Lecture 4:

Grid-point discretisation

Discretisation

When using digital computers variables, functions, operators etc. must be represented DISCRETELY.

→ an extra source of approximation in our models

Must therefore consider extra issues:

- Discretisation error
- Stability of numerical method

We will consider 2 broad classes of discretisation;

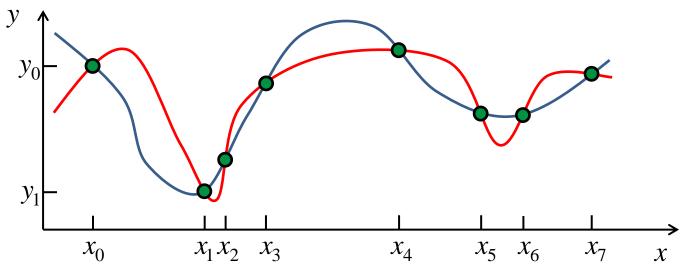
via grids and via basis sets.

Grid-point discretisation

Represent function y(x) and its derivatives $\frac{dy}{dx}$, $\frac{d^2y}{dx^2}$... using

only values of y at a discrete set of points $x_0, x_1, x_2... \equiv \{x_i\}$

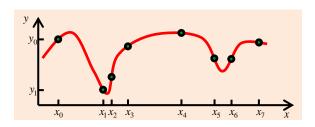
(a) Functions



Continuous y(x) represented by $y(x_0), y(x_1), y(x_2)...$; write $y(x_i) = y_i$, and the set of discrete values as $\{y_i\}$.

Many functions have same $\{y_i\}$, so issue with accuracy.

(b) Derivatives



Use Taylor series

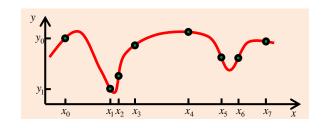
$$y(x+a) = y(x) + ay'(x) + \frac{a^2}{2}y''(x) + \dots + \frac{a^n}{n!}y^{(n)}(x) + \dots$$
 1

to approximate derivatives at grid points, using differences between the y_i

eg
$$y'(x)$$
: At grid point x_i , with $x_{i+1} = x_i + a$, ① gives
$$y(x_{i+1}) = y(x_i) + ay'(x_i) + \frac{a^2}{2}y''(x_i) + ...$$

$$\Rightarrow y'(x_i) = \frac{1}{a} \left\{ y(x_{i+1}) - y(x_i) - \frac{a^2}{2}y''(x_i) - ... \right\}$$
 or, in shorthand: $y_i' = \frac{1}{a} \left\{ y_{i+1} - y_i - \frac{a^2}{2}y_i'' - ... \right\}$

$$y_i' = \frac{1}{a} \left\{ y_{i+1} - y_i \middle| -\frac{a^2}{2} y_i'' - \dots \right\}$$



Terms from here are unknown.

OMIT them all, to yield the

"forward difference approximation" (FDA) to $y'(x_i)$:

$$y_i' \approx \frac{1}{a} \{ y_{i+1} - y_i \}.$$

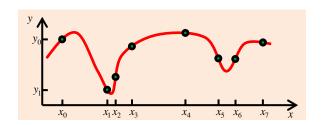
The discretisation error ε contains all the terms we omitted.

Here
$$\varepsilon = \frac{1}{a} \left\{ \frac{a^2}{2} y_i'' + \frac{a^3}{6} y_i''' + \dots \right\}$$



terms get smaller (if a is small)

So for small a, the first omitted term ($\propto a$) dominates ε ; we say that the FDA has discretisation error ε which is O(a).



Similarly, use Taylor

$$y(x-a) = y(x) - ay'(x) + \frac{a^2}{2}y''(x) + \dots + (-1)^n \frac{a^n}{n!}y^{(n)}(x) + \dots$$
 (2)

to obtain another approximation for the derivative at grid point x_i :

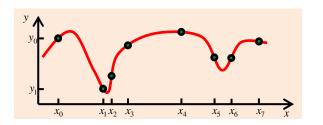
At grid point x_i , with $x_{i-1} = x_i - a$, gives

$$y(x_{i-1}) = y(x_i) - ay'(x_i) + \frac{a^2}{2}y''(x_i) + \dots$$

$$\Rightarrow y'(x_i) = \frac{1}{a} \left\{ y(x_i) - y(x_{i-1}) + \frac{a^2}{2}y''(x_i) - \dots \right\}$$

or, in shorthand:
$$y'_i = \frac{1}{a} \left\{ y_i - y_{i-1} + \frac{a^2}{2} y''_i - \dots \right\}$$

$$y_i' = \frac{1}{a} \left\{ y_i - y_{i-1} \right| + \frac{a^2}{2} y_i'' - \dots \right\}$$



Again,

OMIT all terms from here, to yield the "backward difference approximation" (BDA) to $y'(x_i)$:

$$y_i' \approx \frac{1}{a} \{ y_i - y_{i-1} \}.$$

It is easy to see that BDA also has discretisation error O(a).

$$O(a)$$
 errors aren't very good. If $a \to \frac{a}{2}$, $\varepsilon \to \frac{\varepsilon}{2}$.

Can usually do (a bit) better for not much effort.

