



52nd International Conference on Parallel Processing (ICPP 2023)

# **FaST-GShare: Enabling Efficient Spatio-Temporal GPU Sharing in Serverless Computing for Deep Learning Inference**

**Jianfeng Gu, Yichao Zhu, Puxuan Wang, Mohak Chadha, Michael Gerndt**

**Chair of Computer Architecture and Parallel Systems (CAPS)  
Technical University of Munich**

# Outline

- Background
- Motivation
- Architecture & Implementation
- Evaluation
- Conclusion

# Background – Serverless Computing

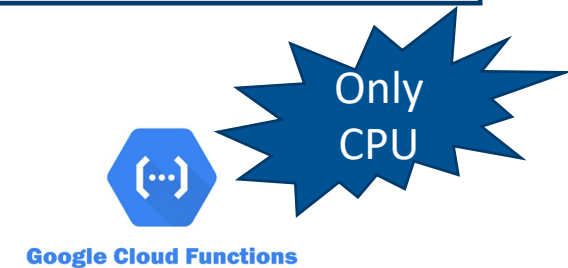
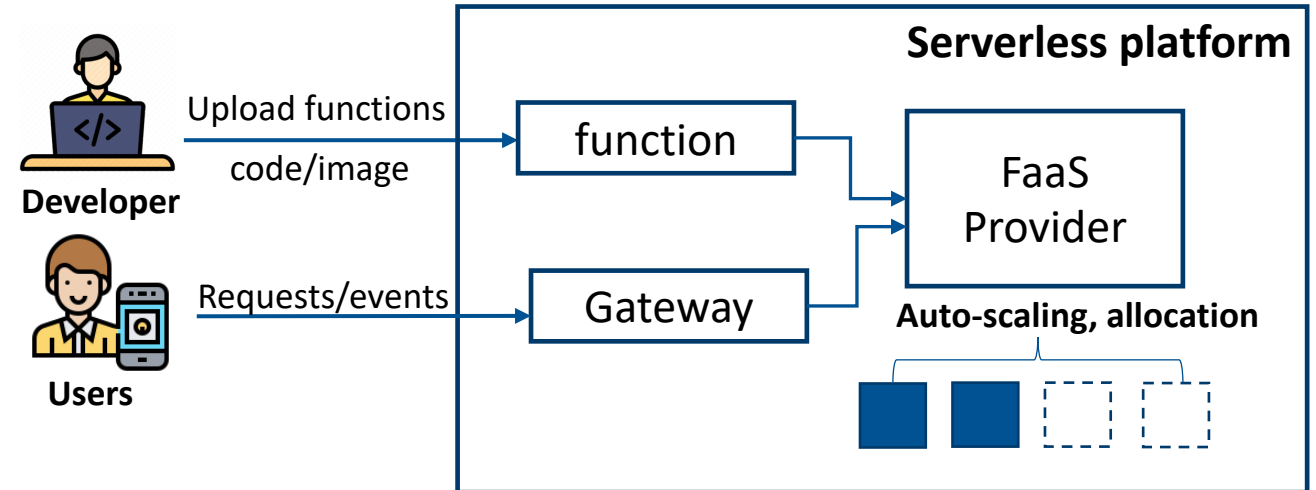
- Serverless – Function as a Service (FaaS)

- Advantages

- Easy deployment;
- Pay-per-use, Cost-effectiveness
- Auto-scaling, high scalability;
- Event-driven, fine-grained.

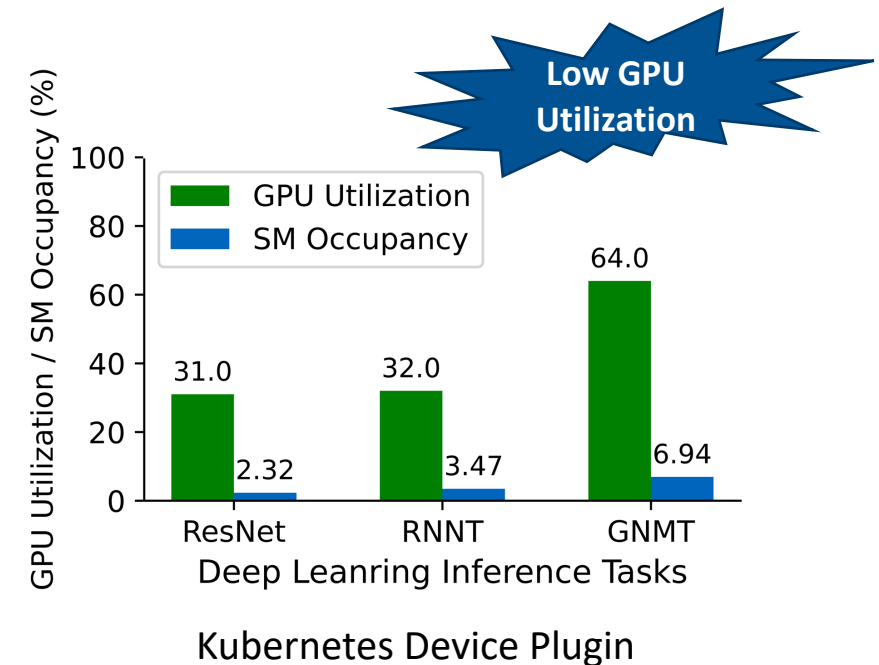
- Popularity

- Lambda, Azure Functions, Google Cloud Functions;
- Problem: only CPU-supported.
- Serverless DL Inference.  
*OSDI22 Orin [10], ATC22 Jie Li, et. al. [11], VLDB22 Ahsan Ali, et. al. [12].*



# Motivation – Coarse GPU Usage in Serverless

- GPU Device Plugin for **Kubernetes** [1]
  - Designed for **DL training**, exclusive GPU usage for a container;
  - **GPU under-utilization** in DL inference;
- Time-Slicing GPUs in Kubernetes [2]
  - **Fair time-sharing**, Not guarantee GPU compute power for each pod.
  - Lack of resource **isolation**, Unpredictable interference among FaaS functions.
  - Service Level Objectives (SLOs) violations.



