26.4395	35.7205	136.5252	186.1075	
3	3	44.2005	380.3201	44.1715	380.2383	
4	3	41.8069	31.0758	-119.8455	203.5486	
0	4	151.1079	500.0000	148.0169	478.7985	
1	4	384.5587	500.0000	239.8032	479.4150	
2	4	167.7929	500.0000	141.3534	244.5300	
3	4	27.9970	241.2485	72.1975	-496.5454	
4	4	-128.0547	500.0000	-86.2478	440.2385	
0	5	-309.0507	-500.0000	-157.9428	0.0000	New Global Best!
1	5	-500.0000	-500.0000	-115.4413	0.0000	
2	5	-500.0000	-500.0000	-332.2071	0.0000	

particle	iteration	position1	position2	velocity1	velocity2	isGlobalBest
3	5	90.0355	500.0000	118.0325	-321.1262	
4	5	212.3308	-500.0000	84.2761	0.0000	

iii Plot the first 5 positions of each of the 5 particles

```
require(ggplot2)

# Plot the first 5 iterations with each particle's position
iterPlot <- swarmData %>%
  ggplot() +

  # Points for the Swarm
  geom_point(aes(x = swarmData$position1,
                 y = swarmData$position2),
             alpha = 0.2, color = 'steelblue3', size = 5) +

  # Red Point for the global best
  geom_point(aes(x = swarmData$globalBest1,
                 y = swarmData$globalBest2),
             alpha = 0.25,
             color = 'tomato3', size = 5, shape = 18) +

  # Label for the global best
  geom_text(label = paste0('      Global Best:      (',
                           round(swarmData$globalBest1, 2), ', ',
                           round(swarmData$globalBest2, 2), ')'),
            aes(x = swarmData$globalBest1,
                y = swarmData$globalBest2),
            color = 'tomato3',
            # alpha = 0.9,
            size = 3) +

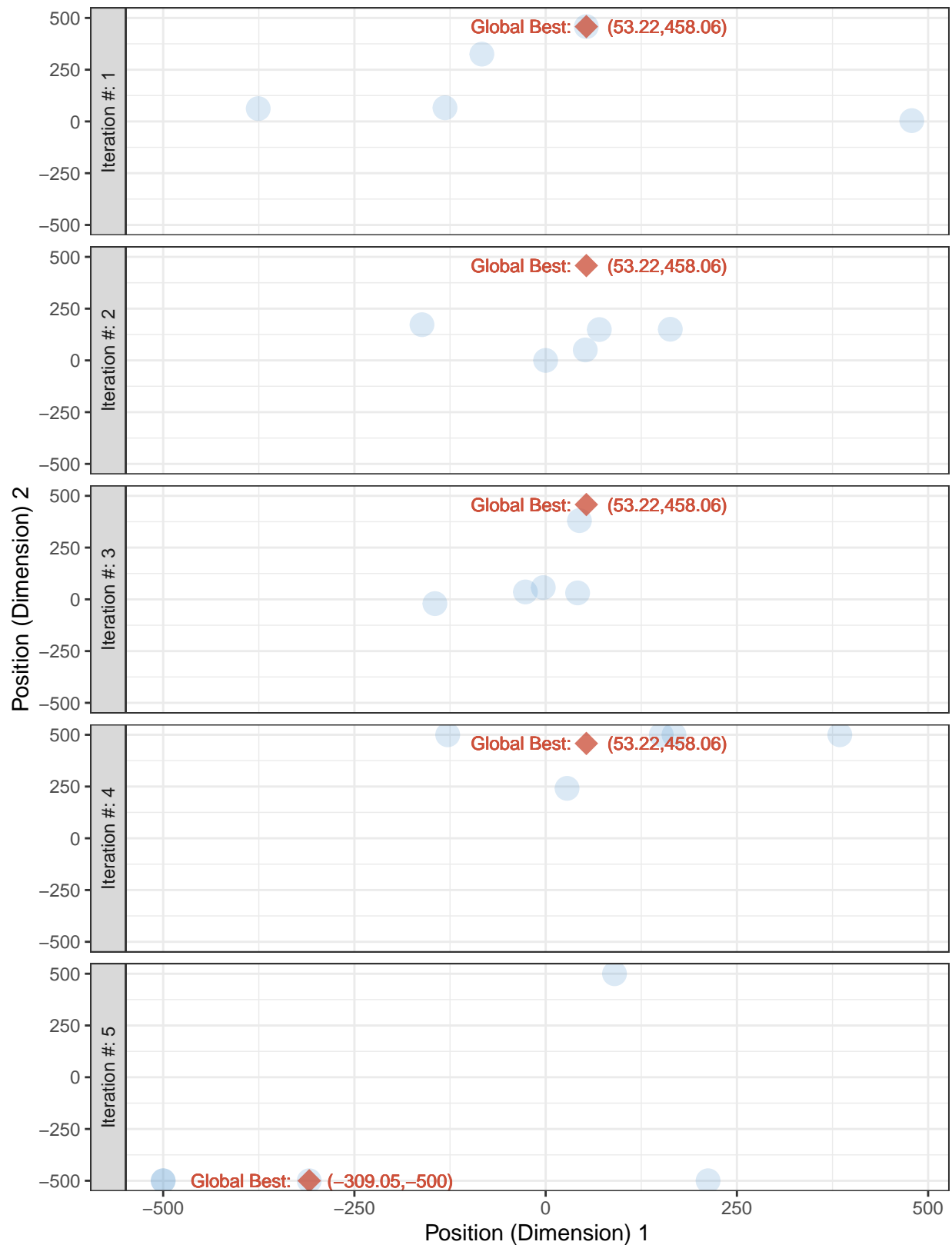
  # Facet by Iteration
  facet_grid(rows = vars(paste0('Iteration #: ', iteration)),
             switch = 'y') +
  labs(title = 'Particle Swarm Optimization',
       subtitle = paste0('Shows the first ', max(swarmData$iteration),
                          ' iterations of the PSO | Daniel Carpenter'),
       x = 'Position (Dimension) 1',
       y = 'Position (Dimension) 2') +

  theme_bw() # a theme

print(iterPlot)
```

