

Networks
Convolutional Laver

Machine Learning

Machine Learning

Lecture Machine Learning vom 24.3.2022

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Convolutional Neura Networks Convolutional Layer

Image classification problem

Given an image - say 64×64 pixels with 3 color channels - predict a probability distribution over predefined classes e.g. cat, dog, cow, plant, One can then assign the image to the most likely class.

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Networks

Convolutional Laver

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Related problems

- Object detection
- Image segmentation
- Videos (i.e. timeseries of images) as input

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Convolutional Neura

Convolutional Layer





input images



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Convolutional Neur

Convolutional Layer

Another feature to classify a dog

input images







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Convolutional Neu

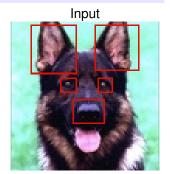
Convolutional Layer

High- and low-level filters

The detection of complex high level filters depends on low-level filters.







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Convolutional Neura Networks Convolutional Layer

Problems with Fully Connected Artificial Neural Nets (only ${\tt Dense}$ layers)

high number of parameters

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Convolutional Neura Networks Convolutional Layer

Problems with Fully Connected Artificial Neural Nets (only ${\tt Dense}$ layers)

- high number of parameters
- when images are input:

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Convolutional Neura Networks Convolutional Laver

Problems with Fully Connected Artificial Neural Nets (only Dense layers)

- high number of parameters
- when images are input:
 - · no notion of pixel neighborhoods
 - no translation invariance

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Convolutional Neura

Convolutional Layer

Idea of a CNN

ullet suppose we have K filters like in the previous slides

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Convolutional Neura Networks Convolutional Laver

Idea of a CNN

- suppose we have *K* filters like in the previous slides
- each filter can detect some feature somewhere in the image

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Convolutional Neura Networks Convolutional Laver

Idea of a CNN

- suppose we have *K* filters like in the previous slides
- each filter can detect some feature somewhere in the image
- stacked layers can start with simple features (low-level) that contribute to the detection of more complex features (high-level)

Machine Learning

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Convolutional Neura Networks Convolutional Laver

Idea of a CNN

- suppose we have *K* filters like in the previous slides
- each filter can detect some feature somewhere in the image
- stacked layers can start with simple features (low-level) that contribute to the detection of more complex features (high-level)
- prediction is based on the filters in the last layer

Cross-correlation (2-dimensional)

Definition 1

Let $A = (a_{ij})_{0 < i,j < m}$ be a square $m \times m$ -dimensional matrix and

$$B = (b_{ij})_{\substack{0 \le i < h \\ 0 < i < w}}$$

be another matrix of shape $h \times w$.

The $h - m + 1 \times w - m + 1$ -dimensional matrix C with entries

$$c_{i,j} := \sum_{i'=0}^{m-1} \sum_{i'=0}^{m-1} a_{i',j'} \cdot b_{i+i',j+j'}$$

is the 2-dimensional cross-correlation of A and B. We write C = A * B.

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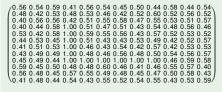
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Example 2

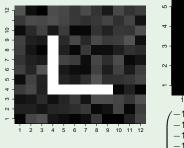
$$m = 2, h = 4, w = 5.$$

$$A = \begin{pmatrix} 1 & -1 \\ 2 & -3 \end{pmatrix} \qquad B = \begin{pmatrix} 2 & -3 & 0 & 2 & -1 \\ 0 & 1 & 4 & 0 & 1 \\ 2 & -2 & 7 & 3 & 0 \\ -1 & 0 & 1 & 0 & 4 \end{pmatrix} \qquad C = \begin{pmatrix} 2 & -13 & 6 & 0 \\ 9 & -28 & 9 & 5 \\ 2 & -12 & 6 & -9 \end{pmatrix}$$

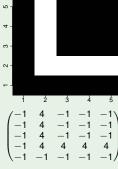
Cross-Correlation of an Image



"filter" A

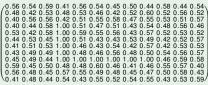


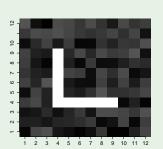
input image B



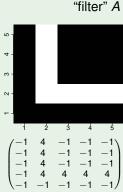
output image C = A * B

Cross-Correlation of an Image





input image B



(6.6 7.4 5.0 4.19 4.7 4.3 4.7 5.2) (6.2 7.9 8.8 4.56 5.3 5.4 4.6 6.2 5.2 5.9 9.2 3.27 4.6 5.2 3.8 6.6 4.7 5.2 12.1 2.57 4.6 5.0 4.0 5.5 4.4 4.1 11.0 0.85 2.0 3.7 3.1 5.1 7.7 9.3 19.3 11.13 11.9 10.8 8.4 7.2 2.7 2.7 9.6 3.9 4.4 5.7 5.4 6.7 3.7 3.1 7.9 4.14 4.8 5.2 5.3 6.0)

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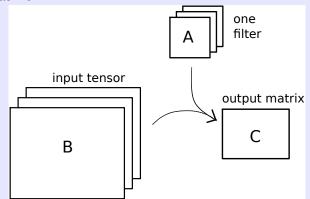


Convolutional Neural Networks

Convolutional Layer

3-dimensional input

- Want to
 - 1 use multiple filters in parallel and
 - 2 stack several (convolutional) layers.
- Also, color images are naturally encoded as 3-dimensional (each pixel has a red, green and blue value).
- Solution: Define convolution for 3-dimensional tensor input as well.