NEED!

Both **efficient** and **SLO-aware** GPU sharing mechanism.

# Motivation – Fine-grained GPU Sharing

- High GPU utilization == Efficient GPU Usage ?
  - GPU utilization and **SM Occupancy**. (Streaming Multiprocessor)
  - NVIDIA V100 GPU: 80 SM units & A100 HGX GPU: 108 SM units.
- Timing Sharing
  - Previous work: *KubeShare* [38], *Gaia-GPU* [4], *vGPU-scheduler*[5], et. al;
  - **Low SM Occupancy**;
- Spatial Sharing
  - vGPU from **Multi-Instance GPU (MIG)**;
  - Limited to 7 pre-defined resource configurations;
  - Previous work: *GSLICE* [6], *gpulets* [7], et al.
  - **Resource-based scaling** not compatible with **Instance-based scaling** in FaaS.
  - *Tencent Cloud qGPU* [8] and *Aliyun cGPU* [9]; **Only Spatial Sharing**
  - No **request** and **limit** mechanism, not flexible to utilize idle resources.

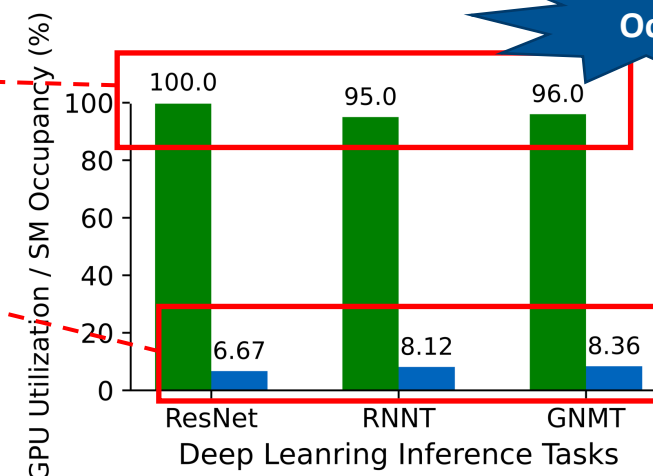


NVIDIA V100

Low SM  
Occupancy

GPU Utilization

SM Occupancy



Time sharing from KubeShare[3].

# Objectives & Challenges

- Objectives

- **Spatio-Temporal** GPU Sharing; (Performance Isolation)
- **SLO-aware**; (Guarantee Function SLOs).
- **Efficient**; (Throughput, GPU Utilization, and SM Occupancy).

- 4 Challenges

- How to **coordinate** GPU spatial and temporal multiplexing for performance isolation and efficiency?
- How to **allocate** the appropriate amount of spatio-temporal resources for each FaaS function?
- How to **schedule** functions across GPU nodes to ensure its SLO, and improve throughput and GPU occupancy?
- How to **alleviate** the GPU memory contention with more FaaS functions sharing a GPU?



**FaST-GShare**

**FaaS-oriented Spatio-Temporal GPU Sharing architecture.**

# Contribution

## FaST-GShare

### FaST-Manager

- How to **coordinate** GPU spatial and temporal multiplexing to ensure both efficiency and isolation?

### FaST-Profiler

- How to **allocate** the appropriate amount of spatio-temporal resources for each FaaS function?