Let us write the two versions of Taylor series side by side:

$$y(x+a) = y(x) + ay'(x) + \frac{a^2}{2}y''(x) + \dots + \frac{a^n}{n!}y^{(n)}(x) + \dots$$

$$y(x-a) = y(x) - ay'(x) + \frac{a^2}{2}y''(x) + \dots + (-1)^n \frac{a^n}{n!}y^{(n)}(x) + \dots$$
 (2)

1-2 yields a "centred-difference approximation" (CDA)

$$y_i' \approx \frac{1}{2a} \{ y_{i+1} - y_{i-1} \}.$$

Since the $\frac{a^2}{2}y''(x)$ terms cancel, ε is now $O(a^2)$.

Note that a <u>regularly-spaced grid</u> is a simple way to produce an $O(a^2)$ approximation to this derivative.

Let us summarize the three formulas we obtained for $y'(x_i)$:

Туре	Formula	Discretisation error
y', FDA	$y_i' \approx \frac{1}{a} \{ y_{i+1} - y_i \}$	O(a)
y', BDA	$y_i' \approx \frac{1}{a} \{ y_i - y_{i-1} \}$	<i>O</i> (<i>a</i>)
y', CDA	$y_i' \approx \frac{1}{2a} \{ y_{i+1} - y_{i-1} \}$	$O(a^2)$

Notes: 1) regular grid is required for CDA

2) FDA and BDA are useful for initial value problems (more details later!)

What about y''(x)?

$$y(x+a) = y(x) + ay'(x) + \frac{a^2}{2}y''(x) + \dots + \frac{a^n}{n!}y^{(n)}(x) + \dots$$

$$y(x-a) = y(x) - ay'(x) + \frac{a^2}{2}y''(x) + \dots + (-1)^n \frac{a^n}{n!}y^{(n)}(x) + \dots$$

1+2 gives

$$y_{i+1} + y_{i-1} = 2y_i + a^2y''(x_i) + \frac{a^4}{12}y''''(x_i) + \cdots$$

And so we obtain:

$$y''(x_i) = \frac{1}{a^2} \left[y_{i+1} + y_{i-1} - 2y_i \right] - \frac{a^4}{12} y''''(x_i) - \cdots$$
Omit terms from here.
Easy to see that the error is
$$O(a^2)$$
L4: Grid-point

A useful set of formulas for discrete derivatives:

Type	Formula	Error
y', FDA	$y_i' \approx \frac{1}{a} \{ y_{i+1} - y_i \}$	<i>O</i> (<i>a</i>)
y', BDA	$y_i' \approx \frac{1}{a} \{ y_i - y_{i-1} \}$	O(a)
y', CDA	$y_i' \approx \frac{1}{2a} \{ y_{i+1} - y_{i-1} \}$	$O(a^2)$
y'', CDA	$y''(x_i) \approx \frac{1}{a^2} [y_{i+1} + y_{i-1} - 2y_i]$	$O(a^2)$

Note: regular grid is required for CDA formulas!

• A side note: One could attempt to obtain $y''(x_i)$ by applying recursively the earlier derived formulas for y':

$$y''(x) = \frac{d}{dx}[y'(x)]$$
 $y''(x_i) \approx \frac{1}{2a}[y'(x_{i+1}) - y'(x_{i-1})]$ with $y'(x_i) \approx \frac{1}{2a}[y(x_{i+1}) - y(x_{i-1})]$

It is easy to see [check it yourself!] that this is equivalent to

$$y''(x_i) \approx \frac{1}{4a^2} [y_{i+2} + y_{i-2} - 2y_i]$$

I.e. we obtained exactly the same formula as we derived earlier, only with a twice larger discretization step $a \rightarrow 2a$

Hence the error is 4 times larger - do not do this!

Computational cost is the reason to chase $\varepsilon \sim O(a^2)$

Express in terms of required memory M and time T

Will see later that to solve a discretised problem with N grid points $M \sim N^2$ $T \sim N^3$

So for an ODE with fixed domain and regular grids, halving the grid spacing $a \to a/2$ requires $N \to 2N$ points leading to $M \to 4M$ and $T \to 8T$

- an expensive change if it only halves ϵ !
- $\varepsilon \sim O(a^2)$ is not great, but MUCH better than $\varepsilon \sim O(a)$

- There are many other discretisation approximations for various order derivatives – check literature. Different problems require different approaches.
- The four formulas we derived (FDA, BDA, CDA for y', and CDA for y'') are the most common.

• $O(a^3)$ errors are achievable, but require much more effort – often not practical.

An example: discretize the following Boundary Value Problem

$$y' + y^4 = 1$$

with Dirichlet conditions y(0) = 0, y(1) = 3

Summary:

- Grid-point discretization is at the core of numerical modelling of many ODE and PDE problems.
- There are many approximations for derivatives via finite differences. Most common are the central-difference based involving nearest neighbours, but other options are also available.
- Always need to consider the cost (in terms of memory and computation time) required to reduce the computation error.
- Solving ODEs and PDEs with grid-point discretization is generally known as the Finite Difference Method

Lecture 5:

Basis-set discretisation

Basis-set discretisation

Expand functions as a sum of BASIS FUNCTIONS.

$$f(t) = \sum_{n} c_n F_n(t) = c_1 F_1(t) + c_2 F_2(t) + c_3 F_3(t) + \cdots$$

 The sum is formally infinite, but will have to be truncated in numerics

- The (discrete) set of coefficients c_n describes the function
- BASIS functions are some known analytical functions. Some popular choices are:
 - Fourier series expansion (periodic functions)
 - Hermite polynomials (quantum harmonic oscillator type equations)
 - Hankel functions (dispersion/diffraction in radially symmetric geometries)

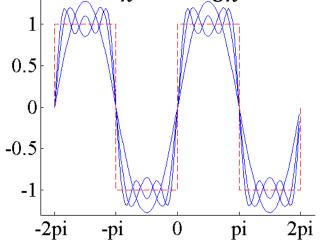
Basis-set discretisation

Expand functions as a sum of BASIS FUNCTIONS.

