

Graph Neural Networks

姜成翰

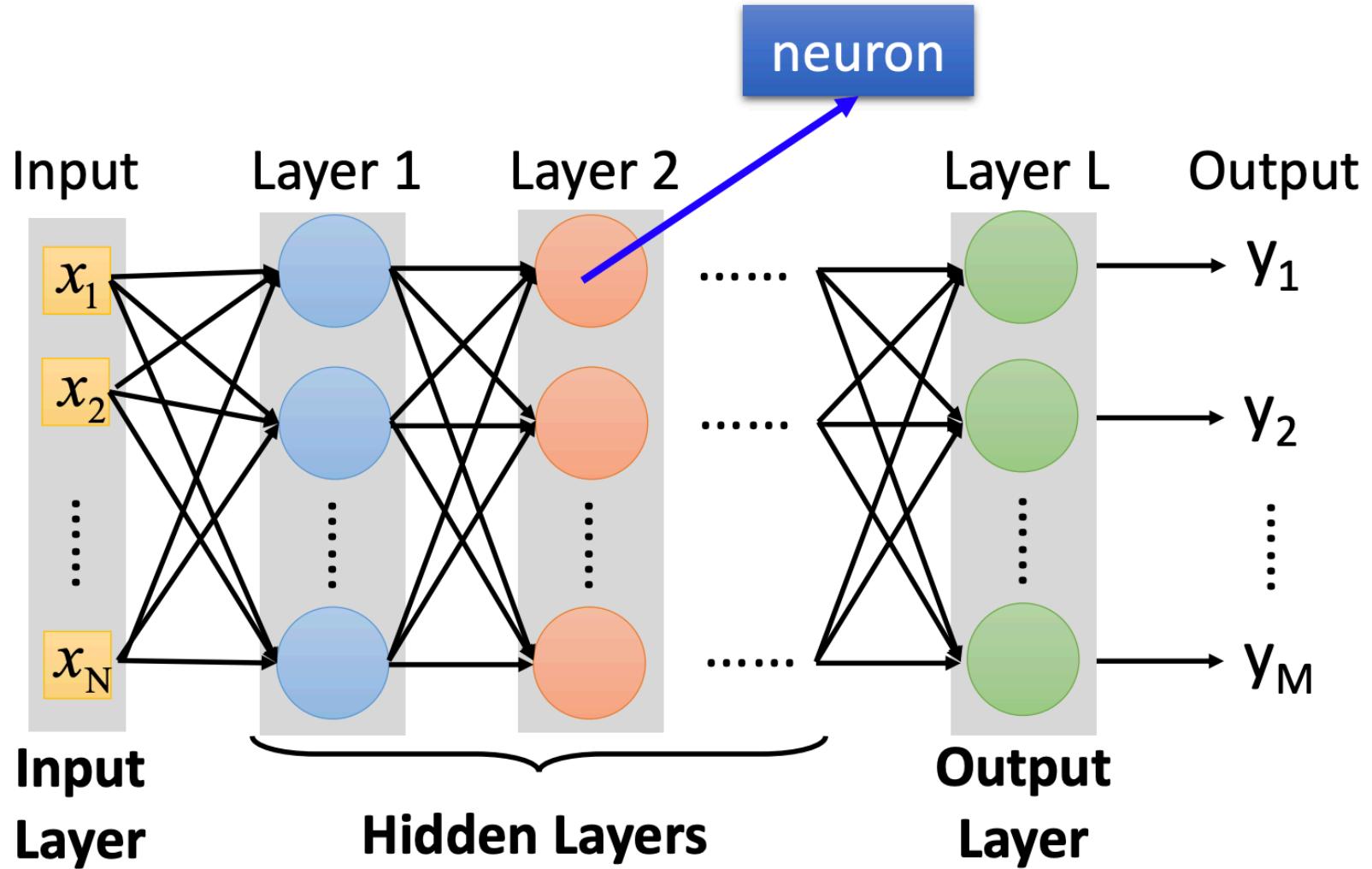
2020.03.26

Outline

- ✓ Introduction
- ✓ Roadmap
- ✓ Tasks, Dataset, and Benchmark
- ✓ Spatial-based GNN
- ✓ Graph Signal Processing and Spectral-based GNN
- ✓ Graph Generation
- ✓ GNN for NLP
- ✓ Online Resources

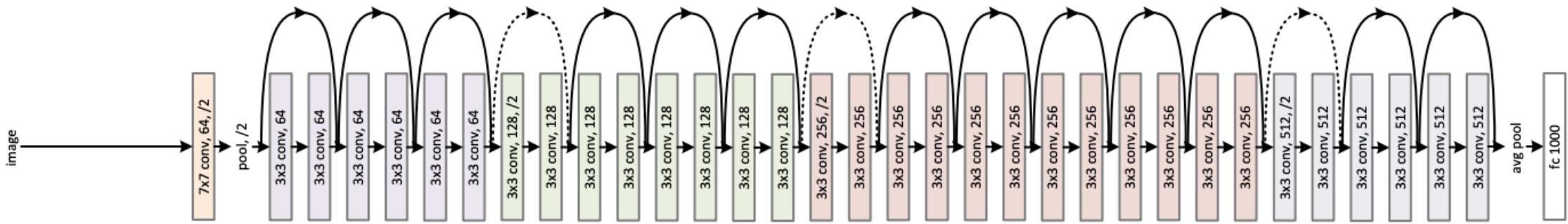
Graph Neural Networks

Neural Network



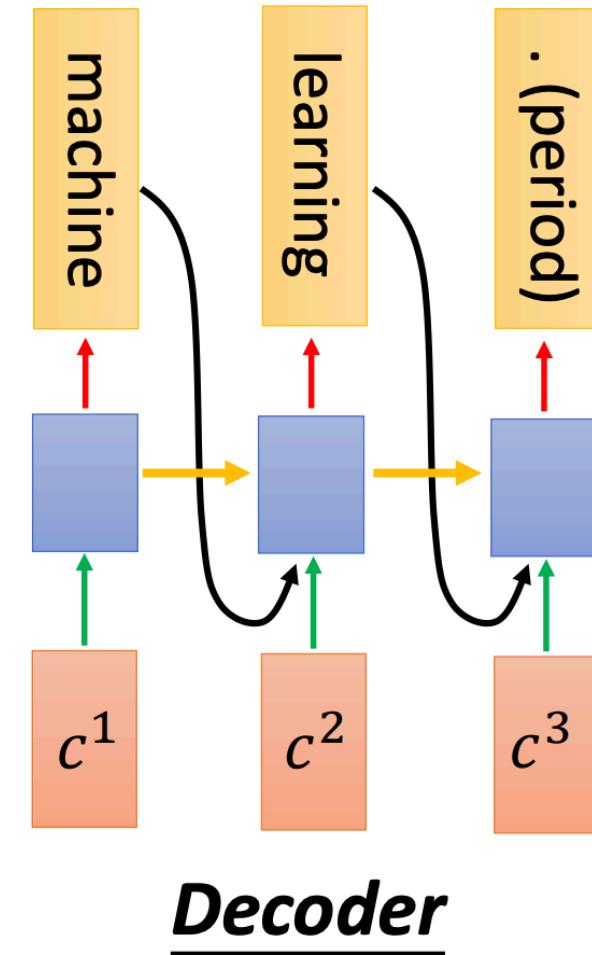
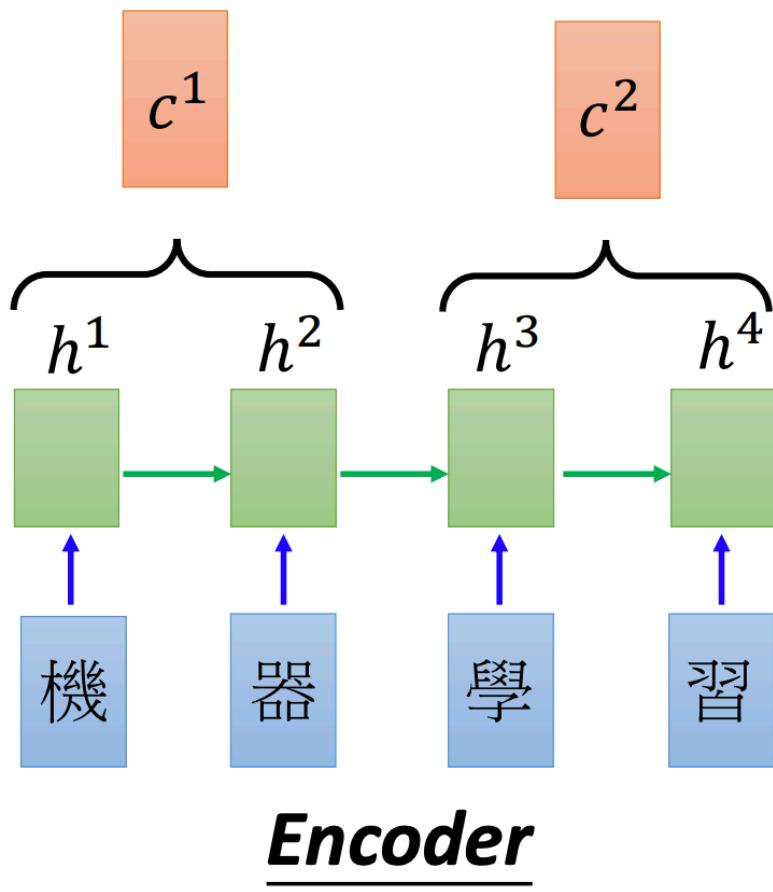
CNN

34-layer residual

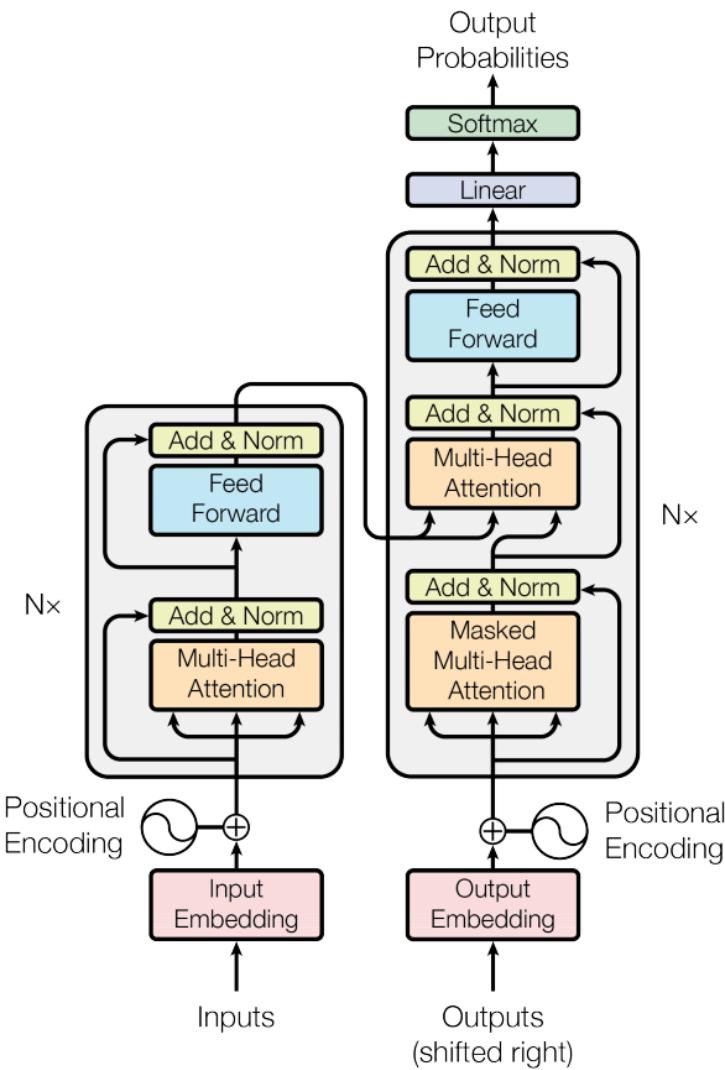


<https://arxiv.org/pdf/1512.03385.pdf>

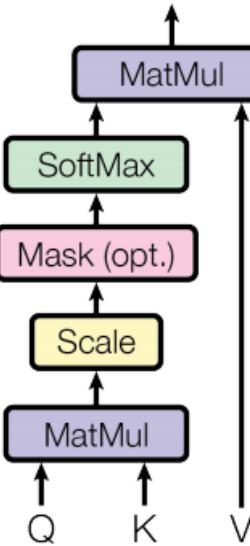
RNN



Transformer

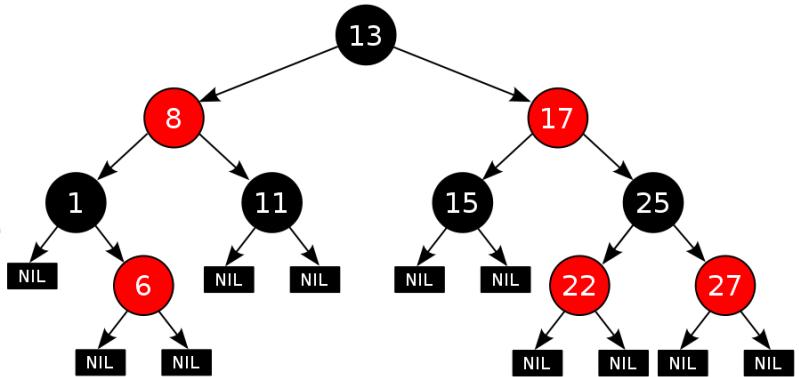
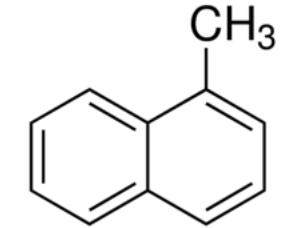
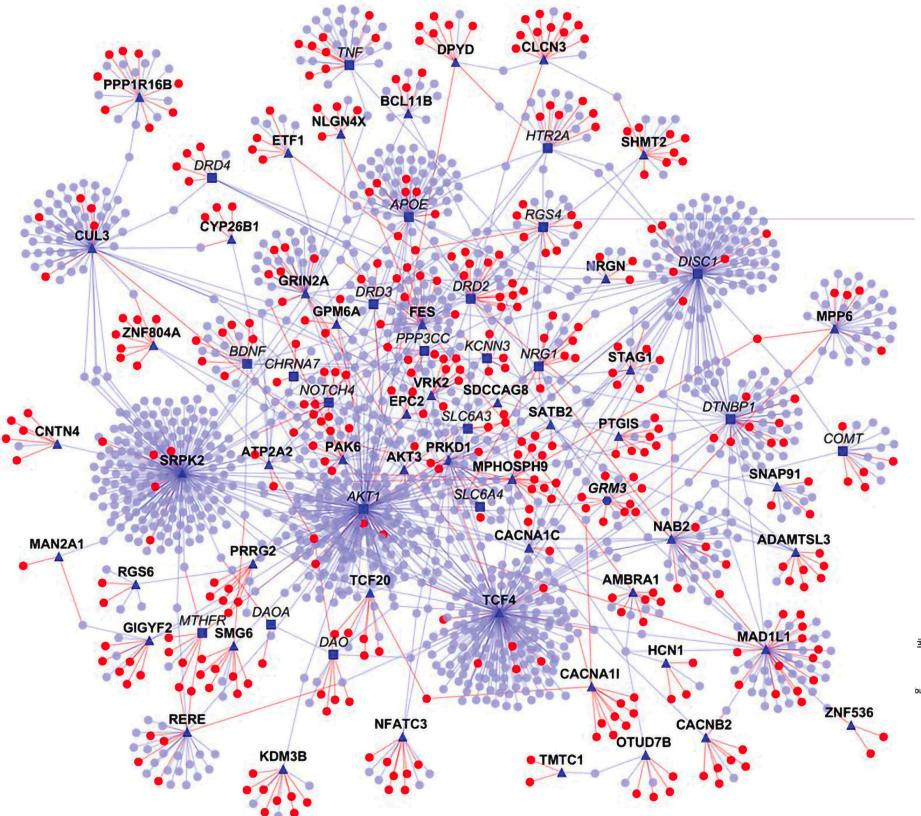


Scaled Dot-Product Attention

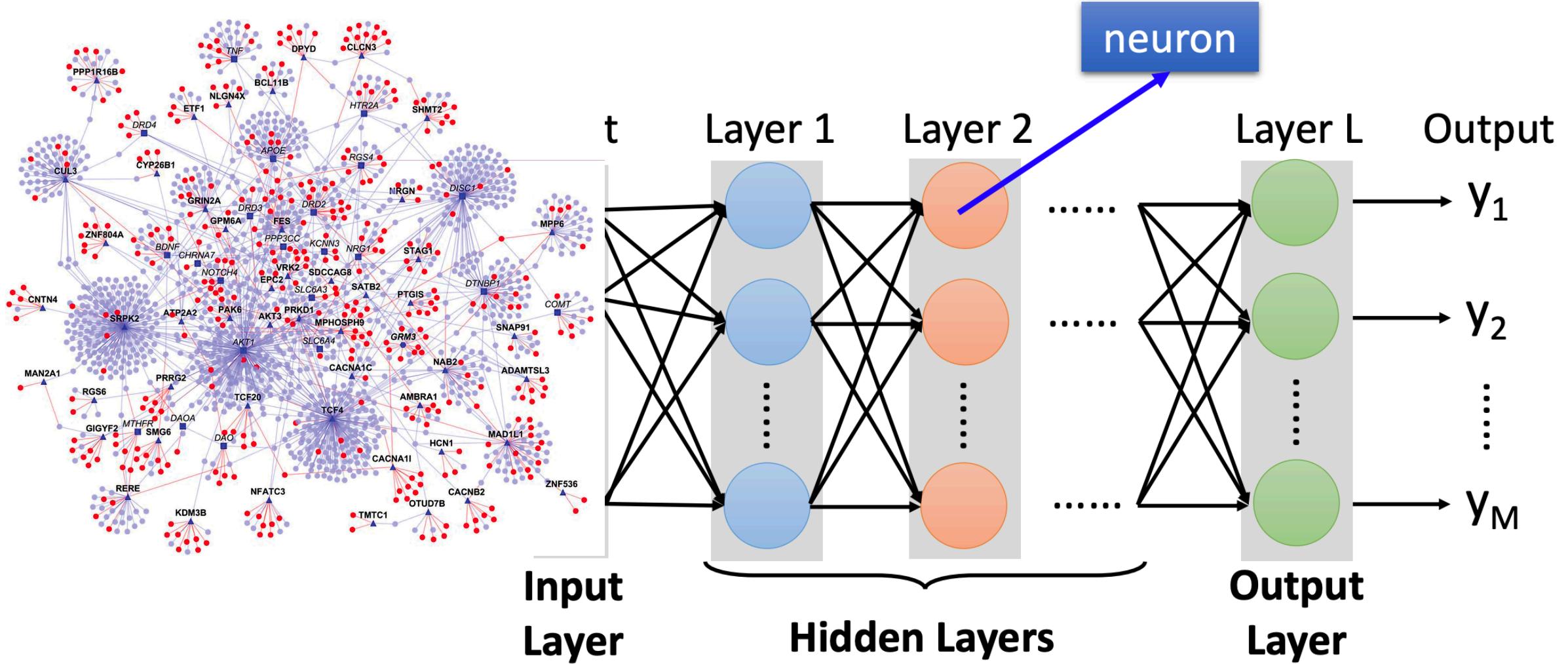


<https://arxiv.org/pdf/1706.03762.pdf>
[http://speech.ee.ntu.edu.tw/~tlkagk/courses/ML_2019/Lecture/Transformer%20\(v5\).pdf](http://speech.ee.ntu.edu.tw/~tlkagk/courses/ML_2019/Lecture/Transformer%20(v5).pdf)

Graph

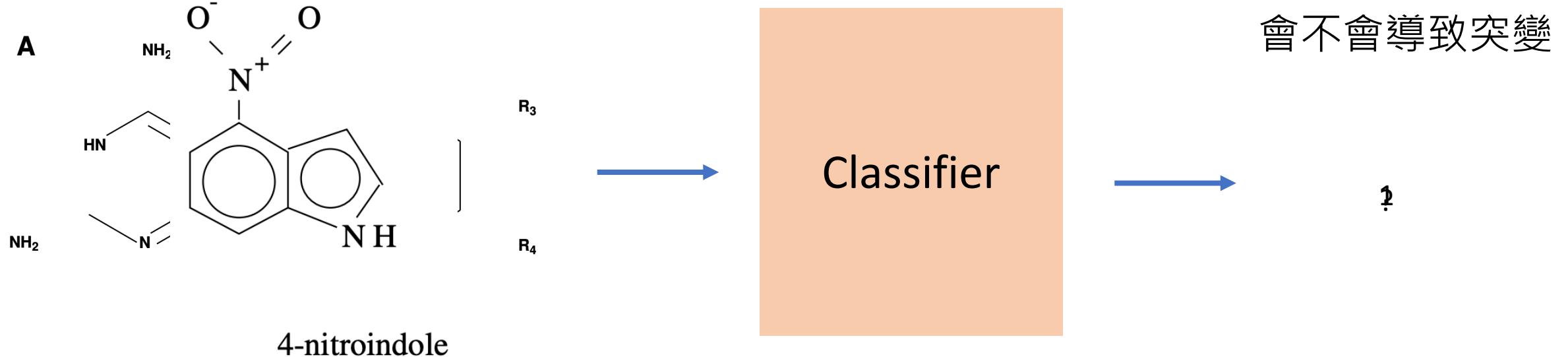


GNN



GNN: Why?

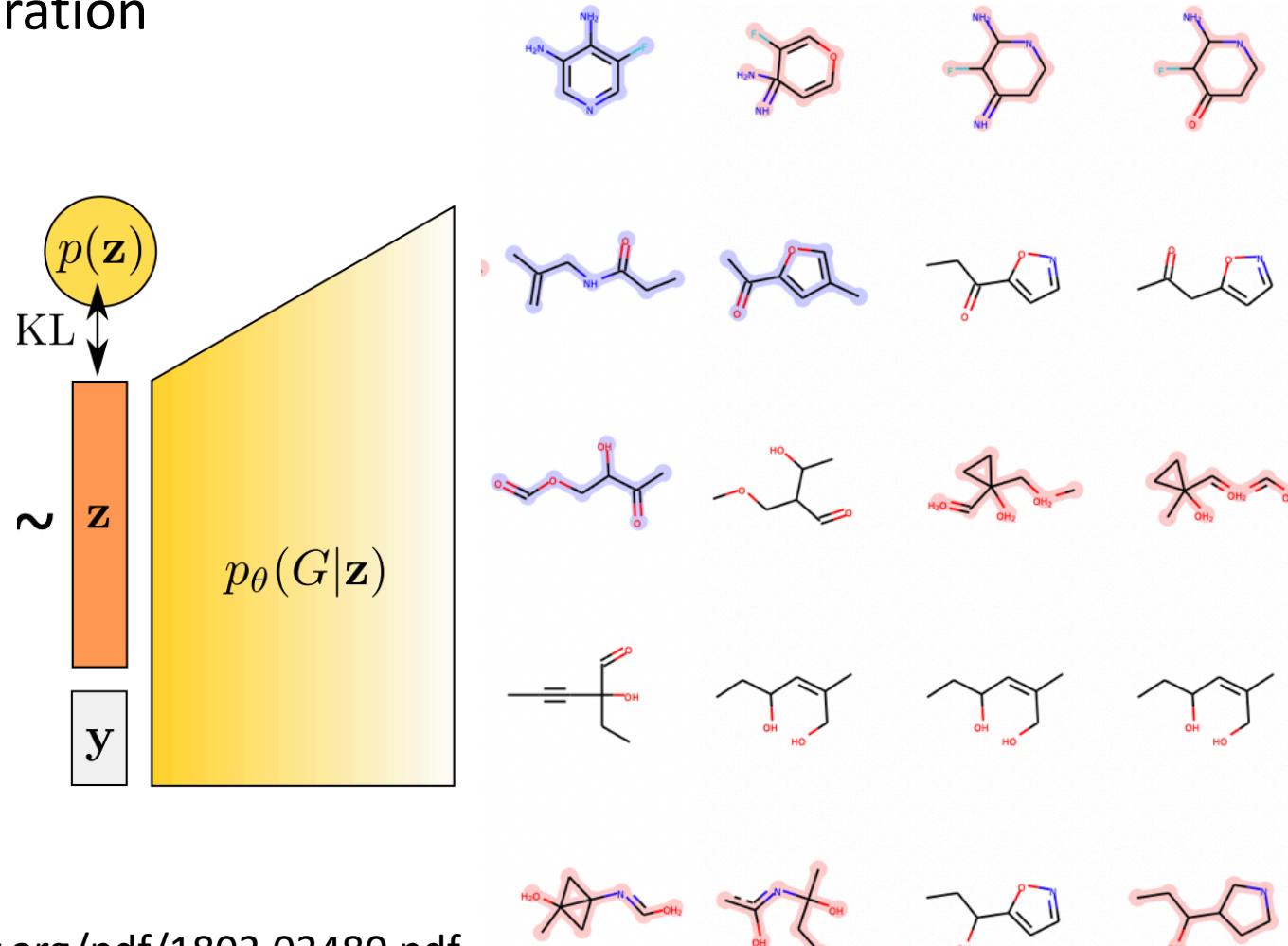
- ✓ Why do we need GNN?
 - Classification



GNN: Why?