Particle Swarm Optimization

Shows the first 5 iterations of the PSO | Daniel Carpenter



1.8.3 1(c) 200D Global Swarm w/Variious Param

Create a swarm to best and solve the 200D Schwefel problem

- Please note I did 50 iterations as stopping criteria simply for the sake a running to completion
- My computer cannot handle such large loads. It is likely that higher number of iterations would lead to closer to the known optima
- You can see that the 2D performs very well, as it does with increased dimensions (just not 200).

```
# 1(c) create a swarm to best and solve the 200D Schwefel problem. -----
# Try different swarm sizes, inertial weights, and values for phi1 and phi2

# 1(c, i) Base 200D
s1 = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 5,       # number of particles in swar
    phi1           = 2,       # Cognitive weight
    phi2           = 2,       # Social weight
    inertiaWeight  = 0.1,     # Constant Inertia weighting value
    totalIterations = 50,     # Stopping criteria = the total number of iterations
    method         = 'global', # 'local' or 'global' best function name
    printDims      = False    # Print the dimension's value or not
)

# 1(c, ii.) 200D, changes: Swarm from 5 to 10
```

```
##
## Global Best Value:      76347.0722
```

```
s2 = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 10,     # number of particles in swar
    phi1           = 2,       # Cognitive weight
    phi2           = 2,       # Social weight
    inertiaWeight  = 0.1,     # Constant Inertia weighting value
    totalIterations = 50,     # Stopping criteria = the total number of iterations
    method         = 'global', # 'local' or 'global' best function name
    printDims      = False    # Print the dimension's value or not
)

# 1(c, iii.) 200D, changes: phi1: 1, phi2: 3
```

```
##
## Global Best Value:      75781.8518
```

```
s3 = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 10,     # number of particles in swar
    phi1           = 1,       # Cognitive weight
    phi2           = 3,       # Social weight
    inertiaWeight  = 0.1,     # Constant Inertia weighting value
    totalIterations = 50,     # Stopping criteria = the total number of iterations
```

```

    method          = 'global', # 'local' or 'global' best function name
    printDims        = False     # Print the dimension's value or not
)

# 1(c, iv.) 200D, changes: inertia weight = 0.9

##
## Global Best Value:      75998.1002

s4 = swarmOptimizationSchwefel(
    numDimensions    = 200,      # number of dimensions of problem
    swarmSize        = 10,      # number of particles in swar
    phi1              = 1,      # Cognitive weight
    phi2              = 3,      # Social weight
    inertiaWeight     = 0.9,     # Constant Inertia weighting value
    totalIterations   = 50,     # Stopping criteria = the total number of iterations
    method            = 'global', # 'local' or 'global' best function name
    printDims         = False    # Print the dimension's value or not
)

# 1(c, v.) 200D, changes: phi1: 3, phi2: 1

##
## Global Best Value:      77573.9291

s5 = swarmOptimizationSchwefel(
    numDimensions    = 200,      # number of dimensions of problem
    swarmSize        = 10,      # number of particles in swar
    phi1              = 3,      # Cognitive weight
    phi2              = 1,      # Social weight
    inertiaWeight     = 0.9,     # Constant Inertia weighting value
    totalIterations   = 50,     # Stopping criteria = the total number of iterations
    method            = 'global', # 'local' or 'global' best function name
    printDims         = False    # Print the dimension's value or not
)

# Compile the results

##
## Global Best Value:      74347.6093

swarmResults = [s1, s2, s3, s4, s5]

print('\n----- Question 1(c) Results of Swarm Runs -----')

##
## ----- Question 1(c) Results of Swarm Runs -----

for result in range(0, len(swarmResults)):
    print('Result', result, ':\t', swarmResults[result])

