# Artificial Intelligence and Machine Learning Barbara Caputo

Perceptron: Non-linearity and preprocessing

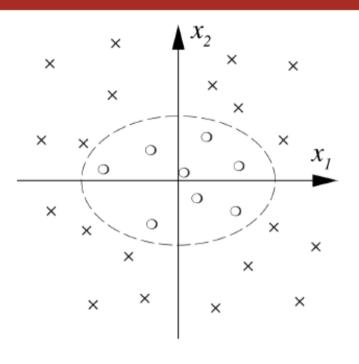
Perceptron

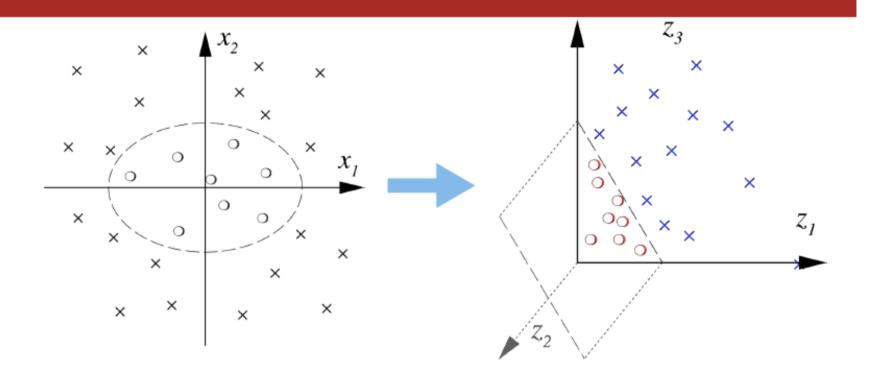
- Perceptron
  - Map data into feature space  $x \to \phi(x)$

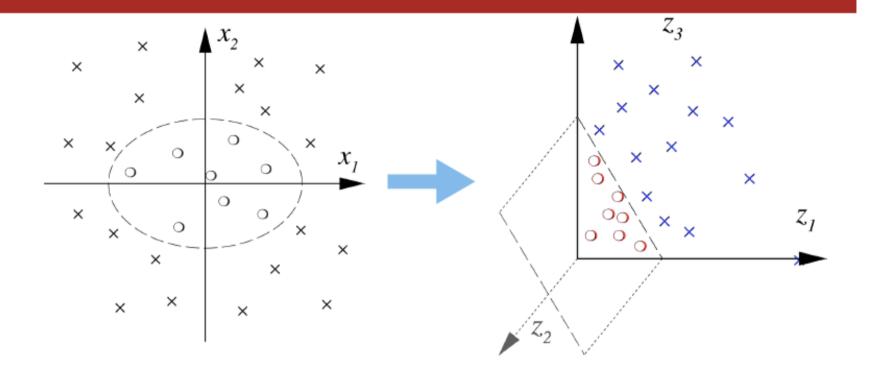
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- Feature Perceptron
  - Solution in span of  $\phi(x_i)$







 Separating surfaces are Circles, hyperbolae, parabolae

# Constructing Features (very naive OCR system)

	Ι	2	3	4	5	6	7	8	9	0
Loops	0	0	0	_	0	_	0	2	_	_
3 Joints	0	0	0	0	0	I	0	0	I	0
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Angles	0	ı	ı	ı	ı	0	ı	0	0	0
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        :from:to:content-type;
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        b=WK2B2+ExWnf/gvTkw6uUvKuP4XeoKnlJq3USYTm0RARK8dSFjy0QsIHeAP9Yssxp60
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From: Tim Althoff <althoff@eecs.berkelev.edu>
Content-Type: multipart/alternative; boundary=f46d043c7af4b07e8d04b5a7113a
--f46d043c7af4b07e8d04b5a7113a
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```

# Feature Engineering for Spam Filtering

- bag of words
- pairs of words
- date & time
- recipient path
- IP number
- sender
- encoding
- links
- ... secret sauce ...

# More feature engineering

Two Interlocking Spirals
 Transform the data into a radial and angular part

$$(x_1, x_2) = (r \sin \phi, r \cos \phi)$$

- Handwritten Japanese Character Recognition
  - Break down the images into strokes and recognize it
  - Lookup based on stroke order
- Medical Diagnosis
  - Physician's comments
  - Blood status / ECG / height / weight / temperature ...
  - Medical knowledge

