Image Processsing and Analysis Lecture 3, Image Enhancement in the Spatial Domain(I)

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Outline Background Intensity Transformation Functions Image Histogram Processing

Preview

- The principal objective of enhancement is to process an image so that the result is more suitable than the original image for a specific application
 - "Specific" means the techniques are very much problem oriented.
- Image enhancement approaches fall into two broad categories, spatial domain methods and frequency domain method.
 - spatial domain methods are based on direct manipulation of pixel in an
 - frequency domain techniques are based on modifying the Fourier transform of an image.
- There is no general theory of image enhancement.
 - When an image is processed for visual interpretation, the viewer is the ultimate judge of how well a particular method works, which makes it difficult to compare the performance of different methods.
 - For machine perception, the evaluation task is somewhat easier, e.g., character recognition task.

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Background

• A mathematical representation of spatial domain processing:

$$g(x,y) = T[f(x,y)],$$

where f(x, y): the input image

q(x, y): the processed image

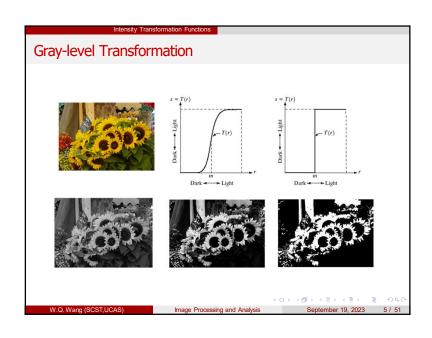
T: an operator on f, defined over some neighborhood of (x, y)

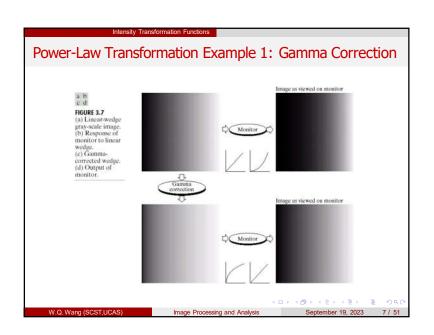
- T can operate on a set of images, e.g., noise reduction
- Square and rectangular neighborhood are by far the most popular due to their ease of implementation, although circle is also used.
- The simplest form of T is when the neighborhood is of size 1×1 . In this case, q depends only on the value of f at (x, y), i.e.,

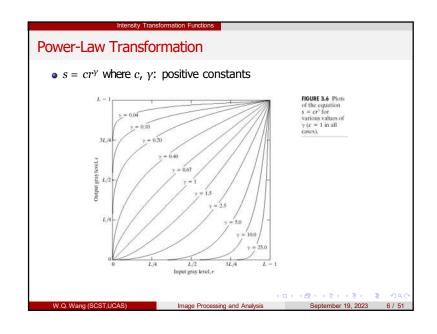
$$s = T(r)$$
,

that is called **Intensity Transformation**

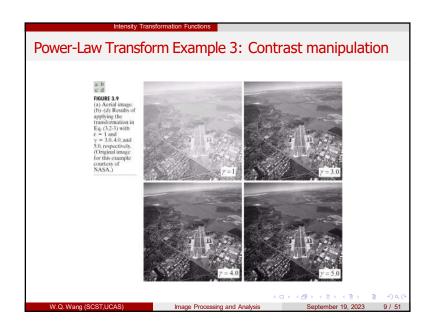
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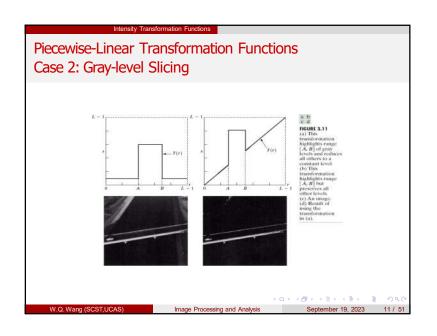


