Artificial Intelligence and Machine Learning Barbara Caputo

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whenever we observe a particular x, the probability of error is :

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Therefore:

whenever we observe a particular x, the probability of error is :

$$P(error \mid x) = P(\omega_1 \mid x)$$
 if we decide ω_2
 $P(error \mid x) = P(\omega_2 \mid x)$ if we decide ω_1

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Therefore:

$$P(error \mid x) = min [P(\omega_1 \mid x), P(\omega_2 \mid x)]$$

(Bayes decision)

Bayes Decision Theory – Continuous Features

- Generalization of the preceding ideas
 - Use of more than one feature
 - Use more than two states of nature
 - Allowing actions and not only decide on the state of nature
 - Introduce a loss of function which is more general than the probability of error

Loss Function

- Allowing actions other than classification primarily allows the possibility of rejection
- Refusing to make a decision in close or bad cases!
- The loss function states how costly each action taken is

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Let $\lambda(\alpha_i \mid \omega_i)$ be the loss incurred for taking

action α_i when the state of nature is ω_i

 $R = Sum \ of \ all \ R(\alpha_i \mid x) \ for \ i = 1,...,a$

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Expected Loss with action i

$$R(\alpha_i \mid x) = \sum_{j=1}^{j=c} \lambda(\alpha_i \mid \omega_j) P(\omega_j \mid x)$$

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Expected Loss with action i

$$R(\alpha_i | x) = \sum_{j=1}^{j=c} \lambda(\alpha_i | \omega_j) P(\omega_j | x)$$

Select the action α_i for which $R(\alpha_i \mid x)$ is minimum

R is minimum and R in this case is called the Risk

Bayes risk = best performance that can be achieved

```
\alpha_1 : deciding \omega_1
```

$$lpha_2$$
 : deciding ω_2

$$\lambda_{ij} = \lambda(\alpha_i \mid \omega_j)$$

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loss incurred for deciding ω_i when the true state of nature is ω_i

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$$\lambda_{ij} = \lambda(\alpha_i \mid \omega_j)$$

loss incurred for deciding ω_i when the true state of nature is ω_j

Conditional risk:

$$R(\alpha_1 \mid \mathbf{x}) = \lambda_{11} P(\omega_1 \mid \mathbf{x}) + \lambda_{12} P(\omega_2 \mid \mathbf{x})$$

$$R(\alpha_2 \mid x) = \lambda_{21} P(\omega_1 \mid x) + \lambda_{22} P(\omega_2 \mid x)$$

Our rule is the following:

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$$(\lambda_{21} - \lambda_{11}) P(\mathbf{x} \mid \omega_1) P(\omega_1) >$$

$$(\lambda_{12} - \lambda_{22}) P(\mathbf{x} \mid \omega_2) P(\omega_2)$$

and decide ω_2 otherwise

Minimum-Error-Rate Classification

Actions are decisions on classes

If action α_i is taken and the true state of nature is ω_j then: decision is correct if i = j and in error if $i \neq j$

Seek a decision rule that minimizes the *probability of error* which is the *error rate*

Let's take a break!



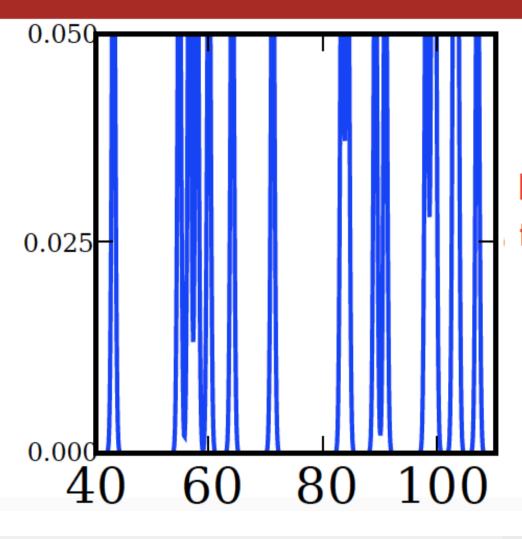
Maximum Likelihood

- Need to measure how well we do
- For density estimation we care about

$$\Pr\left\{X\right\} = \prod_{i=1}^{m} p(x_i)$$

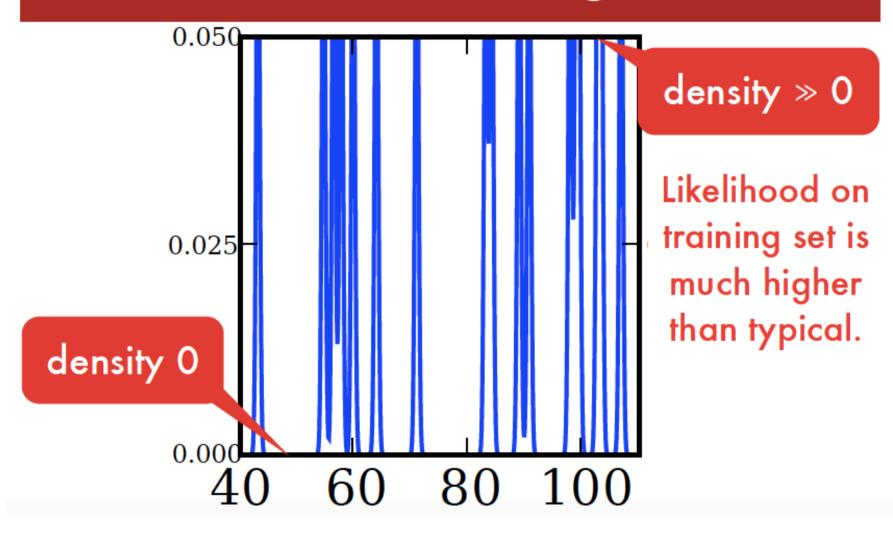
- Finding a that maximizes P(X) will peak at all data points since x_i explains x_i best ...
- Maxima are delta functions on data.
- Overfitting!

Overfitting

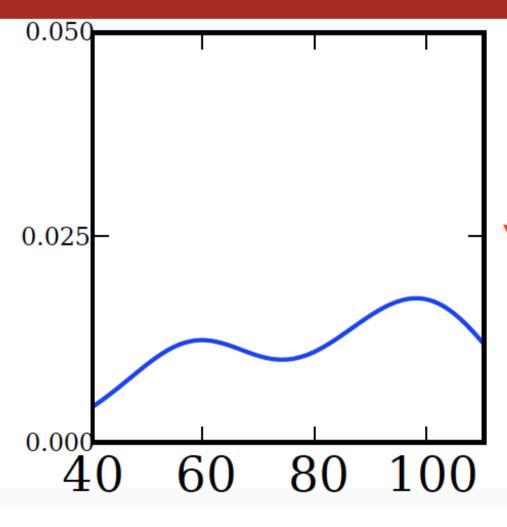


Likelihood on training set is much higher than typical.

Overfitting



Underfitting



Likelihood on training set is very similar to typical one.

Too simple.

Model Selection

- Validation
 - Use some of the data to estimate density.
 - Use other part to evaluate how well it works
 - Pick the parameter that works best

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$$\mathcal{L}(X'|X) := \frac{1}{n'} \sum_{i=1}^{n'} \log \hat{p}(x_i')$$

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- Simple implementation

$$\frac{1}{n} \sum_{i=1}^{n} \log \left[\frac{n}{n-1} p(x_i) - \frac{1}{n-1} k(x_i, x_i) \right] \text{ where } p(x) = \frac{1}{n} \sum_{i=1}^{n} k(x_i, x_i)$$

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