initialize w, b = 0 repeat

```
initialize w, b = 0
repeat
Pick (x_i, y_i) from data
```

```
initialize w,b=0 repeat  \begin{array}{c} \text{Pick } (x_i,y_i) \text{ from data} \\ \text{if } y_i(w\cdot \Phi(x_i)+b) \leq 0 \text{ then} \\ w'=w+y_i\Phi(x_i) \\ b'=b+y_i \\ \text{until } y_i(w\cdot \Phi(x_i)+b)>0 \text{ for all } i \end{array}
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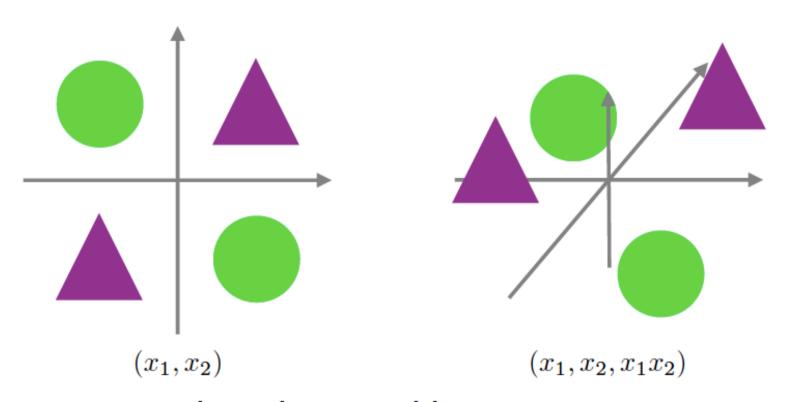
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- Weight vector is linear combination  $w = \sum_{i \in I} y_i \phi(x_i)$
- Classifier is linear combination of inner products  $f(x) = \sum_{i \in I} y_i \langle \phi(x_i), \phi(x) \rangle + b$

### **Problems**

- Problems
  - Need domain expert (e.g. Chinese OCR)
  - Often expensive to compute
  - Difficult to transfer engineering knowledge
- Shotgun Solution
  - Compute many features
  - Hope that this contains good ones
  - Do this efficiently



# Solving XOR



- XOR not linearly separable
- Mapping into 3 dimensions makes it easily solvable

### Quadratic Features in $\mathbb{R}^2$

$$\Phi(x) := \left(x_1^2, \sqrt{2}x_1x_2, x_2^2\right)$$

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#### **Dot Product**

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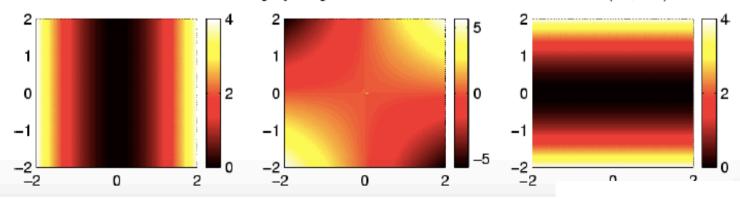
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### Insight

Trick works for any polynomials of order d via  $\langle x, x' \rangle^d$ .



# Computational Efficiency

#### **Problem**

- Extracting features can sometimes be very costly.
- Example: second order features in 1000 dimensions. This leads to 5 · 10<sup>5</sup> numbers. For higher order polynomial features much worse.

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#### Definition

A kernel function  $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is a symmetric function in its arguments for which the following property holds

$$k(x, x') = \langle \Phi(x), \Phi(x') \rangle$$
 for some feature map  $\Phi$ .

If k(x, x') is much cheaper to compute than  $\Phi(x)$  ...

```
\begin{aligned} &\text{repeat} \\ &\text{Pick } (x_i,y_i) \text{ from data} \\ &\text{if } y_i f(x_i) \leq 0 \text{ then} \\ &f(\cdot) \leftarrow f(\cdot) + y_i k(x_i,\cdot) + y_i \\ &\text{until } y_i f(x_i) > 0 \text{ for all } i \end{aligned}
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$$f(x) = \sum_{i \in I} y_i \langle \phi(x_i), \phi(x) \rangle + b = \sum_{i \in I} y_i k(x_i, x) + b$$



# Polynomial Kernels

Idea

## Polynomial Kernels

### Idea

- We want to extend  $k(x,x')=\langle x,x'\rangle^2$  to  $k(x,x')=(\langle x,x'\rangle+c)^d$  where c>0 and  $d\in\mathbb{N}$ .
- Prove that such a kernel corresponds to a dot product.

## Polynomial Kernels

### Idea

**Solution** We want to extend  $k(x, x') = \langle x, x' \rangle^2$  to

$$k(x, x') = (\langle x, x' \rangle + c)^d$$
 where  $c > 0$  and  $d \in \mathbb{N}$ .

Prove that such a kernel corresponds to a dot product.

