

M2 Splines Package

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M2 Workshop
Boise State University

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Piecewise Polynomials

- ▶ \mathcal{P} : subdivision of a simply-connected domain $\Omega \subset \mathbb{R}^n$ by convex polytopes (polytopal complex)

Piecewise Polynomials

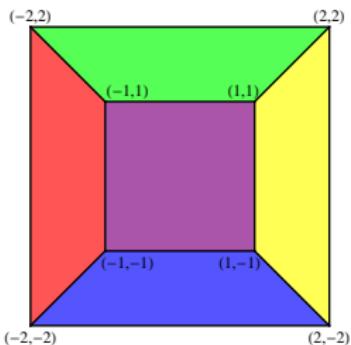
- ▶ \mathcal{P} : subdivision of a simply-connected domain $\Omega \subset \mathbb{R}^n$ by convex polytopes (polytopal complex)
- ▶ $C^r(\mathcal{P})$: all functions $F : \Omega \rightarrow \mathbb{R}$, continuously differentiable of order r , whose restriction to each part of the subdivision \mathcal{P} is a **polynomial**. F is called an **r -spline** (or just a spline).

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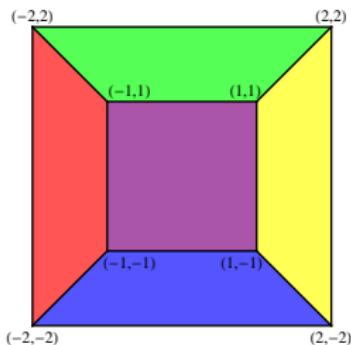
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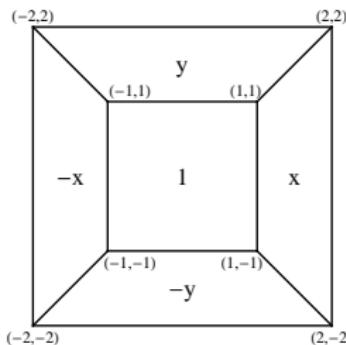
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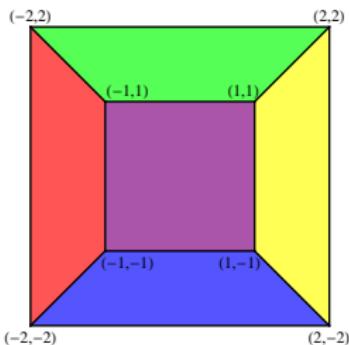
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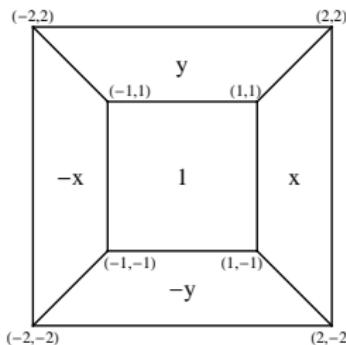
A Spline $F \in C_1^0(\mathcal{Q})$

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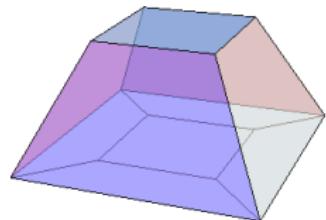
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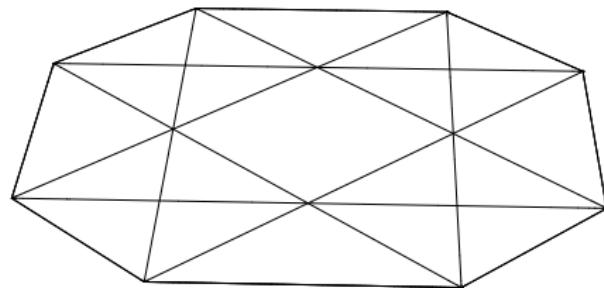