✓ Why do we need GNN?

➤ Generation



GNN: Why?

- ✓ Example: テセウスの船



Name

Feature

Who is the murderer?

GNN: Why?

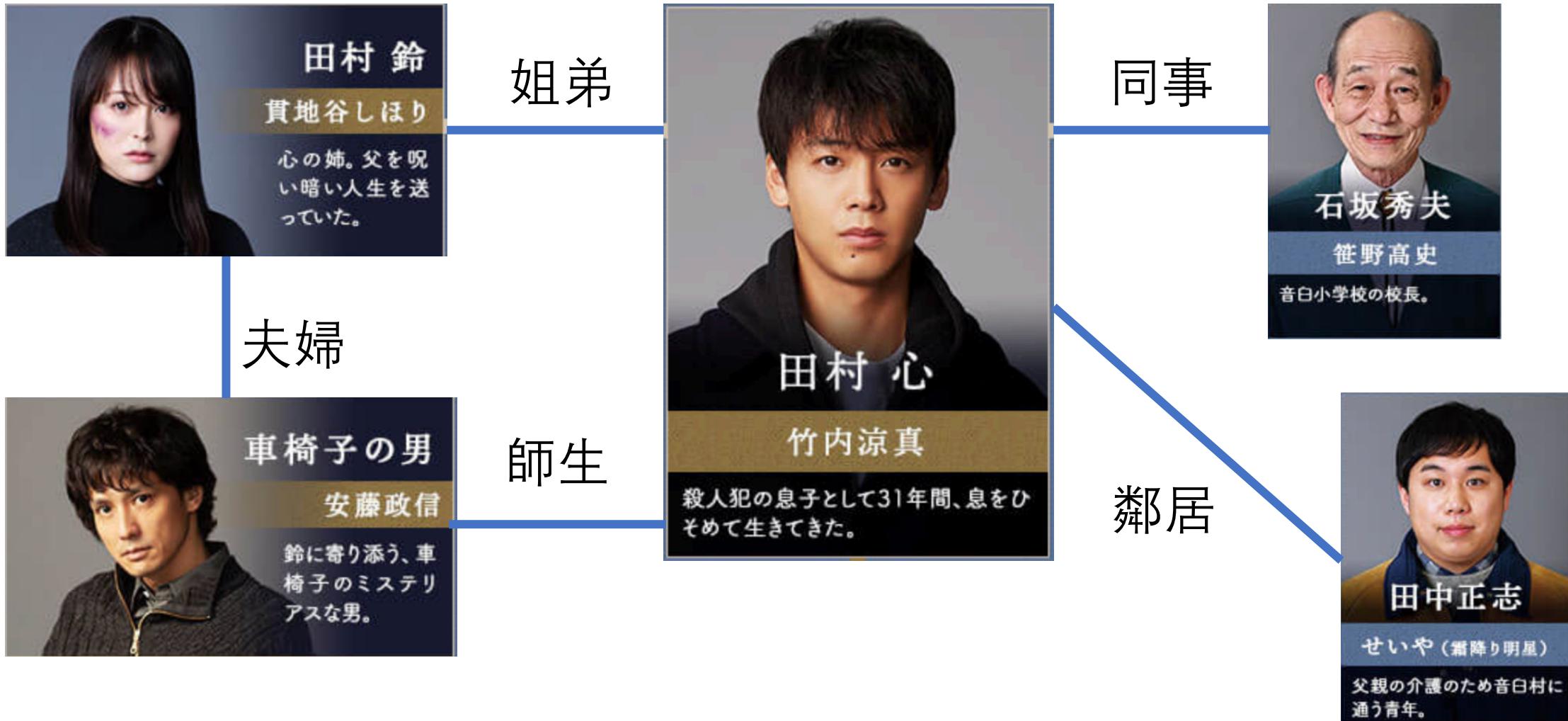
- ✓ We can train a classifier

$$f(\text{田村 鈴}) = \text{False} \quad f(\text{石坂秀夫}) = \text{False}$$
$$f(\text{田村 心}) = \text{False} \quad f(\text{車椅子の男}) = ?$$



GNN: Why?

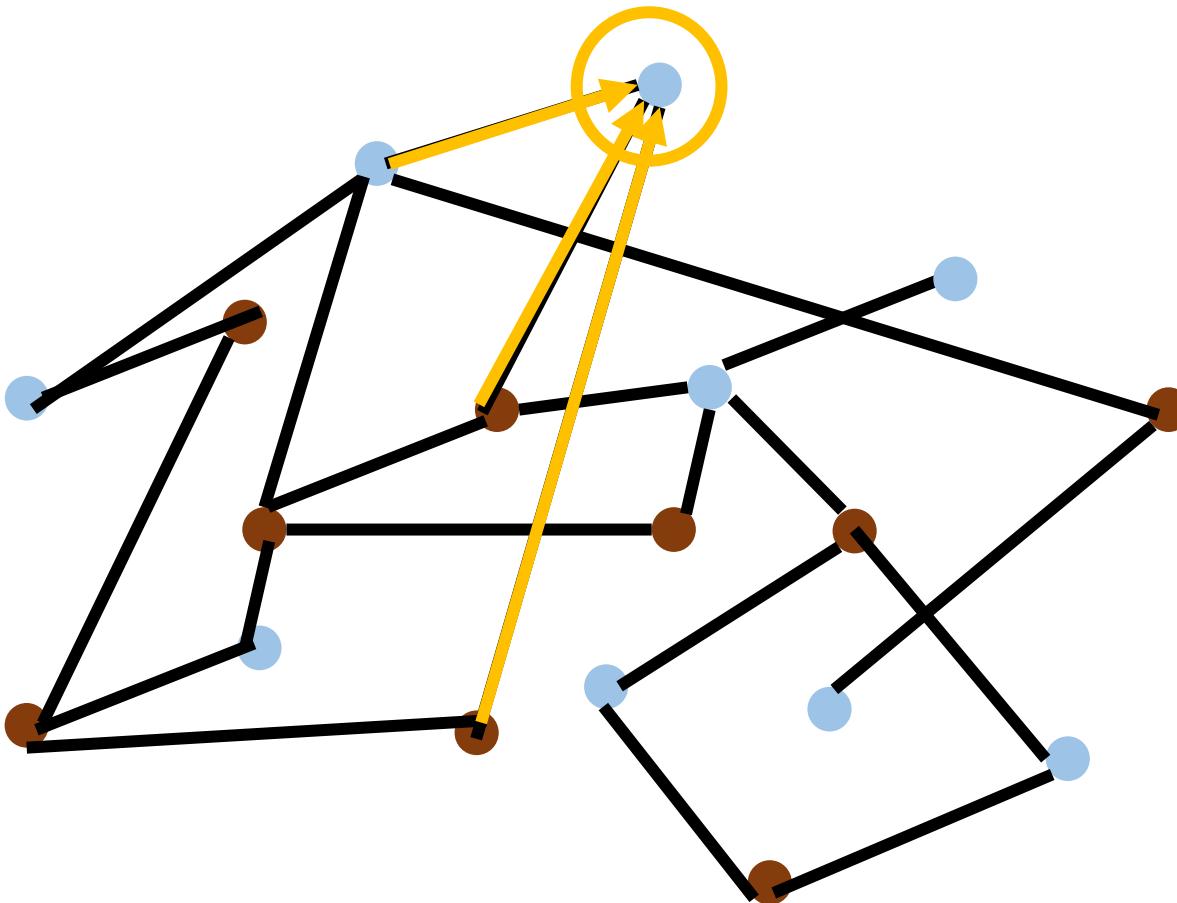
- ✓ The data may have underlying structure and relationship



GNN: Why?

- ✓ How do we utilize the structures and relationship to help our model?
- ✓ What if the graph is larger, like 20k nodes?
- ✓ What if we don't have all the labels?

GNN: Why



- Labeled Node
 - Unlabeled Node
- Semi-Supervised Learning

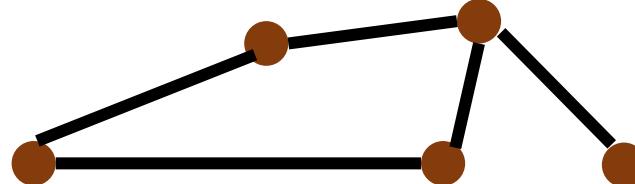
A node can learn the structure from its neighbors, but how?

GNN: How?

- ✓ Convolution?

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image with
3 x 3 kernel



GNN: How?

- ✓ How to embed node into a feature space using convolution?
- ✓ Solution 1: Generalize the concept of convolution (corelation) to graph >> Spatial-based convolution
- ✓ Solution 2: Back to the definition of convolution in signal processing
>> Spectral-based convolution

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GNN Roadmap

Theoretical analysis: GIN, GCN

Convolution

Spatial-based

Aggregation	Method
Sum	NN4G
Mean	DCNN, DGC, GraphSAGE
Weighted sum	MoNET, GAT , GIN
LSTM	GraphSAGE
Max Pooling	GraphSAGE

Spectral-based

ChebNet → **GCN** → HyperGCN

Tasks

- Supervised classification
- Semi-Supervised Learning
- Representation learning: Graph InfoMax
- Generation: GraphVAE, MolGAN, etc.

~~Application: Natural Language Processing~~

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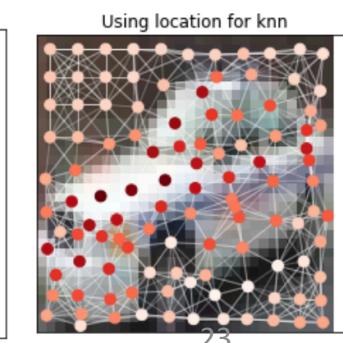
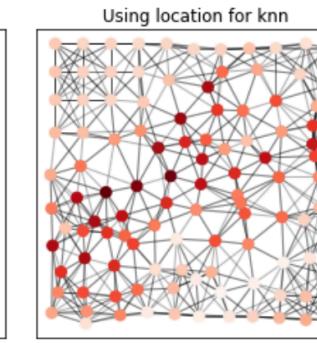
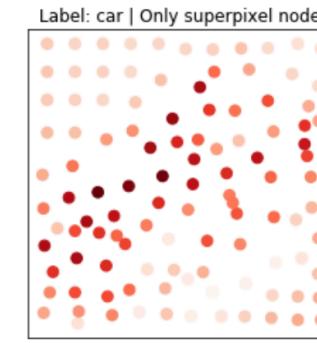
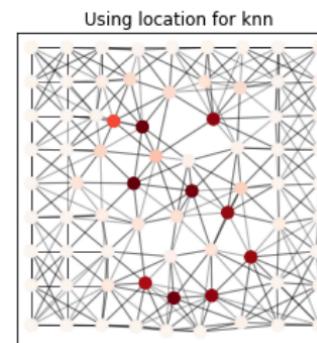
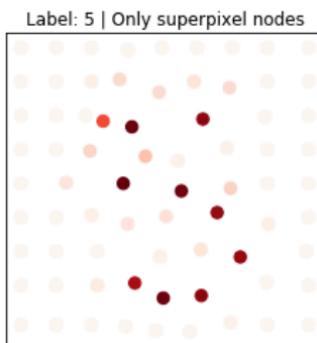
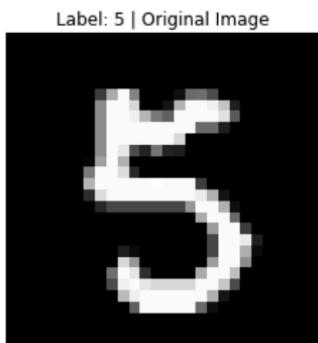
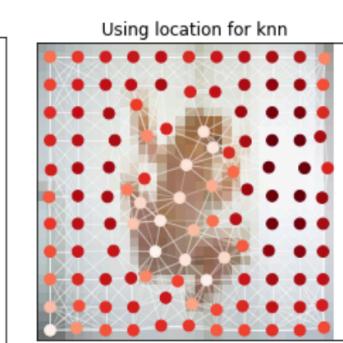
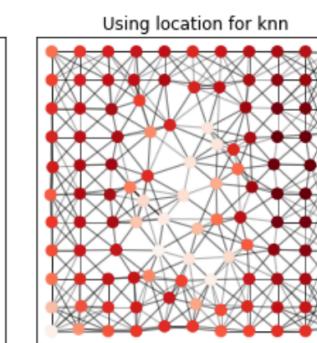
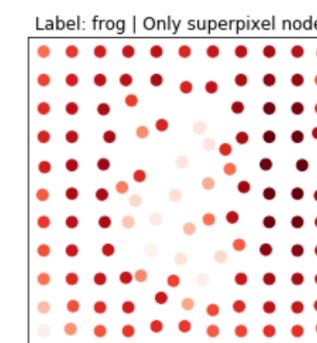
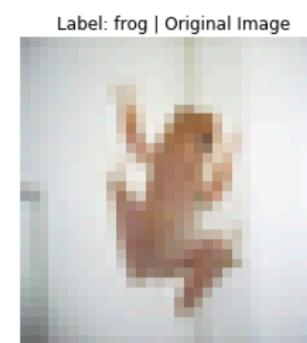
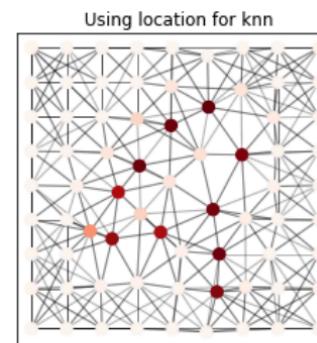
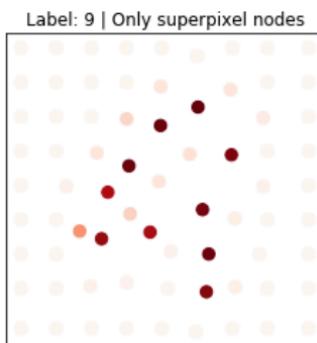
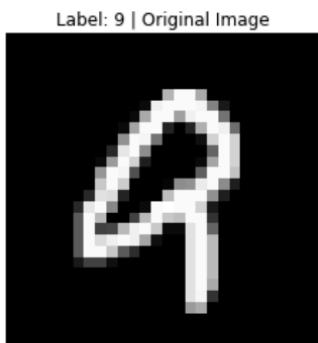
Tasks, Dataset, and Benchmark

- ✓ Tasks
 - Semi-supervised node classification
 - Regression
 - Graph classification
 - Graph representation learning
 - Link prediction
- ✓ Common dataset
 - CORA: citation network. 2.7k nodes and 5.4k links
 - TU-MUTAG: 188 molecules with 18 nodes on average

Benchmark tasks

- ✓ Graph Classification: SuperPixel MNIST and CIFAR10

Domain/Construction	Dataset	# graphs	# nodes
Computer Vision/ Graphs constructed with super-pixels	MNIST	70K	40-75
	CIFAR10	60K	85-150

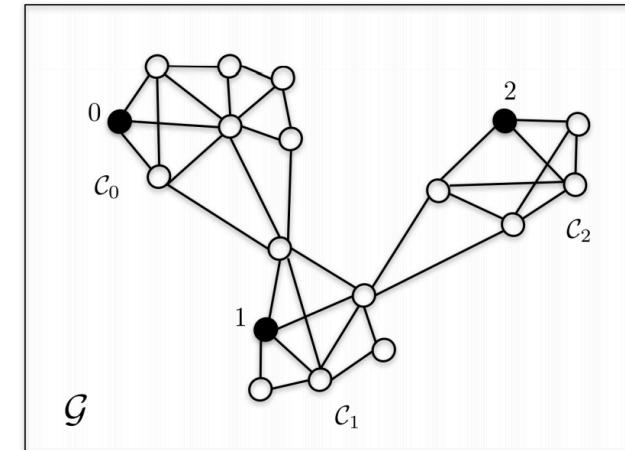
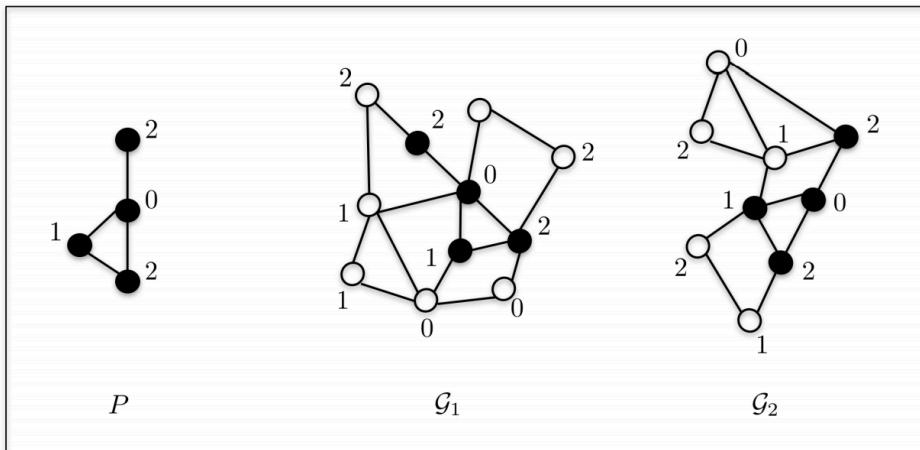


Benchmark tasks

- ✓ Regression: ZINC molecule graphs dataset

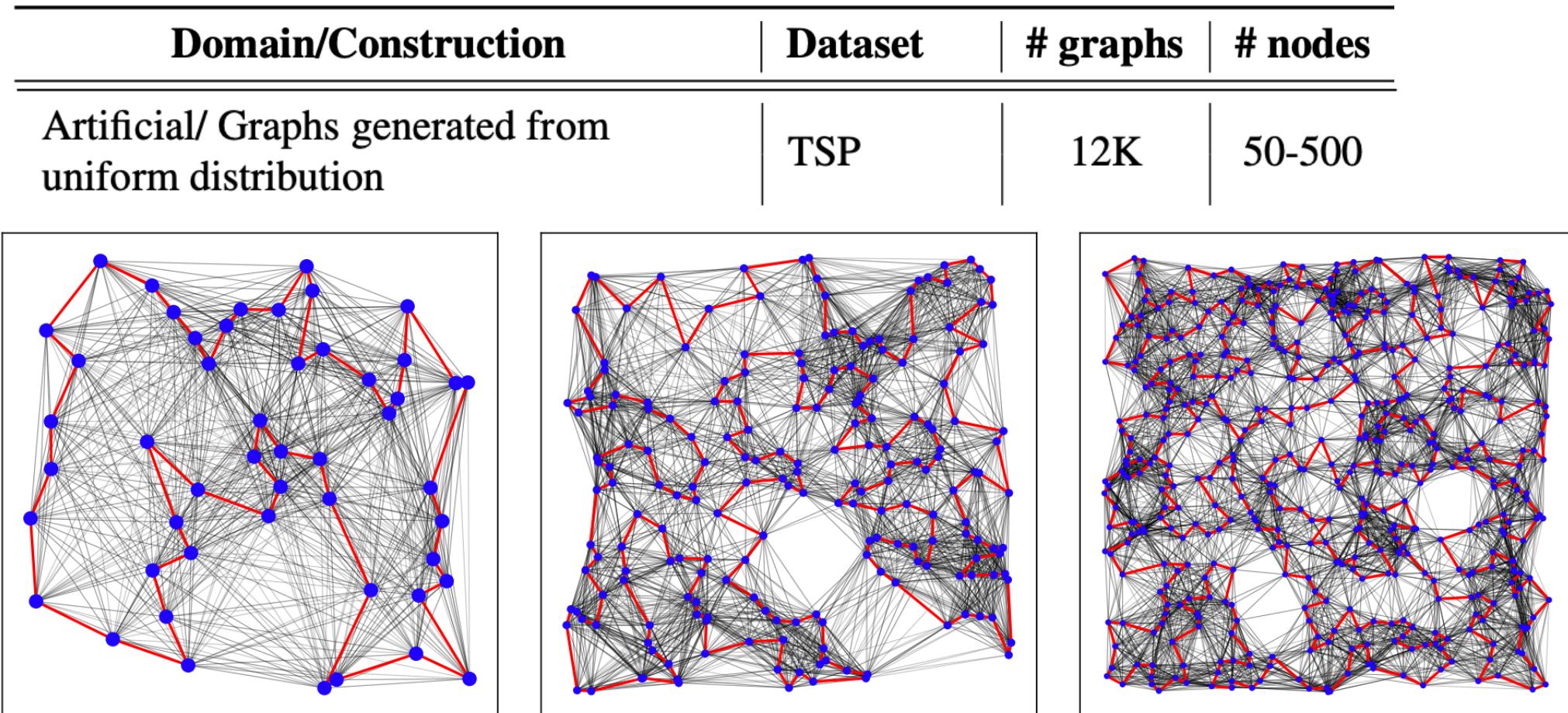
Domain/Construction	Dataset	# graphs	# nodes
Chemistry/ Real-world molecular graphs	ZINC	12K	9-37
Artificial/ Graphs generated from Stochastic Block Model	PATTERN	14K	50-180
	CLUSTER	12K	40-190

- ✓ Node classification: Stochastic Block Model dataset
 - graph pattern recognition and semi-supervised graph clustering



Benchmark tasks

- ✓ Edge classification: Traveling Salesman Problem



(a) TSP50

(b) TSP200

(c) TSP500

Results

✓ SuperPixel

Dataset	Model	#Param	No Residual	
			Acc	Epoch/Total
MNIST	MLP	104044	94.46±0.28	21.82s/1.02hr
	MLP (Gated)	105717	95.18±0.18	22.43s/0.73hr
	GCN	101365	89.05±0.21	79.18s/1.76hr
	GraphSage	102691	97.20±0.17	76.80s/1.42hr
	GIN	105434	93.96±1.30	34.61s/0.74hr
	DiffPool	106538	94.66±0.48	171.38s/4.45hr
	GAT	110400	95.56±0.16	377.06s/6.35hr
	MoNet	104049	89.73±0.48	567.12s/12.05hr
	GatedGCN	104217	97.36±0.12	127.15s/2.13hr
	GatedGCN-E*	104217	97.47±0.13	127.86s/2.15hr
CIFAR10	MLP	104044	56.01±0.90	21.82s/1.02hr
	MLP (Gated)	106017	56.78±0.12	27.85s/0.68hr
	GCN	101657	51.64±0.45	100.30s/2.44hr
	GraphSage	102907	66.08±0.24	96.00s/1.79hr
	GIN	105654	47.66±0.47	44.30s/0.93hr
	DiffPool	108042	56.84±0.37	299.64s/10.42hr
	GAT	110704	65.48±0.33	386.14s/7.75hr
	MoNet	104229	50.99±0.17	869.90s/21.79hr
	GatedGCN	104357	68.92±0.38	145.14s/2.49hr
	GatedGCN-E*	104357	69.37±0.48	145.66s/2.43hr

Results

✓ Regression

Model	#Param	No Residual	
		Acc/MAE	Epoch/Total
MLP	108975	0.710±0.001	1.19s/0.02hr
MLP (Gated)	106970	0.681±0.005	1.16s/0.03hr
GCN	103077	0.525±0.007	2.97s/0.09hr
GraphSage	105031	0.410±0.005	3.20s/0.10hr
GIN	103079	0.408±0.008	2.50s/0.06hr
DiffPool	110561	0.514±0.007	12.36s/0.38hr
GAT	102385	0.496±0.004	21.03s/0.62hr
MoNet	106002	0.444±0.024	11.75s/0.34hr
GatedGCN	105735	0.422±0.006	6.12s/0.17hr
GatedGCN-E*	105875	0.365±0.009	6.17s/0.17hr

Results

✓ SBM

Dataset	Model	#Param	No Residual	
			Acc	Epoch/Total
PATTERN	MLP	105263	50.13±0.00	8.68s/0.10hr
	MLP (Gated)	103629	50.13±0.00	9.78s/0.12hr
	GCN	100923	55.22±0.17	97.46s/2.30hr
	GraphSage	98607	81.25±3.84	79.43s/2.14hr
	GIN	100884	98.25±0.38	14.11s/0.37hr
	GAT	109936	88.91±4.48	229.65s/8.78hr
	MoNet	103775	97.89±0.89	870.05s/24.86hr
	GatedGCN	104003	97.24±1.19	115.03s/2.59hr
CLUSTER	MLP	106015	20.97±0.01	6.54s/0.08hr
	MLP (Gated)	104305	20.97±0.01	7.37s/0.09hr
	GCN	101655	34.85±0.65	66.81s/1.21hr
	GraphSage	99139	53.90±4.12	54.40s/1.19hr
	GIN	103544	52.54±1.03	11.57s/0.27hr
	GAT	110700	54.12±1.21	158.46s/4.53hr
	MoNet	104227	39.48±2.21	600.04s/11.18hr
	GatedGCN	104355	50.18±3.03	80.66s/2.07hr

