

Stabilized High-Order Multirate Time-Integration for Multiphysics via Paired-Explicit Runge-Kutta Methods

SIAM CSE 2025

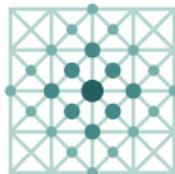
Daniel Doebring¹

in collaboration with

Michael Schlottke-Lakemper², Manuel Torrilhon¹,
and Gregor Gassner³

¹ACoM, RWTH Aachen University ²HPSC, University of Augsburg ³CDS, University of Cologne

2025/03/05



Applied and
Computational
Mathematics

**RWTHAACHEN
UNIVERSITY**

Outline

Stabilized High-Order Multirate Time-Integration for Multiphysics via Paired-Explicit Runge-Kutta Methods

① Scope & Motivation

② Ingredients

③ Application

- Euler-Gravity

④ Conclusion & Outlook

Scope

Consider PDEs of the form

$$\partial_t \mathbf{u}(t, \mathbf{x}) + \nabla \cdot \mathbf{f}(\mathbf{u}, \nabla \mathbf{u}) + \mathbf{g}(\mathbf{u}, \nabla \mathbf{u}) = \mathbf{s}(t, \mathbf{x}; \mathbf{u})$$

which describe e.g. compressible flows and related systems.

Scope

Consider PDEs of the form

$$\partial_t \mathbf{u}(t, \mathbf{x}) + \nabla \cdot \mathbf{f}(\mathbf{u}, \nabla \mathbf{u}) + \mathbf{g}(\mathbf{u}, \nabla \mathbf{u}) = \mathbf{s}(t, \mathbf{x}; \mathbf{u})$$

which describe e.g. compressible flows and related systems.

We employ a **method-of-lines** approach (via the DGSEM) to obtain

$$\frac{d}{dt} \mathbf{U}(t) = \mathbf{F}(t, \mathbf{U}(t))$$



Scope

Consider PDEs of the form

$$\partial_t \mathbf{u}(t, \mathbf{x}) + \nabla \cdot \mathbf{f}(\mathbf{u}, \nabla \mathbf{u}) + \mathbf{g}(\mathbf{u}, \nabla \mathbf{u}) = \mathbf{s}(t, \mathbf{x}; \mathbf{u})$$

which describe e.g. compressible flows and related systems.

We employ a **method-of-lines** approach (via the DGSEM) to obtain

$$\frac{d}{dt} \mathbf{U}(t) = \mathbf{F}(t, \mathbf{U}(t))$$

and target **convection-dominated** PDEs, i.e.,

$$\rho \sim \frac{|a|}{\Delta x} \gg \frac{d}{\Delta x^2}$$

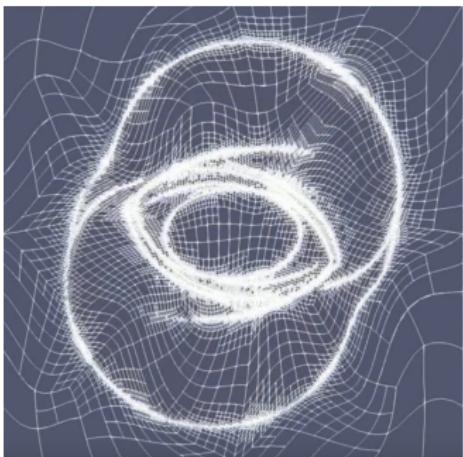
where ρ is the spectral radius of

$$J_{\mathbf{F}}(\mathbf{U}) := \left. \frac{\partial \mathbf{F}}{\partial \mathbf{U}} \right|_{\mathbf{U}}$$

Motivation

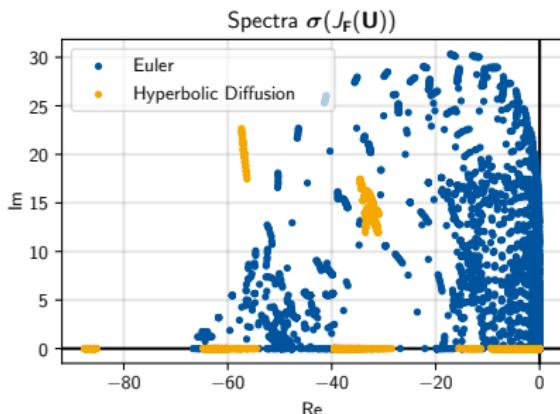
Explicit time-integration for

- ① non-uniform meshes



- ② coupled systems

with **global** time-stepping leaves room
for **efficiency gains!**



Ingredient #1: Optimized Stability Polynomials

Objective:¹

$$\max_{P_{p,S} \in \mathcal{P}_{p,S}} \Delta t \text{ such that } |P_{p,S}(\Delta t \lambda_m)| \leq 1, \quad \lambda_m \in \sigma(J_F(\mathbf{U}_0))$$

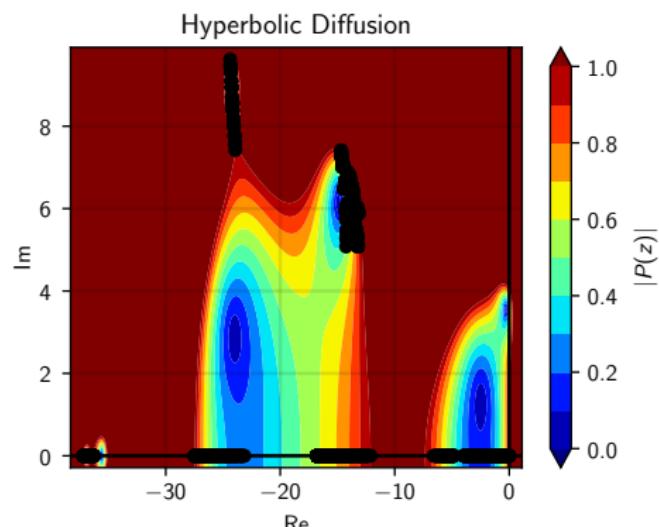
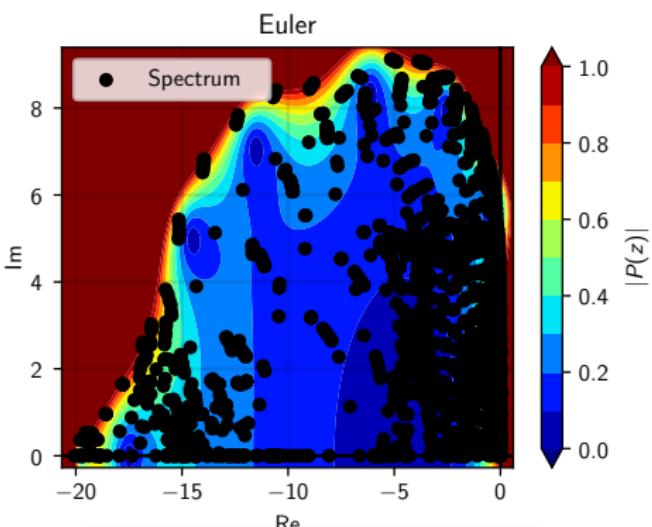
¹Ketcheson & Ahmadia; CAMCoS; 2012



Ingredient #1: Optimized Stability Polynomials

Objective:¹

$$\max_{P_{p,S} \in \mathcal{P}_{p,S}} \Delta t \text{ such that } |P_{p,S}(\Delta t \lambda_m)| \leq 1, \quad \lambda_m \in \sigma(J_F(\mathbf{U}_0))$$

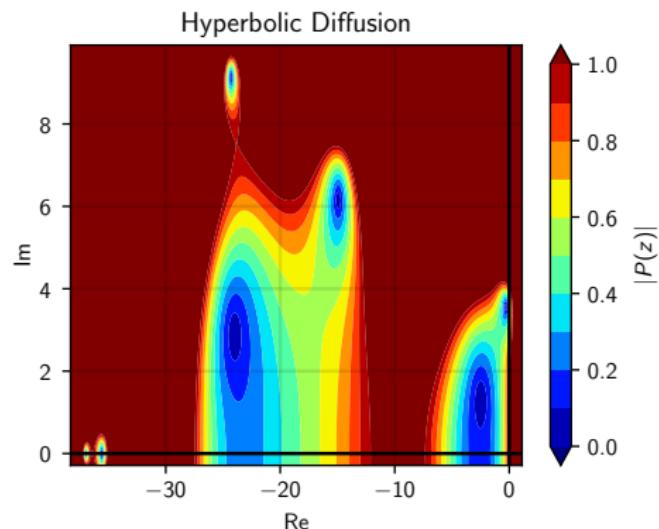
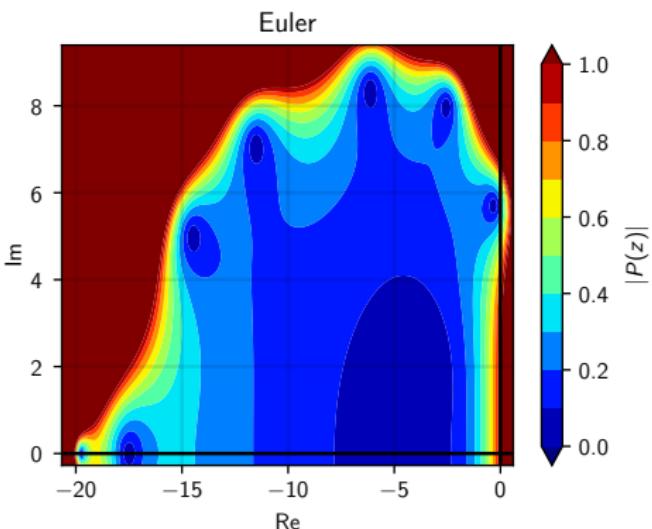


