

Implementation of TLC (Tiny Lambda Calculus)

WANG Hanfei

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Contents

1	Introduction	2
1.1	Specification of the language LAMBDA	2
1.2	Abstract syntax trees	2
1.3	Binding Depth	3
1.4	Primitive operations	3
1.5	output	5
2	Typing	5
2.1	Syntax-directed type synthesiser	5
2.2	step by step of type synthesis	6
2.2.1	Example 1: $\lambda x. \lambda y. x \ y$ (MN: M is a type variable)	8
2.2.2	Example 2: $\lambda x. (\lambda y. \lambda x. y) \ x$ (MN: M is arrow and N is type variable)	10
2.2.3	Example 3: $(\lambda x. \lambda y. x \ y) (\lambda x. x)$ (MN: M and N are both arrow)	11
2.2.4	Example 4: $\lambda x. x \ x$	12
2.2.5	Example 5: <code>let MY = $\lambda x. \lambda y. x \ y$;</code>	13
2.2.6	Example 6: $\lambda x. MY \ x$	14
2.2.7	Example 7: recursions	15
2.3	Church encoding and Type	16
3	TODO	17
3.1	Unification algorithm	17
3.2	the semantic rules of type synthesis	17
3.3	Typing	18
3.4	Memory leaks	19
4	Evaluation	19
4.1	Evaluation of Call-by-value	20
4.1.1	Example 1: $(\lambda x. \lambda y. x \ y) (\lambda x. x)$	20
4.1.2	Example 2: $(\lambda x. \lambda y. x \ y) (\lambda x. x) 3$	20
4.1.3	Example 3: <code>+ 3 4</code>	21
4.1.4	Example 4: <code>let MY = $\lambda x. + \ x \ 3$</code>	21
4.1.5	Algorithm	22
4.2	Evaluation of Call-by-name	24
4.2.1	Example 1: $(\lambda x. \lambda y. x \ y) (\lambda x. x) \ 3$	25
4.2.2	Example 2: <code>+ 2 (* 3 4)</code>	25
4.2.3	Example 3: <code>let MY = $\lambda x. + \ x \ 3$</code>	26
4.3	fixed-point combinators	27
4.3.1	Weak Head Normal Form	27
4.3.2	strict and lazy fixed-point combinators.	27
4.3.3	Lazy infinite list	29
4.4	Output the evaluation tree	29
4.5	Memory Leaks	29
4.5.1	Callgraphs	31
5	TODO	31

6	Compilation to the Abstract Machine	32
6.1	Example 1: <code>+ 1 2</code>	33
6.2	Example 2. <code>let MY = @x.@y.x y</code>	33
6.3	Tail call	33
6.4	Example 3. <code>let MY = @x.@y.x y</code> with tail call	34
7	TOTO	34
7.1	Compilation and Simulator	34
7.2	Optimization of tail call (BONUS)	34

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1 Introduction

Our goal is the effective implementation of the programming language TLC (Tiny Lambda Calculus) by using the [closure](#).

Lambda calculus is a formal system in mathematical logic and computer science for expressing computation by way of variable binding and substitution (see https://en.wikipedia.org/wiki/Lambda_calculus).

It is computation model of Functional Programming (see L. Paulson's lecture [lambda.pdf](#), or my lecture [lambda_lecture.pdf](#), and try lambda reducer at <http://www.itu.dk/people/sestoft/lamreduce/index.html>).

1.1 Specification of the language LAMBDA

the syntax of TLC can be described as:

```
lines : lines decl
      | decl
      ;
decl  : LET ID '=' expr ';'
      | expr ';'
      ;
expr  : INT
      | ID
      | IF expr THEN expr ELSE expr FI
      | '(' expr ')'
      | '@' ID '.' expr
      | expr expr
      ;
```

where `@x.M` is the abstraction (instead of " λ " in lambda calculus for input). `M N` is the application. and the conditional construct is specially added for the lazy evaluation of the conditional lambda terms. the application is left associative. and the precedence from low to high is: conditional construct, abstraction and application.

see [lexer.1](#) and [grammar.y](#) in detail.

1.2 Abstract syntax trees

We use [De Bruijn index](#) for the AST, it will replace the binding variable by the *binding depth*. Ex. `@x.@y.x` is `@x.@y.2`, `@z.(@y.y(@x.x))(@x.z x)` is `@z.(@y.1(@x.1))(@x.2 1)` (see [Figure 1](#)). It will be the key to access the closure environment in the implementation. the free occurrence of variable is strictly forbidden in TLC.

```
typedef enum {CONST=1, VAR=2, COND=3, ABS=4, APP=5} Node_kind;
```

```
typedef struct Ast {
    Node_kind kind;
    int value; /* for CONST and De Bruijn index */
}
```

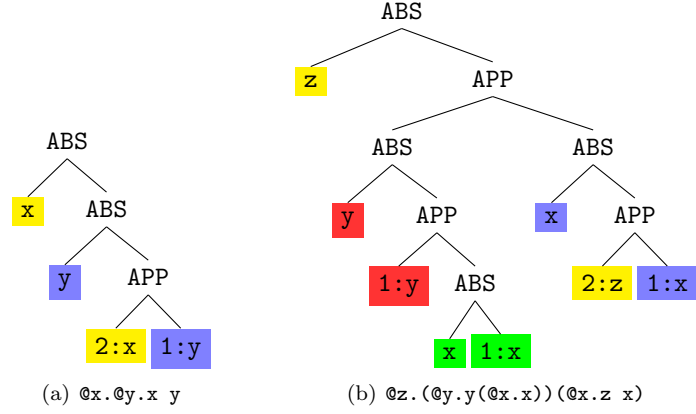


Figure 1: AST with binding depth (the first number of ID node)

```

struct Ast  *lchild, /* for variable name and
                    abstraction variable
                    & apply function  body*/
            *rchild; /* for abstraction body  and app argument*/
struct Ast *cond; /* for condition */
} AST;

```

1.3 Binding Deepth

to find the binding deepth, we use the static stack `char *name_env[MAX_ENV]` with the cursor `int current (tree.c)` to store the abstraction level. each time enter AST with ABS node, we push the abstraction name in the stack, increase `current` for the next, and popup by decreasing `current` after leave the abstraction body. each time a variable encountered in the abstraction body, `find_deepth()` will return the number of the deepth in stack when first occurrence is found, see Figure 2.

```

int find_deepth(char *name)
{
    int i = current - 1;
    while (i + 1) {
        if (strcmp(name, name_env[i]) == 0) return current - i ;
        i--;
    }
    printf("id %s is unbound!\n", name);
    exit (1);
}

```

1.4 Primitive operations

`char *name_env[]` will also store the name of the declaration. so when the following statement is parsed:

```
let I = @x.x;
```

I will stored in `name_env[current]`. and we also store the AST of `@x.x` in the global AST `*ast_env[MAX_ENV]` (all defined in `grammar.y`) for the further uses (typing).

to support the arithmetic operations, `name_env[]` is prestored the following predefined functions:

```
char *name_env[MAX_ENV] = {"+", "-", "*", "/", "=", "<"};
```

to the above binary operators work correctly in λ -calculus, its should interpret as `@x.@y.op x y`, that is prefix notations! so we will write `+ (* 2 3) 4` instead of `2 * 3 + 4`.

the binding deepth is also the key to access the function defined in the declaration. so when I is declared, the `name_env[]` and `ast_env[]` will be

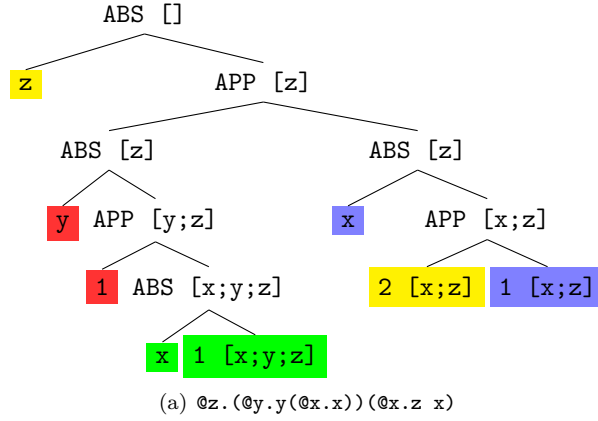


Figure 2: Binding depth

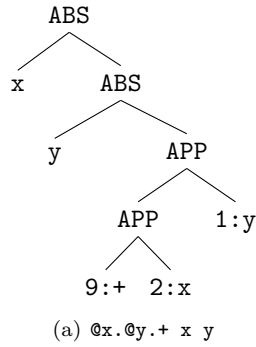


Figure 3: AST of PLUS

```
name_env[MAX_ENV] = {"+", "-", "*", "/", "=", "<", "I"}
ast_env[MAX_ENV] = {NULL, NULL, NULL, NULL, NULL, NULL, @x.(1:x)}
/* AST of operators is not needed for typing */
```

if we declare PLUS by input:

```
let PLUS = @x.@y. + x y;
```

the parser will generate the $(@x.(@y.(((+ : 9)(x : 2))(y : 1))))$. see Figure 3. In fact, after the parser enter the abstraction body $+ x y$, `name_env[]` will be:

```
name_env[MAX_ENV] = {"+", "-", "*", "/", "=", "<", "I", "x", "y"}
```

so `find_depth("+")` will return 9, `find_depth("x")` = 2, and `find_depth("y")` = 1. after finish parsing, `name_env[]` changed to:

```
name_env[MAX_ENV] = {"+", "-", "*", "/", "=", "<", "I", "PLUS"}
```

if we continue define PLUS2 by input:

```
let PLUS = @x.@y + x 2;
```

the parser will generate the $(@x.(@y.(((+ : 10)(x : 2))(y : 1))))$. please remark that the binding depth of $+$ changed to 10 (see Figure 4). this is because the parsing of PLUS2 is based with the new stack top "PLUS" of `name_env[]`, the the relative place of $+$ is increased by 1.

after PLUS2, `name_env[]` changed to:

```
name_env[MAX_ENV] = {"+", "-", "*", "/", "=", "<", "I", "PLUS", "PLUS2"}
```

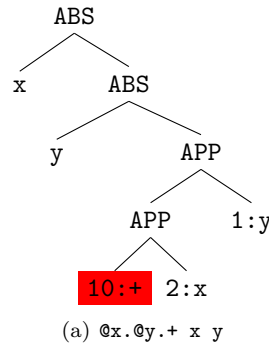


Figure 4: AST of PLUS2

the operators "+", "-", ... must be scanned as normal ID with their binding depth. but "=" is also used as a single character token in the declaration like "let I = ...". we use a global `int is_decl` (defined in `grammar.y`) to tell the lexer if "=" should return '=' or ID, and add a middle action in the `decl` production to active `is_decl`:

```
decl : LET {is_decl = 1; } ID '=' expr ';' {...}
```

deactive each time before return '=' in `lexer.l`:

```
"=" {
    char *id;
    if (is_decl) {is_decl = 0; return '=';}
    id = (char *) malloc(sizeof(char) * (yyleng + 1));
    strcpy(id, yytext);
    yylval = make_string(id);
    return ID;
}
```

1.5 output

We use the L^AT_EX graphic system `tikz/pgf` (<https://sourceforge.net/projects/pgf/>) and `tikz-qtree` (<https://ctan.org/pkg/tikz-qtree>) to illustrate AST. `printtree(AST *)` transforms the AST to L^AT_EX commands and store it in the file `expr.tex` which is the included file of `exptree.tex`. "pdflatex `exptree.tex`" generates the pdf of the AST (see `exptree.pdf`).

