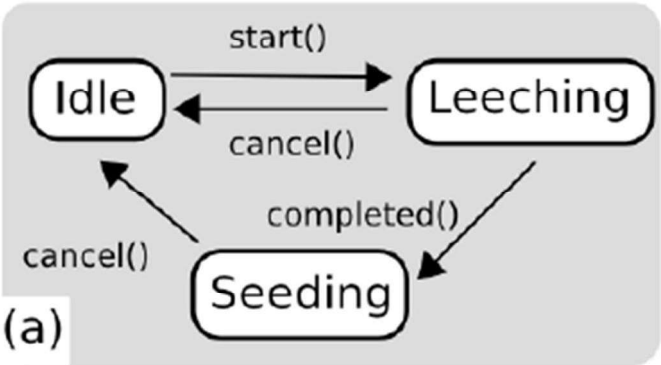
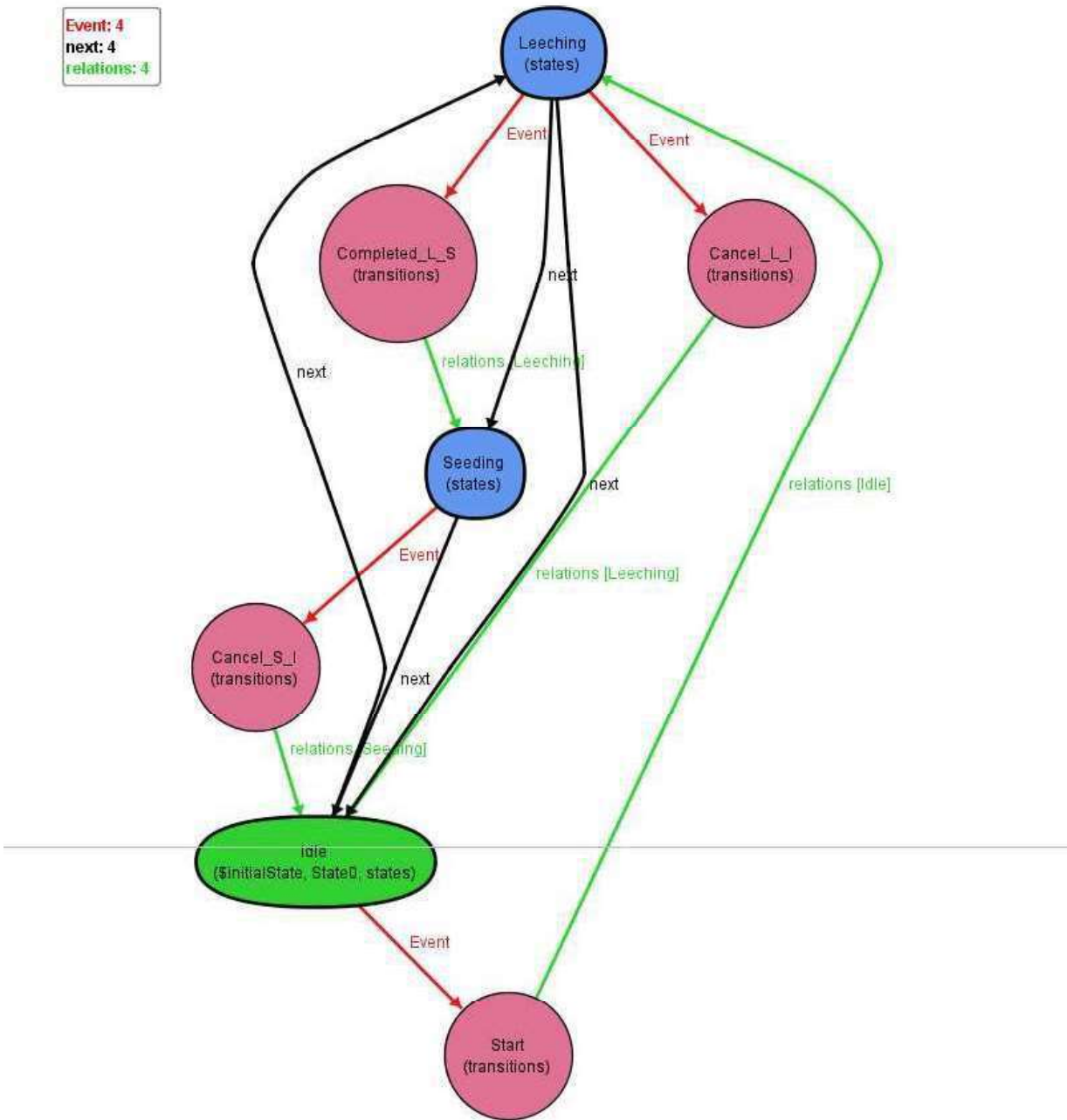


