

```

1  /** A class representing a rover.
2      * @since 1.0
3      * @version 3.0
4      * @author Ludovic Provost
5  */
6  public class Rover {
7
8      /** Right pedal for rover.
9          * Creates a right pedal instance to
10         * be used when right pedal is used.
11     */
12     public Pedal rightPedal = new Pedal( leftOrRight: "R");
13
14     /** Left pedal for rover.
15         * Creates a left pedal instance to
16         * be used when left pedal is used.
17     */
18     public Pedal leftPedal = new Pedal( leftOrRight: "L");
19
20     /** State of rover.
21     */
22     int state;
23     //3   constant forward speed
24     //2   accelerate forward
25     //1   deaccelerate forward
26     //0   rest
27     //-1  deaccelerate backward
28     //-2  accelerate backward
29     //-3  constant backward speed
30
31     /** Creates rover and sets state to rest.
32     */
33     public Rover(int state) {
34         this.state = state;
35     }
36
37     /** Sets state of rover to new specified state.
38         * @param newState new state of rover.
39     */
40     public void setState(int newState) {
41         if (-3 > newState || newState > 3) {
42             throw new IllegalArgumentException("New state must be between -3 and 3.");

```

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32   */
33  public Rover(int state) {
34      this.state = state;
35  }
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37  /** Sets state of rover to new specified state.
38   * @param newState new state of rover.
39   */
40  public void setState(int newState) {
41      if (-3 > newState || newState > 3) {
42          throw new IllegalArgumentException("New state must be between -3 and 3.");
43      }
44      state = newState;
45  }
46
47  /** Returns state of rover as a string.
48   * @return state of rover.
49   */
50  public String printState() {
51      return switch (state) {
52          case (0) -> "rest";
53          case (1) -> "deaccelerate forward";
54          case (2) -> "accelerate forward";
55          case (3) -> "constant forward speed";
56          case (-1) -> "deaccelerate backward";
57          case (-2) -> "accelerate backward";
58          case (-3) -> "constant backward speed";
59          default -> "no current states";
60      };
61  }
62  }

```

```
/** A class representing pedals and their different behaviours.
 * @since 1.0
 * @version 3.0
 * @author Ludovic Provost
 */

public class Pedal {

    /** The placement (left or right) of pedal.
     * Makes the placement easily accessible.
     */
    String leftOrRight;

    /** Creates pedal with the specified placement.
     * @param leftOrRight the placement.
     */
    public Pedal(String leftOrRight) {
        if (leftOrRight == null || !(leftOrRight.equals("L") || leftOrRight.equals("R"))) {
            throw new IllegalArgumentException("The String must be R or L");
        }
        this.leftOrRight = leftOrRight;
    }

    /** The method returns the new state of the rover in the form of an int
     * based on the given number of presses and the rover's current state.
     * @param numberOfPresses number of presses on pedal.
     * @param state current state of rover.
     * @return new state of rover.
     */
    public int press(int numberOfPresses, int state) {

        if (numberOfPresses > 2 || numberOfPresses == 0) {
            throw new IllegalArgumentException("Invalid number of presses.");
        }
        if (numberOfPresses == 1 && state == 0 && leftOrRight.equals("L")) {
            return 2;
        } else if (numberOfPresses == 2 && leftOrRight.equals("R")) {
            if (state == 2) {
                return 1;
            } else if (state == -2) {
                return -1;
            }
        }
    }
}
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    } else if (numberOfPresses == 2 && leftOrRight.equals("R")) {
        if (state == 2) {
            return 1;
        } else if (state == -2) {
            return -1;
        }
    } else {
        throw new IllegalArgumentException("Your number of presses does nothing.");
    }
    System.out.print("Your number of presses does nothing. ");
    return state;
}

/** The method returns the new state of the rover in the form of an int based on the
 *  given number of seconds the pedal has been pressed and the rover's current state.
 *  @param numberOfSeconds number of seconds the pedal is pressed.
 *  @param state current state of rover.
 *  @return new state of rover.
 */
public int hold(int numberOfSeconds, int state) {
    if (numberOfSeconds != 5) {
        throw new IllegalArgumentException("The number of seconds must be 5.");
    }
    if (numberOfSeconds == 5) {
        if (state == 0 && leftOrRight.equals("L")) {
            return -2;
        } else if ((state == -1 || state == -2) && leftOrRight.equals("R")) {
            return -3;
        } else if ((state == 1 || state == 2) && leftOrRight.equals("R")) {
            return 3;
        } else {
            throw new IllegalArgumentException("Your number of seconds does nothing.");
        }
    }
    System.out.print("Your number of seconds does nothing. ");
    return state;
}
}

```