

## 12 Type Rules

This section formally defines the type rules of Cool. The type rules define the type of every Cool expression in a given context. The context is the *type environment*, which describes the type of every unbound identifier appearing in an expression. The type environment is described in Section 12.1. Section 12.2 gives the type rules.

### 12.1 Type Environments

To a first approximation, type checking in Cool can be thought of as a bottom-up algorithm: the type of an expression  $e$  is computed from the (previously computed) types of  $e$ 's subexpressions. For example, an integer 1 has type `Int`; there are no subexpressions in this case. As another example, if  $e_n$  has type `X`, then the expression  $\{ e_1; \dots; e_n \}$  has type `X`.

A complication arises in the case of an expression  $v$ , where  $v$  is an object identifier. It is not possible to say what the type of  $v$  is in a strictly bottom-up algorithm; we need to know the type declared for  $v$  in the larger expression. Such a declaration must exist for every object identifier in valid Cool programs.

To capture information about the types of identifiers, we use a *type environment*. The environment consists of three parts: a method environment  $M$ , an object environment  $O$ , and the name of the current class in which the expression appears. The method environment and object environment are both functions (also called *mappings*). The object environment is a function of the form

$$O(v) = T$$

which assigns the type  $T$  to object identifier  $v$ . The method environment is more complex; it is a function of the form

$$M(C, f) = (T_1, \dots, T_{n-1}, T_n)$$

where  $C$  is a class name (a type),  $f$  is a method name, and  $t_1, \dots, t_n$  are types. The tuple of types is the *signature* of the method. The interpretation of signatures is that in class  $C$  the method  $f$  has formal parameters of types  $(t_1, \dots, t_{n-1})$ —in that order—and a return type  $t_n$ .

Two mappings are required instead of one because object names and method names do not clash—i.e., there may be a method and an object identifier of the same name.

The third component of the type environment is the name of the current class, which is needed for type rules involving `SELF_TYPE`.

Every expression  $e$  is type checked in a type environment; the subexpressions of  $e$  may be type checked in the same environment or, if  $e$  introduces a new object identifier, in a modified environment. For example, consider the expression

```
let c : Int <- 33 in
...
```

The `let` expression introduces a new variable `c` with type `Int`. Let  $O$  be the object component of the type environment for the `let`. Then the body of the `let` is type checked in the object type environment

$$O[Int/c]$$

where the notation  $O[T/c]$  is defined as follows:

$$\begin{aligned} O[T/c](c) &= T \\ O[T/c](d) &= O(d) \text{ if } d \neq c \end{aligned}$$

## 12.2 Type Checking Rules

The general form a type checking rule is:

$$\frac{\vdots}{O, M, C \vdash e : T}$$

The rule should be read: In the type environment for objects  $O$ , methods  $M$ , and containing class  $C$ , the expression  $e$  has type  $T$ . The dots above the horizontal bar stand for other statements about the types of sub-expressions of  $e$ . These other statements are hypotheses of the rule; if the hypotheses are satisfied, then the statement below the bar is true. In the conclusion, the “turnstile” (“ $\vdash$ ”) separates context  $(O, M, C)$  from statement  $(e : T)$ .

The rule for object identifiers is simply that if the environment assigns an identifier  $Id$  type  $T$ , then  $Id$  has type  $T$ .

$$\frac{O(Id) = T}{O, M, C \vdash Id : T} \quad [\text{Var}]$$

The rule for assignment to a variable is more complex:

$$\frac{\begin{array}{l} O(Id) = T \\ O, M, C \vdash e_1 : T' \\ T' \leq T \end{array}}{O, M, C \vdash Id \leftarrow e_1 : T'} \quad [\text{ASSIGN}]$$

Note that this type rule—as well as others—use the conformance relation  $\leq$  (see Section 3.2). The rule says that the assigned expression  $e_1$  must have a type  $T'$  that conforms to the type  $T$  of the identifier  $Id$  in the type environment. The type of the whole expression is  $T'$ .

The type rules for constants are all easy:

$$\frac{}{O, M, C \vdash \text{true} : \text{Bool}} \quad [\text{True}]$$

$$\frac{}{O, M, C \vdash \text{false} : \text{Bool}} \quad [\text{False}]$$

$$\frac{i \text{ is an integer constant}}{O, M, C \vdash i : \text{Int}} \quad [\text{Int}]$$

$$\frac{s \text{ is a string constant}}{O, M, C \vdash s : \text{String}} \quad [\text{String}]$$

There are two cases for **new**, one for **new SELF\_TYPE** and one for any other form:

$$\frac{T' = \begin{cases} \text{SELF\_TYPE}_C & \text{if } T = \text{SELF\_TYPE} \\ T & \text{otherwise} \end{cases}}{O, M, C \vdash \text{new } T : T'} \quad [\text{New}]$$

Dispatch expressions are the most complex to type check.