Results

✓ TSP

Model	#Param	No Residual	
		F1	Epoch/Total
MLP	94394	0.548±0.003	53.92s/2.85hr
MLP (Gated)	115274	0.548±0.001	54.39s/2.44hr
GCN	108738	0.547±0.003	164.41s/10.28hr
GraphSage	98450	0.657±0.002	147.22s/14.33hr
GIN	118574	0.657±0.001	74.71s/5.60h
GAT	109250	0.567±0.003	360.74s/20.55hr
MoNet	94274	0.569±0.002	1472.65s/42.44hr
GatedGCN	94946	0.791±0.003	202.12s/15.20hr
GatedGCN-E*	94946	0.794±0.003	201.32s/15.05hr

Results

✓ TSP

Model	L	#Param	Residual		No Residual	
			F1	Epoch/Total	F1	Epoch/Total
GCN	4	108738	0.628	165.15s/5.69hr	0.552	168.72s/6.14hr
	8	175810	0.639	279.33s/9.86hr	0.568	281.56s/14.16hr
	16	309954	0.651	502.59s/21.37hr	0.532	507.35s/10.72hr
	32	578242	0.666	1042.46s/28.96hr	0.361	1031.62s/15.19hr
GIN	4	118574	0.653	71.41s/2.50hr	0.653	75.63s/3.34hr
	8	223866	0.675	93.95s/4.26hr	0.674	93.41s/5.19hr
	16	434450	0.681	146.09s/5.68hr	0.642	144.52s/2.89hr
	32	855618	0.669	274.5s/3.81hr	0.6063	282.97s/4.40hr
GatedGCN	4	94946	0.792	214.67s/6.50hr	0.787	212.67s/9.75hr
	8	179170	0.817	374.39s/14.56hr	0.807	367.68s/19.72hr
	16	347618	0.833	685.41s/22.85hr	0.810	678.76s/22.07hr
	32	684514	0.843	1760.56s/48.00hr	0.722	1760.55s/33.27hr



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Review: Convolution

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image with
3 x 3 kernel

Layer i

1	0	-1
0	1	3
-2	0	1

3 x 3 kernel

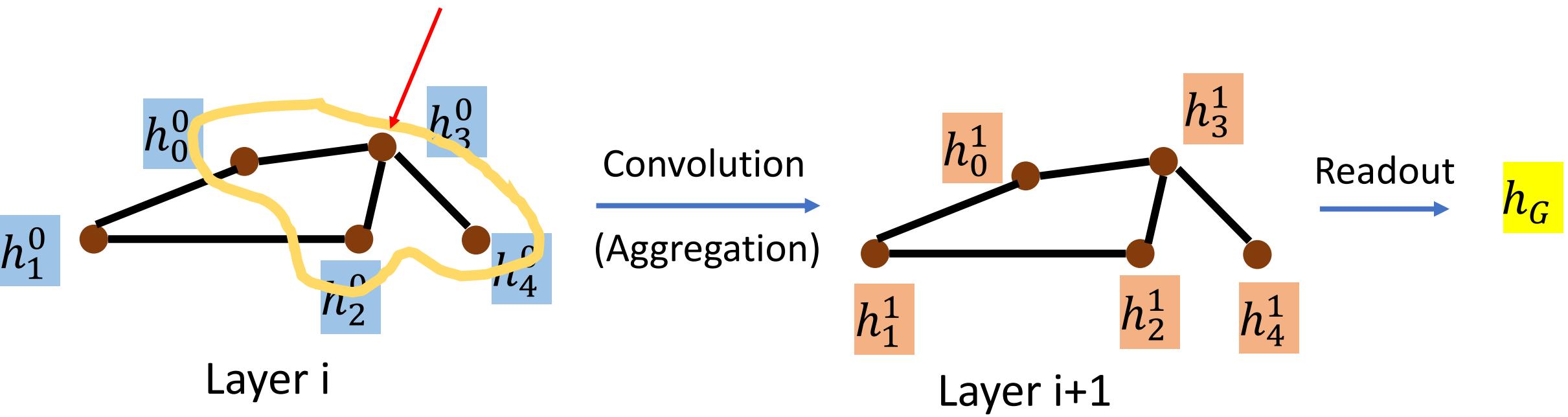
	5	1			

Layer i+1

Spatial-based Convolution

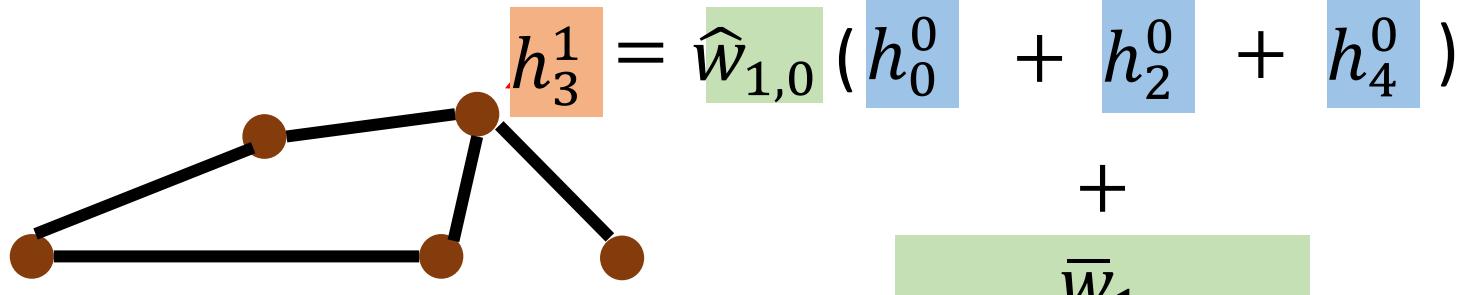
✓ Terminology:

- Aggregate: 用 neighbor feature update 下一層的 hidden state
- Readout: 把所有 nodes 的 feature 集合起來代表整個 graph

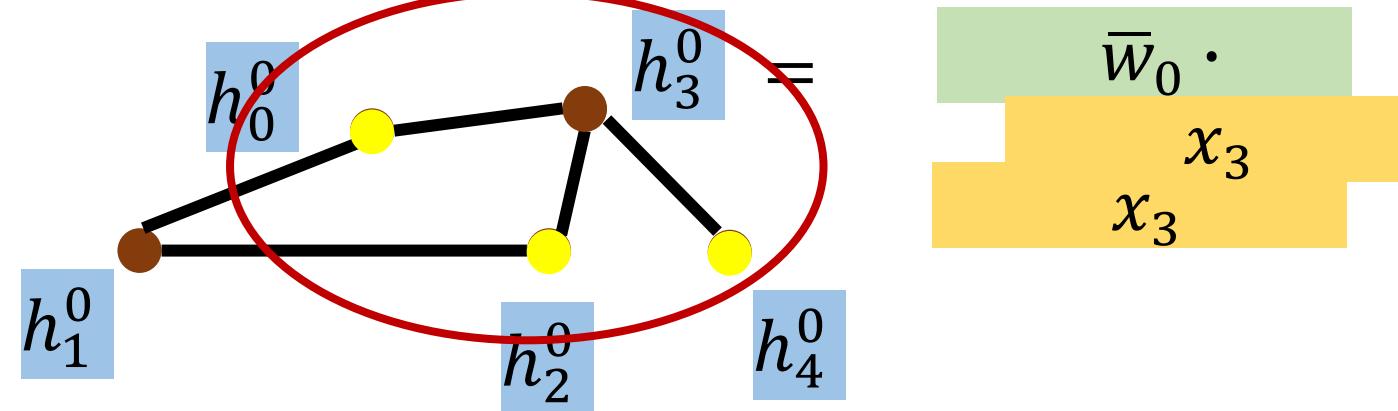


NN4G (Neural Networks for Graph)

Hidden layer 1:

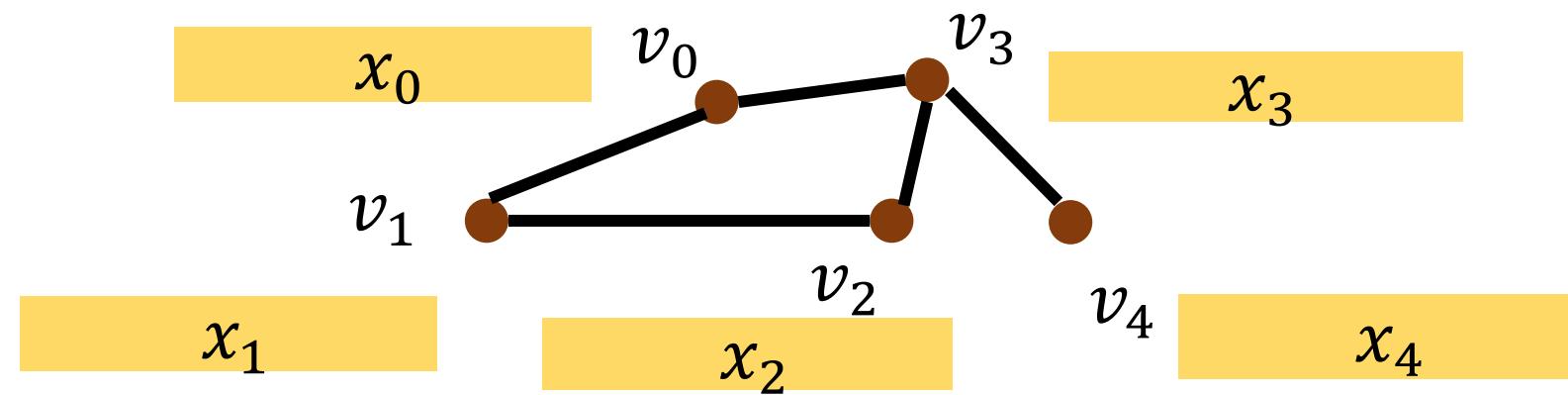


Hidden layer 0:



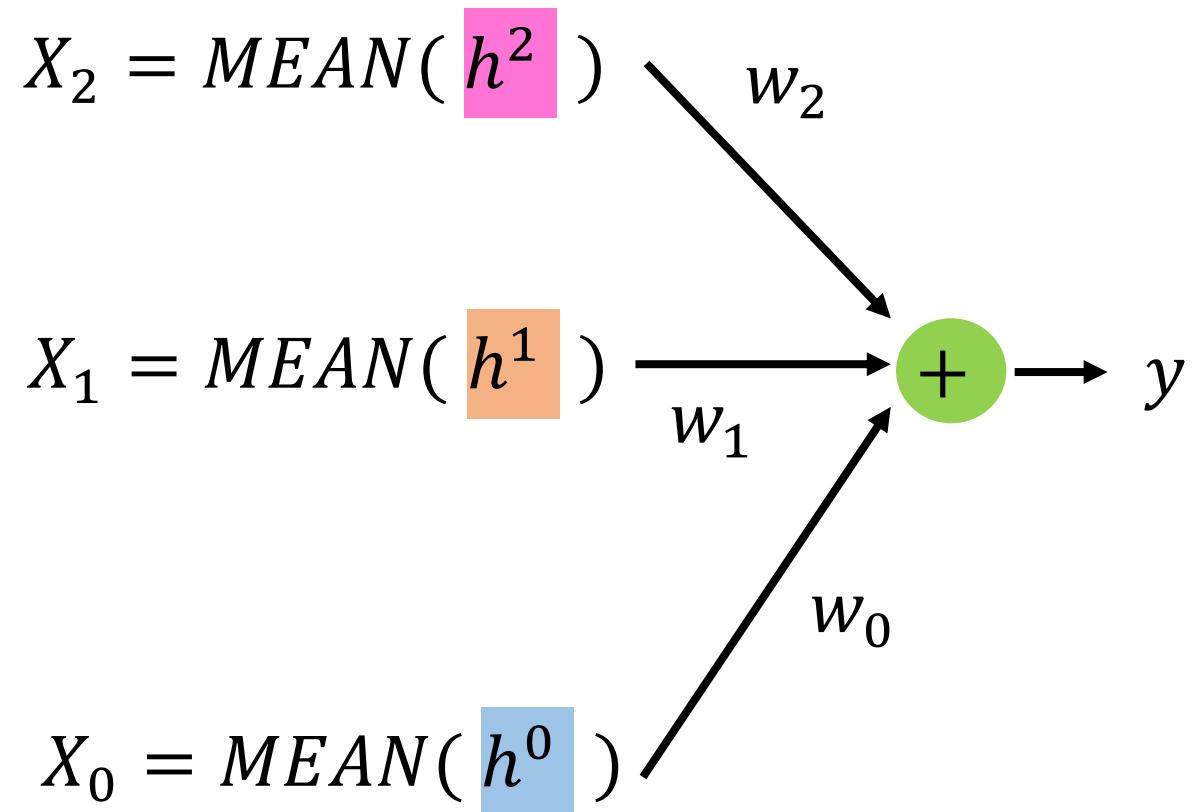
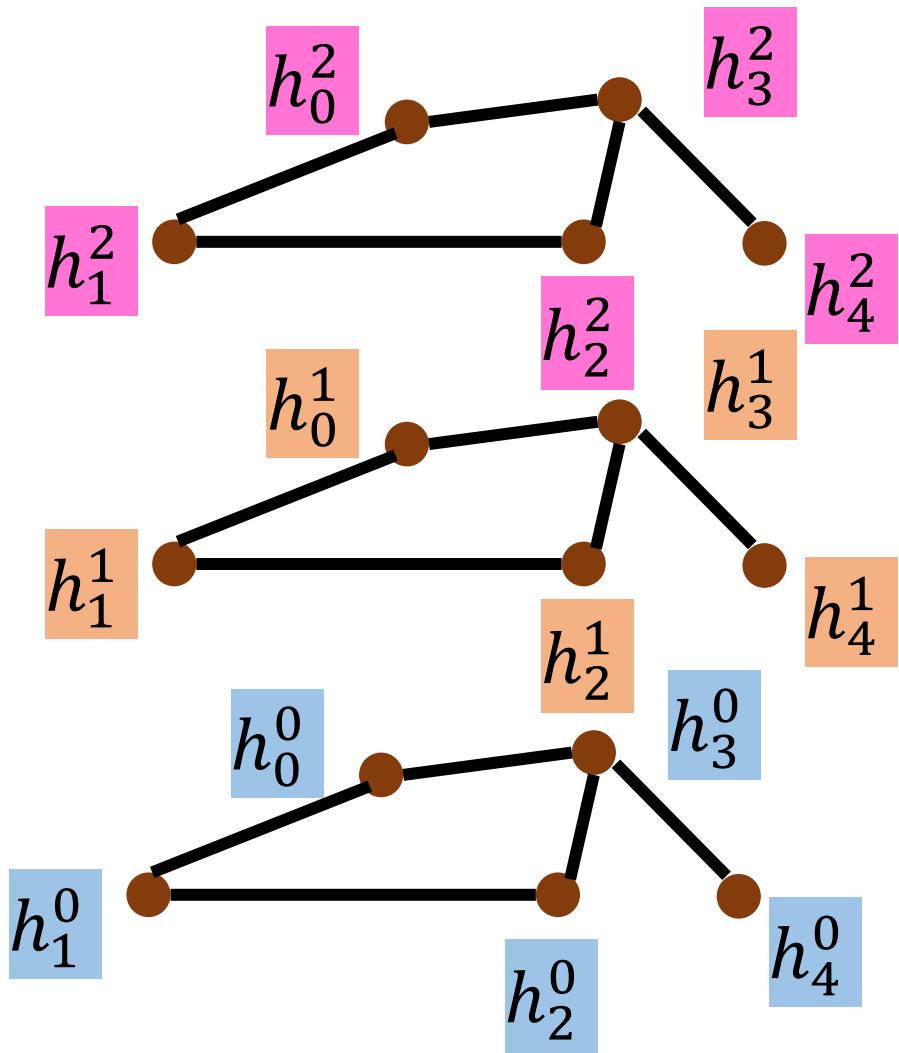
h_{node}^{layer}

Input layer

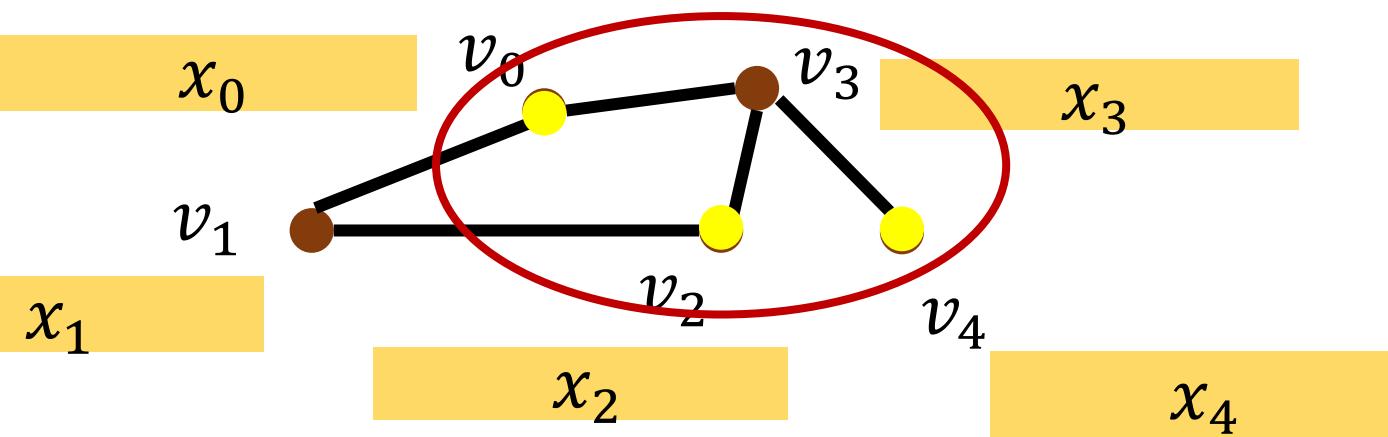
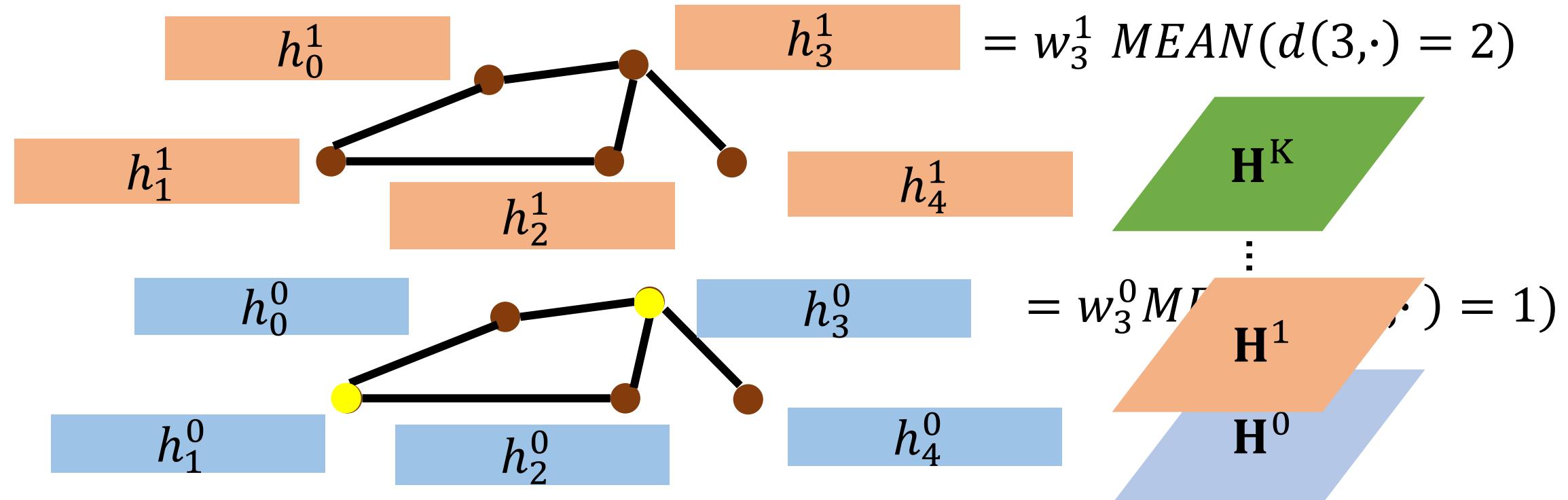


NN4G (Neural Networks for Graph)

✓ Readout:

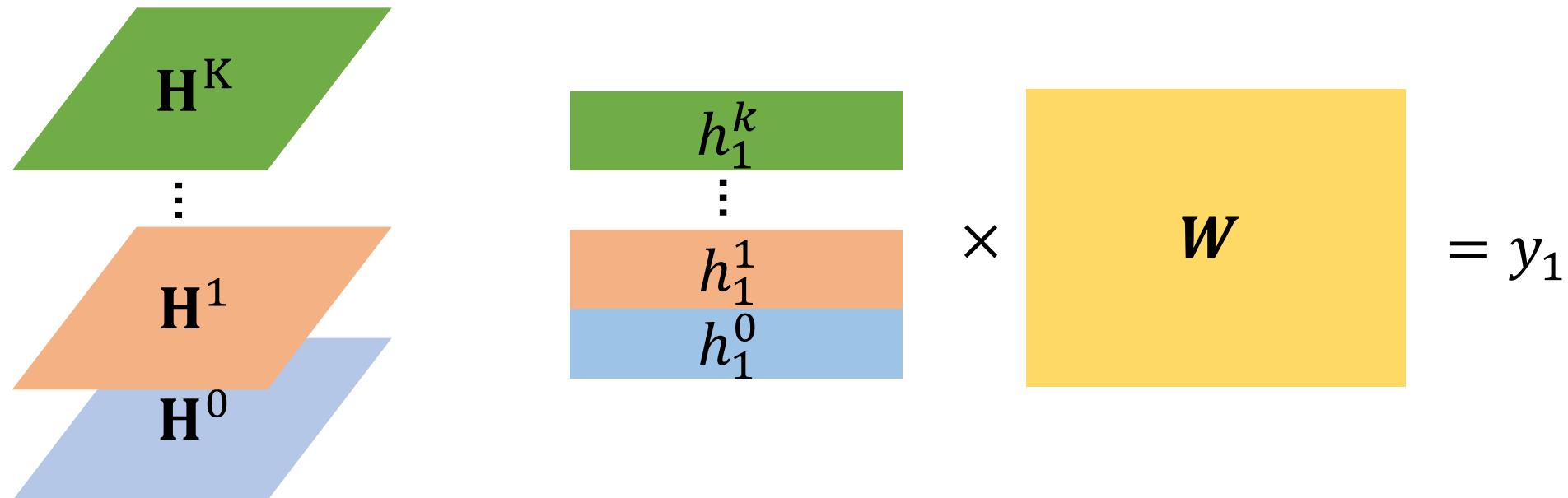


DCNN (Diffusion-Convolution Neural Network)

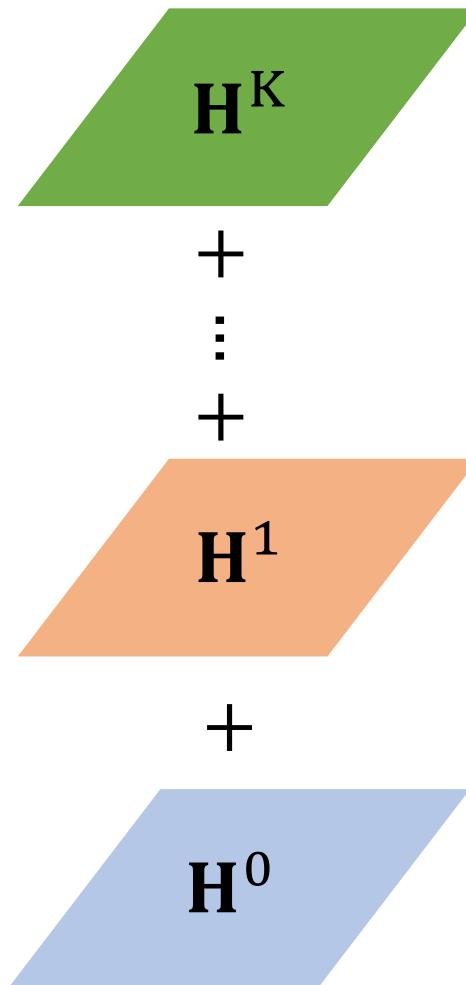


DCNN (Diffusion-Convolution Neural Network)