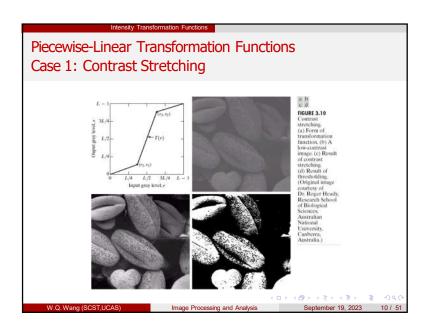


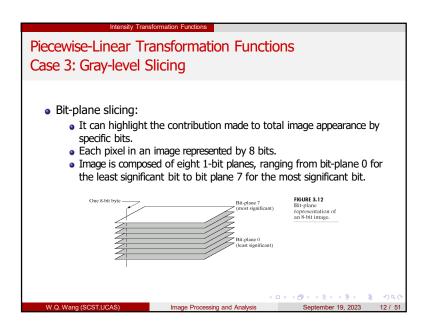


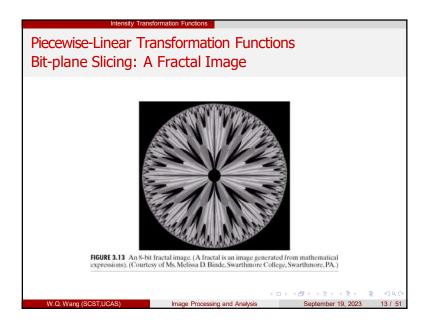




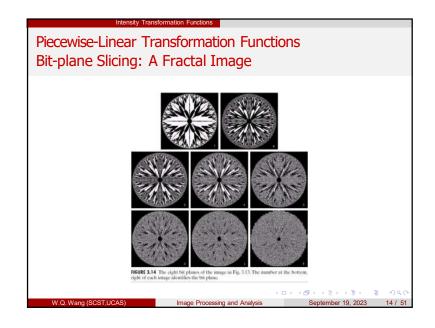


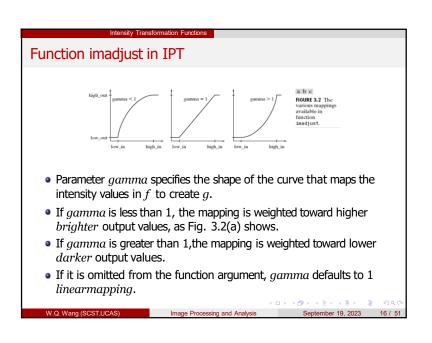


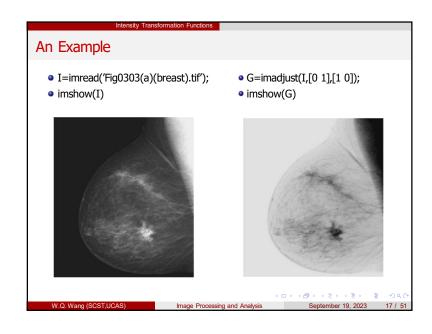


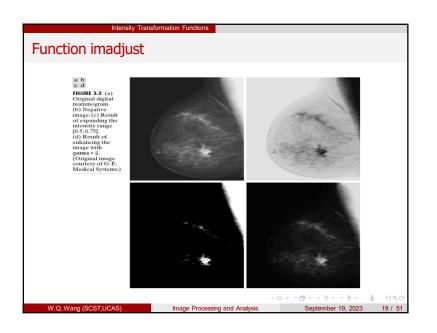


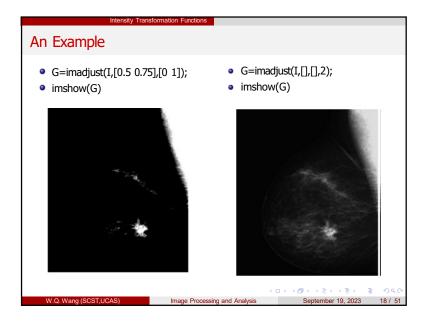
Function imadjust in IPT g = imadjust(f, [low in, high in], [low out, high out], gamma) This function maps the intensity values in image f to new values in g. Such that values between low_in and high_in map to values between low_out and high_out. Values below low_in and above high_in are clipped; that is, values below low_in map to low_out, and those above high_in map to high_out.