Executing showExamples will return the 6 possible scenarios of our peer-to-peer file sharing system:

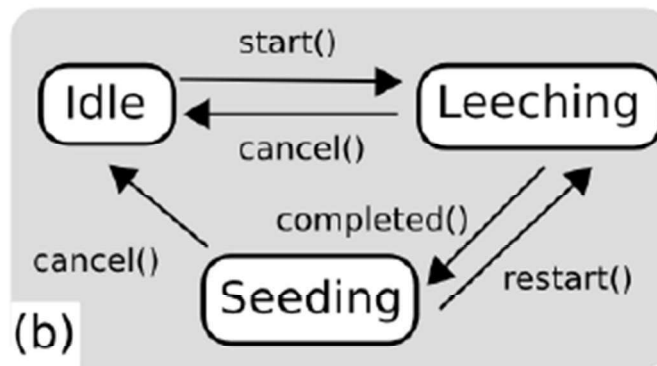
- Scenario 1.1



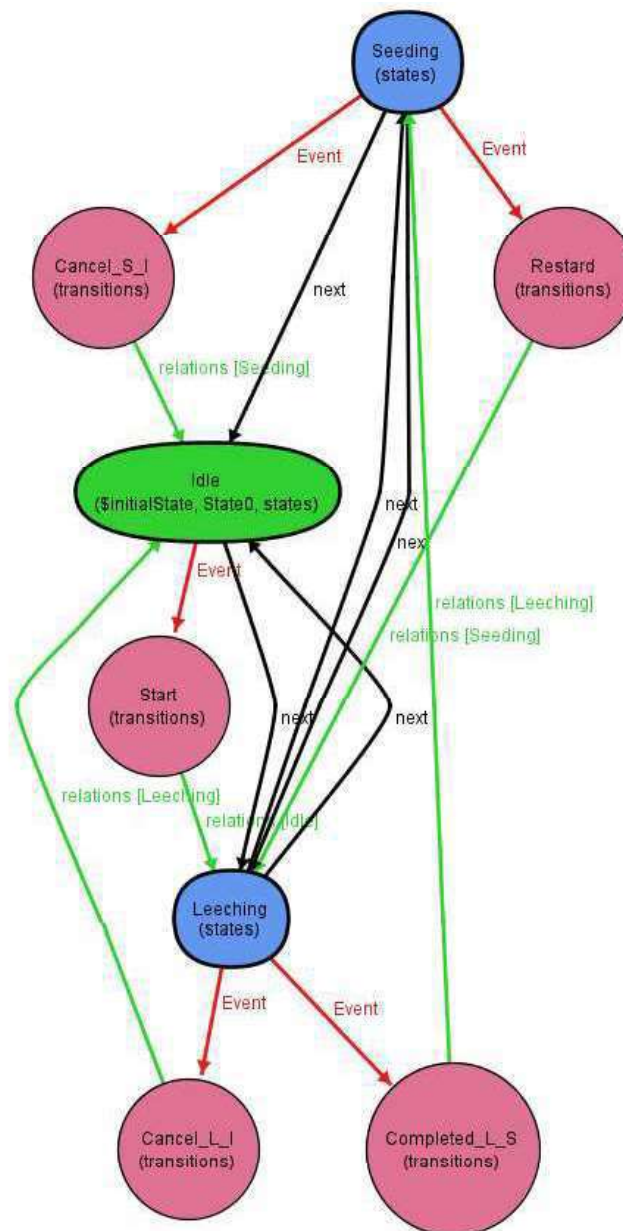
Event: 4
next: 4
relations: 4



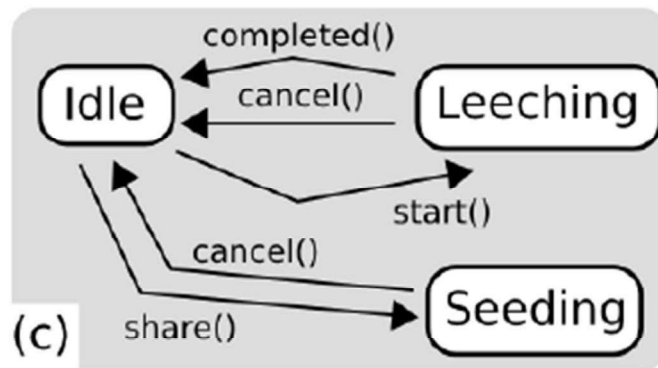