```

```
## Result 0 :      76347.07221466661
## Result 1 :      75781.85183383343
## Result 2 :      75998.1002495657
## Result 3 :      77573.92907934781
## Result 4 :      74347.60932545959
```

1.9 Part 1 (d) & (e) - Local Best Method

1.9.1 Reference: Local Swarm Calculation and Logic

Uses a Ring Topology for Local Best Method

- Note this function already defined but placed here for ease of referencing

```
# =====
# LOCAL MIN VALUE AND POSITION SEARCH FUNCTION
# Topology: Ring structure with n neighbors (default 2)
# Returns the 2 element list of lists with the each particle's local best within neighborhood
# ---- [0] min value and
# ---- [1] associate position of
# Can change numParticlesInNbrhood to consider more or less in particle's neighborhood
# =====
def getLocalBest(fitnessValues, positions, swarmSize,
                 numParticlesInNbrhood = 2): # Number of particles to compare to for local best

    lBestFitValue = [] # will hold the best VALUE of the n surrounding particles, for each particle
    lBestPosition = [] # will hold the best POSITION of the n surrounding particles, for each particle

    # For every particle in the swarm, (starting at n less than index 0)
    for particle in range(-numParticlesInNbrhood, swarmSize - numParticlesInNbrhood):

        # Identify the two neighbors fitness value of this particle,
        # which are the two preceding particles
        personalBestNeighbor1 = fitnessValues[particle]
        personalBestNeighbor2 = fitnessValues[particle + 1]

        # Identify the lowest fitness value of this particle's the two preceding neighbors
        minNeighValue = min(personalBestNeighbor1, personalBestNeighbor2)

        # Store the index of the particle
        minNeighIndex = fitnessValues.index(minNeighValue)

        # Store the particle's best neighbors fitness value and position
        lBestFitValue.append(fitnessValues[minNeighIndex])
        lBestPosition.append(positions[minNeighIndex])

    # Returns a list of particles and the min of their n best fit. valued neighbors
    return[lBestFitValue, lBestPosition]
```

1.9.2 1(d) 2D Local Swarm

Implement a PSO algorithm that uses the *local best* with *ring* topology in place of the global best. See above logic and explanation

```
# 1(d) Create a swarm of size 5 and solve the 2D Schwefel problem. -----
# Implement a PSO algorithm that uses the "local best" in place of the
# global best and explain which topology you are using.

# Topology: Ring structure with 2 neighbors
swarmOptimizationSchwefel(
    numDimensions    = 2,          # number of dimensions of problem
    swarmSize        = 5,          # number of particles in swar
    phi1              = 2,          # Cognitive weight
    phi2              = 2,          # Social weight
    inertiaWeight     = 0.1,        # Constant Inertia weighting value
    totalIterations   = 100000,     # Stopping criteria = the total number of iterations
    method            = 'local',    # 'local' or 'global' best function name
    filename          = 'output',   # Name of the ouput csv file to write first 5 iterations
    printDims         = True        # Print the dimension's value or not
)

##
## Global Best Value:      0.0004
## For each [dimension], Global Best Position:
##
## | Dimension | Global Best |
## |-----|-----|
## |         0 |    420.9179 |
## |         1 |    420.9590 |
## 0.0003635313285030861
```

1.9.3 1(e) 200D Local Swarm w/Variious Params.