### **Proof strategy**

Simple and straightforward: compute the explicit sum given by the kernel, i.e.

$$k(x, x') = (\langle x, x' \rangle + c)^d = \sum_{i=0}^m \binom{d}{i} (\langle x, x' \rangle)^i c^{d-i}$$

Individual terms  $(\langle x, x' \rangle)^i$  are dot products for some  $\Phi_i(x)$ .

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We have to be able to compute k(x, x') efficiently (much cheaper than dot products themselves).

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### **Dot Product in Feature Space**

Is there always a  $\Phi$  such that k really is a dot product?

## Mercer's Theorem

### Mercer's Theorem

### The Theorem

For any symmetric function  $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  which is square integrable in  $\mathcal{X} \times \mathcal{X}$  and which satisfies

$$\int_{\mathcal{X} \times \mathcal{X}} k(x, x') f(x) f(x') dx dx' \ge 0 \text{ for all } f \in L_2(\mathcal{X})$$

there exist  $\phi_i: \mathfrak{X} \to \mathbb{R}$  and numbers  $\lambda_i \geq 0$  where

$$k(x, x') = \sum_{i} \lambda_i \phi_i(x) \phi_i(x')$$
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### Interpretation

Double integral is the continuous version of a vectormatrix-vector multiplication. For positive semidefinite matrices we have

$$\sum \sum k(x_i, x_j)\alpha_i\alpha_j \ge 0$$

### **Distance in Feature Space**

Distance between points in feature space via

$$d(x, x')^{2} := ||\Phi(x) - \Phi(x')||^{2}$$

$$= \langle \Phi(x), \Phi(x) \rangle - 2\langle \Phi(x), \Phi(x') \rangle + \langle \Phi(x'), \Phi(x') \rangle$$

$$= k(x, x) + k(x', x') - 2k(x, x)$$

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#### **Kernel Matrix**

To compare observations we compute dot products, so we study the matrix K given by

$$K_{ij} = \langle \Phi(x_i), \Phi(x_j) \rangle = k(x_i, x_j)$$

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### Similarity Measure

The entries  $K_{ij}$  tell us the overlap between  $\Phi(x_i)$  and  $\Phi(x_j)$ , so  $k(x_i, x_j)$  is a similarity measure.

### K is Positive Semidefinite

Claim:  $\alpha^{\top}K\alpha \geq 0$  for all  $\alpha \in \mathbb{R}^m$  and all kernel matrices  $K \in \mathbb{R}^{m \times m}$ . Proof:

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### **Kernel Expansion**

If w is given by a linear combination of  $\Phi(x_i)$  we get

$$\langle w, \Phi(x) \rangle = \left\langle \sum_{i=1}^{m} \alpha_i \Phi(x_i), \Phi(x) \right\rangle = \sum_{i=1}^{m} \alpha_i k(x_i, x).$$

### A Candidate for a Kernel

$$k(x, x') = \begin{cases} 1 & \text{if } ||x - x'|| \le 1 \\ 0 & \text{otherwise} \end{cases}$$

This is symmetric and gives us some information about the proximity of points, yet it is not a proper kernel . . .

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#### **Kernel Matrix**

We use three points,  $x_1 = 1, x_2 = 2, x_3 = 3$  and compute the resulting "kernelmatrix" K. This yields

$$K = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \text{ and eigenvalues } (\sqrt{2} - 1)^{-1}, 1 \text{ and } (1 - \sqrt{2}).$$

as eigensystem. Hence k is not a kernel.