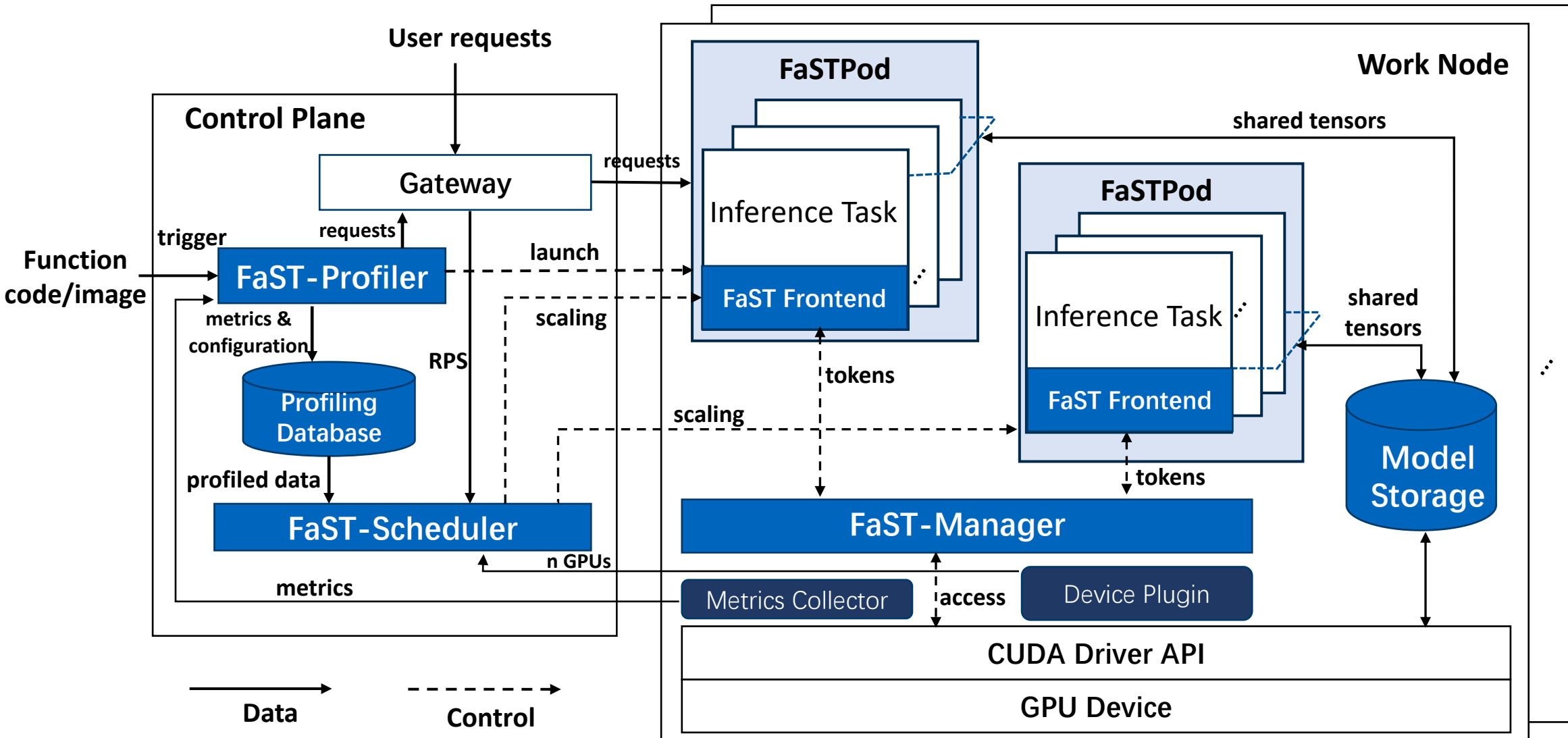
### FaST-Scheduler

- How to **schedule** functions across GPU nodes to ensure its SLO and throughput while improving GPU resource usage?

### Model Sharing

- How to **alleviate** the increased contention of GPU memory with more FaaS functions sharing a GPU?

# Architecture – FaST-GShare Overview

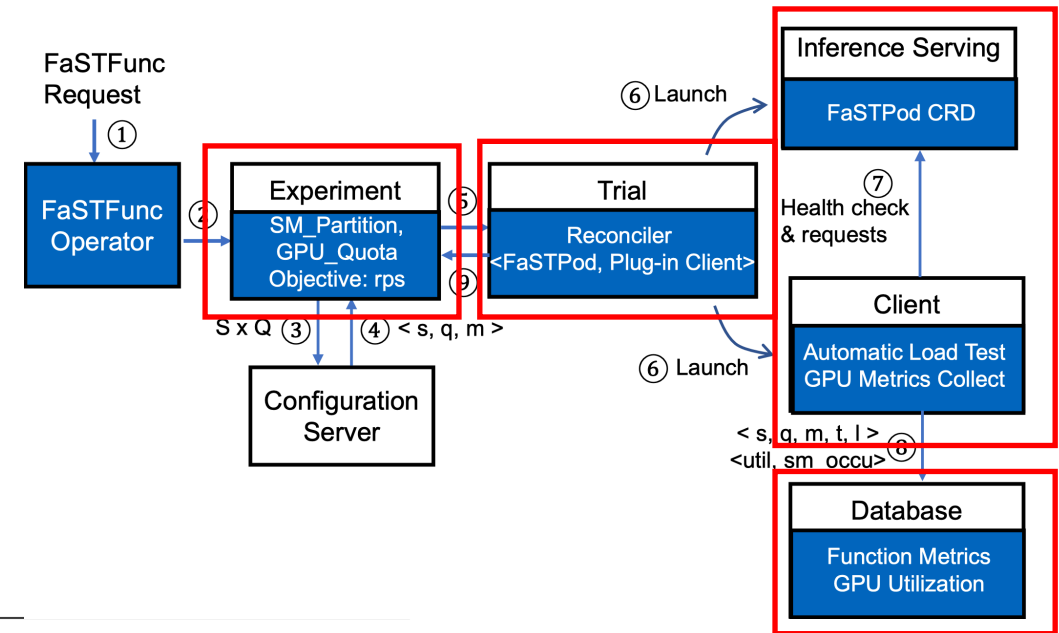




# Architecture – FaST-Profiler

## • Profiler

- **Automatic; Profile** the function **throughput** under **various spatio-temporal** GPU resource allocations; (Function Performance Curves)
- **Automatic** Experiment-Trial workflow;



