```
In[16]:= eq = \left\{\right.
                                                     m(x\theta''[t] + R(\theta''[t] Cos[\theta[t]] - \theta'[t]^2 Sin[\theta[t]])) =
                                                            -f2[t] Cos[\theta[t]] + Fn2[t] Sin[\theta[t]],
                                                      m R \left(-\theta''[t] Sin[\theta[t]] - \theta'[t]^2 Cos[\theta[t]]\right) =  f2[t] Sin[\theta[t]] + Fn2[t] Cos[\theta[t]] - m g, 
                                                     f2[t] - f1[t] = \frac{x0''[t]}{R^2}i
                                                     f1[t] + f2[t] Cos[\theta[t]] + Fn2[t] Sin[\theta[t]] = m x0''[t]
                                               };
                                    {\tt Column[Simplify@eq, Frame \rightarrow All] // TraditionalForm}
                                       f2(t)\cos(\theta(t)) + m(R\theta''(t)\cos(\theta(t)) - R\theta'(t)^2\sin(\theta(t)) + x0''(t)) = Fn2(t)\sin(\theta(t))
                                        g m = f2(t)\sin(\theta(t)) + \operatorname{Fn}2(t)\cos(\theta(t)) + mR\theta''(t)\sin(\theta(t)) + mR\theta'(t)^2\cos(\theta(t))
                                        f2(t) = f1(t) + \frac{i \times 0''(t)}{R^2}
                                       f1(t) + f2(t)\cos(\theta(t)) + Fn2(t)\sin(\theta(t)) = m \times 0''(t)
        In[19]:= elim = Eliminate[eq, {f1[t], Fn2[t]}]
      Out[19]= g \, m \, Sin[\theta[t]] = Cos[\theta[t]]^2 \, f2[t] + f2[t] \, Sin[\theta[t]]^2 +
                                                     \text{m}\,\text{Cos}\,[\theta[\texttt{t}]\,]\,\,x\theta^{\prime\prime}\,[\texttt{t}]\,+\,\text{m}\,\text{R}\,\text{Cos}\,[\theta[\texttt{t}]\,]^2\,\theta^{\prime\prime}\,[\texttt{t}]\,+\,\text{m}\,\text{R}\,\text{Sin}\,[\theta[\texttt{t}]\,]^2\,\theta^{\prime\prime}\,[\texttt{t}]\,\&\&\,
                                          \texttt{i} \times 0^{\prime\prime} \texttt{[t]} = \texttt{R}^2 \left( \texttt{f2[t]} + 2 \, \texttt{Cos}[\boldsymbol{\theta}[\texttt{t}]] \, \, \texttt{f2[t]} - \texttt{m} \, \texttt{R} \, \texttt{Sin}[\boldsymbol{\theta}[\texttt{t}]] \, \, \boldsymbol{\theta}^\prime \texttt{[t]}^2 + \texttt{m} \, \texttt{R} \, \texttt{Cos}[\boldsymbol{\theta}[\texttt{t}]] \, \, \boldsymbol{\theta}^{\prime\prime} \texttt{[t]} \right) \, \&\& \, \texttt{R} \neq 0 \, \texttt{m} \, \texttt{R} \, \texttt{Cos}[\boldsymbol{\theta}[\texttt{t}]] \, \, \boldsymbol{\theta}^\prime \, \texttt{[t]} \, \, \texttt{M} \, \texttt{R} \, \texttt{Cos}[\boldsymbol{\theta}[\texttt{t}]] \, \, \boldsymbol{\theta}^\prime \, \texttt{[t]} \, \, \texttt{M} \, \texttt{R} \, \texttt{M} \, \texttt{M
        Out[22]//TraditionalForm=
                                                -((R^2(-f2(t)\sin^2(\theta(t)) - f2(t)\cos^3(\theta(t)) - f2(t)\cos^2(\theta(t))))
                                                                                                                                                                                                                                                                                                            -((i f2(t) tan^2(\theta(t)) + i f2(t) + m R^2 f2(t) sec(\theta(t)) +
                                                                                                                                        \theta(t)) – f2(t) sin<sup>2</sup>(\theta(t)) cos(\theta(t)) –
                                                                                                                                                                                                                                                                                                                                                           2 m R^2 f2(t) - g i m tan(\theta(t)) sec(\theta(t)) -
                                                                                                                    g m \sin(\theta(t)) \cos(\theta(t)) +
                                                                                                                                                                                                                                                                                                                                                             m^2 R^3 \theta'(t)^2 \tan(\theta(t)))
                                                                                                                    m R \theta'(t)^2 \sin^3(\theta(t)) +
                                                                                                                                                                                                                                                                                                                                        (m R(i \tan^2(\theta(t)) + i + m R^2)))
                                                                                                                    m R \theta'(t)^2 \sin(\theta(t)) \cos^2(\theta(t)))
                                                                             (i\sin^2(\theta(t)) + i\cos^2(\theta(t)) + mR^2\cos^2(\theta(t))))
```