# Examples

### **Examples of kernels** k(x, x')

	near
	HPAI
	ncai
_	

$$\langle x, x' \rangle$$

$$\exp\left(-\lambda \|x - x'\|\right)$$

$$\exp\left(-\lambda \|x - x'\|^2\right)$$

$$(\langle x, x' \rangle + c \rangle)^d, c \ge 0, d \in \mathbb{N}$$

$$B_{2n+1}(x-x')$$

$$\mathbf{E}_c[p(x|c)p(x'|c)]$$

# Examples

### **Examples of kernels** k(x, x')

Linear  $\langle x, x' \rangle$ 

Laplacian RBF  $\exp(-\lambda ||x - x'||)$ 

Gaussian RBF  $\exp(-\lambda ||x - x'||^2)$ 

Polynomial  $(\langle x, x' \rangle + c \rangle)^d, c \geq 0, d \in \mathbb{N}$ 

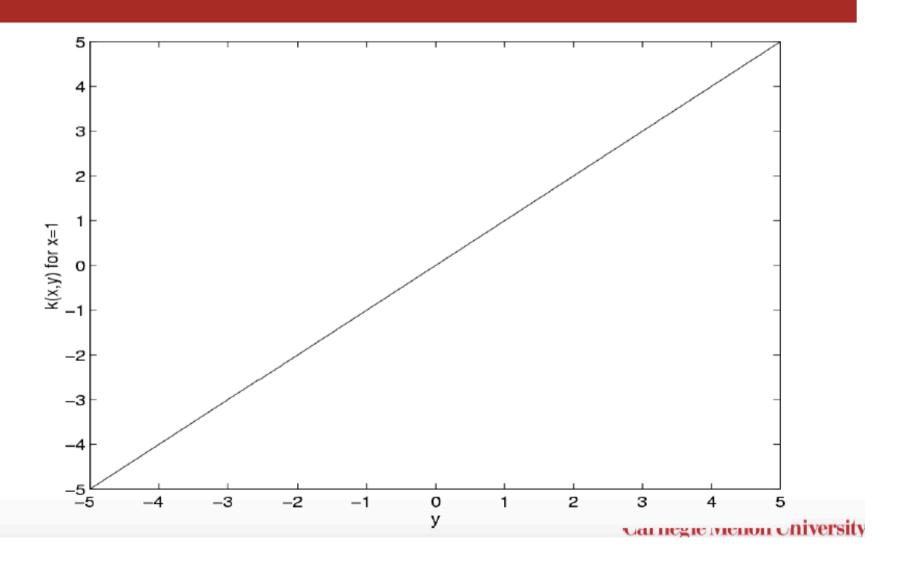
B-Spline  $B_{2n+1}(x-x')$ 

Cond. Expectation  $\mathbf{E}_c[p(x|c)p(x'|c)]$ 

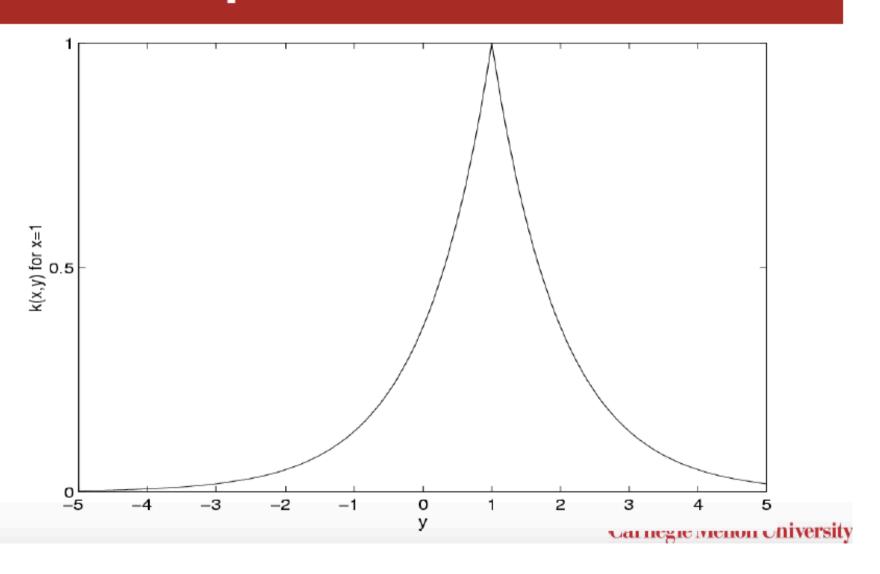
### Simple trick for checking Mercer's condition

Compute the Fourier transform of the kernel and check that it is nonnegative.