$$\frac{\begin{array}{l} O, M, C \vdash e_0 : T_0 \\ O, M, C \vdash e_1 : T_1 \\ \vdots \\ O, M, C \vdash e_n : T_n \\ T'_0 = \begin{cases} C & \text{if } T_0 = \text{SELF\_TYPE}_C \\ T_0 & \text{otherwise} \end{cases} \\ M(T'_0, f) = (T'_1, \dots, T'_n, T'_{n+1}) \\ T_i \leq T'_i \quad 1 \leq i \leq n \\ T_{n+1} = \begin{cases} T_0 & \text{if } T'_{n+1} = \text{SELF\_TYPE} \\ T'_{n+1} & \text{otherwise} \end{cases} \end{array}}{O, M, C \vdash e_0.f(e_1, \dots, e_n) : T_{n+1}} \quad [\text{Dispatch}]$$

$$\frac{\begin{array}{l} O, M, C \vdash e_0 : T_0 \\ O, M, C \vdash e_1 : T_1 \\ \vdots \\ O, M, C \vdash e_n : T_n \\ T_0 \leq T \\ M(T, f) = (T'_1, \dots, T'_n, T'_{n+1}) \\ T_i \leq T'_i \quad 1 \leq i \leq n \\ T_{n+1} = \begin{cases} T_0 & \text{if } T'_{n+1} = \text{SELF\_TYPE} \\ T'_{n+1} & \text{otherwise} \end{cases} \end{array}}{O, M, C \vdash e_0 @ T.f(e_1, \dots, e_n) : T_{n+1}} \quad [\text{StaticDispatch}]$$

To type check a dispatch, each of the subexpressions must first be type checked. The type  $T_0$  of  $e_0$  determines which declaration of the method  $f$  is used. The argument types of the dispatch must conform to the declared argument types. Note that the type of the result of the dispatch is either the declared return type or  $T_0$  in the case that the declared return type is `SELF_TYPE`. The only difference in type checking a static dispatch is that the class  $T$  of the method  $f$  is given in the dispatch, and the type  $T_0$  must conform to  $T$ .

The type checking rules for `if` and `{-}` expressions are straightforward. See Section 7.5 for the definition of the  $\sqcup$  operation.

$$\frac{\begin{array}{l} O, M, C \vdash e_1 : Bool \\ O, M, C \vdash e_2 : T_2 \\ O, M, C \vdash e_3 : T_3 \end{array}}{O, M, C \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \text{ fi} : T_2 \sqcup T_3} \quad [\text{If}]$$

$$\frac{\begin{array}{l} O, M, C \vdash e_1 : T_1 \\ O, M, C \vdash e_2 : T_2 \\ \vdots \\ O, M, C \vdash e_n : T_n \end{array}}{O, M, C \vdash \{ e_1; e_2; \dots e_n; \} : T_n} \quad [\text{Sequence}]$$

The `let` rule has some interesting aspects.

$$\frac{\begin{array}{l} T'_0 = \begin{cases} \text{SELF\_TYPE}_C & \text{if } T_0 = \text{SELF\_TYPE} \\ T_0 & \text{otherwise} \end{cases} \\ O, M, C \vdash e_1 : T_1 \\ T_1 \leq T'_0 \\ O[T'_0/x], M, C \vdash e_2 : T_2 \end{array}}{O, M, C \vdash \text{let } x : T_0 \leftarrow e_1 \text{ in } e_2 : T_2} \quad [\text{Let-Init}]$$

First, the initialization  $e_1$  is type checked in an environment without a new definition for  $x$ . Thus, the variable  $x$  cannot be used in  $e_1$  unless it already has a definition in an outer scope. Second, the body  $e_2$  is type checked in the environment  $O$  extended with the typing  $x : T'_0$ . Third, note that the type of  $x$  may be `SELF_TYPE`.

$$\frac{\begin{array}{l} T'_0 = \begin{cases} \text{SELF\_TYPE}_C & \text{if } T_0 = \text{SELF\_TYPE} \\ T_0 & \text{otherwise} \end{cases} \\ O[T'_0/x], M, C \vdash e_1 : T_1 \end{array}}{O, M, C \vdash \text{let } x : T_0 \text{ in } e_1 : T_1} \quad [\text{Let-No-Init}]$$

The rule for `let` with no initialization simply omits the conformance requirement. We give type rules only for a `let` with a single variable. Typing a multiple `let`

$$\text{let } x_1 : T_1 \leftarrow e_1, x_2 : T_2 \leftarrow e_2, \dots, x_n : T_n \leftarrow e_n \text{ in } e$$

is defined to be the same as typing

$$\text{let } x_1 : T_1 \leftarrow e_1 \text{ in } (\text{let } x_2 : T_2 \leftarrow e_2, \dots, x_n : T_n \leftarrow e_n \text{ in } e)$$

$$\begin{array}{c}
O, M, C \vdash e_0 : T_0 \\
O[T_1/x_1], M, C \vdash e_1 : T'_1 \\
\vdots \\
O[T_n/x_n], M, C \vdash e_n : T'_n \\
\hline
O, M, C \vdash \text{case } e_0 \text{ of } x_1 : T_1 \Rightarrow e_1; \dots x_n : T_n \Rightarrow e_n; \text{ esac} : \bigsqcup_{1 \leq i \leq n} T'_i
\end{array}
\quad [\text{Case}]$$

