

# LLC Resonant Half Bridge Converter

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Hong Huang  
Applications Engineer

# Outline

- Introduction to LLC resonant half bridge converter
  - Benefits
  - Operation principle
  - Design challenges
- Design method
  - Transformer turns ratio selection
  - Magnetizing inductor selection
  - Resonant component selection
- Other design issues for LLC resonant converter
  - Current limiting
  - Soft start
  - OVP and Burst Operation

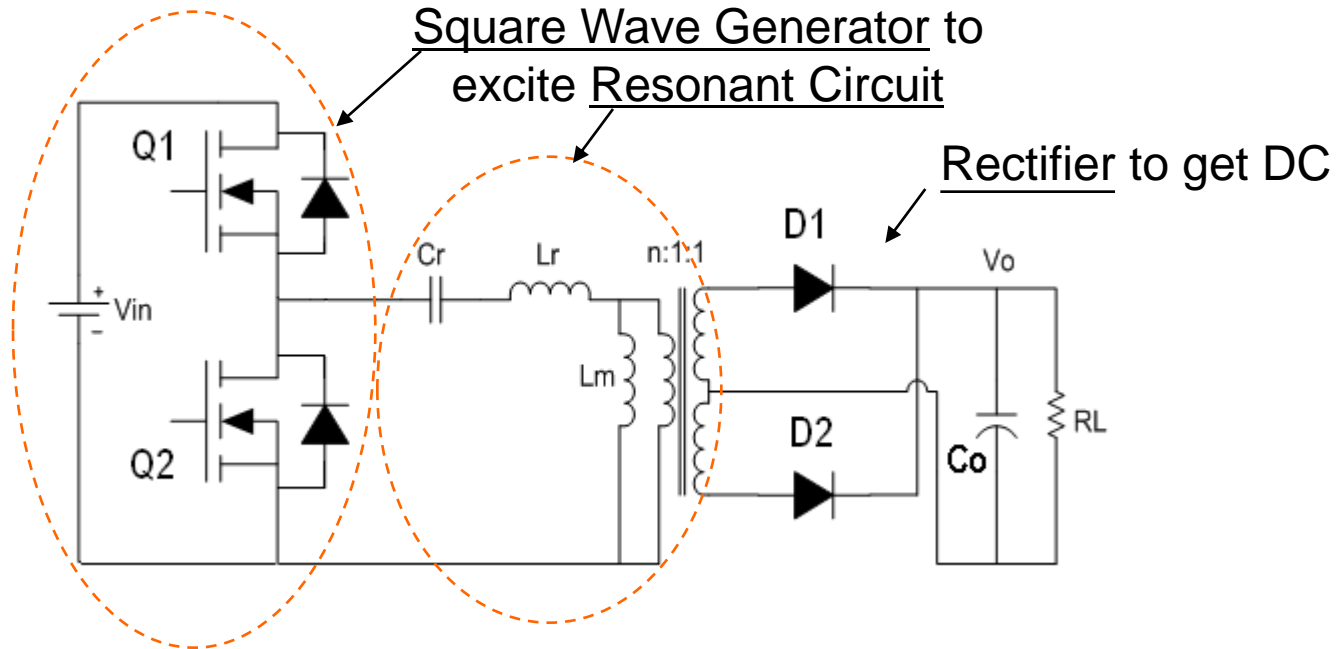
# Design Challenges for DC/DC

- Higher power conversion performance
  - Higher efficiency, smaller heat sink
  - Higher switching frequency, smaller magnetics
  - Less energy storage capacitors, smaller size (e.g., for PFC holdup)
  - Moderate frequency variations
- Wide input voltage variations
  - AC-DC applications: holdup time requirement (PFC from 400V to 300V during holdup)
    - Larger Energy Storage Capacitor – high cost, large size, more space
    - Converter ability to tolerate the variations
  - DC-DC applications
    - Telecom, 36 to 75V (32V to 78V)
    - Some applications even asking 4:1 variations
- Wide output voltage trimming

# Benefits of LLC Resonant Converter

- ZVS can be achieved by utilizing transformer magnetizing inductor
- Capacitor filter, less voltage stress on rectifiers
- Smaller switching loss due to small turn off current
- Variable switching frequency control, not sensitive to load change
- Frequency variations can be designed narrower compared to SRC
- Wide operation range without reducing normal operation efficiency

# LLC Resonant Converter with Wide Operation Range



Resonant  
frequency

$$f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$$

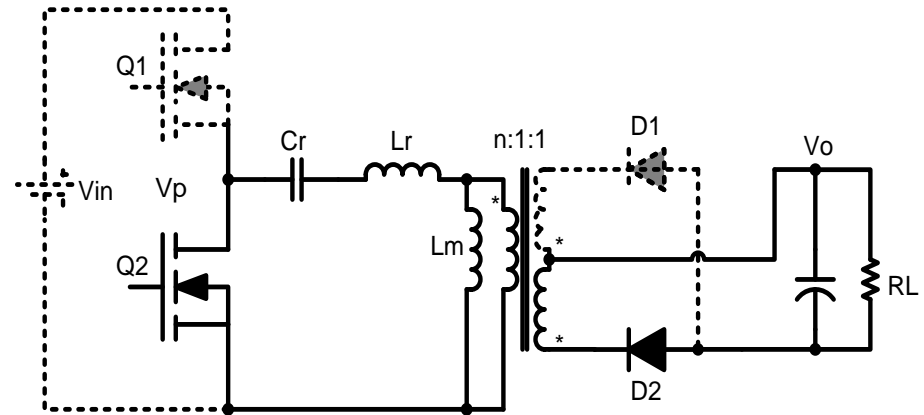
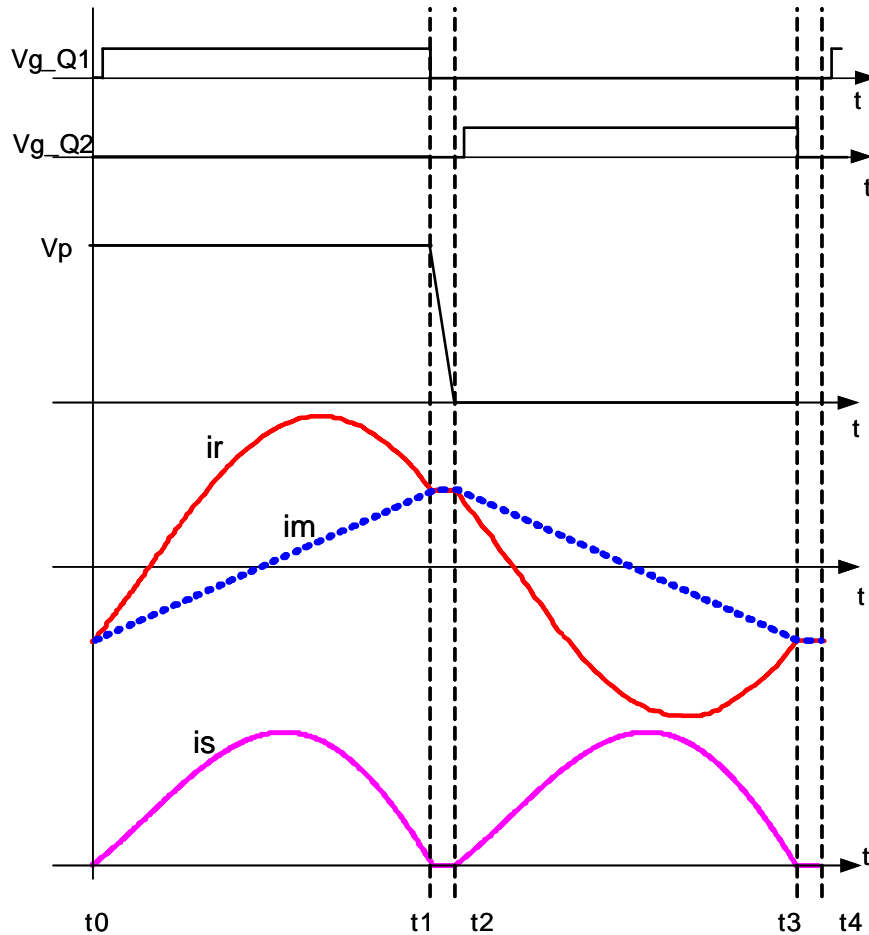
Transformer  
turns-ratio

$$n = \frac{V_{in}/2}{V_o}$$

- $f_{sw}$  is set at resonant frequency at nominal input and output
- $f_{sw}$  is adjusted by feedback loop at other operation conditions

# Operation Principles

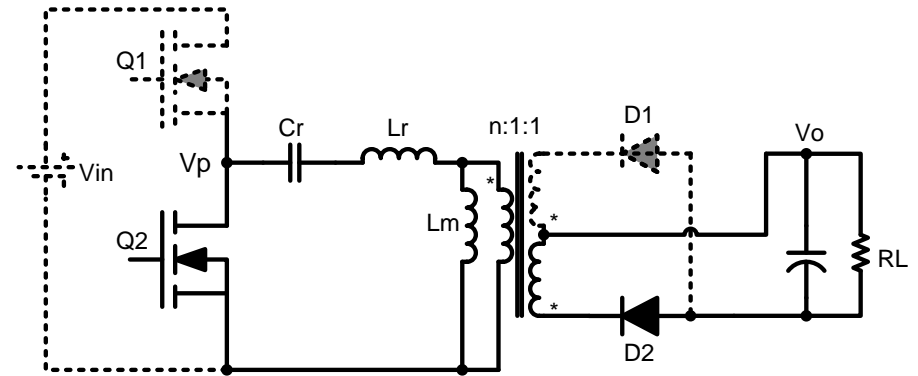
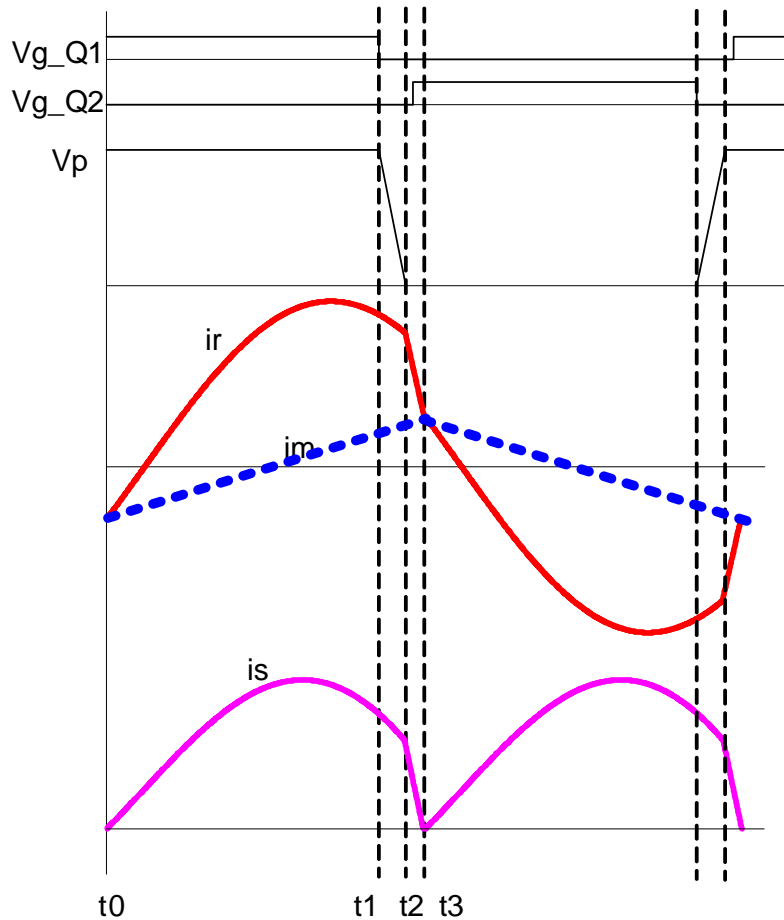
## *At Resonant Frequency*