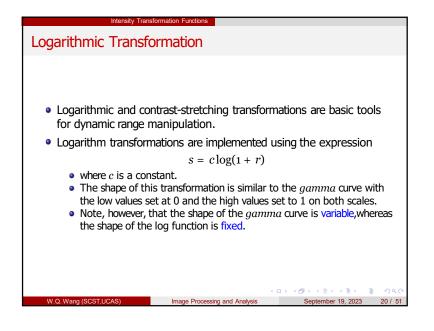












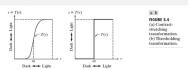
Logarithmic Transformation

- One of the principal uses of the log transformation is to compress dynamic range.
 - For example, it is not unusual to have a Fourier spectrum (Chapter 4) with values in the range [0,106] or higher. When displayed on a monitor that is scaled linearly to 8 bits, the high values dominate the display, resulting in lost visual detail for the lower intensity values in the spectrum. By computing the log, a dynamic range on the order of, for example, 10⁶ is reduced to approximately 14, which is much more manageable.
- When performing a logarithmic transformation, it is often desirable to bring the resulting compressed values back to the full range of the display. For 8 bits, the easiest way to do this in MATLAB is with the statement

qs = im2uint8(mat2gray(q));

• Use of *mat2gray* brings the values to the range [0, 1] and *im2uint8* brings them to the range [0, 255].

Contrast-Stretching Transformation



• A contrast-stretching transformation function can be defined as

$$s = T(r) = \frac{1}{1 + (m/r)^E}$$

- ullet it compresses the input levels lower than m into a narrow range of dark levels in the output image;
- \bullet similarly, it compresses the values above m into a narrow band of light levels in the output;
- where r represents the intensities of the input image, s the corresponding intensity values in the output image, and E controls the slope of the function.
- This equation is implemented in MATLAB for an entire image as

$$g = 1./(1 + (m./(double(f) + eps)).^E)$$

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Logarithmic Transformation • Figure 3.5(a) is a Fourier spectrum with values in the range 0 to displayed on a linearly scaled, 8-bit system. Figure 3.5(b) shows the result obtained using the commands >> g = im2uint8(mat2gray(log(1 + double(f)))); >> imshow(q) a b FIGURE 3.5 spectrum. (b) Result of applying the log transformation given in Eq. (3.2-2) with

Histogram Processing

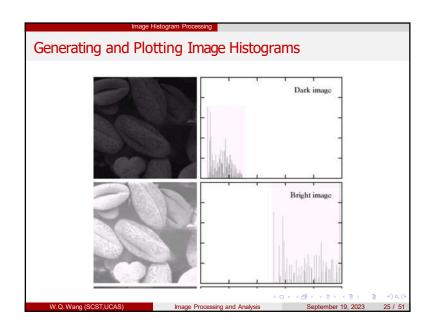
• Intensity transformation are based on information extracted from image intensity histograms, and histogram plays a basic role in image processing, in areas such as enhancement, compression, segmentation, and description.

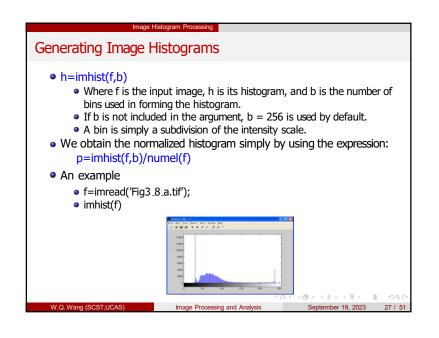
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• The histogram of a digital image with L total possible intensity levels in the range [0,G] is defined as the discrete function

$$h(r_k) = n_k$$

• where r_k is the kth intensity level in the interval [0, G] and n_k is the number of pixels in the image whose intensity level is r_k . The value of G is 255 for images of class uint8, 65535 for images of class uint16, and 1.0 for images of class double.





