A Hardware-Oriented and Memory-Efficient Method for CTC Decoding

Siyuan Lu, Jinming Lu, Jun Lin, Senior Member, IEEE, and Zhongfeng Wang, Fellow, IEEE

Abstract—The Connectionist Temporal Classification (CTC) has achieved great success in sequence to sequence analysis tasks such as automatic speech recognition (ASR) and scene text recognition (STR). These applications can use the CTC objective function to train the recurrent neural networks (RNNs), and decode the outputs of RNNs during inference. While hardware architectures for RNNs have been studied, hardware-based CTCdecoders are desired for high-speed CTC-based inference systems. This paper, for the first time, provides a low-complexity and memory-efficient approach to build a CTC-decoder based on the beam search decoding. Firstly, we improve the beam search decoding algorithm to save the storage space. Secondly, we compress a dictionary (reduced from 26.02MB to 1.12MB) and use it as the language model. Meanwhile searching this dictionary is trivial. Finally, a fixed-point CTC-decoder for an English ASR and an STR task using the proposed method is implemented with C++ language. It is shown that the proposed method has little precision loss compared with its floating-point counterpart. Our experiments demonstrate the compression ratio of the storage required by the proposed beam search decoding algorithm are 29.49 (ASR) and 17.95 (STR).

Index Terms—Connectionist Temporal Classification (CTC) decoding, beam search, softmax, recurrent neural networks (RNNs), sequence to sequence.

I. INTRODUCTION

N most automatic speech recognition (ASR) tasks and some sequential tasks, such as lipreading and scene text recognition, the lengths of output sequences are not fixed. Furthermore, the alignment between input and output is unknown [5]. To address this issue, Graves *et al.* [6] provided the Connectionist Temporal Classification (CTC) objective function to infer this alignment automatically. CTC is an output layer for recurrent neural networks (RNNs), which allows RNNs to be trained for sequence transcription tasks without requiring a prior alignment between the input and target sequences [7].

In ASR tasks, the traditional approach is based on HMMs [16], while recent works have shown great interest in building end-to-end models, using CTC-based deep RNNs. By training networks with large amounts of data, CTC-based models achieved great success [7], [11], [4], [12], [26], [18]. CTC is also widely used in other learning tasks such as handwriting recognition and scene text recognition, offering superior performance [8], [2], [19].

In a learning task using CTC, models are always ended with a softmax layer where the element represents the probability of

The authors are with the School of Electronic Science and Engineering, Nanjing University, Nanjing 210008, China (e-mail: sylu@smail.nju.edu.cn; jmlu@smail.nju.edu.cn; jlin@nju.edu.cn; zfwang@nju.edu.cn).

emitting each label at a specific time step. After being trained with the CTC loss function, the output of the network needs a CTC-decoder during inference. Since the probability of each label is temporally independent, a language model (LM) can be integrated to improve the accuracy of CTC decoding.

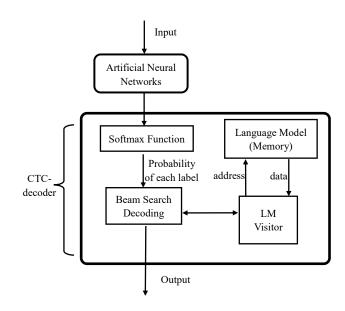


Fig. 1. A sequence processing system using the CTC-decoder designed in this paper.

On one hand, compared with solutions based on CPUs and GPUs, hardware-based sequence to sequence systems can have lower power consumption and higher speed [20] [24] [15]. On the other hand, CTC-decoder is an essential part of a system including CTC-trained neural networks. The outputs of these neural networks cannot be combined into the target output sequences directly without a CTC-decoder. Considering that recent works on hardware-based RNNs have made great progress [9] [23] [22], hardware-based CTC-decoders are desired for high-speed CTC-based inference systems, which can make these systems more efficient. In addition, the softmax function, which is also widely used in various neural networks [25], involves expensive division and exponentiation units. So a low-complexity hardware architecture design of softmax is also in demand.

A sequence processing system using the CTC-decoder designed in this paper is shown in Fig. 1. The system consists of two concatenated stages: the neural network and the CTC-decoder, which can be run in pipline. The network usually

takes more cycles than the CTC-decoder to process a set of data [23], so we do not need the decoder to run at high throughput. Thus, this decoder is designed to be serial to consume less computational resources.

There is no existing work on hardware-oriented algorithm nor hardware architecture for CTC decoding based on the beam search. This paper, for the first time, provides a hardware-oriented CTC decoding approach, employing the CTC beam search decoding with a dictionary as its LM. Our contributions can be summarized as follows:

- We improve the beam search decoding algorithm in [7].
 We choose this decoding method as it can integrate all kinds of LMs. We reduce the memory size used in decoding as much as possible. The improvement is suitable for both software and hardware decoding, regardless of the kind of LM. We further point out that some components can be reused to reduce the hardware complexity.
- 2) Several techniques are exploited to compress the size of a dictionary used as the LM in CTC decoding. By using these techniques, we compress the size of an English dictionary with 191,735 words from 26.05MB to 1.12MB. Meanwhile, we propose a low-complexity algorithm for the LM visitor. Our work on how to compress a dictionary is also useful when more complex LMs are used, as most of these LMs are based on a dictionary.
- 3) We use C++ language to implement a fixed-point CTC decoder applying the hardware-friendly approach for soft-max and the improved beam search decoding algorithm. In our experiments, the fixed-point decoder achieved nearly identical accuracy to the floating-point decoder in ASR and scene text recognition(STR) tasks, with the compression ratio of the storage are 29.49 and 17.95, respectively.

The RNN+CTC model is widely used, and the CTC beam search decoding algorithm is one of the most popular decoding methods [26]. However, the original beam search algorithm consumes a lot of memory space, making us believe that reducing storage consumption is very necessary. The proposed CTC decoding method is useful in improving any CTC-based inference systems, no matter whether it is software-based or hardware-based. Although a complete hardware implementation for the proposed CTC-decoder has not been finished yet (which will be conducted in the future work), we have implemented quantized CTC-decoders in the experiments to prove this.

The rest of this paper is organized as follows. Section II gives a brief review of CTC, the beam search algorithm, and the CTC beam search decoding algorithm. Several algorithmic strength reduction strategies applied in designing a low-complexity architecture for softmax are also introduced in Section II. Section III presents the improved beam search decoding algorithm. Section IV shows the compression of a dictionary used in the beam search decoding. In Section V, we implement the fixed-point CTC-decoder. Section VI concludes this paper.