Solve the 200D Schwefel problem as best as possible

```
# 1(e) create a swarm to best and solve the 200D Schwefel problem. -----
# Same as 1(c) parameters, just using 'local' now
# Topology: Ring structure with 2 neighbors

# 1(e, i) Base 200D
s1e = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 5,      # number of particles in swar
    phi1           = 2,      # Cognitive weight
    phi2           = 2,      # Social weight
    inertiaWeight  = 0.1,    # Constant Inertia weighting value
    totalIterations = 50,    # Stopping criteria = the total number of iterations
    method         = 'local', # 'local' or 'global' best function name
    printDims      = False   # Print the dimension's value or not
)
```

1(e, ii.) 200D, changes: Swarm from 5 to 10

```
##
## Global Best Value:      76065.0451
```

```
s2e = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 10,     # number of particles in swar
    phi1           = 2,      # Cognitive weight
    phi2           = 2,      # Social weight
    inertiaWeight  = 0.1,    # Constant Inertia weighting value
    totalIterations = 50,    # Stopping criteria = the total number of iterations
    method         = 'local', # 'local' or 'global' best function name
    printDims      = False   # Print the dimension's value or not
)
```

1(e, iii.) 200D, changes: phi1: 1, phi2: 3

```
##
## Global Best Value:      77721.3454
```

```
s3e = swarmOptimizationSchwefel(
    numDimensions = 200,      # number of dimensions of problem
    swarmSize      = 10,     # number of particles in swar
    phi1           = 1,      # Cognitive weight
    phi2           = 3,      # Social weight
    inertiaWeight  = 0.1,    # Constant Inertia weighting value
    totalIterations = 50,    # Stopping criteria = the total number of iterations
    method         = 'local', # 'local' or 'global' best function name
    printDims      = False   # Print the dimension's value or not
)
```

1(e, iv.) 200D, changes: interia weight = 0.9

```
##
## Global Best Value:      75777.2461
```

```
s4e = swarmOptimizationSchwefel(
    numDimensions    = 200,      # number of dimensions of problem
    swarmSize        = 10,      # number of particles in swar
    phi1             = 1,       # Cognitive weight
    phi2             = 3,       # Social weight
    inertiaWeight    = 0.9,     # Constant Inertia weighting value
    totalIterations  = 50,      # Stopping criteria = the total number of iterations
    method           = 'local', # 'local' or 'global' best function name
    printDims        = False    # Print the dimension's value or not
)
```

```
# 1(e, v.) 200D, changes: phi1: 3, phi2: 1
```

```
##
## Global Best Value:      75704.8377
```

```
s5e = swarmOptimizationSchwefel(
    numDimensions    = 200,      # number of dimensions of problem
    swarmSize        = 10,      # number of particles in swar
    phi1             = 3,       # Cognitive weight
    phi2             = 1,       # Social weight
    inertiaWeight    = 0.9,     # Constant Inertia weighting value
    totalIterations  = 50,      # Stopping criteria = the total number of iterations
    method           = 'local', # 'local' or 'global' best function name
    printDims        = False    # Print the dimension's value or not
)
```

```
##
## Global Best Value:      75700.0155
```

```
swarmResultsE = [s1e, s2e, s3e, s4e, s5e]
```

```
print('\n----- Question 1(e) Results of Swarm Runs -----')
```

```
##
## ----- Question 1(e) Results of Swarm Runs -----
```

```
for result in range(0, len(swarmResultsE)):
    print('Result', result, ':\t', swarmResultsE[result])
```

```
## Result 0 :      76065.04505657653
## Result 1 :      77721.34535963654
## Result 2 :      75777.24606450333
## Result 3 :      75704.83774699294
## Result 4 :      75700.0155348131
```