Generating the Strong Coupling Hopping Expansion \hookrightarrow and the SU(N) Gauge Integrals

Aleksandra R. Glesaaen - Goethe-Universität Frankfurt am Main

Introduction

Goal

Hopping expand the fermion determinant and calculate the spatial gauge links analytically

Motivation

- The fermion determinant is computationally expensive
- Reduce the DOF to traces over Polyakov loop constructs
- Makes complex Langevin a viable simulation algorithm
- lacksquare The series is convergent at some order in κ

Preliminaries: The hopping expansion

Start off with the standard Wilson QCD action:

$$Z=\int\!\mathcal{D}U_{\mu}\mathcal{D}\bar{\psi}\mathcal{D}\psi\,e^{-S_F-S_G}\text{, with}$$

$$S_F=a^4\!\!\sum_{n,m\in\Omega}\!\!\bar{\psi}(n)D(n|m)\psi(m)\text{,}$$

where the Fermion determinant is

$$D(n|m) = (m + \frac{4}{a})\delta_{n,m} - \frac{1}{2a} \sum_{\mu=\pm 0}^{\pm 3} (1 - \gamma_{\mu})U_{\mu}(n) \,\delta(n + \hat{\mu}, m)$$
$$= D_0 \left(\delta_{n,m} - \kappa H(n|m)\right), \ \kappa = \frac{1}{2(am + 4)}$$

Preliminaries: The hopping expansion

Carrying out the fermion integrals in the partition function

$$Z = \int \mathcal{D}U_{\mu} \, e^{-S_G} \det \left[D \right],$$

and using the standard trace-log identity:

- Determinant expansion

$$\begin{split} \det\left[D\right] &= \exp\left\{-\sum_{n=1}^{\infty} \frac{\kappa^n}{n} \mathrm{tr}\big[H^n\big]\right\} \\ &= 1 - \kappa \, \mathrm{tr}\big[H\big] + \frac{1}{2} \kappa^2 \Big(\mathrm{tr}\big[H\big]\Big)^2 - \frac{1}{2} \kappa^2 \mathrm{tr}\big[H^2\big] + \mathcal{O}(\kappa^3) \end{split}$$

The effective 3D theory

Start by separating the temporal and spatial hops:

$$\det [D] = \det [1 - T - S^{+} - S^{-}]$$

$$= \det [1 - T] \det [1 - (1 - T)^{-1}(S^{+} + S^{-})]$$

$$\equiv \det [Q_{\text{stat}}] \det [1 - P - M]$$

 $\det Q_{\det}$ is known so the terms of interest come from

$$\det [1 - P - M] = \exp \left\{ -\sum_{n=1}^{\infty} \frac{1}{n} \operatorname{tr} [(P + M)^n] \right\},\,$$

where the trace is over all free indices (space, time, Dirac, colour).

Index overload

Ingredients

$$P(\vec{x}, t \mid \vec{y}, \tau) = \kappa Q_{\text{stat}}^{-1}(t, \tau) \sum_{i=1}^{3} (1 - \gamma_i) U_i(\vec{x}) \delta_{\vec{x}, \vec{y} - \hat{i}}$$

$$M(\vec{x}, t \mid \vec{y}, \tau) = \kappa Q_{\text{stat}}^{-1}(t, \tau) \sum_{i=1}^{3} (1 + \gamma_i) U_i^{\dagger}(\vec{y}) \delta_{\vec{x} - \hat{i}, \vec{y}}$$

Every factor of P or M bring a full set of free indices which needs to be reduced before we can carry out the spatial gauge integrals.