Normalized Histogram

• Through dividing all elements of $h(r_k)$ by the total number of pixels in the image, a normalized histogram can be obtained, i.e.,

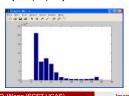
$$p(r_k) = \frac{h(r_k)}{N} = \frac{n_k}{N}, N = \sum_{k=1}^{L} n_k, k = 1, 2, ..., L$$

• From basic probability, we know $p(r_k)$ can be considered as an estimate of the probability of occurrence of intensity level r_k .

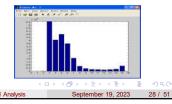
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Plotting Image Histograms

- Histograms often are plotted using bar graphs. For this purpose we can use the function bar(horz, v, width)
 - Where v is a row vector containing the points to be plotted.
 - horz is a vector of the same dimension as v that contains the increments of the horizontal scale. If horz is omitted, the horizontal axis is divided in units from 0 to length(v).
 - width is a number between 0 and 1.
- s=imread('Fig0303(a)(breast).tif');
- h1=imhist(s,16);
- horz=1:16:
- bar(horz,h1,0.8)



- axis([0 16 0 65000]);
- set(gca,'xtick',0:1:16);
- set(gca,'ytick',0:4000:65000);



Plotting Image Histograms using stem

- A stem graph is similar to a bar graph. The syntax is stem(horz, v, 'color linestyle marker', 'fill')
 - where v is row vector containing the points to be plotted, and horz is as described for bar.
 - color_linestyle marker is a triplet of values from Table below.

Symbol	Color	Symbol	Line Style	Symbol	Marker
k	Black	_	Solid	+	Plus sign
W	White		Dashed	0	Circle
r	Red	:	Dotted	*	Asterisk
g	Green		Dash-dot		Point
b	Blue	none	No line	х	Cross
C	Cyan			s	Square
у	Yellow			d	Diamond
m	Magenta			none	No marker

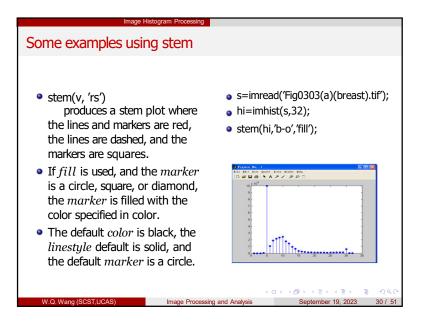
TABLE 3.1 Attributes for functions stem and plot. The none attribute is applicable only to function plot, and must be specified individually. See the syntax for function plot below.

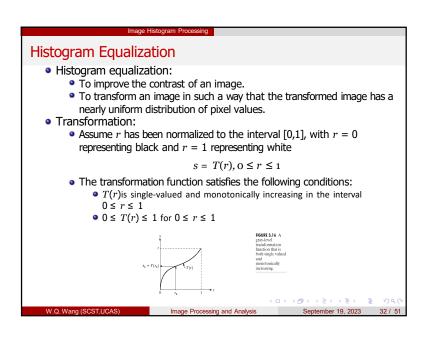
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Plotting Image Histograms using plot s=imread('Fig0303(a)(breast).tif'); Function plot plots a set of points by linking them with hi=imhist(s,32); straight lines. The syntax is plot(hi); plot(horz, v, 'color_linestyle_marker') Bit for Deet Data Year Dec • where the arguments are as defined previously for stem plots. • Function *plot* is used frequently to display transformation functions. 4□ ト 4 億 ト 4 億 ト 4 億 ト 9 頁 9 9 (