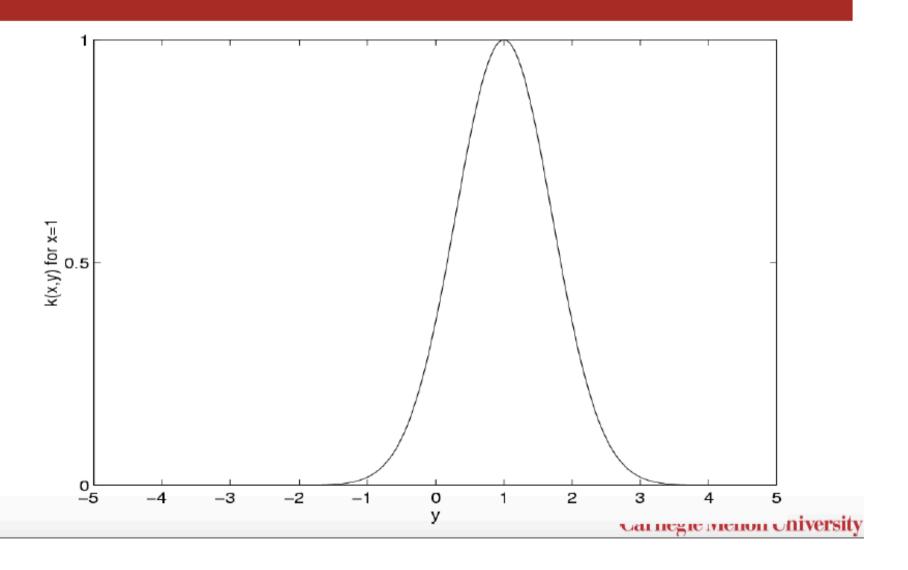
## Linear Kernel



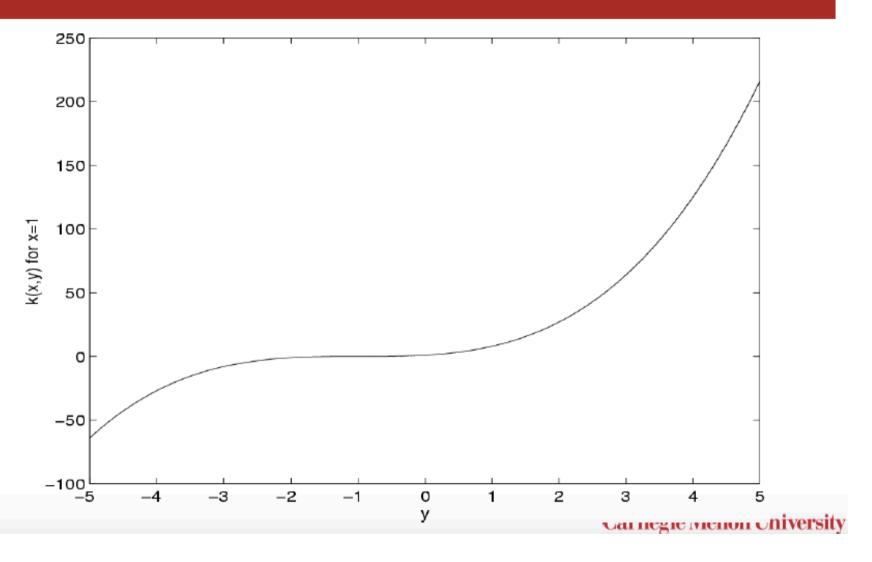
# Laplacian Kernel



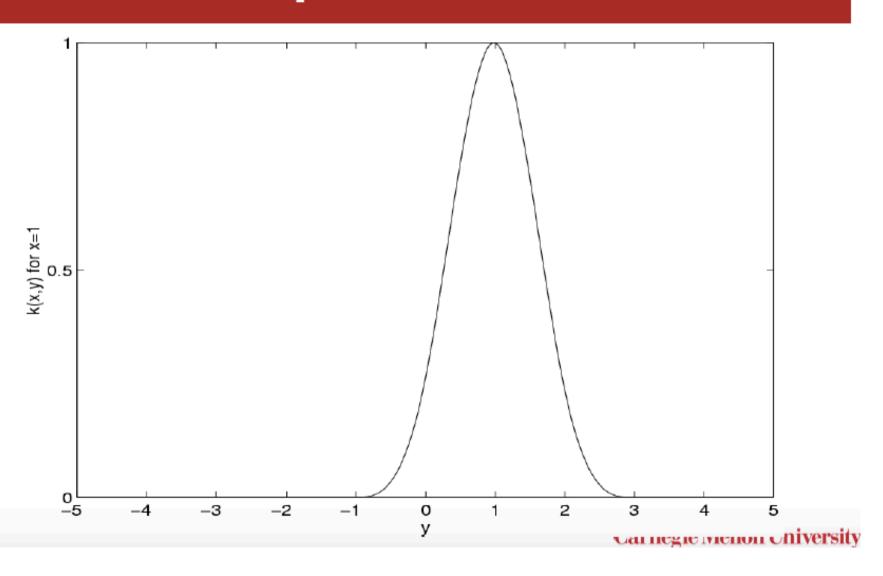
### Gaussian Kernel



# Polynomial of order 3



# B<sub>3</sub> Spline Kernel



5 minutes break!



## **Density Estimation**

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- Want to estimate p(x)

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- Want to estimate p(x)
  - Find unusual observations (e.g. security)
  - Find typical observations (e.g. prototypes)
  - Classifier via Bayes Rule

$$p(y|x) = \frac{p(x,y)}{p(x)} = \frac{p(x|y)p(y)}{\sum_{y'} p(x|y')p(y')}$$

Need tool for computing p(x) easily

## Bin Counting

- Discrete random variables, e.g.
  - English, Chinese, German, French, ...
  - Male, Female
- Bin counting (record # of occurrences)

25	English	Chinese	German	French	Spanish
male	5	2	3	1	0
female	6	3	2	2	1

## Bin Counting

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  - English, Chinese, German, French, ...
  - Male, Female
- Bin counting (record # of occurrences)

25	English	Chinese	German	French	Spanish
male	0.2	0.08	0.12	0.04	0
female	0.24	0.12	0.08	0.08	0.04

- Discrete random variables, e.g.
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not enough data

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# Curse of dimensionality (lite)

- Discrete random variables, e.g.
  - English, Chinese, German, French, ...
  - Male, Female
  - ZIP code
  - Day of the week
  - Operating system
  - ...

