ARTIFACT EVALUATION INSTRUCTIONS PROTECT: PARALLELIZED CONSTRUCTION OF SAFETY BARRIER CERTIFICATES FOR NONLINEAR POLYNOMIAL SYSTEMS

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Welcome to the PRoTECT artifact evaluation instructions. This document explains how to reproduce the results presented in the paper "PRoTECT: $\underline{\mathbf{P}}$ arallelized Const $\underline{\mathbf{R}}$ uction $\underline{\mathbf{o}}$ f Safe $\underline{\mathbf{T}}$ y Barri $\underline{\mathbf{E}}$ r $\underline{\mathbf{C}}$ ertificates for Nonlinear Polynomial Sys $\underline{\mathbf{T}}$ ems". The artifact to be evaluated can be found at:

https://github.com/Kiguli/PRoTECT

This artifact is also assigned a permanent DOI, which can be accessed here on Zenodo. We have also provided some detailed Youtube tutorial videos which explain how to install the tool on Linux (the tool is also viable on MacOS and Windows), how to use the GUI for different case studies of the four types of dynamical systems, and how to edit the example configuration python scripts to use the tool as an application programming interface (API).

1. System Requirements

Since our tool offers a GUI, we recommend using the Linux Virtual Machine (VM), based on Ubuntu 22.04 LTS, provided by the Artifact Evaluation committee that can be downloaded here on Zenodo. We got this to run easily on VirtualBox installed on the host PC and double clicking the Artifact_VM_Ubuntu_22.04.ova file from the download which auto-loaded itself into VirtualBox.

Our tool is installable on Linux, Windows, and MacOS, and we have personally installed it on each of these operating systems. For the purposes of this artifact evaluation, we assume the reviewer is using the above VM, and provide detailed instructions especially for this machine. The repository contains more general instructions for how to install the tool on any operating system.

Table 1 and Table 2 from the paper require the artifact evaluation. We will provide the instructions for how to install our tool PRoTECT, as well as how to install the tool we compare against called FOSSIL. We anticipate that running all the case studies may take up to 2 hours.

Table 1 requires utilizing the tool in both serial and parallel modes, and we will furnish instructions detailing the minor adjustments needed in the files to enable execution in each setting. We do not provide an individual python script for each individual setting of an example to run the tool. Similarly, Table 2 demonstrates running the tool with and without optimization, and we offer instructions for adjusting the settings accordingly in each case.

2. Installation

We have tried our utmost to make the following instructions exhaustive for the VM under consideration, there is also a YouTube video here which also walks through the installation instructions in general. Since we include installation details for FOSSIL in this artifact evaluation, and a couple specific tweaks for this VM, the YouTube tutorial should be used in support of the following instructions and not a straight replacement.

The username of the VM is artifact and the password (required for sudo commands) is also artifact.

2.1. **Install PROTECT.** The first step is to navigate to your home directory (the location that contains the folder **Documents**) and open a terminal (right click then **Open in Terminal**), or open a terminal and run the command

cd \sim

to navigate there.

Install git with the following:

sudo apt-get install git

Clone the repository for the tool PROTECT, then go into the folder and install the required dependencies via:

git clone https://github.com/Kiguli/PRoTECT

cd PRoTECT

pip install -r requirements.txt

For the GUI to run correctly, this VM seems to also require the installation of libxcb-cursor0 (sometimes it is already installed, such as in the VM used in the Youtube tutorial video):

sudo apt-get install libxcb-cursor0

You can test this part of the installation from the PRoTECT directory, the GUI should load with no issues by running:

python3 main.py

2.2. **Get Mosek licence.** For the results in Tables 1 and 2 the solver Mosek was used, therefore we now install the licence for Mosek (there is a free trial as well as it being free for academics).

Fill in your details to get a Mosek licence at https://www.mosek.com/license/request/?i=acp. The licence file will be emailed to you with instructions of where to place the file in your home directory. On the VM this will be adding a folder mosek to the home directory and add the licence file mosek.lic into this directory.