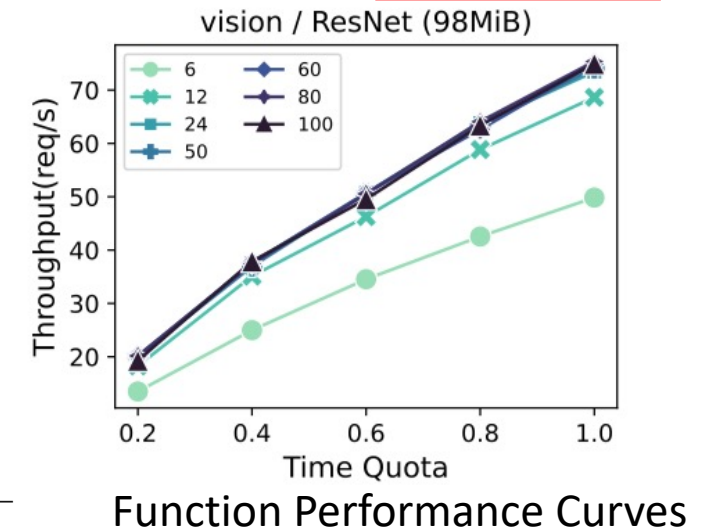
## • FaSTPod

- Basic Deployment Unit;
- **Any granularity** of spatial and temporal GPU resources.

```

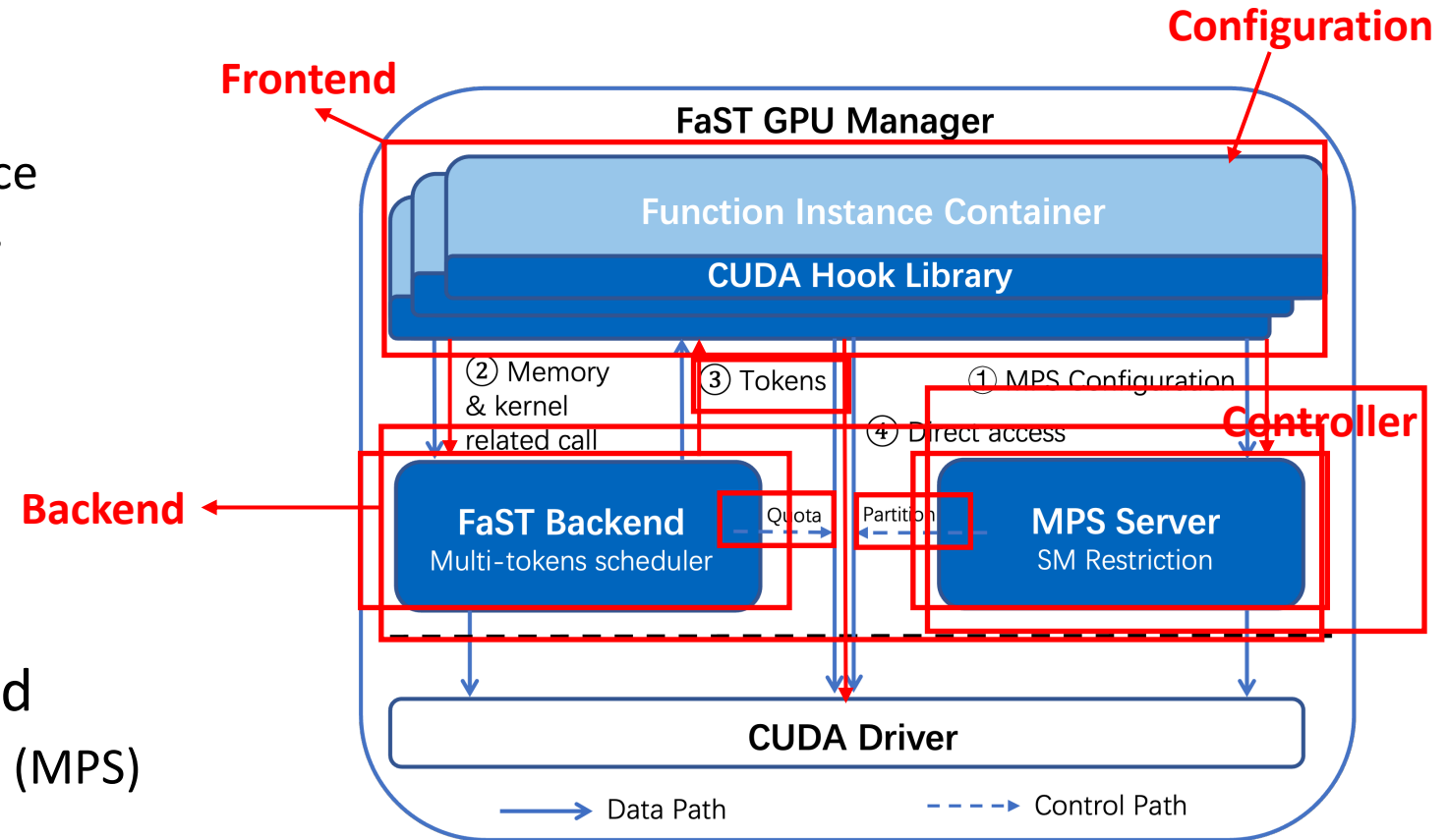
apiVersion: faasshare.com/v1
kind: FaSTPod
metadata:
  annotations:
    faasshare/sm_partition: "12"
    faasshare/quota_limit: "0.8"
    faasshare/quota_request: "0.3"
    faasshare/gpu_mem: "1073741824"
  name: fastsvc-rnnt-q30-p12
spec:
  podSpec:
    containers:
      - env:
        - name: MODEL_NAME
          value: MLPerf-FaaS-rnnt
        image: xxxx/mlperf-faas-rnnt:latest
        replicas: 2

```



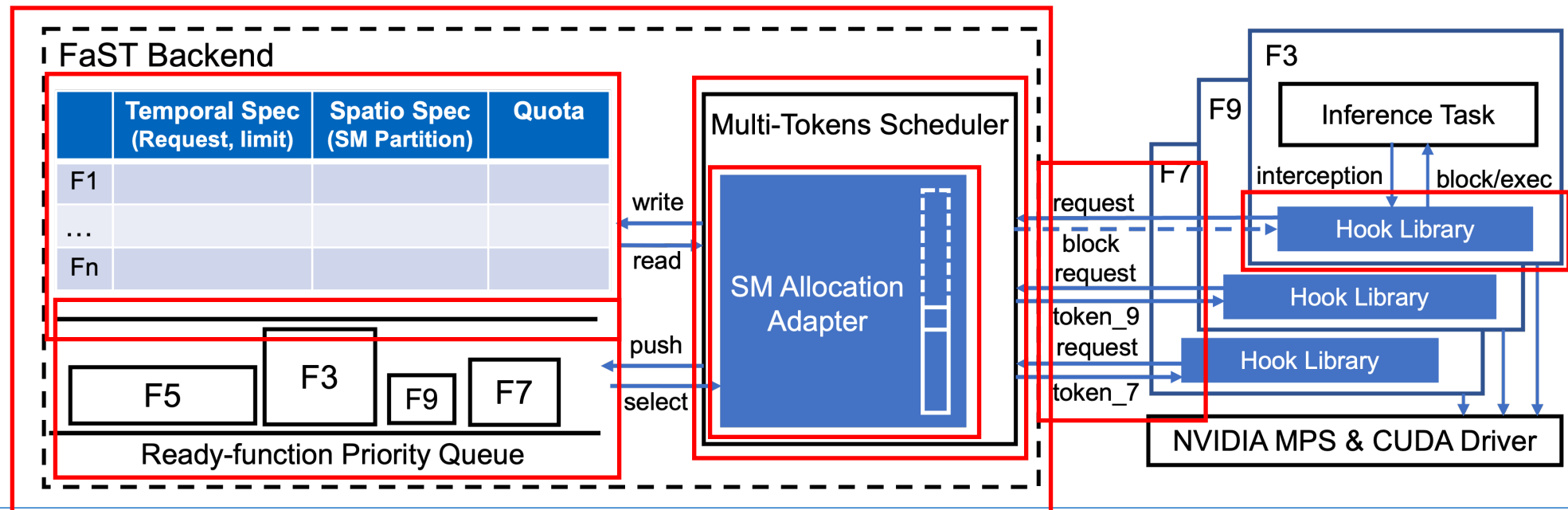
# Architecture – FaST-Manager

- FaST-Manager
  - **Coordinate** and **Isolate** GPU resource in spatial and temporal dimensions.
  - **Frontend-Backend** mechanism;
  - Tokens: Time slices;
- MPS-based Spatial Sharing Backend
  - Controller for Multi-Process Service (MPS)
  - Exposes the IPC namespace.
  - `CUDA_MPS_ACTIVE_THREAD_PERCENTAGE`;