An example: Fourier series

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{in\omega t}; \quad g(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos(n\omega t) + b_n \sin(n\omega t) \right]$$

f(t) must be periodic! $f(t+T) = f(t) \ \forall \ t, \ T = 2\pi/\omega$ For a square wave $g(t) = \frac{4}{\pi} \sin t + \frac{4}{3\pi} \sin 3t + \frac{4}{5\pi} \sin 5t + \dots$



 $T=2\pi$; $\omega=1$

Note that g(t) is defined for ALL t.

Discretisation error (usually) arises once the sum is truncated. LS: Basis-set

Basis-set discretisation

How to choose a basis set?

$$f(t) = \sum_{n} c_n F_n(t) = c_1 F_1(t) + c_2 F_2(t) + c_3 F_3(t) + \cdots$$

Main criteria when selecting the set $F_n(t)$:

• (PREFERABLY) a COMPLETE and ORTHONORMAL set

(means you can expand ANY function)

(this is useful for deriving equations for c_n - see further examples)

Consistency with the auxiliary conditions

[e.g. complex exponents $F_n(t) = \exp(in\omega t)$ satisfy periodic boundary conditions: $F_n\left(t + \frac{2\pi}{\omega}\right) = F_n(t)$]

Speed of numerical conversion from/to the basis set

(i.e. for any function f(t) you should be able to obtain the corresponding set of coefficients c_n , and the same in the opposite direction)

Differential operators act on the individual basis functions.

eg
$$f(t) = \sum_{n} c_n e^{in\omega t}$$
; $\frac{df}{dt} = \sum_{n} in\omega c_n e^{in\omega t}$

So, to discretise an ODE via basis sets:

- Choose a set of basis functions
- Substitute expansion into ODE and re-write as an algebraic equation in the expansion coefficients (c_n)
- Truncate summation if computing...
- Make sure the auxiliary conditions are satisfied (can lead to additional conditions on c_n)

Complex Fourier series expansion

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 t}$$

Eigen-functions of differential operators

$$\frac{d^n}{dt^n}\exp(in\omega_0 t) = (in\omega_0)^n \exp(in\omega_0 t)$$

Requires periodic boundary condition!

$$f(t+T) = f(t) \qquad \omega_0 = 2\pi/T$$

The set is complete, and orthonormal:

$$e_l(t) = e^{il\omega_0 t}$$

$$e_m(t) = e^{im\omega_0 t}$$

$$\frac{1}{T} \int_0^T e_l^*(t) e_m(t) dt = \frac{1}{T} \int_0^T e^{i(m-l)\omega_0 t} dt = \delta_{l,m}$$

Kronecker delta:

$$\delta_{l,m} = \begin{cases} 0, & \text{if } l \neq m \\ 1, & \text{if } l = m \end{cases}$$

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$.

Actually, we know the analytical solution:

$$\Phi(x) = \frac{1}{6}x\left(x^2 - \frac{L^2}{4}\right),$$

But we will pretend we do not know it,

and try to find it numerically with point-grid and basis-set discretisations

$$\frac{d^2\Phi}{dx^2} = x, \qquad \Phi(-L/2) = 0, \qquad \Phi(L/2) = 0.$$
Grid discretisation:
$$a = \frac{L}{N+1}$$

$$-L/2 \quad X_1 \quad X_2 \quad X_N \quad L/2$$

$$\frac{1}{a^2} (\phi_{j+1} + \phi_{j-1} - 2\phi_j) = x_j = -\frac{L}{2} + j\frac{L}{N+1}, \qquad j = 2,3, \dots N-1$$

$$\frac{1}{a^2} (\phi_2 + \mathbf{0} - 2\phi_1) = x_1 = -\frac{L}{2} + \frac{L}{N+1}, \qquad j = 1$$

$$\frac{1}{a^2} (\mathbf{0} + \phi_{N-1} - 2\phi_N) = x_N = -\frac{L}{2} + N\frac{L}{N+1}, \qquad j = N$$

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$.