2 Typing

Well-typed programs cannot go wrong — Robin Milner

(see https://en.wikipedia.org/wiki/Type_safety)

2.1 Syntax-directed type synthesiser

As we know, if we admit the "x x" in lambda term, this will cause the Russell's paradox (see L. Paulson's lecture "Foundation of Functional Programming" (PP. 23). to avoid this paradox, we can annotate each lambda term with a type, and if such type can't be established, the term will be rejected.

as example, if "x x" the first "x" should be a function type of form "A -> B" (A and B are any sets, we call them *type variables*) if it can be applied by an argument, the second "x" must be the type of the domain of first x, that is A. (see https://en.wikipedia.org/wiki/Simply_typed_lambda_calculus or Pierce's Book "Types and Programming Languages", Ch. 9: Simply Typed Lambda-Calculus, in our `compiler_cd` directory). So the type constraint is the equation of type:

A = A -> B

where A is *type variable* in the type set defined recursively as:

1. type constant `int` is a type.
2. X, Y, Z, \dots , the alphabets of *type variable* are the type.
3. if A and B are any type, then $A \rightarrow B$ is a type. (so $X \rightarrow X, X \rightarrow Y, (X \rightarrow Y) \rightarrow Z, \dots$, are types).

because type variable A appears in right side of the above equation, we have not solution for it.

but the lambda term $(\lambda x.x)(\lambda x.x)$ can be type as $X \rightarrow X$. the first $(\lambda x.x)$ (denoted by **alpha**) can be type as $(A \rightarrow A)$ and the second $(\lambda x.x)$ (denoted by **beta**) can be typed as $(B \rightarrow B)$. for the term "**alpha beta**" have sense, the term **alpha** must have type function with domain $B \rightarrow B$, so the type equation is:

$$A = B \rightarrow B$$

so $A = C \rightarrow C$ and $B = C$ is the solution.

and the *domain* type (left side of the arrow) of **alpha** is $C \rightarrow C$, and the type of $(\lambda x.x)(\lambda x.x)$ is the type of the *range* (right side of the arrow) of **alpha**, so $C \rightarrow C$. Remark the type variable may be changed to any other type.

the above equation has infinite solution like:

```
A = (D -> D) -> (D -> D) and B = D -> D
A = ((D -> D) -> D) -> ((D -> D) -> D) and B = ((D -> D) -> D)
.....
```

but all the above solution can be obtained by the substitution of C in the first solution. the first solution is so called *most general*.

the difference of the above 2 term $(x \ x)$ and $(\lambda x.x)(\lambda x.x)$ is the 2 occurrence of x in the first one are the same x . but the second are not the same.

Our goal is establish the most general type of any given lambda term if it has, or announce the type error if not. the method is *syntax-directed type synthesis*.

2.2 step by step of type synthesis

the type structure is defined in `type.h` as:

```
typedef enum { Typevar = 1, Arrow = 2, Int = 3 } Type_kind;
/* for type tree node */

typedef struct type {
    int index; /* for coding type variable */
    Type_kind kind;
    struct type * left, *right;
} Type;

typedef Type * Type_ptr;

typedef struct type_env{
    int redirect; /* for unification use */
    Type_ptr type; /* pointer to the type tree structure */
} Type_env;

typedef Type_env * Type_env_ptr;

extern Type_ptr global_type_env[MAX_ENV];
/* like name_env[] and ast_env[], global_type_env[]
will store the type for the declared lambda term */
```

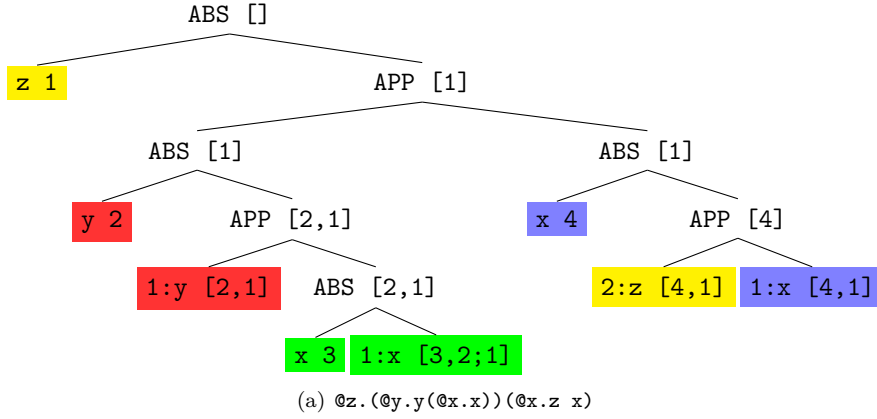


Figure 5: Binding depth for retrieve the type

1. each type variable and arrowtype are coded with a unique index when they are created (see `make_vartype()` and `make_arrowtype()` in `type.c`).
2. store each type tree in the typing environment `Type_env type_env[MAXNODE]` (see `type.c`), and any type of the index `i` will store in `type_env[i]`.
3. with the 1.2 index, the bounded variable in the body of abstraction is represented by the binding depth. to access the corresponding type variable, we can use a stack. like build the AST. each time enter an abstraction body, the corresponding type of the abstraction variable is push to stack, the type of the variable encountered in the body, is just the `n`-th element from the top of the stack, where `n` is the binding depth. in Figure 5, the preorder tree traversal of AST generate a series of new type variable (indexed from 1 to 4 for each abstraction, and push it in the stack when enter the abstraction body. for the `x` in the subterm `@x.x`, the binding depth is 1, so the first element (that's 3) from the top stack `[3,2,1]` (stack top is on the **left**) is the corresponding type. for the `z` in the subterm `@x.z x`, the binding depth is 2, so the second element (that's 1) from the top stack `[4,1]` is the corresponding type.

the stack is implemented by a dynamic list:

```
typedef struct varlist {
    char *var_name;
    struct varlist * next;
} Var_list;
typedef Var_list * Var_list_ptr;
```

4. normally, we should initialize the stack with all elements in `global_type_env[]` of predefined lambda term. it's very heady do to it, if the predefined terms are too many. we split the stack into two parts, the all abstraction of the current term in the dynamic list `Var_list_ptr abs`, and all predefined term in `global_type_env[]` with the top `current - 1` (see 1.3).

Notation: in the following, an entry `type_env[n]` is denoted as `n(redirect, type)`, where `n` is the type index, `redirect` is either `n` or the index of the *redirect* type (see below), `type` is either `n` (type variable), either `int` (type constant), or `(x -> y)` (arrow), like

`1(1, (3 -> 4))`

Example of `type_env[]`

```
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4)]
```

where `3(2,3)` means type variable 3 is *redirect* to 2.

we denote `M == T` if the lambda term `M` has the most general type `T`.

the global environments are setting as:

```

name_env[] = {"+", "-", "*", "/", "=", "<"}
global_type_env[] = [0(int->(int->int)), 1(int->(int->int)), 2(int->(int->int)),
                    3(int->(int->int)), 4(int->(int->int)), 5(int->(int->int))]
current = 6 /* stack top + 1 */

```

the type constant `int` always has the index 0.

Each time typing a lambda term, `type_env[]` will be set to

```

type_env[] = [0(0,int)]
nindex = 1 /* next index for type variable */

```

its can be done by

```

void init_type_env()
{
    int i = 0;

    type_env[0] = &inttype_entry;
    type_env[0] -> type = &inttype;

    while (i < INIT_POS) {
        new_env();
        global_type_env[i] =
            storetype(make_arrowtype( &inttype, make_arrowtype(&inttype, &inttype)));
        /* int -> (int -> int) */
        i++;
    }
    return;
}

```

We will use a serie of the examples to stepwise the typing processus by the **recursive tree traversal** of AST.

2.2.1 Example 1: `@x.@y.x y` (MN: M is a type variable)

The **preorder tree traversal** of AST will compute the stack of abstraction for each AST node. We only setpwise the **postorder traversal** of typing.

step 1

```

top = 8 /* the stack top index = current + lenght(abs) */
abs: [2,1] /* the stack of abstraction */
type_env[] = [0(0,int), 1(1,1), 2(2,2)]
(x:2) |= 1 /* obtain by get 2-th from top of abs */

```

setp 2

```

top = 8:
abs: [2,1]
type_env[] = [0(0,int), 1(1,1), 2(2,2)]
(y:1) |= 2 /* obtain by get 1-th from top of abs */

```

step 3

```

top = 8:
abs: [2,(3 -> 4)]
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4)]
((x:2)(y:1)) |= 4

```

if the term `x y` has sense, the `x` must have the arrow type, but isn't the case. fortunately, `x` is a type variable, it can be change to any type. function `get_instance(Type_ptr)` will do that:


```

Type_ptr get_instance(Type_ptr type_tree)
{
    Type_ptr p = final_type(type_tree);
    /* p must be a no redirect type, see below */
    p -> kind = Arrow;
    p -> left = make_vartype(0, 0);
    p -> right = make_vartype(0, 0);
    return p;
}

```

it rewrites the type of the index 1 to an arrow type. and generate 2 type variables of index 3 and 4. so after `get_instance()`, `x` is changed to type (3 -> 4). and `y` is of type 2. to the application `x y` have the sense, the domain type 2 of `x` and type 3 of `y` **must be** the same. We say they should be *unified*. we can do it simply by changing 3 to 2. but the problem is that all typing environment which refers 3 must be changed to 2. that is hard job (search all `type_env[]`, replacing the index of 3 with 2, just like update the primary key in the database, you must alter all foreign keys that refer the updated primary key)! To simplify this tedious job, we just redirect the entry of 3 in `type_env[]` from itself (3) to 2. so we have 3(2,3) in `type_env[]` where the first component change from 3 to 2 (points to 2). this work can be done by the **side-effect** function `unify_leaf()` (it change the global `type_env[]`!).

```

void unify_leaf(Type_ptr t1, Type_ptr t2)
{
    int index1 = (t1 -> index);
    int index2 = (t2 -> index);

    if (index1 != index2) {
        type_env[index1] -> redirect = index2;
    }
    return;
}

```

a type variable `n(m, t)` in `type_env[]` is called *final* iff `n == m`, ifnot we call it *non-final*. `int final_type()` will across the redirect chain to get the final type. be careful, each time access the type node during the unification process, **you must retrieve the final type**.

```

int final_index (int index)
{
    int i = index;
    if (type_env[i] == NULL) return -1;
    if ( type_env[i] -> type -> kind == Arrow )
        return i;
    if (i == (type_env[i] -> redirect))
        return i;
    return final_index(type_env[i] -> redirect );
}

```

```

/* return final type node for a giving Typevar node */
Type_ptr final_type(Type_ptr t)
{
    int i;
    i = final_index(t -> index);
    if (i == -1) return NULL;
    return type_env[i] -> type;
}

```

step 4

```

top = 7:
abs: [(3 -> 4)]
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4))]
(@y.((x:2)(y:1))) |== (2 -> 4)

```

y is of type 2, and x y is of type 4, the abstraction of @y.x y will be typed as an arrow type with a new generated index 5.

step 5

```
top = 6:
abs: []
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4)),
              6(6,((3 -> 4) -> (2 -> 4)))]
(@x.(@y.((x:2)(y:1)))) == ((3 -> 4) -> (2 -> 4))

printtype(Type_ptr) will recode the final type variable to A - Z, so 2 as A, 4 as B, then output
(@x.(@y.((x:2)(y:1)))) == ((A -> B) -> (A -> B))
```

step 6

```
printtype(Type_ptr) will recode the final type variable to A - Z, so 2 as A, 4 as B, then output
(@x.(@y.((x:2)(y:1)))) == ((A -> B) -> (A -> B))
```

step 7

after the typing process finished, all type that we dynamically allocated must be freed. because every type we made has an index in type_env[], so we can free all of them easily without any memory leak by

```
void new_env(void)
{
    int i;
    for (i = 1; i < nindex; i++) {
        sfree(type_env[i] -> type);
        sfree(type_env[i]);
        /* redefine free as sfree (in emalloc.c) for
           gprofile the call frequencies of free() */
    }
    for (i = 0; i < order; i++)
        index_order [i] = 0;

    nindex = 1;
    order = 1;
    step = 0;
}
```