¹Ketcheson & Ahmadia; CAMCoS; 2012

Ingredient #1: Optimized Stability Polynomials

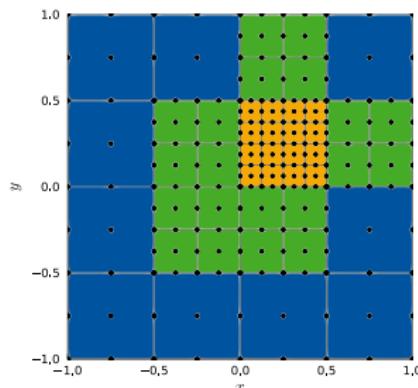
Objective:

$$\max_{P_{p,S} \in \mathcal{P}_{p,S}} \Delta t \text{ such that } |P_{p,S}(\Delta t \lambda_m)| \leq 1, \quad \lambda_m \in \sigma(J_F(\mathbf{U}_0))$$



Ingredient #2: Partitioned RKM

Multirate time-integration by using **stabilized/optimized** schemes in regions with higher characteristic speeds (stricter CFL)

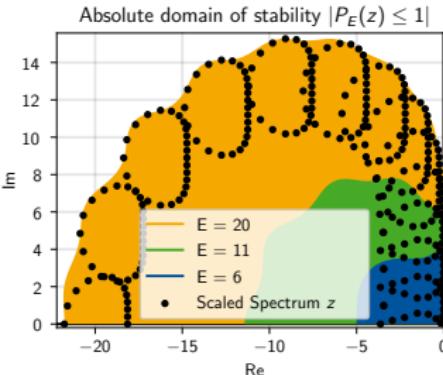
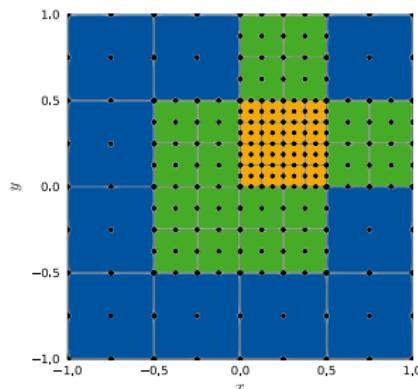


- For *convection-dominated* problems:

$$\Delta t \stackrel{!}{\leq} C_t(S) \cdot C_x(k) \min_{i,j} \frac{\Delta x_i}{|\mu_j(\mathbf{u}_i)|}, \quad \mu_j \in \sigma \left(\frac{\partial \mathbf{f}_j}{\partial \mathbf{u}} \right)$$

Ingredient #2: Partitioned RKM

Multirate time-integration by using **stabilized/optimized** schemes in regions with higher characteristic speeds (stricter CFL)



- For *convection-dominated* problems:

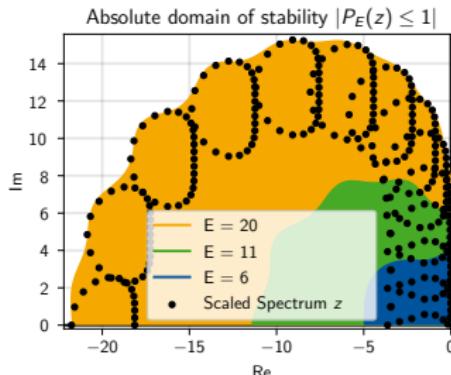
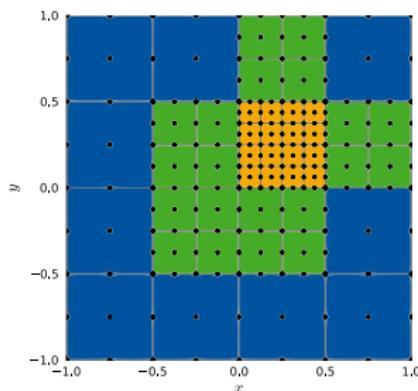
$$\Delta t \stackrel{!}{\leq} C_t(S) \cdot C_x(k) \min_{i,j} \frac{\Delta x_i}{|\mu_j(\mathbf{u}_i)|}, \quad \mu_j \in \sigma \left(\frac{\partial \mathbf{f}_j}{\partial \mathbf{u}} \right)$$

- For *optimized* Runge-Kutta schemes:

$$\Delta t_{p;S} \xrightarrow{S \rightarrow \infty} \Delta t_{p;S_0} \frac{S}{S_0}$$

Ingredient #2: Partitioned RKMs

Multirate time-integration by using **stabilized/optimized** schemes in regions with higher characteristic speeds (stricter CFL)



- For *convection-dominated* problems:

$$\Delta t \stackrel{!}{\leq} C_t(S) \cdot C_x(k) \min_{i,j} \frac{\Delta x_i}{|\mu_j(\mathbf{u}_i)|}, \quad \mu_j \in \sigma \left(\frac{\partial \mathbf{f}_j}{\partial \mathbf{u}} \right)$$

- For *optimized* Runge-Kutta schemes:

$$\Delta t_{p;S} \stackrel{S \rightarrow \infty}{\simeq} \Delta t_{p;S_0} \frac{S}{S_0}$$

Ingredient #2: Partitioned RKM

Partition ODE according to characteristic speeds $a_i := \min_j \frac{\Delta x_i}{|\mu_j(\mathbf{u}_i)|}$

$$\mathbf{U}'(t) = \begin{pmatrix} \mathbf{U}^{(1)}(t) \\ \vdots \\ \mathbf{U}^{(R)}(t) \end{pmatrix}' = \begin{pmatrix} \mathbf{F}^{(1)}(t, \mathbf{U}^{(1)}(t), \dots, \mathbf{U}^{(R)}(t)) \\ \vdots \\ \mathbf{F}^{(R)}(t, \mathbf{U}^{(1)}(t), \dots, \mathbf{U}^{(R)}(t)) \end{pmatrix} = \mathbf{F}(t, \mathbf{U}(t))$$



Ingredient #2: Partitioned RKM

Partition ODE according to characteristic speeds $a_i := \min_j \frac{\Delta x_i}{|\mu_j(\mathbf{u}_i)|}$

$$\mathbf{U}'(t) = \begin{pmatrix} \mathbf{U}^{(1)}(t) \\ \vdots \\ \mathbf{U}^{(R)}(t) \end{pmatrix}' = \begin{pmatrix} \mathbf{F}^{(1)}(t, \mathbf{U}^{(1)}(t), \dots, \mathbf{U}^{(R)}(t)) \\ \vdots \\ \mathbf{F}^{(R)}(t, \mathbf{U}^{(1)}(t), \dots, \mathbf{U}^{(R)}(t)) \end{pmatrix} = \mathbf{F}(t, \mathbf{U}(t))$$

and employ different RKM

$$\mathbf{K}_i^{(r)} = \mathbf{F}^{(r)} \left(t_n + c_i \Delta t, \mathbf{U}_n + \Delta t \sum_{j=1}^S \sum_{k=1}^R a_{i,j}^{(k)} \mathbf{K}_j^{(k)} \right),$$

$$\mathbf{U}_{n+1} = \mathbf{U}_n + \Delta t \sum_{i=1}^S b_i \sum_{k=1}^R \mathbf{K}_i^{(r)}$$

optimized for the spectrum $\sigma \left(\frac{\partial \mathbf{F}}{\partial \mathbf{U}} \Big|_{\mathbf{U}_0} \right)$. (*Ingredient #1*)