II. BACKGROUND

A. Review of CTC

Assume that the output sequence and the target sequence of the system shown in Fig. 1 have K labels, and another blank label \emptyset is covered in the intermediate calculations. The \emptyset means a null emission. Define $X=(X_1,...,X_T)$ as the input sequence of the network. Define $Y=(Y_1,...,Y_T)$ as the output sequence of the network. At time t, we have $Y_t=(Y_t^1,...,Y_t^{K+1})$. So each of the outputs of the softmax layer represents the probability of each label:

$$Pr(k, t|X) = \frac{exp(Y_t^k)}{\sum_{i=1}^{K+1} exp(Y_t^i)}.$$
 (1)

A CTC path π which is introduced in [6] as a sequence of labels (including \emptyset), can be expressed as $\pi = (\pi_1, ..., \pi_T)$. Assuming that the probabilities of emitting a label at different times are conditionally independent, the probability of a CTC path π can be calculated as follows:

$$Pr(\pi|X) = \prod_{t=1}^{T} Pr(\pi_t, t|X). \tag{2}$$

The target sequence L is corresponding to a set of CTC paths, and the mapping function β is described in [6]. The function β removes all repeated labels and blanks from the path (e.g. $\beta(c \phi \phi a \phi t) = \beta(c c \phi a a a \phi \phi t t) = cat$). We can evaluate the probability of the target sentence as the sum of the probabilities of all the CTC paths in the set:

$$Pr(L|X) = \sum_{\pi \in \beta^{-1}(L)} Pr(\pi|X). \tag{3}$$

However, it is virtually impossible to sum the probabilities of all the paths in $\beta^{-1}(L)$. To calculate Pr(L|X), the CTC Forward-Backward Alogrithm was invented in [6]. Afterwards, the network can be trained with the CTC objective function:

$$CTC(X) = -logPr(L|X).$$
 (4)

B. CTC Beam Search Decoding

Decoding a CTC network means finding the most probable output sequence for a given input. The simplest way to decode it is the best path decoding introduced in [6]: by picking the single most probable label at every time step, the most probable sequence will correspond to the most probable labelling. Some works use this decoding method to build the CTC-layers in their hardware architectures of RNNs [17]. Although this way can already provide useful transcriptions, its limited accuracy is not sufficient to meet the demands of many sequence tasks [26].

The CTC beam search decoding searches for the most probable sequence in all the sequences ($length \leq T$) combined with K labels (\emptyset will not appear in output sequence). The number of all the sequences is growing exponentially with the increase of T, but the number of the sequences searched with the CTC beam search decoding is no larger than $K \cdot W \cdot T$. The beam width W determines the complexity and accuracy of the algorithm. If W is big enough, the probability will be

one so that the beam search is equal to the breadth first search (BFS). However, the algorithm will be too complex. But if W is too small, the probability of using beam search to find the correct answer will be too small. So there is a trade off between the size of W and the accuracy.

The probability of output sequence \mathbf{y} (including \emptyset) at time t is defined as $Pr(\mathbf{y},t)$. All the paths in $\beta^{-1}(\mathbf{y})$ can be classified into two sets, $\xi_1(\mathbf{y})$ and $\xi_2(\mathbf{y})$. The last label of any path in $\xi_1(\mathbf{y})$ must be \emptyset , while the last label of any path in $\xi_2(\mathbf{y})$ can be any label except \emptyset . Defining the sum of the probabilities of the paths in $\xi_1(\mathbf{y})$ and $\xi_2(\mathbf{y})$ as $Pr^-(\mathbf{y},t)$ and $Pr^+(\mathbf{y},t)$, respectively, we have $Pr(\mathbf{y},t) = Pr^-(\mathbf{y},t) + Pr^+(\mathbf{y},t)$. Define θ as the empty sequence $(Pr^+(\theta,t)=0)$, $\hat{\mathbf{y}}$ as the prefix of \mathbf{y} with its last label removed, and \mathbf{y}^e as the last label of \mathbf{y} . The CTC beam search decoding is described in Algorithm 1.

Algorithm 1 CTC Beam Search Decoding

```
1: t = 0
 2: B \leftarrow \{\theta\}, Pr^{-}(\theta, t) \leftarrow 1
 3: while t < T do
         \hat{B} \leftarrow the W most probable sequences in B
         B \leftarrow \{\}
 5:
         for y \in \hat{B} do
 6:
             Pr^{-}(\boldsymbol{y},t) \leftarrow Pr(\boldsymbol{y},t-1)Pr(\phi,t|X)
 7:
             if y \neq \theta then
 8:
                 Pr^+(\boldsymbol{y},t) \leftarrow Pr^+(\boldsymbol{y},t-1)Pr(\boldsymbol{y^e},t|X)
 9:
10:
                     Pr^+(\boldsymbol{y},t) \leftarrow Pr^+(\boldsymbol{y},t) + Pr(\boldsymbol{y^e},\boldsymbol{\hat{y}},t)
11:
                 end if
12:
13:
             Pr(\mathbf{y},t) = Pr^{+}(\mathbf{y},t) + Pr^{-}(\mathbf{y},t), Add \mathbf{y} to B
14:
             for k = 1...K do
15:
                 Pr^{-}(\boldsymbol{y}+k,t) \leftarrow 0
16:
                 Pr^+(\boldsymbol{y}+k,t) \leftarrow Pr(k,\boldsymbol{y},t)
17:
                 Pr(y+k,t) = Pr^{-}(y+k,t) + Pr^{+}(y+k,t)
18:
                 Add y + k to B
19:
20:
             end for
         end for
21:
22:
         t \leftarrow t + 1
23: end while
24: output the most probable sequence in \hat{B}
```

Pr(k, t|X) is defined in Equation (1). The extension probability Pr(k, y, t) is defined in Equation (5):

$$Pr(k, \boldsymbol{y}, t) = \begin{cases} Pr(k|\boldsymbol{y})Pr(k, t|X)Pr^{-}(\boldsymbol{y}, t - 1) & y^{e} = k, \\ Pr(k|\boldsymbol{y})Pr(k, t|X)Pr(\boldsymbol{y}, t - 1) & y^{e} \neq k. \end{cases}$$
(5)

The transition probability from y to y + k is Pr(k|y), allowing prior linguistic information to be integrated. All Pr(k|y) are set by the LM. If no LM is used, all Pr(k|y) are set to 1. If the LM is just a dictionary, Pr(k|y) will be set in accordance with Equation (6).

$$Pr(k|\mathbf{y}) = \begin{cases} 1 & (\mathbf{y} + k) \text{ is in the dictionary,} \\ 0 & (\mathbf{y} + k) \text{ is not in the dictionary.} \end{cases}$$
 (6)

If a more complicated LM is used, Pr(k|y) will be set differently, which has been discussed in [7]. In this work we just focus on the dictionary LM.

C. Low-Complexity Softmax Function

The softmax function is described in Equation (1), which is widely used in various neural network systems. Our previous work [21] proposed a high-speed and low-complexity architecture for softmax function. For computational characteristics of CTC-decoder, a variant model for softmax is used in this work.

1) Log-Sum-Exp Trick: The log-sum-exp trick is adopted as Equation (7) [25]. After this mathematical transformation, we not only replace the division operation by a subtraction operation but also avoid numerical underflow.

$$p_{k} = \frac{y_{k} - y_{max}}{\sum_{i=1}^{K+1} exp(y_{i} - y_{max})}$$

$$= exp(y_{k} - y_{max} - ln(\sum_{i=1}^{K+1} exp(y_{i} - y_{max})))$$

$$(\forall k \in 1, 2, ..., K+1, y_{max} \ge y_{k}).$$
(7)

2) The Transformation of Exponential Function: The exponential function is not so easy to calculate, but if we limit its inputs within a specific range, the calculation will be much simplified.

