

# Real-Time Outlier Detection with Dynamic Process Limits

## Process Control 2023

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## 1 Motivation

## 2 Gaps in Existing Solutions

## 3 Proposed Approach

## 4 Results

## 1 Motivation

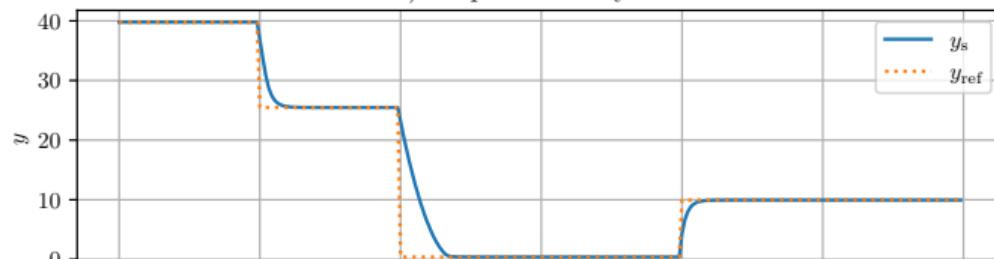
## 2 Gaps in Existing Solutions

## 3 Proposed Approach

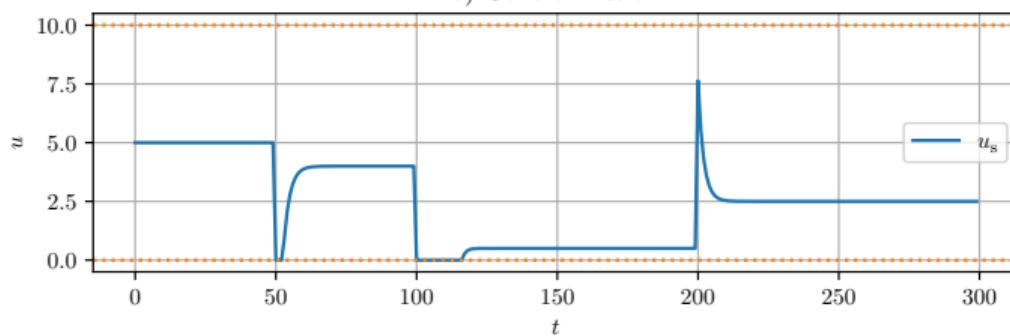
## 4 Results

# Simulation Results

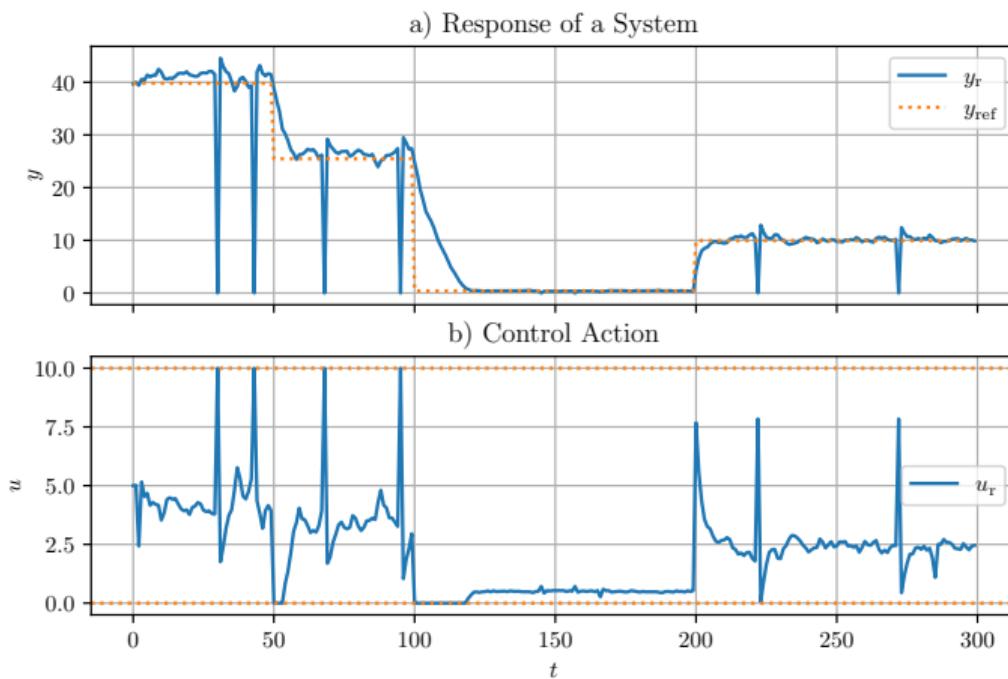
a) Response of a System