Ingredient #2: Partitioned/Paired RKM

- $S = 6, p = 2$ Paired¹ $E = \{3, 6\}$ RK

i	\mathbf{c}	$A^{(1)}$					$A^{(2)}$				
1	0										
2	$1/10$	$1/10$					$1/10$				
3	$2/10$	$2/10$	0				$2/10 - a_{3,2}^{(2)}$	$a_{3,2}^{(2)}$			
4	$3/10$	$3/10$	0	0			$3/10 - a_{4,3}^{(2)}$	0	$a_{4,3}^{(2)}$		
5	$4/10$	$4/10$	0	0	0		$4/10 - a_{5,4}^{(2)}$	0	0	$a_{5,4}^{(2)}$	
6	$5/10$	$5/10 - a_{6,5}^{(1)}$	0	0	0	$a_{6,5}^{(1)}$	$5/10 - a_{6,4}^{(2)}$	0	0	0	$a_{6,4}^{(2)}$
	\mathbf{b}^T	0	0	0	0	0	1	0	0	0	0

¹Vermeire; JCP; 2019



Ingredient #2: Partitioned/Paired RKM

- $S = 6, p = 2$ Paired¹ $E = \{3, 6\}$ RK

i	\mathbf{c}	$A^{(1)}$				$A^{(2)}$			
1	0								
2	$1/10$	$1/10$				$1/10$			
3	$2/10$	$2/10$	0			$2/10 - a_{3,2}^{(2)}$	$a_{3,2}^{(2)}$		
4	$3/10$	$3/10$	0	0		$3/10 - a_{4,3}^{(2)}$	0	$a_{4,3}^{(2)}$	
5	$4/10$	$4/10$	0	0	0	$4/10 - a_{5,4}^{(2)}$	0	0	$a_{5,4}^{(2)}$
6	$5/10$	$5/10 - a_{6,5}^{(1)}$	0	0	0	$5/10 - a_{6,4}^{(2)}$	0	0	$a_{6,4}^{(2)}$
	\mathbf{b}^T	0	0	0	0	0	0	0	0
					1				1

- Method $r = 1$ requires $\mathbf{F}^{(1)}$ evaluation only for $i = 1, 5, 6$

¹Vermeire; JCP; 2019

Ingredient #2: Partitioned/Paired RKM

- $S = 6, p = 2$ Paired¹ $E = \{3, 6\}$ RK

i	\mathbf{c}	$A^{(1)}$				$A^{(2)}$			
1	0								
2	$1/10$	$1/10$				$1/10$			
3	$2/10$	$2/10$	0			$2/10 - a_{3,2}^{(2)}$	$a_{3,2}^{(2)}$		
4	$3/10$	$3/10$	0	0		$3/10 - a_{4,3}^{(2)}$	0	$a_{4,3}^{(2)}$	
5	$4/10$	$4/10$	0	0	0	$4/10 - a_{5,4}^{(2)}$	0	0	$a_{5,4}^{(2)}$
6	$5/10$	$5/10 - a_{6,5}^{(1)}$	0	0	0	$5/10 - a_{6,4}^{(2)}$	0	0	$a_{6,4}^{(2)}$
	\mathbf{b}^T	0	0	0	0	0	0	0	0
						0	0	0	1

- Method $r = 1$ requires $\mathbf{F}^{(1)}$ evaluation only for $i = 1, 5, 6$
- Method $r = 2$ requires $\mathbf{F}^{(2)}$ evaluation for all $i = 1, \dots, 6$

¹Vermeire; JCP; 2019



Application: Euler-Gravity

Euler (2D)

$$\partial_t \begin{pmatrix} \rho \\ \rho v_x \\ \rho v_y \\ E \end{pmatrix} + \nabla \cdot \begin{pmatrix} \rho v_x & \rho v_y \\ \rho v_x^2 + p & \rho v_x v_y \\ \rho v_x v_y & \rho v_y^2 + p \\ (E + p)v_x & (E + p)v_y \end{pmatrix}$$

¹Schlottke-Lakemper et al.; JCP; 2021



Application: Euler-Gravity

Euler (2D)

$$\partial_t \begin{pmatrix} \rho \\ \rho v_x \\ \rho v_y \\ E \end{pmatrix} + \nabla \cdot \begin{pmatrix} \rho v_x & \rho v_y \\ \rho v_x^2 + p & \rho v_x v_y \\ \rho v_x v_y & \rho v_y^2 + p \\ (E + p)v_x & (E + p)v_y \end{pmatrix}$$

+ a self-gravitational potential ϕ

$$-\Delta\phi = -4\pi G\rho$$

¹Schlottke-Lakemper et al.; JCP; 2021



Application: Euler-Gravity

Euler (2D)

$$\partial_t \begin{pmatrix} \rho \\ \rho v_x \\ \rho v_y \\ E \end{pmatrix} + \nabla \cdot \begin{pmatrix} \rho v_x & \rho v_y \\ \rho v_x^2 + p & \rho v_x v_y \\ \rho v_x v_y & \rho v_y^2 + p \\ (E + p)v_x & (E + p)v_y \end{pmatrix} = \begin{pmatrix} 0 \\ -\rho \partial_x \phi \\ -\rho \partial_y \phi \\ -\rho \mathbf{v} \cdot \nabla \phi \end{pmatrix}$$

+ a self-gravitational potential ϕ

$$-\Delta \phi = -4\pi G \rho$$

which *couples* to the momentum and energy equations¹.

¹Schlottke-Lakemper et al.; JCP; 2021



Application: Euler-Gravity

Euler (2D) (hyperbolic)

$$\partial_t \begin{pmatrix} \rho \\ \rho v_x \\ \rho v_y \\ E \end{pmatrix} + \nabla \cdot \begin{pmatrix} \rho v_x & \rho v_y \\ \rho v_x^2 + p & \rho v_x v_y \\ \rho v_x v_y & \rho v_y^2 + p \\ (E + p)v_x & (E + p)v_y \end{pmatrix} = \begin{pmatrix} 0 \\ -\rho \partial_x \phi \\ -\rho \partial_y \phi \\ -\rho \mathbf{v} \cdot \nabla \phi \end{pmatrix}$$

+ a self-gravitational potential ϕ (elliptic)

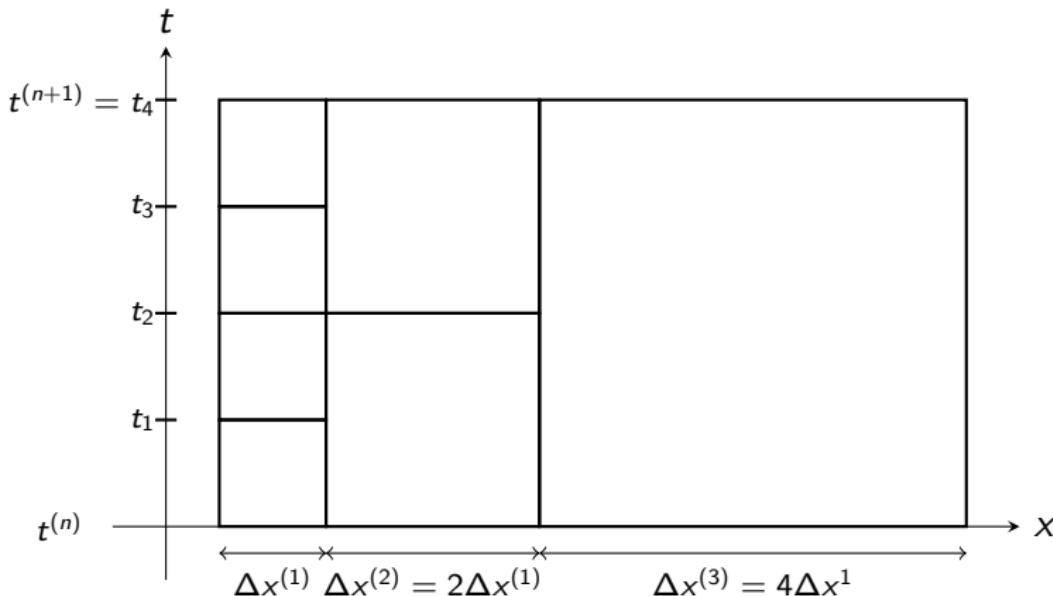
$$-\Delta \phi = -4\pi G \rho$$

which *couples* to the momentum and energy equations¹.