2.2.2 Example 2: @x.(@x.@y.x y) x (MN: M is arrow and N is type variable)

the first 5 steps are the same as [Example 1](#) with all indexes increased by 1.

step 5

```
top = 7:
abs: [1]
type_env[] = [0(0,int), 1(1,1), 2(2,(4 -> 5)), 3(3,3), 4(3,4), 5(5,5), 6(6,(3 -> 5)),
              7(7,((4 -> 5) -> (3 -> 5)))]
(@x.(@y.((x:2)(y:1)))) == ((4 -> 5) -> (3 -> 5))
```

step 6

```
top = 7:
abs: [1]
type_env[] = [0(0,int), 1(1,1), 2(2,(4 -> 5)), 3(3,3), 4(3,4), 5(5,5), 6(6,(3 -> 5)),
              7(7,((4 -> 5) -> (3 -> 5)))]
(x:1) == 1
```

step 7

```
top = 7:
abs: [1]
type_env[] = [0(0,int), 1(2,1), 2(2,(3 -> 5)), 3(3,3), 4(3,4), 5(5,5), 6(6,(3 -> 5)),
              7(7,((3 -> 5) -> (3 -> 5)))]
((@x.(@y.((x:2)(y:1))))(x:1)) |== (3 -> 5)
```

in this time, the function $((@x.(@y.((x:2)(y:1))))$ of the application is already an arrow type $((4 \rightarrow 5) \rightarrow (3 \rightarrow 5))$ where $(4 \rightarrow 5)$ is of the index 2, the argument is type variable 1, we can just redirect 1 to unify the domain type of the arrow and the argument type. so we have the side-effect $1(2,1)$ in `type_env[]`.

```
void unify_leaf_arrow(Type_ptr leaf, Type_ptr t)
{
    int index = leaf -> index;
    type_env[index] -> redirect = t -> index;
    return;
}
```

step 8

```
top = 6:
abs: []
type_env[] = [0(0,int), 1(2,1), 2(2,(3 -> 5)), 3(3,3), 4(3,4), 5(5,5), 6(6,(3 -> 5)),
              7(7,((3 -> 5) -> (3 -> 5))), 8(8,(1 -> (3 -> 5)))]
(@x.((@x.(@y.((x:2)(y:1))))(x:1))) |== (1 -> (3 -> 5))
```

remark that the domain type 1 of $8(8,(1 \rightarrow (3 \rightarrow 5)))$ is non-final, the redirect final type is $2(2,(3 \rightarrow 5))$. so

step 9

```
(@x.((@x.(@y.((x:2)(y:1))))(x:1))) |== ((A -> B) -> (A -> B))
```

2.2.3 Example 3: $(@x.@y.x\ y)(@x.x)$ (MN: M and N are both arrow)

the first 5 steps is the same as [Example 1](#).

step 5

```
top = 6:
abs: []
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4)),
              6(6,((3 -> 4) -> (2 -> 4)))]
(@x.(@y.((x:2)(y:1)))) |== ((3 -> 4) -> (2 -> 4))
```

step 6

```
top = 7:
abs: [7]
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4)),
              6(6,((3 -> 4) -> (2 -> 4))), 7(7,7)]
(x:1) |== 7
```

step 7

```
top = 6:
abs: []
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4)),
              6(6,((3 -> 4) -> (2 -> 4))), 7(7,7), 8(8,(7 -> 7))]
(@x.(x:1)) |== (7 -> 7)
```

step 8

```

top = 6:
abs: []
type_env[] = [0(0,int), 1(1,(2 -> 4)), 2(7,2), 3(2,3), 4(7,4), 5(5,(2 -> 4)),
              6(6,((2 -> 4) -> (2 -> 4))), 7(7,7), 8(8,(7 -> 7))]
((@x.(@y.((x:2)(y:1))))(@x.(x:1))) |== (2 -> 4)

```

in this time, the argument of function is also function (7 -> 7) which should be unified with (2 -> 4). the unification can be done by unify both domain type and range type of the arrow. `unify(2, 7)` is the case `unify_leaf()` which redirect 2 to 7. `unify(4, 7)` redirect 4 to 7 also.

step 9

```

((@x.(@y.((x:2)(y:1))))(@x.(x:1))) |== (A -> A)

```

2.2.4 Example 4: @x.x x

step 1

```

top = 7:
abs: [1]
type_env[] = [0(0,int), 1(1,1)]
(x:1) |== 1

```

step 2

```

top = 7:
abs: [1]
type_env[] = [0(0,int), 1(1,1)]
(x:1) |== 1

```

step 3

```

top = 7:
abs: [(2 -> 3)]
type_env[] = [0(0,int), 1(1,(2 -> 3)), 2(2,2), 3(3,3)]
((x:1)(x:1)) |== NULL
type A and type (A -> B) can't be unified!

```

the function type is a type variable 1. `get_instance(1)` rewrite to an arrow. the side-effect change the argument type (second x) to the same arrow. `unify(2, 1)` is the case `unify_leaf_arrow(2, 1)`, but if we redirect 2 to 1. but 2 is in type `1(1, (2 -> 3))`. it's not typable this will also cause the cyclic chain of redirection. it is strictly forbidden. `is_occur_node(2, (2 -> 3))` checks if such case. if the occurrence take place, report typing error and return NULL.

```

int is_occur_node(int index, Type_ptr type_tree)
{
    int i = index;
    if (type_tree == NULL) return 1;

    switch (type_tree -> kind) {
    case Typevar:
        return type_env[type_tree -> index] -> redirect == i;
    case Arrow:
        /* left and right may be not final!!! */
        return is_occur_node(i, final_type(type_tree -> left)) ||
               is_occur_node(i, final_type(type_tree -> right));
    case Int:
        return 0;
    }
}

```

2.2.5 Example 5: let MY = @x.@y.x y;

the first 5 steps is the same as [Example 1](#).

step 5

```
top = 6:
abs: []
type_env[] = [0(0,int), 1(1,(3 -> 4)), 2(2,2), 3(2,3), 4(4,4), 5(5,(2 -> 4)),
              6(6,((3 -> 4) -> (2 -> 4)))]
(@x.(@y.((x:2)(y:1)))) |= ((3 -> 4) -> (2 -> 4))
```

step 6

We will store the name MY in `name_env[6]` and the AST `(@x.(@y.((x:2)(y:1))))` in `ast_env[6]`, and the type in `global_type_env[6]`. if the next lambda term refers the MY, we should restore the type of MY in new `type_env[]`. `storetype(Type_ptr t)` will reindex the arrow type with 0 and the final type variable from 1 to n if the type tree has n different leaves.

```
/* generate type_env independant type tree */
Type_ptr storetype(Type_ptr tree)
{
    if (tree == NULL) return;
    switch ( tree -> kind ) {
    case Int: return &inttype;
    case Typevar: {
        int i = final_index(tree -> index);
        Type_ptr t = type_env[i] -> type;
        switch (t -> kind) {
        case Int: return &inttype;
        case Arrow:
            tree -> left = t -> left;
            tree -> right = t -> right;
            break;
        default: {
            int offset = find_index(i); /* reindex the type variable */
            Type_ptr tmp;
            if (offset == 0) {
                return &inttype;
            }
            tmp = (Type_ptr) smalloc(sizeof(Type));
            tmp -> index = offset;
            tmp -> kind = Typevar;
            tmp -> left = tmp -> right = NULL;
            return tmp;
        }
    }
    }
}

{
    Type_ptr tmp = (Type_ptr) smalloc(sizeof(Type));
    tmp -> index = 0;
    tmp -> kind = Arrow;
    tmp -> left = storetype(tree -> left);
    tmp -> right = storetype(tree -> right);
    return tmp;
}
```

so `global_type_env[6] = (1 -> 2) -> (1 -> 2)`, and the cursor `current` for the next abstraction or definition is increased to 7.

2.2.6 Example 6: @x.MY x

it is the same of [Example 2](#), but the subterm ($@x.@y.x\ y$) is predefined. we should access the correct place in `global_type_env[6]` and restore the type of MY in the new `type_env[]`.

step 1

```
top = 8:
abs: [1]
type_env[] = [0(0,int), 1(1,1), 2(2,2), 3(3,3), 4(4,(3 -> 2)), 5(5,(3 -> 2)),
              6(6,((3 -> 2) -> (3 -> 2)))]
(MY:2) |= ((3 -> 2) -> (3 -> 2))
```

MY is of binding depth 2 which is greater than the stack length `abs`, so it is a predefined name. because the `global_env[current - 1]` is the extension of the stack, we can get it by `top - 2`. `get_nth([1], 2, 8)` will restore the type of MY as `6(6,((3 -> 2) -> (3 -> 2)))` with new series of indexes from 2 to 6.

```
Type_ptr get_nth_from_global(int i)
{
    /* if i is the fixed-point combinator, we will
       assign it with the type (A -> A) -> A.
       Z, Y and rec is defined in library.txt */
    if (strcmp(name_env[i], "Z") == 0 ||
        strcmp(name_env[i], "Y") == 0 ||
        strcmp(name_env[i], "rec") == 0) {
        return make_rec_type();
    }
    return restoretype(global_type_env[i]);
    /* restoretype will reindex the type variable in new type_env[] */
}

/* pos is the current top of name_env[] */
/* n is the binding depth of the lambda variable */
Type_ptr get_nth(Var_list_ptr list, int n, int pos)
{
    int i = 0;
    while (i != n - 1 && list != NULL) {
        list = list -> next;
        i++;
    }

    /* is an abstraction */
    if (i == n - 1 && list != NULL)
        return list -> type_var;

    /* is a predefined name */
    if ((pos - n) >= 0)
        return get_nth_from_global(pos - n);

    printf("wrong access global type env\n");
    exit (1);
}
```

the following steps are as [Example 2](#).