Grid discretisation
 linear matrix equation

$$\widehat{M}\overrightarrow{x} = \overrightarrow{b}$$
, $\overrightarrow{x} = [\phi_1, \phi_2, ..., \phi_N]^T$, - unknowns

$$\widehat{M} = \frac{1}{a^2} \begin{bmatrix} -2 & 1 & 0 & \cdots & \cdots & \cdots & 0 \\ 1 & -2 & 1 & 0 & \cdots & \cdots & 0 \\ 0 & 1 & -2 & 1 & 0 & \cdots & 0 \\ \cdots & \cdots & \ddots & \ddots & \ddots & \cdots & \cdots \\ 0 & \cdots & 0 & 1 & -2 & 1 & 0 \\ 0 & \cdots & \cdots & 0 & 1 & -2 & 1 \\ 0 & \cdots & \cdots & 0 & 1 & -2 \end{bmatrix}$$
- $N \times N$ tri-diagonal matrix

$$\vec{b} = \left[-\frac{L}{2} + \frac{L}{N+1}, -\frac{L}{2} + \frac{2L}{N+1}, \dots, -\frac{L}{2} + \frac{NL}{N+1} \right]^{T},$$

An important observation so far:

Our initial problem is a differential equation

$$\frac{d^2\Phi}{dx^2} = x,$$
 $\Phi(-L/2) = 0,$ $\Phi(L/2) = 0.$

By implementing grid-point discretization, we reduced it to the linear algebra problem (a set of linear algebraic equations):

$$\widehat{M}\vec{x}=\vec{b},$$

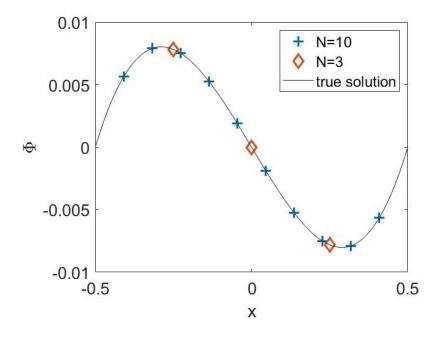
for the N-component vector of unknowns \vec{x} which gives N values of the (discretized) function $\Phi(x)$ at regular grid points in the interval (-L/2, L/2)

This linear algebra problem can be solved on a computer (we will learn later how!)

• **Grid discretisation** → linear matrix equation

$$\vec{x} = [\phi_1, \phi_2, ..., \phi_N]^T$$
, - unknowns $\vec{b} = [a, 2a, 3a, ..., Na]^T$,

Solve the matrix equation numerically (e.g. in Matlab):



See "test_grid_point_vs_basis_set.m" matlab code uploaded on Moodle page

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$.

Basis set

$$\Phi(x) = \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 x} \qquad \text{select} \quad \omega_0 = 2\pi/L$$

Note: this means $\Phi(x + L) = \Phi(x)$

Compatible with the boundary conditions??

Dirichlet BC sets the value for $\Phi(0)$ – this is more restricting than periodic BC!

Substitute into the equation:

$$-\sum_{n}(n\omega_0)^2c_ne^{in\omega_0x}=x$$

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$

$$\Phi(x) = \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 x}, \qquad \omega_0 = 2\pi/L$$

$$-\sum_{n}(n\omega_0)^2c_ne^{in\omega_0x}=x$$

Apply "closure": multiply both sides by $\exp(-im\omega_0 x)$ and integrate over the period:

$$-\sum_{n}(n\omega_{0})^{2}c_{n}\frac{1}{L}\int_{0}^{L}\exp[i(n-m)\omega_{0}x]dx = \frac{1}{L}\int_{0}^{L}x\exp[-im\omega_{0}x]dx$$

$$\uparrow \qquad \qquad \uparrow$$

$$= \delta_{n,m} \text{ (orthogonality)}$$

$$= \frac{1}{L}\int_{0}^{L}x\exp[-im\omega_{0}x]dx$$

$$= F_{m} \text{ (Fourier series coefficient of } [the periodic version] of } f(x) = x)$$



$$(m\omega_0)^2 c_m = -F_m = \frac{i(-1)^m}{m\omega_0}$$

Note: in this example the integral is easy to tackle analytically and obtain this result for F_m . In real-life situation, you will need to compute such integrals numerically. We will learn how to do it later! (Fast Fourier Transforms)

L5: Basis-set

$$\frac{d^2\Phi}{dx^2} = x,$$

$$\Phi(-L/2) = 0, \qquad \Phi(L/2) = 0$$

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$ $\Phi(x) = \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 x}$, $\omega_0 = 2\pi/L$

$$(m\omega_0)^2 c_m = -F_m = \frac{i(-1)^{m+1}}{m\omega_0}$$

In this case, we obtained a trivial set of equations for c_m coefficients, which we can solve by hand:

$$c_m = \frac{i(-1)^{m+1}}{(m\omega_0)^3}$$

- But what about c_0 ?? $(0 \cdot \omega_0)^2 c_0 = -F_0$
- It is easy to see that $F_0 = \frac{1}{L} \int_0^L x \exp[-i(0 \cdot \omega_0)x] dx = 0$
- Does that mean that c_0 can be anything??

No! Need to satisfy Auxiliary Conditions!