Transform e^{y_i} with the following expression:

$$e^{y_i} = 2^{y_i \cdot \log_2 e} = 2^{u_i + v_i} = (2^{u_i}) \cdot (2^{v_i}).$$

$$u_i = |y_i \cdot \log_2 e|, \quad v_i = y_i - u_i.$$
(8)

Since u_i is an integer, and v_i is limited in (0,1], we can replace the original exponential unit with the operation $f(v_i) = 2^{v_i}$ and a simple shift operation. The operation $f(v_i) = 2^{v_i}$ can be approximated as functions $f(x) = x + d_1$ or $f(x) = x + d_2$, where two bias values d_1 and d_2 correspond to the first and Second exponential operations, respectively.

3) The Transforamtion of Logarithmic Function: Similarly, we can simplify the calculation of logarithmic function by limiting the range of its input.

Transform lnF with the following expression:

$$lnF = ln2 \cdot log_2 F = ln2 \cdot (\omega + log_2 \kappa).$$

$$\omega = |log_2 F|, \quad \kappa = F \div 2^{\omega}.$$
(9)

As a result, κ is limited in [1,2), so the approximation $log_2\kappa \approx k-1$ can be used. Finally, the logarithmic function can be simplified as $lnF = ln2 \cdot (\kappa - 1 + \omega)$.

III. CTC BEAM SARCH DECODING IMPROVEMENTS

This section improves the CTC beam search decoding (Algorithm 1) to save memory space. Additionally, the time complexity of the improved algorithm (Algorithm 5) is the same as that of Algorithm 1, which is $O(T \cdot W \cdot K)$. As mentioned before, the improved serial algorithm is suitable for both software and hardware decoding.

A. Memory Space Required by Original CTC Beam Search Decoding Algorithm

The storage structure of the original algorithm (Algorithm 1) is described in Fig. 2. There are (K+2)W label sequences. W sequences are in \hat{B} , and (K+1)W sequences are in B. $\hat{B}(i)$ or B(i) represents each label sequence in \hat{B} or B.

For convenience of discussion, we use \boldsymbol{y} to denote a B(i) or a B(i). To store each \boldsymbol{y} , required information includes the three probabilities $(Pr^-(\boldsymbol{y},t),Pr^+(\boldsymbol{y},t),Pr(\boldsymbol{y},t))$, the SL (used to store some necessary information related to LM) and the Sentence. The Sentence is used to store every label of \boldsymbol{y} in chronological order. Considering the worst situation, each Sentence consists of T labels.

			\widehat{B}		
		$\hat{B}(1)$	3 probabilities	SL	Sentence
		$\hat{B}(2)$	3 probabilities		
W	{				
	1				
		$\hat{B}(W)$			
	•				

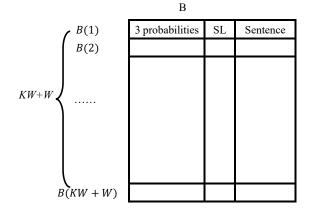


Fig. 2. The storage structure of the Algorithm 1. The width of each probability is determined by the experiment. SL is used to store some necessary information related to LM. Its width is decided by the LM. Each Sentence consists of T labels, requiring $T \cdot \lceil \log_2 K \rceil$ bits.

B. First Improvement: Decrease the Number of Sequences in B

Most of the sequences stored in B are useless. In fact, only W of the sequences in B can be reserved in each iteration. In this subsection, the number of sequences in B is reduced to W sequences.

We define the minimum of Pr(B(i),t) as min(Pr). The solution of working out min(Pr) can be a sorting block on hardware platform, or using a min-heap [3]. The min-heap is a binary tree, and each node represents each Pr(B(i),t). The value of the root node is min(Pr), and the value of each node other than the root node is not less than its parent node. When a new sequence is evaluated, its probability will be compared with min(Pr). Only if the probability is larger than

TABLE I

Variable	Description	
B1(i)	the index of prefix of $\hat{B}(i)$. Sentence	
	if the prefix exists in \hat{B}	
B2(i) B3(i)	the last label k of $\hat{B}(i)$. Sentence	
B3(i)	$Pr(B2(i), \hat{B}(B1(i)), t)$	

min(Pr), the new sequence can take place of the sequence whose probability is min(Pr).

Nevertheless, simply reducing the size of B and giving the min(Pr) could not give the right answer as Algorithm 1 gives. Pay attention to the line 11 of Algorithm 1, where a special situation is taken into consideration. For example, assume $\hat{y} = (a \ b \ c)$ and $y = (a \ b \ c)$. Calculating $Pr^+(y,t)$ requires $Pr(d,\hat{y},t)$, which has probably been discarded if it is smaller than min(Pr). Therefore, all values of Pr(y+k,t) must be calculated before the values of Pr(y,t) in the improved algorithm, and then special probabilities like $Pr(d,\hat{y},t)$ can be reserved. We use three arrays, B1, B2 and B3, to save these probabilities. The detailed descriptions of them are listed in TABLE I

The modified algorithm is Algorithm 2. B can be set as a min-heap, and finding min(Pr) will be very easy (the position of it will be fixed in B). But the heap needs to be adjusted when new elements come in. Another choice is to figure out the position of min(Pr) in real time, which will be easy to implement on hardware platform by using a sorting block.

Algorithm 2 obviously outperforms Algorithm 1. Firstly, Algorithm 2 solves the problem of finding the W most probable sequences in B, which is mentioned in the line 4 of Algorithm 1. Secondly, the memory space used in Algorithm 2 is obviously smaller than Algorithm 1. The storage structure of Algorithm 2 is shown in Fig. 3. The memory space required by B1, B2 and B3 is much smaller than B, and now the size of B is the same as \hat{B} . In most cases, the reduction of B will compress the required memory space to nearly $\frac{3}{K+2}$ of the original size. K is probably much larger than 10, so the compression ratio will be much larger than 5. Thirdly, the number of assignments of B is significantly reduced. Compared with Algorithm 1, Algorithm 2 takes a few more steps to fill B1 and B2, which is a perfectly acceptable tradeoff.

C. Second Improvement: Remove All the Sentences in B

Although Algorithm 2 has saved most of the required memory space, there is still redundant storage. In this subsection, we remove all the Sentences of B to further improve the beam search algorithm and get a higher compression ratio.

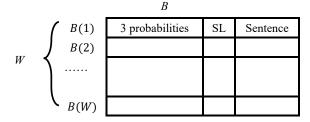
In Fig. 3, $\hat{B}.Sentence$ and B.Sentence take up a lot of space. Each B(i) or $\hat{B}(i)$ contains only three probabilities, but each B(i).Sentence or $\hat{B}(i).Sentence$ has hundreds of labels (in most cases, T is much larger than 100). The width of each probability saved in B or \hat{B} is probably no bigger than 64 bits. The width of each label is $\lceil \log_2 K \rceil$. If K is bigger than 10, the space used by B.Sentence will almost be twice the size of the space used by all the probabilities in B.