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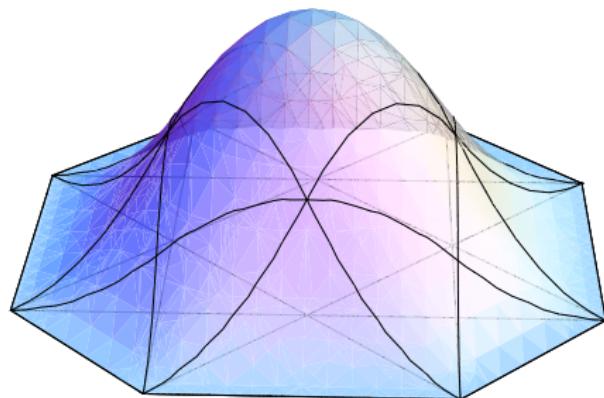
Graph of F

A More Interesting Example



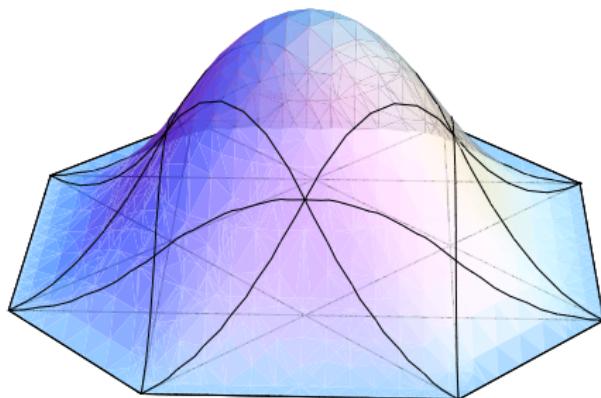
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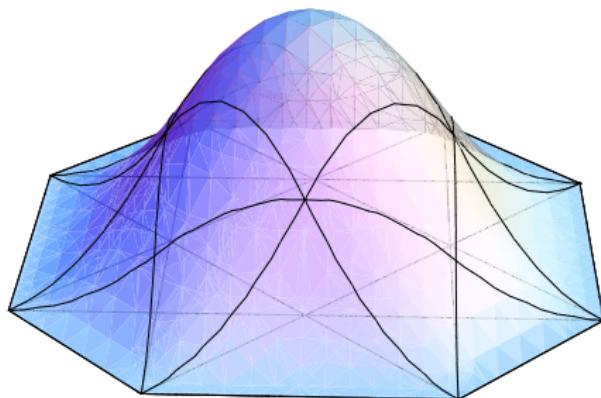
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- ▶ Graph of the **Zwart-Powell element**: a spline in $C_2^1(\mathcal{P})$.
- ▶ Twenty-seven polynomials fit together to form this spline.
- ▶ This is an example of a **box spline**.