step 2

```
top = 8:
abs: [1]
```

```
type_env[] = [0(0,int), 1(1,1), 2(2,2), 3(3,3), 4(4,(3 -> 2)), 5(5,(3 -> 2)),
              6(6,((3 -> 2) -> (3 -> 2)))]
```

```
(x:1) |== 1
```

step 3

```
top = 8:
```

```
abs: [1]
```

```
type_env[] = [0(0,int), 1(5,1), 2(2,2), 3(3,3), 4(4,(3 -> 2)), 5(5,(3 -> 2)),
              6(6,((3 -> 2) -> (3 -> 2)))]
```

```
((MY:2)(x:1)) |== (3 -> 2)
```

step 4

```
top = 7:
```

```
abs: []
```

```
type_env[] = [0(0,int), 1(5,1), 2(2,2), 3(3,3), 4(4,(3 -> 2)), 5(5,(3 -> 2)),
              6(6,((3 -> 2) -> (3 -> 2))), 7(7,(1 -> (3 -> 2)))]
```

```
(@x.((MY:2)(x:1))) |== (1 -> (3 -> 2))
```

step 5

```
(@x.((MY:2)(x:1))) |== ((A -> B) -> (A -> B))
```

2.2.7 Example 7: recursions

the fixed-point combinator (https://en.wikipedia.org/wiki/Fixed-point_combinator) can be pre-defined as

```
let Y=@f.(@x.f(x x))(@x.f(x x));
let Z=@f.(@x.f(@y.(x x)y))(@x.f(@y.(x x)y));
```

because $x\ x$ (apply itself) can't be typable. so if we input:

```
@f.(@x.f(x x))(@x.f(x x));
```

```
typing step 1 and top = 9:
```

```
abs: [2,1]
```

```
type_env[] = [0(0,int), 1(1,1), 2(2,2)]
```

```
(f:2) |== 1
```

```
typing step 2 and top = 9:
```

```
abs: [2,1]
```

```
type_env[] = [0(0,int), 1(1,1), 2(2,2)]
```

```
(x:1) |== 2
```

```
typing step 3 and top = 9:
```

```
abs: [2,1]
```

```
type_env[] = [0(0,int), 1(1,1), 2(2,2)]
```

```
(x:1) |== 2
```

```
type A and type (A -> B) can't be unified!
```

```
typing step 4 and top = 9:
```

```
abs: [(3 -> 4),1]
```

```
type_env[] = [0(0,int), 1(1,1), 2(2,(3 -> 4)), 3(3,3), 4(4,4)]
```

```
((x:1)(x:1)) |== NULL
```

to type the recursive function defined by the fixed-point combinators, we should assign them the type $(A \rightarrow A) \rightarrow A$. so we have:

```
let fact = (Z (@f.@n. (if (= n 0) then 1 else (* n (f (- n 1)) fi))));
```

it will return

```
((Z:1)(@f.(@n.if(((=:7)(n:1))0)then1else(((=:9)(n:1))((f:2)((=:10)(n:1))1))))
|== (int -> int)
```

this can be done in `get_n_th_from_global(int i)` by checking if `name` of a global `i` is `Y`, `Z`, or `rec`. if so, just return the above type.

2.3 Church encoding and Type

In mathematics, Church encoding is a means of representing data and operators in the lambda calculus. The data and operators form a mathematical structure which is embedded in the lambda calculus. The Church numerals are a representation of the natural numbers using lambda notation. The method is named for Alonzo Church, who first encoded data in the lambda calculus this way (https://en.wikipedia.org/wiki/Church_encoding). You can see this encoding in `library.txt`.

1. Church numerals:

```
ZERO |== (A -> (B -> B))
ONE  |== ((A -> B) -> (A -> B))
TWO  |== ((A -> A) -> (A -> A))
.....
FIVE |== ((A -> A) -> (A -> A))
```

2. Arithmetic operation:

```
ADD |== (((((A -> B) -> (C -> A)) -> ((A -> B) -> (C -> B)))
-> (D -> E)) -> (D -> E))
SUB |== (A -> (((((((B -> (C -> B)) -> D) -> ((E -> (D -> F)) -> F)) ->
(((G -> (G -> H)) -> H) -> ((I -> (J -> J)) -> K))) -> ((D -> E) ->
(G -> K))) -> (A -> L)) -> L))
MULT |== (((A -> B) -> ((C -> (D -> D)) -> E)) -> (((((F -> G) -> (H -> F))
-> ((F -> G) -> (H -> G))) -> (A -> B)) -> E))
PRED |== ((((((A -> (B -> A)) -> C) -> ((D -> (C -> E)) -> E)) -> ((F -> (F -> G)) -> G)
-> ((H -> (I -> I)) -> J))) -> ((C -> D) -> (F -> J)))
```

3. Booleans

```
(TRUE:65) |== (A -> (B -> A))
(FALSE:64) |== (A -> (B -> B))
IF |== ((A -> (B -> C)) -> (A -> (B -> C)))
OR |== (((A -> (B -> A)) -> (C -> D)) -> (C -> D))
AND |== ((A -> ((B -> (C -> C)) -> D)) -> (A -> D))
NOT |== (((A -> (B -> B)) -> ((C -> (D -> C)) -> E)) -> E)
GE |== (((((((A -> (B -> A)) -> C) -> ((D -> (C -> E)) -> E)) -> ((F -> (F -> G)) -> G)
-> ((H -> (I -> I)) -> J))) -> ((C -> D) -> (F -> J))) ->
(K -> ((L -> (M -> (N -> N))) -> ((O -> (P -> O)) -> Q)))) -> (K -> Q))
LE |== (A -> (((((((B -> (C -> B)) -> D) -> ((E -> (D -> F)) -> F)) ->
(((G -> (G -> H)) -> H) -> ((I -> (J -> J)) -> K))) -> ((D -> E) -> (G -> K))) ->
(A -> ((L -> (M -> (N -> N))) -> ((O -> (P -> O)) -> Q)))) -> Q))
EQ |== NULL
let LEQ = @m.@n.ISZERO (SUB m n);
LEQ |== (A -> (((((((B -> (C -> B)) -> D) -> ((E -> (D -> F)) -> F)) ->
(((G -> (G -> H)) -> H) -> ((I -> (J -> J)) -> K))) -> ((D -> E) -> (G -> K)))
-> (A -> ((L -> (M -> (N -> N))) -> ((O -> (P -> O)) -> Q)))) -> Q))
let EQ1 = @m.@n. AND (LEQ m n) (LEQ n m);
EQ1 |== NULL
```

EQ and EQ1 can't be typed!

4. Recursions

```
Y |== NULL
Z |== NULL
FACT |== NULL
SUM |== NULL
DIV |= NULL
fact |== (int -> int)
```



```
ACK |== ((((((A -> B) -> (A -> B)) -> C) -> (((((A -> B) -> (A -> B)) -> C) ->
(C -> D)) -> D)) -> (((E -> F) -> (F -> G)) ->
(E -> F) -> (E -> G))) -> H)) -> H)
```

FACT and SUM coding with Church numerals can't be typed, even added the axiom $Y \models (A \rightarrow A) \rightarrow A$. fact with lazy if is typable under the axiom. Ackermann function (https://en.wikipedia.org/wiki/Ackermann_function) is typable.

3 TODO

3.1 Unification algorithm

refer the unification algorithm of Dragon book (PP. 397) finish the side-effect unification algorithm

```
/* return 1 if unified; return 0 ifnot */
int unify(Type_ptr t1, Type_ptr t2)
{
    t1 = simply(t1);
    t2 = simply(t2);
    if (t1 == NULL || t2 == NULL) {
        printf("null type occur! typing error!\n");
        return 0;
    }
    switch (t1 -> kind) {
    case Int: {
        /* todo */
    }
    case Typevar: {
        /* todo */
    }
    case Arrow: {
        /* todo */
    }
    }
    return 1;
}
```

3.2 the semantic rules of type synthesis

each AST T has 3 attributes:

1. T.top := current + abstraction depth
2. T.abs: the stack of the type of the abstraction.
3. T.type: type

the typing will work with the global `type_env[]`, `name_env`, `global_type_env[]`, `nindex`, `current...`

AST	semantic rules
ROOT	ROOT.abs = [] /* empty stack */ ROOT.top = current
T = CONST n	T.type = int
T = VAR (n:x)	T.type = get_nth(T.abs, n, T.top)
T = ABS (x, T1)	x.type = make_vartype() T1.abs = add_list(x.type, T.abs) T.type = make_arrow(x.type, T1.type) T1.top = T.top + 1
T = COND(T1, T2, T3)	T1.abs = T.abs T1.top = T.top T2.abs = T.abs T2.top = T.top T3.abs = T.abs T3.top = T.top if (T1.type == int && unify(T2.type, T3.type)) T.type = T2.type else T.type = NULL
T = APP (T1, T2)	/* todo */ /* you should included this SDD in the file type.c */

3.3 Typing

the attributes T.abs and T.top are L-attributed. T.type is S-attributed. so we can solve them with recursive tree traversal. Implement the following typing function.

```
Type_ptr typing (Var_list_ptr abs, AST *t, int top)
{
    Type_ptr tmp; /* for store the return type */

    if (t == NULL) return NULL;

    switch (t -> kind) {
    case CONST: return make_inttype();
    case VAR: {
        tmp = get_nth(abs, t -> value, top);
        break;
    }

    case ABS: {
        /* todo */
    }

    case COND: {
        /* todo */
    }
    case APP: {
        /* todo */
    }
    }

    if (yyin == stdin) {
        printf("typing step %d and top = %d:\n", ++ step, top);
        print_abs(abs);
        print_env();
        print_expression(t, stdout);
        printf(" |== "); print_type_debug(tmp); printf("\n");
    }
    free_list(abs);
    return tmp;
}
```

Be careful: every recursive call of typing() should pass the copy of abs list by call Var_list_ptr list_copy (Var_list_pt).

3.4 Memory leaks

Your program should have no memory leaks! you can test it by input multiple lines:

```
@m.m(@f.@n.n f(f(@f.@x.f x)))(@n.@f.@x.n f (f x));
```

then `gprof ./lambda`. the difference of `smalloc` and `sfree` should be the same like:

ONE INPUT of the above lambda term:

% time	cumulative seconds	self seconds	calls	self Ts/call	total Ts/call	name
0.00	0.00	0.00	602	0.00	0.00	print_type_debug
0.00	0.00	0.00	268	0.00	0.00	smalloc
0.00	0.00	0.00	226	0.00	0.00	sfree
.....						

TWO INPUT of the above lambda term:

% time	cumulative seconds	self seconds	calls	self Ts/call	total Ts/call	name
0.00	0.00	0.00	1204	0.00	0.00	print_type_debug
0.00	0.00	0.00	470	0.00	0.00	smalloc
0.00	0.00	0.00	428	0.00	0.00	sfree
.....						

please send your `type.c` as attached file to [mailto:hfwang@whu.edu.cn?subject=ID\(05\)](mailto:hfwang@whu.edu.cn?subject=ID(05)) where the ID is your student id number.

4 Evaluation

We will implement an efficient interpreter of lambda calculus by using de Bruijn index and closure environment.

the [closure](#) is first used in [ISWIM](#) (abstract computer programming language devised by Peter J. Landin and first described in his article [The Next 700 Programming Languages](#), published in the Communications of the ACM in 1966. the closure can be abstracted by a pair of `<val, env>` where they are recursively defined as

```
val ::= Int    /* constant */
      | Op c   /* primitive operator and c = +, -, *, /, =, < */
      | (ABS T) * env /* closure: product of AST with node kind ABS, and env */
env ::= [v1; v2; ...; vn] /* env is a list of value */
```

As we know, the β -reduction:

```
(<@x.M> N => M[N/x] /* substitute each occurrence of x in M by N */
```

with the closure environment, we will replace the heavy jobs of substitutions (see `./lambda_ocaml.ml` in detail) by the access of environment:

```
<(<@x.M> N, env)> => <M, N::env> /* N::env is list by add head N in env */
```

if an `x` encountered in the evaluation of `M`, we can get it by the binding depth in `N::env`, just like get the type of an abstraction variable in typing, or like access the local variable via the `offset` in stack runtime environment.

4.1 Evaluation of Call-by-value

the syntax-directed reduction rules are:

1. rule of constant

$$\frac{}{\langle \text{CONST } n, \text{env} \rangle \Rightarrow n} \text{cst}$$

2. rule of variable

$$\frac{}{\langle \text{VAR } n, \text{env} \rangle \Rightarrow v_n} \text{var}$$

where $\text{env} = [v_1; \dots; v_n; \dots; v_p]$.