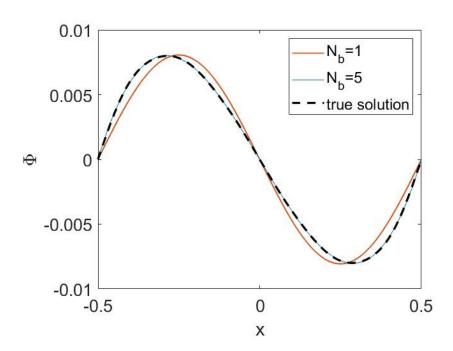
ightharpoonup Need to set $c_0=0$

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$

Basis-set

$$\Phi(x) = \sum_{\substack{n = -\infty, \\ n \neq 0}}^{\infty} \frac{i(-1)^{m+1}}{(m\omega_0)^3} e^{in2\pi x},$$

In practice, you will need to truncate this sum at some $n = \pm N_h$



See "test_grid_point_vs_basis_set.m" matlab code uploaded on Moodle page

Original problem: linear ODE boundary value problem

$$\frac{d^2\Phi}{dx^2} = x$$
, $\Phi(-L/2) = 0$, $\Phi(L/2) = 0$



1. Discretize

Grid: $\phi_j = \Phi(\mathbf{x}_j)$

E.g. for N=3 points:

$$\frac{1}{(L/4)^2}(\phi_3 + \phi_1 - 2\phi_2) = 0,$$

$$\frac{1}{(L/4)^2}(\phi_2 - 2\phi_3) = \frac{L}{4},$$

$$\frac{1}{(L/4)^2}(\phi_2 - 2\phi_1) = -\frac{L}{4},$$

Basis-set: $\Phi(\mathbf{x}) = \sum_{n} c_n \exp\left(in\left(\frac{2\pi}{L}\right)t\right)$

Truncate infinite sum e.g. for $-1 \le n \le 1$

$$\left(-\frac{2\pi}{L}\right)^2 c_{-1} = -\frac{iL}{2\pi}$$

$$c_0 = 0$$

$$\left(\frac{2\pi}{L}\right)^2 c_1 = \frac{iL}{2\pi}$$

- 2. Solve (on a computer) the set of linear algebraic equations
- 3. Obtain values of the function at the grid points ϕ_i

3. Obtain values of the expansion coefficients c_n

Summary:

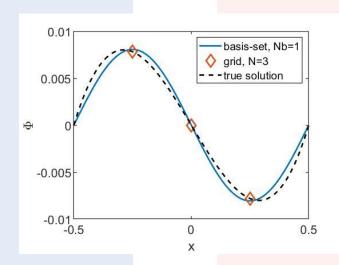
Grid



Basis-set

- Easy to setup, including various auxiliary conditions
- Reduces the problem to the set of N coupled algebraic equations

(in higher-dimensional problems the number of equations grows exponentially!)



- Requires some effort to setup, take special care of:
- auxiliary conditions;
- choice of the basis set
- Reduces the problem to the set of N coupled algebraic equations

(with a proper basis set choice) easy to solve and/or have good convergence (i.e. require only few equations to solve)

 Solution is obtained at discrete points
 => may be problematic for postprocessing Solution is obtained in analytic form: convenient for post-processing BUT can have poor convergence Lecture 6:

Discretisation: ODEs with variable coefficients and nonlinear ODEs

An example: find localized states in a 1D quantum well

$$-\frac{\hbar^2}{2m}\frac{d^2\Psi}{dx^2} + \mathbf{V}(\mathbf{x})\Psi = E\Psi,$$

1) De-dimensionalize:

$$x = \frac{\hbar}{\sqrt{2mE_0}} \xi$$

$$E = E_0 \epsilon$$

$$-\frac{d^2 \Psi}{d\xi^2} + \mathbf{u}(\xi) \Psi = \epsilon \Psi,$$

 E_0 - a "characteristic" energy (can choose a value to rescale the potential function $u=V/E_0$)

2) Interested in localized states only => can have freedom in choosing boundary conditions for large enough computational window

Note: how large is "large"? Requires some physical intuition!

3) Attempt point-grid and basis-set (Fourier) discretisations

ODE with a variable coefficient

Grid (v1): Dirichlet BCs: $\Psi(-L/2) = 0$, $\Psi(L/2) = 0$ $-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi$,

4(3),~

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

$$\Psi\left(-\frac{L}{2}\right)$$
 is set by BC!

Similar on this end

the grid starts at

$$\xi = -\frac{L}{2} + a$$

Grid step

$$a = L/(N+1)$$



$$-\frac{1}{a^2}(\Psi_{j+1} + \Psi_{j-1} - 2\Psi_j) + u_j\Psi_j = \epsilon \Psi_j, \qquad j = 2,3,...N - 1$$

$$-\frac{1}{a^2}(\Psi_2 + \mathbf{0} - 2\Psi_1) + u_1\Psi_1 = \epsilon \Psi_1, \qquad j = 1$$

$$-\frac{1}{a^2}(\mathbf{0} + \Psi_{N-1} - 2\Psi_N) + u_N\Psi_N = \epsilon \Psi_N, \quad j = N$$

Grid (v2): Neumann BCs: $\Psi'(-L/2) = 0$, $\Psi'(L/2) = 0$ $-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi$, $\Psi\left(-\frac{L}{2}\right)$ is not

known!