Polynomials of ZP Element

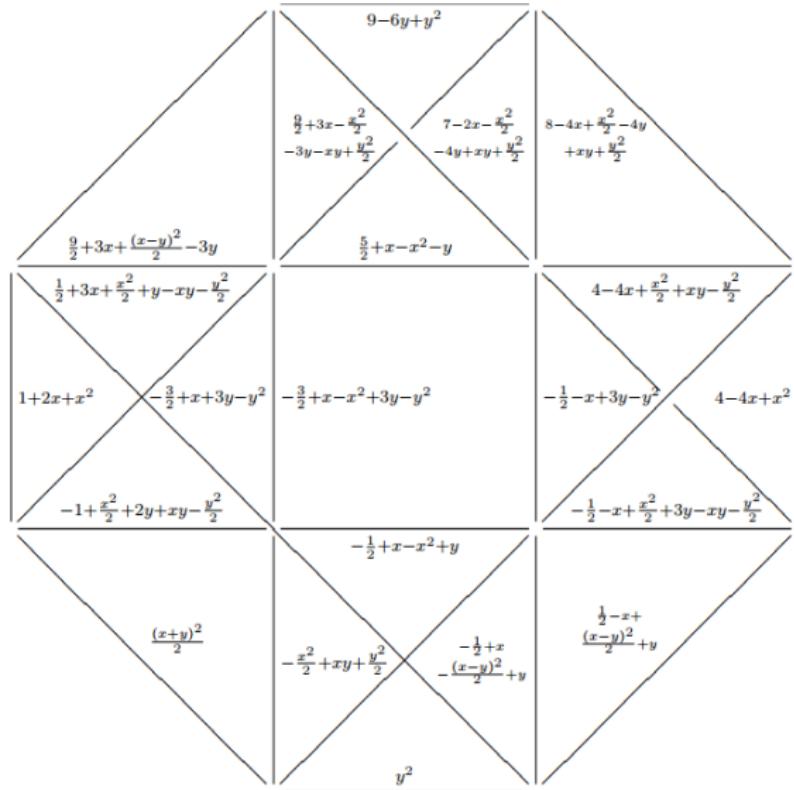
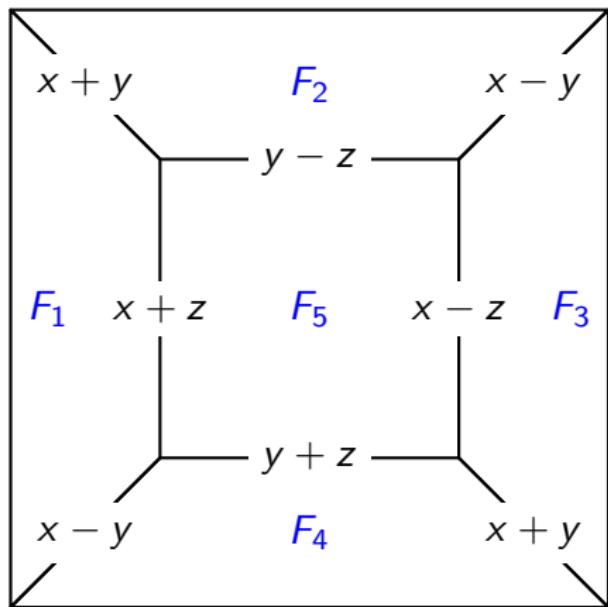
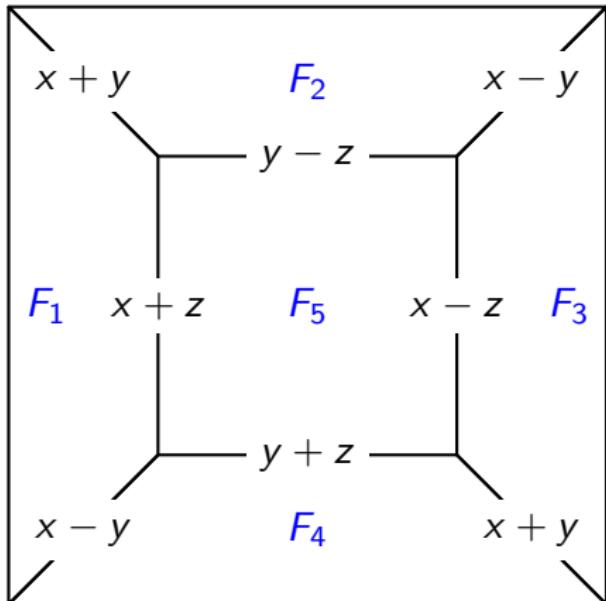


Image taken from C. Procesi, 'The algebra of the box-spline,' Temple University, 2006.

Algebraic Criterion



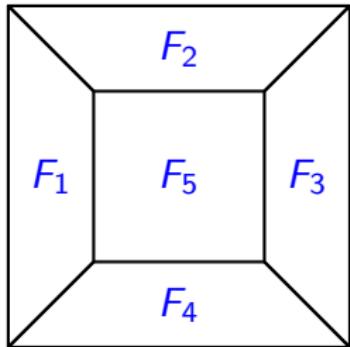
Algebraic Criterion



$(F_1, F_2, F_3, F_4, F_5) \in C^r(\hat{\mathcal{Q}}) \iff$
there are
 $f_1, \dots, f_8 \in S = \mathbb{R}[x, y, z]$ s.t.

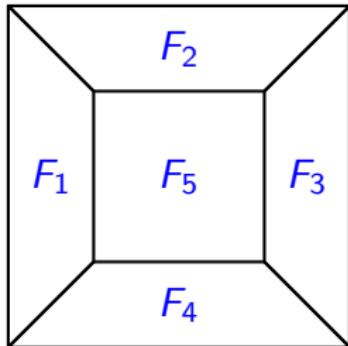
$$\begin{aligned}F_1 - F_2 &= f_1(x+y)^{r+1} \\F_2 - F_3 &= f_2(x-y)^{r+1} \\F_3 - F_4 &= f_3(x+y)^{r+1} \\F_4 - F_1 &= f_4(x-y)^{r+1} \\F_1 - F_5 &= f_5(x+z)^{r+1} \\F_2 - F_5 &= f_6(y-z)^{r+1} \\F_3 - F_5 &= f_7(x-z)^{r+1} \\F_4 - F_5 &= f_8(y+z)^{r+1}\end{aligned}$$

