Fourier integral approximation with FFT

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1 The problem and its solution

Recently I had to compute number of integrals for multiple p in the form of:

$$\hat{f}(p) = \int_{-\infty}^{+\infty} e^{-ixp} f(x) dx \tag{1}$$

which is just continious Fourier transform. The performance with Gaus-Kronrod quadrature was quite acceptable in the limit where $p \to 0$, but in most cases it took too long. Doing some research on it I found [fourint] where the Fourier integral is approximated with trapezodial rule and given for FFT for computing sums.

The requirement on function f(x) is to be localised in some interval [a, b] and also it needs to be bounded or $|f(x)| \leq M$ which allows to rewrite (1):

$$\hat{f}(p) = \int_{a}^{b} e^{-ixp} f(x) dx \tag{2}$$

where introduced error of approximation will be estimated later. For simplicity we can change integration variables x = (b - a)y + a:

$$\hat{f}(p) = \int_0^1 e^{-i(b-a)yp} e^{-iap} f[(b-a)y + a](b-a)dy$$
 (3)

$$= (b-a)Me^{-iap} \int_0^1 e^{-i(b-a)yp} \frac{f[(b-a)y+a]}{M} dy$$
 (4)

$$= (b-a)Me^{-iap}\hat{f}'[(b-a)p]$$
(5)

Therefore the general problem is reduced to computation of:

$$\hat{f}'(p) = \int_0^1 e^{-ixp} f'(x) dx$$
 (6)

where f'(x) = f[(b-a)y + a]/M.

At the next step we are going to introduce the trapezodial approximation

where by using f(a) = f(b) = 0 we obtain:

$$\hat{f}'(p) = \int_0^{(N-1)\Delta x} e^{-ixp} \Theta(1-x) f'(x) dx$$
 (7)

$$= \sum_{n=0}^{N-1} e^{-ipn\Delta x} \Theta(1 - x_n) f'(x_n) \Delta x \tag{8}$$

$$= \frac{1}{N_0 - 1} \sum_{n=0}^{N-1} e^{-inp/(N_0 - 1)} \Theta(1 - x_n) f'(x_n)$$
 (9)

where $\Delta x = 1/(N_0 - 1)$, $x_n = n/(N_0 - 1)$ and $\Theta(x)$ is Heaviside step function. Now we are specifieng the values of transformed variable p for which the integral is calculated¹:

$$p_m = 2\pi (N_0 - 1) \left(\frac{m}{N} - \frac{1}{2}\right) \tag{10}$$

which after putting in (9) one obtains:

$$\hat{f}'(p_m) = \frac{1}{N_0 - 1} \sum_{n=0}^{N-1} e^{-2\pi i n m/N} e^{-\pi i n} \Theta(1 - x_n) f'(x_n)$$
 (11)

Now it is appearent that the sum can be expressed as discrete Fourier transform giving:

$$\hat{f}'(p_m) = \frac{1}{N_0 - 1} FFT\{(-1)^n \Theta(1 - x_n) f'(x_n)\}_m$$
 (12)

2 Error estimations

First error was introduced considering the f(x) to be localised with what we rewrited (1) to (2) where for exact calculation we would write:

$$\int_{-\infty}^{+\infty} e^{-ixp} f(x) dx = \int_a^b e^{-ixp} f(x) dx + \int_b^{+\infty} e^{-ixp} f(x) dx + \int_{-\infty}^a e^{-ixp} f(x) dx$$
(13)

Since $e^{-ixp} \leq 1$ then the error can be estimated:

$$error = \left| \int_{-\infty}^{+\infty} e^{-ixp} f(x) dx - \int_{a}^{b} e^{-ixp} f(x) dx \right| \le \int_{b}^{+\infty} |f(x)| dx + \int_{-\infty}^{a} |f(x)| dx$$

$$\tag{14}$$

where the last integrals could be done numerically.