- Scenario 12



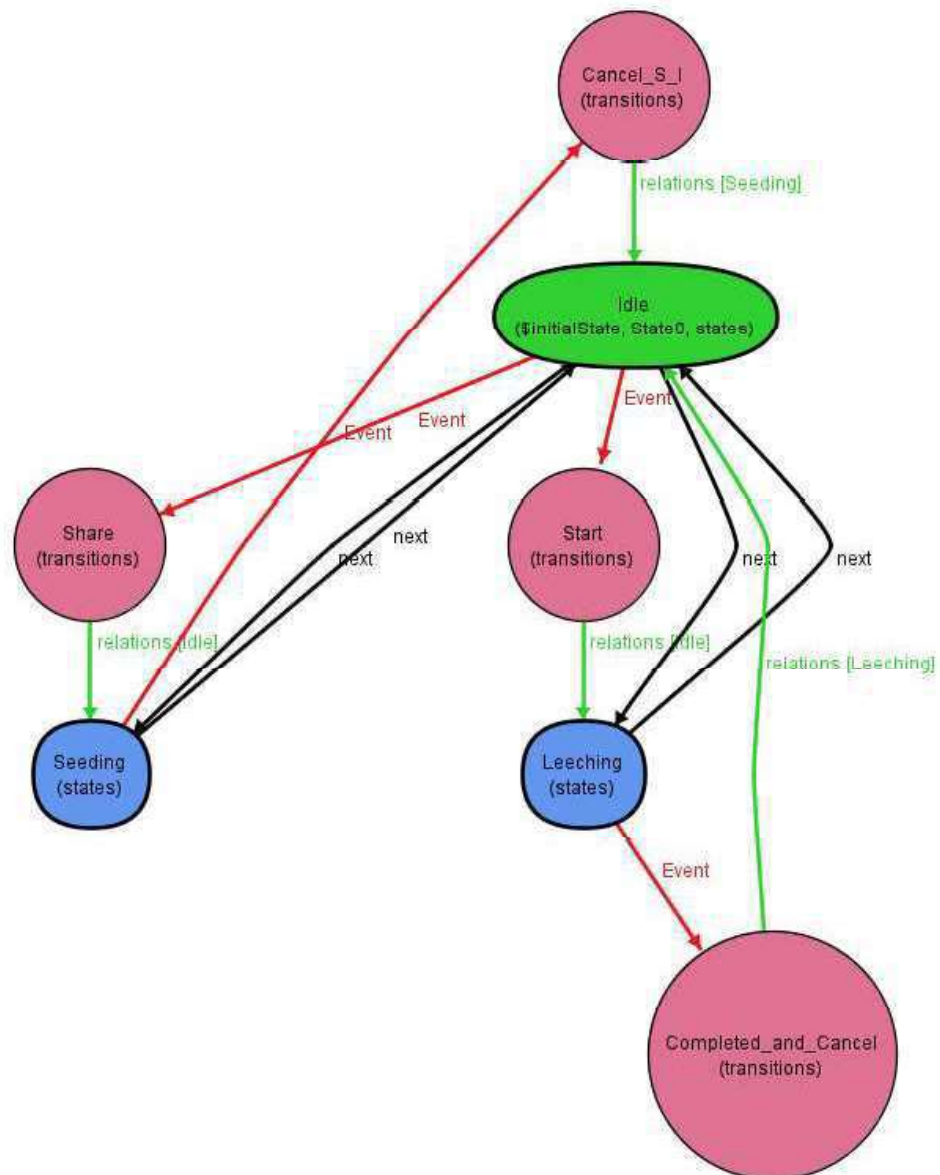
Event: 5
next: 5
relations: 5



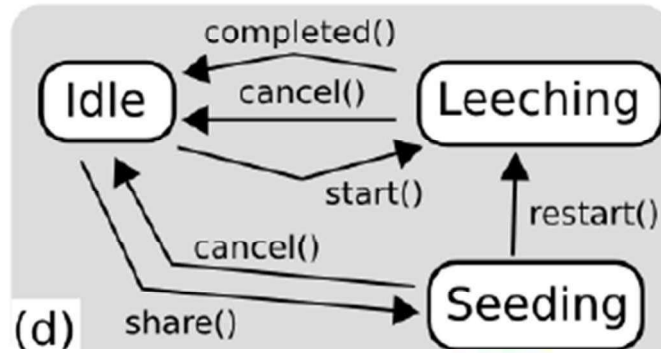
- Scenario 21



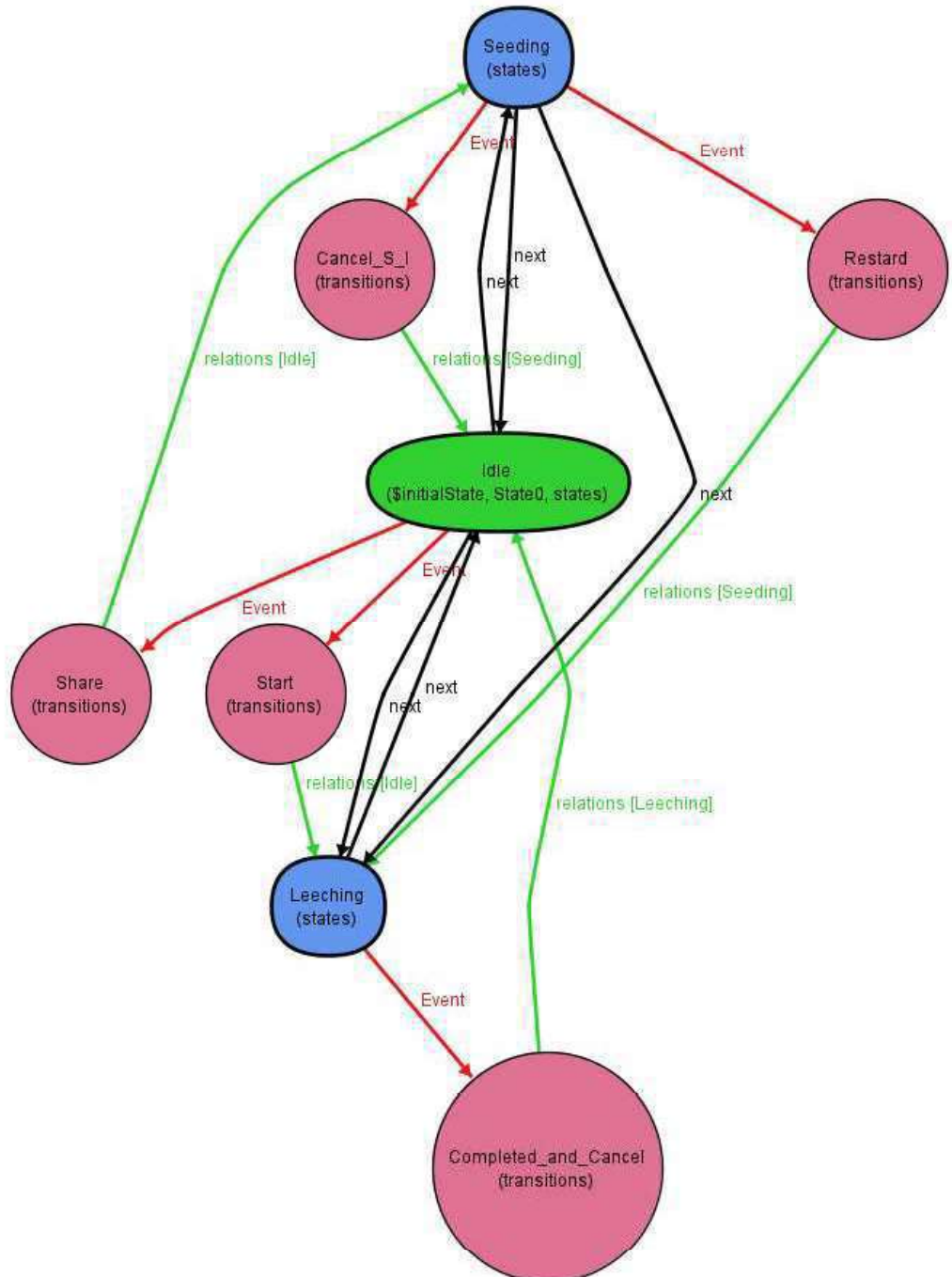
Event: 4
next: 4
relations: 4



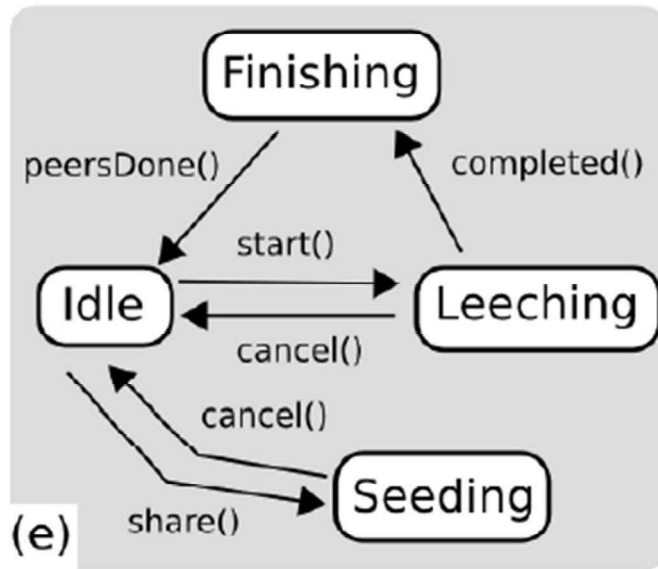