#bins grows exponentially

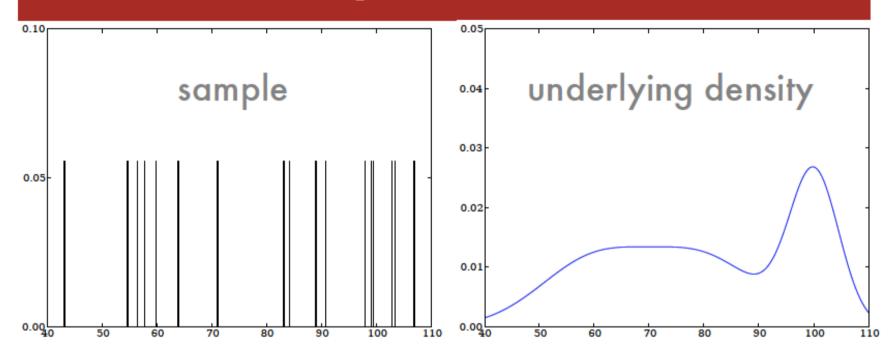
# Curse of dimensionality (lite)

- Discrete random variables, e.g.
  - English, Chinese, German, French, ...
  - Male, Female
  - ZIP code
  - Day of the week
  - Operating system
  - ...
- Continuous random variables
  - Income
  - Bandwidth
  - Time