If for whatever reason, the Mosek licence is not available for the reviewer to get, there is a free solver cuxopt which can also be used, in all the example files the line 'solver': "mosek", in the dictionary fixed_params should be changed to 'solver': "cuxopt",. The table results might be a little different to the solutions that used Mosek.

2.3. Installing FOSSIL. Go back to the home directory and open a new terminal or navigate the terminal back to the home directory with $cd \sim$. Then clone the FOSSIL repository from Github and install the dependencies using the following commands:

```
git clone https://github.com/oxford-oxcav/fossil
sudo apt-get install -y python3 python3-pip curl
curl -fsSL https://raw.githubusercontent.com/dreal/dreal4/master/setup/ubuntu/20.04/install.sh
| sudo bash
cd fossil
pip3 install .
```

Note: there is one command starting from curl -fsSL and ending at bash which is one single long command and should not be split across two lines like this document has auto-formatted it to do. Additionally, the dot in the last command is important to point to the current directory.

2.4. Copying PROTECT models into FOSSIL. To run the provided FOSSIL versions of our examples from Table 1, we need to copy the used models from PROTECT into FOSSIL. This is easier to do without the terminal. First navigate inside of the PROTECT folder to the path:

```
\sim/PRoTECT/ex/benchmarks-deterministic/FOSSIL-versions/
```

Open the file models.py and copy all of the content from this file. Then navigate to the FOSSIL tool (the fossil folder) to the path:

```
\sim/fossil/experiments/benchmarks/
```

open the file models.py and paste the copied code at line 12 of the file, then save and exit.

2.5. **Setup PYTHONPATH.** The final task in the setup and installation of this artifact evaluation is to add the paths of both PRoTECT and FOSSIL to the PYTHONPATH so that the python scripts we will call can find the functions they require from the PYTHONPATH. Again this section can be completed without needing the terminal.

Go to the home directory and open the hidden file .profile. Assuming you are using the VM mentioned, and that both the folders PRoTECT and fossil are in the home directory, add the following line to the end of the .profile file:

```
export PYTHONPATH = $PYTHONPATH:/home/artifact/PRoTECT:/home/artifact/fossil
```

This adds the location of both repositories we have downloaded to the PYTHONPATH. After this is done, save and exit the file and then restart the VM to enable the PYTHONPATH to be permanently updated on the PC.

If not already visible, you can see hidden files in the file manager by going to the menu and ticking the box "Show Hidden Files".

3. Running the Examples

After the previous installation instructions have been setup correctly, it should be straightforward to run all the examples that make up Tables 1 and 2. The results for these tables were acquired by running the python scripts in the folder ex and not from using the GUI. This is in part because the GUI provides an overhead that somewhat reduces the efficiency of the functions being called, and secondly it provides a fairer comparison against FOSSIL which does not use a GUI.

3.1. **Smoke Test.** To run the smoke test to check that PRoTECT and FOSSIL are both installed correctly navigate first to the folder:

```
~/PRoTECT/ex/benchmarks-deterministic/PRoTECT-versions/
and run in the terminal:

python3 ex1_dt_DS.py

You should see output similar to:

Sympy variables: (x1,)
elapsed time: 0.09335684776306152
{'b_degree': 2, 'barrier': 3.651*(1 - 0.016*x1)**2, 'gamma': 3.8977794359919664, 'lambda': 4.0398245551064065}
```

To check FOSSIL is installed and working correctly, navigate first to the folder:

 \sim /PRoTECT/ex/benchmarks-deterministic/FOSSIL-versions/

and run in the terminal:

python3 ex1_dt_DS.py

You should see output similar to:

Found a valid BARRIERALT certificate

Elapsed Time: 0.3446953239999857

If you receive both of these, you can consider the smoke test to be passed.