- $Q2$  and  $D2$  ON,  $Q1$  and  $D1$  OFF
- Magnetizing current in  $L_m$ ,  $i_m$
- $C_r$  resonates with  $L_r$ ,  $i_r$
- $C_r$  and  $L_r$  deliver energy to output

# Operation Principle

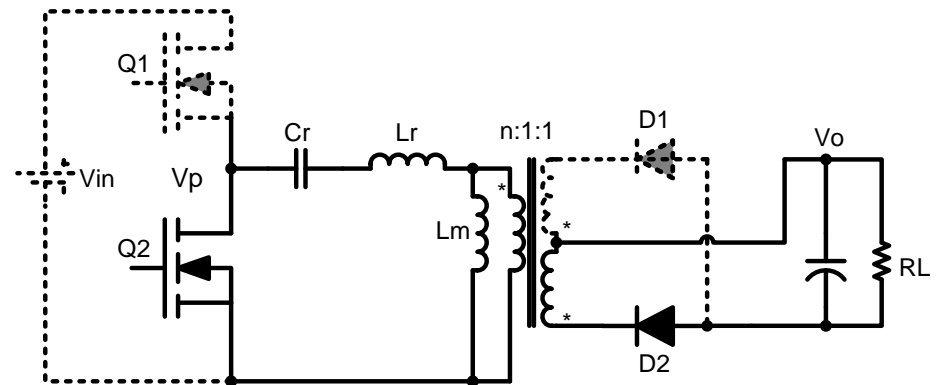
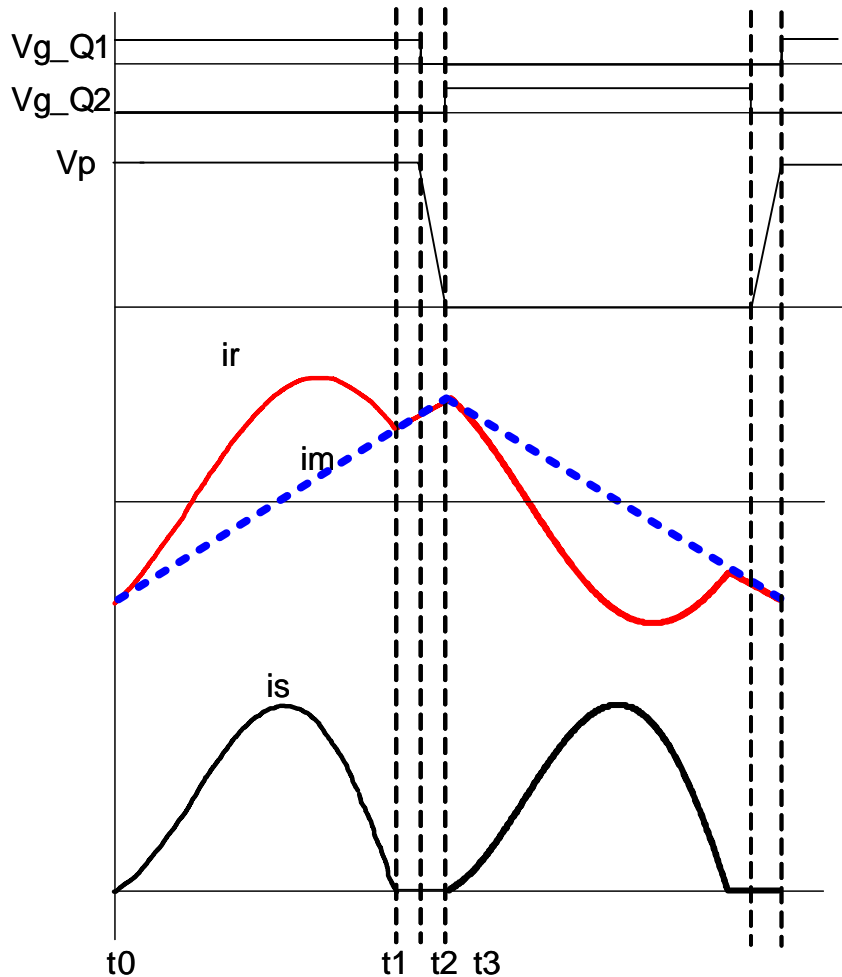
## *Above Resonant Frequency*



- When switching frequency is above resonant frequency, circuit behaves as SRC
- Secondary current becomes CCM, reverse recovery loss increases

# Operation Principle

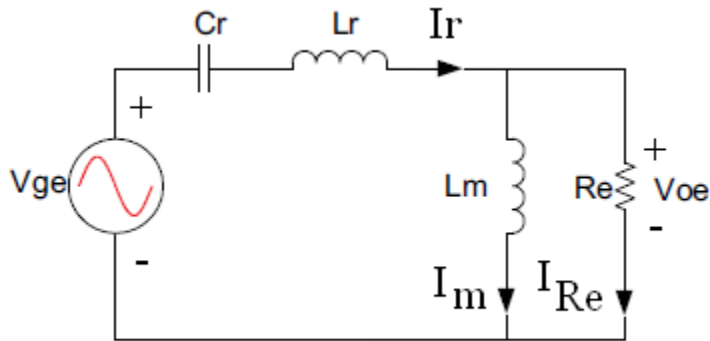
## *Below Resonant Frequency*



- When switching frequency is below resonant frequency, magnetizing inductor begins to participate in resonant and increases voltage gain
- Secondary diode becomes discontinuous



# LLC Resonant Converter Gain Function



$$M = \frac{nV_o}{V_{DC}/2} \approx \frac{V_{oe}}{V_{ge}} = \left| \frac{\frac{j\omega L_m R_e}{j\omega L_m + R_e}}{\frac{j\omega L_m R_e}{j\omega L_m + R_e} + \frac{1}{j\omega C_r} + j\omega L_r} \right|$$

$$V_{oe} = V_{os,1}^{rms} = \frac{2\sqrt{2}}{\pi} nV_o \quad R_e = \frac{8}{\pi^2} n^2 R_L$$

$$I_{Re} = I_{os,1}^{rms} = \left( \frac{\pi}{2\sqrt{2}} I_o \right) / n$$

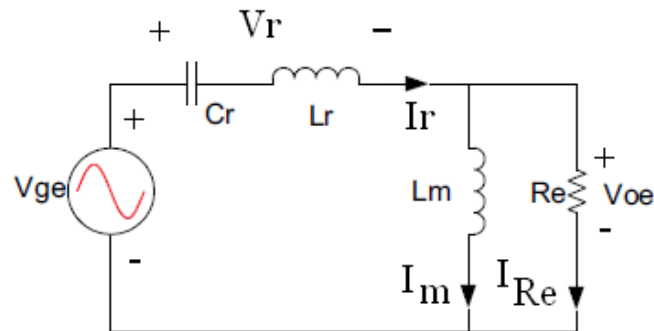
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$$M = \left| \frac{L_n f_n^2}{L_n f_n^2 + (f_n^2 - 1)(1 + jf_n L_n Q_e)} \right|$$

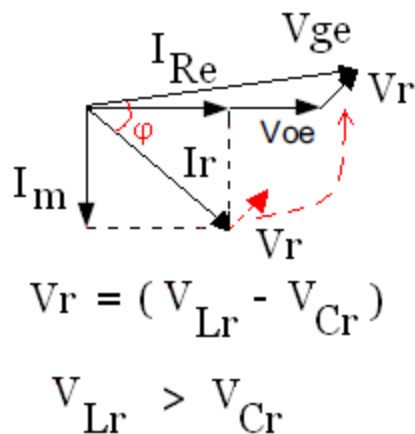
NORMALIZED GAIN	RESONANT FREQUENCY	QUALITY FACTOR	NORMALIZED FREQUENCY	INDUCTOR RATIO
$M = \frac{V_o}{V_{DC}/2}$	$f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$	$Q_e = \frac{\sqrt{L_r/C_r}}{R_e}$	$f_n = \frac{f}{f_0}$	$L_n = \frac{L_m}{L_r}$

# LLC Resonant Converter with Wide Operation Range

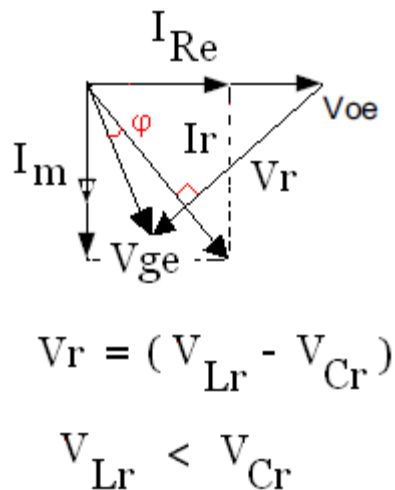
- Unity gain is reached at  $V_r = (V_{Lr} - V_{Cr}) = 0$ , where input voltage is in phase with output voltage, and input voltage applies to load ( $R_e$ ) directly



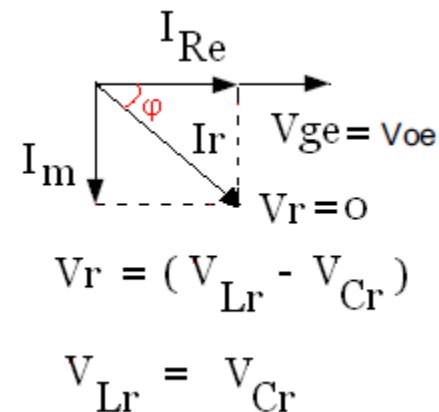
Inductive Region,  
 $I_r$  lagging  $V_{ge}$



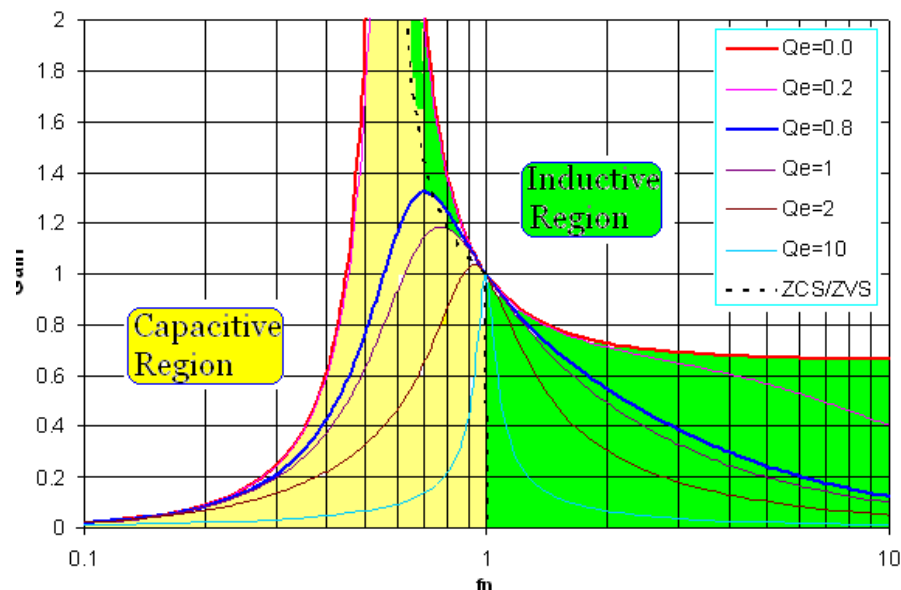
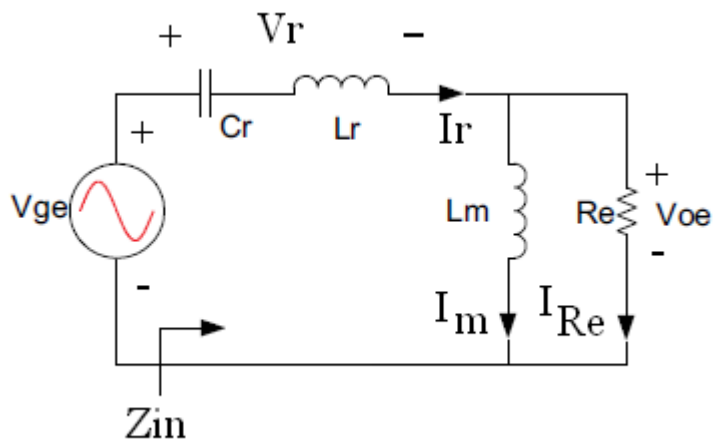
Capacitive Region,  
 $I_r$  leading  $V_{ge}$



Unity Gain,  $V_r = 0$   
 $V_{oe}$  in phase with  $V_{ge}$



# LLC Resonant Converter with Wide Operation Range

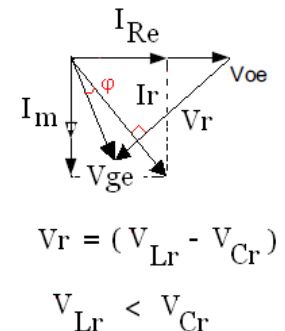


## Working regions (Modes)

- Inductive Region, if resonant network current is lagging input voltage
- Capacitive Region, if resonant network current is leading input voltage
- Resistive Region, if resonant network current is in phase with input voltage  
(boundary to divide Inductive and capacitive, by let the imaginary part zero of the input impedance)
- Unity gain happens at  $(V_{Lr} - V_{Cr}) = 0$ , where input voltage in phase with output voltage, and input voltage applies to load ( $R_e$ ) directly

# LLC Resonant Converter with Wide Operation Range

- Should operate in ZVS region (Inductive Region,  $I_r$  lagging  $V_{ge}$ )
- Avoid ZCS region (Capacitive Region,  $I_r$  leading  $V_{ge}$ )
  - Hard switching of half bridge switches
  - Reverse recovery losses in primary FET body diodes
  - Large spikes on switch node
  - Higher EMI levels
  - Frequency relationship reversed
    - Frequency increases as load increases

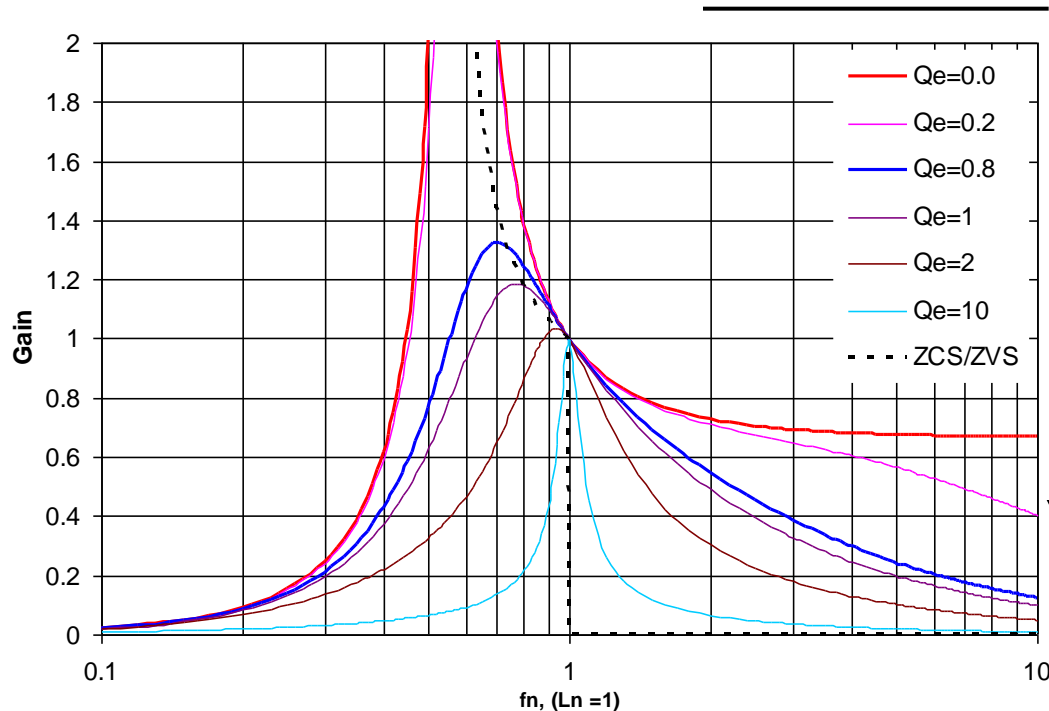


# Gain Characteristics with Ln and Qe

$$Q_e = \frac{\sqrt{L_r / C_r}}{R_e}$$

$Q_e$  is related to output load

$Q_e$  Increasing with Load Current



$$R_e = \frac{8}{\pi^2} n^2 R_L$$

$$f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$$

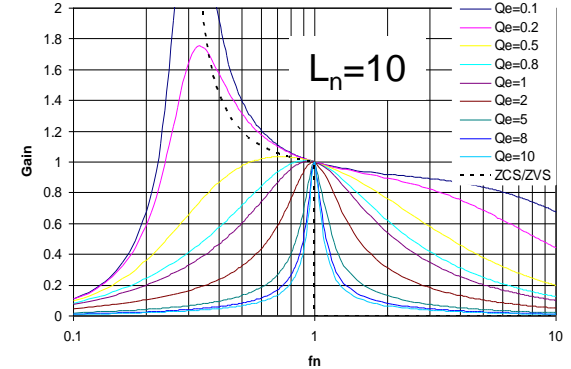
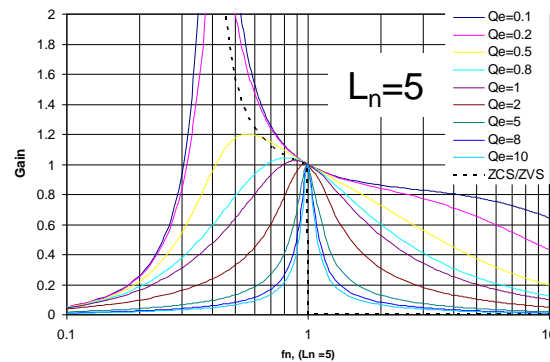
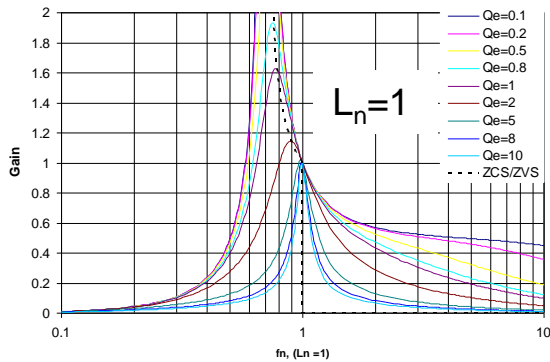
$$f_p = \frac{1}{2\pi\sqrt{(L_r + L_m)C_r}}$$

$$f_n = \frac{f}{f_0}$$

$Q_e$  increase with  $L_n$  constant (designed  $L_r$ ,  $C_r$ , and operational  $R_L$ ),

- Peak-gain becomes lower
- Frequency at peak-gain moving to right
- Better "frequency-selective"

# Impacts of Circuit Parameters

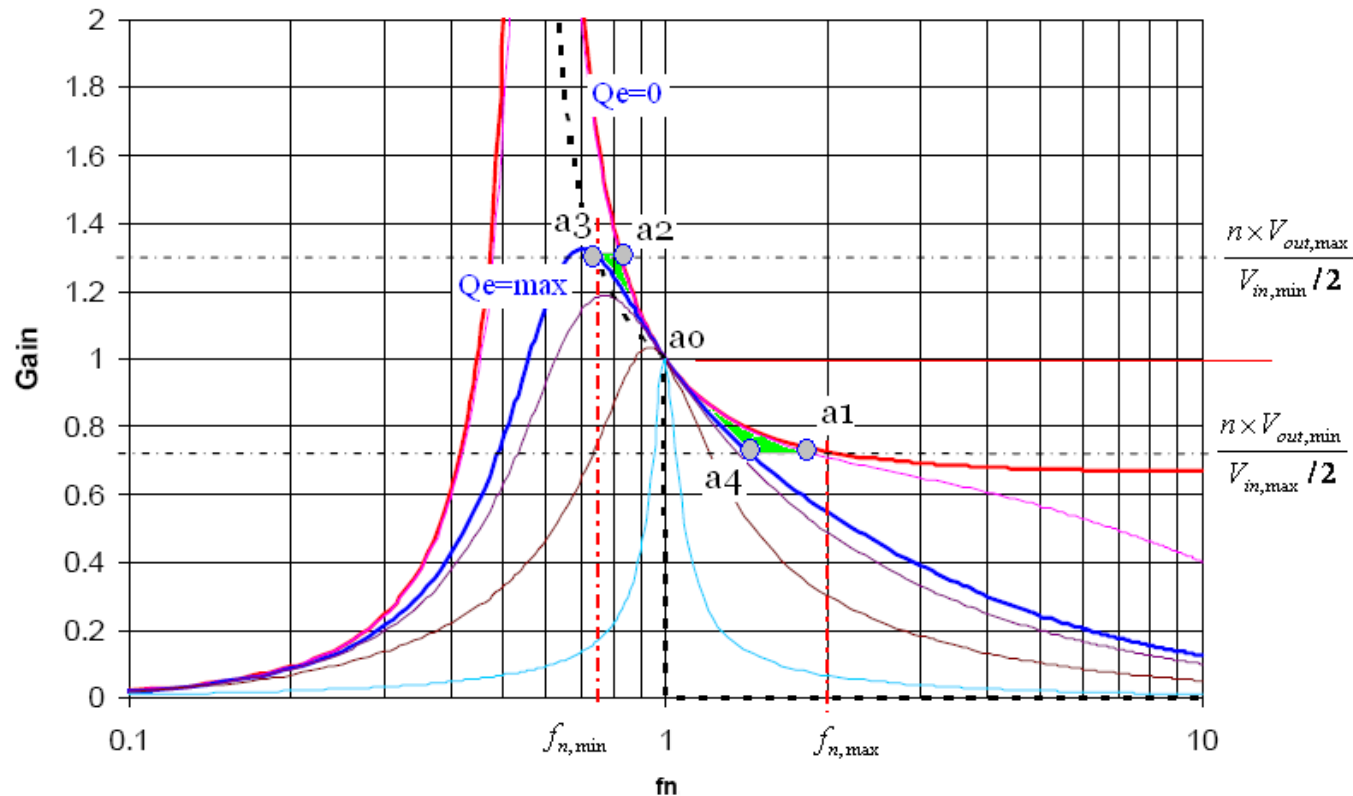


## Gain Change with $L_n$ and $Q_e$

- $L_n$  increase with  $Q_e$  constant (designed  $L_r$ ,  $C_r$ , and operational  $RL$ ),
  - flat,
  - magnitude shift-up,
  - frequency value at peak-gain moving towards more left,
  - less “frequency-selective”
  - wide frequency variation from no load to full load (more discussion later)

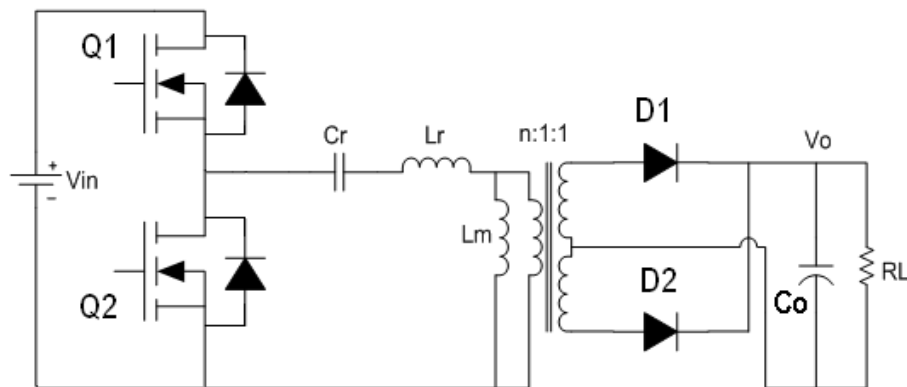
$L_n$  somewhere 3 to 5 look best balance between peak gain and frequency change – can be initially pick-up

# LLC Resonant Converter Operation for design consideration



- Operation/design with no load and minimum gain at  $a_1$
- Operation /design with full load and maximum gain at  $a_3$
- All gain curves cross at unity at  $f_n = 1$ , or  $f = f_0$
- $Q_e$  design consideration at Heavy load, OCP, Short Circuit

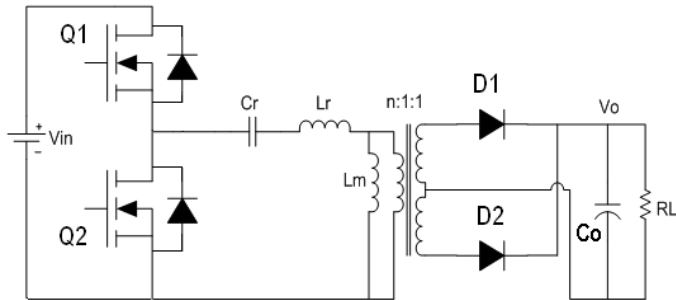
# Design Goals for LLC Resonant Converter



- Minimize RMS current under normal operation condition
- Ensure ZVS operation
- Ensure desired operation range

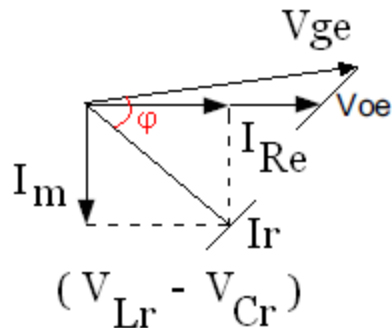
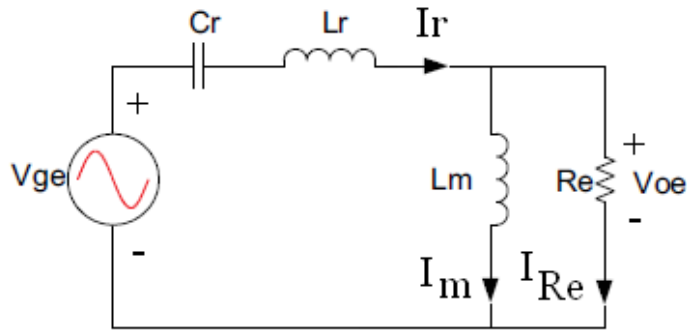


# Design Consideration -1: *Primary RMS Current at Normal Operation*



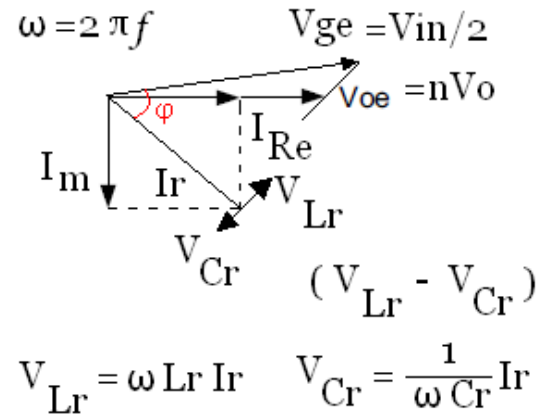
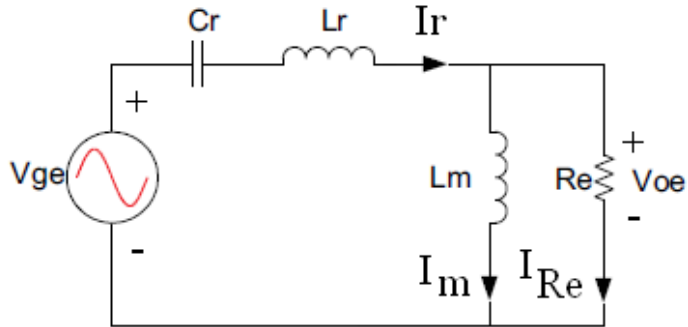
$$I_{P,RMS} = I_r = \sqrt{I_m^2 + I_{Re}^2} =$$

$$FHA \rightarrow \sqrt{\left( \frac{2\sqrt{2}}{\pi} \frac{nV_o}{\omega L_m} \right)^2 + \left( \frac{\pi}{2\sqrt{2}} \frac{I_o}{n} \right)^2}$$



- Primary current can be easily calculated from the phasor circuit
- Primary side RMS current is summation of magnetizing current and load current
- Larger  $L_m$  is better for less conduction losses

## Design Consideration -2: Secondary winding RMS Current

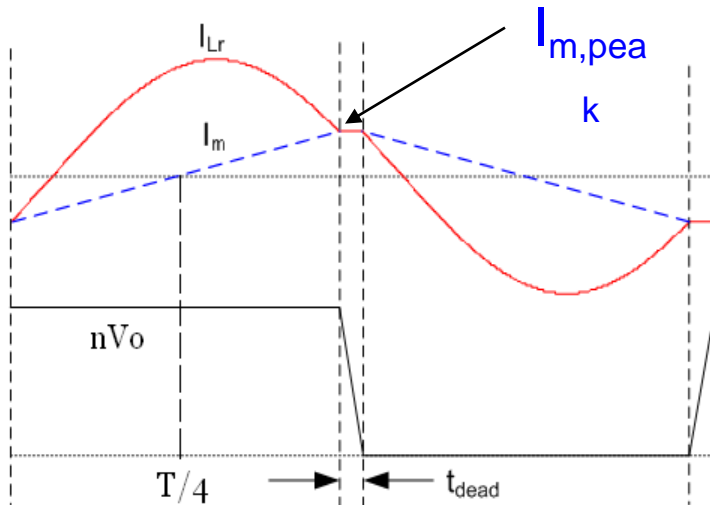


$$I_{RMS\_S} = (I_{Re} \times n) / 2 = \frac{\pi}{4\sqrt{2}} I_o \Rightarrow I_{peak\_S} = \frac{\pi}{4} I_o, \quad \text{center-tapped}$$

$$I_{RMS\_S} = I_{Re} \times n = \frac{\pi}{2\sqrt{2}} I_o \Rightarrow I_{peak\_S} = \frac{\pi}{2} I_o, \quad \text{bridge}$$

- Secondary side current is the difference between resonant tank current and magnetizing current

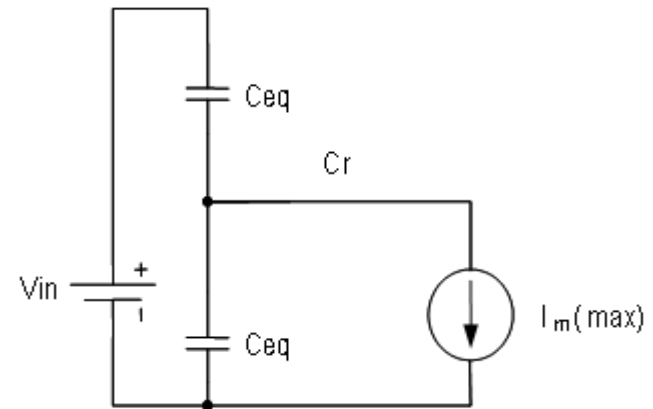
# Design Consideration -3: Zero Voltage Switching



$$\frac{1}{2}(L_m + L_r)I_{m,peak}^2 \geq \frac{1}{2}(2C_{eq})V_{in}^2$$

ZVS conditions:

- Enough H-field energy to balance E-field Energy in less than half cycle
- Enough time to make the energy conversion
- Worst operation for ZVS,
  - $V_{o,min}$ ,  $I_{m,peak}$  becomes small
  - $V_{in,max}$ , more  $C_{eq}$  energy needs to discharge



$$I_{m,peak} = \frac{nV_o}{L_m} \frac{T}{4}$$

$$I_{m,peak} \times t_{dead} \geq 2C_{eq}V_{in}$$

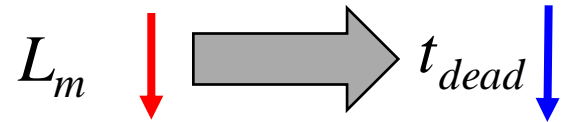
$$L_m \leq \frac{T \times t_{dead}}{16C_{eq}}$$

# Trade-off Design of Dead Time



- Smaller turn off current
- Smaller magnetizing current

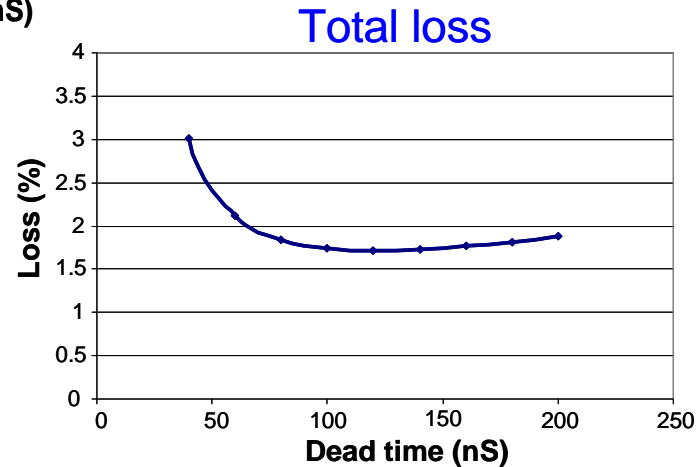
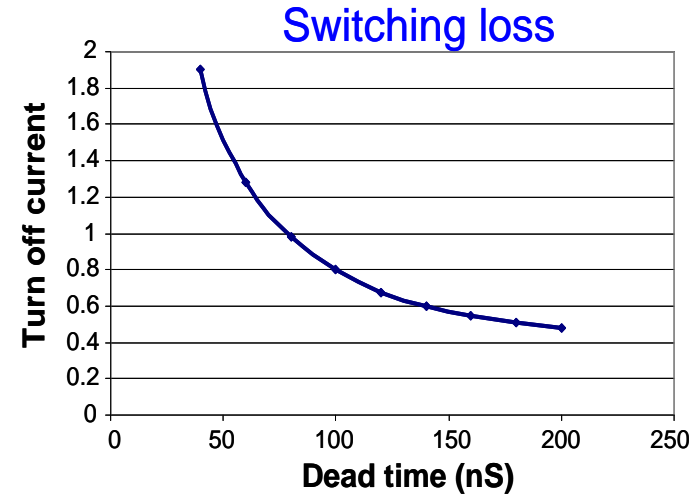
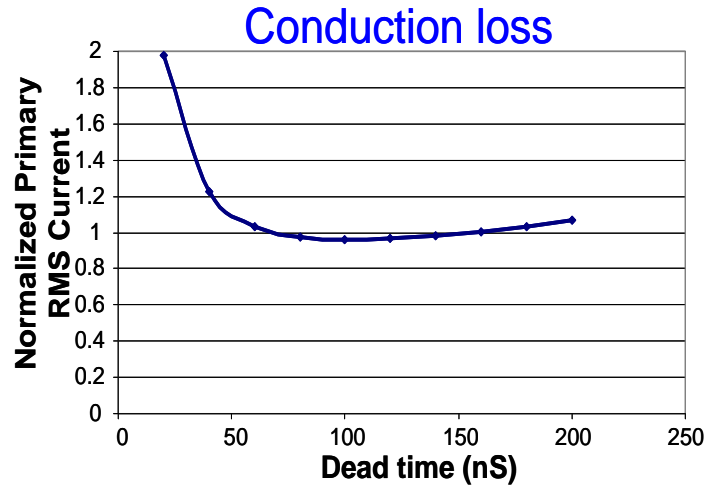
➤ Increase RMS current due to duty cycle loss



- Smaller duty cycle loss

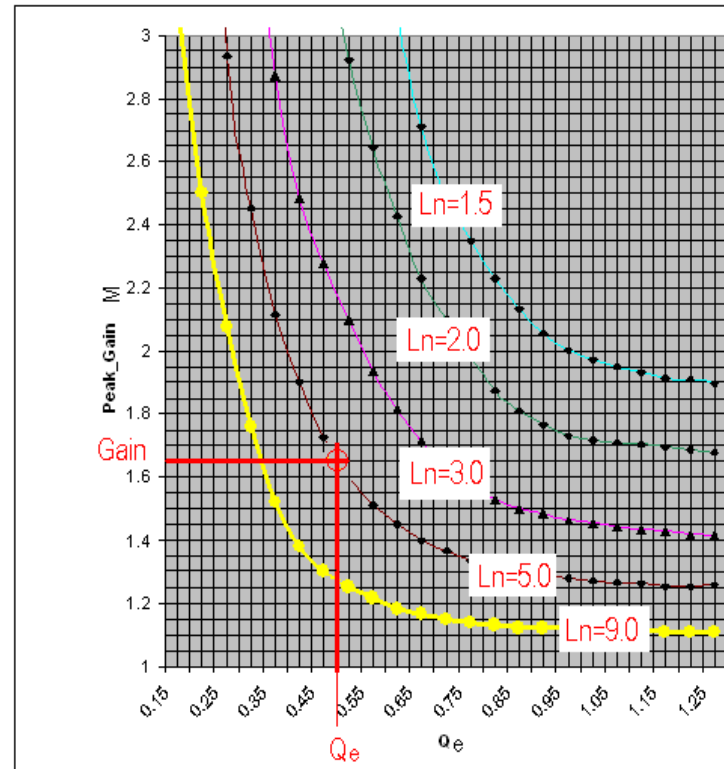
➤ Larger magnetizing current  
➤ Larger turn off loss

# Trade-off Design of Dead Time



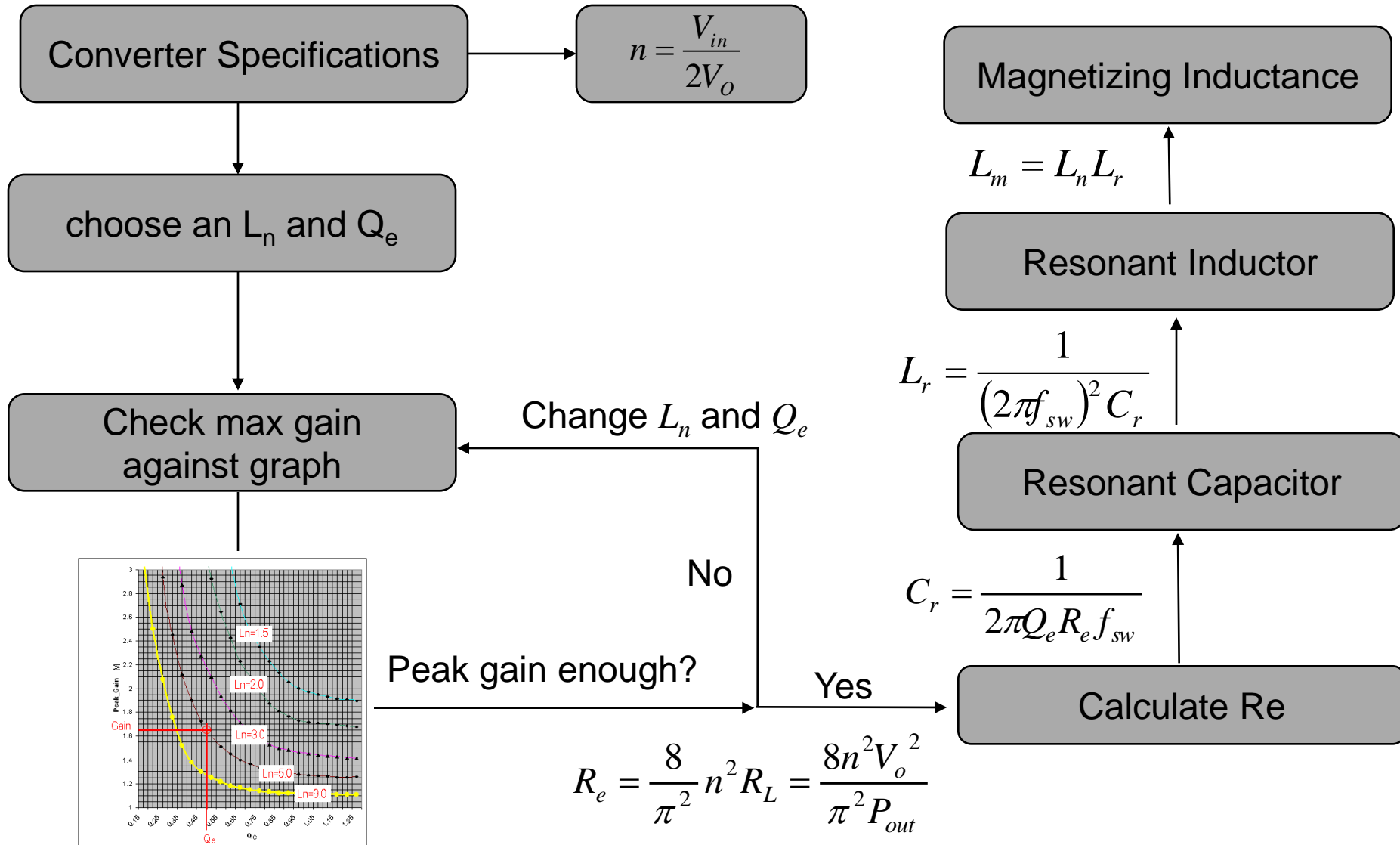
➤ Trade-off between the switching loss and conduction loss on a case of 100ns dead time

# Peak Gains with Ln and Qe

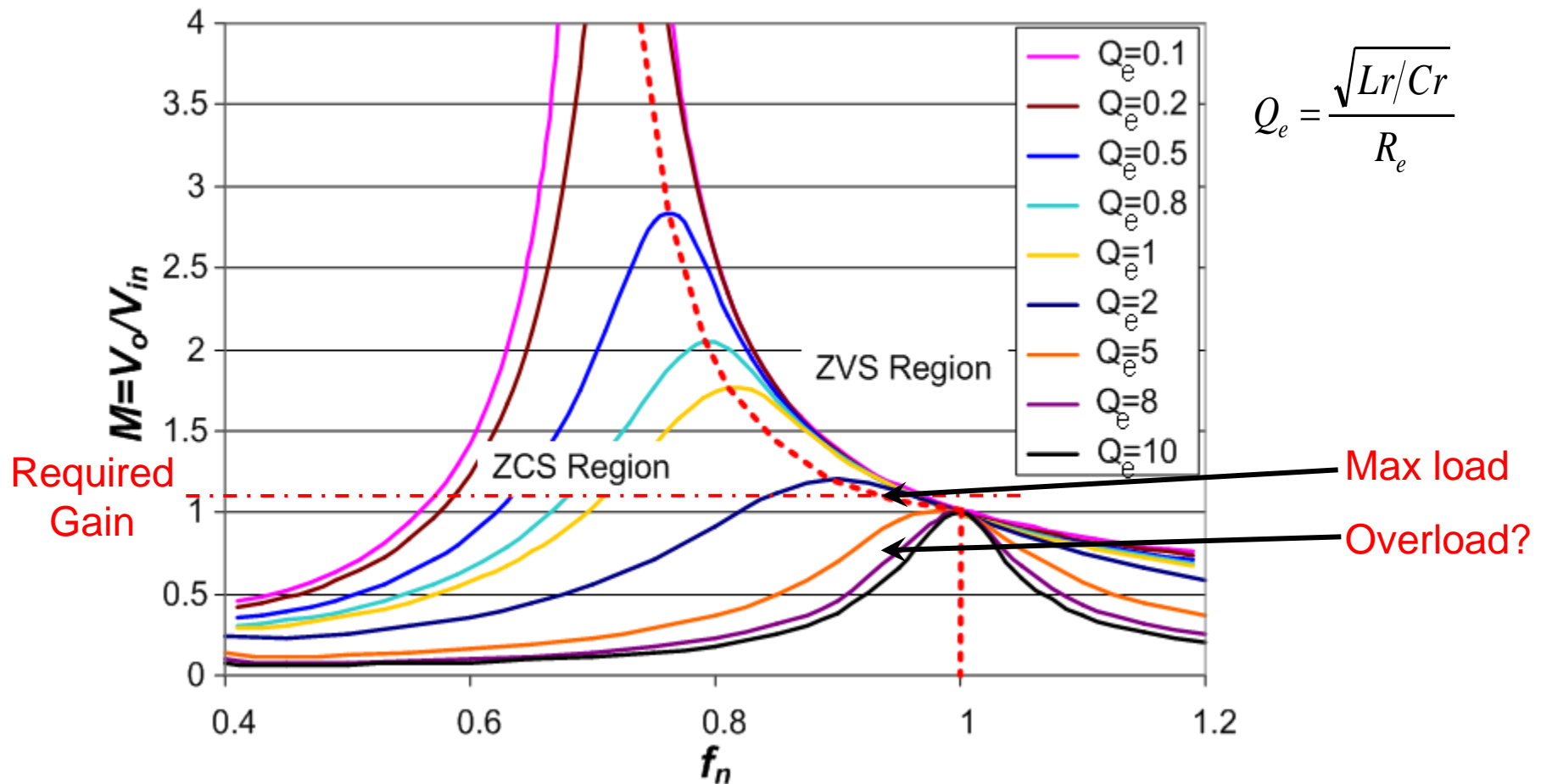


- Initially select  $L_n$  in the range of 3 to 5 (gain curve not very flat and able to narrow down the frequency change while there is still enough gain)
- Find proper  $Q_e$  to get enough peak gain

# Design Flow Chart for LLC Resonant Converter



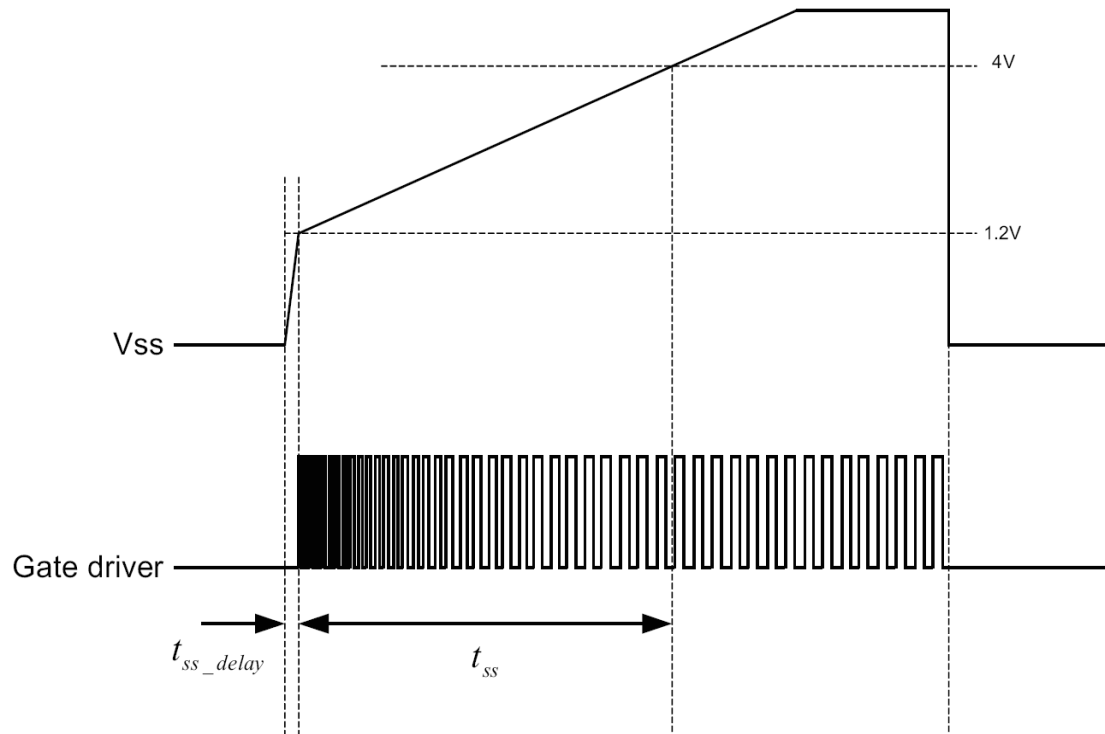
# Design - Over Current Protection



➤ During over load condition, check if the converter enters ZCS region



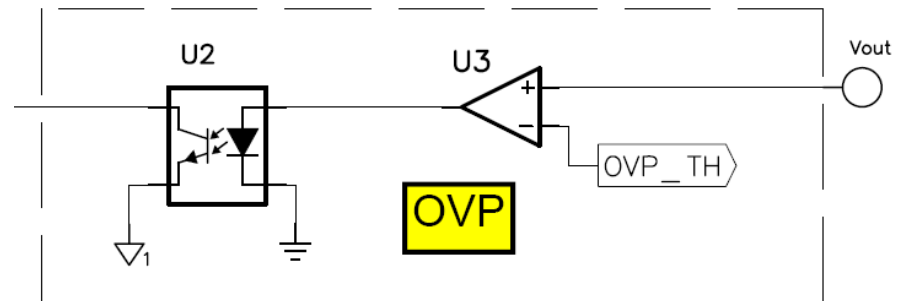
# Design - *Soft start*



- Soft start is achieved by frequency control

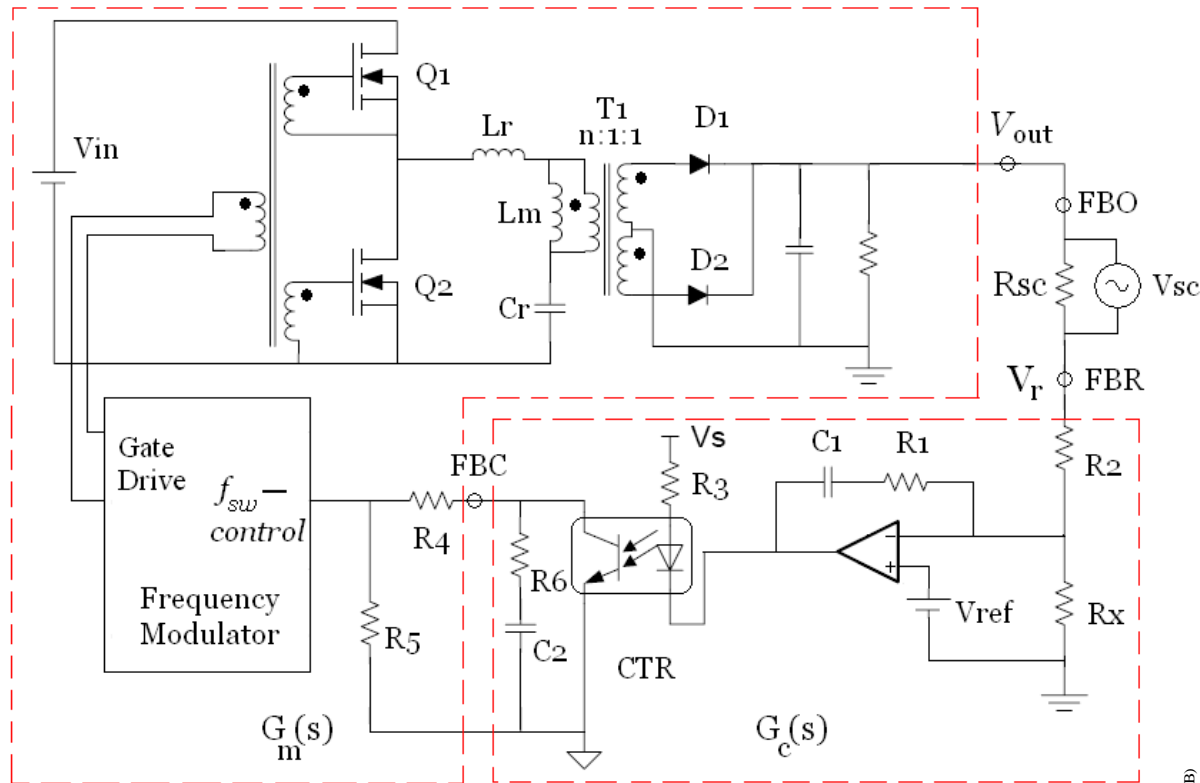
# Design – OVP and Burst Operation

- Secondary OVP
  - Feedback loop fault may cause output over voltage.
  - Slow loop response may also cause OVP.
  - Independent OVP circuit is needed.

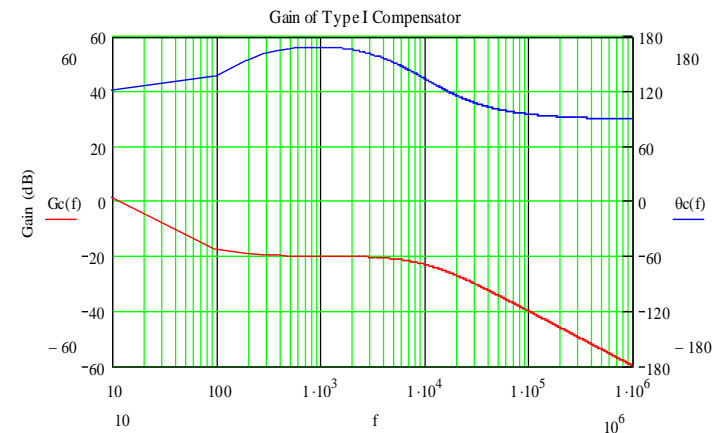
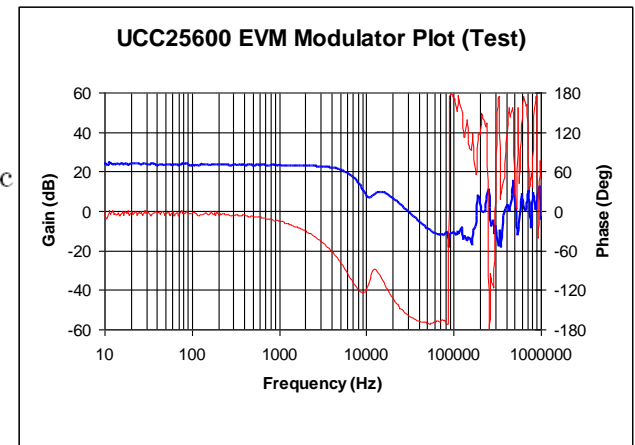


- Burst Operation
  - To cover no load operation, smaller  $L_n$  is needed which increases circulating (magnetizing) current, leading more conduction losses.
  - To reduce switching losses, ZVS is still needed at no load. This requires higher magnetizing current, too.
  - To maintain output regulation, burst operation at light load and no load is an alternative to balance switching losses and conduction losses.

# Feedback Loop Design



$$G_c(S) = K_{dc} \frac{\frac{S}{C1 \times R2} + 1}{S \times \left( \frac{k_{opto} S}{2\pi \times f_{p\_opto}} + 1 \right)}$$



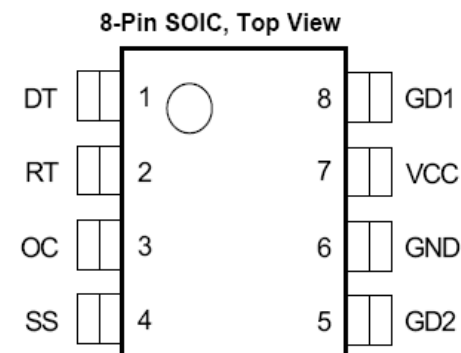
- Measure  $G_m(j\omega)$
- Design  $G_c(j\omega)$  based on  $G_m(j\omega)$  measurement

# Summary

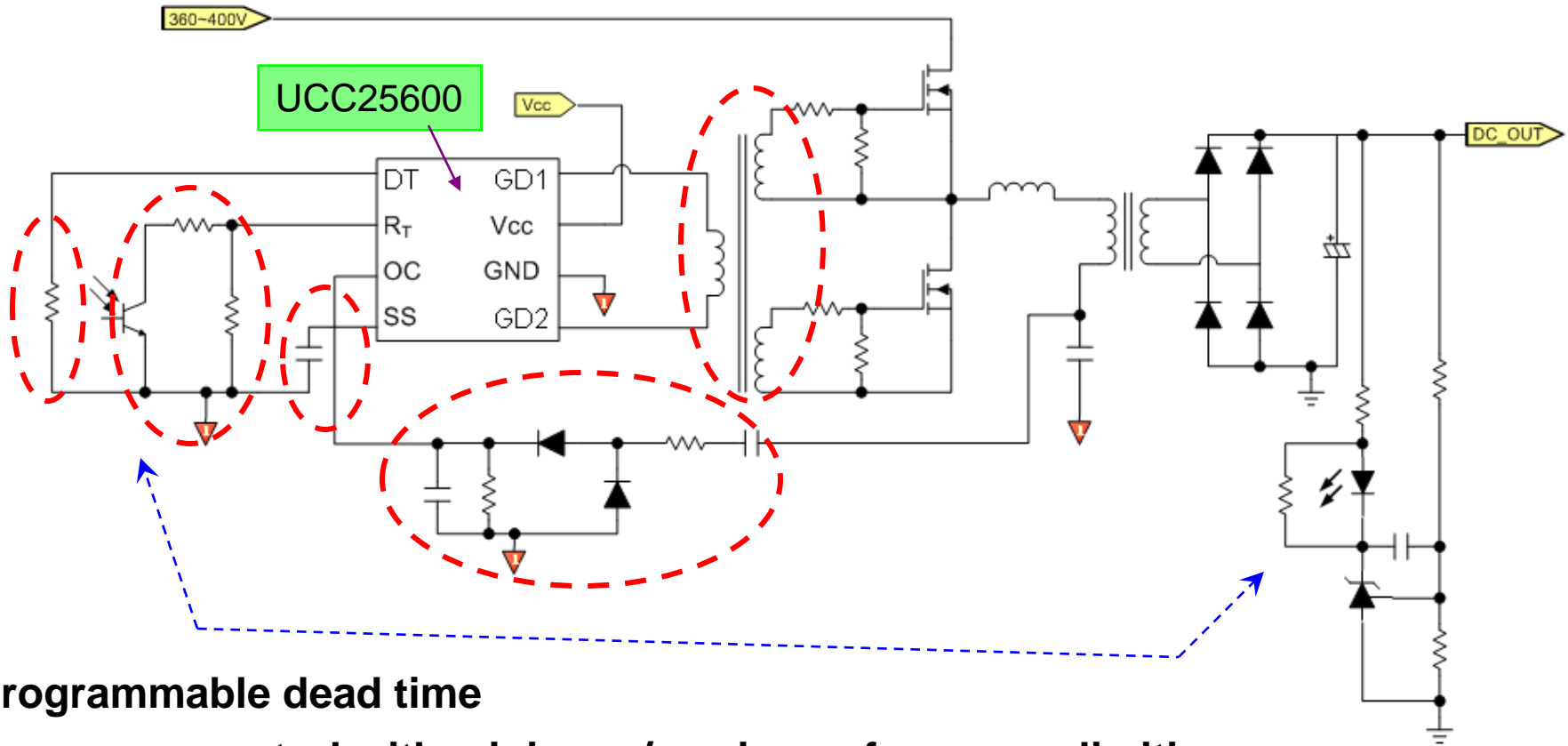
- LLC resonant converter is able to achieve wide operation together with high efficiency
- Due to low switching losses, LLC resonant converter is able to operate at high switching frequencies, while maintaining high efficiency
- LLC resonant converter design needs to find a suitable magnetizing inductor to ensure small conduction losses and switching losses
- By choosing a suitable  $L_n$  and  $Q_e$  value, desired voltage gain can be achieved to input and output voltage variation range

# UCC25600 Resonant Half Bridge Controller

- Complete system features
  - Programmable soft start
  - Programmable dead time
  - Programmable maximum/minimum switching frequency
  - 0.4A source, 0.8A sink driving capability
  - Simple ON/OFF control
  - Burst operation at light load condition
- Precise timing control
  - 3% accuracy on minimum switching frequency setting with only external resistor
  - $\pm 50\text{ns}$  matching on dead time
  - Soft start timer range from 1ms to 500ms
- Complete protection functions
  - Two levels over current protection, auto recovery and latch off
  - Bias voltage UVLO and OV protection
  - Over temperature protection
  - Soft start enabled after all fault conditions
- 8 pin SOIC package, simplifies design and layout



# Application Circuit



**Programmable dead time**

**Frequency control with minimum/maximum frequency limiting**

**Programmable soft start with on/off control**

**Two level over current protection, auto-recovery and latch up**

**Matching output with 50ns tolerance**

# Test based on EVM (UCC25600EVM)

**Table 1. UCC25600EVM Electrical Performance Specifications**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
<b>Input Characteristics</b>					
Voltage range	$V_{IN}$	375	390	405	$V_{DC}$
Maximum input current	$V_{IN} = 390 V_{DC}$ , $I_{OUT} = 25A$			0.88	A
Switching frequency	$V_{IN} = 390 V_{DC}$ , $I_{OUT} = 25A$		110		kHz
<b>Output Characteristics</b>					
Output voltage $V_{OUT}$	$V_{IN}: 390 V_{DC}$ , $I_{OUT}: 1A$	11.9	12	12.2	$V_{DC}$
Load current <sup>(1)</sup>	$V_{IN}: 390 V_{DC}$	0		25	A
Continuous output power	$V_{IN}: 390 V_{DC}$			300	W
Line regulation	$V_{IN}: 375 V_{DC}$ to $405 V_{DC}$ , $I_{OUT} = 1.0A$			5	mV
Load regulation	$V_{IN}: 390 V_{DC}$ , $I_{OUT}: 1 - 25A$			50	
Load starting burst <sup>(1)</sup>	$V_{IN}: 390 V_{DC}$		0.5		A
Ripple and noise (20 MHz BW)	$V_{IN}: 390 V_{DC}$ , $I_{OUT} = 25A$			120	mVpk-pk
Over current threshold, $I_{o\_ocp}$	$V_{IN}: 390 V_{DC}$		30		A
Max power limit	$V_{IN}: 390 V_{DC}$		350		W
<b>Efficiency</b>					
Peak	$V_{IN} = 390 V_{DC}$ , $I_{OUT} = 15 A$		92.5%		
Full load	$V_{IN} = 390 V_{DC}$ , $I_{OUT} = 25 A$		91%		
Operation ambient temperature	Full load, forced air cooling 400 LFM			45	C

<sup>(1)</sup> The EVM output may present saw-tooth waveforms or a voltage higher than the regulation point typically about 13.1 V depending on load levels and the speed when the load is reduced. The saw-tooth waveform is caused by UCC25600 burst operation. The output voltage of 13.1 V is caused by output over voltage protection.

# Test with EVM: Resonant Tank

- Ch3: Lr Current
  - Scale: 3.4A/div
- Primary Peak Current: 2.72A
- Secondary Peak Current (Nt=16.7):
  - $3.4\text{A/div} \times 0.8\text{div} \times 16.7 = 45.4\text{A}$
- Load Current: 25A
  - $I_o/I_s = 25/45.4 = 0.55$
  - Compare: half wave rectifier

