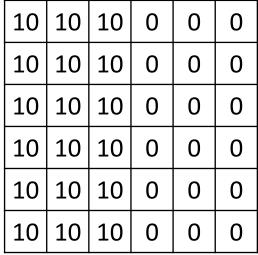
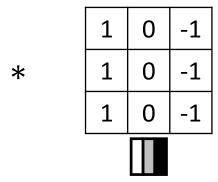


## Convolutional Neural Networks

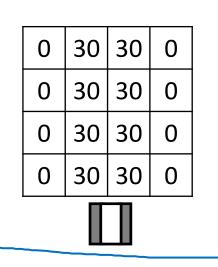
# More edge detection

#### Vertical edge detection examples





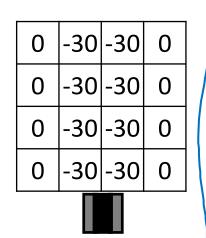
So because the shade of the transition is reversed, the 30s now get reversed as well.





0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10
0	0	0	10	10	10

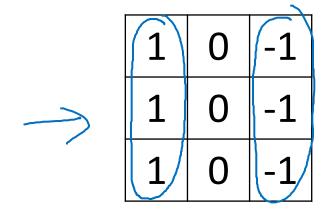
\* 1 0 -1 0 -1 0 -



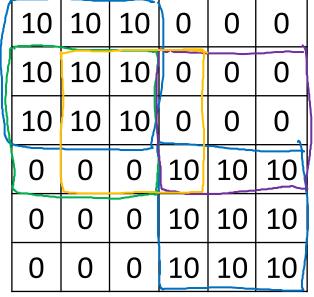


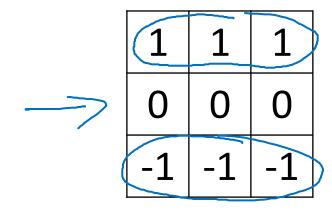
**Andrew Ng** 

### Vertical and Horizontal Edge Detection









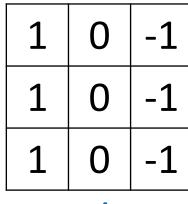
Horizontal

	1	1	
	0	0	
	-1	-1	
_			

0003010-10-303010-10-300000



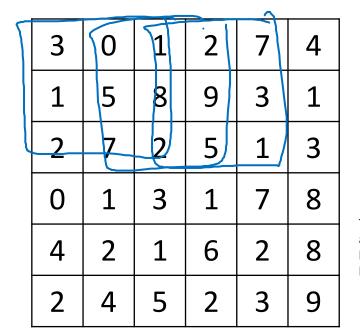
#### Learning to detect edges



And the advantage of this is, it puts a little bit more weight to the central row, the central pixel and this makes it maybe a little bit more robust.

(	0	-
2	0	-2
	$\bigcirc$	-1

1



Treating these 9 numbers as parameters. The backprop can choose to learn filters.

W	$\widehat{w_2}$	W <sub>3</sub>
W <sub>4</sub>	W <sub>5</sub>	$\overline{w_6}$
$\overline{w_7}$	$\widetilde{w_8}$	$\widehat{W_9}$
	$\rightarrow$	

543

3	0	-3
0	0	0
3	J	-3

Schor Filter

