



Changes to ossimTileToPlImage

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Overview of Talk

- ▼ Introduction
- ▼ Making the image a color image instead of grayscale
 - ▼ Accessing OpenCV image data
 - ▼ Accessing ossimImageData data
 - ▼ Allocating an image
 - ▼ Displaying images
- ▼ Adding a threshold to the image
 - ▼ Using what we learned from previous examples
- ▼ Blob process the image
 - ▼ Allocating an image
 - ▼ Converting a color image to grayscale
 - ▼ Extracting the individual blobs and printing their information to the screen
- ▼ Conclusions

Accessing OpenCV image data

- Image data is stored in an array
- To access all data in an image you will need to use a loop similar to:

```
for(i=0;i<height;i++){  
    for(j=0;j<width;j++){  
        for(k=0;k<channels;k++){  
            data[i*step+j*channels+k]=0;  
        }  
    }  
}
```

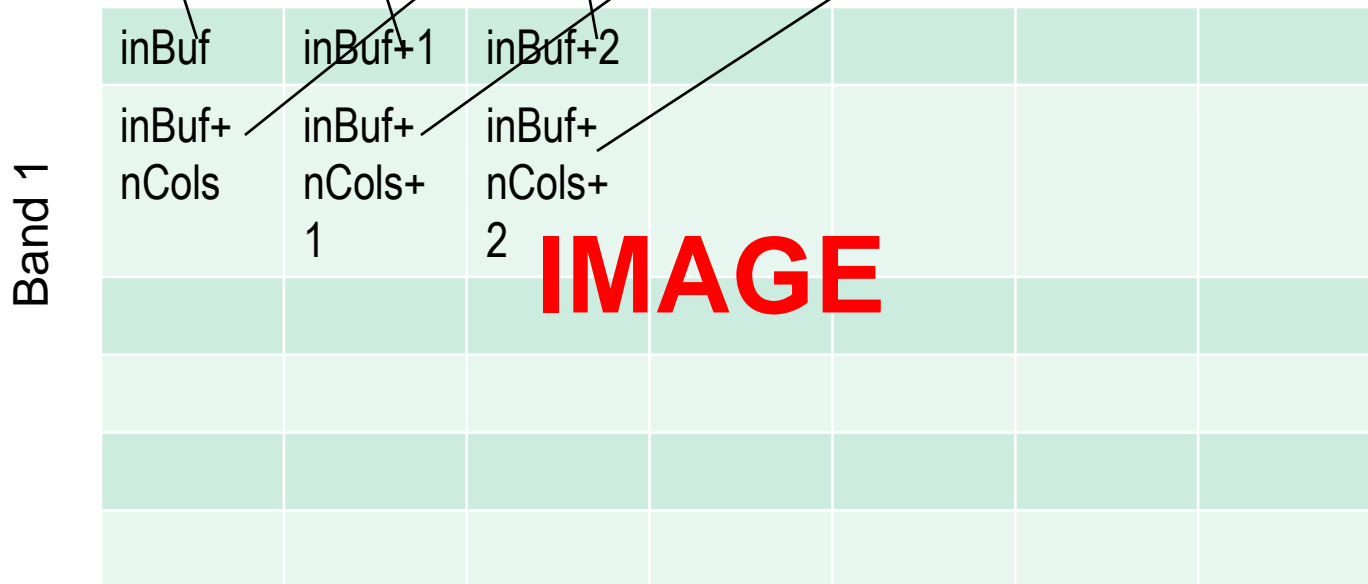
RGBRGBRGBRGB...

Accessing ossimImageData data

- For images with bit depth == 8
- `unsigned char* inBuf = static_cast<unsigned char*>(inputTile->getBuf(band));`
- `unsigned char pixVal = (unsigned char)(*inBuf);`
- The ossim image data is organized by:
 - `R(1,1)R(1,2)R(1,3)...G(1,1)G(1,2)G(1,3)...B(1,1)B(1,2)B(1,3)`
- That is the fastest changing data is the data along the rows of the image, then the columns, then the bands

