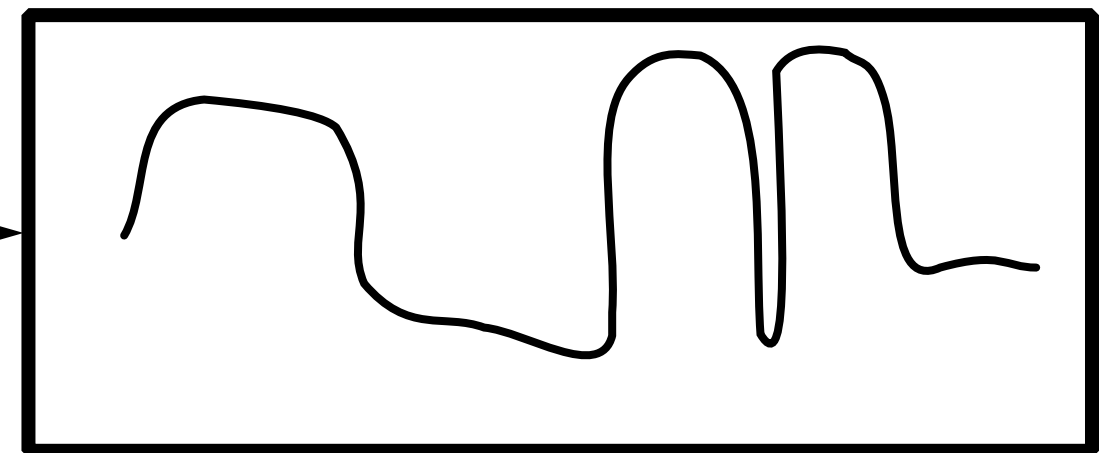


Control Input  $u$



System



Output  $y$