¹ Schlottke-Lakemper et al.; JCP; 2021

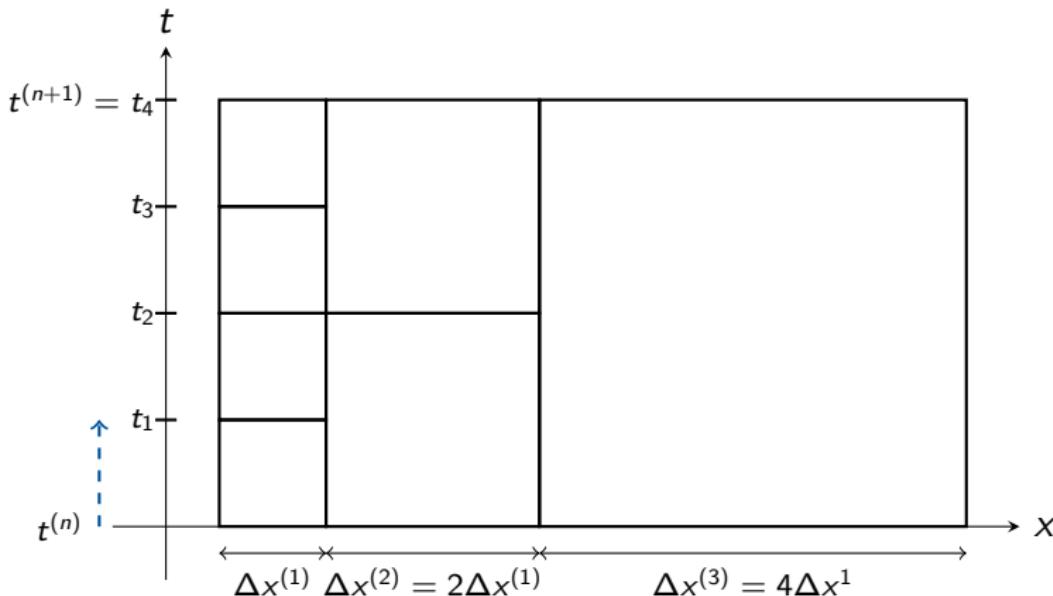
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



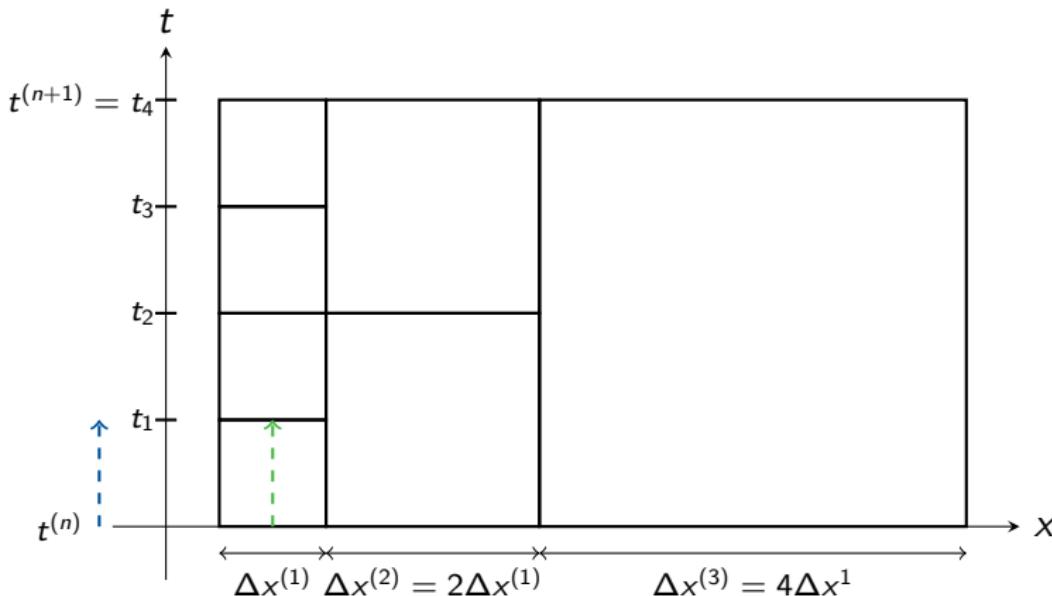
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



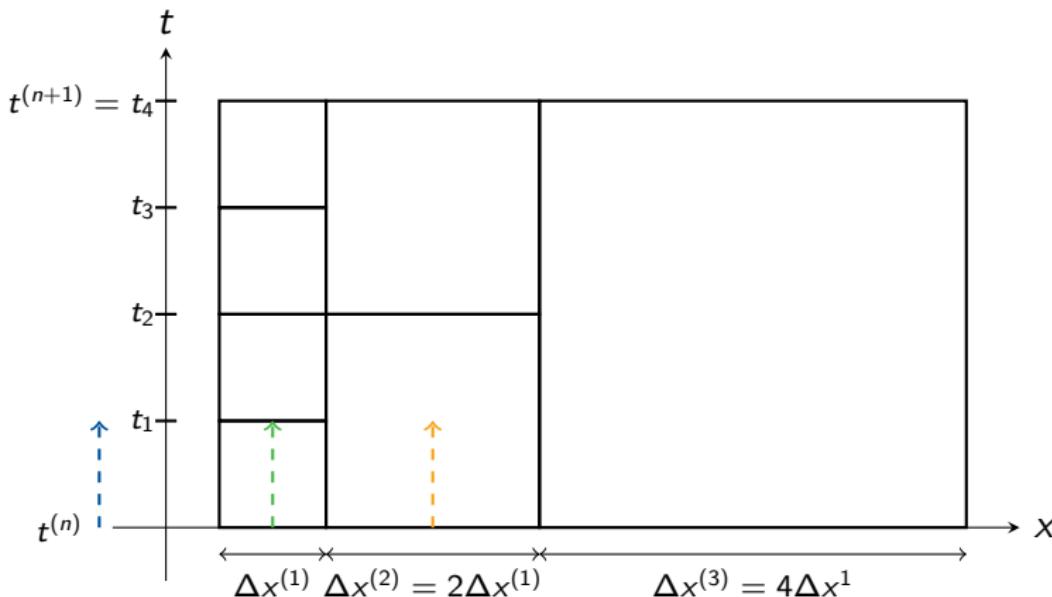
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



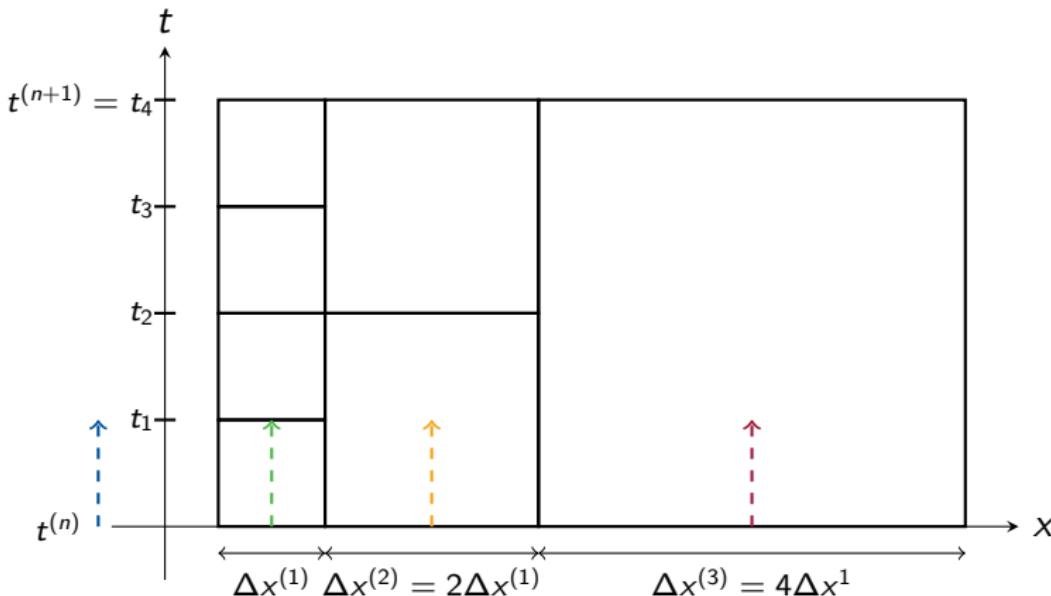
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