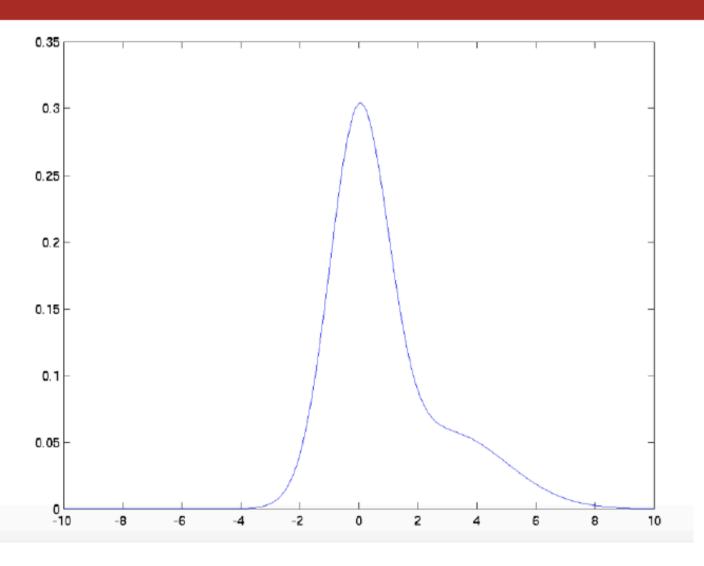
need many bins per dimension

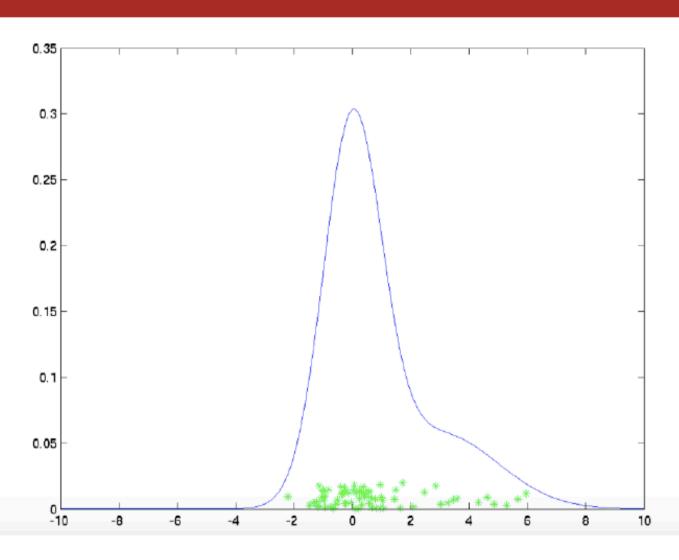
#bins grows exponentially

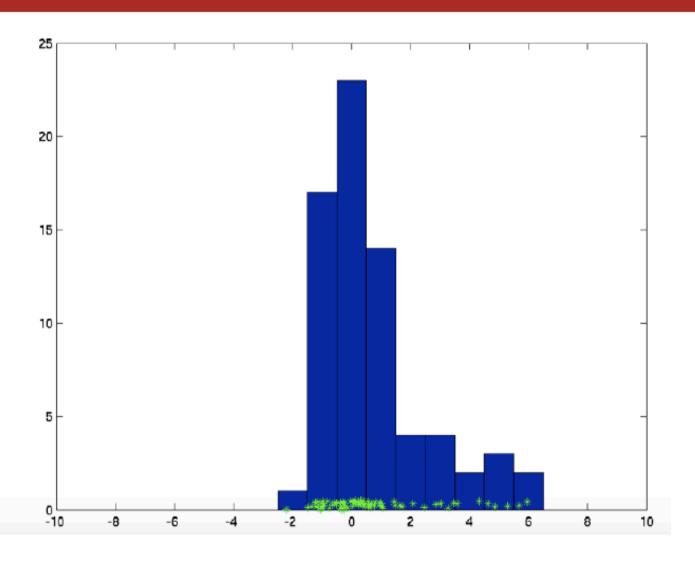
### Density Estimation

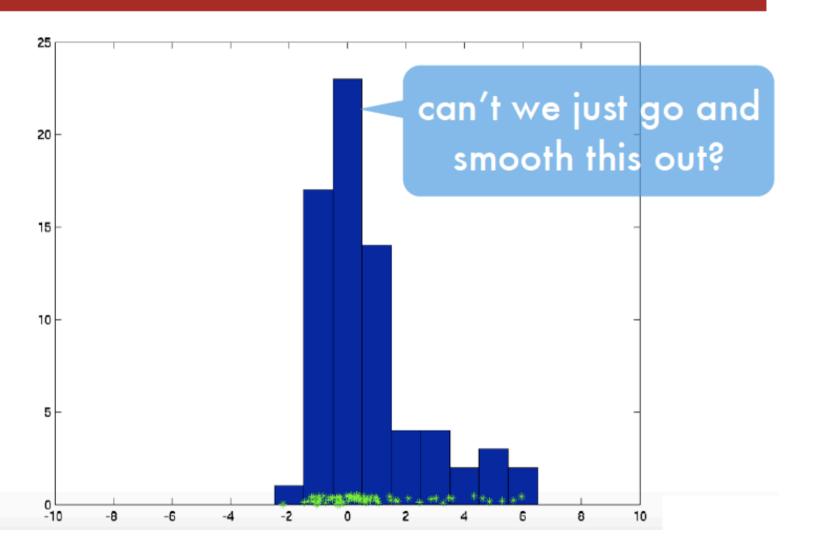


- Continuous domain = infinite number of bins
- Curse of dimensionality
  - 10 bins on [0, 1] is probably good
  - 10<sup>10</sup> bins on [0, 1]<sup>10</sup> requires high accuracy in estimate: probability mass per cell also decreases by 10<sup>10</sup>









Naive approach
 Use empirical density (delta distributions)

$$p_{\rm emp}(x) = \frac{1}{m} \sum_{i=1}^{m} \delta_{x_i}(x)$$

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- This breaks if we see slightly different instances
- Kernel density estimate
   Smear out empirical density with a nonnegative smoothing kernel k<sub>x</sub>(x') satisfying

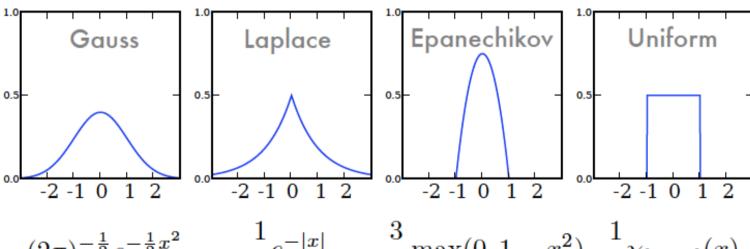
$$\int_{\mathcal{X}} k_x(x')dx' = 1 \text{ for all } x$$

#### Density estimate

$$p_{\text{emp}}(x) = \frac{1}{m} \sum_{i=1}^{m} \delta_{x_i}(x)$$

$$\hat{p}(x) = \frac{1}{m} \sum_{i=1}^{m} k_{x_i}(x)$$

#### Smoothing kernels



$$(2\pi)^{-\frac{1}{2}}e^{-\frac{1}{2}x^2} \qquad \frac{1}{2}e^{-|x|} \qquad \frac{3}{4}\max(0, 1 - x^2) \quad \frac{1}{2}\chi_{[-1,1]}(x)$$