- ✓ Node features



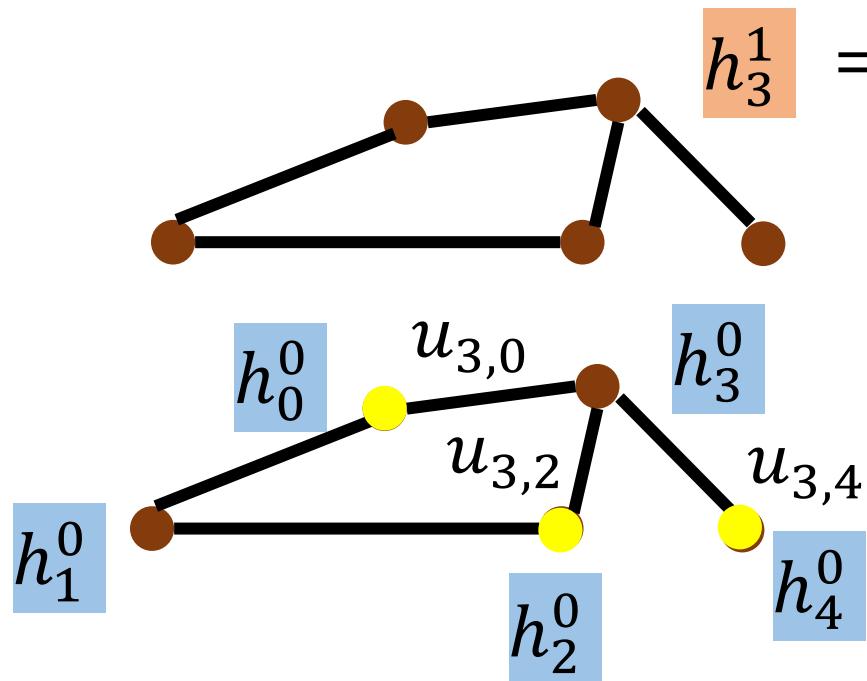
DGC (Diffusion Graph Convolution)



Published as a conference paper at ICLR 2018

MoNET (Mixture Model Networks)

- ✓ Define a measure on node ‘distances’
- ✓ Use weighted sum (mean) instead of simply summing up (averaging) neighbor features.



$$h_3^1 = w(\hat{u}_{3,0}) \times h_0^0 + w(\hat{u}_{3,2}) \times h_2^0 + w(\hat{u}_{3,4}) \times h_4^0$$

\$w(\cdot)\$ is a NN, \$\hat{u}\$ is a transform from \$u\$

$$\mathbf{u}(x, y) = \left(\frac{1}{\sqrt{\deg(x)}}, \frac{1}{\sqrt{\deg(y)}} \right)^T$$

$$\sum_{y \in \mathcal{N}(x)} e^{-\frac{1}{2}(\tilde{\mathbf{u}}(x,y) - \boldsymbol{\mu}_j)^\top \boldsymbol{\Sigma}_j^{-1} (\tilde{\mathbf{u}}(x,y) - \boldsymbol{\mu}_j)} f_l(y)$$

MoNET

✓ Experiment

Method	Cora	PubMed
DCNN [2]	$76.80 \pm 0.60\%$	$73.00 \pm 0.52\%$
GCN [26]	$81.59 \pm 0.42\%$	$78.72 \pm 0.25\%$
MoNet	$81.69 \pm 0.48\%$	$78.81 \pm 0.44\%$

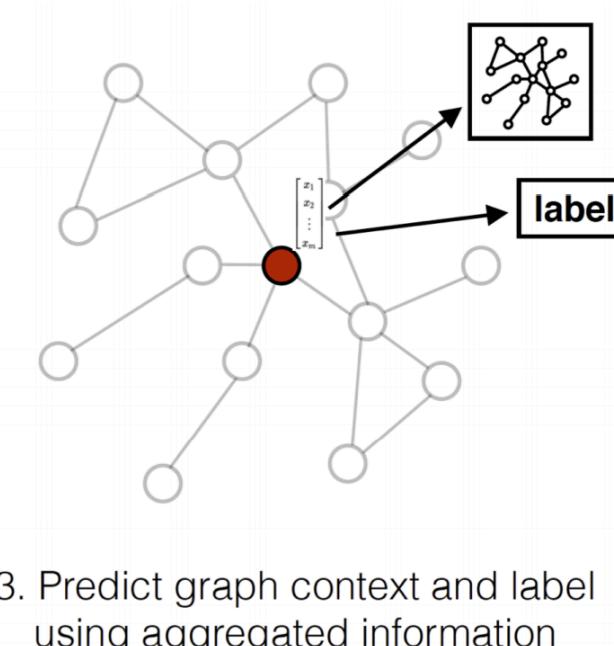
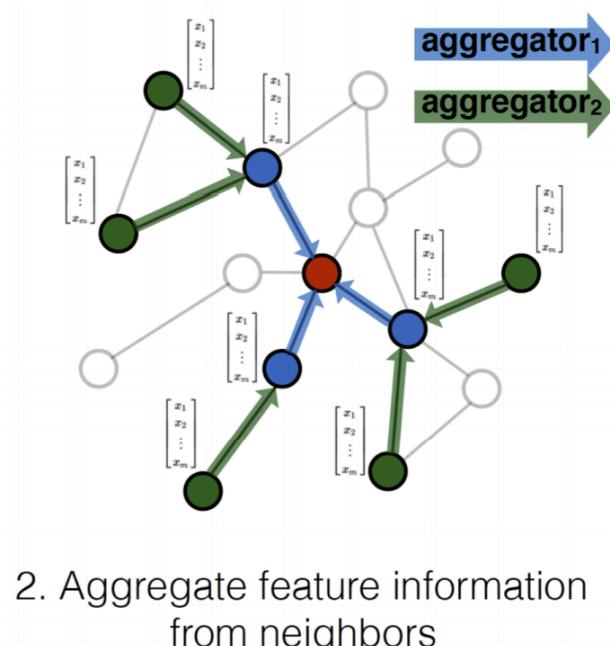
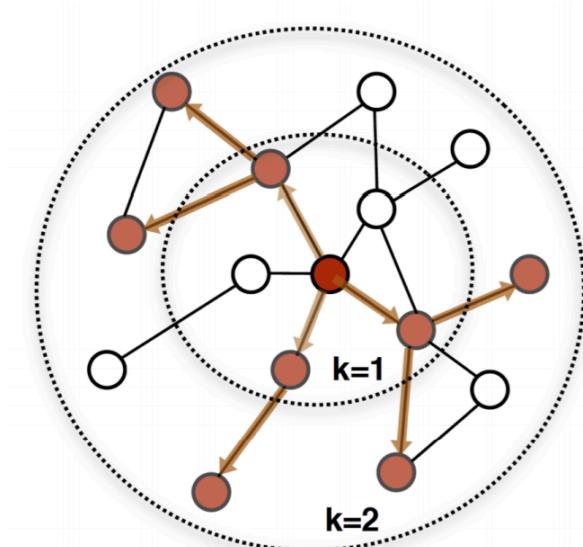
GraphSAGE

- ✓ SAmples and aggreGatE
- ✓ Can work on both transductive and inductive setting
- ✓ GraphSAGE learns how to embed node features from neighbors

```
1  $\mathbf{h}_v^0 \leftarrow \mathbf{x}_v, \forall v \in \mathcal{V}$ ;  
2 for  $k = 1 \dots K$  do  
3   for  $v \in \mathcal{V}$  do  
4      $\mathbf{h}_{\mathcal{N}(v)}^k \leftarrow \text{AGGREGATE}_k(\{\mathbf{h}_u^{k-1}, \forall u \in \mathcal{N}(v)\});$   
5      $\mathbf{h}_v^k \leftarrow \sigma(\mathbf{W}^k \cdot \text{CONCAT}(\mathbf{h}_v^{k-1}, \mathbf{h}_{\mathcal{N}(v)}^k))$   
6   end  
7    $\mathbf{h}_v^k \leftarrow \mathbf{h}_v^k / \|\mathbf{h}_v^k\|_2, \forall v \in \mathcal{V}$   
8 end  
9  $\mathbf{z}_v \leftarrow \mathbf{h}_v^K, \forall v \in \mathcal{V}$ 
```

GraphSAGE

- ✓ AGGREGATION: mean, max-pooling, or LSTM



<https://arxiv.org/pdf/1706.02216.pdf>

GraphSAGE

✓ Result

Name	Citation		Reddit		PPI	
	Unsup. F1	Sup. F1	Unsup. F1	Sup. F1	Unsup. F1	Sup. F1
GraphSAGE-GCN	0.742	0.772	0.908	0.930	0.465	0.500
GraphSAGE-mean	0.778	0.820	0.897	0.950	0.486	0.598
GraphSAGE-LSTM	0.788	0.832	0.907	0.954	0.482	0.612
GraphSAGE-pool	0.798	0.839	0.892	0.948	0.502	0.600
% gain over feat.	39%	46%	55%	63%	19%	45%

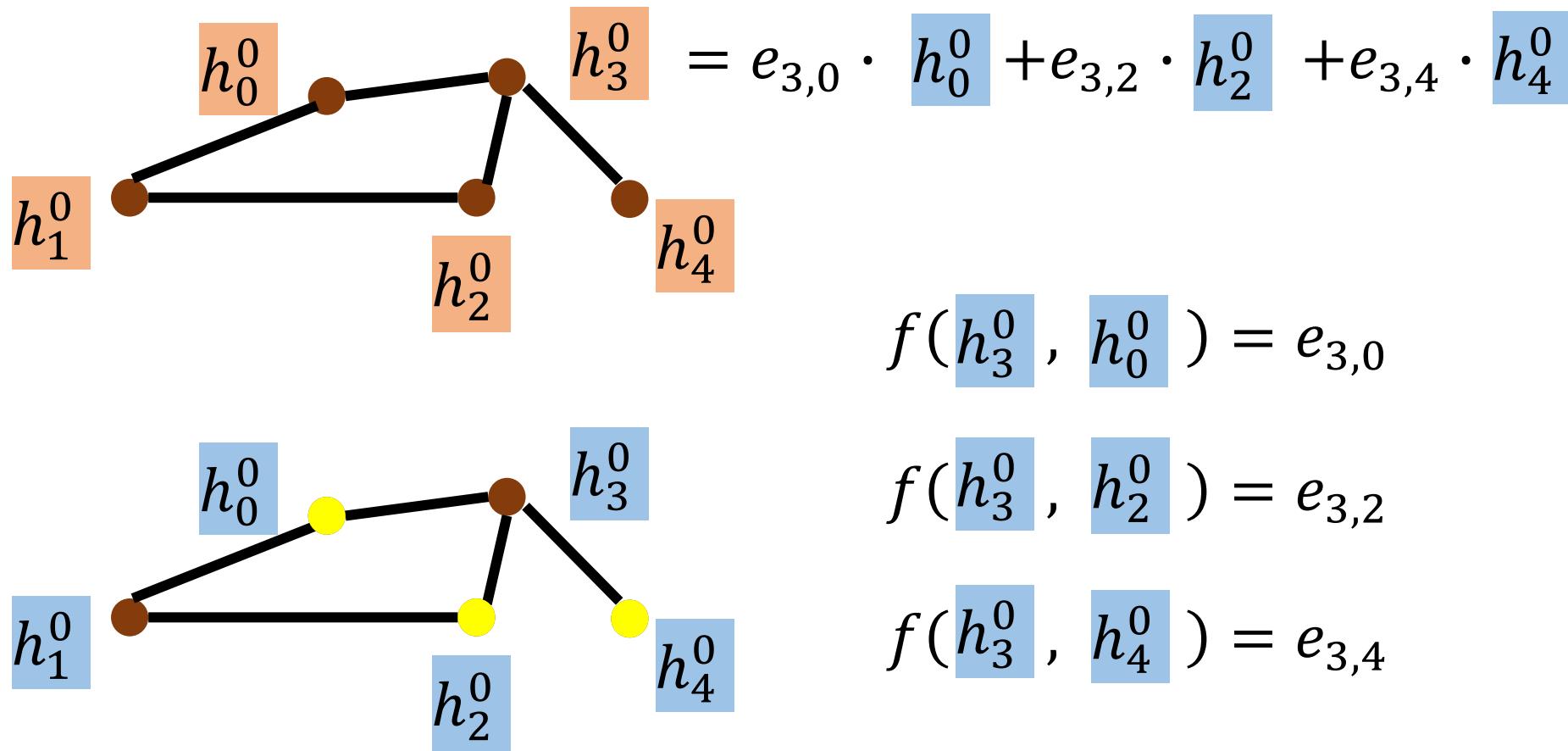
GAT (Graph Attention Networks)

- ✓ Input: node features $\mathbf{h} = \{\vec{h}_1, \vec{h}_2, \dots, \vec{h}_N\}, \vec{h}_i \in \mathbb{R}^F$.
- ✓ Calculate energy: $e_{ij} = a(\mathbf{W}\vec{h}_i, \mathbf{W}\vec{h}_j)$
- ✓ Attention score (over the neighbors)

$$\alpha_{ij} = \frac{\exp \left(\text{LeakyReLU} \left(\vec{a}^T [\mathbf{W}\vec{h}_i \| \mathbf{W}\vec{h}_j] \right) \right)}{\sum_{k \in \mathcal{N}_i} \exp \left(\text{LeakyReLU} \left(\vec{a}^T [\mathbf{W}\vec{h}_i \| \mathbf{W}\vec{h}_k] \right) \right)}$$

<https://arxiv.org/pdf/1710.10903.pdf>

GAT (Graph Attention Networks)



GAT (Graph Attention Networks)

✓ Experiment

Transductive

Method	Cora	Citeseer	Pubmed
MLP	55.1%	46.5%	71.4%
Chebyshev (Defferrard et al., 2016)	81.2%	69.8%	74.4%
GCN (Kipf & Welling, 2017)	81.5%	70.3%	79.0%
MoNet (Monti et al., 2016)	$81.7 \pm 0.5\%$	—	$78.8 \pm 0.3\%$
GCN-64*	$81.4 \pm 0.5\%$	$70.9 \pm 0.5\%$	79.0 ± 0.3%
GAT (ours)	$83.0 \pm 0.7\%$	$72.5 \pm 0.7\%$	$79.0 \pm 0.3\%$

Inductive

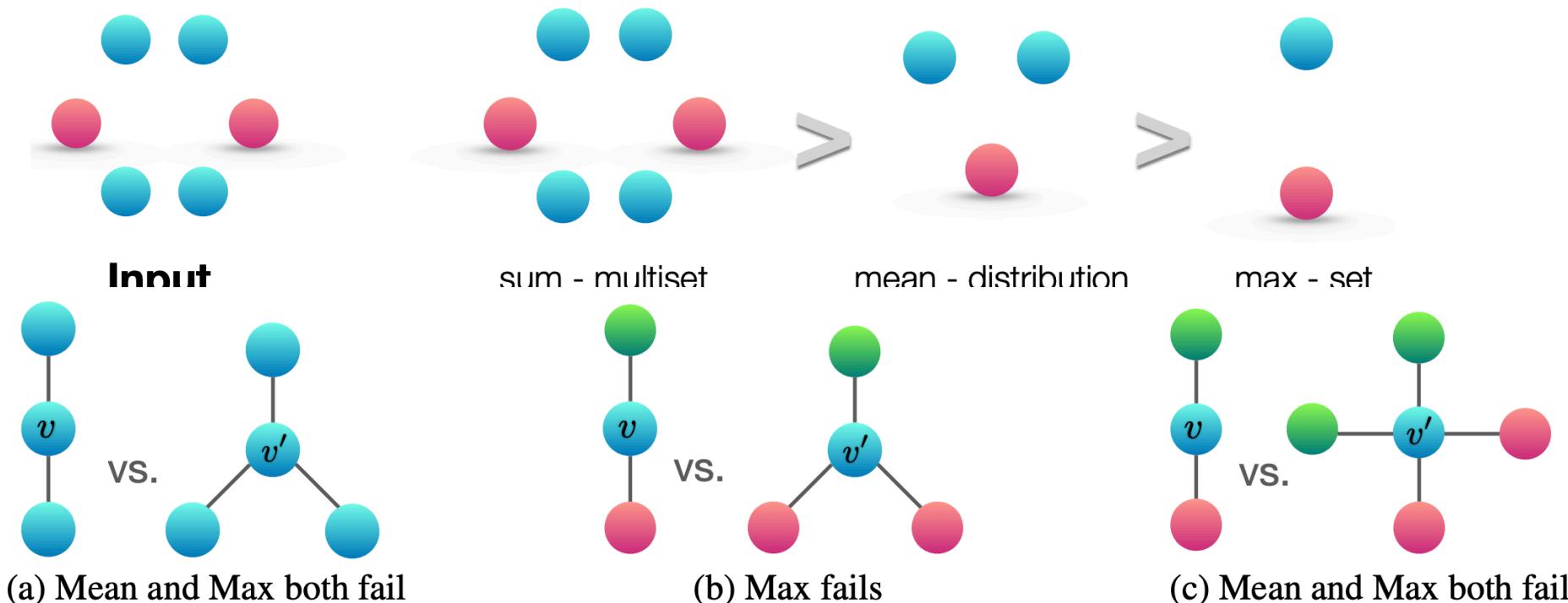
Method	PPI
Random	0.396
MLP	0.422
GraphSAGE*	0.768
Const-GAT (ours)	0.934 ± 0.006
GAT (ours)	0.973 ± 0.002

GIN (Graph Isomorphism Network)

- ✓ A GNN can be at most as powerful as WL isomorphic test
- ✓ Theoretical proofs were provided

GIN (Graph Isomorphism Network)

- ✓ $h_v^{(k)} = \text{MLP}^{(k)} \left(\left(1 + \epsilon^{(k)} \right) \cdot h_v^{(k-1)} + \sum_{u \in \mathcal{N}(v)} h_u^{(k-1)} \right)$
- ✓ Sum instead of mean or max
- ✓ MLP instead of 1-layer



GIN (Graph Isomorphism Network)

✓ Experiment

Datasets	IMDB-B	IMDB-M	RDT-B	RDT-M5K	COLLAB	MUTAG	PROTEINS	PTC	NCI1	
# graphs	1000	1500	2000	5000	5000	188	1113	344	4110	
# classes	2	3	2	5	3	2	2	2	2	
Avg # nodes	19.8	13.0	429.6	508.5	74.5	17.9	39.1	25.5	29.8	
GNN variants	SUM-MLP (GIN-0)	75.1 ± 5.1	52.3 ± 2.8	92.4 ± 2.5	57.5 ± 1.5	80.2 ± 1.9	89.4 ± 5.6	76.2 ± 2.8	64.6 ± 7.0	82.7 ± 1.7
	SUM-MLP (GIN-ϵ)	74.3 ± 5.1	52.1 ± 3.6	92.2 ± 2.3	57.0 ± 1.7	80.1 ± 1.9	89.0 ± 6.0	75.9 ± 3.8	63.7 ± 8.2	82.7 ± 1.6
	SUM-1-LAYER	74.1 ± 5.0	52.2 ± 2.4	90.0 ± 2.7	55.1 ± 1.6	80.6 ± 1.9	90.0 ± 8.8	76.2 ± 2.6	63.1 ± 5.7	82.0 ± 1.5
	MEAN-MLP	73.7 ± 3.7	52.3 ± 3.1	50.0 ± 0.0	20.0 ± 0.0	79.2 ± 2.3	83.5 ± 6.3	75.5 ± 3.4	66.6 ± 6.9	80.9 ± 1.8
	MEAN-1-LAYER (GCN)	74.0 ± 3.4	51.9 ± 3.8	50.0 ± 0.0	20.0 ± 0.0	79.0 ± 1.8	85.6 ± 5.8	76.0 ± 3.2	64.2 ± 4.3	80.2 ± 2.0
	MAX-MLP	73.2 ± 5.8	51.1 ± 3.6	–	–	–	84.0 ± 6.1	76.0 ± 3.2	64.6 ± 10.2	77.8 ± 1.3
	MAX-1-LAYER (GraphSAGE)	72.3 ± 5.3	50.9 ± 2.2	–	–	–	85.1 ± 7.6	75.9 ± 3.2	63.9 ± 7.7	77.7 ± 1.5

Outline

- ✓ Introduction
- ✓ Roadmap
- ✓ Tasks, Dataset, and Benchmark
- ✓ Spatial-based GNN
- ✓ **Graph Signal Processing and Spectral-based GNN**
- ✓ Graph Generation
- ✓ GNN for NLP
- ✓ Online Resources

Review: Convolution

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image with
3 x 3 kernel

Layer i

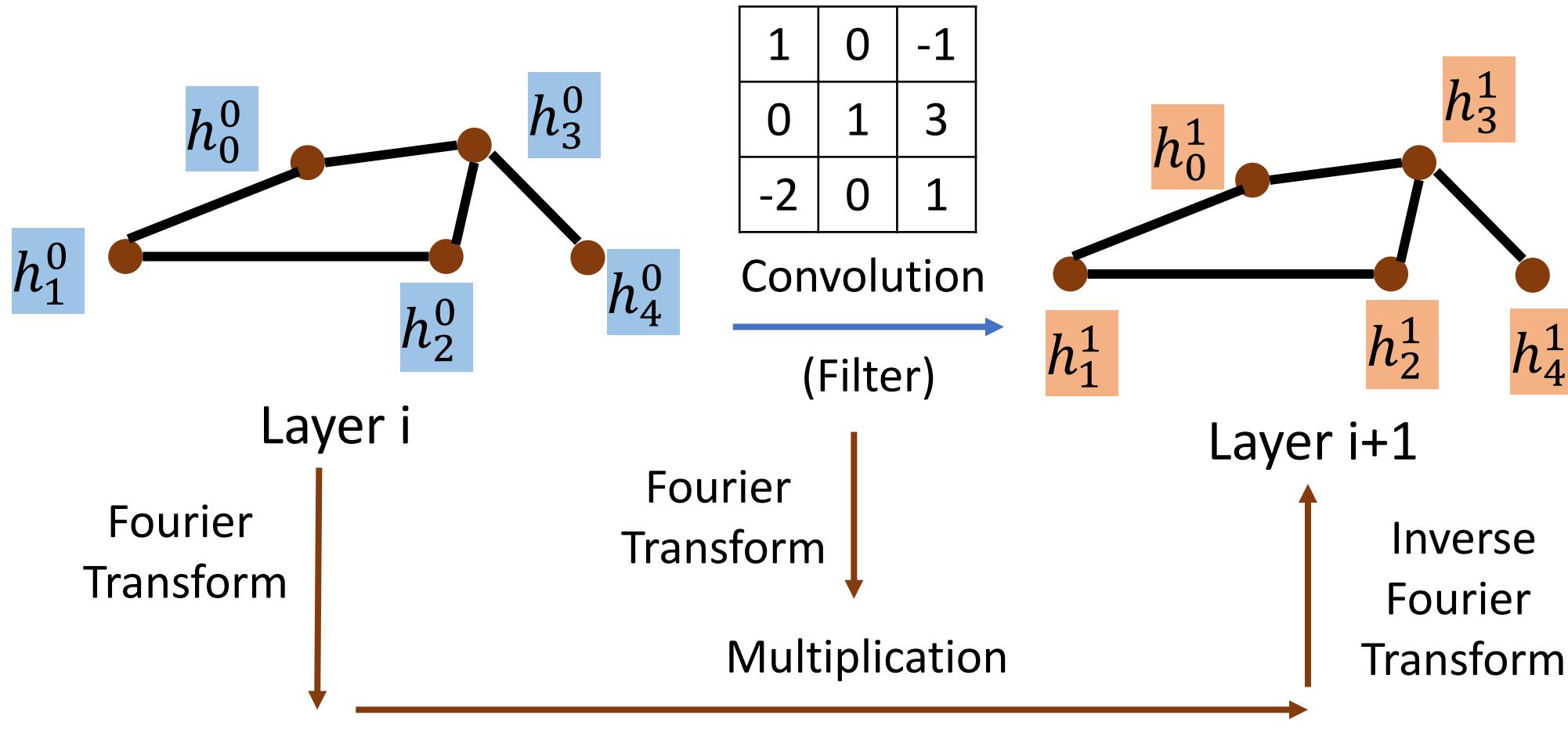
1	0	-1
0	1	3
-2	0	1

Filter

	5	1			

Layer i+1

Spectral-Based Convolution



Warning
of
~~=Math(?)~~
Signal And System

Some of the following slides are from
Signal and System lectured by Prof. Lin Shan, Lee

N-dim Vector Space (P.31 of 1.0)

$$\vec{A} = \sum_{k=1}^N a_k \hat{v}_k \quad (\text{合成})$$

$$a_j = \vec{A} \cdot \hat{v}_j \quad (\text{分析})$$

$$\hat{v}_i \cdot \hat{v}_j = \delta_{ij}$$

Fourier Series Representation

- Fourier Series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{\infty} a_k \phi_k(t)$$

$a_j \phi_j(t)$: j-th harmonic components

$-x(t)$ real

$$a_k^* = a_{-k}$$

$$x(t) = a_0 + 2 \sum_{k=1}^{\infty} A_k \cos(k\omega_0 t + \theta_k), a_k = A_k e^{j\theta_k}$$

$$= a_0 + 2 \sum_{k=1}^{\infty} [B_k \cos k\omega_0 t - C_k \sin k\omega_0 t], a_k = B_k + jC_k$$