3.2. Full Evaluation. The folder ex contains three subfolders; GUI_config_files, benchmarks-stochastic and benchmarks-deterministic. The subfolder GUI_config_files can be ignored since it is not necessary for this artifact evaluation. It contains all the examples as JSON files which can be imported by the GUI to run the examples via that interface. The subfolder benchmarks-stochastic contains the examples used to construct Table 2 for the stochastic cases of both discrete-time stochastic systems (dt-SS) and continuous-time stochastic systems (ct-SS). The final subfolder benchmarks-deterministic contains the examples for discrete-time deterministic systems (dt-DS) and continuous-time deterministic systems (ct-DS). This folder also contains two subfolders, the first has the examples in the form that uses PRoTECT called PRoTECT-versions, and the second has the examples in the form that uses FOSSIL called FOSSIL-versions.

The files themselves are python scripts e.g. ex2_jet_engine_ct_DS.py. The deterministic case studies are by default set to run in the mode with the heading named serial from Table 1. The stochastic case studies are by default set to run in the mode with heading named Standard from Table 2. Each example can be run from the terminal in the correct directory with:

python3 example.py

where example.py should be replaced by the exact name of the example file to be run. This includes both the examples that use PRoTECT and the examples that use FOSSIL. The output of the examples will always include a solving time which should be compared with Table 1 and Table 2 as well as for the PRoTECT case studies additional parameters $b_degree, \gamma, \lambda, c, \phi$ can be compared with the outputs from the returned dictionary $b_degree, gamma, lambda, c, and confidence, respectively.$

In the outputs for the examples, you might see some lines saying Error in degree followed by some information. These errors let the user know that no solution was available for the barrier with the b_degree listed in the Error message and the cause for this is lack of a barrier certificate e.g. Error in degree: 2

- -- barrier is scalar! These factors should not cause concern; rather, they serve to provide users with insights into addressing the complexity of the system being solved.
- 3.3. Table 1: Tweaking the Parallelism Option. For the deterministic case studies, we also run the scripts in the PRoTECT-versions folder in parallel. To do this, a small tweak should be done to each of the python scripts at approx. lines 60 70 of the script. The following lines can be found in the script (in this case for a ct-DS example):

```
### Uncomment this line to run the parallel implementation
#result = parallel_ct_DS(max_degree_values, **fixed_params)
### Uncomment this line to run the serial implementation
result = ct_DS(single_degree_values, **fixed_params)
```

The character # is used to comment out a line of code so it does not get called by the script to run. To change from serial implementation to parallel implementation, simply remove # from the second line above and add # to the fourth line, as here:

```
### Uncomment this line to run the parallel implementation
result = parallel_ct_DS(max_degree_values, **fixed_params)

### Uncomment this line to run the serial implementation
#result = ct_DS(single_degree_values, **fixed_params)
```

After saving and exiting this change, you can then run the script file again using:

```
python3 example.py
```

to run the parallel version of the example.

3.4. Table 2: Tweaking the Optimization Option. Similar to the parallelism changes, for the Optimized examples, small tweaks should be made to each of the python scripts in the folder benchmarks-stochastic. In particular, the dictionary fixed_params should be edited to set the parameter 'Optimize' to True and the parameter 'lam' to the λ value for the case study found in Table 2 (usually 10 except for the Van der Pol oscillator which is 1000).

Inside the script the following code:

```
fixed_params = {
...
```

```
'optimize': False,
'solver': "mosek",
'confidence': None,
'gam': None,
'lam': None,
. . .
}
should be changed by setting the values 'Optimize' to True and the parameter 'lam' to the \lambda value (in this
case 10):
fixed_params = {
'optimize': True,
'solver': "mosek",
'confidence': None,
'gam': None,
        10,
'lam':
. . .
Once changed, save and exit the file. Then run the script with:
python3 example.py
for the optimized case.
```

4. Running New Case Studies with Protect

We have tried to make using PRoTECT for your own examples as easy as possible, this can be done in two ways, either through the provided graphic user interface (GUI) or through python scripts that call the PRoTECT functions as an API.