Histogram Equalization

- Histogram equalization is based on a transformation of the probability density function of a random variable.
- Let $p_r(r)$ and $p_s(s)$ denote the probability density function of random variable r and s, respectively.
- ullet If $p_r(r)$ and T(r) are known, then the probability density function $p_s(s)$ of the transformed variable s can be obtained

$$p_s(s) = p_r(r) \left| \frac{dr}{ds} \right|$$

Define a transformation function

$$s = T(r) = \int_0^r p_r(w) dw$$

ullet where w is a dummy variable of integration and the right side of this equation is the cumulative distribution function of random variable r.

Histogram Equalization

- In discrete version:
 - The probability of occurrence of gray level r_k in an image is

$$p_r(r_k) = \frac{n_k}{N}, k = 1, 2, ..., L$$

The transformation function is

$$s = T(r_k) = \sum_{j=0}^{k} p_r(r_j) = \sum_{j=0}^{k} \frac{n_j}{N}$$

ullet Thus, an output image is obtained by mapping each pixel with level r_k in the input image into a corresponding pixel with level s_k .

Histogram Equalization

• Given transformation function T(r)

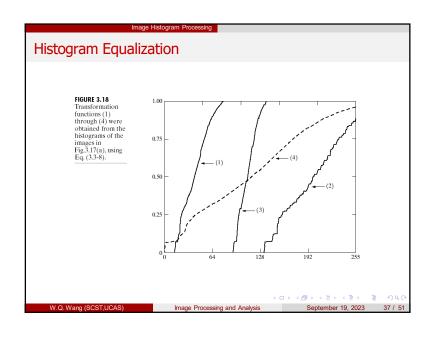
$$s = T(r) = \int_0^r p_r(w)dw$$
$$\frac{ds}{dr} = \frac{dT(r)}{dr} = \frac{d\left[\int_0^r p_r(w)dw\right]}{dr} = p_r(r)$$

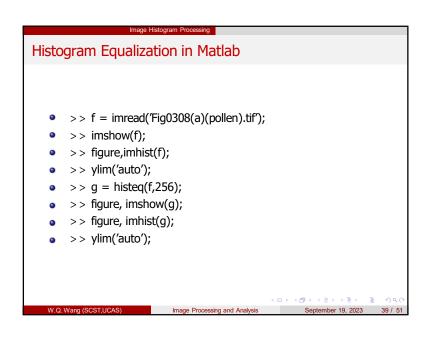
$$p_s(s) = p_r(r) \left| \frac{dr}{ds} \right| = p_r(r) \frac{1}{p_r(r)} = 1, 0 \le s \le 1$$

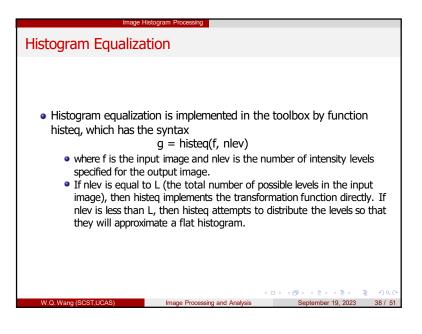
- $p_s(s)$ now is a uniform probability density function.
- T(r) depends on $p_r(r)$, but the resulting $p_s(s)$ always is uniform.

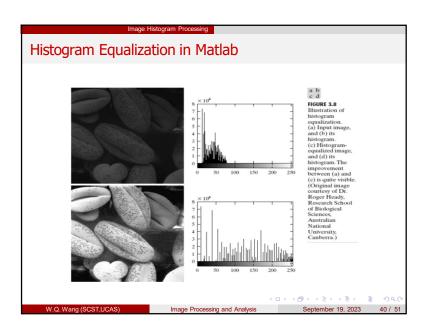
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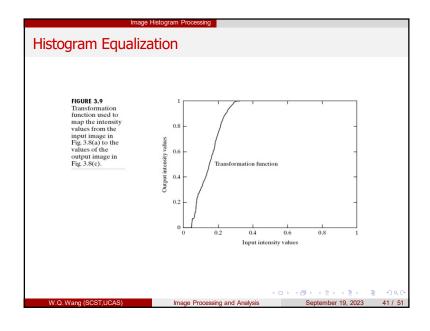
Histogram Equalization