Determination of a_k

$$\vec{A} \cdot \hat{v}_n = (\sum_k a_k \hat{v}_k) \cdot \hat{v}_n$$

$$\hat{v}_k \cdot \hat{v}_n = \begin{cases} T, k = n & \text{Not unit vector} \\ 0, k \neq n & \text{orthogonal} \end{cases}$$

$$\vec{A} \cdot \hat{v}_n = T a_n$$

$$a_n = \frac{1}{T} (\vec{A} \cdot \hat{v}_n) \quad (\text{分析})$$

Signal Representation in Two Domains

Time Domain Basis

$$\vec{A} = \sum_i a_i \vec{v}_i$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$= \sum_k (\cdots) b_k \vec{u}_k$$

Frequency Domain Basis

$$\vec{A} = \sum_k b_k \vec{u}_k$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$

$$= \sum_i (\cdots) a_i \vec{v}_i$$

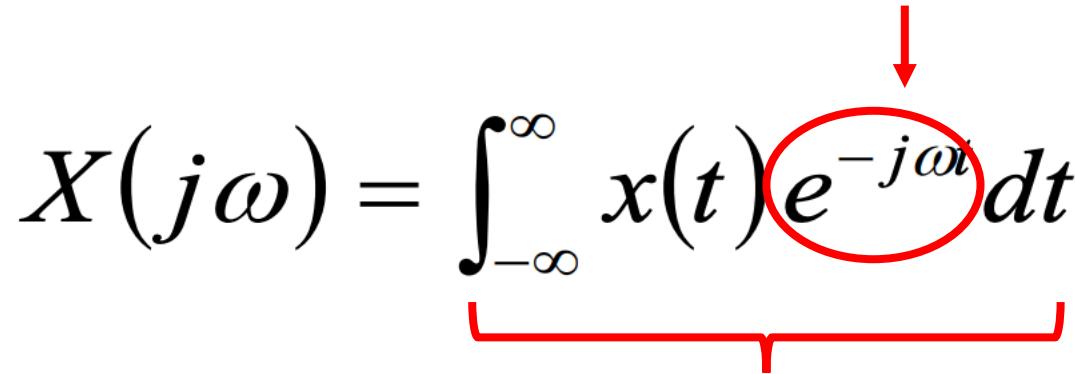
Fourier transform

Basis (Eigenfuntion)

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

: spectrum, frequency domain
Fourier Transform

Inner-Product (分析)



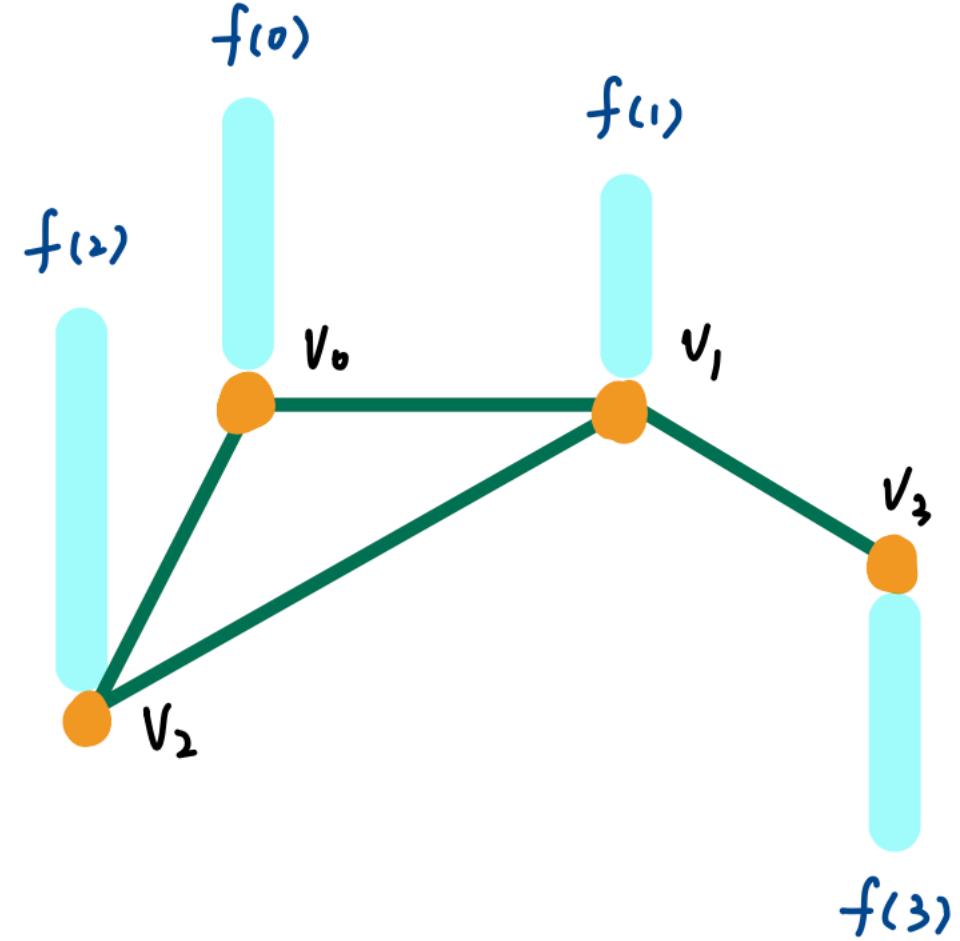
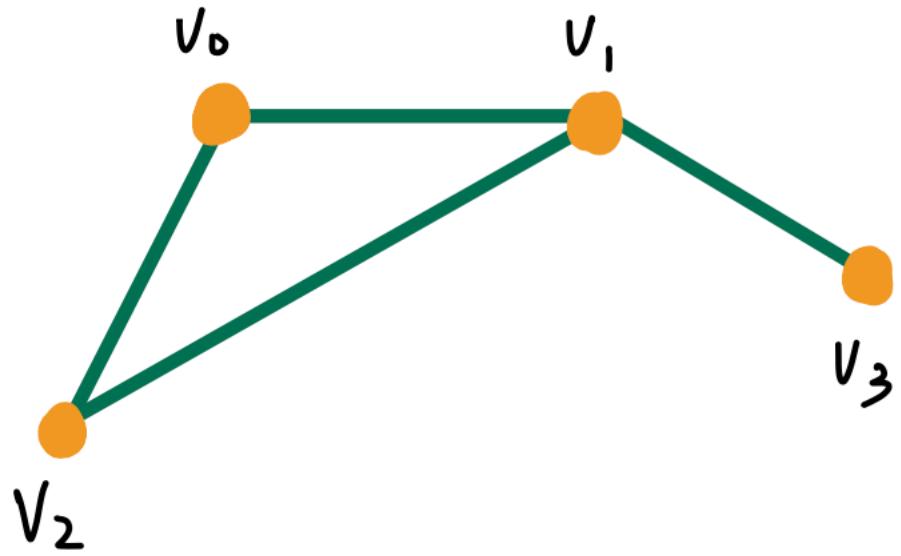
Spectral Graph Theory

- ✓ Graph: $G = (V, E)$, $N = |V|$
- ✓ $A \in \mathbb{R}^{N \times N}$, adjacency matrix (weight matrix).
$$A_{i,j} = 0 \text{ if } e_{i,j} \notin E, \text{ else } A_{i,j} = w(i,j)$$
- ✓ We only consider undirected graph
- ✓ $D \in \mathbb{R}^{N \times N}$, degree matrix

$$D_{i,j} = \begin{cases} d(i) & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases} \quad (\text{Sum of row } i \text{ in } A)$$

- ✓ $f: V \rightarrow \mathbb{R}^N$, signal on graph (vertices). $f(i)$ denotes the signal on vertex i

Spectral Graph Theory



Spectral Graph Theory

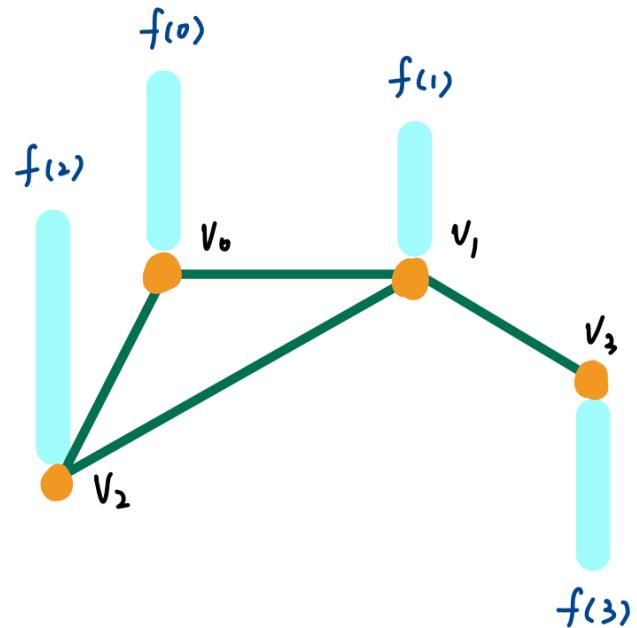
- ✓ Graph Laplacian $L = D - A$, $L \geq 0$ (Positive semidefinite)
- ✓ L is symmetric (for undirected graph)
- ✓ $L = U\Lambda U^T$ (spectral decomposition)
- ✓ $\Lambda = \text{diag}(\lambda_0, \dots, \lambda_{N-1}) \in \mathbb{R}^{N \times N}$
- ✓ $U = [u_0, \dots, u_{N-1}] \in \mathbb{R}^{N \times N}$, orthonormal
- ✓ λ_l is the frequency, u_l is the basis corresponding to λ_l

$$L = U \Lambda U^T$$

The diagram illustrates the spectral decomposition of a 4x4 matrix L (represented by a yellow grid) into its components. The matrix U is shown as a 4x4 grid of light blue vertical columns labeled u_0, u_1, u_2, u_3 . The diagonal matrix Λ is represented by four green squares containing the eigenvalues $\lambda_0, \lambda_1, \lambda_2, \lambda_3$. The matrix U^T is shown as a 4x4 grid of light blue horizontal rows labeled u_0, u_1, u_2, u_3 .

Spectral Graph Theory

- ✓ Vertex domain signal



$$D = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$L = \begin{bmatrix} 2 & -1 & -1 & 0 \\ -1 & 3 & -1 & -1 \\ -1 & -1 & 2 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix} \quad \Lambda = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

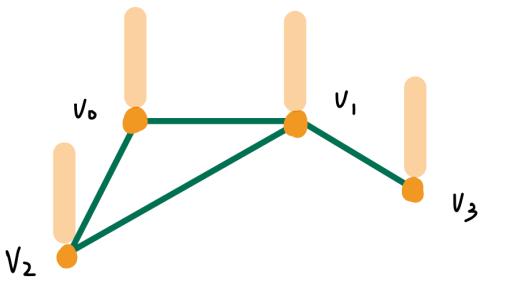
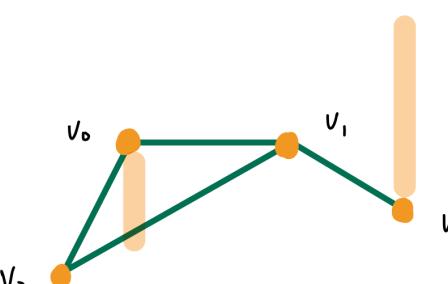
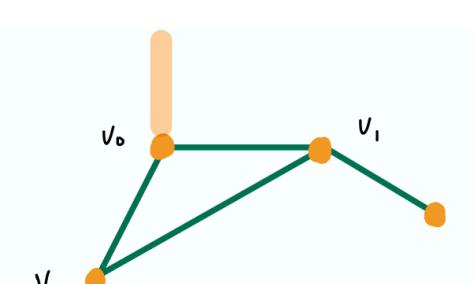
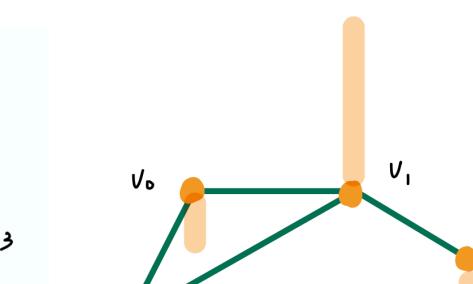
$$f = \begin{bmatrix} 4 \\ 2 \\ 4 \\ -3 \end{bmatrix}$$

$$U = \begin{bmatrix} 0.5 & -0.41 & 0.71 & -0.29 \\ 0.5 & 0 & 0 & 0.87 \\ 0.5 & -0.41 & -0.71 & -0.29 \\ 0.5 & 0.82 & 0 & -0.29 \end{bmatrix}$$

Spectral Graph Theory

Low frequency

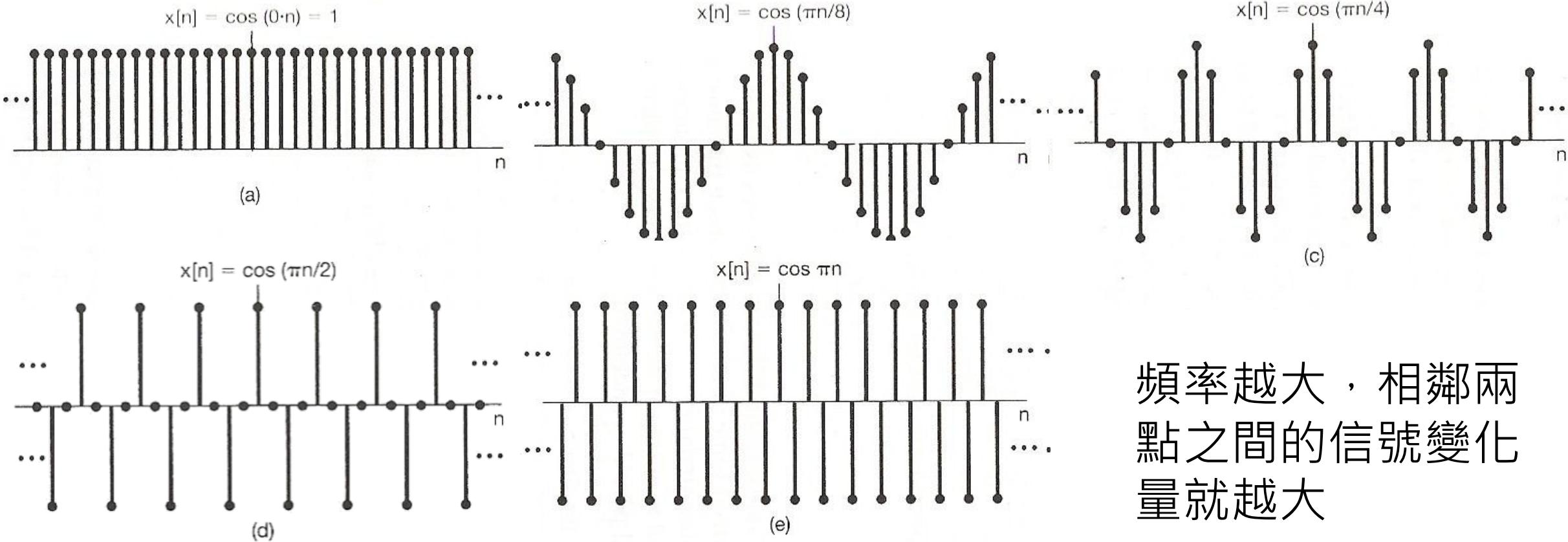
High frequency

λ	0	1	3	4
u	$[0.5 \ 0.5 \ 0.5 \ 0.5]^T$	$[-0.41 \ 0 \ -0.41 \ 0.82]^T$	$[0.71 \ 0 \ -0.71 \ 0]^T$	$[-0.29 \ 0.87 \ -0.29 \ -0.29]^T$
				

(DC component)

Spectral Graph Theory

✓ Discrete time Fourier basis

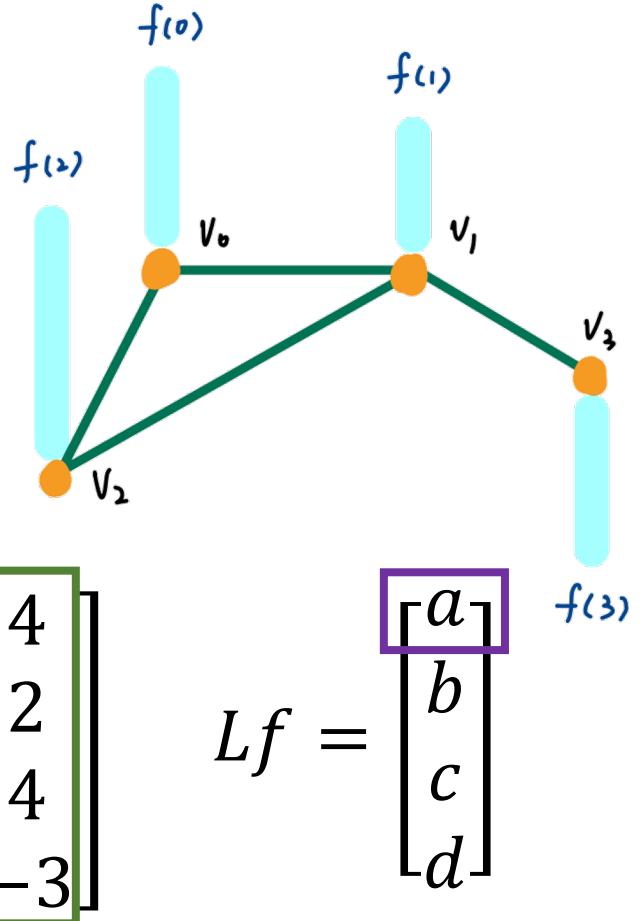


頻率越大，相鄰兩點之間的信號變化量就越大

Spectral Graph Theory

- ✓ Interpreting vertex frequency
 - L as an operator on graph
 - Given a graph signal f , what does Lf mean?
 - $Lf = (D - A)f = Df - Af$

$$D = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \quad f = \begin{bmatrix} 4 \\ 2 \\ 4 \\ -3 \end{bmatrix}$$



➤ Lets focus on the first row of Lf

$$a = [2 0 0 0] \cdot [4 2 4 -3] - [0 1 1 0] \cdot [4 2 4 -3]$$

of neighbors of v_0 Signal on v_0 's neighbors

$$= 2 \times 4 - 2 - 4 = (4 - 2) + (4 - 4) = 2$$

Signal on v_0

Sum of difference between v_0 and its neighbors

Spectral Graph Theory

- ✓ $(Lf)(v_i) = \sum_{v_j \in V} w_{i,j}(f(v_i) - f(v_j))$, where $w_{i,j}$ is the $(i,j)^{th}$ entry of A

$$f^T L f = \sum_{v_i \in V} f(v_i) \sum_{v_j \in V} w_{i,j}(f(v_i) - f(v_j))$$

$$= \sum_{v_i \in V} \sum_{v_j \in V} w_{i,j}(f^2(v_i) - f(v_i)f(v_j))$$

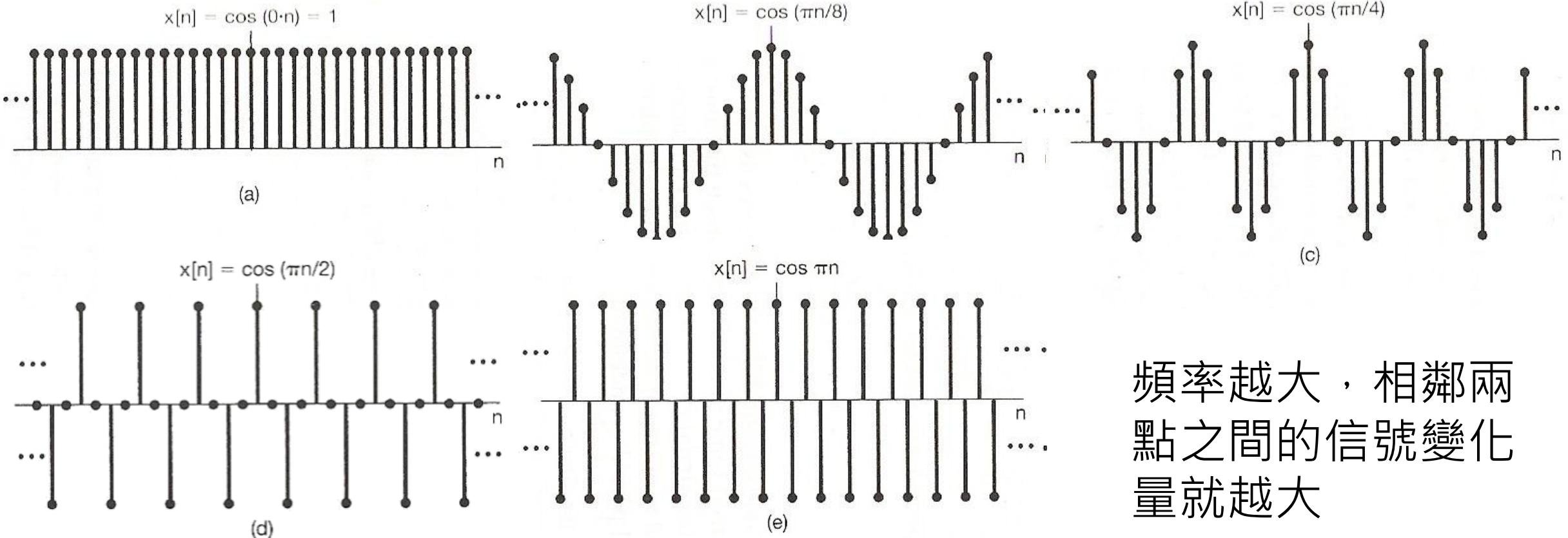
$$= \frac{1}{2} \sum_{v_i \in V} \sum_{v_j \in V} w_{i,j}(f^2(v_i) - f(v_i)f(v_j) + f^2(v_j) - f(v_j)f(v_i))$$

$$= \frac{1}{2} \sum_{v_i \in V} \sum_{v_j \in V} w_{i,j} (f(v_i) - f(v_j))^2$$

“Power” of signal variation
between nodes, i.e.,
smoothness of graph signal

Spectral Graph Theory

- ✓ Discrete time Fourier basis



頻率越大，相鄰兩點之間的信號變化量就越大

- ✓ $f^T L f$ represents “power” of signal variation between nodes

Frequency of f ?