Grid step

Similar on this end

Similar on this end

$$3 = \frac{1}{2}$$

Grid step

 $a = L/(N-1)$

Window of SiRe L

$$-\frac{1}{a^2}(\Psi_{j+1} + \Psi_{j-1} - 2\Psi_j) + u_j\Psi_j = \epsilon \Psi_j, \qquad j = 2,3,...N - 1$$

Apply BCs V2a: Use FDA/BDA

$$-\frac{1}{a^2}(\Psi_2 + \Psi_1 - 2\Psi_1) + u_1\Psi_1 = \epsilon \Psi_1, \quad j = 1 \quad a\Psi_1' = (\Psi_1 - \Psi_0)$$

$$-\frac{1}{\sigma^2}(\Psi_N + \Psi_{N-1} - 2\Psi_N) + u_N \Psi_N = \epsilon \Psi_N, \quad j = N \quad a\Psi_N' = (\Psi_{N+1} - \Psi_N)$$

L6: Further examples

Grid (v2): Neumann BCs: $\Psi'(-L/2) = 0$, $\Psi'(L/2) = 0$ $-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi$,

$$\Psi\left(-\frac{L}{2}\right)$$
 is not

Similar on this end

$$3 = \frac{1}{2}$$

Grid step

 $a = L/(N-1)$

Similar on this end

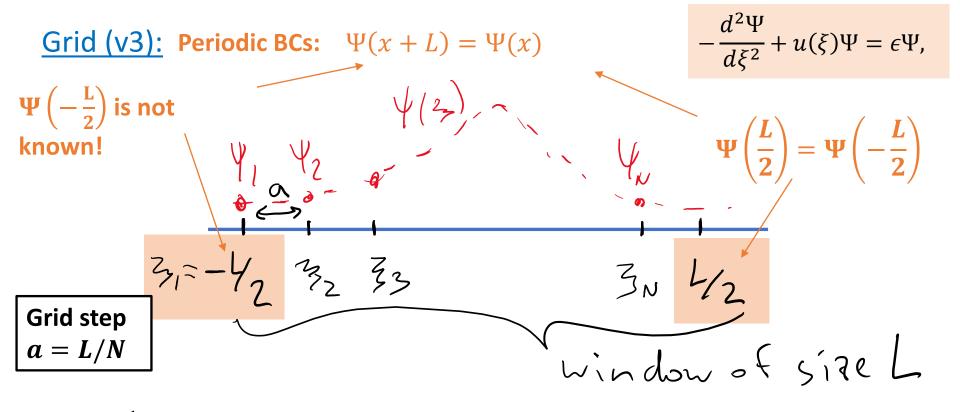
 $3 = \frac{1}{2}$

Window of SiRe L

$$-\frac{1}{a^2}(\Psi_{j+1} + \Psi_{j-1} - 2\Psi_j) + u_j\Psi_j = \epsilon \Psi_j, \qquad j = 2,3, \dots N - 1$$

Apply BCs V2b: Use CDA
$$-\frac{1}{a^2}(\Psi_2 + \Psi_2 - 2\Psi_1) + u_1\Psi_1 = \epsilon \Psi_1, \quad j = 1 \qquad \Psi_1' = \frac{\Psi_2 - \Psi_0}{2a}$$

$$-\frac{1}{a^2}(\Psi_{N-1} + \Psi_{N-1} - 2\Psi_N) + u_N \Psi_N = \epsilon \Psi_N, \quad j = N \quad \Psi_N' = \frac{\Psi_{N+1} - \Psi_{N-1}}{2a}$$
L6: Further examples



$$-\frac{1}{a^2}(\Psi_{j+1} + \Psi_{j-1} - 2\Psi_j) + u_j\Psi_j = \epsilon \Psi_j, \qquad j = 2,3,...N - 1$$

Apply BCs:

$$-\frac{1}{a^{2}}(\Psi_{2} + \Psi_{N} - 2\Psi_{1}) + u_{1}\Psi_{1} = \epsilon \Psi_{1}, \quad j = 1$$

$$-\frac{1}{a^{2}}(\Psi_{1} + \Psi_{N-1} - 2\Psi_{N}) + u_{N}\Psi_{N} = \epsilon \Psi_{N}, \quad j = N$$

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

Eigen-value problem

$$\widehat{M}\vec{x}=\epsilon\vec{x},$$

$$\vec{\chi} = [\Psi_1, \Psi_2, ..., \Psi_N]^T$$
 - Unknown discretized wave function (eigen-vector)

∈ - Unknown energy (eigen-value)

Note: expect real values for ϵ , but complex \vec{x}

$$\widehat{M} = \frac{1}{a^2} \begin{bmatrix} A + a^2u_1 & B & 0 & \cdots & \cdots & C \\ -1 & 2 + a^2u_2 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & -1 & \ddots & -1 & 0 & \cdots & 0 \\ \cdots & \cdots & \ddots & \ddots & \ddots & \cdots & \cdots \\ 0 & \cdots & 0 & -1 & \ddots & -1 & 0 \\ 0 & \cdots & 0 & -1 & \ddots & -1 & 0 \\ 0 & \cdots & \cdots & 0 & -1 & \ddots & -1 \\ C & \cdots & \cdots & 0 & B & A + a^2u_N \end{bmatrix}$$
- $N \times N$ sparce matrix

• coeffs A,B,C are determined by BCs

• real matrix

• symmetric

- $N \times N$ sparce matrix

- Tri-diagonal, unless using periodic BCs

L6: Further examples

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

Eigen-value problem

$$\widehat{M}\vec{x}=\epsilon\vec{x},$$

Use numerical algorithms to solve the eigen-value problem



Can try to utilize an optimized method for the specific properties of \widehat{M}

- **Expect** *N* **eigenvalues (and eigenvectors)**
- How to identify *LOCALIZED* eigenvectors?