# Architecture – FaST-Manager

- FaST Time Sharing Backend
  - CUDA Driver API **Interception**, Linux *LD\_PRELOAD*.
  - Multi-tokens Scheduler;
  - Control Spatial multiplexing through timing tokens → the spatio-temporal limitation collaboration;



# Architecture – FaST-Scheduler


- FaST-Scheduler

- Scale and schedule functions across GPU nodes to guarantee SLOs and improve GPU efficiency.
- 1. Heuristic Auto-Scaling;
- 2. Maximal Rectangles Algorithm for node selection;

- Heuristic Auto-Scaling

- Utilize Profiling data. Decide the number of function pods and corresponding resource allocations;
- Scaling-up and Scaling-down;
- A metric RPR;
- Priority queue in the ascending order by  $RPR$ .

Processing gap

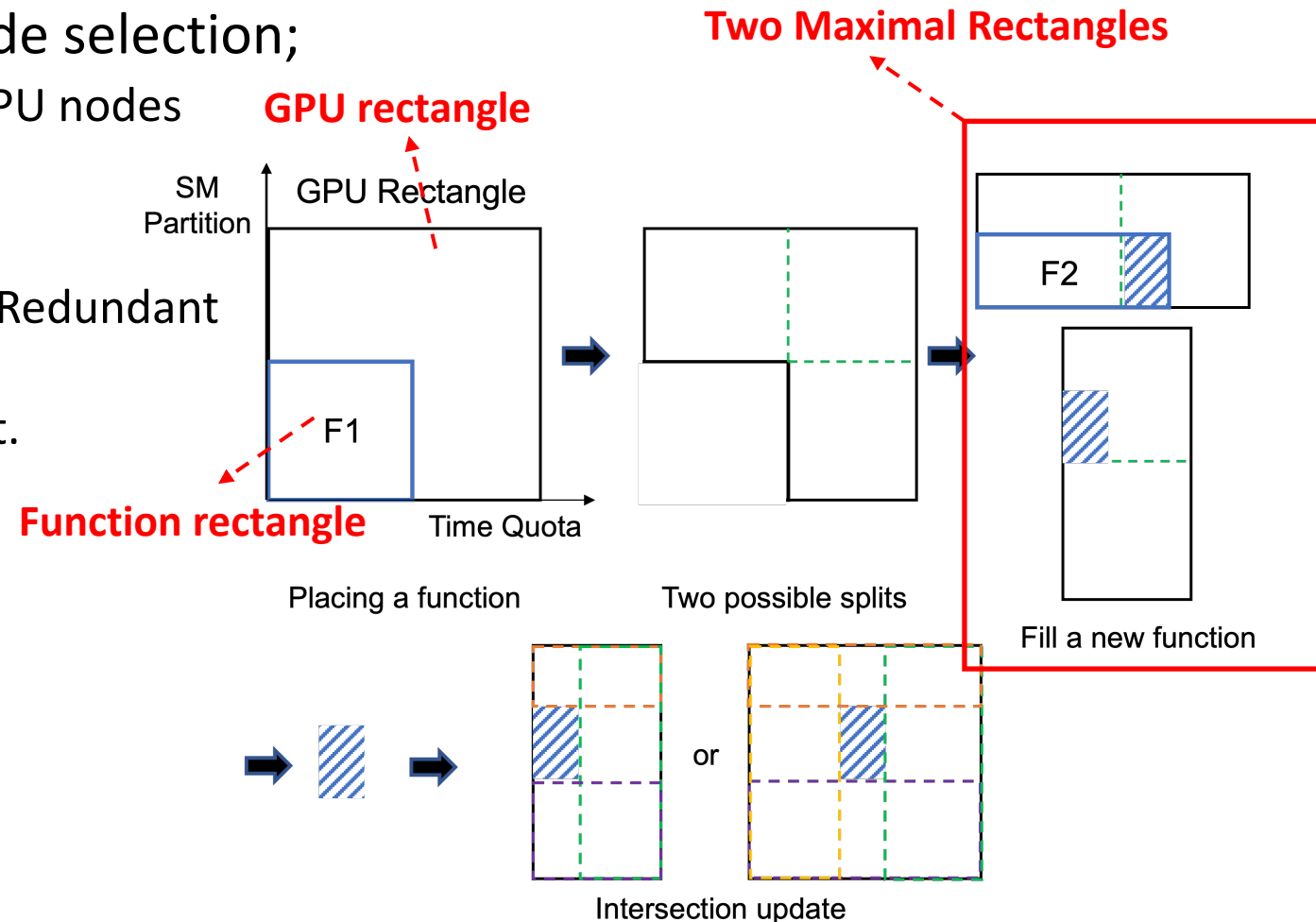

$$\Delta RPS_j = R_j - \left( \sum_{J_i \in F_j} T_{j,i} \right)$$

$$RPR \text{ (RPS per Resource)} = \frac{T_{j,p}}{S_{j,p} * Q_{j,p}}$$

# Architecture – FaST-Scheduler

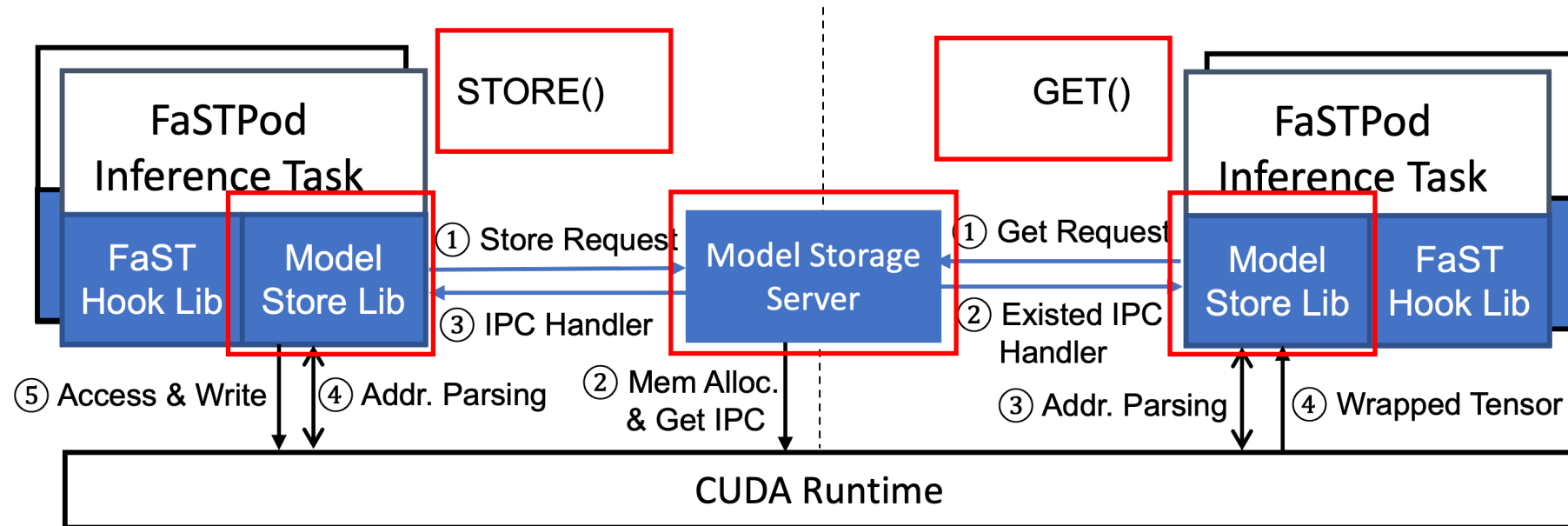
- Maximal Rectangles Algorithm for node selection;

- Effectively schedule function pods to GPU nodes
- Dynamic 2D resource **restructuring**.
- **GPU rectangle** and **function rectangle**.
- 3 Steps: Split, Intersection update, and Redundant rectangle removing;
- Two maximal rectangles during the split.