3. rule of primitive

$$\frac{\text{env} = [n; m; \dots]}{\langle \text{Op } c, n :: m :: \text{env} \rangle \Rightarrow m \ c \ n} \text{op}$$

4. rule of abstraction

$$\frac{}{\langle \text{ABS } T, \text{env} \rangle \Rightarrow (\text{ABS } T, \text{env})} \text{abs}$$

5. rule of application

$$\frac{\langle M, \text{env} \rangle \Rightarrow (\text{@.}M', \text{env}') \quad \langle N, \text{env} \rangle \Rightarrow v' \quad \langle M', v' :: \text{env}' \rangle \Rightarrow v}{\langle \text{APP } M \ N, \text{env} \rangle \Rightarrow v} \text{app}$$

6. rule of condition

$$\frac{\langle C, \text{env} \rangle \Rightarrow n \ (n \neq 0) \quad \langle M, \text{env} \rangle \Rightarrow v}{\langle \text{COND } C \ M \ N, \text{env} \rangle \Rightarrow v} \text{cond}_T \quad \frac{\langle C, \text{env} \rangle \Rightarrow 0 \quad \langle N, \text{env} \rangle \Rightarrow v}{\langle \text{COND } C \ M \ N, \text{env} \rangle \Rightarrow v} \text{cond}_F$$

so if-then-else is lazy evaluated

4.1.1 Example 1: $(\text{@x.}@y.x \ y)(\text{@x.x})$

$$\frac{\frac{\frac{}{\langle \text{@x.}(\text{@y.}((:2)(:1))) \rangle, [] \rangle \Rightarrow (\text{@x.}(\text{@y.}((:2)(:1))) \rangle, [])}{\text{abs}} \quad \frac{\frac{}{\langle \text{@x.}(:1) \rangle, [] \rangle \Rightarrow (\text{@x.}(:1) \rangle, [])}{\text{abs}}}{\frac{\langle \text{@y.}((:2)(:1))) \rangle, [(\text{@.}(:1))] \rangle \Rightarrow \langle (\text{@.}((:2)(:1))) \rangle, [(\text{@.}(:1), [])] \rangle}{\text{abs}}} \frac{}{\langle (\text{@.}(\text{@.}((:2)(:1))) \rangle(\text{@.}(:1))) \rangle \Rightarrow \langle (\text{@.}((:2)(:1))) \rangle, [(\text{@.}(:1), [])] \rangle} \text{app}$$

4.1.2 Example 2: $(\text{@x.}@y.x \ y)(\text{@x.x})3$

Let $\text{my} = (\text{@x.}@y.x \ y)(\text{@x.x})$ in the following reduction tree.

$$\frac{\frac{\frac{}{\langle \text{my}, [] \rangle \Rightarrow \langle (\text{@.}((:2)(:1))) \rangle, [(\text{@.}(:1), [])] \rangle} \text{ex1} \quad \frac{\frac{}{\langle 3, [] \rangle \Rightarrow 3} \text{cst}}{\frac{}{\langle (:2)(:1) \rangle, [3; (\text{@.}(:1), [])] \rangle \Rightarrow 3} \text{app}}} \frac{\frac{\frac{}{\langle (:2) \rangle, [3; (\text{@.}(:1), [])] \rangle \Rightarrow (\text{@.}(:1), [])} \text{var} \quad \frac{\frac{}{\langle (:1) \rangle, [3; (\text{@.}(:1), [])] \rangle \Rightarrow 3} \text{var}}{\frac{}{\langle (:1) \rangle, [3] \rangle \Rightarrow 3} \text{var}}} \frac{}{\langle (\text{@x.}@y.x \ y)(\text{@x.x})3, [] \rangle \Rightarrow 3} \text{app}$$

4.1.3 Example 3: + 3 4

like typing, we divide the closure environment in two parts (static + dynamic), the static parts store pre-evaluated closure of the primitives and predefined terms (CLOSURE *global_eval_env[MAX_ENV]). it's initialized as

```
global_eval_env = [(0.(0p +), []); (0.(0p -), []); (0.(0p *), []);
                  (0.(0p /), []); (0.(0p =), []); (0.(0p <), [])]
```

we can access the static part with the index `top - n` (`n` is binding depth), and `top` can be calculated by `current + length(env)`. for example, `<(:6), []>` in the following reduction tree, `current` is 6, `length([]) = 0`, so the rule `var` will return `global_eval_env[0]`.

$$\frac{}{\langle (:6), [] \rangle \Rightarrow (0.(0p +), [])} \text{ var}$$

hence

$$\frac{\frac{\frac{}{\langle (:6), [] \rangle \Rightarrow (0.(0p +), [])} \text{ var} \quad \frac{\frac{}{\langle 1, [] \rangle \Rightarrow 1} \text{ cst} \quad \frac{}{\langle (0.(0p +)), [1] \rangle \Rightarrow ((0.(0p +)), [1])} \text{ abs}}{\langle (:6)1, [] \rangle \Rightarrow ((0.(0p +)), [1])} \text{ app} \quad \frac{\frac{}{\langle 2, [] \rangle \Rightarrow 2} \text{ cst} \quad \frac{}{\langle (0p +), [2; 1] \rangle \Rightarrow 3} \text{ op}}{\langle ((:6)1)2, [] \rangle \Rightarrow 3} \text{ app}$$

4.1.4 Example 4: let MY = @x.+ x 3

firstly, `@x.+ x 3` is evaluated, then store in `global_eval_env[7]`, if `current = 7`, then increase `current` to 8.

$$\frac{}{\langle @x.(((+ :7)(x :1))3), [] \rangle \Rightarrow \langle @x.(((+ :7)(x :1))3), [] \rangle} \text{ abs}$$

if we input `MY 4`; the return result is 12, isn't 7. what's wrong? let's look the detail of reduction tree:

$$\frac{\frac{\frac{\frac{}{\langle (:7), [4] \rangle \Rightarrow (0.(0p +), [])} \text{ var} \quad \frac{\frac{}{\langle (:1), [4] \rangle \Rightarrow 4} \text{ cst} \quad \frac{}{\langle (0p -), [4] \rangle \Rightarrow (0.(0p *), [4])} \text{ abs}}{\langle (:7)(:1), [4] \rangle \Rightarrow (0.(0p *), [4])} \text{ app} \quad \frac{\frac{}{\langle 3, [4] \rangle \Rightarrow 3} \text{ cst} \quad \frac{}{\langle (0p *), [3; 4] \rangle \Rightarrow -1} \text{ op}}{\langle ((:7)(:1))3, [4] \rangle \Rightarrow 12} \text{ app} \quad \frac{}{\langle (:1), [] \rangle \Rightarrow (0.(((:7)(:1))3), [])} \text{ var} \quad \frac{}{\langle 4, [] \rangle \Rightarrow 4} \text{ cst}}{\langle (:1)4, [] \rangle \Rightarrow -1} \text{ app}$$

`current = 8` and `length([]) = 0`, so `global_eval_env[8 - 1]` get perfectly newly stored `MY` pre-evaluated closure.

$$\frac{}{\langle (:1), [] \rangle \Rightarrow (0.(((:7)(:1))3), [])} \text{ var}$$

but in `<(:7), [4]>`, `length([4]) = 1`, so `top = 9` and `global_eval_env[9 - 7]` got `(0.(0p *), [])`

$$\frac{}{\langle (:7), [4] \rangle \Rightarrow (0.(0p *), [])} \text{ var}$$

it's because that we use **wrong** `current` for `MY`. In fact, the environment of `MY` is

```
[4; global_eval_env[5]; global_eval_env[4]; ...; global_eval_env[0]]
```

so `current` for `MY` is `index - 1` where `index` is the index we store `MY` in the global environment `global_eval_env[index]`, so is 6 and hence the real `top` is `6 + 1` and `global_eval_env[7 - 7]` got the correct `0p +`.

so we should store each `current` in the closure environment at name declaration time. like `(@x.(((+ :7)(x :1))3), [], 7)` to indicate the proper static continuation of environment of `MY` which begins at `global_eval_env[7 - 1]`. After declaration of `MY`, `global_eval_env[]` is

And the new reduction rules are:

- $$\frac{}{\langle \text{CONST } n, \text{env}, i \rangle \Rightarrow n} \text{cst}$$

- $$\overline{\langle \text{VAR } n, \text{env}, i \rangle \Rightarrow \text{vn}}^{\text{var}}$$

$$\frac{\text{env}=[n; m; \dots]}{\langle 0p \ c, n::m::\text{env}, i \rangle \Rightarrow m \ c \ n} \text{op}$$

- $$\frac{}{\langle \text{ABS } T, \text{env}, i \rangle \Rightarrow (\text{ABS } T, \text{env}, i)} \text{abs}$$

- $$\frac{\langle M, \text{env}, i \rangle \Rightarrow (\text{@.}M', \text{env}', \mathbf{i}') \quad \langle N, \text{env}, i \rangle \Rightarrow v \quad \langle M', v'::\text{env}', \mathbf{i}' \rangle \Rightarrow v}{\langle \text{APP } M \ N, \text{env}, i \rangle \Rightarrow v} \text{app}$$

- $$\frac{\langle C, \text{env}, i \rangle \Rightarrow n \text{ (no 0)} \quad \langle M, \text{env} \rangle \Rightarrow v}{\langle \text{COND } C \text{ } M \text{ } N, \text{env}, i \rangle \Rightarrow v} \text{cond}_T \quad \frac{\langle C, \text{env}, i \rangle \Rightarrow 0 \quad \langle N, \text{env} \rangle \Rightarrow v}{\langle \text{COND } C \text{ } M \text{ } N, \text{env}, i \rangle \Rightarrow v} \text{cond}_F$$

	var	cst	abs
<(:7), [4], 6>=>(0, (0, (0p +)), [], 1)	<(:1), [4], 6>=>4	<0, (0p +), [4], 1>=>(0, (0p +), [4], 1)	
	app	cst	op
<(:7) (:1), [4], 6>=>(0, 0p *, [4], 1)	<3, [4], 6>=> 3	<(0p +), [3;4], 1>=>7	app
<(:1), [], 7>=>(0, ((((:7) (:1)) 3), [], 6)	<4, [], 7>=>4	<(((:7) (:1)) 3), [4], 6>=>7	app
<(:1) 4, [], 7>=>7			

```
typedef struct Closure_list CLOSURE_LIST;
```

and `get_nth()` in typing is rewritten as

```
CLOSURE *get_global(int i)
{
    return clone_clos( (global_eval_env[i]));
    /* always get the copy of env */
}

CLOSURE *get_argument(int n, CLOSURE_LIST *env, int index)
{
    int i = 0;
    while ( i != n -1 && env != NULL ) {
        env = env -> next;
        i ++;
    }

    if (i == n - 1 && env != NULL) return clone_clos(env -> clos);
    /* always get the copy of env */

    if (index - (n - i) >=0 ) return get_global(index - n + i );
    /* index + i is top of stack is relative top */
    printf("wrong access closure env\n");
    exit (1);
}
```

You should always work with its proper environment with the following duplicate function

```
CLOSURE *clone_clos(CLOSURE *source)
{
    if (source == NULL) return NULL;
    return make_clos(clone_tree(source -> ast),
                     clone_list(source -> env),
                     source -> index);
}

CLOSURE_LIST *clone_list(CLOSURE_LIST *source)
{
    if (source == NULL) return NULL;
    return make_list(clone_clos(source -> clos), clone_list(source -> next));
}
```

so the recursive evaluation of call-by-value

```
CLOSURE *eval_cbv(CLOSURE *clos)
{
    /* always make new return clos and free the evaluated clos */
    AST *exp = clos -> ast;
    CLOSURE_LIST *env = clos -> env;
    CLOSURE *result;
    int index = clos -> index;
    step++;
    switch (exp -> kind) {
    case CONST:
        free_list(env);
        clos -> env = NULL;
        return clos;
    case VAR:
        if (exp -> value <= 0) {
            result = cbv_primitive (clos);
            return result;
        }
    }
```

```

    }
    result = get_argument(exp -> value, env, index);
    free_clos(clos);
    return (result);
case ABS:
    return (clos);
case COND: {
    /* todo */
}
default: { /* APP */
    /* todo */
    /* for (APP M N),
       1/ eval(M, env, index) to (@.M', env', index')
       2/ eval(N, env, index) to N'
       3/ return eval(M', N'::env, index')
    */
}
}
}
}