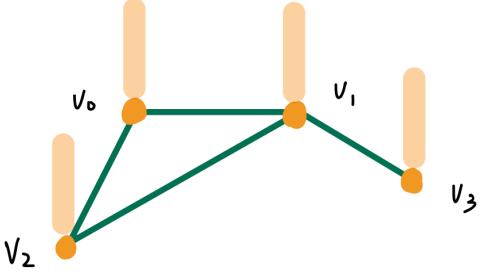
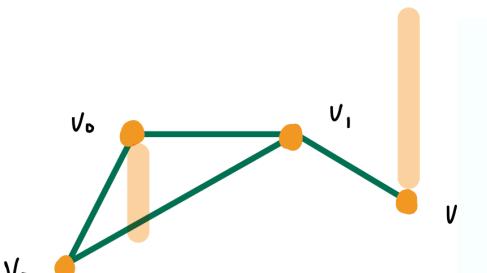
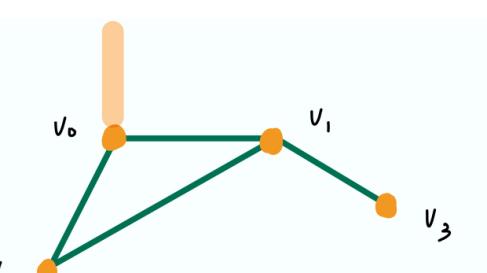
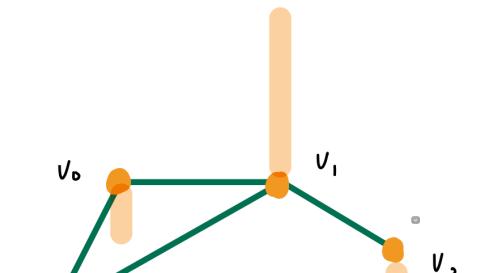
Spectral Graph Theory

- ✓ $u_i^T L u_i = u_i^T \lambda_i u_i = \lambda u_i^T u_i = \lambda_i$
- ✓ The eigenvectors corresponding to small λ belong to the low-pass part of a graph signal

Low frequency



High frequency

λ	0	1	3	4
u	$[0.5 \ 0.5 \ 0.5 \ 0.5]^T$	$[-0.41 \ 0 \ -0.41 \ 0.82]^T$	$[0.71 \ 0 \ -0.71 \ 0]^T$	$[-0.29 \ 0.87 \ -0.29 \ -0.29]^T$
				

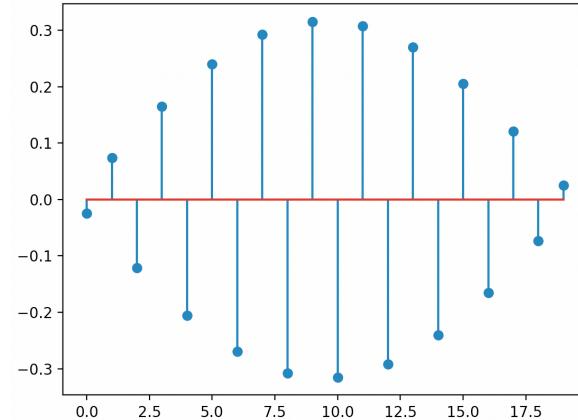
(DC component)

Spectral Graph Theory

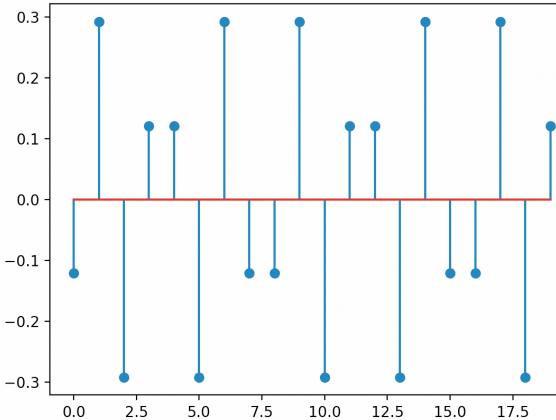


- ✓ A special example: a line graph with 20 nodes

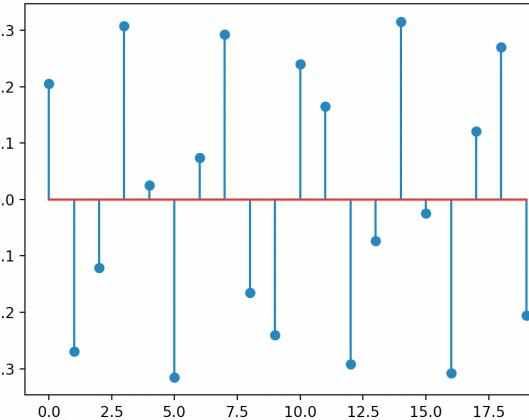
$$\lambda = 3.97$$



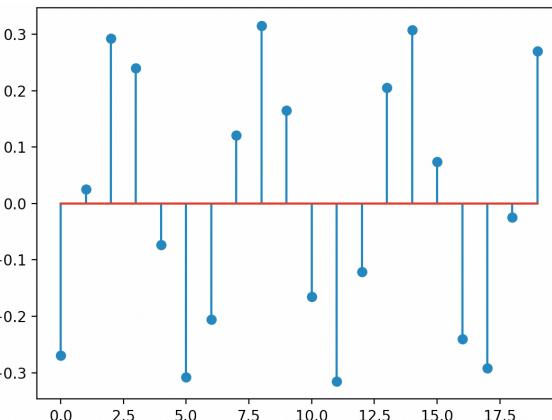
$$\lambda = 3.41$$



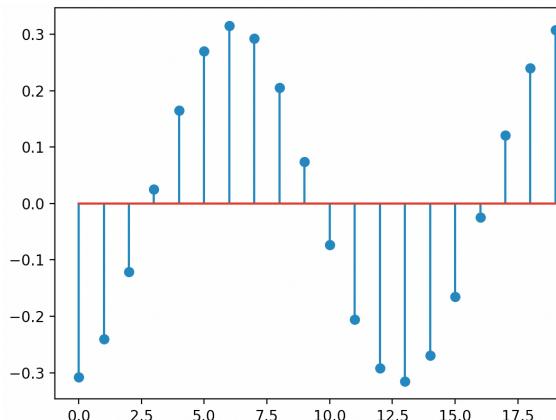
$$\lambda = 2.31$$



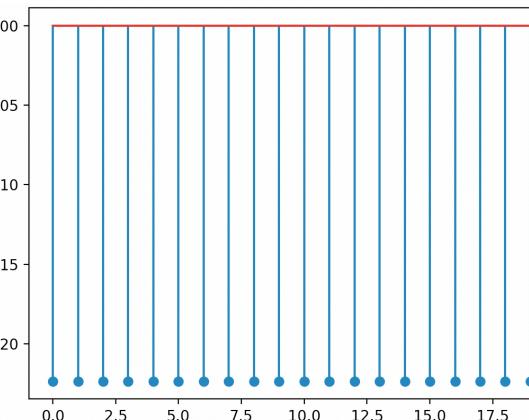
$$\lambda = 1.10$$



$$\lambda = 0.22$$



$$\lambda = 0$$

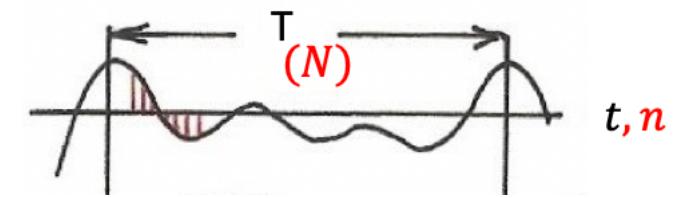
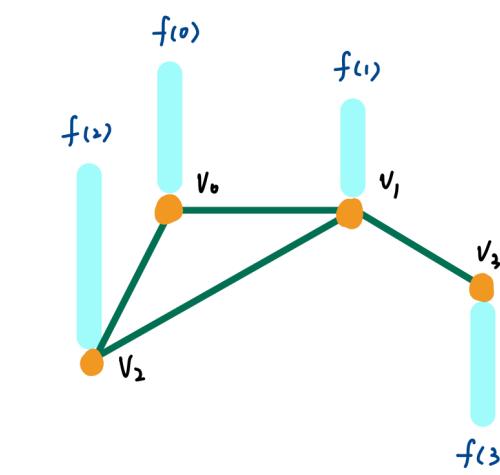
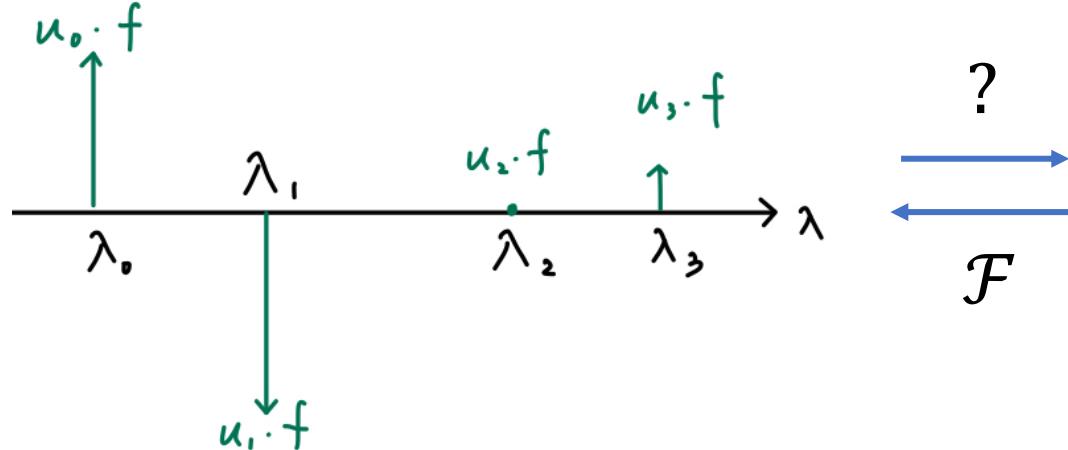


Spectral Graph Theory

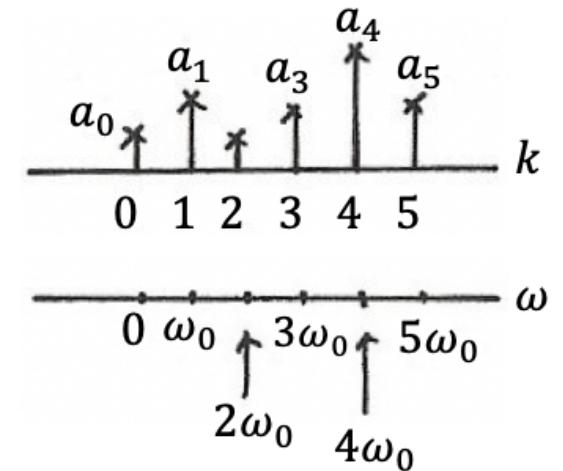
✓ Graph Fourier Transform of signal x : $\hat{x} = U^T x$

$$\begin{array}{l} \text{分析} \\ \text{分析} \\ \text{分析} \\ \text{分析} \end{array} \begin{matrix} u_0 \cdot x \\ u_1 \cdot x \\ u_2 \cdot x \\ u_3 \cdot x \end{matrix} = \begin{matrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{matrix} \quad \hat{x} = U^T x \quad \text{合成}$$

Spectral domain Vertex domain

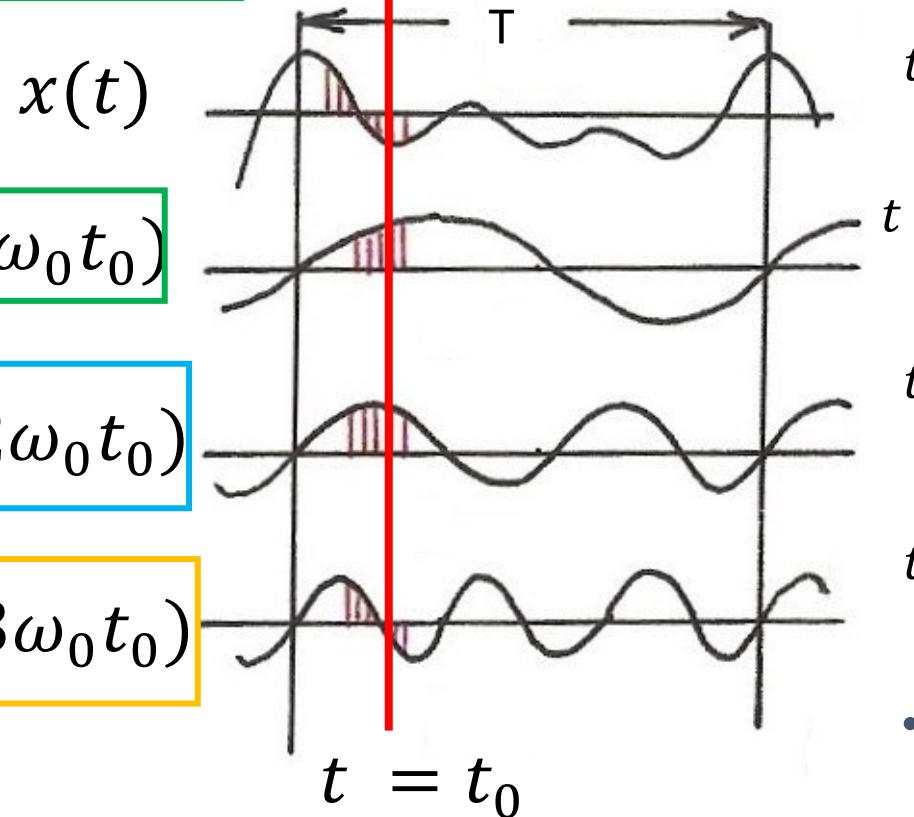


$$\uparrow \downarrow \mathcal{F}$$



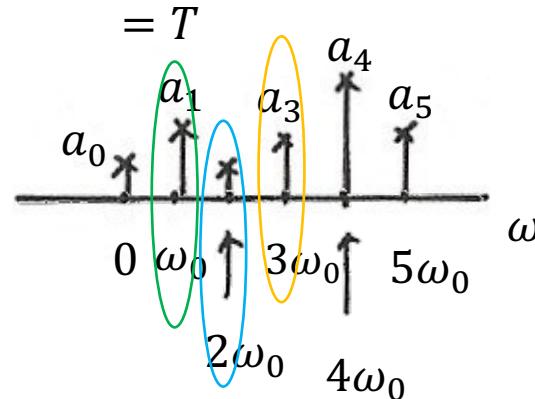
Harmonically Related Exponentials for Periodic Signals

$$a_1 \cos(\omega_0 t_0) + a_2 \cos(2\omega_0 t_0) + a_3 \cos(3\omega_0 t_0) + \dots$$



$V = \{x(t) | x(t) \text{ periodic, fundamental period}$

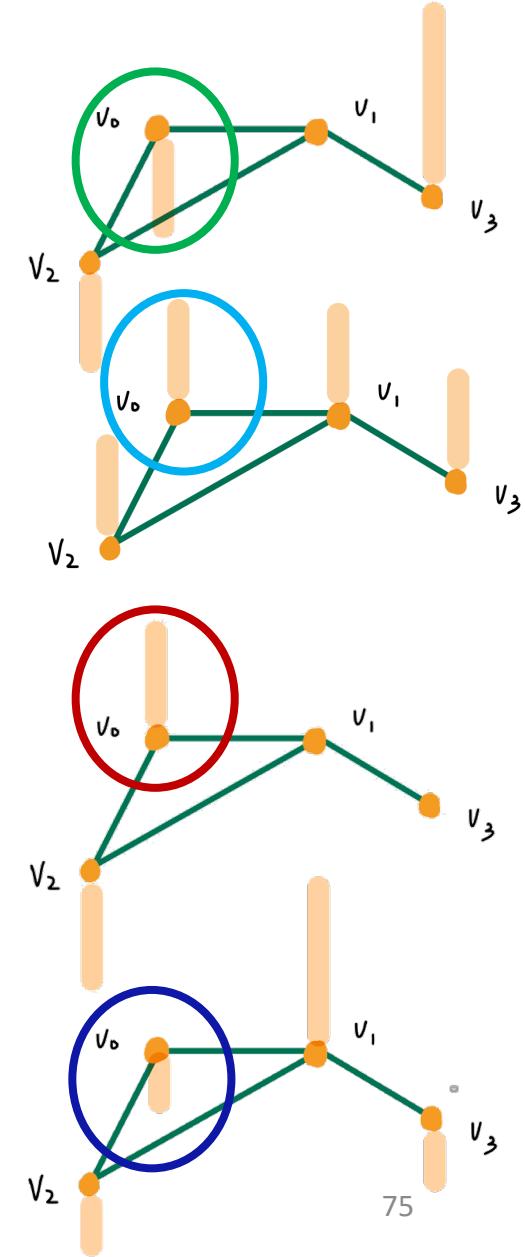
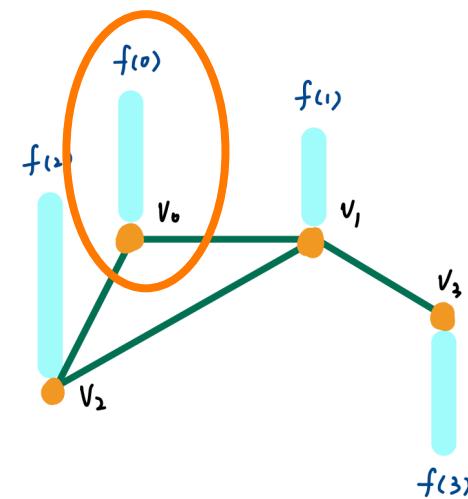
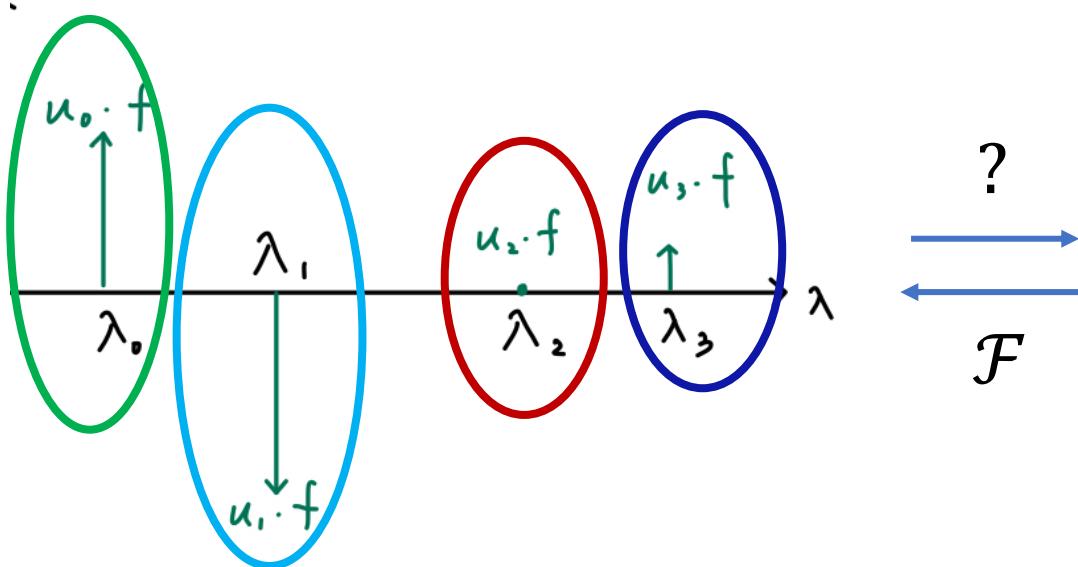
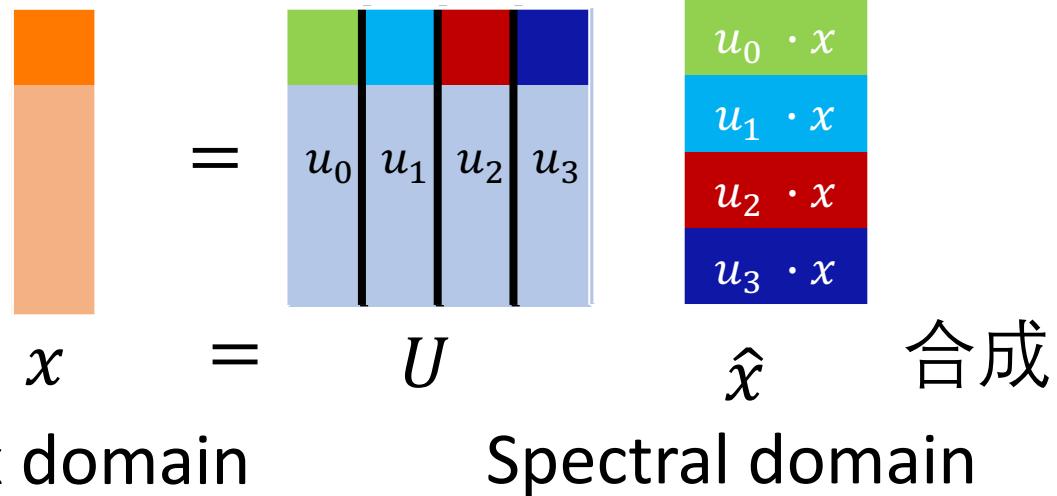
$$\omega_0 = \frac{2\pi}{T}$$



- All with period T : integer multiples of ω_0
- Discrete in frequency domain

Spectral Graph Theory

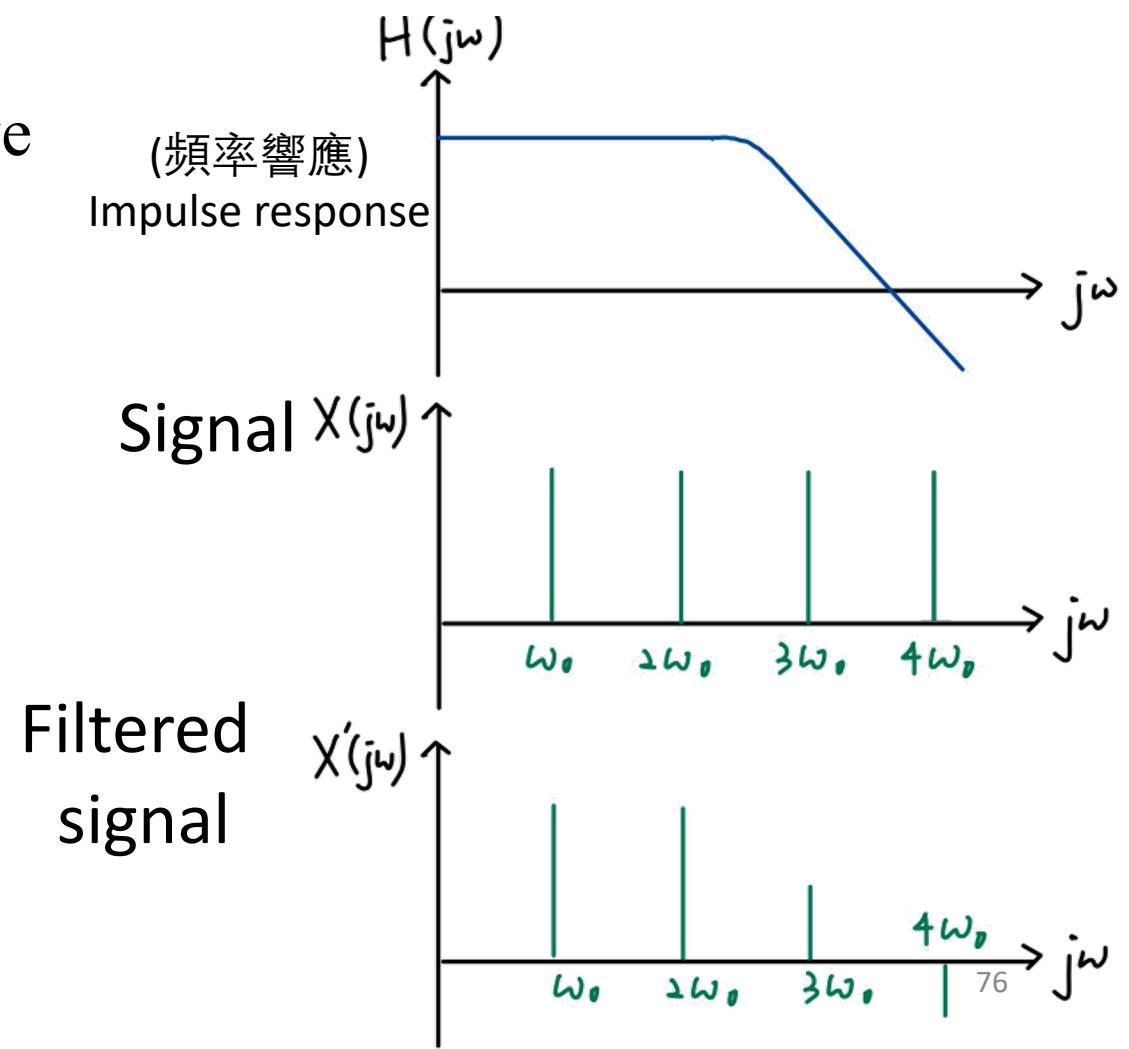
- ✓ Inverse Graph Fourier Transform of signal \hat{x} : $x = U\hat{x}$



Filtering

modifying the amplitude/ phase of the different frequency components in a signal, including eliminating some frequency components entirely