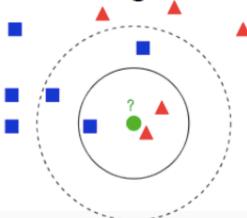
**Nearest Neighbor** 

# Nearest Neighbors

Table lookup
 For previously seen instance remember label

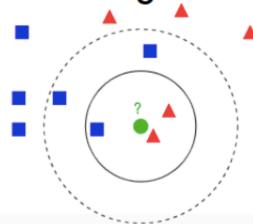
### Nearest Neighbors

- Table lookup
   For previously seen instance remember label
- Nearest neighbor
  - Pick label of most similar neighbor
  - Slight improvement use k-nearest neighbors

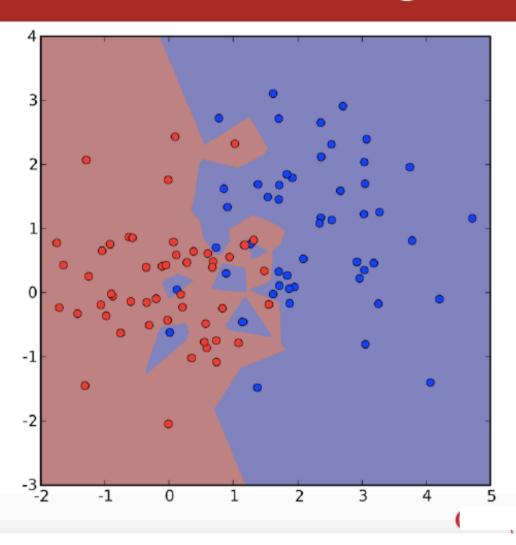


### Nearest Neighbors

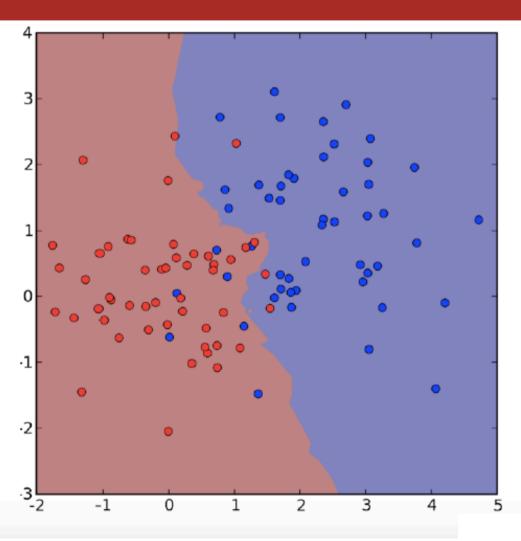
- Table lookup
   For previously seen instance remember label
- Nearest neighbor
  - Pick label of most similar neighbor
  - Slight improvement use k-nearest neighbors
  - Really useful baseline!
  - Easy to implement for small amounts of data.



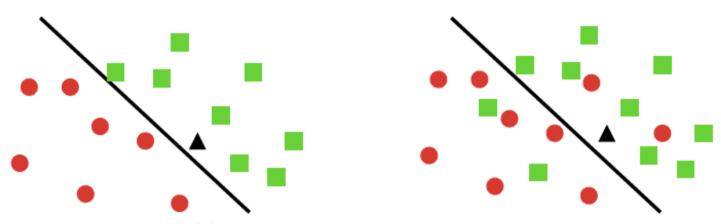
# 1-Nearest Neighbor



# 4-Nearest Neighbors Sign

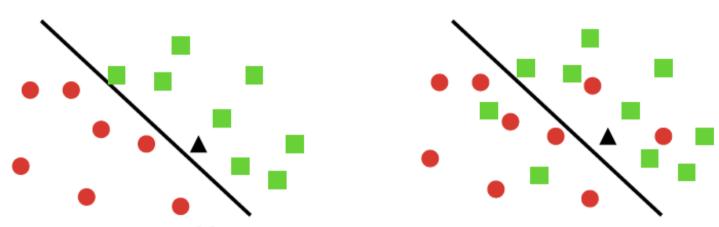


## If we get more data



- 1 Nearest Neighbor
  - Converges to perfect solution if separation
  - Twice the minimal error rate 2p(1-p) for noisy problems

## If we get more data



- 1 Nearest Neighbor
  - Converges to perfect solution if separation
  - Twice the minimal error rate 2p(1-p) for noisy problems
- k-Nearest Neighbor
  - Converges to perfect solution if separation (but needs more data)
  - Converges to minimal error min(p,1-p) for noisy problems (use increasing k)

That's all