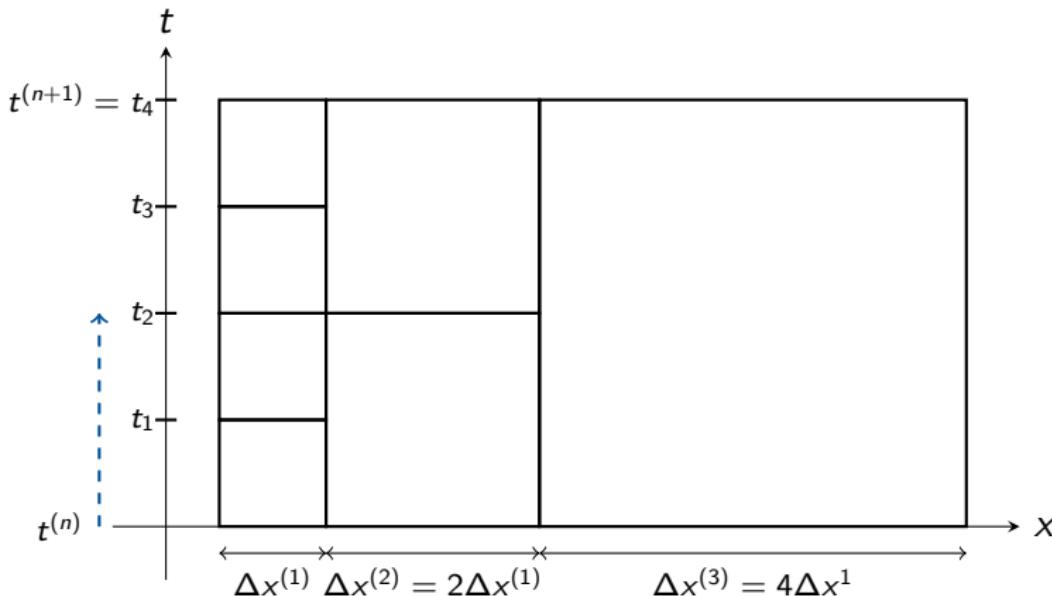
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



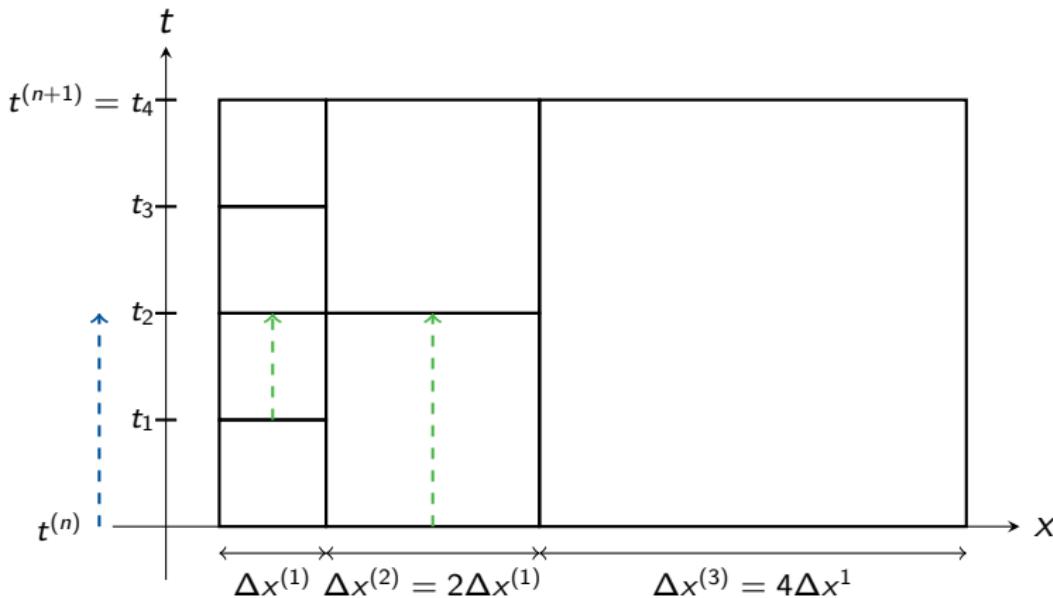
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



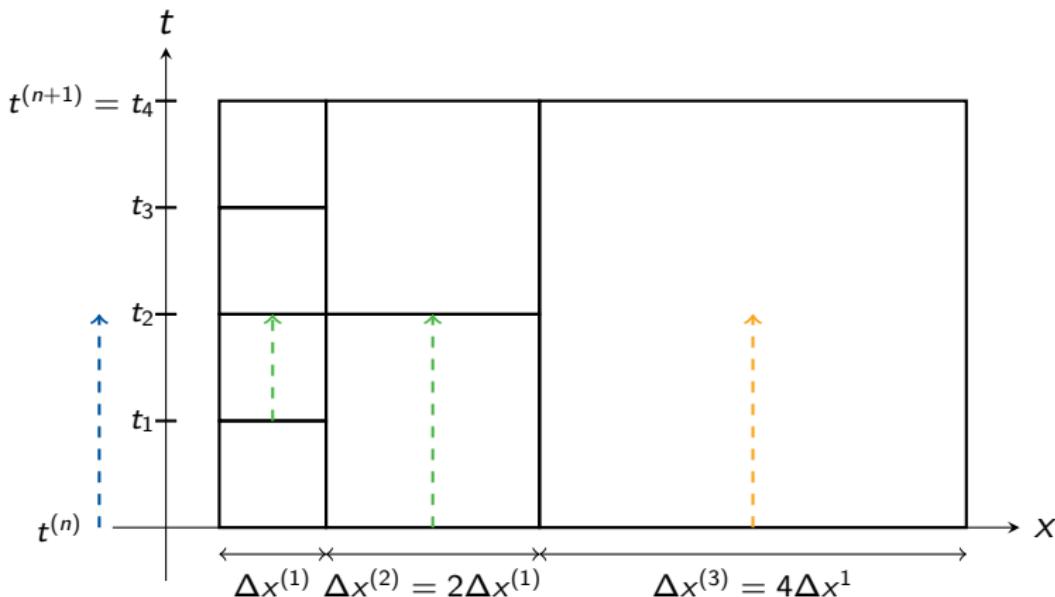
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



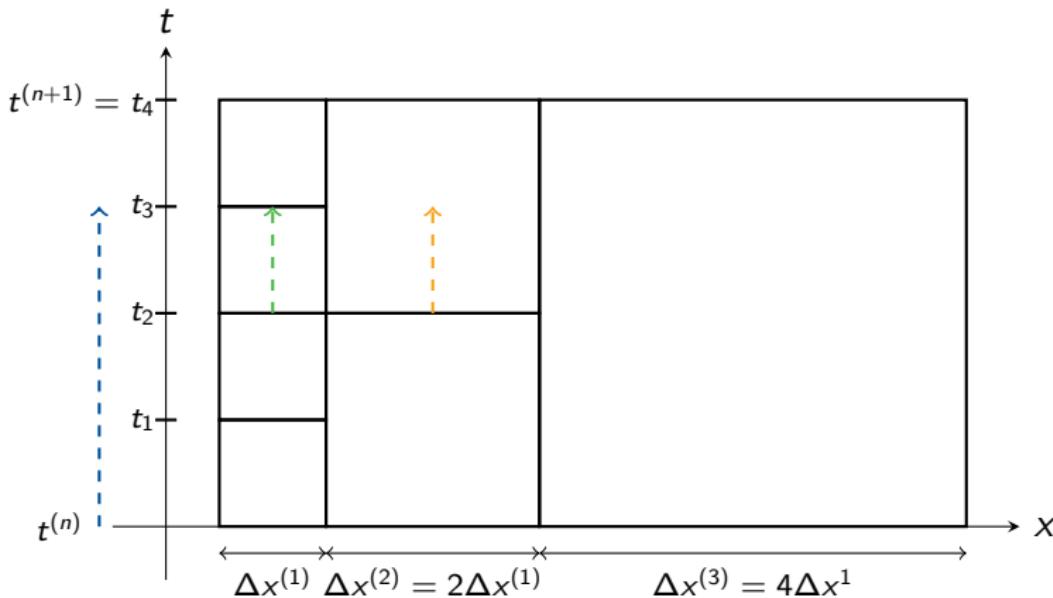
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



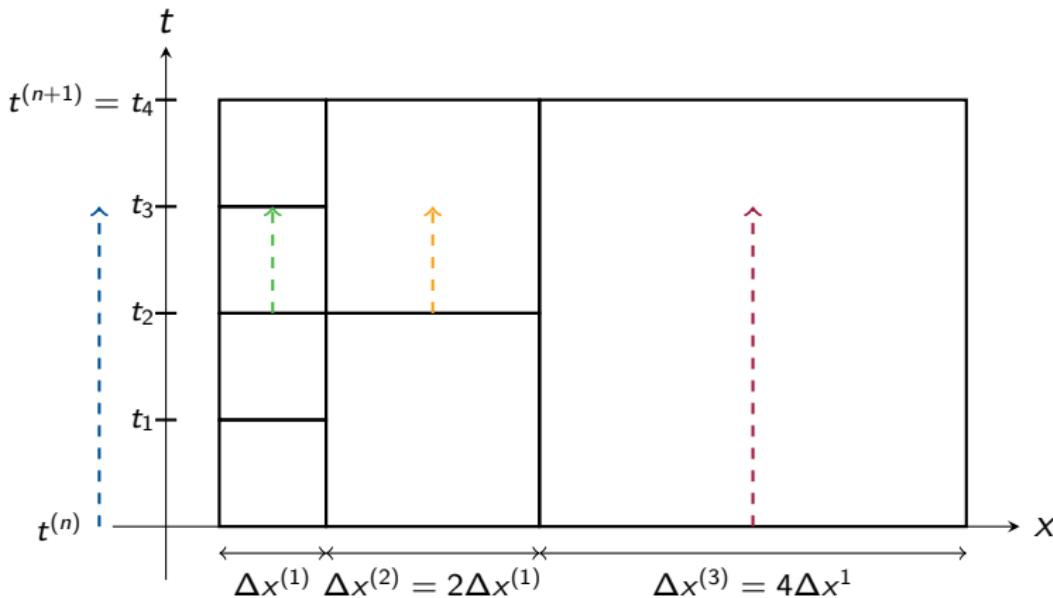
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