The trace is our friend

Initial expression -

$$\det D = \exp \left\{ -\sum_{n=1}^{\infty} \frac{1}{n} \mathrm{tr} \big[(P+M)^n \big] \right\}$$

Both P and M has temporal movement because of Q_{stat}^{-1} , but primarily

- lacksquare P does one forwards spatial jump
- ullet M does one backwards spatial jump

 $N_P = N_M$, to satisfy the spatial trace

The trace is our friend

Initial expression

$$\det D = \exp\left\{-\sum_{n=1}^{\infty} \frac{1}{n} \operatorname{tr}[(P+M)^n]\right\}$$

Rule #1

 $N_P=N_M$, to satisfy the spatial trace

$$\det D = \exp\left\{-\operatorname{tr}[P] - \operatorname{tr}[M] - \frac{1}{2}\operatorname{tr}[P^2] - \frac{1}{2}\operatorname{tr}[PM] - \frac{1}{2}\operatorname{tr}[MP] - \frac{1}{2}\operatorname{tr}[M^2] + \mathcal{O}(\kappa^4)\right\}$$
$$= \exp\left\{-\operatorname{tr}[PM] + \mathcal{O}(\kappa^4)\right\}$$

Limiting spatial indices

Every term includes the direction the jump is to be taken, we want to limit this as much as possible.

$$P(\vec{x}, t \mid \vec{y}, \tau) = \kappa Q_{\text{stat}}^{-1}(t, \tau) \sum_{i=1}^{3} (1 - \gamma_i) U_i(\vec{x}) \delta_{\vec{x}, \vec{y} - \hat{i}}$$

Tracing a contribution and carrying out the intermediate sums leaves us with:

$$\sum_{i_1, i_2, \dots, i_n} \delta(s_1 \hat{i_1} + s_2 \hat{i_2} + \dots + s_n \hat{i_n}), \quad s_j = \frac{1, i_j \text{ from } P}{-1, i_j \text{ from } M}$$

Example: PPMM

Assume we pull the jump-indices out of P and M:

$$\mathrm{tr}\big[PPMM\big] = \mathrm{tr} \underset{i,j,k,l \, \in \, \{\hat{x},\hat{y},\hat{z}\}}{\sum} P_i P_j M_k M_l$$

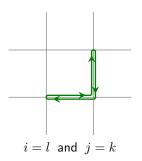
This gives the following Delta:

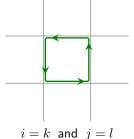
which has two solutions

$$i=l$$
 and $j=k,$ or $i=k$ and $j=l$

Example: PPMM cont.

These two solutions can graphically be represented as





A look into the future

These diagrams yield the following spatial gauge integrals

$$i=l$$
 and $j=k$
$$\int \mathcal{D}U_{\mu}\,U_i(\vec{x})U_j(\vec{x}+\hat{i})U_j^{\dagger}(\vec{x}+\hat{i})U_i^{\dagger}(\vec{x})$$

$$i=k \ {
m and} \ j=l$$

$$\int {\cal D} U_\mu \, U_i(\vec x) U_j(\vec x+\hat i) U_i^\dagger(\vec x+\hat j) U_j^\dagger(\vec x)$$

A look into the future

These diagrams yield the following spatial gauge integrals

$$i=l$$
 and $j=k$
$$\left(\int \mathrm{d}U\,UU^\dagger\right)^2$$

$$i=k$$
 and $j=l$
$$\bigg(\int \mathrm{d}U\,U\bigg)^2 \bigg(\int \mathrm{d}U\,U^\dagger\bigg)^2$$

Vanishing gauge integrals

A quick result from a paper by Creutz¹

– Vanishing integrals –

$$\int_{U \in \mathrm{SU}(3)} \mathrm{d}U \, U^n \big(U^\dagger \big)^m = 0, \quad \text{if} \quad \begin{cases} n + 2m \neq 0 \pmod{3}, \text{ or } \\ 2n + m \neq 0 \pmod{3} \end{cases}$$

 $^{^{1}}$ M. Creutz, "On Invariant Integration Over SU(N)", J.Math.Ph, 1978

Vanishing gauge integrals

A quick result from a paper by Creutz¹

Vanishing integrals -

$$\int_{U \in SU(3)} dU U^n (U^{\dagger})^m = 0, \text{ if } \begin{cases} n + 2m \neq 0 \pmod{3}, \text{ or } \\ 2n + m \neq 0 \pmod{3} \end{cases}$$