Algorithm 2 CTC Beam Search Decoding with First Improvement

```
1: t \leftarrow 0
 2: \hat{B}(1).Sentence \leftarrow \theta, Pr^{-}(\hat{B}(1)) \leftarrow 1
 3: while t < T do
       for (B(i), B(j)) \in B, (i \neq j) do
 4:
          if \hat{B}(i).Sentence = \hat{B}(j).Sentence + k then
 5:
             B1(i) = j, B2(i) = k
 6:
          end if
 7:
       end for
 8:
       for \hat{B}(i) in \hat{B} do
 9:
          for k = 1...K do
10:
             Temp \leftarrow Pr(k, \hat{B}(i), t)
11:
12:
             T_S \leftarrow information \ received \ from \ LM
             if (\hat{B}(i) = B1(j)) \land (k = B2(j)) then
13:
                B3(j) \leftarrow Temp
14:
             end if
15:
             find B(mi) as min(Pr)
16:
                                                                   mi
             Pr(B(mi),t) \leq Pr(B(j),t)
             if Temp > min(Pr) then
17:
                Pr(B(mi),t) \leftarrow Temp
18:
                B(mi).SL \leftarrow T_S
19:
                Pr^+(B(mi),t) \leftarrow Temp
20:
                Pr^{-}(B(mi),t) \leftarrow 0
21:
22:
                B(mi).Sentence \leftarrow B(i).Sentence + k
                if B is a min-heap, adjust it
23:
             end if
24:
          end for
25:
       end for
26:
27:
       for \hat{B}(i) in \hat{B} do
28:
          Temp^- \leftarrow Pr(B(i), t-1) \cdot Pr(\phi, t|X)
          Temp^+ \leftarrow Pr^+(\hat{B}(i), t-1) \cdot Pr(\hat{B}(i)^e, t) + B3(i)
29:
          Temp \leftarrow Temp^- + Temp^+
30:
31:
          if B(i).Sentence = B(j).Sentence then
             (Pr^{-}(B(j),t), Pr^{+}(B(j),t), Pr(B(j),t))
32:
             \leftarrow (Temp^-, Temp^+, Temp)
             B(j).SL \leftarrow \hat{B}(i).SL
33:
             if B is a min-heap, adjust it
34:
35:
          else
             find B(mi) as min(Pr) (same as line 16)
36:
             if Temp > min(Pr) then
37:
                Pr(B(mi),t) \leftarrow Temp
38:
                B(mi).SL \leftarrow \hat{B}(i).SL
39:
                Pr^+(B(mi),t) \leftarrow Temp^+
40:
                Pr^{-}(B(mi),t) \leftarrow Temp^{-}
41:
                B(mi).Sentence \leftarrow B(i).Sentence
42:
                if B is a min-heap, adjust it
43:
             end if
44.
          end if
45:
       end for
46:
       B \leftarrow B
47:
       t \leftarrow t + 1
48:
49: end while
50: output the most probable sequence in \hat{B}
```

	•			
- ($\hat{B}(1)$	3 probabilities	SL	Sentence
	$\hat{B}(1)$ $\hat{B}(2)$			
W				
($\hat{B}(W)$			

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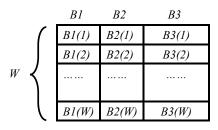


Fig. 3. The storage structure of the Algorithm 2. The width of B1 is $\lceil \log_2 W \rceil$. The width of B2 is $\lceil \log_2 K \rceil$. The width of B3 is the same as the width of each probability in B.

The only function of B.Sentence is to iterate and update $\hat{B}.Sentence$, as shown in the line 47 of Algorithm 2. However, $\hat{B}.Sentence$ can be iterated and updated without B.Sentence. The prefix of B(i).Sentence with its last label removed or the B(i).Sentence itself can certainly be found in $\hat{B}.Sentence$, by mapping sequences in B into sequences in B. Define this mapping as $\rho:B\to \hat{B}.$ ρ is a general mapping, which means sequences in B may have no preimage or more than one preimages. Based on ρ , Algorithm 3 is introduced to replace line 47 in Algorithm 2. New arrays A1, A2, d and c are defined in TABLE II. The size of A1 is the same as B1, and the size of A2 is as big as B2. Boolean arrays d and d only consume d bits. Note that an LOD can be reused on hardware platform for the calculation in the line 22 of Algorithm 3.

The key problem solved by Algorithm 3 can be outlined as follows:

1) The Problem: Define C_p as a combination of W numbers in $\{1,2,...,W\}$ (not ordered). C_p is saved in array \bar{L} (ordered). A W-length array is defined as L, $L=(C^1,C^2,...,C^W)$. Define Comb(L) as a combination of all the superscripts of C in L. The purpose is to transform L so that Comb(L) is equal to C_p , using only one operation: copying its own element to cover another element of it. Apart from L, there is no other place to store any C^i . Meanwhile,

TABLE II

Variable	Description	
A1(i)	the index of the prefix of $B(i).Sentence$	
	or $B(i).Sentence$ itself in \hat{B}	
A2(i)	the last label k of $B(i)$. Sentence or zero	
d(i)	whether the information in $\hat{B}(i)$ has been	
	updated by B	
c(i)	whether $B(i)$ has replaced the information	
	\hat{B}	

Algorithm 3 Update \hat{B} without B.Sentence

```
1: for i = 1...W do
       d(i) \leftarrow false, c(i) \leftarrow false
 3:
       A1(i) \leftarrow \rho(B(i))
       if when B(i) was added in B, the Sentence was
       enlarged with k then
          A2(i) \leftarrow k
 5:
       else
 6:
          A2(i) \leftarrow 0
 7:
       end if
 9: end for
10: for i = 1...W do
       if (d(A1(i)) = false) then
11:
          \hat{B}(A1(i)).probability\&SL \leftarrow B(i)
12:
          if A2(i) > 0 then
13:
             \hat{B}(A1(i)).Sentence = \hat{B}(A1(i)).Sentence +
14:
          end if
15:
          d(a(i)) = true
16:
17:
          c(i) = true
       end if
18:
19: end for
20: for i = 1...W do
       if c(i) = false then
21.
22:
          j \leftarrow the \ leading \ 0 \ in \ d
23:
          \hat{B}(j).probability\&SL \leftarrow B(i)
          \hat{B}(j).Sentence \leftarrow \hat{B}(i).Sentence
24:
          if A2(i) > 0 then
25:
             \hat{B}(i).Sentence = \hat{B}(i).Sentence + A2(i)
26:
          end if
27:
28:
       end if
29: end for
```

try to make the number of the copies as few as possible.

2) An Example: Shown in TABLE III.

TABLE III

Name	Value
W	8
L (in beginning)	$(C^1, C^2, C^3, C^4, C^5, C^6, C^7, C^8)$
Comb(L)	(1, 2, 3, 4, 5, 6, 7, 8)
C_p	(4, 6, 8, 6, 3, 3, 7, 1)

3) The Solution: In Algorithm 3, the first loop is the initialization, and the main procedure is comprised of the

rest two loops. In the first loop of the main procedure, the C^j in correct place is fixed. In this example, we have d=(true,false,true,true,false,true,true,true) and c=(true,true,true,false,true,false,true,true) after the first loop of the main procedure. After the main procedure, L is transformed to what we want: $(C^1,C^6,C^3,C^4,C^3,C^6,C^7,C^8)$.