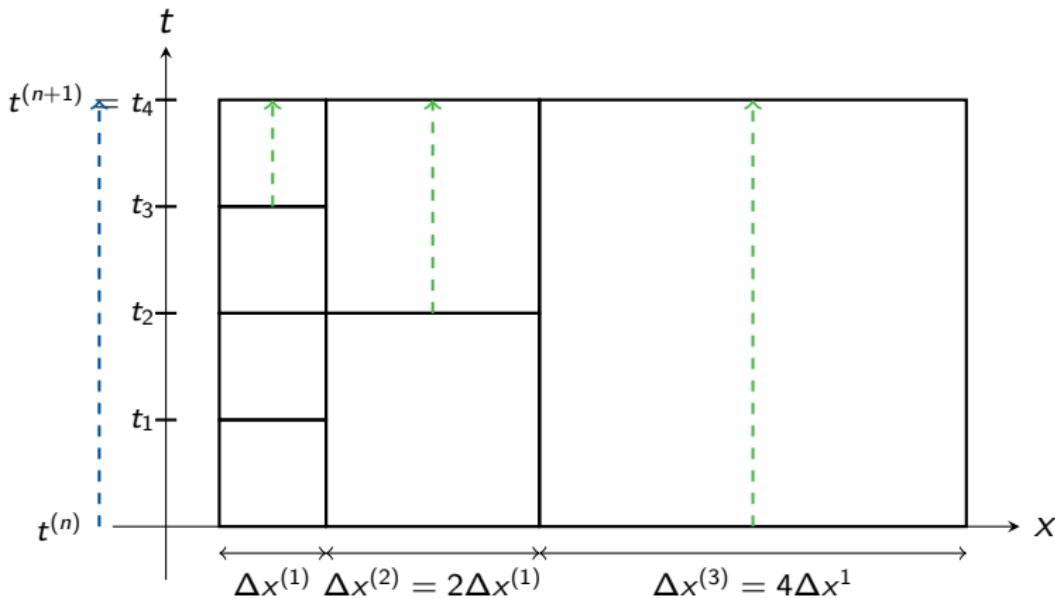
Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



Application: Euler-Gravity

- Hyperbolic – Elliptic coupling for Local Time-Stepping



Application: Euler-Gravity

Need to solve

$$-\Delta\phi = -4\pi G\rho$$

after every update to ρ .

Application: Euler-Gravity

Need to solve

$$-\Delta\phi = -4\pi G\rho$$

$$\rightsquigarrow \underbrace{\partial_\tau \begin{pmatrix} \phi \\ q_1 \\ q_2 \end{pmatrix} + \nabla \cdot \begin{pmatrix} -q_1 & -q_2 \\ -\phi/T_r & 0 \\ 0 & -\phi/T_r \end{pmatrix}}_{\text{Hyperbolic Diffusion Equations}} = \begin{pmatrix} -4\pi G\rho \\ -q_1/T_r \\ -q_2/T_r \end{pmatrix}, \quad \begin{aligned} \mathbf{q} &= \nabla\phi \\ T_r &= \text{const} \end{aligned}$$

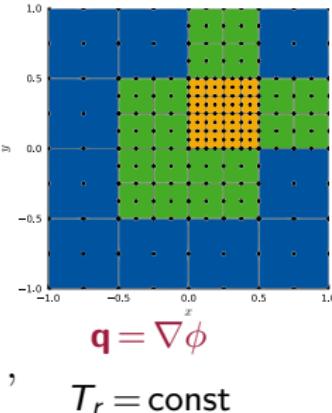
after every update to ρ .



Application: Euler-Gravity

Need to solve

$$-\Delta\phi = -4\pi G\rho$$



$$\rightsquigarrow \underbrace{\partial_\tau \begin{pmatrix} \phi \\ \mathbf{q}_1 \\ \mathbf{q}_2 \end{pmatrix} + \nabla \cdot \begin{pmatrix} -\mathbf{q}_1 & -\mathbf{q}_2 \\ -\phi/T_r & 0 \\ 0 & -\phi/T_r \end{pmatrix}}_{\text{Hyperbolic Diffusion Equations}} = \begin{pmatrix} -4\pi G\rho \\ -\mathbf{q}_1/T_r \\ -\mathbf{q}_2/T_r \end{pmatrix},$$

after every update to ρ .

- P-ERK schemes: Always at same time-level $t = t_n + c_i \Delta t$!

$$\mathbf{c} = \begin{matrix} c_1 \\ \vdots \\ c_S \end{matrix} \quad \left| \begin{array}{c|c|c} & A^{(1)} & A^{(2)} \\ & & A^{(3)} \end{array} \right| \quad \mathbf{b}^T$$

Application: Euler-Gravity

- Convergence Study

$$\rho = 2 + \frac{1}{10} \sin(\pi(x + y - t))$$

$$v_x = v_y = 1$$

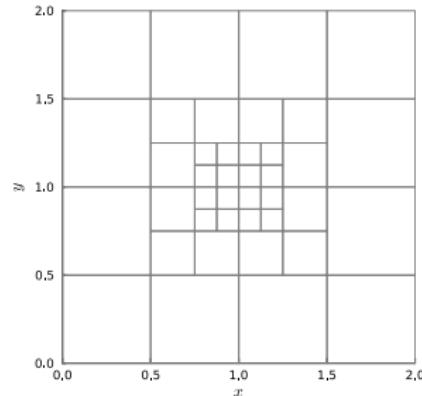
$$p = \frac{\rho^2}{\pi^2}$$

$$\phi = \frac{2}{\pi}(2 - \rho)$$

+ source terms (manufactured solution)

3-Level Grid

⇒ 3-Level methods for Euler & Hyp.-Diff.



Application: Euler-Gravity

- Convergence Study

3-Level Grid

⇒ 3-Level methods for Euler & Hyp.-Diff.

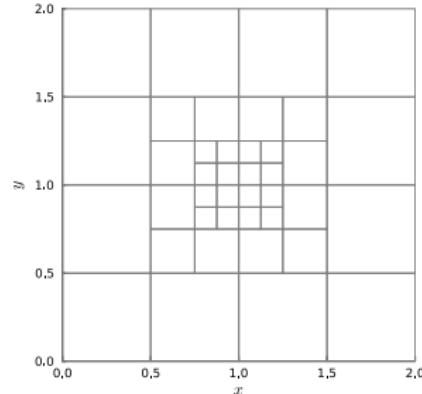
$$\rho = 2 + \frac{1}{10} \sin(\pi(x + y - t))$$

$$v_x = v_y = 1$$

$$p = \frac{\rho^2}{\pi^2}$$

$$\phi = \frac{2}{\pi}(2 - \rho)$$

+ source terms (manufactured solution)



N	$L^\infty(\rho)$	$L^\infty(v_{x,y})$	$L^\infty(p)$	$L^\infty(\phi)$	$L^\infty(q_{1,2})$
40	$2.5 \cdot 10^{-4}$	$5.2 \cdot 10^{-4}$	$3.0 \cdot 10^{-3}$	$1.5 \cdot 10^{-3}$	$3.8 \cdot 10^{-3}$
160	$1.4 \cdot 10^{-4}$	$4.4 \cdot 10^{-5}$	$1.6 \cdot 10^{-4}$	$7.4 \cdot 10^{-5}$	$2.8 \cdot 10^{-4}$
640	$6.6 \cdot 10^{-6}$	$3.0 \cdot 10^{-6}$	$1.0 \cdot 10^{-5}$	$7.8 \cdot 10^{-6}$	$3.2 \cdot 10^{-5}$
2560	$4.2 \cdot 10^{-7}$	$2.1 \cdot 10^{-7}$	$5.9 \cdot 10^{-7}$	$4.4 \cdot 10^{-6}$	$3.8 \cdot 10^{-6}$
Avg. EOC	4.2	3.75	4.1	2.8	3.3

Application: Euler-Gravity

- Convergence Study

$$\rho = 2 + \frac{1}{10} \sin(\pi(x + y - t))$$

$$v_x = v_y = 1$$

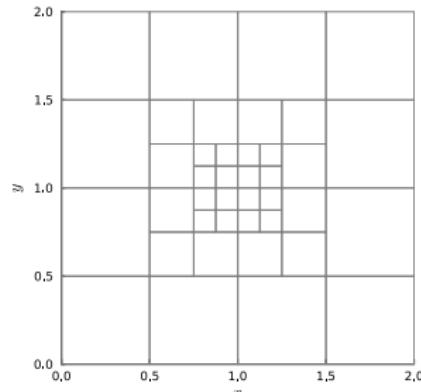
$$p = \frac{\rho^2}{\pi^2}$$

$$\phi = \frac{2}{\pi}(2 - \rho)$$

+ source terms (manufactured solution)

3-Level Grid

⇒ 3-Level methods for Euler & Hyp.-Diff.