4.1. Graphic User Interface (GUI). To enhance accessibility and user-friendliness of the tool, PRoTECT offers the Model-View-Presenter architecture incorporating a GUI. Specifically, a GUI strengthens user-friendliness by abstracting away implementation details for the code, allowing for a push-button method to construct barrier certificates. In Fig. 1, color notation is utilized to represent labels by their corresponding color and number. While PRoTECT provides GUIs for all four classes of systems (see Fig. 1 (blue-1)), we only

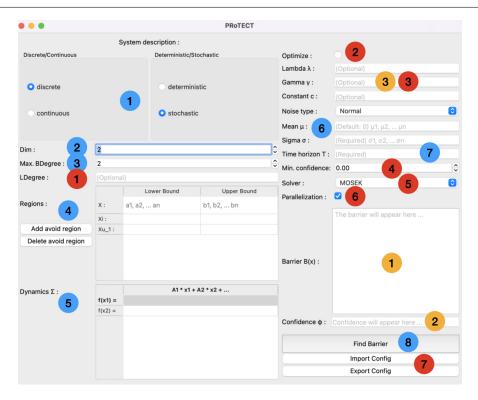


FIGURE 1. PROTECT GUI for dt-SS, where required parameters, optional parameters, and outputs are marked with blue, red, and yellow circles, respectively.

depict it for dt-SS here to avoid excessive information. Our tool offers two implementations, either serial or parallel (red-6). The tool processes the information entered into the GUI before executing the desired function upon pressing the *Find Barrier* button (blue-8). Outputs of barrier certificate $\mathcal{B}(x)$, confidence ϕ , level sets γ and λ , and constant c are displayed at (yellow-1), (yellow-2), and (yellow-3), respectively. Optionally, the GUI allows for the import and export of configuration parameters in JSON format using the *Import Config* and *Export Config* buttons (red-7), with all the examples from Table 1 and Table 2 of the paper available in the folder /ex/GUI_config_files.

By navigating to the PRoTECT folder in a terminal and running:

python3 main.py

you can open the PRoTECT GUI, to then run examples. We have provided extensive *Youtube tutorial videos* to help with this for the four classes of dynamical systems, as well as the importing and exporting of the config files: here.

4.2. **Treating PRoTECT as an API.** In addition to the GUI, as already seen in the artifact evaluation part of this document, we provide python scripts which can be used to call the PRoTECT functions as an API. We

will now describe for each of the four dynamical systems how to use these functions as an API, in addition we have a *Youtube tutorial video* which explains the python scripts used by PRoTECT and explains how to edit them: here.

4.2.1. Discrete-Time Stochastic Systems (dt-SS). In general, the backend of PRoTECT behaves as an API, with functions that can be called and used in any python program. We provide some generic configuration files in /ex/benchmarks-stochastic and /ex/benchmarks-deterministic, which demonstrate how to use the functions in a standard python program. The user is expected to provide the following required parameters: dimension of the state set $X \subseteq \mathbb{R}^n$ (blue-2), indicated by dim, and the degree of the barrier certificate (blue-3), denoted by b_degree. The lower and upper bounds of the initial region $X_{\mathcal{I}}$, labeled as L_initial and U_initial; lower and upper bounds of the unsafe region $X_{\mathcal{U}}$, referred to as L_unsafe and U_unsafe; lower and upper bounds for the state set X, denoted as L_space and U_space; where the value of each dimension is separated with a comma (blue-4). Due to possible scenarios with multiple unsafe regions, the unsafe region is passed to the functions as a numpy array of numpy arrays describing each individual unsafe region. The transition map f, represented by f, written as a SymPy expression for each dimension using states $x1, x2, \ldots$ and noise parameters varsigma1, varsigma2, ... (blue-5). The time horizon \mathcal{T} , noted as t (blue-7). The distribution of the noise, NoiseType, can be specified as either "normal", "exponential", or "uniform" (blue-6).