Histogram Matching

• We know from the discussion in the previous section that the transformation:

$$s = T(r) = \int_0^r p_r(w) dw$$

result in a ideal equalized histogram $p_s(s)$.

Suppose now we define a variable z with the property

$$H(z) = \int_0^z p_z(w) dw = s$$

• From the preceding two equations, it follows that

$$z = H^{-1}(s) = H^{-1}(T(r));$$

• We can find T(r) from the input image (this is the histogram equalization transformation discussed in the previous section), so it follows that we can use the preceding equation to find the transformed levels z whose PDF is the specified $p_z(z)$ as long as we can find H^{-1} .

Histogram Matching

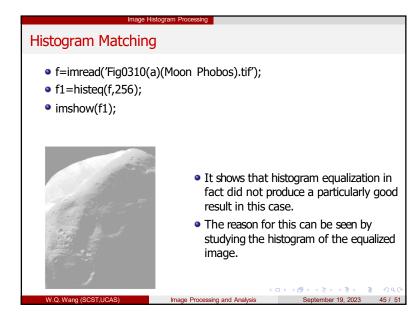
- Histogram matching is similar to histogram equalization, except that instead of trying to make the output image have a flat histogram, we would like it to have a histogram of a specified shape.
- Consider for a moment continuous levels that are normalized to the interval [0, 1], and let r and z denote the intensity levels of the input and output images. The input levels have probability density function $p_r(r)$ and the output levels have the specified probability density function $p_z(z)$.

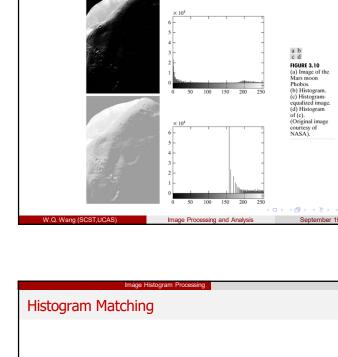
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Histogram Matching

- The toolbox implements histogram matching using the following syntax in histeq:
 - q = histeq(f, hspec)
 - where f is the input image, hspec is the specified histogram (a row vector of specified values), and g is the output image, whose histogram approximates the specified histogram, hspec.
- This vector should contain integer counts corresponding to equally spaced bins. A property of histeg is that the histogram of g generally better matches hspec when length (hspec) is much smaller than the number of intensity levels in f.

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Histogram Matching

- One possibility for remedying this situation is to use histogram matching, with the desired histogram having a lesser concentration of components in the low end of the gray scale, and maintaining the general shape of the histogram of the original image.
- We note that the histogram of original image is basically bimodal, with one large mode at the origin, and another, smaller, mode at the high end of the gray scale. These types of histograms can be modeled, for example, by using multimodal Gaussian functions.

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- The following M-function computes a bimodal Gaussian function normalized to unit area, so it can be used as a specified histogram.
 - Function twomodegauss:

Histogram Matching

$$p(x) = k + \frac{A_1}{\sqrt{2\pi}\sigma_1} \exp\left(-\frac{(x - m_1)^2}{2\sigma_1^2}\right) + \frac{A_2}{\sqrt{2\pi}\sigma_2} \exp\left(-\frac{(x - m_2)^2}{2\sigma_2^2}\right)$$

- The following interactive function accepts inputs from a keyboard and plots the resulting Gaussian function. Refer to Section 2.10.5 for an explanation of the functions input and str2num. Note how the limits of the plots are set.
 - Function manualhist

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