- Reclamation: "keep-restructure" policy;



# Architecture – Model Sharing

- Model Sharing Storage
  - Mitigate memory contention.
  - Model Store Library and Model Storage Server.
  - STORE() and GET().

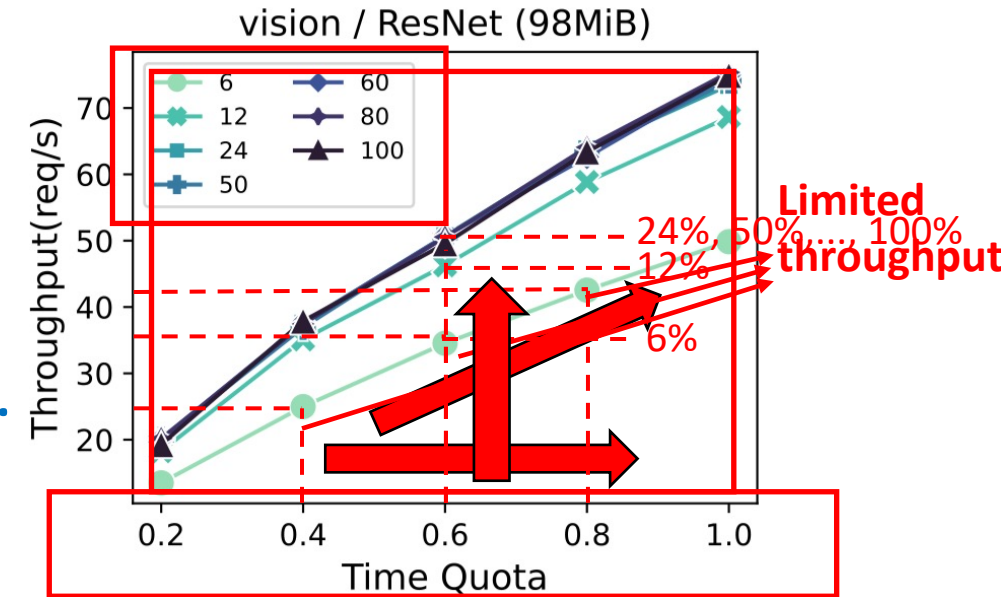


# Experiment Setup

- Testbed
  - Serverless platform: **OpenFaaS** with **faas-netes**.
  - The master node: Intel(R) Xeon(R) CPU @ 2.00GHz with 48 cores and 60GB RAM.
  - **4 work nodes**, each with a **NVIDIA Tesla V100 GPU** with 80 SM units, and **16GB device memory**.
- Workload
  - **MLPerf Benchmark** [14] from NVIDIA, including **ResNet**, **BERT**, **RNNT**, and **GNMT**;
  - Larger transformer models: **ResNeXt** [37] (vision) and **ViT\_huge**[16];
  - ML framework: **PyTorch** and **TensorFlow**;

# Evaluation – Performance Isolation

- Profiling points
  - Temporal dimension: 0.2, 0.4, 0.6, 0.8, 1.0.
  - Spatial dimension: 6%, 12%, 24%, 50%, 60%, 80%, 100%;
- Temporal dimension
  - The throughput of the model increases proportionally.
  - **Limited throughput** → **Effective temporal resource isolation.**
- Spatial dimension
  - At a certain point, the throughput will no longer increase.
  - → **A model cannot fully occupy all SMs;**
  - → **Effective spatial resource isolation;**
- → Profiling performance curves for FaST-Scheduler