Users may also specify optional parameters, with default values provided in Listing 1. These include the degree of the Lagrangian multipliers $l_i(x), l_u(x), l(x)$: 1_degree (red-1), which, if not specified (i.e., set to None), will default to the same value as b_degree; the type of solver: solver (red-5), that can be either set to "mosek" or "cvxopt". The confidence level ϕ (in equation (5) of the paper) can be optimized using optimize (red-2), if set to True. In this case, due to having a bilinearity between γ and λ (in equation (5) of the paper), the user is required to provide one λ : lam, e.g., select $\lambda = 1$ (red-3). The tool will then optimize for the other decision variables including γ and c to provide the highest confidence level ϕ . Alternatively, the user can select a minimum confidence level ϕ (red-4) using confidence they desire, so that PRoTECT attempts to search for a barrier certificate satisfying that confidence level. The parameters for the distributions should be specified as follows (blue-6): for normal distributions, the mean μ can be set using mean, and the diagonal covariance matrix σ can be provided using sigma. For exponential distributions, the rate parameter for each dimension can be set using rate. For uniform distributions, the boundaries for each dimension can be set using a and b. We provide two functions for dt-SS (red-6): the first dt_SS finds a barrier for a single degree, and the second parallel_dt_SS runs the first function in parallel for all barrier degrees up to the maximum barrier degree specified (also called b_degree).

¹https://docs.sympy.org/latest/tutorials/intro-tutorial/basic_operations.html

```
dt_SS(b_degree, dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x,
    varsigma, f, t, l_degree=None, NoiseType="normal", optimize=False, solver="mosek",
    confidence=None, gam=None, lam=None, c_val=None, mean=None, sigma=None, rate=None, a=None
    , b=None)

parallel_dt_SS(b_degree, dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x,
    varsigma, f, t, l_degree=None, NoiseType="normal", optimize=False, solver="mosek",
    confidence=None, gam=None, lam=None, c_val=None, mean=None, sigma=None, rate=None, a=None
    , b=None)
```

LISTING 1. dt-SS functions.

4.2.2. Discrete-Time Deterministic System (dt-DS). The user is required to input necessary (and optional) parameters as outlined in Subsection 4.2.1, excluding those parameters relevant to stochasticity (e.g., time horizon, constant c, noise distribution, and confidence level). Optionally, the user can specify the level sets γ using gam or λ using lam. It is important to note that optimization for the level sets γ and λ is not performed, as any feasible solution with $\lambda > \gamma$ ensures a safety guarantee over an infinite time horizon. Similarly, we provide two functions dt_DS and parallel_dt_DS for the serial and parallel execution.

```
dt_DS(b_degree,dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x, f,

l_degree=None, solver="mosek",gam=None,lam=None)

parallel_dt_DS(b_degree,dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x,

f, l_degree=None, solver="mosek",gam=None,lam=None)
```

LISTING 2. dt-DS functions.

4.2.3. Continuous-Time Stochastic System (ct-SS). The user is asked to enter necessary (and optional) parameters as detailed in Subsection 4.2.1. Additionally, via the corresponding GUI, users must provide the diffusion term δ using delta for Brownian motion, the reset term ρ using rho for Poisson process, and the Poisson process rate ω using p_rate. For cases lacking either Brownian motion or Poisson processes, the corresponding parameter should be set to zero. The confidence level ϕ can also be optimized if optimize is set to True. We provide functions ct_SS and parallel_ct_SS for the serial and parallel execution.

```
ct_SS(b_degree, dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x, f, t,
l_degree=None, delta=None, rho=None, p_rate=None, optimize=False, solver="mosek",
confidence=None, gam=None, lam=None, c_val=None)

parallel_ct_SS(b_degree, dim, L_initial, U_initial, L_unsafe, U_unsafe, L_space, U_space, x,
f, t, l_degree=None, delta=None, rho=None, p_rate=None, optimize=False, solver="mosek",
confidence=None, gam=None, lam=None, c_val=None)
```

Listing 3. ct-SS functions.

4.2.4. Continuous-Time Deterministic System (ct-DS). The user is expected to input necessary (and optional) parameters as detailed in Subsection 4.2.1, omitting parameters pertinent to stochasticity (e.g., time horizon, constant c, and confidence level). Optionally, users can define the level sets γ using gam or λ using lam. Optimization for level sets γ and λ is not conducted, i.e., any feasible solution where $\lambda > \gamma$ ensures a safety guarantee over an infinite time horizon. Functions ct_DS and parallel_ct_DS are employed for the serial and parallel execution.

LISTING 4. ct-DS functions.