```

4.2 Evaluation of Call-by-name

for evaluate APP(M N) in normal order evaluation, N will delay as **thunk**, a closure like (N, []). But it's question where it is put in the our closure environment? Because it's outmost order, and it's inverse order of the binding deepth! we can't direct put it in the closure of M. so we need an extra stack to store the thunk, and for each abstraction, put it back to the closure.

```

<(((@.@.@.M)N1)N2)N3, [], []> /* third is stack for thunk */
=> <(((@.@.@.M)N1)N2, [], [(N3, [])])>
=> <(@.@.@.M)N1, [], [(N2, []); (N3, [])]>
=> <@.@.@.M, [], [(N1, []); (N2, []); (N3, [])]>
=> <@.@.M, [(N1, [])], [(N2, []); (N3, [])]>
=> <@.M, [(N2, []); (N1, [])], [(N3, [])]>
=> <M, [(N3, []); (N2, []); (N1, [])], []>

```

so we can correct access the closure environment with binding depth in M

the news closure environment for is recursively defined as

```

val -> Int    /* constant */
    | Op c    /* primitive operator and c = +, -, *, /, =, < */
    | T * env /* product of any AST T and env */
env -> [v1; v2; ...; vn] /* env is a list of value */
stack -> env /* stack for thunk */

```

the reduction of call-by-name is

1. rule of constant

$$\frac{}{\langle \text{CONST } n, \text{env}, \text{stack} \rangle \Rightarrow n} \text{cst}$$

2. rule of variable

$$\frac{\langle \text{tn}, \text{en}, \text{stack} \rangle \Rightarrow v}{\langle \text{VAR } n, \text{env}, \text{stack} \rangle \Rightarrow v} \text{var}$$

where env=[v1;...;(tn,en);...;vp].

3. rule of primitive

$$\frac{\langle t1, e1, [] \rangle \Rightarrow n \quad \langle t2, e2, [] \rangle \Rightarrow m}{\langle 0p \ c, (t1, e1)::(t2, e2)::env \rangle \Rightarrow m \ c \ n} \text{op}$$

4. rule of abstraction

$$\frac{\langle T, s::env, stack \rangle \Rightarrow v}{\langle ABS \ T, env, s::stack \rangle \Rightarrow v} \text{ abs}$$

5. rule of application

$$\frac{\langle M, N, (N, \text{env}) :: \text{stack} \rangle \Rightarrow v}{\langle \text{APP } M \ N, \text{env}, \text{stack} \rangle \Rightarrow v} \text{app}$$

6. rule of condition

$$\frac{\frac{\langle C, \text{env}, \text{stack} \rangle \Rightarrow n \ (n \neq 0) \quad \langle M, \text{env}, \text{stack} \rangle \Rightarrow v}{\langle \text{COND } C \ M \ N, \text{env}, \text{stack} \rangle \Rightarrow v} \text{cond}_T}{\frac{\langle C, \text{env}, \text{stack} \rangle \Rightarrow 0 \quad \langle N, \text{env}, \text{stack} \rangle \Rightarrow v}{\langle \text{COND } C \ M \ N, \text{env}, \text{stack} \rangle \Rightarrow v} \text{cond}_F}$$

so `if-then-else` is lazy evaluated

4.2.1 Example 1: $(@x.@y.x\ y)(@x.x)\ 3$

$$\begin{array}{c}
\text{cst} \\
\hline
\langle 3, [], [] \rangle \Rightarrow 3 \\
\hline
\text{var} \\
\langle (:1), [(3, []); (@. (:1), [])], [] \rangle \Rightarrow 3 \\
\hline
\text{var} \\
\langle (:1), [((:1), [(3, []); (@. (:1), [])]), []] \rangle \Rightarrow 3 \\
\hline
\text{abs} \\
\langle @. (:1), [], [((:1), [(3, []); (@. (:1), [])])] \rangle \Rightarrow 3 \\
\hline
\text{var} \\
\langle (:2), [(3, []); (@. (:1), [])], [\langle (:1), [(3, []); (@. (:1), [])] \rangle] \rangle \Rightarrow 3 \\
\hline
\text{app} \\
\langle (:2) (:1), [(3, []); (@. (:1), [])], [] \rangle \Rightarrow 3 \\
\hline
\text{abs} \\
\langle @. ((:2) (:1)), [(@. (:1), [])], [(3, [])] \rangle \Rightarrow 3 \\
\hline
\text{abs} \\
\langle @. (@. ((:2) (:1))), [], [(@. (:1), []); (3, [])] \rangle \Rightarrow 3 \\
\hline
\text{app} \\
\langle (@. (@. ((:2) (:1)))) (@. (:1)), [], [(3, [])] \rangle \Rightarrow 3 \\
\hline
\text{app} \\
\langle (@. (@. ((:2) (:1)))) (@. (:1)) 3, [], [] \rangle \Rightarrow 3
\end{array}$$

4.2.2 Example 2: + 2 (* 3 4)

like CBV, we divide the closure environment in two parts (static + dynamic), the static parts store evaluated closure of the primitives and predefined terms (`CLOSURE *global_eval_env[MAX_ENV]`). it's initialized as same as CBV

```
global_eval_env = [(('@. (@p +)', []), (@. (@p -)', []), (@. (@p *)', []),
                    (@. (@p /)', []), (@. (@p =)', []), (@. (@p <)', [])]
```

our implementation will use a commnad option (-v, choose CBV, default is CBN) to fix the strategie of the evaluation. it can't be changed during the execution of the interpreter.

$$\begin{array}{c}
\frac{}{<4, [], []>=4} \text{cst} \quad \frac{}{<3, [], []>=3} \text{cst} \\
\frac{}{<(Op \ *) , [<4, [], 6> ; <3, [], 6>] , []>=12} \text{op} \\
\frac{}{<(@. (Op \ *)) , [<3, [], 6>] , [<4, [], 6>]>=<12, [], 0>} \text{abs} \\
\frac{}{<(@. (@. (Op \ *))) , [], [<3, [], 6> ; <4, [], 6>]>=<12, [], 0>} \text{abs} \\
\frac{}{<(:4) , [], [<3, [], 6> ; <4, [], 6>]>=<12, [], 0>} \text{var} \\
\frac{}{<((:4)3) , [], [<4, [], 6>]>=<12, [], 0>} \text{app} \\
\frac{}{<(((:(4)3)4) , [], []>=<12, [], 0>} \text{app} \quad \frac{}{<2, [], []>=2} \text{cst} \\
\frac{}{<(Op \ +) , [<(((:(4)3)4) , [], 6> ; <2, [], 6>] , []>=14} \text{op} \\
\frac{}{<(@. (Op \ +)) , [<2, [], 6>] , [<(((:(4)3)4) , [], 6>]>=<14, [], 0>} \text{abs} \\
\frac{}{<(@. (@. (Op \ +))) , [], [<2, [], 6> ; <(((:(4)3)4) , [], 6>]>=<14, [], 0>} \text{abs} \\
\frac{}{<(:6) , [], [<2, [], 6> ; <(((:(4)3)4) , [], 6>]>=<14, [], 0>} \text{var} \\
\frac{}{<((:6)2) , [], [<(((:(4)3)4) , [], 6>]>=<14, [], 0>} \text{app} \\
\frac{}{<(((:(6)2) (((:(4)3)4)) , [], []>=<14, [], 0>} \text{app}
\end{array}$$

4.2.3 Example 3: let MY = @x.+ x 3

like CBV, we coded OP +, ..., OP < with VAR (:0), ..., VAR (-5). and add index (defined in ??) in closure. and the new rules are:

1. rule of constant

$$\frac{}{<CONST \ n , \ env , \ stack , \ i> \Rightarrow \ n} \text{cst}$$

2. rule of variable

$$\frac{<tn, en, stack, \textcolor{red}{i}'> \Rightarrow v}{<VAR \ n , \ env , \ stack , \ i> \Rightarrow v} \text{var}$$

where env=[v1; ...; (tn, en, i'); ...; vp].

3. rule of primitive

$$\frac{<t1, e1, i1,> \Rightarrow n \quad <t2, e2, [], i2> \Rightarrow m}{<Op \ c , \ (t1,e1,i1)::(t2,e2,i2)::env> \Rightarrow m \ c \ n} \text{op}$$

4. rule of abstraction

$$\frac{<T, s::env, stack, i> \Rightarrow v}{<ABS \ T , \ env , \ s::stack , \ i> \Rightarrow v} \text{abs}$$

5. rule of application

$$\frac{<M, N, (N,env,i)::stack, i> \Rightarrow v}{<APP \ M \ N , \ env , \ stack , \ i> \Rightarrow v} \text{app}$$

6. rule of condition

$$\frac{<C, env, stack, i> \Rightarrow n \ (!= \ 0) \quad <M, env, stack, i> \Rightarrow v}{<COND \ C \ M \ N , \ env , \ stack , \ i> \Rightarrow v} \text{cond}_T \\
\frac{<C, env, stack, i> \Rightarrow 0 \quad <N, env, stack, i> \Rightarrow v}{<COND \ C \ M \ N , \ env , \ stack , \ i> \Rightarrow v} \text{cond}_F$$

for `let MY = @x. + x 3`, we preevaluate `@x. + x 3`,

`<@.(((+:7)(:1))3), [], [], 6>=>(<@x.(((+:7)(:1))3), [], 6)`

where `VAR (:0)` refers `(OP +)` and `current` is 6. then store the closure `(@x.(((+:7)(:1))3), [], 6)` in `global_eval_env[6]` and increased `current` to 7. with the `index 6`, we can perfectly access the environment of `MY`, if input: `MY 4`;

$$\begin{array}{c}
\frac{}{cst} \quad \frac{}{cst} \quad \frac{}{var} \\
\frac{}{cst} \quad \frac{}{var} \\
\frac{}{op} \\
\frac{}{abs} \\
\frac{}{abs} \\
\frac{}{var} \\
\frac{}{app} \\
\frac{}{app} \\
\frac{}{abs} \\
\frac{}{var} \\
\frac{}{app}
\end{array}$$

4.3 fixed-point combinators

4.3.1 Weak Head Normal Form

with CBV or CBN, we stop the evaluation if the AST top of the lambda term is an abstraction (weaker than Weak Head Normal Form (https://en.wikipedia.org/wiki/Lambda_calculus_definition#Normal_form)). so for `(@x.(@x.x)x)` isn't evaluated:

```

(@x.(@x.x)x);
(@x.((@x.(x:1))(x:1))) == (A -> A)
(@x.((@x.(x:1))(x:1))) => (@x.((@x.(x:1))(x:1)))
>>> step = 1

```

and if there is an argument 1 for the above term, both CBV and CBN will return the normal form. for CBV,

```

((@x.((@x.(x:1))(x:1)))1) == int
((@x.((@x.(x:1))(x:1)))1) => 1
>>> step = 7

```

4.3.2 strict and lazy fixed-point combinators.