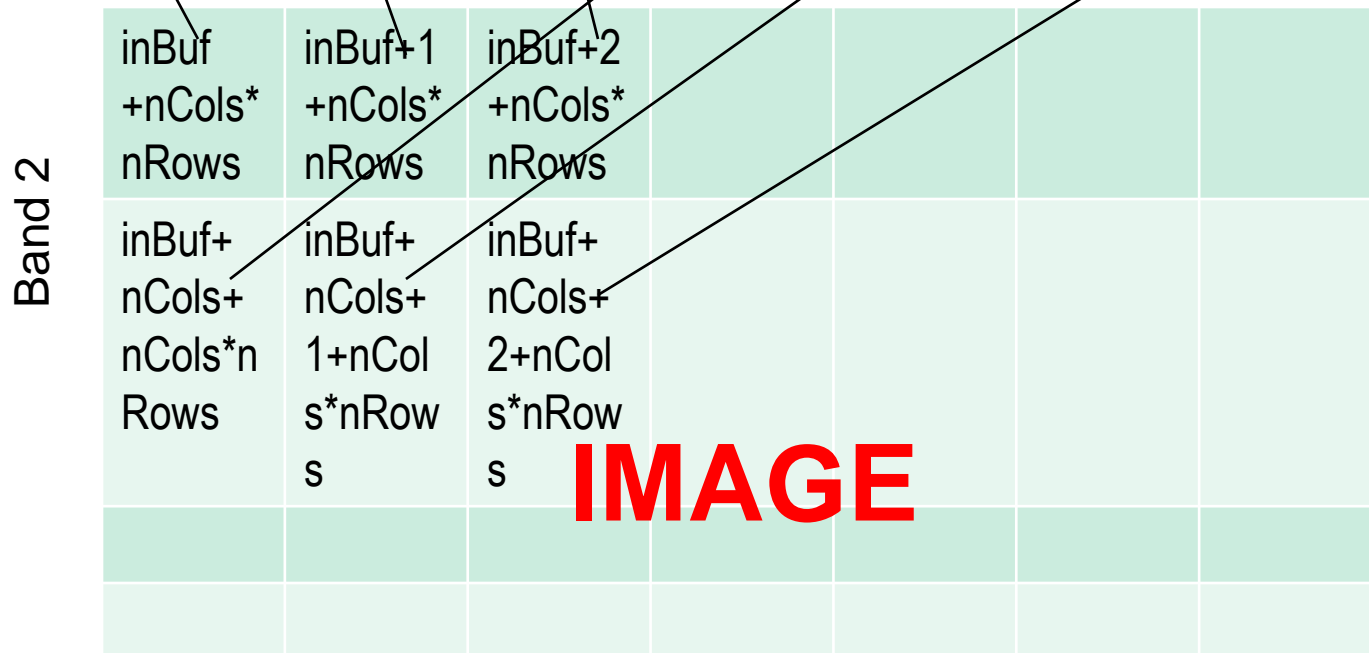
Accessing ossimImageData data

- $\langle b1y1x1 \rangle \langle b1y1x2 \rangle \langle b1y1x3 \rangle \dots \langle b1y2x1 \rangle \langle b1y2x2 \rangle \langle b1y2x3 \rangle \dots$
- $\langle b2y1x1 \rangle \langle b2y1x2 \rangle \langle b2y1x3 \rangle \dots \langle b2y2x1 \rangle \langle b2y2x2 \rangle \langle b2y2x3 \rangle \dots$