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Convolutional Neural Networks

Convolutional Layer

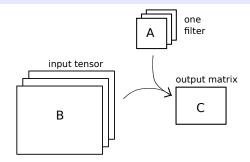
3-dimensional cross-correlation

Let
$$B = \begin{pmatrix} b_{ijk} \end{pmatrix}$$
 $0 \le i < h \atop 0 \le j < w \atop 0 \le k < d}$ be a tensor of shape $h \times w \times d$ and

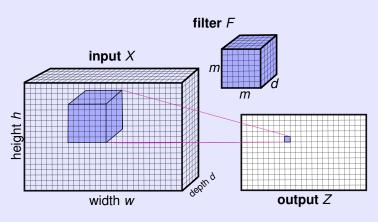
let
$$A = (a_{ijk})_{\substack{0 \le i, j < m \\ 0 \le k < d}}$$
 be another tensor ("filter").

The cross-correlation of A and B is then the $h-m+1 \times w-m+1$ -dimensional matrix C=A*B with entries

$$c_{i,j} := \sum_{i'=0}^{m-1} \sum_{i'=0}^{m-1} \sum_{k=0}^{d-1} a_{i',j',k} \cdot b_{i+i',j+j',k}.$$

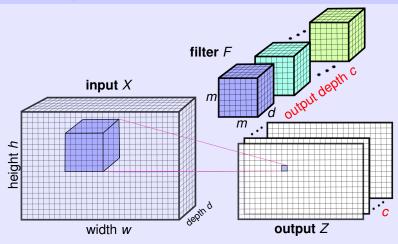


Deep Learning for Computer Vision



$$z_{i,j} = \sum_{i'=0}^{m-1} \sum_{j'=0}^{m-1} \sum_{k=0}^{d-1} x_{i+i',j+j',k} \cdot f_{i',j',k}$$

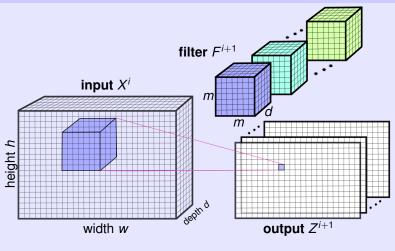
Deep Learning for Computer Vision



$$z_{i,j,r} = \sum_{i'=0}^{m-1} \sum_{j'=0}^{m-1} \sum_{k=0}^{d-1} x_{i+i',j+j',k} \cdot f_{i',j',k,r} + b_r$$
bias

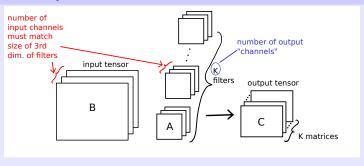
Deep Learning for Computer Vision

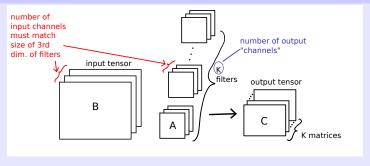
Convolutional Layer



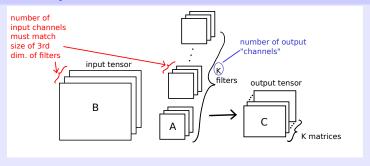
$$X^{i+1} = \max(Z^{i+1}, 0)$$

(Rectified Linear Unit)

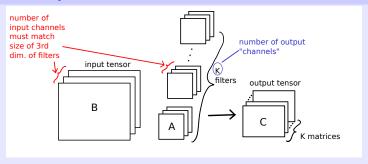




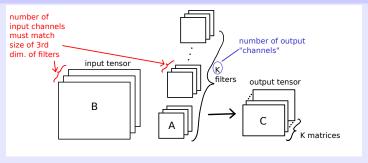
 The input width and height can be conserved in the ouput layer by zero-padding of input (padding = 'same')



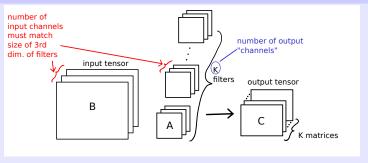
- The input width and height can be conserved in the ouput layer by zero-padding of input (padding = 'same')
- Stride (Schrittweite) s: Skip s-1 positions in each direction when 'sliding' A over $B \Rightarrow$ decreases output layer size up to a factor of s^2 .



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- Convolution is a special case of a fully-connected layer, in which certain parameters are shared (*parameter sharing*).



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- The matrices A are learned, not set manually. The derivative wrt. to the filter matrix parameters is computed during BackProp.
- Convolution is a special case of a fully-connected layer, in which certain parameters are shared (*parameter sharing*).
- Output neurons of convolution can detect lower-level features like ("lower left corner", "pupil") and be combined in deeper layers.

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Convolutional Neural Networks Convolutional Laver

Pooling-Layers

Max-Pooling (tf.keras.layers.MaxPool2D)

- similar to a convolutional layer
- requires a pool_size m like the filter size
- does not have any parameters
- computes output

$$Z_{i,j,r} = \max_{\substack{i' \in [0, m) \\ j' \in [0, m)}} X_{s \cdot i + i', s \cdot j + j', r}$$

- is usually applied with a stride s ≥ 2 and therefore reduces height and width
- often s = m, can have different strides for each dimension
- intuition:

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Convolutional Neural Networks

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With an analogous definition, average pooling averages over regions of size $m \times m$, but is used less often.

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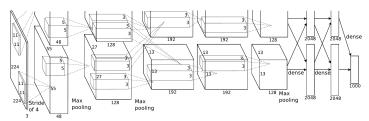
Convolutional Neural Networks

Convolutional Layer

Multi-Layered CNN example

Photo classification

- CNN from 2012 ("AlexNet")
- classification into 1000 categories



Alex Krizhevsky, Ilya Sutskever and Geoffrey Hinton, "ImageNet Classification with Deep Convolutional Neural Networks", NIPS, 201: