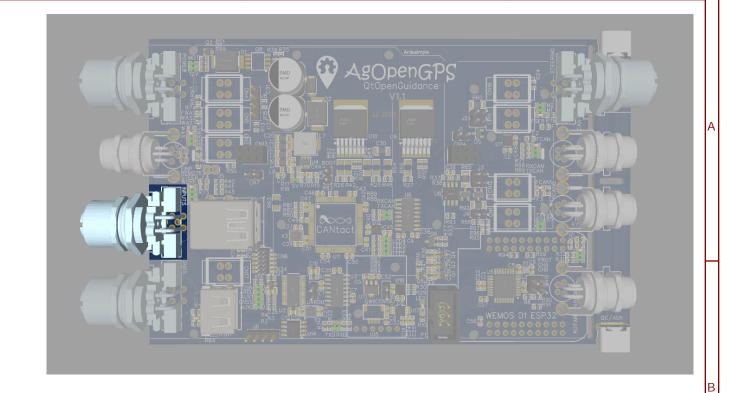


- Annotations:
   Steer signal will be automatically asserted when motor driver is powered if J7 is unfitted
   Remote and Work signals may be analog 0..15V if using the ESP32 option









Cable M12-A male 4/5pole, e. g. weidmueller.com SAIL-M12G-5-1.5U (945761<u>0150</u>)

5 pole 1.5m unshielded = 0150cm

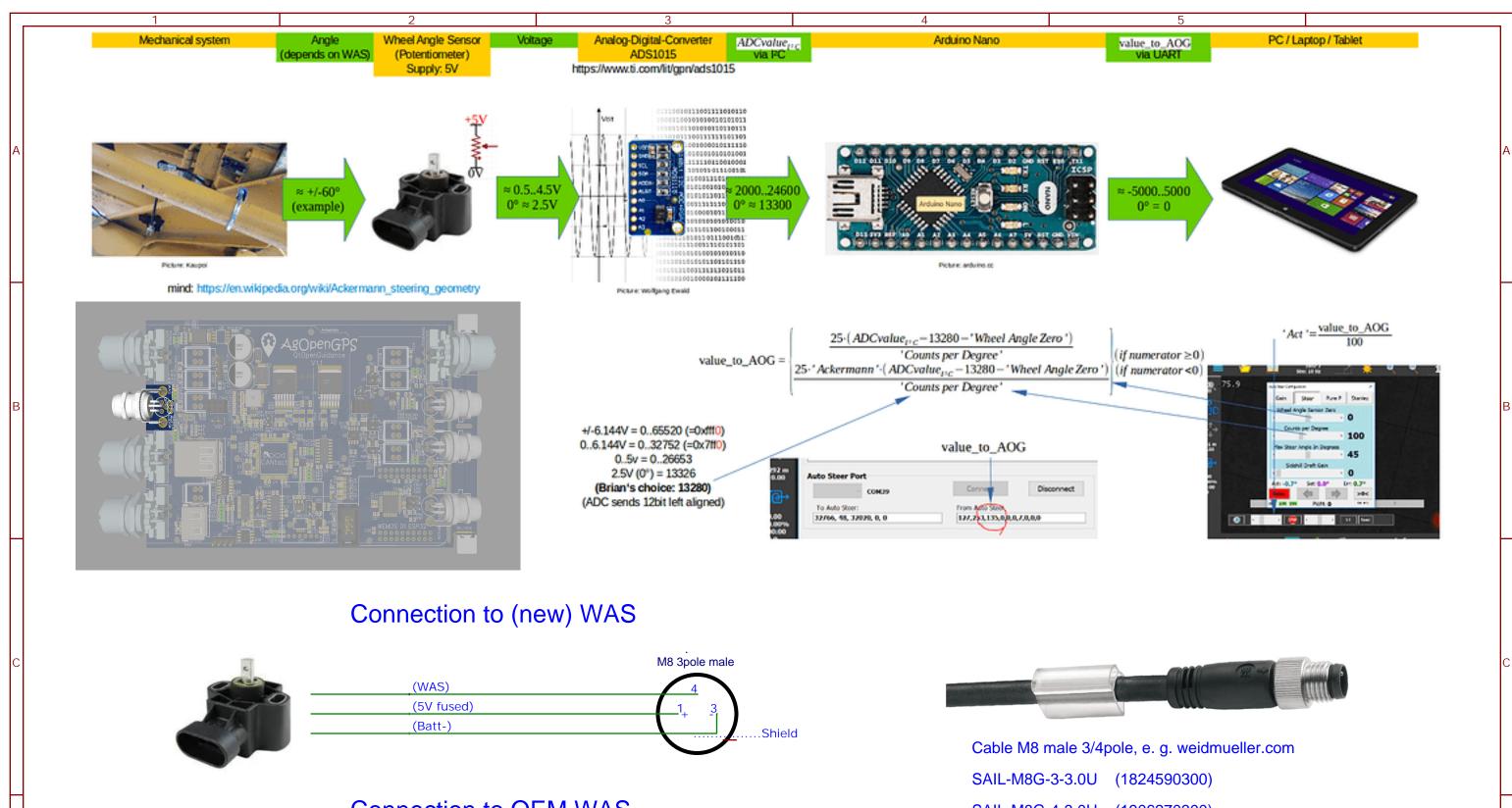
TITLE: Connecting Power Socket REV: 1.0

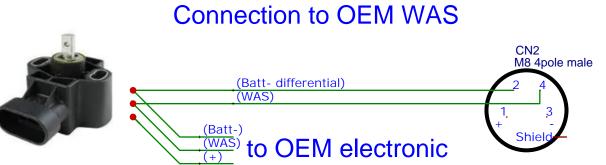
**EasyEDA** 

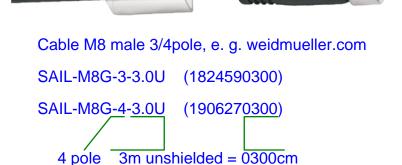
Company: agopengps.discourse.group

Date: Drawn By: GoRoNb 2021-01-09

Sheet: 1/1





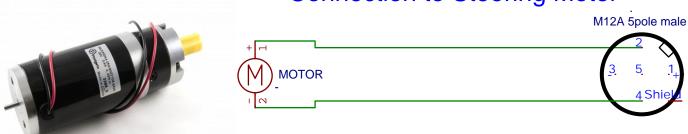


TITLE: Connecting the Wheel Angle Sensor (WAS)		REV: 1.0
O = ===	Company: agopengps.discourse.group	Sheet: 1/1
FosyFD&		

2021-01-09

Drawn By: GoRoNb

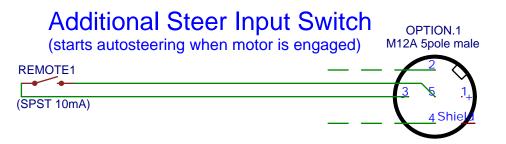




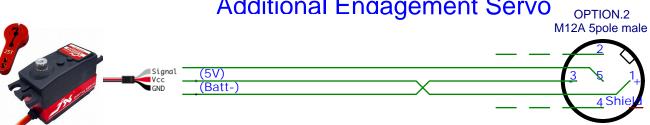
# Connection to Hydraulic Valves

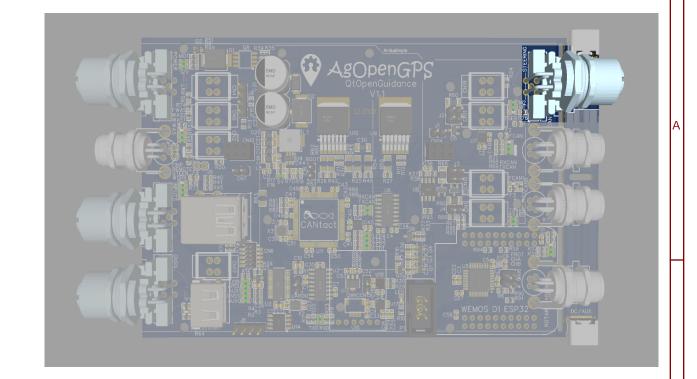






## Additional Engagement Servo







Cable M12-A male 4/5pole, e. g. weidmueller.com

SAIL-M12G-5-1.5U (945761<u>0150</u>)

5 pole 1.5m unshielded = 0150cm

TITLE: Connecting Motor or Valves

Company: agopengps.discourse.group **EasyEDA** 

Date: Drawn By: GoRoNb 2021-01-09

Sheet: 1/1

REV: 1.0

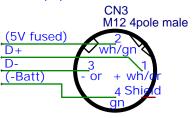




### USB\* or I <sup>2</sup> C\*\*

(\*) e. g. to Rooftop Unit

(\*\*) remove R43 + R46 and connect I <sup>2</sup> C to CN3









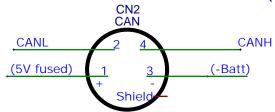


Cable M12D male-male 4pole, e. g. weidmueller.com IE-C5DD4UG0030MCSMCS-E (1025950030)

4 pole 3m = 0030dm

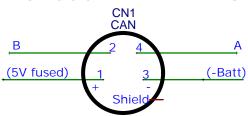


Controller Area Network (CAN)





RS485 / ModbusRTU





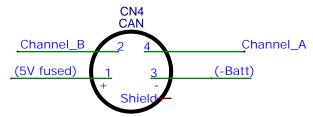
Cable M8 male 4pole, e. g. weidmueller.com

SAIL-M8G<u>-4</u>-<u>3.0U</u> (190627<u>0300</u>)

4 pole 3m unshielded = 0300cm



# Alternative: Rotary Encoder



TITLE:
Bus Connections
REV: 1.0

**€** EasyEDA

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Date: 2021-01-09 Drawn By: GoRoNb

Sheet: 1/1

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