Examples

$$\int \mathrm{d}U\,U^\dagger = \int \mathrm{d}U\,UU = \int \mathrm{d}U\,UUUU^\dagger = 0$$

¹M. Creutz, "On Invariant Integration Over SU(N)", J.Math.Ph, 1978

Different contributions

Mesonic contributions

$$\int dU \left(UU^{\dagger}\right)^{n_m}$$

Baryonic contributions -

$$\int \mathrm{d} U \left(U U U \right)^{n_b} \ \text{or} \ \int \mathrm{d} U \left(U^\dagger U^\dagger U^\dagger \right)^{\bar{n_b}}$$

Mixed contributions -

$$\int dU \left(UU^{\dagger}\right)^{n_m} \left(UUU\right)^{n_b} \left(U^{\dagger}U^{\dagger}U^{\dagger}\right)^{\bar{n_b}}$$

Mesonic contributions

One can get these contributions by connecting pairs of P's and M's with the following rule:

¬ Rule #3 —

Every connected P and M must have a equal number of P's and M's in between, to allow for complete backtracking.

A connected pair must be at the same space-time position, and must jump in the same spatial direction.

Diagrammic notation









Diagrammic notation

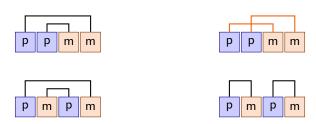




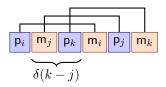




Diagrammic notation



Sometimes also impose additional index restrictions



Multi-trace contributions

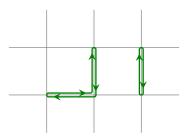
Determinant expansion

$$\det [D] = \exp \left\{ -\sum_{n=1}^{\infty} \frac{\kappa^n}{n} \operatorname{tr}[H^n] \right\}$$
$$= 1 - \kappa \operatorname{tr}[H] + \frac{1}{2} \kappa^2 \left(\operatorname{tr}[H] \right)^2 - \frac{1}{2} \kappa^2 \operatorname{tr}[H^2] + \mathcal{O}(\kappa^3)$$

Multi-trace contributions are separate diagrams which can be located anywhere on the lattice.

Multi-trace contributions: Example

So the PPmm • Pm would graphically be represented as:



However, it doesn't get interesting until they somehow overlap.

Resummation

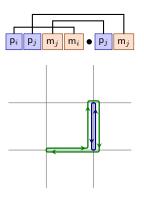
$$\begin{split} Z &= 1 + \sum_{\vec{x},t} S_{PM} + S_{PPMM} + S_{PMPM} + S_{PM.PM} + \mathcal{O}(\kappa^6) \\ &= \exp\left\{\sum_{\vec{x},t} S_{PM} + S_{PPMM} + S_{PMPM} + S_{PM.PM} \\ &- \mathsf{counter\ terms} + \mathcal{O}(\kappa^6)\right\} \end{split}$$

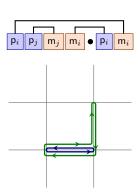
The counter terms are the disconnected multi-trace terms.

$$\sum_{\vec{x},\vec{y},t,\tau} S_{PM}(\vec{x},t) S_{PM}(\vec{y},\tau) = \sum_{\vec{x},t} S_{PM.PM}^{\rm d}(\vec{x},t)$$

Contributing multi-trace diagrams

Only new contributions from ${\rm tr} \big[PPMM \big] {\rm tr} \big[PM \big]$ are:





The large N_T limit

The last two steps of the analytic part of the calculation are:

- Further restricting temporal variables
- Inserting the proper gauge integrals

$$P_i M_i P_j M_j \sum_{i,j} \sum_{t,\tau} \int dU_i(t) dU_j(\tau) U_i(t) U_i^{\dagger}(t) U_j(\tau) U_j^{\dagger}(\tau)$$