- frequency shaping, frequency selective



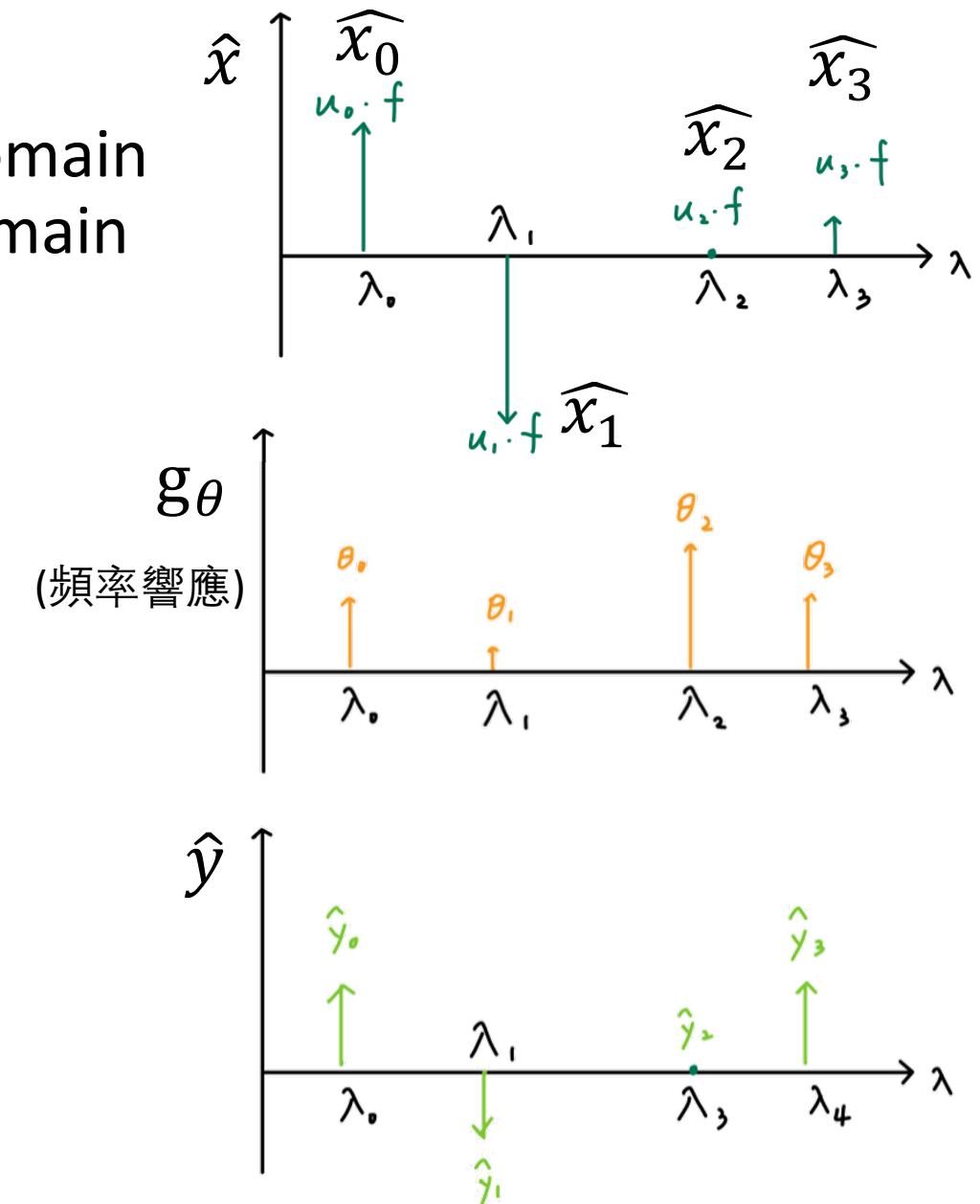
Spectral Graph Theory

- ✓ Filtering: Convolution in time domain is multiplication in frequency domain
- ✓ $\hat{y} = g_\theta(\Lambda) \hat{x}$

$$\begin{matrix} \widehat{y}_0 \\ \widehat{y}_1 \\ \widehat{y}_2 \\ \widehat{y}_3 \end{matrix} = \begin{matrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{matrix} \begin{matrix} \widehat{x}_0 \\ \widehat{x}_1 \\ \widehat{x}_2 \\ \widehat{x}_3 \end{matrix}$$

$$\hat{y} = g_\theta(\Lambda) \hat{x}$$

$$g_\theta(\lambda_i) = \theta_i$$



Spectral Graph Theory

$$\begin{matrix} \widehat{y_0} \\ \widehat{y_1} \\ \widehat{y_2} \\ \widehat{y_3} \end{matrix} = \begin{matrix} \theta_0 \\ & \theta_1 \\ & & \theta_2 \\ & & & \theta_3 \end{matrix} \begin{matrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{matrix} x$$
$$\hat{y} = g_\theta(\Lambda) U^T$$

$$\begin{matrix} u_0 & | & u_1 & | & u_2 & | & u_3 \end{matrix} \begin{matrix} \widehat{y_0} \\ \widehat{y_1} \\ \widehat{y_2} \\ \widehat{y_3} \end{matrix} = \begin{matrix} u_0 & | & u_1 & | & u_2 & | & u_3 \end{matrix} \begin{matrix} \theta_0 \\ & \theta_1 \\ & & \theta_2 \\ & & & \theta_3 \end{matrix} \begin{matrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{matrix} x$$
$$U \hat{y} = U g_\theta(\Lambda) U^T x$$

Inverse Fourier Transform



Spectral Graph Theory

$$y = U \begin{pmatrix} \widehat{y}_0 \\ \widehat{y}_1 \\ \widehat{y}_2 \\ \widehat{y}_3 \end{pmatrix} = U \begin{pmatrix} u_0 & u_1 & u_2 & u_3 \end{pmatrix} \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} U^T x$$

$$\widehat{y} = g_\theta(U \Lambda U^T) x$$

$$\widehat{y} = g_\theta(L) x$$

$$y = g_\theta(L) x$$

Parameters to be learnt

$g_\theta(\cdot)$ can be any function. For example,

$$g_\theta(L) = \log(I + L) = L - \frac{L^2}{2} + \frac{L^3}{3} \dots, \lambda_{max} < 1$$

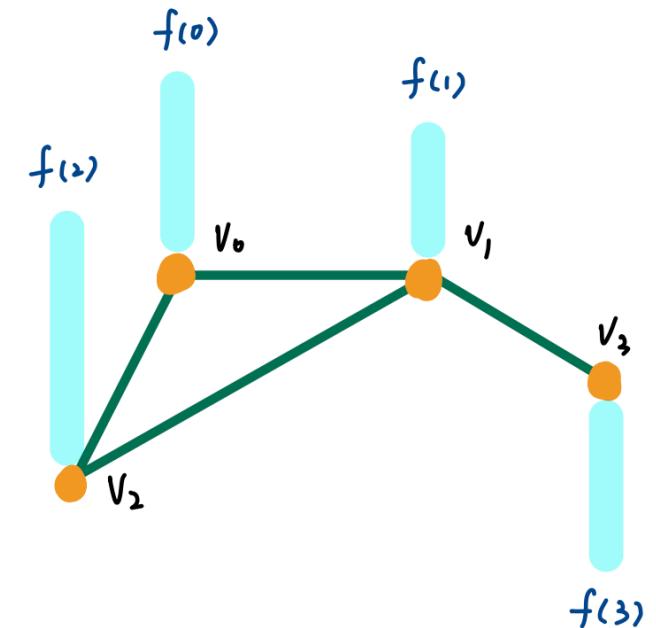
Problem 1: Learning complexity is $O(N)!!$

Spectral Graph Theory

- ✓ How about $g_\theta(L) = \cos(L) = I - \frac{L^2}{2!} + \frac{L^4}{4!} \dots$
 $y = g_\theta(L)x$
- ✓ What does this mean?
 If $g_\theta(L) = L^2$, then $y = Lx^2$

$$\begin{matrix} 1 \\ 4 \\ 1 \\ -6 \end{matrix} = \begin{matrix} 6 & -4 & -3 & 1 \\ -4 & 12 & -4 & -4 \\ -3 & -4 & 6 & 1 \\ 1 & -4 & 1 & 2 \end{matrix} \begin{matrix} 4 \\ 2 \\ 4 \\ -3 \end{matrix}$$

$$y = L^2 x$$



Lemma 3 Let G be a weighted graph, and \mathcal{L} the graph Laplacian of G . Fix an integer $s > 0$, and pick vertices m and n . Then $(\mathcal{L}^s)_{m,n} = 0$ whenever $d_G(m, n) > s$.

Spectral Graph Theory

- ✓ If we select $g_\theta(L) = \cos(L) = I - \frac{L^2}{2!} + \frac{L^4}{4!} \dots$
- ✓ If a connected graph has N nodes, then L^N will make all nodes be able to share their signals with each other

Problems 2: Not localize!!!

Review CNN

- ✓ Selecting different kernel size mean different receptive field
- ✓ We only consider local information within the receptive field

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image with
3 x 3 kernel

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image with
5 x 5 kernel

ChebNet

✓ Solution to Problem 1 and 2:

➤ Use polynomial to parametrize $g_\theta(L)$

$$g_\theta(L) = \sum_{k=0}^K \theta_k L^k$$

Now it is K-localized

$$g_\theta(\Lambda) = \sum_{k=0}^K \theta_k \Lambda^k$$

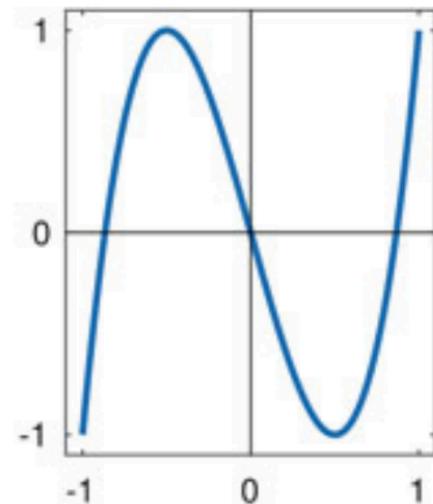
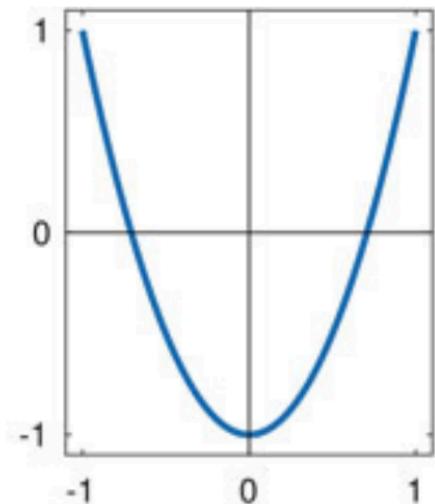
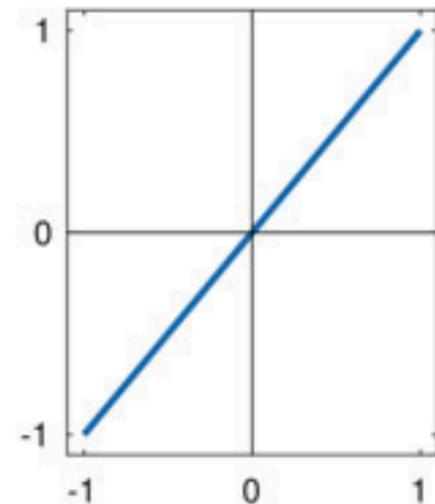
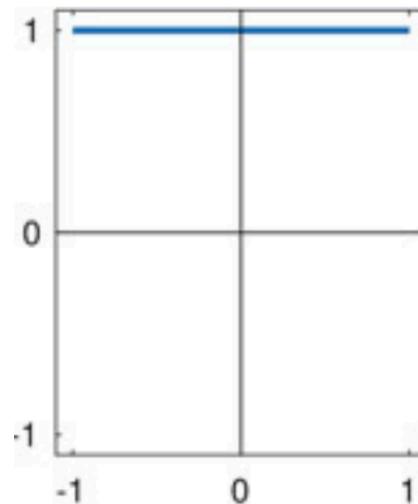
Parameters to be learnt: $O(K)$

Problem 3:
Time complexity: $O(N^2)$

$$y = U g_\theta(\Lambda) U^T x = U \left(\sum_{k=0}^K \theta_k \Lambda^k \right) U^T x$$

ChebNet

- ✓ Solution to Problem 3:
 - Use a polynomial function that can be computed recursively from L
- ✓ Chebyshev polynomial
 - $T_0(x) = 1, T_1(x) = x, T_k(x) = 2xT_{k-1}(x) - T_{k-2}(x), x \in [-1, 1]$



ChebNet

$$T_0(\tilde{\Lambda}) = \mathbf{I}, T_1(\tilde{\Lambda}) = \tilde{\Lambda}, T_k(\tilde{\Lambda}) = 2\tilde{\Lambda}T_{k-1}(\tilde{\Lambda}) - T_{k-2}(\tilde{\Lambda})$$

where $\tilde{\Lambda} = \frac{2\Lambda}{\lambda_{max}} - \mathbf{I}$, $\tilde{\lambda} \in [-1, 1]$

$$g_\theta(\Lambda) = \sum_{k=0}^K \theta_k \Lambda^k \longrightarrow g_{\theta'}(\tilde{\Lambda}) = \sum_{k=0}^K \theta'_k T_k(\tilde{\Lambda})$$

$$y = g_{\theta'}(\tilde{L})x = \sum_{k=0}^K \theta'_k T_k(\tilde{L})x$$

ChebNet

$$g_{\theta}(\Lambda) = \sum_{k=0}^K \theta_k \Lambda^k \longrightarrow g_{\theta'}(\tilde{\Lambda}) = \sum_{k=0}^K \theta'_k T_k(\tilde{\Lambda})$$

[例題 4] (綜合除法的應用)

設多項式 $f(x) = 3x^4 - 7x^3 - 2x^2 + 2x + 18$

$$= a(x-2)^4 + b(x-2)^3 + c(x-2)^2 + d(x-2) + e ,$$

其中 a, b, c, d, e 皆為實數。

- (1) 求 a, b, c, d, e 之值 (2) 求 $f(1.99)$ 的近似值到小數第三位。

~56~

ChebNet

$$\begin{aligned}y = g_{\theta'}(L)x &= \sum_{k=0}^K \theta'_k T_k(\tilde{L})x \\&= \theta'_0 \textcolor{red}{T}_0(\tilde{L})x + \theta'_1 \textcolor{red}{T}_1(\tilde{L})x + \theta'_2 \textcolor{red}{T}_2(\tilde{L})x + \cdots + \theta'_K \textcolor{red}{T}_K(\tilde{L})x\end{aligned}$$

$$T_0(\tilde{L}) = I, T_1(\tilde{L}) = \tilde{L}, T_k(\tilde{L}) = 2\tilde{L}T_{k-1}(\tilde{L}) - T_{k-2}(\tilde{L})$$

$$T_0(\tilde{L})x = x, T_1(\tilde{L})x = \tilde{L}x, T_k(\tilde{L})x = 2\tilde{L}T_{k-1}(\tilde{L})x - T_{k-2}(\tilde{L})x$$

Define $T_k(\tilde{L})x = \bar{x}_k$

$$\bar{x}_0 = x, \bar{x}_1 = \tilde{L}x, \bar{x}_k = 2\tilde{L}\bar{x}_{k-1} - \bar{x}_{k-2}$$

ChebNet

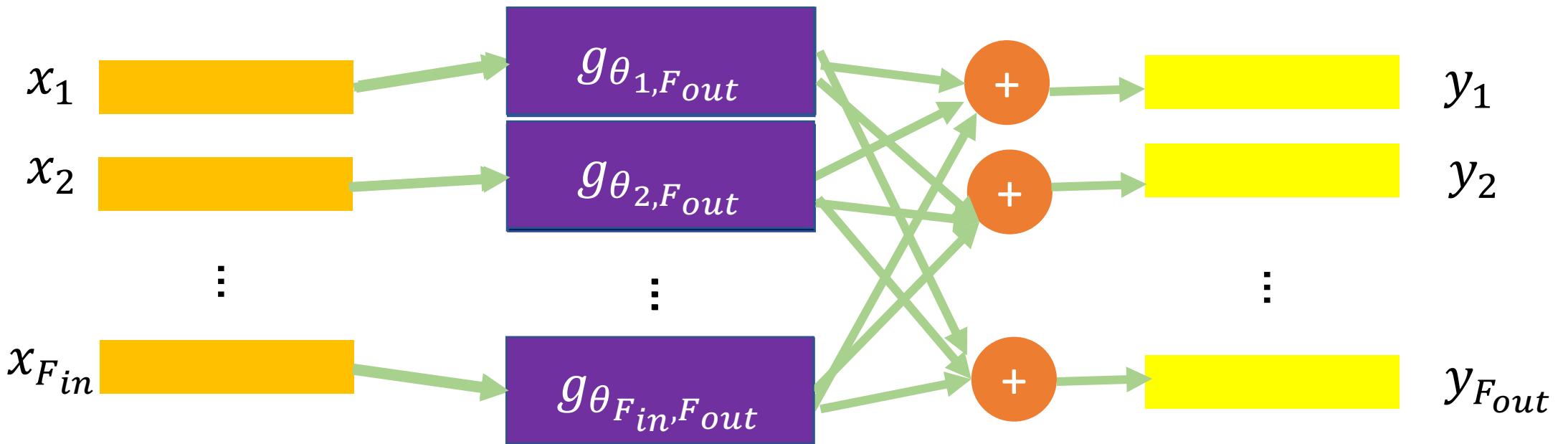
$$y = g_{\theta'}(L)x = \sum_{k=0}^K \theta'_k T_k(\tilde{L})x$$

$$\bar{x}_0 = x, \bar{x}_1 = \tilde{L}x, \bar{x}_k = 2\tilde{L}\bar{x}_{k-1} - \bar{x}_{k-2}$$

$$\begin{aligned} &= \theta'_0 \textcolor{red}{T}_0(\tilde{L})x + \theta'_1 \textcolor{red}{T}_1(\tilde{L})x + \theta'_2 \textcolor{red}{T}_2(\tilde{L})x + \cdots + \theta'_K \textcolor{red}{T}_K(\tilde{L})x \\ &= \theta'_0 \bar{x}_0 + \theta'_1 \bar{x}_1 + \theta'_2 \bar{x}_2 + \cdots + \theta'_K \bar{x}_K \\ &= [\bar{x}_0 \ \bar{x}_1 \ \dots \ \bar{x}_K] [\theta'_0 \ \theta'_1 \ \dots \ \theta'_K] \end{aligned}$$

Calculating $\bar{x}_k = 2\tilde{L}\bar{x}_{k-1} - \bar{x}_{k-2}$ cost $O(E)$
Total complexity: $O(KE)$

ChebNet



GCN

✓ $y = g_{\theta'}(L)x = \sum_{k=0}^K \theta'_k T_k(\tilde{L})x , K = 1$

<https://openreview.net/pdf?id=SJU4ayYgI>

$$\begin{aligned}
 y &= g_{\theta'}(L)x = \theta'_0 x + \theta'_1 \tilde{L}x \\
 &= \theta'_0 x + \theta'_1 \left(\frac{2L}{\lambda_{max}} - I \right) x \quad \because \lambda_{max} \approx 2 \\
 &= \theta'_0 x + \theta'_1 (L - I)x \quad \because L = I - D^{-\frac{1}{2}}AD^{-\frac{1}{2}} \\
 &= \theta'_0 x - \theta'_1 (D^{-\frac{1}{2}}AD^{-\frac{1}{2}})x \quad \because \theta = \theta'_0 = -\theta'_1 \\
 &= \theta (I + D^{-\frac{1}{2}}AD^{-\frac{1}{2}})x
 \end{aligned}$$

renormalization trick: $I_N + D^{-\frac{1}{2}}AD^{-\frac{1}{2}} \rightarrow \tilde{D}^{-\frac{1}{2}}\tilde{A}\tilde{D}^{-\frac{1}{2}}$

$$H^{(l+1)} = \sigma \left(\tilde{D}^{-\frac{1}{2}}\tilde{A}\tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)} \right)$$

GCN

$$H^{(l+1)} = \sigma\left(\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)}\right)$$

Can be rewritten as:

$$h_v = f\left(\frac{1}{|\mathcal{N}(v)|} \sum_{u \in \mathcal{N}(v)} Wx_u + b\right), \quad \forall v \in \mathcal{V}.$$

GCN

- ✓ Experiment: Semi-supervised classification

Dataset	Type	Nodes	Edges	Classes	Features	Label rate
Citeseer	Citation network	3,327	4,732	6	3,703	0.036
Cora	Citation network	2,708	5,429	7	1,433	0.052
Pubmed	Citation network	19,717	44,338	3	500	0.003
NELL	Knowledge graph	65,755	266,144	210	5,414	0.001

- ✓ Node features:
 - Citation network: Bag of Word of the document
 - In the knowledge base, each relation is denoted as a triplet (e_1, r, e_2)

GCN

Method	Citeseer	Cora	Pubmed	NELL
ManiReg [3]	60.1	59.5	70.7	21.8
SemiEmb [28]	59.6	59.0	71.1	26.7
LP [32]	45.3	68.0	63.0	26.5
DeepWalk [22]	43.2	67.2	65.3	58.1
ICA [18]	69.1	75.1	73.9	23.1
Planetoid* [29]	64.7 (26s)	75.7 (13s)	77.2 (25s)	61.9 (185s)
GCN (this paper)	70.3 (7s)	81.5 (4s)	79.0 (38s)	66.0 (48s)
GCN (rand. splits)	67.9 ± 0.5	80.1 ± 0.5	78.9 ± 0.7	58.4 ± 1.7

Comparison between the above GNNs

- ✓ Benchmark tasks

GRAPH NEURAL NETWORKS EXPONENTIALLY LOSE EXPRESSIVE POWER FOR NODE CLASSIFICATION

Kenta Oono^{1, 2}, Taiji Suzuki^{1, 3}

{kenta_oono, taiji}@mist.i.u-tokyo.ac.jp

¹The University of Tokyo

²Preferred Networks, Inc.

³RIKEN Center for Advanced Intelligence Project (AIP)

ICLR'20 spotlight (8, 6, 8)

Application to GCN

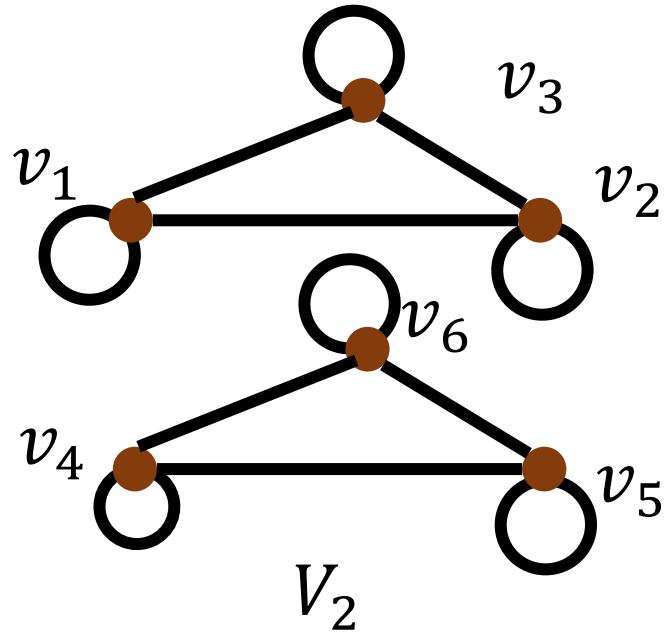
Theorem 2. For any initial value $X^{(0)}$, the output of l -th layer $X^{(l)}$ satisfies $d_{\mathcal{M}}(X^{(l)}) \leq (s\lambda)^l d_{\mathcal{M}}(X^{(0)})$. In particular, $d_{\mathcal{M}}(X^{(l)})$ exponentially converges to 0 when $s\lambda < 1$.