- Scenario 22



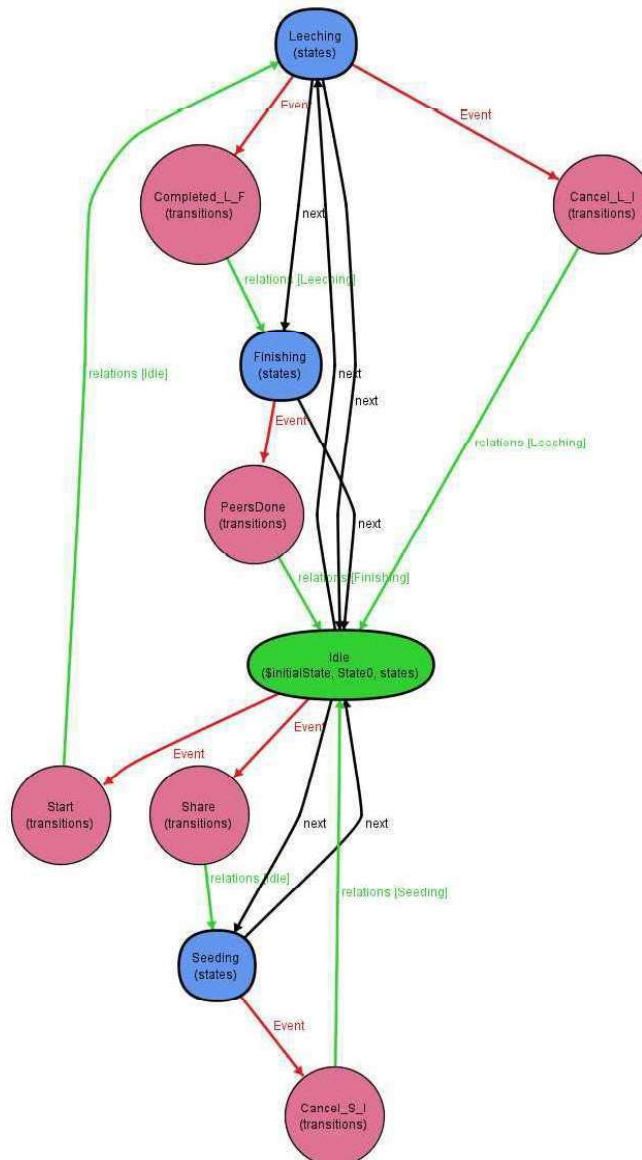
Event: 5
next: 5
relations: 5



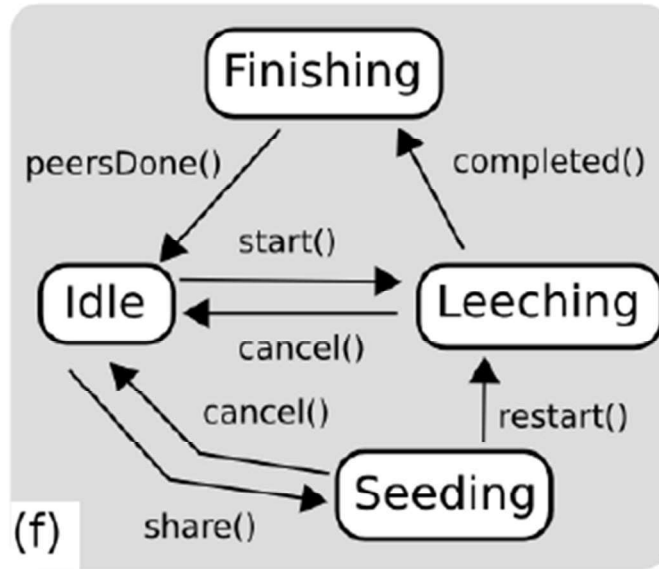
- Scenario 31



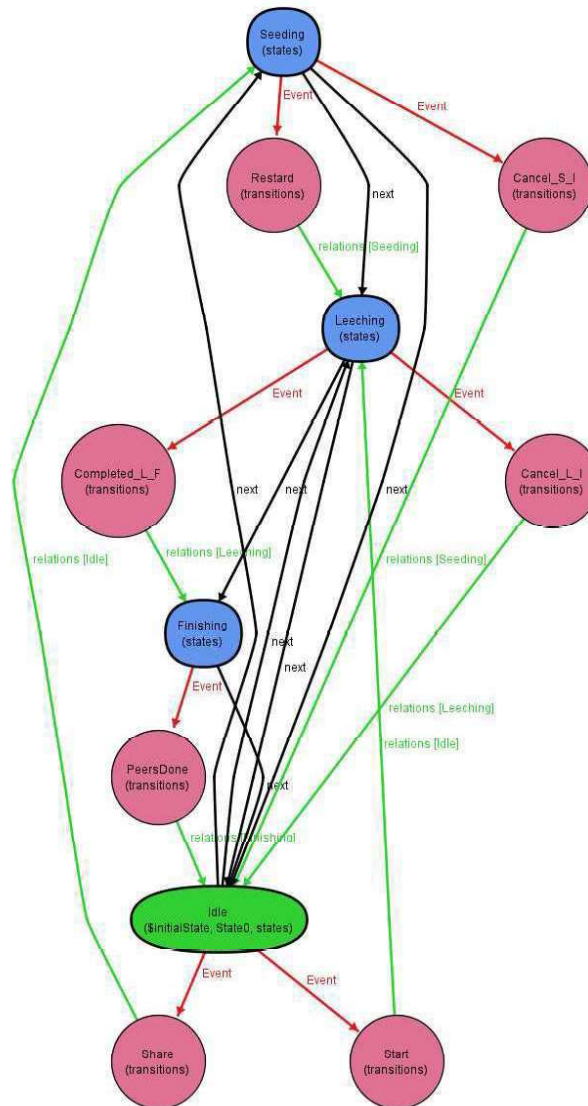
Event: 6
next: 6
relations: 6



- Scenario 33



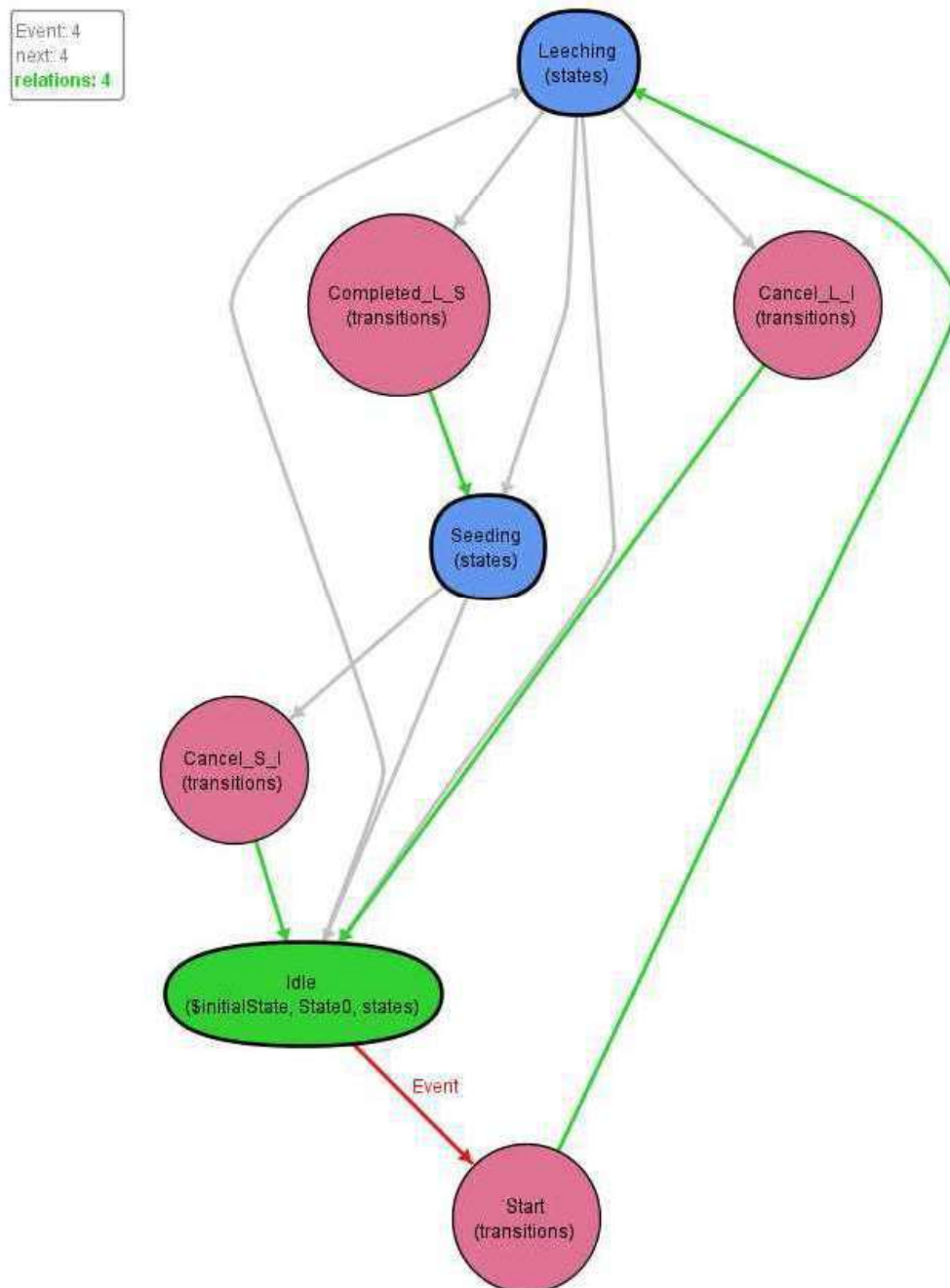