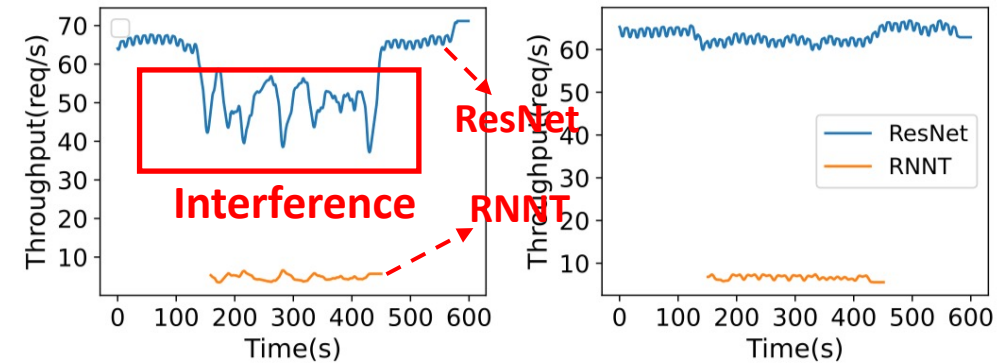
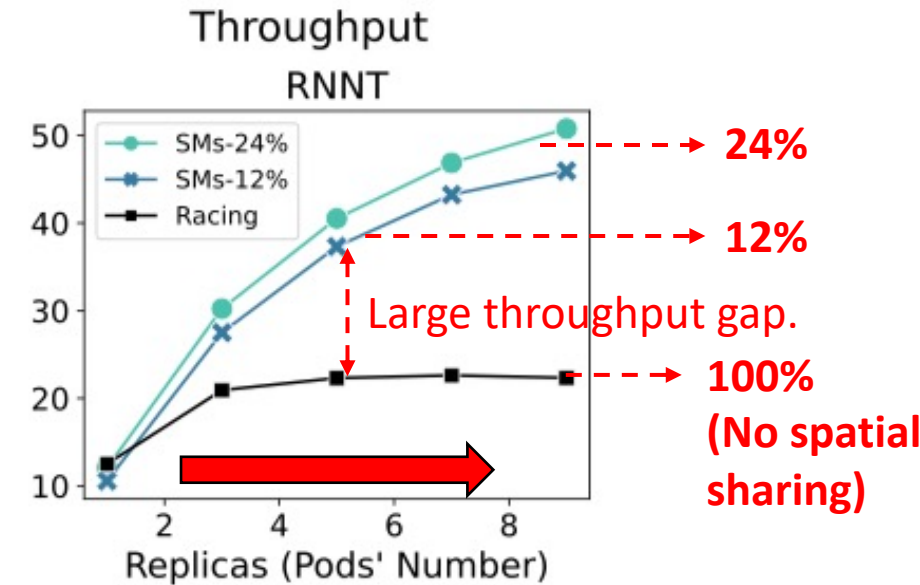


Function throughput of ResNet from FaST-Profiler.



# Evaluation – Spatial Sharing Performance

- 100% time quota allocation
  - No spatial sharing (racing, 100% partition).
  - 12% partition;
  - 24% partition;
- Throughput Improvement:
  - **Improve throughput by x3.15.**
- Avoid Interference
  - Time quotas (limit):  
ResNet: 80%, RNNT: 50%. >100%
  - **Effectiveness of spatial sharing in FaST-Manger.**

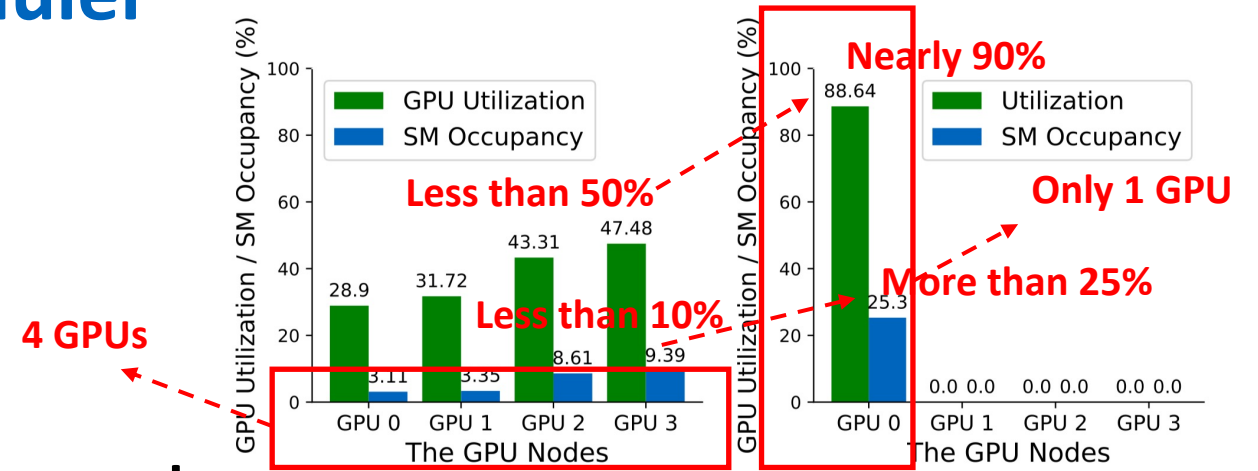


(a) Only time sharing.

(b) Spatio-Temporal sharing.