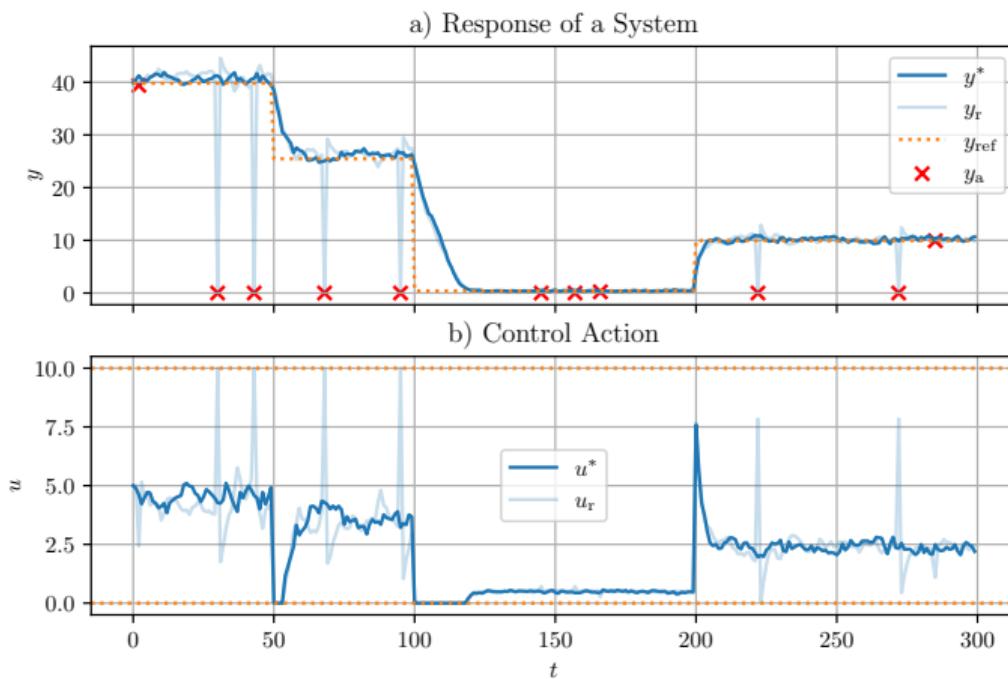
b) Control Action



## Practical Scenario



# Control Engineering meets Artificial Intelligence



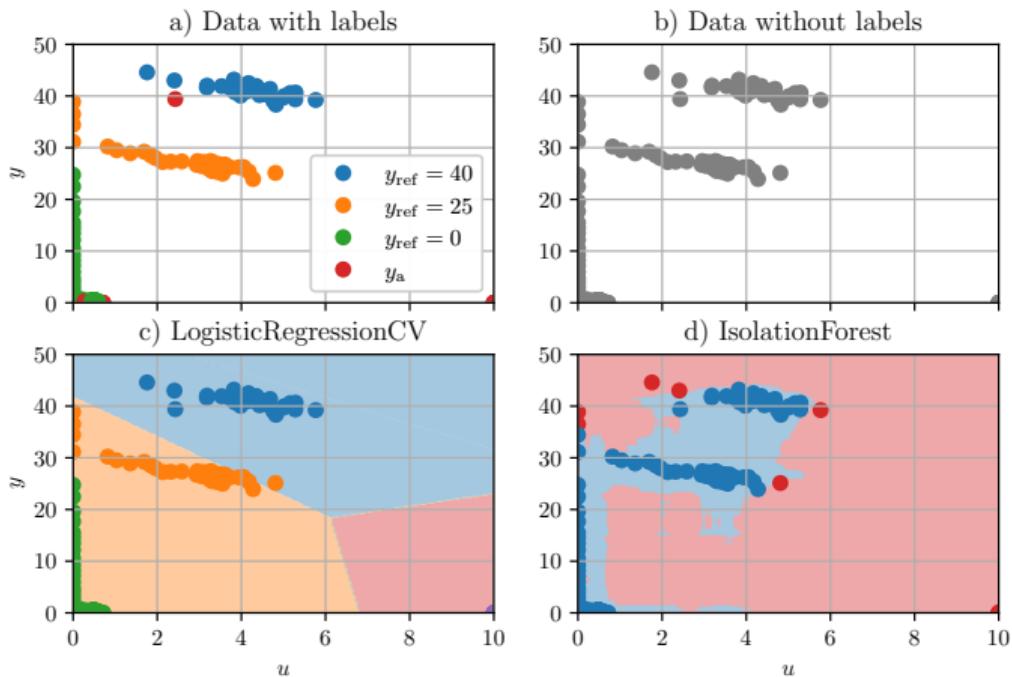
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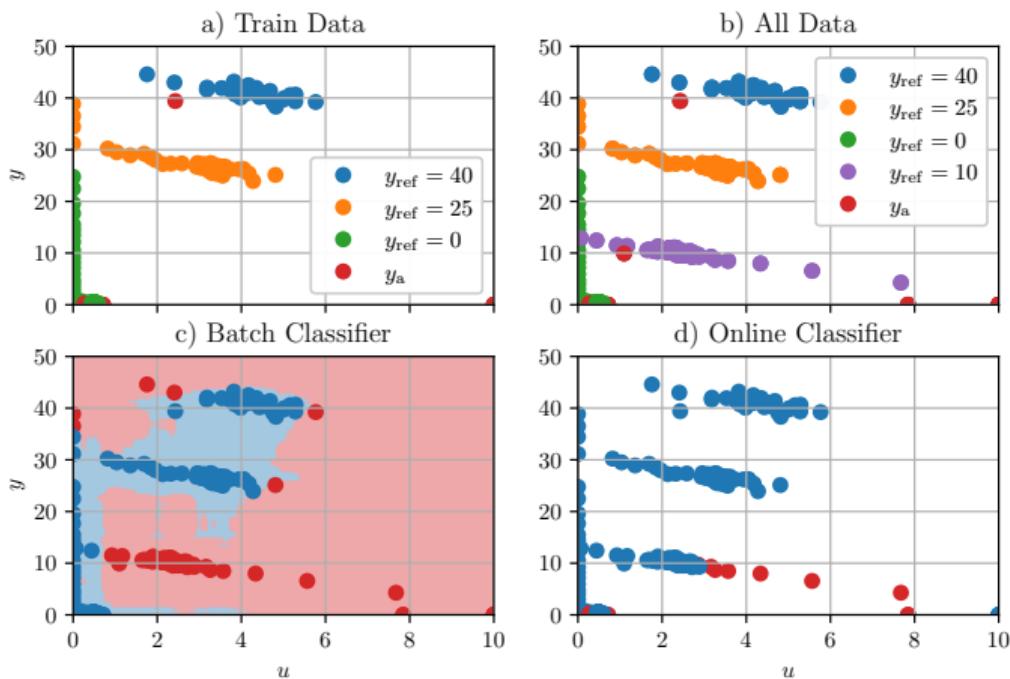
## 3 Proposed Approach

## 4 Results

# Lack of Labels



## Changes in Distribution



# Goals

We need to make detector that:

- Does not require huge amount of data
- Adapts to unseen operation
- Offers credible decision boundary