The second error comes from approximating integral with trapezidual rule

 $^{^{1}}$ It is possible to shift p_{m} in any region however for simplicity the symetric case is considered

in (9). For it the error estimation is given as²:

$$error \leq (b-a) \frac{\Delta x^{2}}{12} \max \left| \frac{d^{2}}{dx^{2}} e^{-ixp} f(x) \right|$$

$$= (b-a) \frac{\Delta x^{2}}{12} \max \left| -p^{2} e^{-ixp} f(x) - ipe^{-ixp} \frac{d}{dx} f(x) + e^{-ixp} \frac{d^{2}}{dx^{2}} f(x) \right|$$

$$\leq (b-a) \frac{\Delta x^{2}}{12} \left[p_{b}^{2} \max |f(x)| + p_{b} \max \left| \frac{d}{dx} f(x) \right| + \max \left| \frac{d^{2}}{dx^{2}} f(x) \right| \right]$$

$$(15)$$

where p_b gives the region of transformed variable $-p_b . In the case where <math>p_b$ is choosen to fully represent the transformed function, the function e^{-ip_bx} varies much faster than f(x) therefore error can be estimated as:

$$error \le \frac{(b-a)\Delta x^2 p_b^2}{12} \max |f(x)| = \frac{(b-a)^3 p_b^2}{12(N_0 - 1)^2} M$$
 (18)

Calculating the reduced problem (6) the error becomes:

$$error_reduced \le \frac{p_b^2}{12(N_0 - 1)^2} \tag{19}$$

which from previous equation is releated with error of general problem:

$$error = M(b-a) \cdot error_reduced$$
 (20)

3 Defining input and output and processing

3.1 Input

- 1. The function f(x)
- 2. Range of localisation [a, b]
- 3. Bound $|f(x)| \leq M$
- 4. Range for output p_b
- 5. Spacing of output Δp
- 6. Absolute error epsabs

3.2 Output

- 1. Exact vlues for p_m
- 2. The calculated function values $\hat{f}(p_m)$

²Taken from Wikipedia Trapezidoal Rule

3.3 Algorithm

Firstly the problem is reformulated as reduced one (6):

$$epsabs \to \frac{epsabs}{M(b-a)}$$
 (21)

$$\frac{f[(b-a)y+a]}{M} \to f(y) \tag{22}$$

$$(b-a)p \to p \tag{23}$$

where from last input aslo comes:

$$(b-a)p_b \to p_b \tag{24}$$

$$(b-a)\Delta p \to \Delta p \tag{25}$$

At the next step we are choosin the needed size of sample for integration or N_0 which according to (18) can be estimated as:

$$N_0 = \frac{p_b^2}{12 \cdot epsabs} \tag{26}$$

The all sample size N however is related to the resolution of output or Δp which from (10) gives us:

$$N \approx 2\pi \frac{N_0}{\Delta p} \tag{27}$$

At this point input vector is fully defined and can be fully evaluated with discrete Fourier transform or by repeating the (12), (10) one gets:

$$x_n = \Delta x n = \frac{n}{N_0 - 1} \tag{28}$$

$$p_m = p_m = 2\pi (N_0 - 1) \left(\frac{m}{N} - \frac{1}{2}\right)$$
 (29)

$$\hat{f}(p_m) = \frac{1}{N_0 - 1} FFT\{(-1)^n \Theta(1 - x_n) f(x_n)\}_m$$
(30)

The last step is to use reduced problem results in order to come back to the general problem. From (6) it is:

$$(b-a)Me^{-iap_m/(b-a)}\hat{f}(p_m) \to \hat{f}_m$$
(31)

$$p_m/(b-a) \to p_m \tag{32}$$

4 Examples

After implementing the algorithm in *Python* I computed some specific examples which I compared with analitically known transforms³.