The large N_T limit

$$P_i M_i P_j M_j \sum_{i,j} \sum_{t,\tau} \int dU_i(t) dU_j(\tau) U_i(t) U_i^{\dagger}(t) U_j(\tau) U_j^{\dagger}(\tau)$$

The sums over t and τ can be divided into two different regions:

$$i
eq j ext{ or } t
eq au$$

$$\sim N_T(N_T - 1) \bigg(\int \mathrm{d}U \, U U^\dagger \bigg)^2$$

$$i = j ext{ and } t = au$$

$$\sim N_T \bigg(\int \mathrm{d}U \, U U^\dagger U U^\dagger \bigg)$$

The large N_T limit

The sums over t and τ can be divided into two different regions:

$$i
eq j ext{ or } t
eq au$$

$$\sim N_T(N_T - 1) \bigg(\int \mathrm{d}U \, U U^\dagger \bigg)^2$$

$$i = j ext{ and } t = au$$

$$\sim N_T \bigg(\int \mathrm{d}U \, U U^\dagger U U^\dagger \bigg)$$

Thus in the limit $N_T \to \infty$, only the simple mesonic integrals contribute.

Intermediate summary

Rules of the game

- \blacksquare Only terms with equally many P's and M's contribute
- $lue{2}$ One have to link every P with an M (or sets of three P's and M's)
- Between every single-trace link there must be a valid term
- 4 (Multi-trace links are a bit more difficult...)

Intermediate summary

Rules of the game

- \blacksquare Only terms with equally many P's and M's contribute
- $lue{2}$ One have to link every P with an M (or sets of three P's and M's)
- Between every single-trace link there must be a valid term
- 4 (Multi-trace links are a bit more difficult...)

And Now for Something Completely Different™

$\mathsf{SU}(N)$ gauge integrals

Goal

Calculate integrals of the form:

$$I = \int dU U_{i_1,j_1} \dots U_{i_n,j_n} U_{k_1,l_1}^{\dagger} \dots U_{k_m,l_m}^{\dagger}$$

$$U \in SU(N)$$

in the fundamental representation.

This presentation will closely follow the previously cited paper by M. Creutz²

²M. Creutz, "On Invariant Integration Over SU(N)", J.Math.Ph, 1978

Generating function

Introduce the generating function \boldsymbol{W} in the standard way:

Generating function -

$$W(J,K) = \int \mathrm{d} U \, \exp \left\{ \mathrm{tr} \big[J U + K U^\dagger \big] \right\}$$

where J and K are arbitray $N \times N$ matrices. Thus:

$$I = \left(\frac{\delta}{\delta J_{j_1, i_1}} \cdots \frac{\delta}{\delta J_{j_n, i_n}} \frac{\delta}{\delta K_{l_1, k_1}} \cdots \frac{\delta}{\delta K_{l_m, k_m}} W(J, K) \right) \Big|_{J = K = 0}$$

Rewriting U^{\dagger}

We can rewrite all U^\dagger (= U^{-1}) matrices in terms of the cofactor of U using the identity $U^{-1} = \left(\operatorname{cof} U \right)^T$

$$U_{i,j}^{\dagger} = \frac{1}{(N-1)!} \varepsilon_{j,k_1,\dots,k_{N-1}} \varepsilon_{i,l_1,\dots,l_{N-1}} U_{k_1,l_1} \cdots U_{k_{N-1},l_{N-1}}$$

We can thus eliminate K from the generating funtional, and from now on, W=W(J).

An analytic expression for W(J)

Because of the properties of the gauge group elements of SU(N), W(J) can only be a function of J's determinant:

$$W(J) = \sum_{n=0}^{\infty} a_n (\det J)^n$$

Using the fact that, $\det U=0 \ \forall \ U\in \mathrm{SU}(N)$, and a bit of algebra, it follows that

$$W(J) = \sum_{n=0}^{\infty} \frac{2! \cdots (N-1)!}{n! \cdots (n+N-1)!} (\det J)^n$$

The final piece

Finally, inserting the analytic expression for a matrix determinant, one is ready to go

$$\det J = \frac{1}{N!} \varepsilon_{i_1,\dots,i_N} \varepsilon_{j_1,\dots,j_N} J_{i_1,j_1} \cdots J_{i_N,j_N}$$

From this we can see that the equation for the vanishing integrals presented earlier is correct as $W\sim 1+J^N+J^{2N}+\dots$, and an integral of type

$$\int dU U^n (U^\dagger)^m$$

requires n + (N-1)m derivatives w.r.t. J.