N	$L^1(\rho)$	$L^1(v_{x,y})$	$L^1(p)$	$L^2(\phi)$	$L^2(q_{1,2})$
40	$2.8 \cdot 10^{-4}$	$7.8 \cdot 10^{-5}$	$3.5 \cdot 10^{-4}$	$4.4 \cdot 10^{-4}$	$7.1 \cdot 10^{-4}$
160	$1.5 \cdot 10^{-5}$	$5.6 \cdot 10^{-6}$	$1.9 \cdot 10^{-5}$	$1.4 \cdot 10^{-5}$	$5.0 \cdot 10^{-5}$
640	$7.3 \cdot 10^{-7}$	$3.2 \cdot 10^{-7}$	$9.2 \cdot 10^{-7}$	$3.2 \cdot 10^{-6}$	$3.6 \cdot 10^{-6}$
2560	$4.4 \cdot 10^{-8}$	$1.9 \cdot 10^{-8}$	$5.6 \cdot 10^{-8}$	$2.9 \cdot 10^{-6}$	$2.5 \cdot 10^{-7}$
Avg. EOC	4.2	4.0	4.2	2.4	3.8

Application: Euler-Gravity

Jeans Gravitational Instability¹

- Stable oscillation of a self-gravitating gas cloud
- Analytical expressions for pot., kin., int. energies

¹ Binney, Tremaine; Galactic Dynamics; 2011.

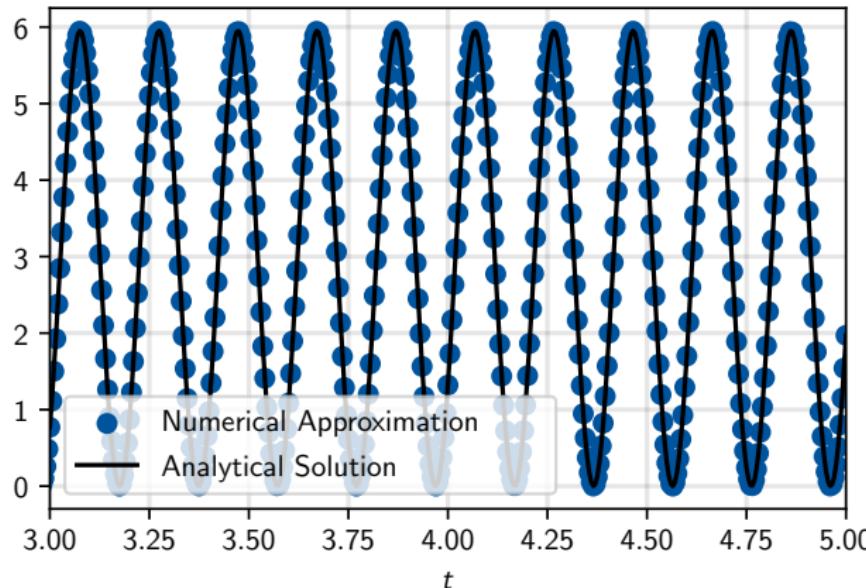


Application: Euler-Gravity

Jeans Gravitational Instability¹

- Stable oscillation of a self-gravitating gas cloud
- Analytical expressions for pot., kin., int. energies

Kinetic Energy



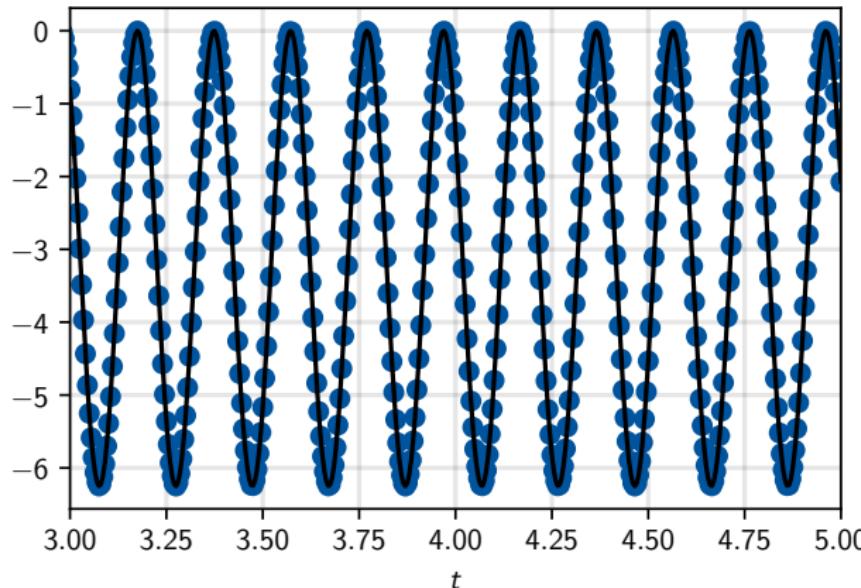
¹ Binney, Tremaine; Galactic Dynamics; 2011.

Application: Euler-Gravity

Jeans Gravitational Instability¹

- Stable oscillation of a self-gravitating gas cloud
- Analytical expressions for pot., kin., int. energies

Internal Energy



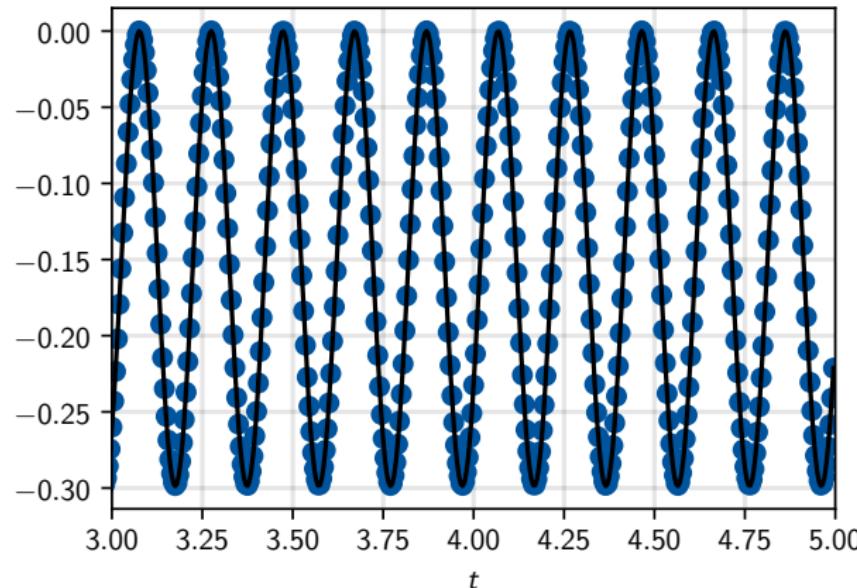
¹ Binney, Tremaine; Galactic Dynamics; 2011.