³Taken from form section Fourier Transforms in Wikipedia

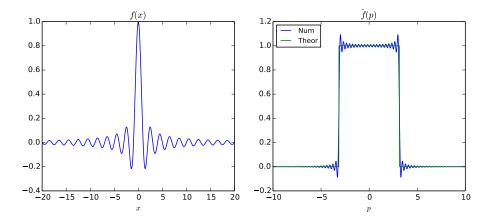


Figure 1: $sinc(x) \xrightarrow{F} rect(\frac{p}{2\pi})$

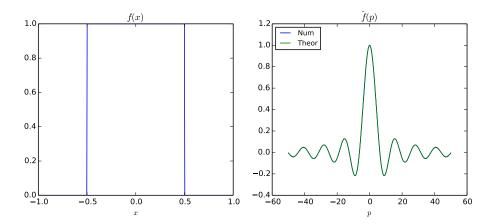


Figure 2: $rect(x) \xrightarrow{F} sinc(\frac{p}{2\pi})$

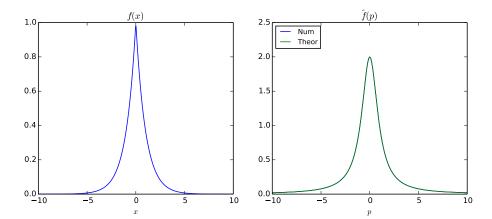


Figure 3: $e^{-|x|} \xrightarrow{F} \frac{2}{1+p^2}$

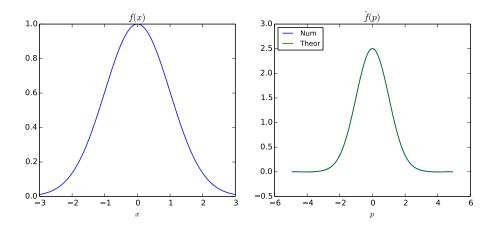
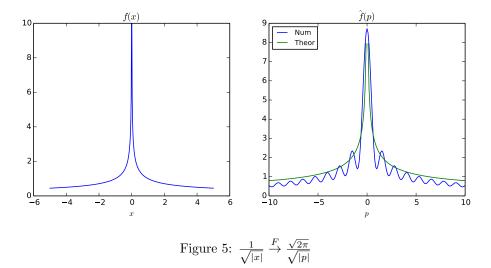


Figure 4: $e^{-x^2/2} \xrightarrow{F} \sqrt{2\pi} e^{-p^2/2}$



5 Further development

- More examples of transformation is needed
- Performance should be checked
- Deeper error analysis should be performed numerically
- ullet Range of localisation [a,b] should be determined automatically.
- Bound M is possible to determine as Global minimum of -|f(x)|
- Range of output p_b could be estimated from normalisation condition or:

$$\int f(x)f^{*}(x)dx = \frac{1}{2\pi} \int \hat{f}(p)\hat{f}^{*}(p)dp$$
 (33)

with iterative process of enlarging sample size by factor of 2 (even and odd parts of FFT).

- Instead of explicitly giving p_b , Δp it could be given as linearly spaced vector (interpolation is unavoidable due to restriction of N, N_0 to be integers in (10))
- Due to [fourint] performance can be increased (as rule of thumb) by a facrotr of 3 on the Fourier transform.

6 Implementation in Python

```
# -*- coding: utf-8 -*-
    Created on Sat Jun 7 23:07:13 2014
     Qauthor: akels
    import numpy as np
    def _fourier_N(f,N,N0):
11
        Computes the:
12
13
        .. math::
14
            15
16
17
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19
20
        n = np.arange(0,N0)
21
        x_n = n/(N0 - 1.)

f_n = f(x_n)
22
23
24
        tilde_f = np.zeros(N)
tilde_f[0:N0] = (-1)**n * f_n
25
26
27
        hat_f = np.fft.fft(tilde_f) / (NO - 1.)
29
30
        return hat_f
31
32
    def fourier_reduced(f,spacing,bound,epsabs=1e-4):
33
34
        .. math::
```

```
36
37
38
39
                                                   where :math: '\Delta p' is given as spacing but :math: 'p_b' as bound.
 40
 41
 42
                                                  {\tt NO} = int( bound/12 / np.sqrt(epsabs) )   
# Without pedantic ceiling
 43
 44
                                                  N = 2 * int(np.pi * NO/ spacing)
 45
 46
  47
                                                  print("N={}\t NO = {}\t .format(N,NO))
 48
                                                # For simplicity. Additional optimisation possible.
m = np.arange(N)
p_m = np.pi * (NO - 1)*(2.*m/N - 1)
valid = np.abs(p_m)< bound</pre>
 49
50
51
 52
 53
 54
                                                  # Using already implemented
hat_f_m = _fourier_N(f,N,NO)
55
56
57
                                                  return p_m[valid], hat_f_m[valid]
58
 59
 60
                           def fourier(f,a,b,spacing,bound,M=1,epsabs=1e-2):
 61
                                                   .. math::
62
                                                                      \label{eq:linear_constraints} $$ \left( \frac{1}{a} \right) \in \left( \frac{a}^{b} \right) e^{-i x p} f(x) dx \setminus p_m \mathcal{B} \right) = \left( \frac{a}^{b} \right) e^{-i x p} f(x) dx \setminus p_m \mathcal{B} \right) = \left( \frac{a}{a} \right) \left( \frac{
63
64
 65
  66
                                                  where :math: '\Delta p' is given as spacing but :math: 'p_b' as bound.
 67
 68
69
                                                  p_r, f_r = fourier\_reduced(lambda y: f((b-a)*y + a)/M, spacing=(b-a)*spacing, bound = (b-a)*bound, epsabs = epsabs/M/(b-a))
 70
  71
  72
                                                  p = p_r/(b-a)
73
74
                                                  f = (b-a)*np.exp(-1j*p*a)* M *f_r
 75
 76
                                                  return p,f
```