Accessing ossimImageData data

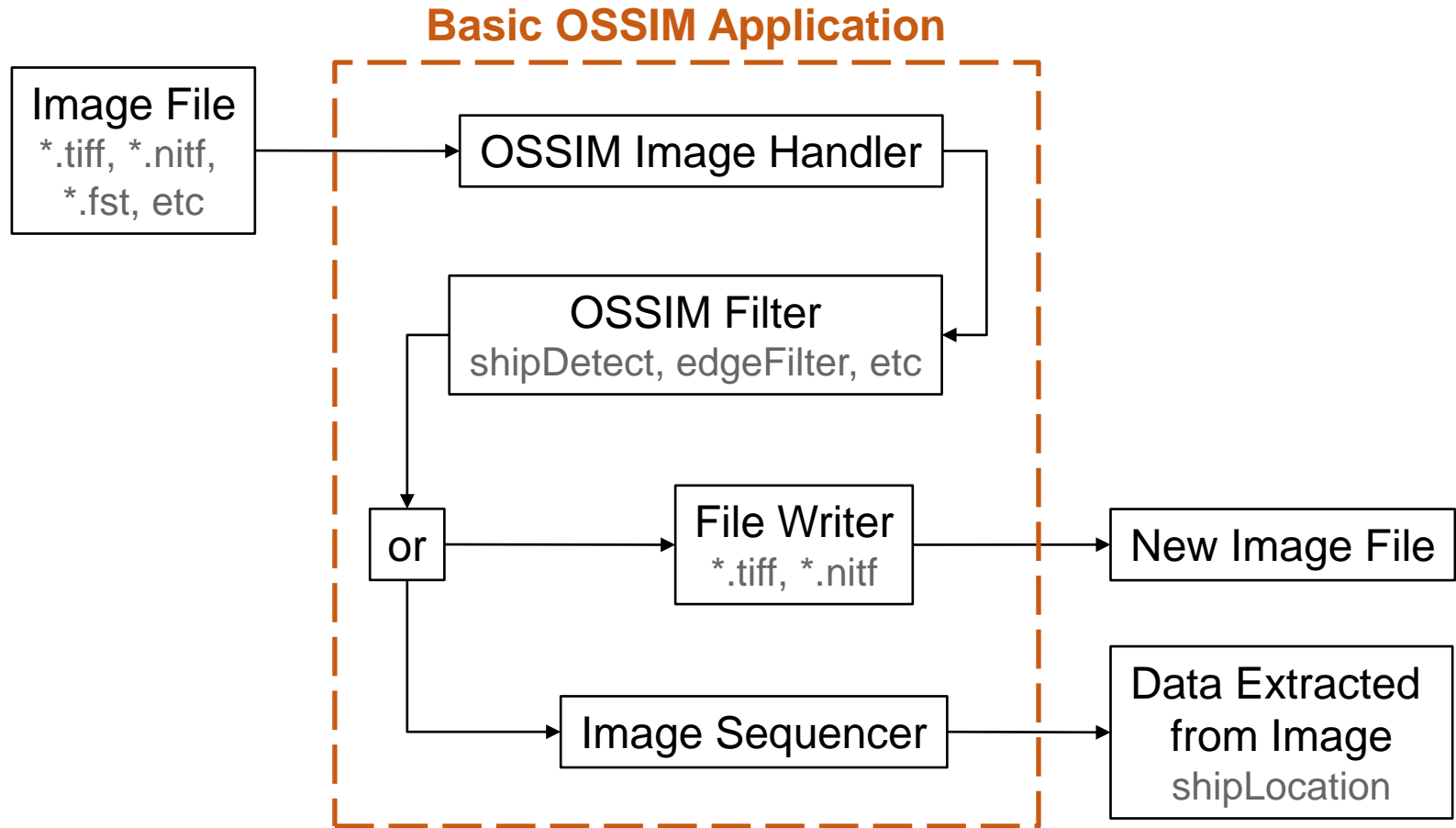
- $\langle b1y1x1 \rangle \langle b1y1x2 \rangle \langle b1y1x3 \rangle .. \langle b1y2x1 \rangle \langle b1y2x2 \rangle \langle b1y2x3 \rangle$
- $\langle b2y1x1 \rangle \langle b2y1x2 \rangle \langle b2y1x3 \rangle .. \langle b2y2x1 \rangle \langle b2y2x2 \rangle \langle b2y2x3 \rangle$



Allocating an Image

- `IplImage* image = cvCreateImage(size,depth,numChannels);`
- `size = cvSize(width, height)`
- `depth =`
 - `IPL_DEPTH_8U` – 8 bit unsigned
 - `IPL_DEPTH_16U` – 16 bit unsigned
 - `IPL_DEPTH_16S` - 16 bit signed
 - `IPL_DEPTH_32F` – 32 bit floating point
- `numChannels = number of channels in the input image`

OSSIM Basics



OSSIM Basics

```
ossimInit::instance()->initialize();
```

```
ossimRefPtr<ossimImageHandler> ih = ossimImageHandlerRegistry::instance()->open(image_file);
```

Image Handler

```
TileToIpl->connectMyInputTo(0,ih.get());
```

```
ossimRefPtr<ossimTileToIplFilter> TileToIpl = new ossimTileToIplFilter();
```

Filters

```
sequencer->connectMyInputTo(TileToIpl.get());
```

Sequencer
Or
Writer

```
ossimRefPtr<ossimImageSourceSequencer> sequencer = new ossimImageSourceSequencer();
```

RUN THE CHAIN

```
while( (dataObject=sequencer->getNextTile()).valid() );
```