Application: Euler-Gravity

Jeans Gravitational Instability¹

- Stable oscillation of a self-gravitating gas cloud
- Analytical expressions for pot., kin., int. energies

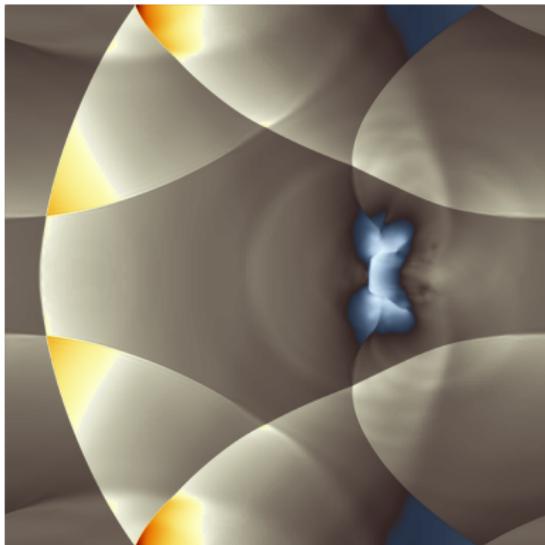
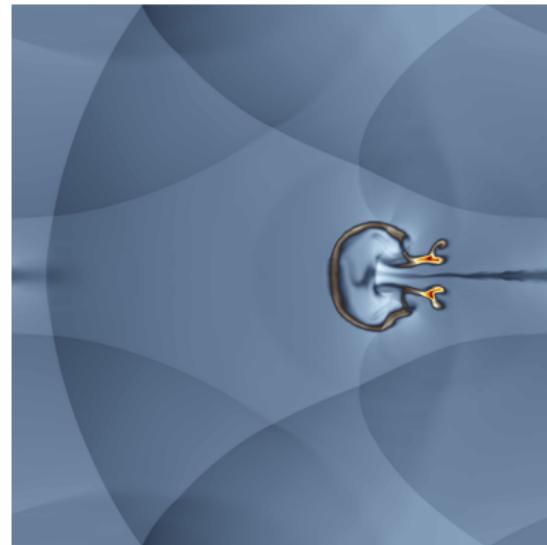
Potential Energy



¹ Binney, Tremaine; Galactic Dynamics; 2011.

Application: Euler-Gravity

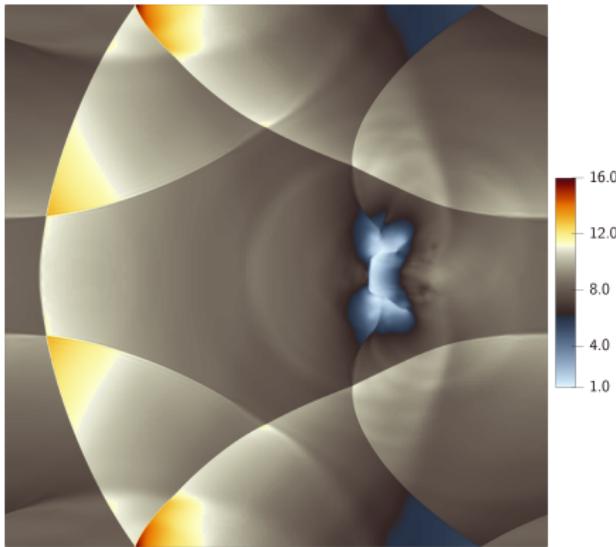
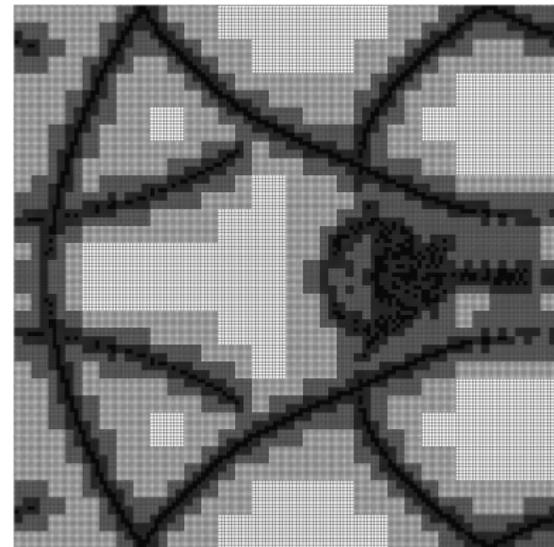
Blob Test¹ + Self-Gravity

Pressure p Density ρ

¹ Aretz et al.; Mon. Not. R. Astron. Soc; 2006.

Application: Euler-Gravity

Blob Test¹ + Self-Gravity

Pressure p 

Mesh

¹ Aretz et. al; Mon. Not. R. Astron. Soc; 2006.

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

- Ease of Implementation

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

- Ease of Implementation
- Optimality of Composing Schemes

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

- Ease of Implementation
- Optimality of Composing Schemes
- Reduced Operations for Hyperbolic-Elliptic Problems compared to Local Time-Stepping

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

- Ease of Implementation
- Optimality of Composing Schemes
- Reduced Operations for Hyperbolic-Elliptic Problems compared to Local Time-Stepping

Up next:

- Two-Fluid Euler-Poisson

Conclusion & Outlook

Advantages of Multirate RK Schemes for Multiphysics:

- Ease of Implementation
- Optimality of Composing Schemes
- Reduced Operations for Hyperbolic-Elliptic Problems compared to Local Time-Stepping

Up next:

- Two-Fluid Euler-Poisson
- Shallow-Water with non-hydrostatic Pressure

Thank You for your attention!

Questions?

- ✉ doehring@acom.rwth-aachen.de
- 🌐 <https://www.acom.rwth-aachen.de>
- ⌚ <https://github.com/DanielDoehring>

Application: Euler-Acoustic

Sound by rotating vortices

- Acoustic-Purturbation Equations (APE)



Application: Euler-Acoustic

Sound by rotating vortices

- Acoustic-Purturbation Equations (APE)
- with Lamb-vector source term from CEE



Application: Euler-Acoustic

Sound by rotating vortices

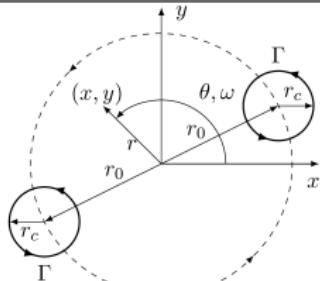
- Acoustic-Purturbation Equations (APE)
- with Lamb-vector source term from CEE
- Hybrid method: CAA + CFD



Application: Euler-Acoustic

Sound by rotating vortices

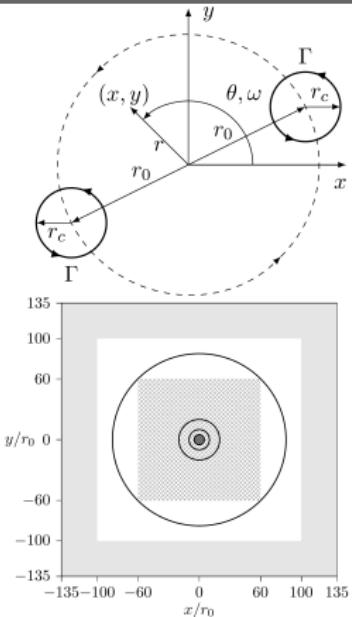
- Acoustic-Perturbation Equations (APE)
- with Lamb-vector source term from CEE
- Hybrid method: CAA + CFD



Application: Euler-Acoustic

Sound by rotating vortices

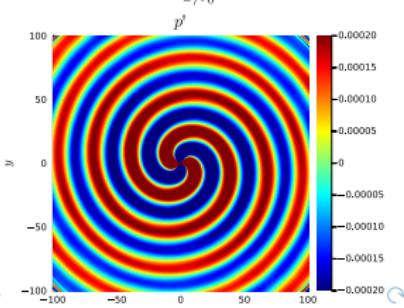
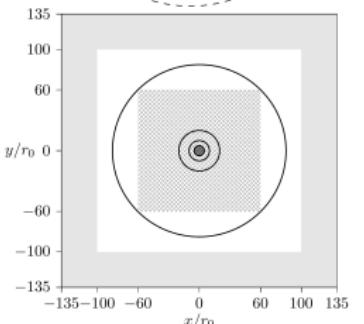
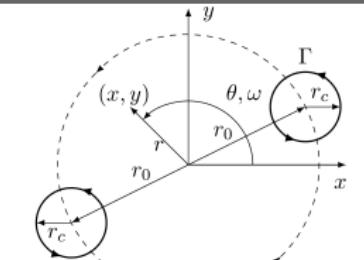
- Acoustic-Perturbation Equations (APE)
- with Lamb-vector source term from CEE
- Hybrid method: CAA + CFD



Application: Euler-Acoustic

Sound by rotating vortices

- Acoustic-Perturbation Equations (APE)
- with Lamb-vector source term from CEE
- Hybrid method: CAA + CFD



Application: Euler-Acoustic

Sound by rotating vortices

- Acoustic-Purturbation Equations (APE)
- with Lamb-vector source term from CEE
- Hybrid method: CAA + CFD

Method	τ/τ^*	$N_{\text{RHS}}/N_{\text{RHS}}^*$
P-ERK _{4;{5,6,8,13}} , P-ERK _{4;{5,6,9,14}}	1.0	1.0
P-ERK _{4;13} , P-ERK _{4;14}	1.82	2.08
NDB _{4;14}	2.28	2.71
TD _{4;8}	3.32	3.73
CFR _{4;6}	4.72	5.29
RK _{4;4}	6.13	5.45