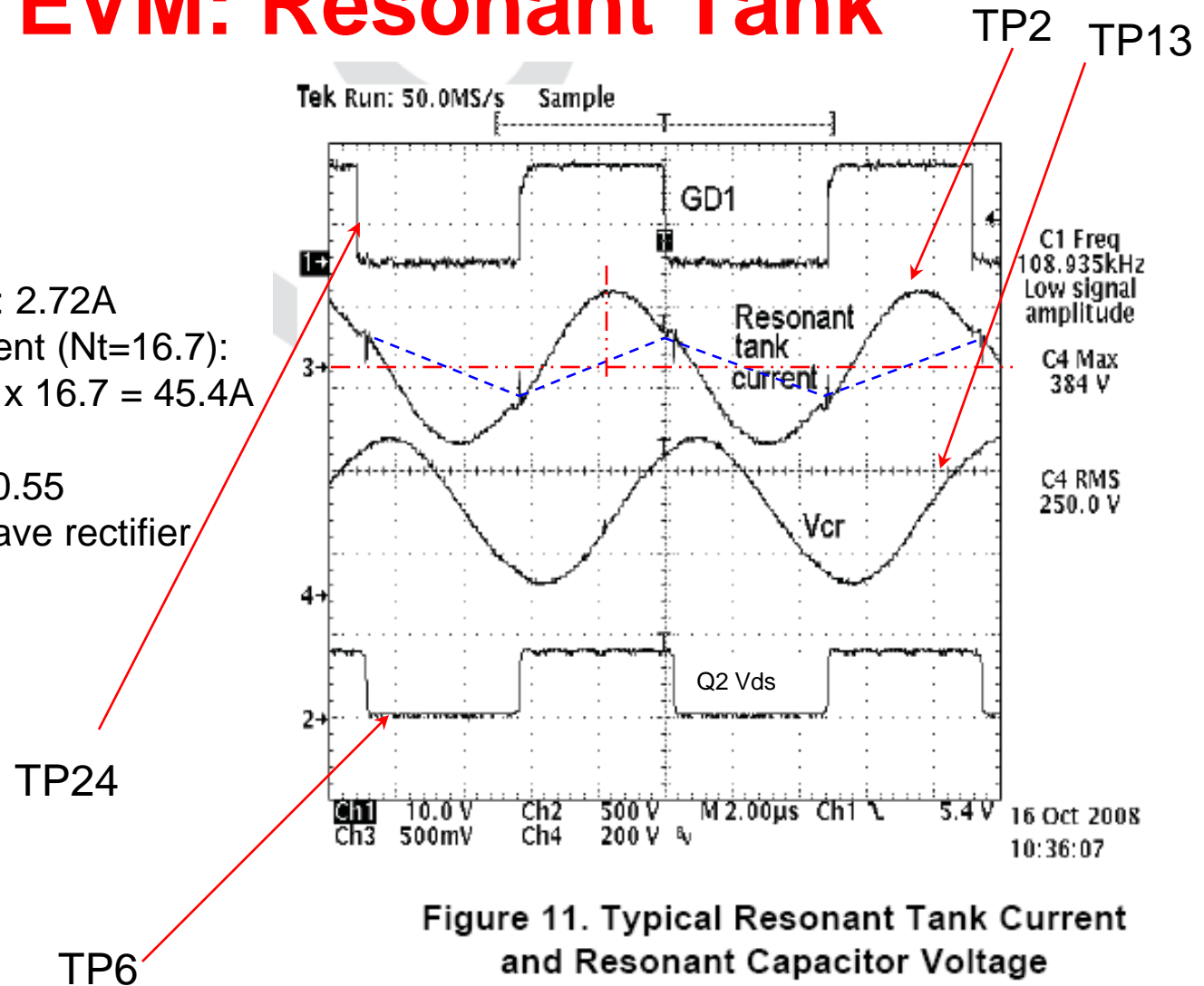


Figure 11. Typical Resonant Tank Current and Resonant Capacitor Voltage



# Test with EVM: Ripple and Hiccup

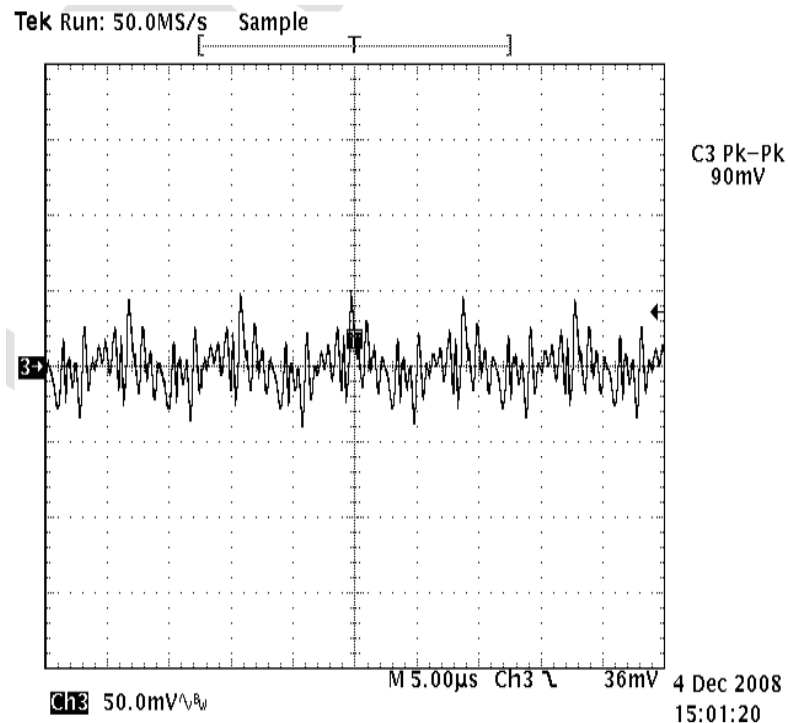


Figure 7. Typical Output Voltage Ripple Waveform at  $V_{IN} = 390\text{ V}$  and  $I_O = 15\text{ A}$  (TP15)

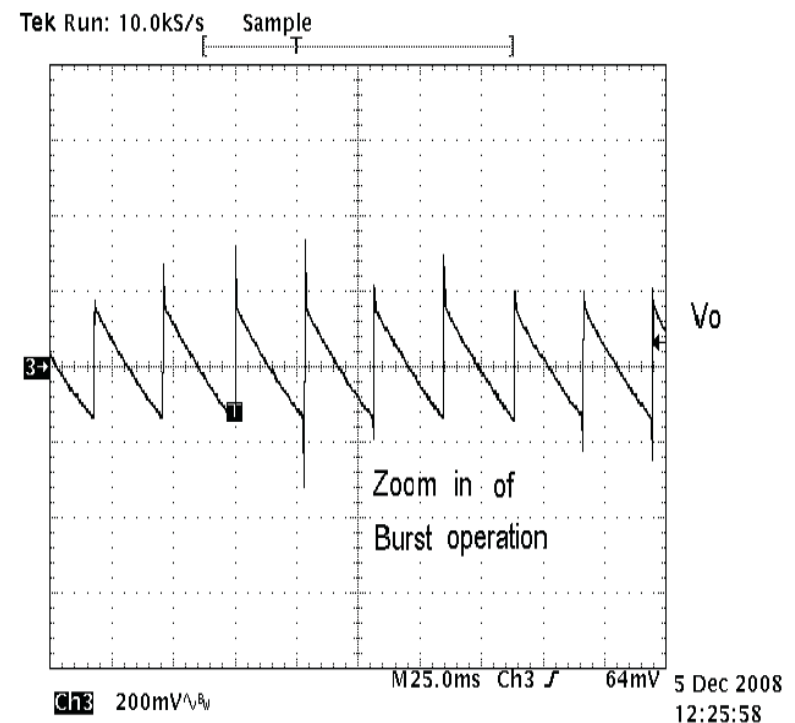
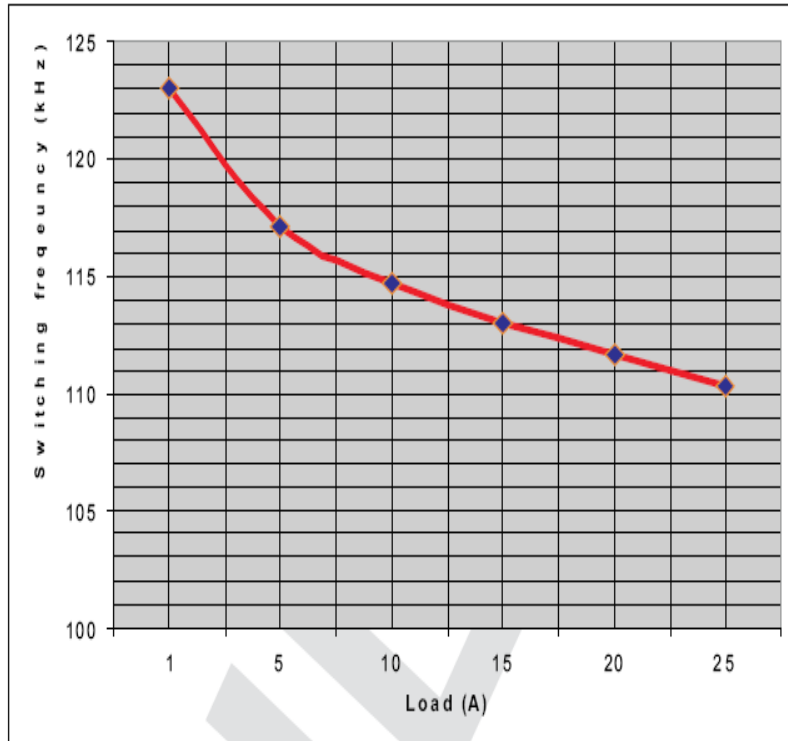
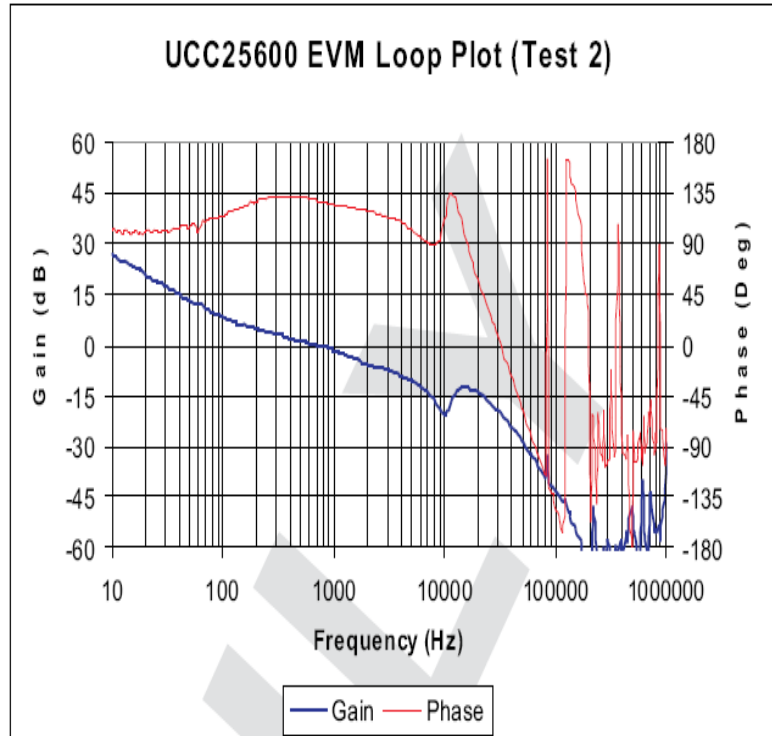


Figure 16. Typical Output Voltage in Burst Operation (TP15)

# Test with EVM: Freq and Feedback

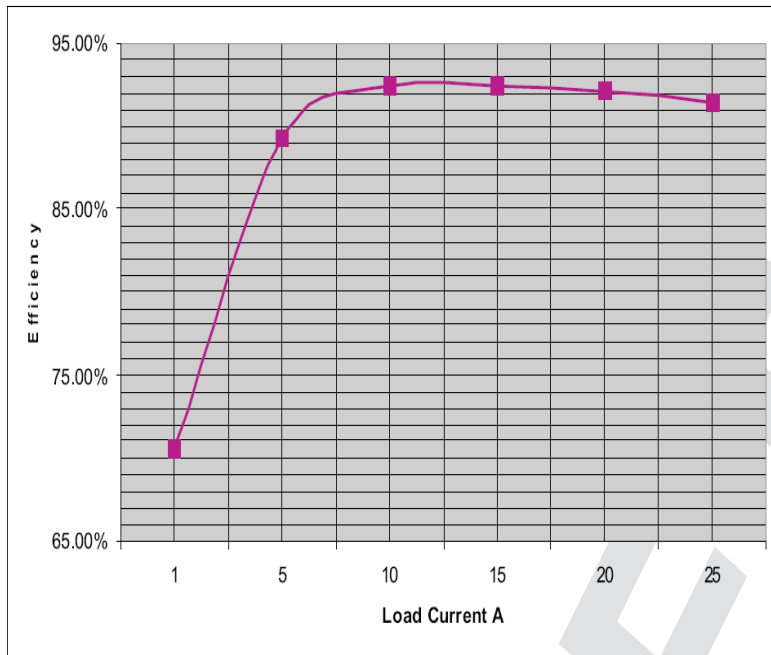


Frequency Variation

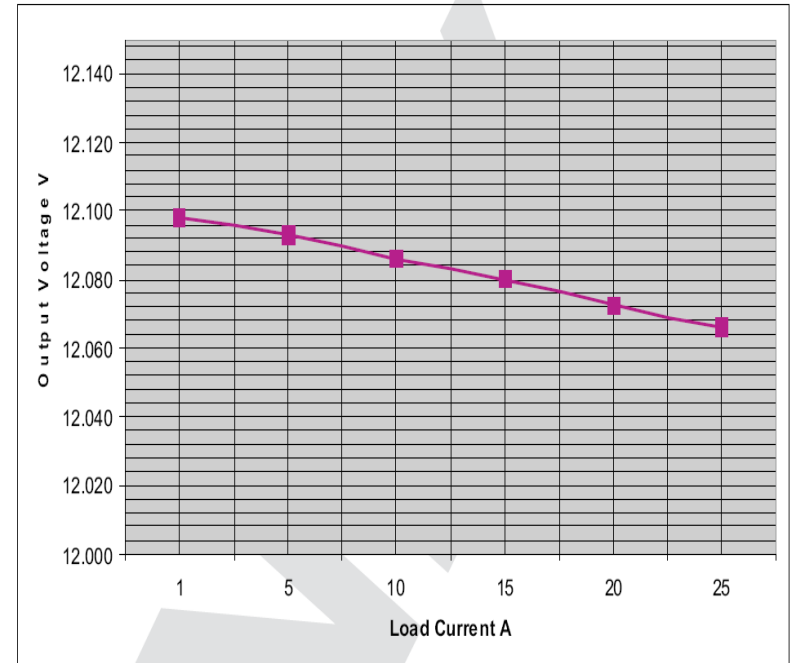


Feedback Loop Bode Plots

# Test with EVM: Efficiency and Load Regulation



Efficiency



Load Regulation

# Thank You!