On one hand, Algorithm 3 keeps the number of the assignments of $\hat{B}.Sentence$ as few as possible. On the other hand, Algorithm 3 removes all the Sentences of B, but it needs more space for A1,A2,d and c. However, the size of them is far smaller than B.Sentence, which means Algorithm 3 further compresses the memory space used by the beam search decoding. The remaining memory space after these first two improvements can be seen in Fig. 4.

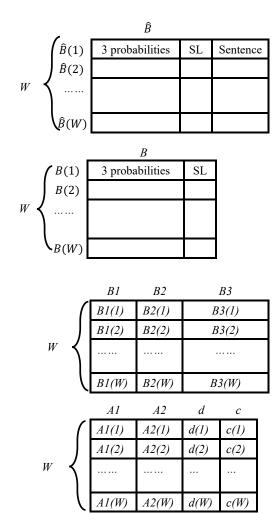


Fig. 4. The storage structure of the Algorithm 5. The width of A1 is the same as B1. The width of A2 is the same as B2. The widths of c and d are both 1 bit.

D. Third Improvement: Prevent Probabilities from Being Too Small

The first two improvements have already made the CTC beam search decoding highly memory-efficient, but we find all the probabilities in \hat{B} tend to become smaller in decoding.

Because the output of softmax is smaller than 1, all the probabilities will converge to 0. To tackle this problem, an adjustment of these probabilities is added after the update of \hat{B} . Here we give a conclusion which is proved in Appendix A: At each time after the update of \hat{B} , if all the probabilities of \hat{B} increase (or decrease) by the same times, the output of the whole system will not change.

According to this conclusion, a lower limit (named as P_l) is set for the maximum of $Pr(\hat{B}(i),t)$ (named as max(Pr)). After the update of \hat{B} , max(Pr) is compared with P_l . If max(Pr) is less than P_l , it will be enlarged to ensure that it is no smaller than P_l . The last step is to increase all the rest probabilities (including Pr^-, Pr^+ and Pr) by the same scale. To make the algorithm easier to be implemented in hardware we use Equation (10) to determine P_l .

$$\frac{1}{4W} < P_l \le \frac{1}{2W}, P_l = 2^n, n \le -1 \bigwedge n \in Z.$$
 (10)

As a fix-pointed binary number, only one bit of P_l is set to 1. The position of this 1 is called as $index(P_l)$. The calculation steps of this adjustment are shown in Algorithm 4. This algorithm also guarantees that $\sum_{i=1}^W Pr(\hat{B}(i),t) < 1$.

Algorithm 4 Adjust Probabilities

```
1: find \hat{B}(mi) as max(Pr): \forall j \neq mi, Pr(\hat{B}(mi), t) \geq Pr(\hat{B}(j), t)

2: j \leftarrow position of the leading 1 in max(Pr)

3: if j < index(P_l), (max(Pr) < P_l) then

4: i \leftarrow index(P_l) - j

5: end if

6: for all probabilities in \hat{B} do

7: probability=probability<< i

8: end for
```

Again, the LOD can be reused for the step in the line 2. The sorting block for finding the maximum can also be reused in the line 49 of Algorithm 5. As a result, this algorithm consumes few resources on hardware platform, but solves the problem of probabilities in \hat{B} being too smaller.

IV. COMPRESSED DICTIONARY

This section talks about the LM visitor module and the LM stored in memory. An LM is integrated to improve the precision of decoding by adjusting the value of Pr(k|y) in Equation (5). In Algorithm 5, the calculation of Pr(k|y) is only required in the line 11, where $y=\hat{B}(i)$. The dictionary is the simplest LM, including a specific number of words. In this section, an English dictionary (191,735 words, from the vocabulary of OpenSLR) is used as an example to demonstrate the effect of the compression. Subsection A talks about the basic data structure (DS) of the dictionary. In Subsection B and C, strategies of the compression are explained. In Subsection D, an algorithm is presented to apply the compressed dictionary to decoding.

Algorithm 5 CTC Beam Search Decoding with All Improvements

```
1: t \leftarrow 0
 2: \hat{B}(1).sentence \leftarrow \theta, Pr^{-}(\hat{B}(1)) \leftarrow 1
 3: while t < T do
       for (\hat{B}(i), \hat{B}(j)) \in \hat{B}, (i \neq j) do
 4:
          if \hat{B}(i).sentence = \hat{B}(j).sentence + k then
 5:
             B1(i) = j, B2(i) = k
 6:
 7:
          end if
       end for
 8:
       for \hat{B}(i) in \hat{B} do
 9:
          for k = 1...K do
10:
             Temp \leftarrow Pr(k, \hat{B}(i), t)
11:
             T_S \leftarrow information \ received \ from \ LM
12:
             if (\hat{B}(i) = B1(i))AND(k = B2(i)) then
13:
                B3(j) \leftarrow Temp
14:
             end if
15:
             find B(mi) as min(Pr)
16:
                                                                    mi.
             Pr(B(mi), t) \leq Pr(B(j), t)
             if Temp > min(Pr) then
17:
                Pr(B(mi), t) \leftarrow Temp
18:
                B(mi).SL \leftarrow T_S
19:
                Pr^+(B(mi),t) \leftarrow Temp
20:
                Pr^{-}(B(mi),t) \leftarrow 0
21:
                A1(mi) \leftarrow i
22:
                A2(mi) \leftarrow k
23:
                if B is a min-heap, adjust it
24:
             end if
25:
          end for
26:
       end for
27:
       for \hat{B}(i) in \hat{B} do
28:
          Temp^- \leftarrow Pr(\hat{B}(i), t-1) \cdot Pr(\phi, t|X)
29:
          Temp^+ \leftarrow Pr^+(\hat{B}(i), t-1) \cdot Pr(\hat{B}(i)^e, t) + B3(i)
30:
31:
          Temp \leftarrow Temp^- + Temp^+
          if B1(i) = A1(j) \land B2(i) = A2(j) then
32:
             (Pr^{-}(B(j),t), Pr^{+}(B(j),t), Pr(B(j),t))
33:
             \leftarrow (Temp^-, Temp^+, Temp)
             B(j).SL \leftarrow \hat{B}(i).SL
34:
             if B is a min-heap, adjust it
35:
36:
             find B(mi) as min(Pr) (same as line 16)
37:
             if Temp > min(Pr) then
38:
                Pr(B(mi), t) \leftarrow Temp
39:
                B(mi).SL \leftarrow \hat{B}(i).SL
40:
                Pr^+(B(mi),t) \leftarrow Temp^+
41:
                Pr^{-}(B(mi),t) \leftarrow Temp^{-}
42:
                A1(mi) \leftarrow i
43:
                A2(mi) \leftarrow k
44:
45:
                if B is a min-heap, adjust it
             end if
46:
          end if
47:
       end for
48:
       Update \hat{B} without B.sentence(Algorithm 3)
49:
       Adjust Probabilities (Algorithm 4)
50:
51:
       t \leftarrow t + 1
52: end while
53: output the most probable sequence in \hat{B}
```

A. Basic Data Structure: Trie-tree

The straightforward way to store a dictionary is to list every word in it, with a lookup time complexity of $O(N \cdot S)$ (N represents the number of words, and S represents the length of the word). Apparently, by using this DS, Algorithm 5 will perform poorly in the calculation of $Pr(k|\hat{B}(i))$ in the line 11. To reduce the time complexity, a trie can replace the list. An example is shown in Fig. 5.