Each branch of a **case** is type checked in an environment where variable  $x_i$  has type  $T_i$ . The type of the entire **case** is the join of the types of its branches. The variables declared on each branch of a **case** must all have distinct types.

$$\begin{array}{c}
O, M, C \vdash e_1 : \text{Bool} \\
O, M, C \vdash e_2 : T_2 \\
\hline
O, M, C \vdash \text{while } e_1 \text{ loop } e_2 \text{ pool} : \text{Object}
\end{array}
\quad [\text{Loop}]$$

The predicate of a loop must have type *Bool*; the type of the entire loop is always *Object*. An **isvoid** test has type *Bool*:

$$\begin{array}{c}
O, M, C \vdash e_1 : T_1 \\
\hline
O, M, C \vdash \text{isvoid } e_1 : \text{Bool}
\end{array}
\quad [\text{Isvoid}]$$

With the exception of the rule for equality, the type checking rules for the primitive logical, comparison, and arithmetic operations are easy.

$$\begin{array}{c}
O, M, C \vdash e_1 : \text{Bool} \\
\hline
O, M, C \vdash \neg e_1 : \text{Bool}
\end{array}
\quad [\text{Not}]$$

$$\begin{array}{c}
O, M, C \vdash e_1 : \text{Int} \\
O, M, C \vdash e_2 : \text{Int} \\
op \in \{<, \leq\} \\
\hline
O, M, C \vdash e_1 \text{ op } e_2 : \text{Bool}
\end{array}
\quad [\text{Compare}]$$

$$\begin{array}{c}
O, M, C \vdash e_1 : \text{Int} \\
\hline
O, M, C \vdash \sim e_1 : \text{Int}
\end{array}
\quad [\text{Neg}]$$

$$\begin{array}{c}
O, M, C \vdash e_1 : \text{Int} \\
O, M, C \vdash e_2 : \text{Int} \\
op \in \{*, +, -, /\} \\
\hline
O, M, C \vdash e_1 \text{ op } e_2 : \text{Int}
\end{array}
\quad [\text{Arith}]$$

The wrinkle in the rule for equality is that any types may be freely compared except **Int**, **String** and **Bool**, which may only be compared with objects of the same type.

$$\begin{array}{c}
O, M, C \vdash e_1 : T_1 \\
O, M, C \vdash e_2 : T_2 \\
T_1 \in \{\text{Int}, \text{String}, \text{Bool}\} \vee T_2 \in \{\text{Int}, \text{String}, \text{Bool}\} \Rightarrow T_1 = T_2 \\
\hline
O, M, C \vdash e_1 = e_2 : \text{Bool}
\end{array}
\quad [\text{Equal}]$$

The final cases are type checking rules for attributes and methods. For a class  $C$ , let the object environment  $O_C$  give the types of all attributes of  $C$  (including any inherited attributes). More formally, if  $x$  is an attribute (inherited or not) of  $C$ , and the declaration of  $x$  is  $x : T$ , then

$$O_C(x) = \begin{cases} \text{SELF\_TYPE}_C & \text{if } T = \text{SELF\_TYPE} \\ T & \text{otherwise} \end{cases}$$

The method environment  $M$  is global to the entire program and defines for every class  $C$  the signatures of all of the methods of  $C$  (including any inherited methods).

The two rules for type checking attribute definitions are similar the rules for **let**. The essential difference is that attributes are visible within their initialization expressions. Note that **self** is bound in the initialization.

$$\frac{\begin{array}{l} O_C(x) = T_0 \\ O_C[\mathbf{SELF\_TYPE}_C/\mathbf{self}], M, C \vdash e_1 : T_1 \\ T_1 \leq T_0 \end{array}}{O_C, M, C \vdash x : T_0 \leftarrow e_1;} \quad [\text{Attr-Init}]$$

$$\frac{O_C(x) = T}{O_C, M, C \vdash x : T;} \quad [\text{Attr-No-Init}]$$

The rule for typing methods checks the body of the method in an environment where  $O_C$  is extended with bindings for the formal parameters and **self**. The type of the method body must conform to the declared return type.

$$\frac{\begin{array}{l} M(C, f) = (T_1, \dots, T_n, T_0) \\ O_C[\mathbf{SELF\_TYPE}_C/\mathbf{self}][T_1/x_1] \dots [T_n/x_n], M, C \vdash e : T'_0 \\ T'_0 \leq \begin{cases} \mathbf{SELF\_TYPE}_C & \text{if } T_0 = \mathbf{SELF\_TYPE} \\ T_0 & \text{otherwise} \end{cases} \end{array}}{O_C, M, C \vdash f(x_1 : T_1, \dots, x_n : T_n) : T_0 \{ e \};} \quad [\text{Method}]$$