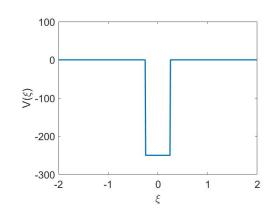
E.g. expect negative energies for localized states

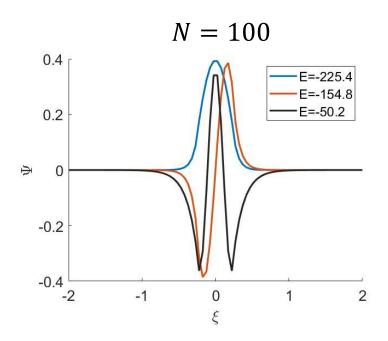
$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

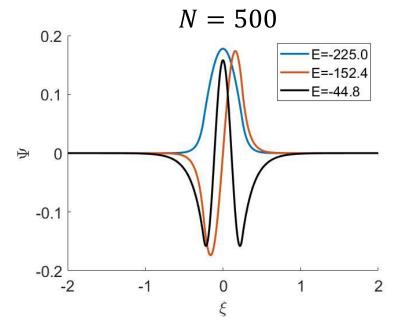
• Eigen-value problem

$$\widehat{M}\vec{x}=\epsilon\vec{x},$$

Numerically obtained eigen-states in a square well potential







See "Schroedinger_ev_point_grid.m" matlab code uploaded on Moodle page

A useful shortcut

 $-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$

 Eigen-states of a <u>linear</u> (!) symmetric problem inherit the symmetry (are either odd- or even-)

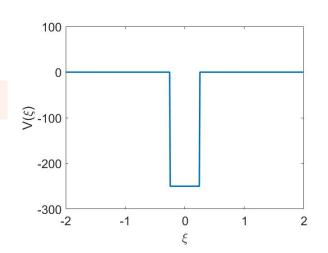
Note: This is only true for linear problems

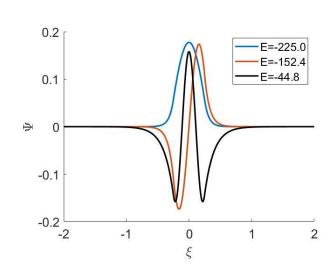
• Could solve on half-interval with the symmetry conditions imposed at x = 0:

$$\Psi(-x) = \Psi(x)$$

AND
$$\Psi(-x) = -\Psi(x)$$

- Reduce the number of grid points by half, but need to solve twice. Do you gain anything?
- Remember for matrix problems such as eigenvalue memory scales as $M \sim N^2$ and time scales as $T \sim N^3$
- YES, the gain is worth the effort, especially for large grids





Basis-set (using Fourier Series):

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

$$\Psi(\xi) = \sum_{n=0}^{\infty} c_n e^{in\omega_0 \xi}, \qquad \omega_0 = \frac{2\pi}{L}$$

• Substitute:

Note: Using Fourier series expansion => assume periodic boundary conditions

$$-\sum_{n=-\infty}^{\infty} (-n\omega_0)^2 c_n e^{in\omega_0 \xi} + u(\xi) \cdot \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 \xi} = \epsilon \cdot \sum_{n=-\infty}^{\infty} c_n e^{in\omega_0 \xi}$$

• **Apply "closure"** (multiply by $e^{-im\omega_0\xi}$ and integrate $\left(\frac{1}{L}\right)\int_0^L \dots d\xi$):

$$-\sum_{n=-\infty}^{\infty}(-n\omega_0)^2c_n\delta_{n,m}+\frac{1}{L}\int_0^Lu(\xi)\cdot\sum_{n=-\infty}^{\infty}c_n\mathrm{e}^{i(n-m)\omega_0\xi}\,d\xi=\epsilon\cdot\sum_{n=-\infty}^{\infty}c_n\delta_{n,m}$$

Basis-set (using Fourier Series):

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

$$-\sum_{n=-\infty}^{\infty}(-n\omega_0)^2c_n\delta_{n,m} + \frac{1}{L}\int_0^L u(\xi)\cdot\sum_{n=-\infty}^{\infty}c_n\mathrm{e}^{i(n-m)\omega_0\xi}\,d\xi = \epsilon\cdot\sum_{n=-\infty}^{\infty}c_n\delta_{n,m}$$

$$m^2 \omega_0^2 c_m + \sum_{n=-\infty}^{\infty} U_{m-n} \cdot c_n = \epsilon \cdot c_m$$

where

$$U_{m-n} = \frac{1}{L} \int_{0}^{L} u(\xi) e^{-i(m-n)\omega_{0}\xi} d\xi$$

is (m-n)th complex Fourier Series coefficient of the *(periodic version of)* potential function $u(\xi)$

Basis-set (using Fourier Series):

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

Can write it in the matrix form:

$$\widehat{M}\vec{c}=\epsilon\vec{c},$$

$$\Psi(\xi) \approx \sum_{n=-N}^{N} c_n e^{in(2\pi/L)\xi},$$

 $-if u(-\xi) = u(\xi) \Rightarrow U_k = U_{-k}$

=> symmetric matrix

$$\vec{c} = [c_{-N}, c_{-N+1}, \dots, c_0, c_1, \dots, c_N]^T$$
 - Unknown Fourier coeffs (eigen-vector)