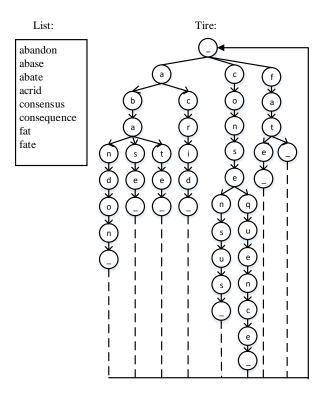


Fig. 5. This dictionary includes 8 words. The trie is a tree. '_' marks blank in English sentences.

The trie is a tree, and each node in the trie reflects a label. As an English dictionary, the label is just the character. Note that in this case K is equal to 27 because there are 26 characters in English plus the blank symbol. Make all the child nodes of each parent node in alphabetical order. The special label in the trie is the blank, separating every word in an English sentence. To distinguish it from ' ϕ ', we use '_' to mark it. Every word except the first one in an English sentence starts from a blank and ends with a blank, so each path in trie starting from the root node and ending with '_' can describe a specific word. Notice that if a node N_x has a child node which is '_', the address of this child node is the same as the address of the root node. This means the '_' at the end of each word does not actually take space. This mechanism enables us to search the tree circularly and save the memory space for the '_' at the end of each word.

By shaping the dictionary into a trie, the time complexity of checking if y+k is in the dictionary is reduced. Define a dictionary pointer as DP(i) of $\hat{B}(i)$ to mark the address of the last character in the last word in $\hat{B}(i)$. Every time when $Pr(k|\hat{B}(i))$ is calculated, we only need to find out if k is one

of the successors of the node which is pointed to by DP(i). As a result, the lookup time complexity is reduced to O(K). And each DP(i) can be stored in $\hat{B}(i).SL$.

If the English dictionary with 191,735 words is stored as a trie, there will be 425,983 nodes in it. Each node may have at most K (K = 27) successors, and the address of each successor takes 19 bits ($\log_2 425983 = 18.7$). To store a single node, the addresses of its all successors are in need. These addresses are stored, so that the storage structure can be designed as a matrix which has 425,983 rows and 27 columns. Because of the search direction in the trie (following the arrows in Fig. 5), the character which is represented by each node does not need to be saved in this matrix. So the storage with an immediate way takes $425983 \times 27 \times 19 = 218,529,279$ bits=26.05MB. The size of the trie is much smaller than that of n-gram LM, but it still can be futher compressed. Actually, the number of the successors of most of these nodes are smaller than K, so the matrix is a sparse one.

B. Transform the Trie Into a Binary Tree

The first compression strategy is reshaping the trie. A typical way to transform a multi-branched tree into a binary tree is to merely save a node's first child node and the first sibling from the right, so that each node will have only two child nodes.

A binary tree is well suited as the DS for the dictionary which is used in the CTC beam search decoding, because of the calculation order of Pr(k|y) (k = 1, 2, ..., K).

More importantly, a binary trie created by this means can save storage space. The transformation of the DS of trie is shown in Fig. 6. To store a node in the binary trie, the information in need includes which character this node represents where its left child (first child in the original trie) is and where its right child (first sibling from the right in the original trie) is. And they share the same address in memory space. As the character consumes 5 bits ($\log_2 27 = 4.75$), the storage space occupies $425983 \times (5+2 \times 19) = 18,317,269$ bits=2.18MB.

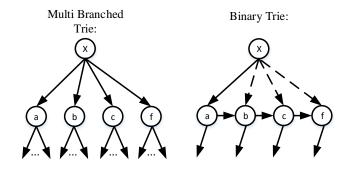


Fig. 6. Transforming each node in the multi branched trie in this way will create a binary trie.

Another way to transform the multi-branched trie into a binary trie is to use the PATRICIA algorithm [13]. A Patricia tree is a special type of trie, highly-efficient in string matching. It is a more appropriate method for matching a single word, but not suitable for the decoding algorithm used in this paper.

C. Compress the Address

For each node, the addresses of its child nodes still occupy too much space. In this subsection, we compress the address of the left child first, and then we compress the other.

- 1) Compress the Address of the Left Child: All nodes in binary trie except the '_' at the end of a word must have a left child, because every word ends with a blank. Assuming that each node is next to its first child in memory, a single bit is already enough to identify its left child: 1 represents that the left child is the '_', and 0 represents that it is not the '_'. To make sure every node is next to its left child, the preorder traversal of the binary trie should be stored in memory.
- 2) Compress the Address of the Right Child: The absolute address of the right child of node N_x can be replaced with a relative address. The relative address is the difference between the address of the right child of N_x and the absolute address of N_x . In the dictionary with 191,735 words, the maximum of this difference is 41,647. So the relative address takes 16 bits $(\log_2 41647 = 15.35)$.

After compressing these addresses, the storage space decreases to $425983 \times (5+1+16)=9,371,626$ bits=1.12MB. The data storage format of the compressed dictionary is given in Fig. 7.

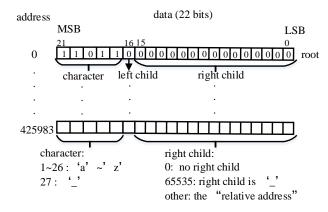


Fig. 7. The data storage format of the compressed dictionary. The root node is stored in address 0.

D. Apply the Compressed Dictionary to Decoding

To ensure the low dependency between the modules in the CTC-decoder, we set the LM Visitor module to control the access to LM. Algorithm 5 leaves three interfaces to make connections with the LM Visitor, including DP(i), $Pr(k|\hat{B}(i))$ and T_S . When the $Pr(k|\hat{B}(i))$ is calculated in the line 11 of Algorithm 5, the LM Visitor needs the value of DP(i), and gives the value of $Pr(k|\hat{B}(i))$ back. Afterwards, the LM Visitor assigns the variable T_S in the line 12 of Algorithm 5. Algorithm 6 is used by the LM Visitor. The connections between Algorithm 5, Algorithm 6 and various modules in the CTC-decoder are shown in Fig. 8. Note that the constant inv means the given address is invalid (at the same time, the $Pr(k, \hat{B}(i), t)$ must be zero).