Event: 7
next: 7
relations: 7



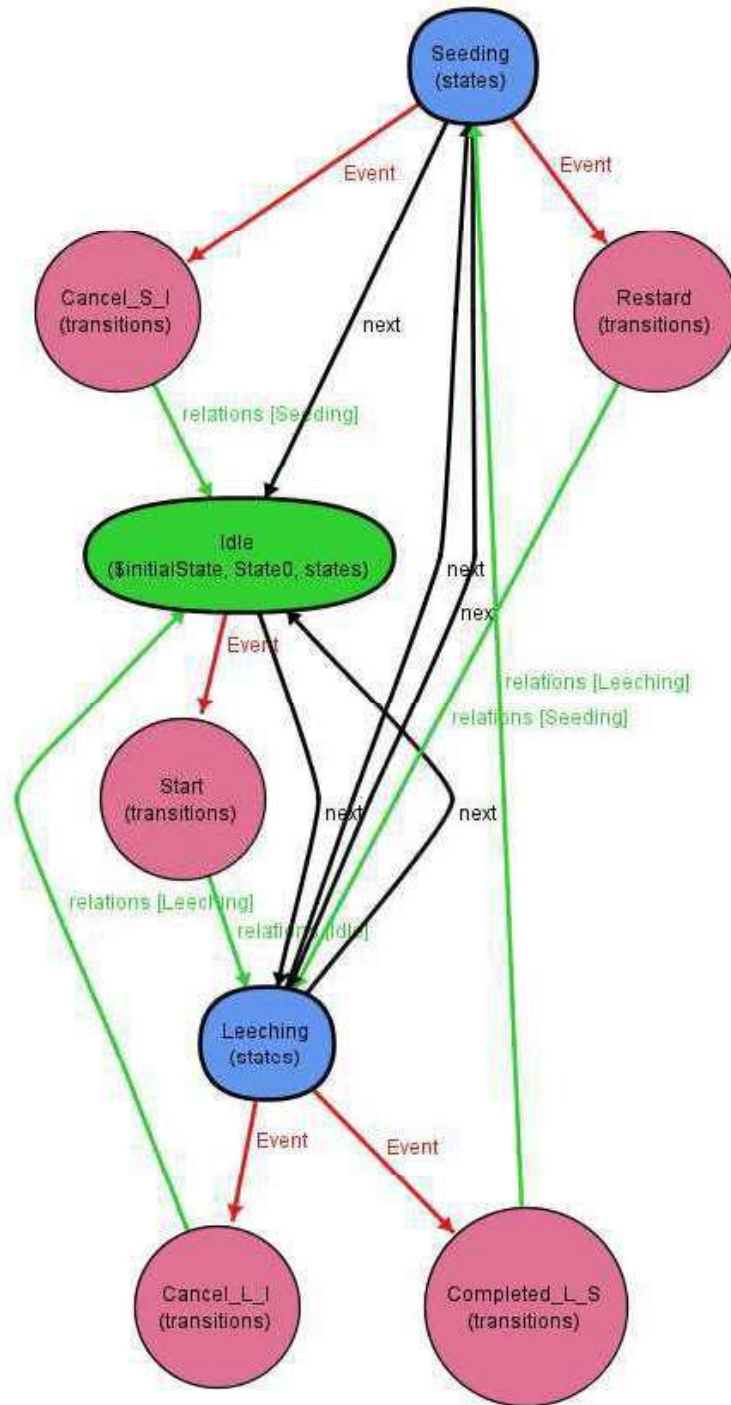
As an example, if we want to check the constraint SC1 with CTL, we can just write our specification in the section 'assert CTL_Formula':

```
// ***** CTL checking *****
assert CTL_Formula{ // here you can write your CTL spec
  ctl_mc[ ag[{
    s:TS.states | s in Idle implies Seeding in s.(TS.next) // this is the SC1
  }] ]
}
```

Our program will return all counter examples when Seeding is not directly reachable from Idle (2 cases):



Event: 5
next: 5
relations: 5



We can construct the partial models' table of truth, we take the HC1 as example. In the first execution, we execute the HC1 predicate with $\#Completed_and_Cancel = 1$, and we will find some instances in the output, which means: $\Phi_M \wedge \Phi_P = SAT$, and then we run HC1 with $\#Completed_and_Cancel = 0$ (negation), we will find some instances in the output, which means: $\Phi_M \wedge \text{not } \Phi_P = SAT$, so we have the truth value *Maybe*, we do the same thing to fill the truth table with the other cases.