Spline Matrix for $C^r(\widehat{\mathcal{Q}})$



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$$\begin{pmatrix} 1 & -1 & 0 & 0 & 0 & (x-y)^{r+1} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & (x+y)^{r+1} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & (x-y)^{r+1} & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & (x+y)^{r+1} & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & (x+z)^{r+1} & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 & (y-z)^{r+1} & 0 \\ 0 & 0 & 1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & (x-z)^{r+1} \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & (x+z)^{r+1} \end{pmatrix} \begin{pmatrix} F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ -f_1 \\ -f_2 \\ -f_3 \\ -f_4 \\ -f_5 \\ -f_6 \\ -f_7 \\ -f_8 \end{pmatrix} = 0$$

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Key Fact: $C_d^r(\mathcal{P})$ is a finite dimensional real vector space.

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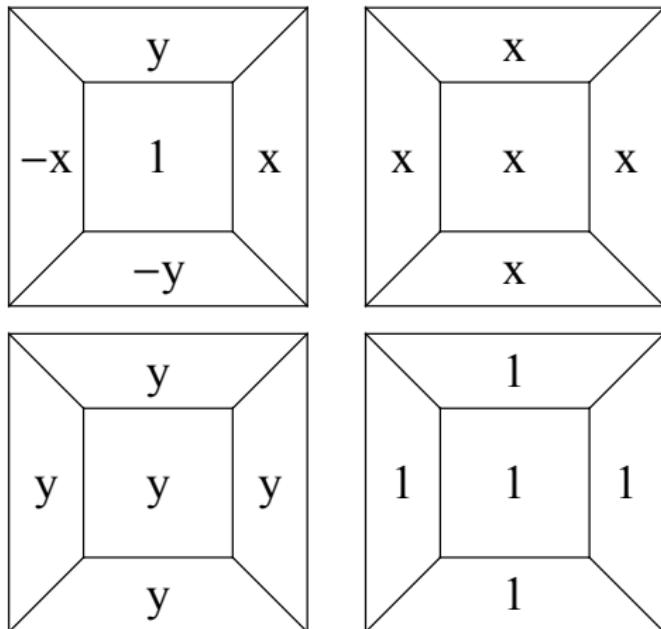
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$$\dim_{\mathbb{R}} C_1^0(\mathcal{Q}) = 4$$

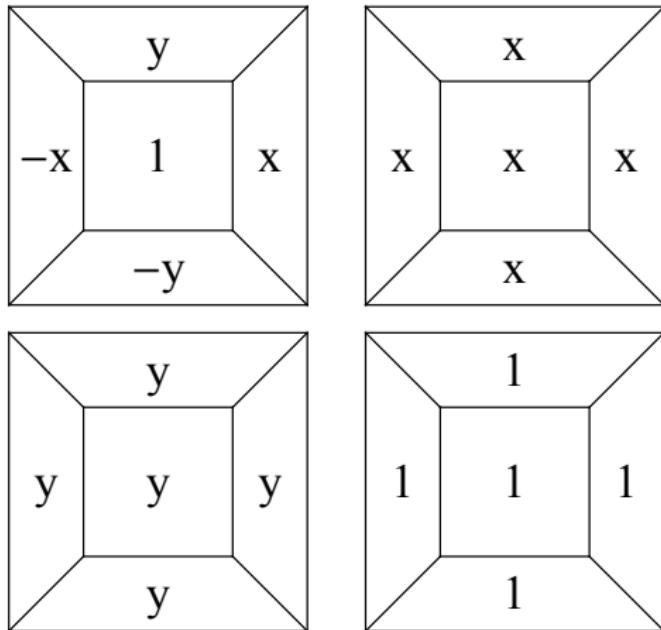


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Two central problems in approximation theory:

1. Determine $\dim C_d^r(\mathcal{P})$
2. Construct a basis of $C_d^r(\mathcal{P})$ with 'good' properties