Algorithm 6 LM Visitor

```
1: const inv = 2^{19} - 1 = 524287
 2: when a new DP(i) reached:
 3: address \leftarrow DP(i)
 4: flag \leftarrow 0
 5: send address to LM, get data from LM
 6: if data(16) = 0 then
 7:
       address \leftarrow address + 1
 8:
       send address to LM, get data from LM
 9: else
       flag = 2
10:
11: end if
12: for k = 1...26 do
       if flag = 0 and data(21:17) = k then
13:
          Pr(k|B(i)) \leftarrow 1
14:
          T_S \leftarrow address
15:
          if data(15:0) = 0 then
16:
17:
             flag \leftarrow 1
          else
18:
             if data(15:0) = 65535 then
19:
20:
                flag \leftarrow 2
             else
21:
               address \leftarrow address + data(15:0)
22:
               send address to LM, get data from LM
23:
24:
             end if
25:
          end if
26:
       else
          Pr(k|\hat{B}(i)) \leftarrow 0
27:
28:
          T_S \leftarrow inv
       end if
29:
30: end for
31:
    k \leftarrow 27
32: if f lag = 1 then
       Pr(k|B(i)) \leftarrow 0
34:
       T_S \leftarrow inv
35:
       Pr(k|\hat{B}(i)) \leftarrow 1
36:
37.
       T_S \leftarrow 0
38: end if
```

V. EXPERIMENT

As mentioned earlier, we provide hardware-oriented and memory-efficient ways to implement every single module in the CTC-decoder shown in Fig. 8. The architecture of softmax functoin module is shown in Fig. 9, using several algorithmic strength reduction strategies described in Section II. To demonstrate the advantages of our method, CTC-decoder is applied to a speech recognition task and a scene text recognition task. Meanwhile, we take a floating-point CTC-decoder using Algorithm 1 as the baseline. Since there are some proper nouns and abbreviations in the transcriptions of these tasks, we add all words of datasets to our dictionary, and append *apostrophe* in label list. The modification does not significantly affect original size and structure.

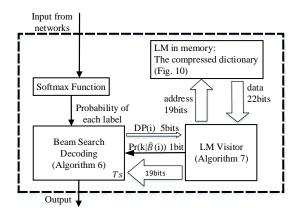


Fig. 8. The CTC-decoder designed by this work.

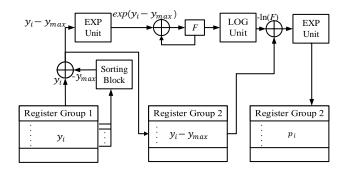


Fig. 9. The architecture of softmax in our CTC-deocder.

A. Speech Recognition Task

In this experiment, we evaluate our method on a pre-trained Deep-speech-2 model [1], which is trained on LibriSpeech ASR corpus [14]. The WER is 11.27% on "test-clean" set with greedy decoding used.¹

1) Determine the Value of W: In Section II, the background of the beam search algorithm has been discussed. To balance the model size and performance, we conduct some experiments to evaluate the accuracy under different W. Fig. 4 illustrates the fact that the memory space used by Algorithm 5 grows linearly as the data size increases. The function of the size of W vs. the word error rate (WER) of decoding is given in Fig. 10.

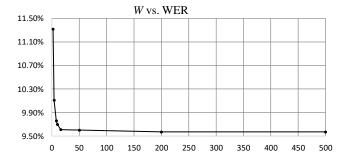


Fig. 10. The function relationship between W and WER.

When W < 4, the accuracy is unsatisfactory. When W > 50, the calculation complexity becomes unacceptable while accuracy increases little. In addition, as the width of B1 is $\lceil \log_2 W \rceil$, it is better that w is an integral power of 2. At last, we choose 8 as the value of W.

2) Fixed-Point Model of the Decoder: After the determination of W, we build a model for a fixed-point CTC-decoder depicted in Fig. 8.

The number of integer bits is decided by the range of input y_i , while the number of fractional bits (denoted as n) is decided by the experiment. The value of n has an impact on WER, and their functional relationship is depicted in Fig. 11. As a result, the input y_i has eight bits: one sign bit, five integer bits and two fractional bits.

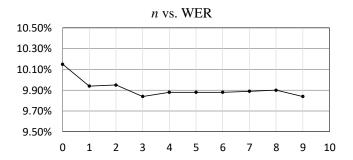


Fig. 11. The function relationship between n and WER.

In the experiment, we also find that the CTC-decoder does not require very accurate probabilities given by the softmax function. We can adjust the resolution of softmax function by three parameters: λ , d_1 , d_2 , where λ is used to approximate the ratio of e^x and 2^x . We use $\lambda=1.5, 1/\lambda=0.625$ in this task, where 4-bits are used. The linear functions used in EXP Unit and LOG Unit may sacrifice the accuracy, but d_1 and d_2 can be adjusted to counteract this influence. Some values of WER when d_1 and d_2 are set to different values are listed in TABLE IV.

TABLE IV SOME VALUES OF WER WHEN d_1 AND d_2 ARE SET TO DIFFERENT VALUES

d_1 (binary)	$d_2(binary)$	WER
1.0000000110	0.1111111110	12.931%
0.1111010001	0.1111111111	11.185%
0.1101000001	0.1111111111	10.587%
0.1011010110	0.11111110010	10.014%
0.1011110111	0.1111110010	9.992%

In addition, the probabilities calculated in the beam search decoding module also require fix-point processing. The experiment shows that if its decimal bit q is less than 26, in some cases all the probabilities in \hat{B} are smaller than 2^{-26} , so they are all assigned to 0. To avoid this situation, we set q equal to 30.

After the fix-point processing of softmax and the beam search decoding, a hardware-friendly model is created for softmax, replacing the most complex components by easy

¹https://github.com/SeanNaren/deepspeech.pytorch/

ones. With a greedy search strategy, we find a set of parameters for best WER, where $W=8,\,q=30,\,\lambda=1.5,\,1/\lambda=0.625,\,d_1=0.10111110111,\,d_2=0.1111110010.$ The WER is 9.99%, while 9.76% in floating-point version. This minor loss of accuracy is generally acceptable. Experiment results are shown in TABLE V. The baseline is a deepspeech2 model without a language model. W=1 means that CTC-Greedy Decoder is used. The floating-point and the fixed-point models share same configurations based on our method.

TABLE V EVALUATION RESULTS ON LIBRISPEECH TEST-CLEAN

Model	W	WER
baseline(no LM)	1	11.27%
baseline(no LM)	8	11.12 %
floating-point	8	9.76%
fixed-point	8	9.99%

B. Scene Text Recognition Task

Synth90k dataset [10] is a synthetically generated dataset for text recognition, which consists of 9 million images covering 90k English words. We use a CRNN model [19] pre-trained on a subset of Synth90k dataset ². A subset of dataset containing only character labels is used as test data. Experiment results are shown in TABLE VI, where the baseline is a CRNN model without a language model.

TABLE VI EVALUATION RESULTS ON SYNTH90k DATASET

Model	\overline{W}	Accuracy
baseline(no LM)	1	47.47%
baseline(no LM)	8	88.02%
floating-point	8	90.85%
fixed-point	8	90.87%

C. Analysis of Applying Algorithm 6 to the Beam Search Decoding

Section IV improves the beam search decoding to reduce the memory space. In this subsection, we will figure out the compression ratio of the space used by the beam search decoding module in the English ASR task.

Each probability consumes 30 bits, and each SL consumes 19 bits (the address of a single node in the dictionary). Each Sentence has to store T labels, while each label takes 5 bits ($\log_2 K = \log_2 28 = 4.81$). According to Fig. 2, the original algorithm occupies (109 + 5T)(KW + 2W) = (26160 + 1200T) bits. According to Fig. 4, Algorithm 5

consumes (2128 + 40T) bits. The results of each task are listed in TABLE VII.