with those strategies, we can predefined the fixed-point combinators without any risk of the infinite loop of the preevaluation:

```

let Y=@f.(@x.f(x x))(@x.f(x x)); /* lazy fixed-point combinator */
let Z=@f.(@x.f(@y.(x x)y))(@x.f(@y.(x x)y)); /* strict fixed-point combinator */

```

even the Church's numeral function with no lazy `IF` and `Z` can be predefined (see the definition in [library.txt](#)):

```

let FACT = Z (@f.@n.IF (ISZERO n) ONE (MULT n (f (PRED n))));

```

BUT CBV works only with our lazy if-then-else-fi and strict Z.

```

let fact = Z (@f.@n. (if (= n 0) then 1 else (* n (f (- n 1))) fi));
>>> (fact:1) |== (int -> int)
fact 10;
((fact:1)10) |== int
((fact:1)10) => 3628800
>>> step = 332

```

because the evaluation of $Y\ M$ (M is any term) will go infinite loop in CBV, we can't predefine any recursive function with Y as fixed-point combinator, like :

```

let fact = Y (@f.@n. (if (= n 0) then 1 else (* n (f (- n 1))) fi));

>>>((:19)(@.(@.(((64)((39)(:1)))(:45))(((36)(:1))((:2)((40)(:1)))))))
please input a lambda term with ";":

```

Program received signal SIGSEGV, Segmentation fault.
0xb7e7a7e7 in _int_malloc (av=av@entry=0xb7fb1420 <main_arena>, bytes=bytes@entry=20) at malloc.c:2913

Y and Z , even Church no-lazy IF work fine in CBN:

```

fact 10; /* Z */
((fact:1)10) => 3628800
>>> step = 1249

```

```

let fact = (Y (@f.@n. (if (= n 0) then 1 else (* n (f (- n 1))) fi)));
fact 10; /* lazy Y */
((fact:1)10) => 3628800
>>> step = 1129 /* fewer steps than Z */

```

```

let FACT=Y (@f.@n.IF (ISZERO n) ONE (MULT n (f (PRED n)))); /* Church IF */
>>> ((Y:19)(@f.(@n.(((IF:64)((ISZERO:39)(n:1)))(ONE:45))(((MULT:36)(n:1))((f:2)
>>> ((PRED:40)(n:1))))))) |== NULL

```

```

/* Church numeral factorial */
FACT TWO (@x.+x 1) 0;
(((FACT:1)(THREE:42))(@x.(((+77)(x:1))1)))0 |== NULL
(((FACT:1)(THREE:42))(@x.(((+77)(x:1))1)))0 => 2
>>> step = 1141
/* FACT TWO return the closure of @f.@x.f(f x). so FACT TWO (@x.+x 1) 0
return 2 */

```

```

FACT THREE (@x.+x 1) 0;
(((FACT:1)(THREE:42))(@x.(((+77)(x:1))1)))0 |== NULL
(((FACT:1)(THREE:42))(@x.(((+77)(x:1))1)))0 => 6
>>> step = 6681 /* wait 2 minutes! */

```

```

let FACT=Z (@f.@n.IF (ISZERO n) ONE (MULT n (f (PRED n))));
((Z:20)(@f.(@n.(((IF:66)((ISZERO:41)(n:1)))(ONE:47))(((MULT:38)(n:1))((f:2)
((PRED:42)(n:1))))))) |== NULL

```

```

FACT TWO (@x.+x 1) 0;
(((FACT:1)(TWO:45))(@x.(((+79)(x:1))1)))0 |== NULL
>>> (((FACT:1)(TWO:45))(@x.(((+79)(x:1))1)))0 => 2

```

```

FACT THREE (@x.+x 1) 0;
>>> (((FACT:1)(THREE:42))(@x.(((+77)(x:1))1)))0 |== NULL
killed /* memory exhausted */

```

So the CBN is inefficient, and Y is more efficient than Z in CBN. in real world of functional programming language, we can't use this CBN.

1. mutual recursion.

```
let EVEN = @f.@g.@n.if (= n 0) then 1 else g (- n 1) fi;
let ODD = @f.@g.@n.if (= n 0) then 0 else f (- n 1) fi;

let ev =Z(@f.@n.EVEN f (Z(@g.@n.ODD (Z(@f.@n.EVEN f g n)) g n)) n);
let od = Z(@g.@n. ODD (Z(@f.@n.EVEN f g n)) g n);

ev 6;
((ev:2)6) |== int
((ev:2)6) => 1
>>> step = 394
```

4.3.3 Lazy infinite list

Because the preevaluation of FIBOGEN ZERO ONE in CBV will go infinite loop, We add an abstraction in the definition of FIBO (see [library.txt](#)). You should redefine as `let FIBO = FIBOGEN ZERO ONE` in CBN mode. `GETN NUM FIBO (@x.+x 1) 0` will retrieve the NUM-th element of the infinite Fibonacci sequence.

```
let FIBO=FIBOGEN ZERO ONE;
GETN THREE FIBO (@x.+x 1) 0;
((((GETN:12)(THREE:40))(FIBO:9))(@x.(((+:70)(x:1))1)))0) |== NULL
((((GETN:14)(THREE:42))(FIBO:1))(@x.(((+:77)(x:1))1)))0) => 2
step = 1406
```

4.4 Output the evaluation tree

Our sample program `./lambda` is compiled under UBUNTU X64. it can output the evaluation tree to L^AT_EX source file `evaltree.tex` (in proofree format, [proofree.sty](#) included). You can `pdflatex eval_a31.tex` (A3 paper landscape) or `pdflatex eval_a41.tex` (A4 paper landscape) to generate the pdf file (both in CBV and CBN mode).

Because the limitation of [proofree.sty](#), we only trace the first 50 steps of the evaluations. and the evaluation of large steps can cause `pdflatex` error.

4.5 Memory Leaks

We can gprofile the memory leaks:

1. CBN

```
$ ./lambda
SUM TWO (@x.+ x 1) 0;
>>> 3
>>> step = 611
CTRL+D
$ gprof ./lambda
% cumulative self self total
time seconds seconds calls ms/call ms/call name
31.25 0.05 0.05 356729 0.00 0.00 free_ast
15.62 0.07 0.03 356729 0.00 0.00 free_clos
12.50 0.10 0.02 4309502 0.00 0.00 smalloc
12.50 0.12 0.02 1398179 0.00 0.00 make_app
12.50 0.14 0.02 356747 0.00 0.00 free_list
6.25 0.14 0.01 3588583 0.00 0.00 make_ast
6.25 0.15 0.01 356542 0.00 0.00 clone_tree
3.12 0.16 0.01 356781 0.00 0.00 clone_list
0.00 0.16 0.00 4306063 0.00 0.00 sfree
.....
```

```

$ ./lambda
SUM THREE (@x.+ x 1) 0;
>>> 6
>>> step = 1390
CTRL+D
$ gprof ./lambda
Each sample counts as 0.01 seconds.
%   cumulative   self           self       total
time  seconds  seconds   calls   s/call   s/call   name
24.83    0.73    0.73  6772543    0.00    0.00  clone_tree
19.05    1.29    0.56  6772966    0.00    0.00  free_ast
 9.52    1.57    0.28 69207383    0.00    0.00  make_ast
 7.82    1.80    0.23  6772999    0.00    0.00  free_list
 6.80    2.00    0.20  6773015    0.00    0.00  clone_list
 5.44    2.16    0.16 82760466    0.00    0.00  smalloc
 5.44    2.32    0.16 27044285    0.00    0.00  make_app
 5.27    2.48    0.15  6772543    0.00    0.00  clone_clos
 4.42    2.60    0.13 82757027    0.00    0.00  sfree
.....

```

so smalloc - sfree is constant

2. CBV

```

$ ./lambda -v
fact 5;
>>> 120
>>> step = 172
CTRL+D
$ gprof ./lambda
%   cumulative   self           self       total
time  seconds  seconds   calls  ms/call  ms/call   name
 0.00    0.00    0.00   25555    0.00    0.00  smalloc
 0.00    0.00    0.00   21119    0.00    0.00  sfree
 0.00    0.00    0.00   15718    0.00    0.00  make_ast
.....

```

```

$ ./lambda -v
fact 10;
>>> 3628800
>>> step = 332
CTRL+D
$ gprof ./lambda
%   cumulative   self           self       total
time  seconds  seconds   calls  ms/call  ms/call   name
 0.00    0.00    0.00   33665    0.00    0.00  smalloc
 0.00    0.00    0.00   29229    0.00    0.00  sfree
 0.00    0.00    0.00   22448    0.00    0.00  make_ast
 0.00    0.00    0.00    8670    0.00    0.00  make_var
.....

```

so smalloc - sfree is also constant.

You can also use valgrind (<http://valgrind.org>) to check the memory leaks, like:

```

~$ valgrind --leak-check=full ./lambda
Call by NAME mode!!!
please input a lambda term with ";":
let Y=@f.(@x.f(x x))(@x.f(x x));

```

```

please input a lambda term with ";":
let facty = (Y(@f.@n. (if (= n 0) then 1 else (* n (f (- n 1))) fi)));

abs: []
type_env[] = [0(0,int), 1(1,(int -> int))]
((facty:1)3) |= int
((facty:1)3) |= int
((facty:1)3) => 6
>>> step = 170

please input a lambda term with ";":
CTRL+D
.....

==3263== LEAK SUMMARY:
==3263==    definitely lost: 112 bytes in 6 blocks
==3263==    indirectly lost: 48 bytes in 3 blocks
==3263==    possibly lost: 0 bytes in 0 blocks
==3263==    still reachable: 22,380 bytes in 146 blocks
==3263==    suppressed: 0 bytes in 0 blocks
==3263== Reachable blocks (those to which a pointer was found) are not shown.
==3263== To see them, rerun with: --leak-check=full --show-leak-kinds=all
==3263==
==3263== For counts of detected and suppressed errors, rerun with: -v
==3263== ERROR SUMMARY: 5 errors from 5 contexts (suppressed: 0 from 0)

```

if we rerun it with facty 7, valgrind will summary the same results.

4.5.1 Callgraphs

to visualize the gprof data, you can use `./gprof2dot` (a python script) (<http://code.google.com/p/jrfonseca/wiki/Gprof2Dot>) to transfer the gprof data to graphviz file(.dot), then visualize with dotty.

```

~$ ./lambda
.....
CTRL+D

~$ gprof ./macro |./gprof2dot.py -c gray|dot -Tpdf -o profile.pdf

see profile.pdf for detail.
you can also visualize the callgraph by valgrind like:

~$ valgrind --tool=callgrind --dump-before=main ./lambda
.....
CTRL+D

~$ ./gprof2dot.py -f callgrind ./callgrind.out.4014 | dot -Tpdf -o callgrind.pdf

```

where callgrind.out.4014 is the output of valgrind. see [callgrind.pdf](#) for detail.

5 TODO

Complete `eval_cbv()` and `eval_cbn()` of `closure.c`.

please send your `closure.c` as attached file to [mailto:hanfei.wang@gmail.com?subject=ID\(06\)](mailto:hanfei.wang@gmail.com?subject=ID(06)) where the ID is your student id number.