 ϵ - Unknown energy (eigen-value)

$$\widehat{M} = \begin{bmatrix} D_{-N} & U_{-1} & U_{-2} & \cdots & \cdots & \cdots & U_{-2N} \\ U_1 & D_{-N+1} & U_{-1} & U_{-2} & \cdots & \cdots & U_{-2N+1} \\ U_2 & U_1 & \ddots & \ddots & \ddots & \cdots & \cdots \\ \cdots & \cdots & U_1 & D_0 & U_{-1} & \cdots & \cdots \\ \cdots & \cdots & \cdots & \ddots & D_1 & \ddots & \cdots \\ U_{2N} & \cdots & \cdots & \cdots & U_2 & U_1 & D_N \end{bmatrix} - (2N+1) \times (2N+1)$$

$$full \ matrix$$

$$- Real \ u(\xi) \Rightarrow U_k = U_{-k}^*$$

$$=> Hermitian \ matrix$$

$$D_k = k^2 \omega_0^2 + U_0$$
 $U_k = \frac{1}{L} \int_0^L u(\xi) e^{-ik\omega_0 \xi} d\xi$

Basis-set vs grid

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$

 For a comparable matrix size, basis-set approach will take much longer to solve

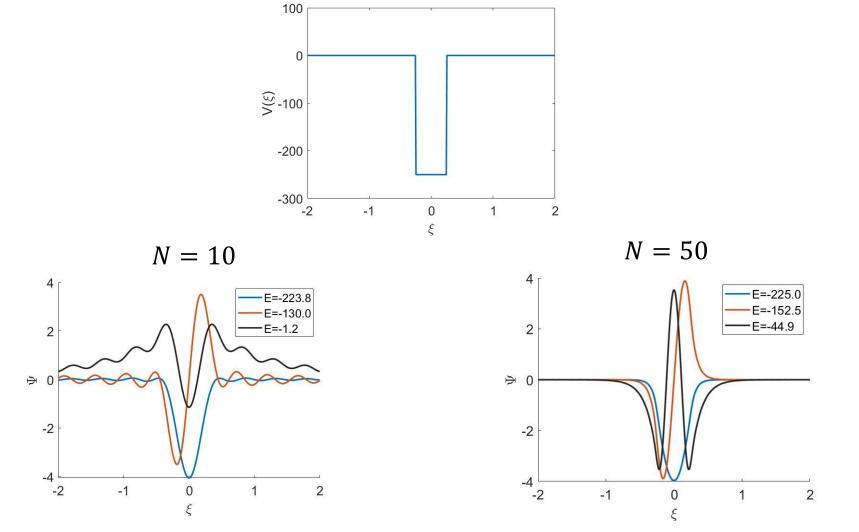
Discretization error in basis-set is due to truncation in the Fourier series.
 The required number of harmonics depends on the problem

$$\Psi(\xi) \approx \sum_{n=-N}^{N} c_n e^{in(2\pi/L)\xi},$$

 Basis-set could still be advantageous, if the Fourier series convergence is good

Basis-set: square well potential example

$$-\frac{d^2\Psi}{d\xi^2} + u(\xi)\Psi = \epsilon\Psi,$$



See "Schroedinger_ev_basis_set.m" matlab code uploaded on Moodle page

Another example: nonlinear pendulum

$$\ddot{\theta} + \frac{g}{l}\sin\theta = 0, \qquad \theta(0) = 0, \qquad \theta(T) = 0$$

1) De-dimensionalize:

$$t = \sqrt{l/g} \tau \qquad \Longrightarrow \qquad \frac{d^2\theta}{d\tau^2} + \sin\theta = 0, \qquad \theta(0) = 0, \theta(\tau_0) = 0$$

$$T_0 = \sqrt{l/g}$$
 - Period of the linear pendulum (i.e. in the limit $heta \ll 1$)

$$\tau_0 = T/T_0$$
 - Dimensionless period

$$\frac{d^2\theta}{d\tau^2} + \sin\theta = 0, \qquad \theta(0) = 0, \theta(\tau_0) = 0$$

$$\frac{1}{a^2}(\theta_{j+1} + \theta_{j-1} - 2\theta_j) + \sin \theta_j = 0, j = 2,3, \dots N - 1$$

$$\frac{1}{a^2}(\theta_2 - 2\theta_1) + \sin \theta_1 = 0, j = 1$$

$$\frac{1}{a^2}(\theta_{N-1} - 2\theta_N) + \sin \theta_N = 0, j = N$$

A system of coupled nonlinear algebraic equations

Basis-set (using Fourier):

$$\frac{d^2\theta}{d\tau^2} + \sin\theta = 0, \qquad \theta(0) = 0, \theta(\tau_0) = 0$$

$$heta(au) = \sum_n c_n e^{in\omega_0 au}$$
 , $\omega_0 = 2\pi/ au_0$

$$-(n\omega_0)^2 c_n + \frac{1}{\tau_0} \int_0^{\tau_0} e^{-in\omega_0 \tau} \sin \left[\sum_k c_k e^{ik\omega_0 \tau} \right] d\tau = 0,$$

A (much more complicated!) system of coupled nonlinear integral equations

Summary:

 Grid-point discretization is much easier to implement for ODEs and PDEs with variable coefficients.

 Basis-set discretisation is only useful if the convergence is good (smaller size matrix problems compared to grid-point).

Need to be smart with the choice of the basis! Fourier series is not necessarily the best option.

Basis-set is generally not a good idea for solving nonlinear problems

BUT we will re-consider this problem later...