TABLE VII COMPRESSION RATIO RESULTS

Tasks	T	Compression Ratio
ASR	1800	29.49
STR	25	17.95

Meanwhile, the experiments prove that the time of Algorithm 5 spent in decoding (denoted as τ_2) is less than the time spent by Algorithm 1 (denoted as τ_1). In our tests, when the number of the output vectors of softmax function is 697,310, we get $\tau_1=23.353$ seconds, and $\tau_2=20.816$ seconds.

VI. CONCLUSION AND FUTURE WORK

This paper has provided a hardware-oriented approach to build an CTC-decoder based on an improved CTC beam search decoding. The decoder has been implemented using C++ language and the experiments demonstrate that in English ASR tasks and STR tasks, the fixed-point CTC-decoder can save memory space for the beam decoding algorithm for 29.49 times and 17.95 times, respectively. The size of dictionary is compressed by 23 times. Additionally, there is little loss of precision compared with the floating-point CTC-decoder, and no increase is observed in computation time of the improved CTC beam search decoding. In the future, a complete hardware implementation for the CTC-decoder will be conducted.

APPENDIX A

To reach the conclusion, we need to compare the probabilities adjusted by Algorithm 4 with the original probabilities. To distinguish the adjusted probabilities from original ones, we use $Pr(\boldsymbol{y},t), Pr^+(\boldsymbol{y},t))$ and $Pr^-(\boldsymbol{y},t))$ to denote them.

Firstly, we assume that all the probabilities of \hat{B} are enlarged by α_t at each time after update of \hat{B} .

Secondly, by using mathematical induction, Equation (11) can be proved.

$$\forall t \in N^{+}, i \in \{1, 2, ..., W\}, \exists ! M_{t} > 0 :$$

$$\begin{cases} \frac{Pr(\hat{B}(i), t)}{Pr^{+}(\hat{B}(i), t)} = M_{t} \cdot Pr(\hat{B}(i), t), \\ \frac{Pr^{+}(\hat{B}(i), t)}{Pr^{-}(\hat{B}(i), t)} = M_{t} \cdot Pr^{-}(\hat{B}(i), t). \end{cases}$$

$$(11)$$

²https://github.com/MaybeShewill-CV/CRNN_Tensorflow

The proof of Equation (11) can be expressed as follows:

$$(1)t = 1, \forall i \in \{1, 2, ..., W\}$$
:

$$\begin{cases} \frac{Pr(\hat{B}(i), 1)}{Pr^{+}(\hat{B}(i), 1)} = \alpha_{1} \cdot Pr(\hat{B}(i), 1), \\ \frac{Pr^{+}(\hat{B}(i), 1)}{Pr^{-}(\hat{B}(i), 1)} = \alpha_{1} \cdot Pr^{+}(\hat{B}(i), 1), \\ \frac{Pr^{-}(\hat{B}(i), 1)}{Pr^{-}(\hat{B}(i), 1)} = \alpha_{1} \cdot Pr^{-}(\hat{B}(i), 1). \end{cases}$$

(2)Assume Equation (11) is true when t = m, so we have:

$$\begin{cases} \frac{Pr(\hat{B}(i), m) = M_m \cdot Pr(\hat{B}(i), m),}{Pr^{+}(\hat{B}(i), m) = M_m \cdot Pr^{+}(\hat{B}(i), m),} \\ \frac{Pr^{-}(\hat{B}(i), m) = M_m \cdot Pr^{-}(\hat{B}(i), m).} \end{cases}$$

Noticing line 17 and line 30 in Algorithm 5, the update of $Pr(\hat{B}(i),t)$ is based on the W biggest probabilities from all Temp. Define \underline{Temp} , \underline{Temp}^+ and \underline{Temp}^- as adjusted ones. Considering line 11 and line 29-31 in Algorithm 6, they can be evaluated as:

$$\underline{Temp^+} = M_m \cdot Temp^+, \underline{Temp^-} = M_m \cdot Temp^-$$

$$\underline{Temp} = Temp^+ + Temp^- = M_m \cdot Temp$$

As $M_m>0$, the judging results of the inequalities in line 17 and line 30 are the same with or without the adjustment. [7] After the loop from line 28 to line 48, probabilities in B can be found as follows:

$$\begin{cases} \frac{Pr(B(i), m+1)}{Pr^{+}(B(i), m+1)} = M_m \cdot Pr(B(i), m+1), \\ \frac{Pr^{+}(B(i), m+1)}{Pr^{-}(B(i), m+1)} = M_m \cdot Pr^{-}(B(i), m+1). \end{cases}$$

So in line 51, when $t = m + 1, \forall i \in \{1, 2, ..., W\}$:

$$\begin{cases} \frac{Pr(\hat{B}(i), m+1) = M_m \cdot \alpha_{m+1} \cdot Pr(\hat{B}(i), m+1),}{Pr^+(\hat{B}(i), m+1) = M_m \cdot \alpha_{m+1} \cdot Pr^+(\hat{B}(i), m+1),} \\ \frac{Pr^-(\hat{B}(i), m+1) = M_m \cdot \alpha_{m+1} \cdot Pr^-(\hat{B}(i), m+1).}{Pr^-(\hat{B}(i), m+1) = M_m \cdot \alpha_{m+1} \cdot Pr^-(\hat{B}(i), m+1).} \end{cases}$$

Let $M_{m+1} = M_m \cdot \alpha_{m+1}$,

$$\begin{cases} \frac{Pr(\hat{B}(i), m+1)}{Pr^{+}(\hat{B}(i), m+1)} = M_{m+1} \cdot Pr(\hat{B}(i), m+1), \\ \frac{Pr^{+}(\hat{B}(i), m+1)}{Pr^{-}(\hat{B}(i), m+1)} = M_{m+1} \cdot Pr^{-}(\hat{B}(i), m+1). \end{cases}$$

So when t = m + 1, Equation (11) is correct.

As a result, when $t \in N^+$, Equation (11) is correct.

Thirdly, by setting t as T, the mathematical relationship between $Pr(\hat{B}(i),T)$ and $Pr(\hat{B}(i),T)$ can be expressed as:

$$\forall i \in \{1, 2, ..., W\}, \exists M_T > 0:$$

 $Pr(\hat{B}(i), T) = M_T \cdot Pr(\hat{B}(i), T).$ (12)

Fourthly, set the maximum of $Pr(\hat{B}(i),T)$ as $Pr(\hat{B}(maxi),T)$:

$$\forall i \in \{1, 2, ..., W\} : Pr(\hat{B}(maxi), T) > Pr(\hat{B}(i), T).$$
 (13)

According to Equations (15) and (16), it can be shown that:

$$\forall i \in \{1, 2, ..., W\}:$$

$$M_T \cdot Pr(\hat{B}(maxi), T) > M_T \cdot Pr(\hat{B}(i), T), \qquad (14)$$

$$Pr(\hat{B}(maxi), T) > Pr(\hat{B}(i), T).$$

Finally, it is proved the maximum of $Pr(\hat{B}(i),T)$ is still $Pr(\hat{B}(maxi),T)$.

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