6 Compilation to the Abstract Machine

The abstract machine (see [From Interpreter to Compiler and Virtual Machine: a Functional Derivation](#)) is in fact is a serie of the instructions which can treat the evaluation of the last section. The compilation of the λ -term is in fact the serializations of the evaluation of CBV or CBN.

suppose our abstract machine (simplified [SECD machine](#)) is stack machine. its' memory can hold the normal constant of integer, closure, instruction list and environment so called the **object**.

the machine state is triple (pc, e, s) where pc is program counter which represented as a list of instructions whose first element is the current instruction being executed, e is the register which always hold the current environment, and s the stack which stores the evaluation results.

the CBV evaluation will suggest the instructions of the abstract machine:

1. NUM n : push n on the stack
2. GET n : the register e must be the env, push $get_n_th(e, n)$ to the stack.
3. PUT c : push $CLOS(c, e)$ on the stack where c is the code of the function body and e is the current register.
4. RET: return caller env.
5. APPLY: pop function argument and closure from stack, store current env and rest code as closure, and execute the code of the function.
6. BRANCH: pop constant n , code of the true branch and code of the false branch, if n is no zero, then execute the concatenation of the code of the true branch and the rest code, else the false one.
7. the arithmetic op (ADD, SUB, MULT, DIV and EQ): pop 2 constants, push the arithmetic result in stack.

formally, the code and the object (or value) are recursively defined as:

```
code ::= NUM of int
      | GET of int
      | PUT of code list
      | RET
      | APPLY
      | BRANCH
      | ADD | SUB | MULT | DIV | EQ

object ::= CONST of int
        | ENV of object list
        | CLOS of (code list) * (object list)
```

the transitions table of the instructions:

Before			After		
pc	register	stack	pc	register	stack
(NUM n)::c	e	s	c	e	(CONST n)::s
(GET n)::c	e	s	c	e	$get_n_th(e, n)$::s
(PUT c')::c	e	s	c	e	$CLOS(c', e)$::s
RET::c	e	$v::CLOS(c', e')$::s	c'	e'	$v::s$
APPLY::c	e	$v::CLOS(c', e')$::s	c'	$v::e'$	$CLOS(c, e)$::s
BRANCH::c	e	$(CONST\ n)::CLOS(t, l)::CLOS(f, l)::s$	$t++c$	e	s
BRANCH::c	e	$(CONST\ 0)::CLOS(t, l)::CLOS(f, l)::s$	$f++c$	e	s
ADD::c	$(CONST\ m)::(CONST\ n)::e$	s	c	unchanged	$(CONST\ n+m)::s$
SUB::c	$(CONST\ m)::(CONST\ n)::e$	s	c	unchanged	$(CONST\ n-m)::s$
MULT::c	$(CONST\ m)::(CONST\ n)::e$	s	c	unchanged	$(CONST\ n*m)::s$
DIV::c	$(CONST\ m)::(CONST\ n)::e$	s	c	unchanged	$(CONST\ n/m)::s$
EQ::c	$(CONST\ m)::(CONST\ n)::e$	s	c	unchanged	$(CONST\ n==m)::s$

the SDD of the compilation

AST	semantic rules
$T = CONST\ n$	$T.code = [NUM\ n]$
$T = VAR\ n$	$T.code = [GET\ n]$
$T = ABS(x, T1)$	$T.code = [PUT\ (T1.code\ ++\ [RET])]$
$T = COND(T1, T2, T3)$	$T.code = (PUSH\ T3.code)::(PUSH\ T2.code)::T1.code::[BRANCH]$
$T = APP\ (T1, T2)$	$T.code = T1.code\ ++\ T2.code\ ++\ [APPLY]$
$T = Op\ +$	$T.code = [PUT\ [PUT\ [ADD; RET]; RET]]$

like the typing and the evaluation, the global code execution environment is the extension of the environment, which hold the static part of the register. it is initializes as:

```
global_exec_env[] = [CLOS([PUT [ADD; RET]; RET], []),
                    CLOS([PUT [SUB; RET]; RET], []),
                    CLOS([PUT [MULT; RET]; RET], []),
                    CLOS([PUT [DIV; RET]; RET], []),
                    CLOS([PUT [EQ; RET]; RET], [])]
```

6.1 Example 1: + 1 2

the AST of + 1 2 is APP(APP(Op +, 1 2)), the compiled code is [GET 6; NUM 1; APPLY; NUM 2; APPLY].

step	PC	register	stack
0	[GET 6; NUM 1; APPLY; NUM 2; APPLY]	[]	[]
1	[NUM 1; APPLY; NUM 2; APPLY]	[]	[CLOS([PUT[ADD; RET]; RET], [])]
2	[APPLY; NUM 2; APPLY]	[]	[CONST 1; CLOS([PUT[ADD; RET]; RET], [])]
3	[PUT[ADD; RET]; RET]	[CONST 1]	[CLOS([NUM 2; APPLY], [])]
4	[RET]	[CONST 1]	[CLOS([ADD; RET], [CONST 1]); CLOS([NUM 2; APPLY], [])]
5	[NUM 2; APPLY]	[]	[CLOS([ADD; RET], [CONST 1])]
6	[APPLY]	[]	[CONST 2; CLOS([ADD; RET], [CONST 1])]
7	[ADD; RET]	[CONST 2; CONST 1]	[CLOS([], [])]
8	[RET]	[CONST 2; CONST 1]	[CONST 3; CLOS([], [])]
9	[]	[]	[CONST 3]

6.2 Example 2. let MY = @x.@y.x y

the code of MY is [PUT [PUT [GET 2;GET 1; APPLY];RET]]. We pre-execute the code

step	PC	register	stack
0	[PUT [PUT [GET 2;GET 1; APPLY]; RET]; RET]	[]	[]
1	[]	[]	CLOS([PUT [GET 2; GET 1; APPLY; RET]; RET], [])

and put the result in global_exec_env[]:

```
global_exec_env[] = [..., CLOS([PUT [EQ; RET]; RET], []),
                    CLOS([PUT [GET 2; GET 1; APPLY; RET]; RET], [])]
```

the compiled code of MY (@x.x) 3 is [GET 1; PUT [GET 1; RET]; APP; NUM 3;APP]

step	pc	register	stack
0	[GET 1; PUT [GET 1; RET]; APPLY; NUM 3; APPLY]	[]	[]
1	[PUT [GET 1; RET]; APPLY; NUM 3; APPLY]	[]	[CLOS([PUT [GET 2; GET 1; APPLY; RET]; RET])]
2	[APPLY; NUM 3; APPLY]	[]	[CLOS([GET 1; RET], []); CLOS([PUT [GET 2; GET 1; APPLY; RET]; RET])]
3	[PUT [GET 2; GET 1; APPLY; RET]; RET]	[CLOS([GET 1; RET], [])]	[CLOS([NUM 3; APPLY], [])]
4	[RET]	[CLOS([GET 1; RET], [])]	[CLOS([GET 2; GET 1; APPLY; RET], [CLOS([GET 1; RET], [])]); CLOS([NUM 3; APPLY], [])]
5	[NUM 3; APPLY]	[]	[CLOS([GET 2; GET 1; APPLY; RET], [CLOS([GET 1; RET], [])])]
6	[APPLY]	[]	[CONST 3; CLOS([GET 2; GET 1; APPLY; RET], [CLOS([GET 1; RET], [])])]
7	[GET 2; GET 1; APPLY; RET]	[CONST 3; CLOS([GET 1; RET], [])]	[CLOS([], [])]
8	[GET 1; APPLY; RET]	[CONST 3; CLOS([GET 1; RET], [])]	[CLOS([GET 1; RET], []); CLOS([], [])]
9	[APPLY; RET]	[CONST 3; CLOS([GET 1; RET], [])]	[CONST 3; CLOS([GET 1; RET], []); CLOS([], [])]
10	[GET 1; RET]	[CONST 3]	[CLOS([RET], [CONST 3; CLOS([GET 1; RET], [])]); CLOS([], [])]
11	[RET]	[CONST 3]	[CONST 3; CLOS([RET], [CONST 3; CLOS([GET 1; RET], [])]); CLOS([], [])]
12	[RET]	[CONST 3; CLOS([GET 1; RET], [])]	[CONST 3; CLOS([], [])]
13	[]	[]	[CONST 3]

6.3 Tail call

APPLY should store the current environment and the rest code as closure in stack for the continuation. RET will jump to the prestored continuation. in @x.@y.x y, the code @y.x y is PUT [GET 2;GET 1; APPLY; RET] which means that the last operation of the body of the function @y.x y is APPLY, after APPLY, the function will RET immediately to the caller. so this kind APPLY is not needed to save the continuation as closure and even RET can be

So if RET is immediately after APPLY, the continuation for APPLY is RET. so it is not needed for next use. We observe the **step 9** of the above example: because the continuation of APPLY is just RET which means the closure env for the continuation of next APPLY is not used for RET, so called **tail call**.

We can change such APPLY RET with a new instruction TAIL, so it can significant saving stack space:

Before			After		
pc	register	stack	pc	register	stack
...
TAIL::c	e	v::CLOS(c',e')::s	c'	v::e'	s

6.4 Example 3. let MY = @x.@y.x y with tail call

the code of MY is [PUT [PUT [GET 2;GET 1; APPLY];RET]]. We pre-execute the code

step	PC	register	stack
0	[PUT [PUT [GET 2;GET 1; TAIL]; RET]	[]	[]
1	[]	[]	CLOS([PUT [GET 2; GET 1; TAIL]; RET],[])

and put the result in global_exec_env[]:

```
global_exec_env[] = [..., CLOS([PUT [EQ; RET]; RET], []),
                    CLOS([PUT [GET 2; GET 1; TAIL]; RET], [])]
```

the compiled code of MY (@x.x) 3 is [GET 1; PUT [GET 1; RET]; APP; NUM 3;APP]

step	pc	register	stack
0	[GET 1; PUT [GET 1; RET]; APPLY; NUM 3; APPLY]	[]	[]
1	[PUT [GET 1; RET]; APPLY; NUM 3; APPLY]	[]	[CLOS([PUT [GET 2; GET 1; TAIL]; RET])]
2	[APPLY; NUM 3; APPLY]	[]	[CLOS([GET 1; RET],[]); CLOS([PUT [GET 2; GET 1; TAIL]; RET])]
3	[PUT [GET 2; GET 1; TAIL]; RET]	[CLOS([GET 1; RET],[])]	[CLOS([NUM 3; APPLY],[])]
4	[RET]	[CLOS([GET 1; RET],[])]	[CLOS([GET 2; GET 1; TAIL],[CLOS([GET 1; RET],[])]); CLOS([NUM 3; APPLY],[])]
5	[NUM 3; APPLY]	[]	[CLOS([GET 2; GET 1; TAIL],[CLOS([GET 1; RET],[])])]
6	[APPLY]	[]	[CONST 3; CLOS([GET 2; GET 1; TAIL],[CLOS([GET 1; RET],[])])]
7	[GET 2; GET 1; TAIL]	[CONST 3; CLOS([GET 1; RET],[])]	[CLOS([],[])]
8	[GET 1; TAIL]	[CONST 3; CLOS([GET 1; RET],[])]	[CLOS([GET 1; RET],[]); CLOS([],[])]
9	[TAIL]	[CONST 3; CLOS([GET 1; RET],[])]	[CONST 3; CLOS([GET 1; RET],[]); CLOS([],[])]
10	[GET 1; RET]	[CONST 3]	[CLOS([],[])]
11	[RET]	[CONST 3]	[CONST 3; CLOS([],[])]
12	[]	[]	[CONST 3]

7 TOTO

7.1 Compilation and Simulator

Please complete INSTRUCTION *compile(AST * t) and the stepwise simulator STATE *step_exe(STATE *state) of code.c.

7.2 Optimization of tail call (BONUS)

Please design the new SDD so the tail call can be replace by TAIL, implement your new compile.

please send your code.c as attached file to [mailto:hfwang@whu.edu.cn?subject=ID\(07\)](mailto:hfwang@whu.edu.cn?subject=ID(07)) where the ID is your student id number.

-hfwang November 21, 2018