Solve the system

Solve for x0"[t]

$$\begin{split} &\textbf{x0ppsol} = \textbf{First@Simplify@Solve} \Big[\textbf{eq} \big[\big[\textbf{3} \big] \big] \text{, } \textbf{x0''} \big[\textbf{t} \big] \Big] \\ & \Big\{ \textbf{x0''} \big[\textbf{t} \big] \, \rightarrow \, - \, \frac{ R^2 \, \left(f1 \big[\textbf{t} \big] \, - \, f2 \big[\textbf{t} \big] \right)}{i} \Big\} \end{aligned}$$

Column[eqs2 = Simplify[eq /. x0ppsol], Frame → All] // TraditionalForm

```
f2(t)\cos(\theta(t)) = \frac{mR(Rf1(t) - Rf2(t) - i\theta''(t)\cos(\theta(t)) + i\theta'(t)^2\sin(\theta(t)))}{mR(Rf1(t) - Rf2(t) - i\theta''(t)\cos(\theta(t)) + i\theta'(t)^2\sin(\theta(t)))} + Fn2(t)\sin(\theta(t))
g m = f2(t)\sin(\theta(t)) + Fn2(t)\cos(\theta(t)) + mR\theta''(t)\sin(\theta(t)) + mR\theta'(t)^2\cos(\theta(t))
True
\frac{mR^{2}(f1(t)-f2(t))}{(t)} + f1(t) + f2(t)\cos(\theta(t)) + Fn2(t)\sin(\theta(t)) = 0
```

Solve for θ "[t]

$$\begin{split} & \textbf{\it oppsol} = \textbf{First@Simplify@Solve} \big[\textbf{\it eqs2} \big[\big[1 \big] \big], \, \boldsymbol{\it \theta''} \big[\textbf{\it t} \big] \big] \\ & \left\{ \boldsymbol{\it \theta''} \big[\textbf{\it t} \big] \, \rightarrow \, \frac{ \text{m R}^2 \, \text{f1} \big[\textbf{\it t} \big] \, \text{Sec} \big[\boldsymbol{\it \theta} \big[\textbf{\it t} \big] \big] \, - \, \text{f2} \big[\textbf{\it t} \big] \, \left(\textbf{\it i} + \text{m R}^2 \, \text{Sec} \big[\boldsymbol{\it \theta} \big[\textbf{\it t} \big] \big] \right) \, + \, \textbf{\it i} \, \text{Tan} \big[\boldsymbol{\it \theta} \big[\textbf{\it t} \big] \big] \, \left(\text{Fn2} \big[\textbf{\it t} \big] + \, \text{m R} \, \boldsymbol{\it \theta'} \, \big[\textbf{\it t} \big]^2 \right) }{ \text{i m R}} \right\} \end{split}$$

Column[eqs3 = Simplify[eqs2 /. ⊖ppsol], Frame → All] // TraditionalForm

True
$g m = \frac{\sec(\theta(t)) \left(m R(Rf1(t) \sin(\theta(t)) - Rf2(t) \sin(\theta(t)) + i \theta'(t)^2 \right) + i Fn2(t) \right)}{i}$
True
$\lim_{t} \frac{m R^2 (f1(t) - f2(t))}{t} + f1(t) + f2(t) \cos(\theta(t)) + Fn2(t) \sin(\theta(t)) = 0$

Solve for f1[t]

f1sol = First@Simplify@Solve[eqs2[[4]], f1[t]]

$$\left\{ \texttt{f1[t]} \, \rightarrow \, \frac{\texttt{m}\, R^2\,\, \texttt{f2[t]} \, - i\, \texttt{Cos}\left[\varTheta[t]\right]\,\, \texttt{f2[t]} \, - i\, \texttt{Fn2[t]}\,\, \texttt{Sin}\left[\varTheta[t]\right]}{i\, + \, \texttt{m}\, R^2} \right\}$$

Column[eqs4 = Simplify[eqs3 /. f1sol], Frame → All] // TraditionalForm

```
True
g m = \sec(\theta(t))
True
```

Solve for Fn2[t]

Fn2sol = First@Simplify@Solve[eqs4[[2]], Fn2[t]]

$$\Big\{ Fn2[t] \rightarrow \frac{m \left(R^2 \ f2[t] \ \left(2 \, Sin[\varTheta[t]] + Sin[2\varTheta[t]] \right) + 2 \left(i + m \, R^2 \right) \ \left(g \, Cos[\varTheta[t]] - R \varTheta'[t]^2 \right) \right)}{2 \, i + m \, R^2 + m \, R^2 \, Cos[2\varTheta[t]]} \Big\}$$

In[41]:= SetDirectory[NotebookDirectory[]]

Export["Explicitly solving for Matlab.pdf", EvaluationNotebook[]]

Out[41]= /home/eric/Documents/School/QEA2/Module 3/QEA-BB8/v2