The Levi-Civita symbol

To finalise the computation we need a way to sum over repeated indices in Levi-Civita symbols:

$$\varepsilon_{i_1,i_2,i_3,\ldots,i_N}\varepsilon_{j_1,j_2,\ldots,j_N} \;=\; \left| \begin{array}{cccc} \delta_{i_1,j_1} & \delta_{i_1,j_2} & \cdots & \delta_{i_1,j_N} \\ \delta_{i_2,j_1} & \delta_{i_2,j_2} & \cdots & \delta_{i_2,j_N} \\ \delta_{i_3,j_1} & \delta_{i_3,j_2} & \cdots & \delta_{i_3,j_N} \\ \vdots & \vdots & \ddots & \vdots \\ \delta_{i_N,j_1} & \delta_{i_N,j_2} & \cdots & \delta_{i_N,j_N} \end{array} \right|$$

The Levi-Civita symbol

To finalise the computation we need a way to sum over repeated indices in Levi-Civita symbols:

$$\sum_{i} \varepsilon_{i_{1},i_{2},i,\ldots,i_{N}} \varepsilon_{j_{1},i,\ldots,j_{N}} = \begin{pmatrix} \delta_{i_{1},j_{1}} & \delta_{i_{1},j_{2}} & \cdots & \delta_{i_{1},j_{N}} \\ \delta_{i_{2},j_{1}} & \delta_{i_{2},j_{2}} & \cdots & \delta_{i_{2},j_{N}} \\ \delta_{i_{3},j_{1}} & \delta_{i_{3},j_{2}} & \cdots & \delta_{i_{3},j_{N}} \\ \vdots & & \ddots & \vdots \\ \delta_{i_{N},j_{1}} & \delta_{i_{N},j_{2}} & \cdots & \delta_{i_{N},j_{N}} \end{pmatrix}$$

An example

Finally, a short example

$$I = \int \mathrm{d} U \, U_{i,j} U_{k,l}^\dagger$$

$$U \in \mathrm{SU}(N)$$

$$I = \frac{1}{(N-1)!} \varepsilon_{l,i_{1},...,i_{N-1}} \varepsilon_{k,j_{1},...,j_{N-1}} \int dU \, U_{i,j} U_{i_{1},j_{1}} \cdots U_{i_{N-1},j_{N-1}}$$

$$= \frac{1}{(N-1)!} \varepsilon_{l,i_{1},...,i_{N-1}} \varepsilon_{k,j_{1},...,j_{N-1}} \left(\frac{\delta}{\delta J_{i,j}} \frac{\delta}{\delta J_{i_{1},j_{1}}} \cdots \frac{\delta}{\delta J_{i_{N-1},j_{N-1}}} W(J) \right) \Big|_{J=0}$$

$$= \frac{1}{(N-1)!N!} \varepsilon_{l,i_{1},...,i_{N-1}} \varepsilon_{k,j_{1},...,j_{N-1}} \varepsilon_{i,i_{1},...,i_{N-1}} \varepsilon_{j,j_{1},...,j_{N-1}}$$

$$= \frac{1}{(N-1)!N!} (N-1)! \, \delta_{i,l} (N-1)! \, \delta_{j,k} = \frac{1}{N} \delta_{i,l} \delta_{j,k}$$

Final summary

- \blacksquare Used a generating function to simplify the calculation of $\mathsf{SU}(N)$ group integrals
- Rewrote the generating function as the determinant of its sources
- Showed how gauge integrals can be written as products of Levi-Civita symbols