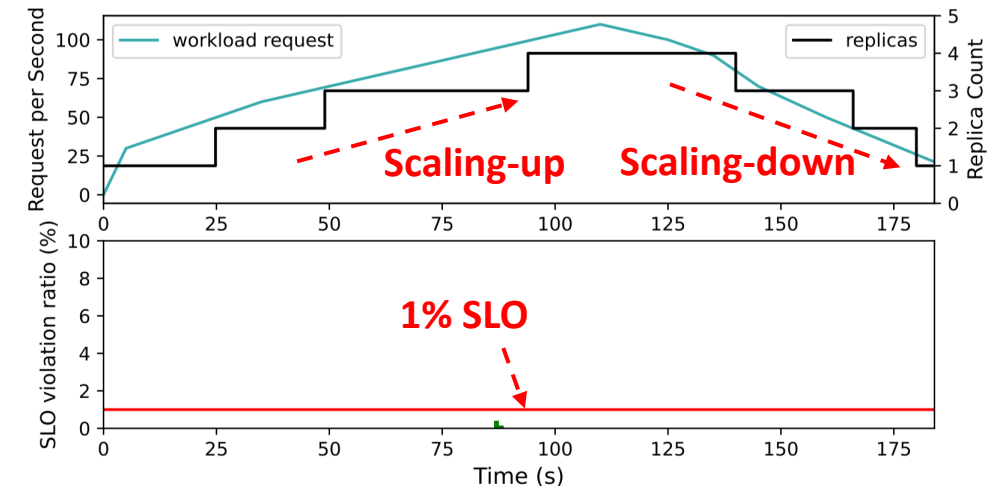
# Evaluation – Efficient FaST-Scheduler

- Workload (SM partitions, time quotas)
  - 4 ResNet pods, (12%, 40%)
  - 2 RNNT pods, (24%, 40%)
  - 2 BERT pods, (50%, 60%)
- GPU utilization and SM occupancy Improvement
  - 4 GPUs → 1 GPU
  - GPU utilization by x1.34,  
SM occupancy by x3.13 on average;
- SLO-Aware
  - Effective Auto-scaling;
  - ResNet SLO of 69ms, **no SLO violation** exceeding 1% .



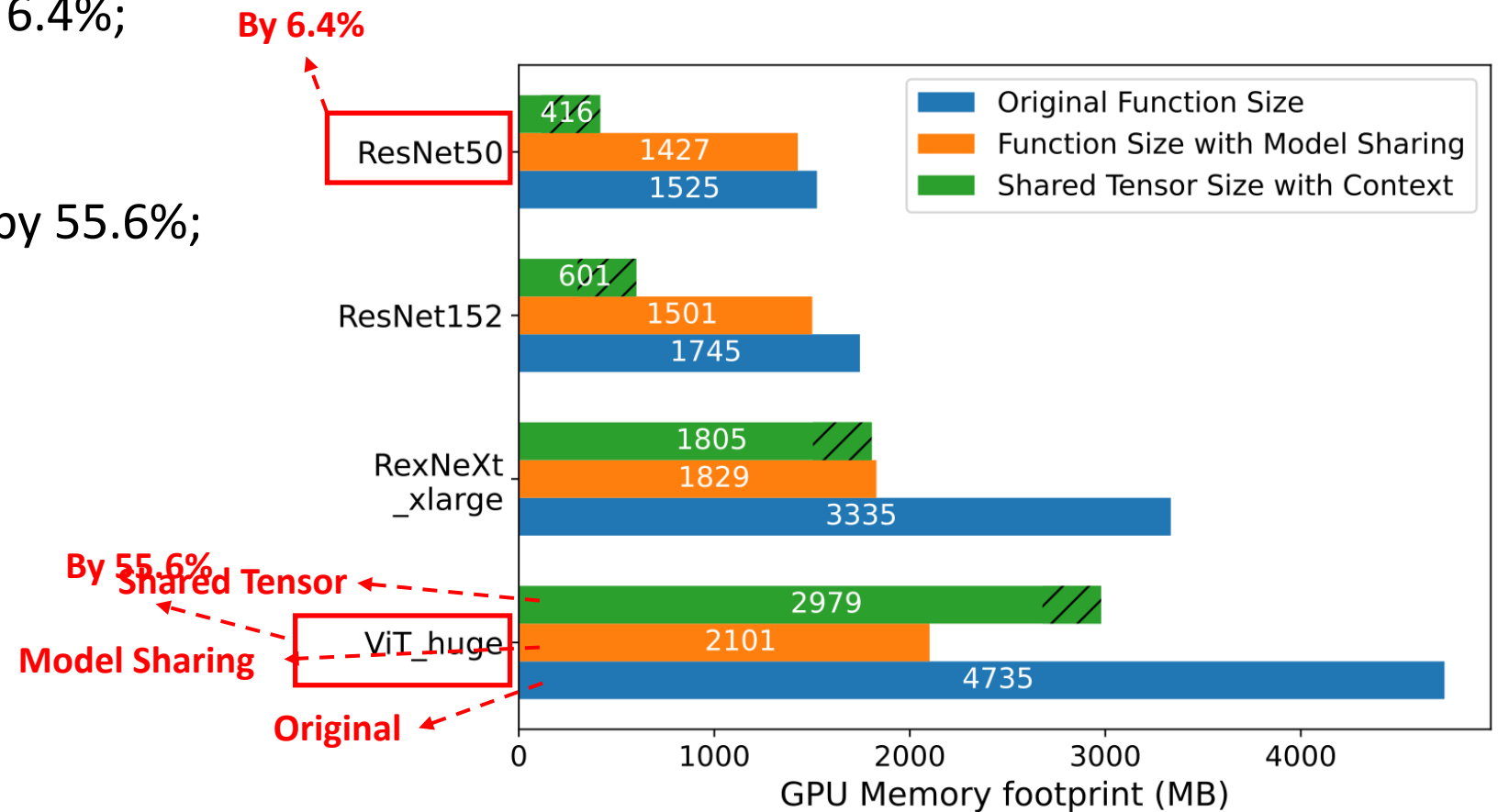
(a) Only time sharing [38].

(b) FaST-Scheduler.



# Evaluation – Model Sharing

- ResNet model decreased by 6.4%;
  - 1525M to 1427M
- ViT\_huge model decreased by 55.6%;
  - 4735M --> 2101M



# Conclusion

- **FaST-GShare**
  - An efficient FaaS-oriented Spatio-Temporal GPU Sharing architecture for deep learning inferences;
- **FaST-Manager**
  - Limit and isolate spatio-temporal resources for GPU multiplexing.
- **FaST-Profiler & FaST-Scheduler,**
  - Guarantee function SLOs and maximize GPU usage;
- **Model Sharing**
  - Alleviate Memory Contention;
- **Performance**
  - Improve throughput by 3.15x, GPU utilization by 1.34x, and SM occupancy by 3.13x on average.