- ✓ 翻譯：如果 $s\lambda < 1$ · X 經過多層的 MLP 之後會落在 subspace \mathcal{M} 裡面

$$X = [\alpha e_1 + \delta e_2 \quad \beta e_1 + \varepsilon e_2 \quad \gamma e_1 + \varphi e_2] \xrightarrow{\text{Feature dim}}$$
$$e_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad e_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$
$$X = \frac{1}{\sqrt{3}} \begin{bmatrix} \alpha & \beta & \gamma \\ \alpha & \beta & \gamma \\ \alpha & \beta & \gamma \\ \delta & \varepsilon & \varphi \\ \delta & \varepsilon & \varphi \\ \delta & \varepsilon & \varphi \end{bmatrix} \in \mathcal{M}$$

↓ Node

Application to GCN



$$X = \frac{1}{\sqrt{3}}$$

α	β	γ
α	β	γ
α	β	γ
δ	ε	φ
δ	ε	φ
δ	ε	φ

On the left, a vertical list of node labels $v_1, v_2, v_3, v_4, v_5, v_6$ is shown. To the right, curly braces group the nodes into two sets: $V_1 = \{v_1, v_2, v_3\}$ and $V_2 = \{v_4, v_5, v_6\}$. The first three rows of the matrix correspond to V_1 , and the last three rows correspond to V_2 . The columns are labeled α, β, γ at the top.

$$s\lambda < 1 \quad \lambda < 1 \quad \text{If } s < 1$$

exponential information loss of GCNs in terms of the layer size

$$\text{If } s \geq 1$$

Information loss may still happen

Discussion

- ✓ In reality, graph is usually not too sparse, so GCN is still applicable
- ✓ Find the sweet-spot to make the singular value of the weight not too small and not too big
- ✓ Remedy for over-smoothing: sample edges while training to make the graph sparser

DROPEdge: Towards Deep Graph Convolutional Networks on Node Classification

Yu Rong¹, Wenbing Huang^{2*}, Tingyang Xu¹, Junzhou Huang¹

¹ Tencent AI Lab

² Beijing National Research Center for Information Science and Technology (BNRist),
State Key Lab on Intelligent Technology and Systems,
Department of Computer Science and Technology, Tsinghua University

ICLR'20 poster (6, 3, 3)

<https://openreview.net/pdf?id=Hkx1qkrKPr>

DropEdge

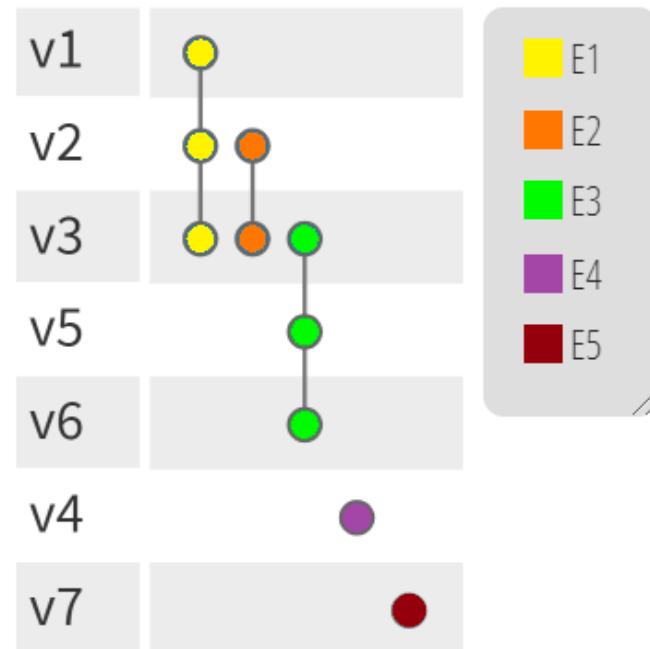
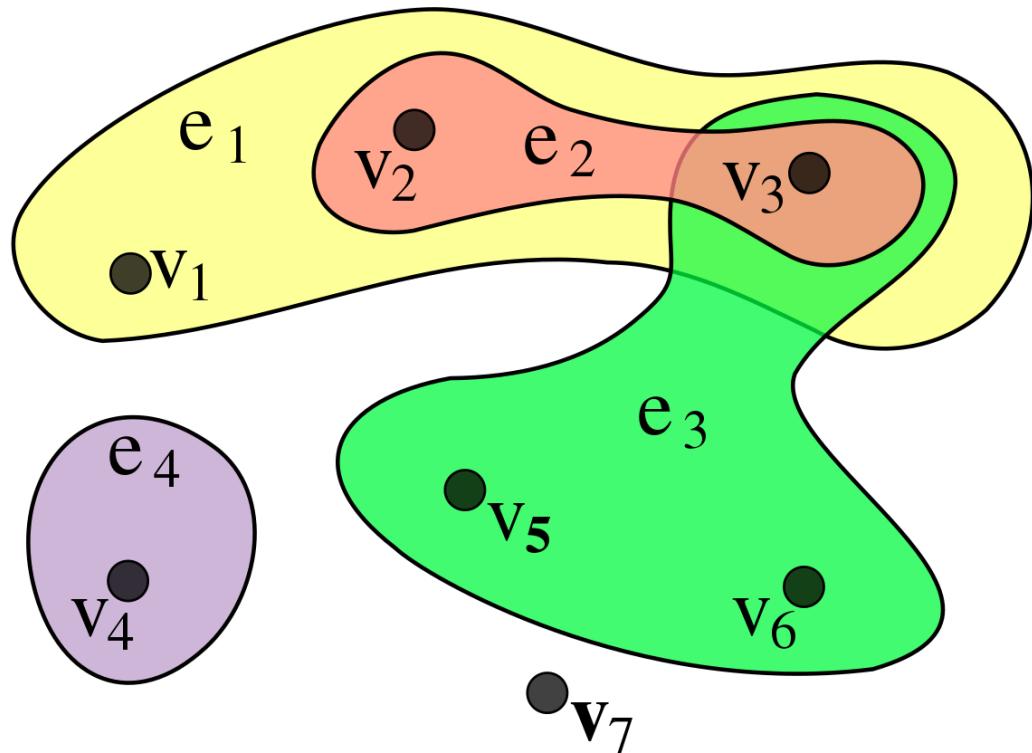
- ✓ Randomly drop the edge of input graph with probability p
 - 每一層都用同一個 drop 過的 adjacency matrix
 - 每一層都用不同的 drop 過的 adjacency matrix
- ✓ 可以避免 over-smoothing 的問題

DropEdge

Dataset	Backbone	2 layers		8 layers		32 layers	
		Original	DropEdge	Original	DropEdge	Original	DropEdge
Cora	GCN	86.10	86.50	78.70	85.80	71.60	74.60
	ResGCN	-	-	85.40	86.90	85.10	86.80
	JKNet	-	-	86.70	87.80	87.10	87.60
	IncepGCN	-	-	86.70	88.20	87.40	87.70
	GraphSAGE	87.80	88.10	84.30	87.10	31.90	32.20
Citeseer	GCN	75.90	78.70	74.60	77.20	59.20	61.40
	ResGCN	-	-	77.80	78.80	74.40	77.90
	JKNet	-	-	79.20	80.20	71.70	80.00
	IncepGCN	-	-	79.60	80.50	72.60	80.30
	GraphSAGE	78.40	80.00	74.10	77.10	37.00	53.60
Pubmed	GCN	90.20	91.20	90.10	90.90	84.60	86.20
	ResGCN	-	-	89.60	90.50	90.20	91.10
	JKNet	-	-	90.60	91.20	89.20	91.30
	IncepGCN	-	-	90.20	91.50	OOM	90.50
	GraphSAGE	90.10	90.70	90.20	91.70	41.30	47.90
Reddit	GCN	96.11	96.13	96.17	96.48	45.55	50.51
	ResGCN	-	-	96.37	96.46	93.93	94.27
	JKNet	-	-	96.82	97.02	OOM	OOM
	IncepGCN	-	-	96.43	96.87	OOM	OOM
	GraphSAGE	96.22	96.28	96.38	96.42	96.43	96.47

HyperGCN

✓ Hypergraph



HyperGCN

- ✓ Hypergraph in real life(?)
- ✓ Co-author network, co-citation network

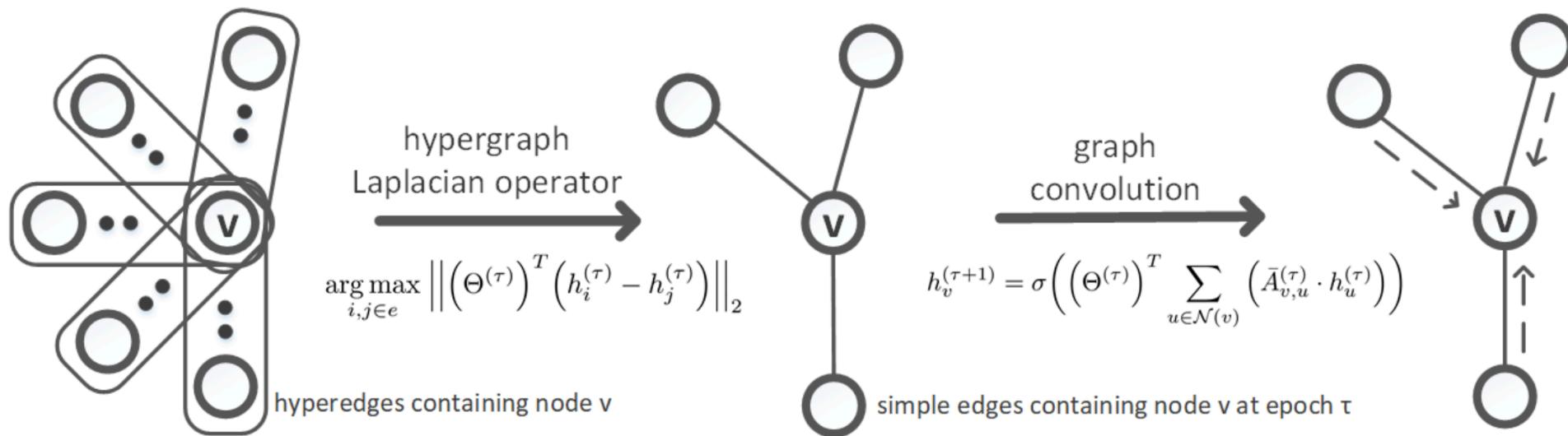


Figure 1: Graph convolution on a hypernode v using HyperGCN.

<https://arxiv.org/pdf/1809.02589.pdf>

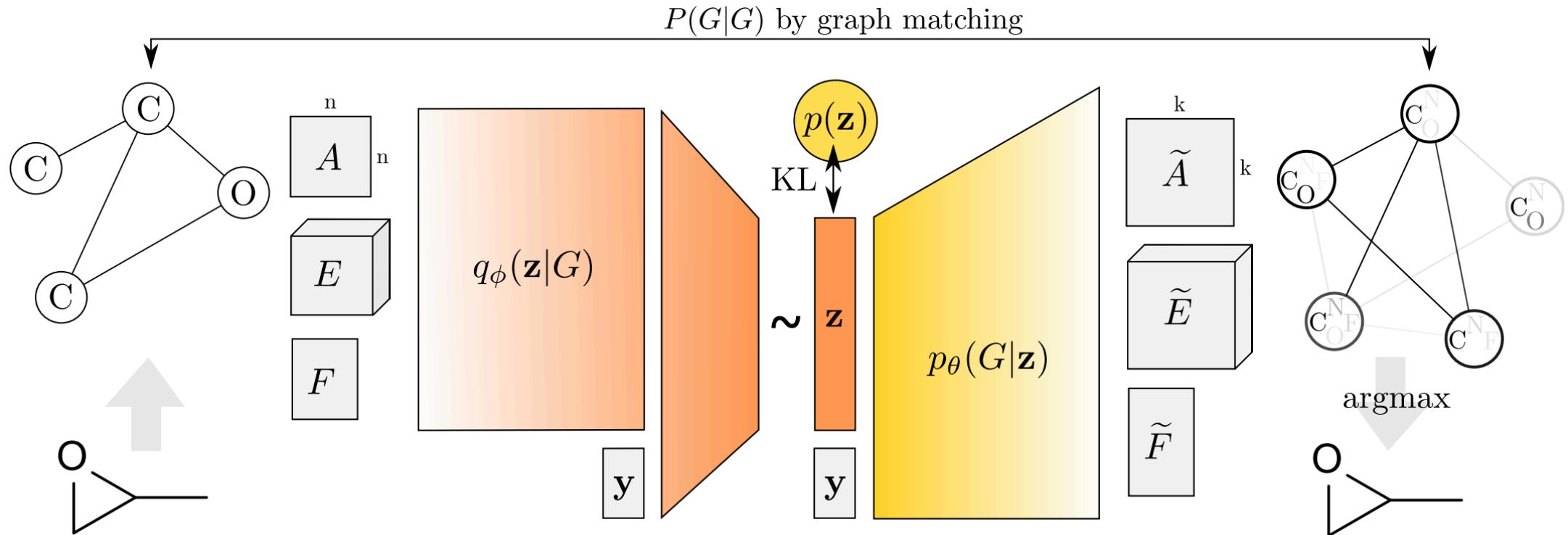
Outline

- ✓ Introduction
- ✓ Roadmap
- ✓ Tasks, Dataset, and Benchmark
- ✓ Spatial-based GNN
- ✓ Graph Signal Processing and Spectral-based GNN
- ✓ **Graph Generation**
- ✓ GNN for NLP
- ✓ Online Resources

Graph Generation

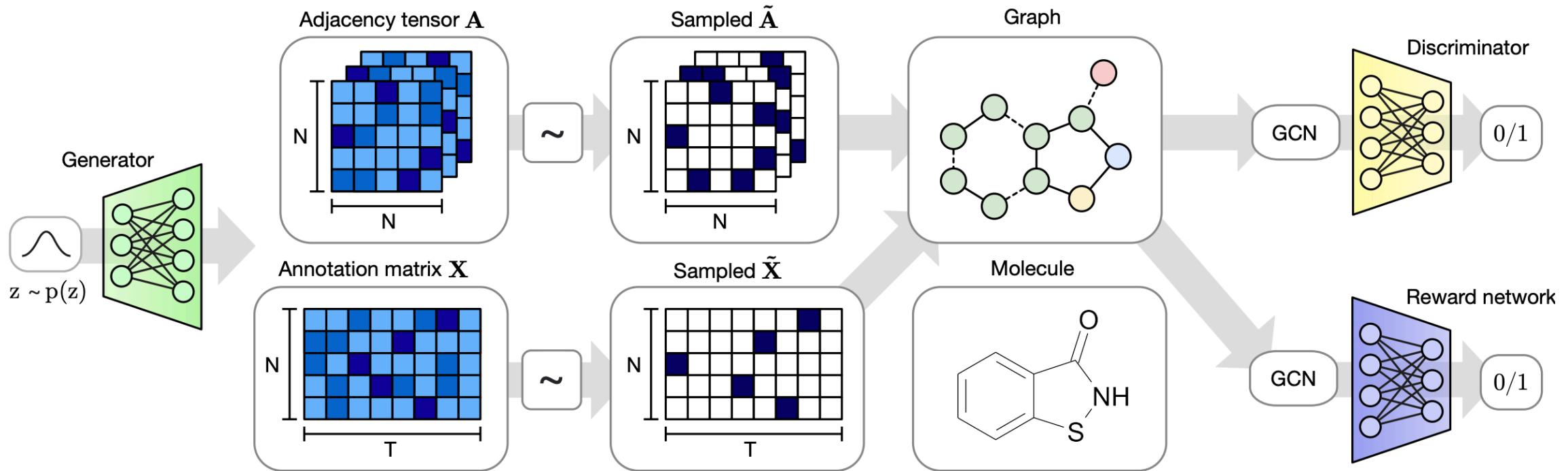
- ✓ VAE-based model: Generate a whole graph in one step
- ✓ GAN-based model: Generate a whole graph in one step
- ✓ Auto-regressive-based model: Generate a node or an edge in one step

VAE based model



<https://arxiv.org/pdf/1802.03480.pdf>

GAN-based model



AR-based model

<https://arxiv.org/pdf/1803.03324.pdf>

$$f_{addnode}(G) = \mathbf{s}, f_{addedge}(G, v) = f_{addnode}(G) = f_{addedge}(G, v) = f_{nodes}(G, v) = \text{softmax}(\mathbf{s})$$

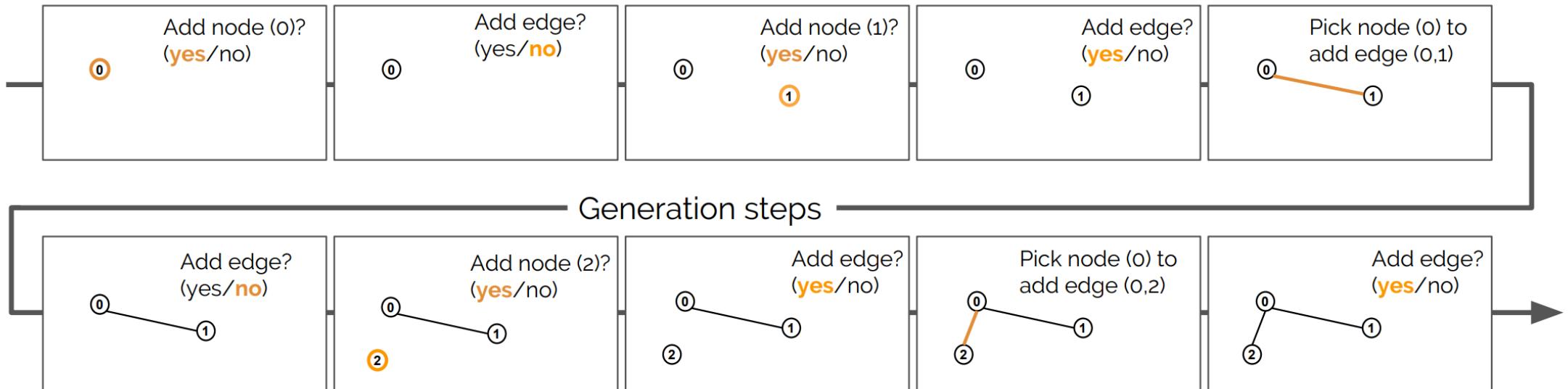


Figure 1. Depiction of the steps taken during the generation process.

$$\mathbf{a}_v = \sum_{u:(u,v) \in E} f_e(\mathbf{h}_u, \mathbf{h}_v, \mathbf{x}_{u,v}) \quad \forall v \in V$$

$$\mathbf{h}'_v = f_n(\mathbf{a}_v, \mathbf{h}_v) \quad \forall v \in V,$$

$$\begin{aligned} \mathbf{h}_V^{(T)} &= \text{prop}^{(T)}(\mathbf{h}_V, G) \\ \mathbf{h}_G &= R(\mathbf{h}_V^{(T)}, G) \end{aligned}$$

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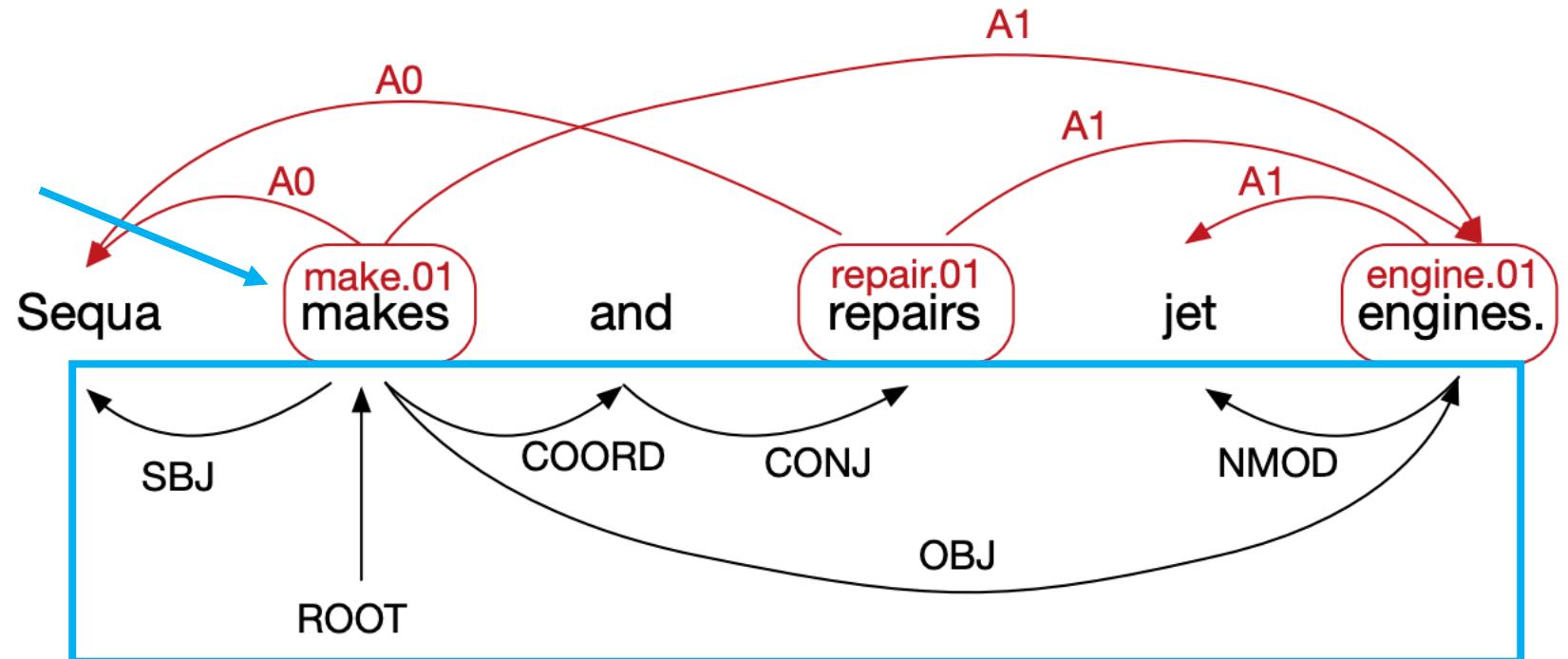
GNN for NLP

- ✓ Semantic Roles Labeling
- ✓ Event Detection
- ✓ Document Time Stamping
- ✓ Name Entity Recognition
- ✓ Relation Extraction
- ✓ Knowledge Graph

GCN for Semantic Roles Labeling

- ✓ Assume we have syntactic parse tree, we know where the predicates in the sentences are, and our model don't need to deal with predicate disambiguation problems.

We have the
disambiguated predicates



We have the syntactical tree

GCN for Semantic Roles Labeling

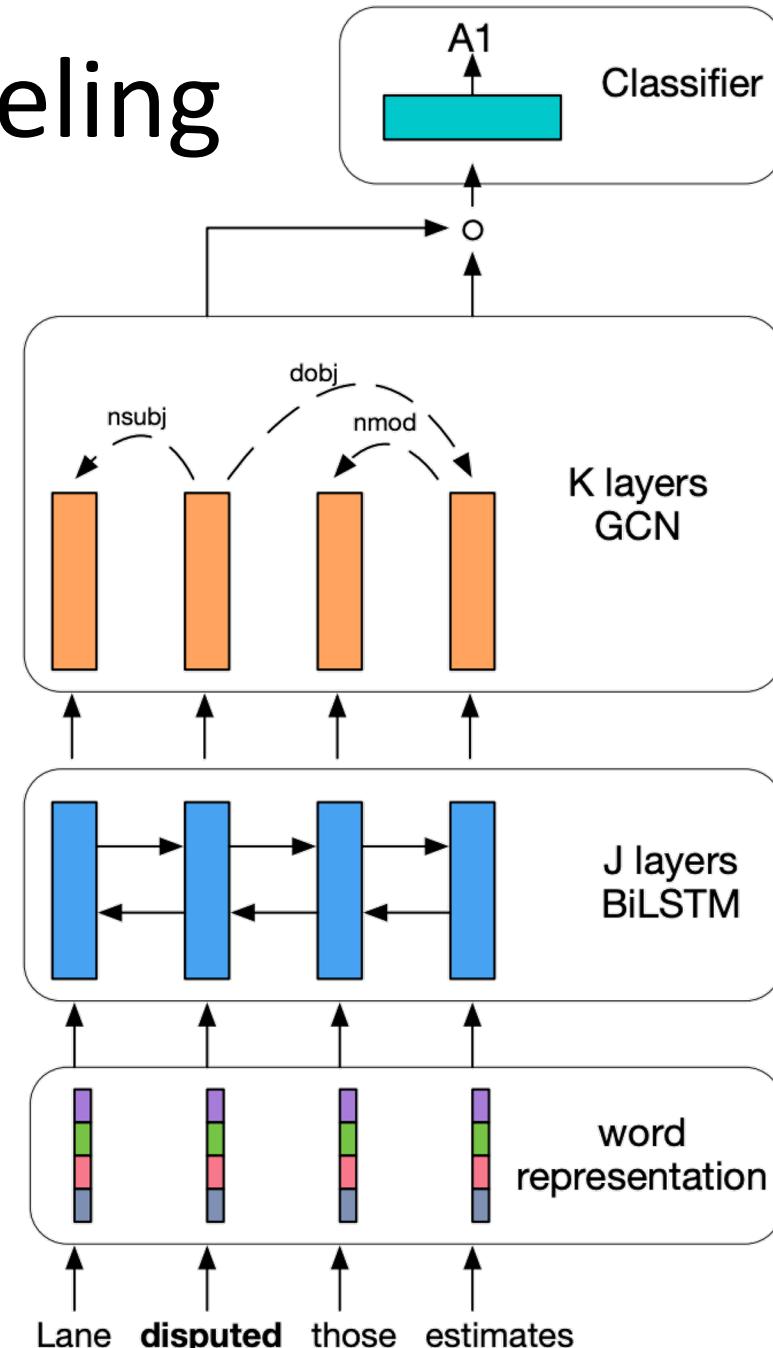
- ✓ Model architecture

Bias depends on dependency relation

$$h_v^{(k+1)} = \text{ReLU} \left(\sum_{u \in \mathcal{N}(v)} (V_{\text{dir}(u,v)}^{(k)} h_u^{(k)} + b_{L(u,v)}^{(k)}) \right)$$

Weight, just like GAT

- Different edge directions use different weight
- 1) Head > dependent
 - 2) Dependent > head
 - 3) Self-loop

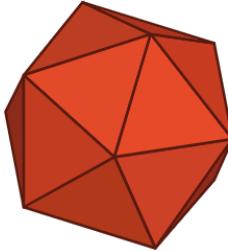


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PyTorch

- ✓ [PyTorch Geometric](#)



PyTorch
geometric

- ✓ [Deep Graph Library](#)

DeepGraphLibrary

GNN Roadmap

Theoretical analysis: GIN, GCN

Convolution

Spatial-based

Aggregation	Method
Sum	NN4G
Mean	DCNN, DGC, GraphSAGE
Weighted sum	MoNET, GAT, GIN
LSTM	GraphSAGE
Max Pooling	GraphSAGE

Spectral-based

ChebNet → **GCN** → HyperGCN

Tasks

- Supervised classification
- Semi-Supervised Learning
- Representation learning: Graph InfoMax
- Generation: GraphVAE, MolGAN, etc.

~~Application: Natural Language Processing~~

Summary and Take Home Notes

- ✓ GAT and GCN are the most popular GNNs
- ✓ Although GCN is mathematically driven, we tend to ignore its math
- ✓ GNN (or GCN) suffers from information loss while getting deeper
- ✓ Many deep learning models can be slightly modified and designed to fit graph data, such as Deep Graph InfoMax, Graph Transformer, GraphBert.
- ✓ Theoretical analysis must be dealt with in the future
- ✓ GNN can be applied to a variety of tasks

Q&A

Reference

- ✓ [Functions of Matrices: Theory and Computation](#)
- ✓ Signal and System by Prof. Lee:
<http://speech.ee.ntu.edu.tw/courses.html>
- ✓ Machine Learning by Prof. Hung-yi Lee
<http://speech.ee.ntu.edu.tw/~tlkagk/courses.html>
- ✓ [Vertex-Frequency Analysis of Graph Signals](#)
- ✓ All the papers mentioned have link appended on the corresponding page