- Does not alter operation of existing systems

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Methodology

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# Proposed Solution

Real-Time Outlier Detection with Dynamic Process Limits combining:

- Online Learning
- Outlier Detection
- Self-supervised Learning
- Soft Real-Time System
- Invertible Probabilistic Model

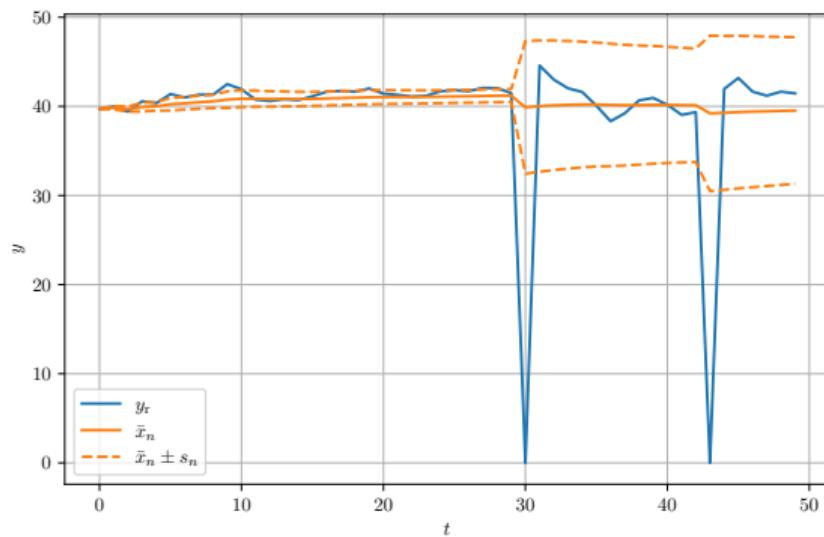
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## 3 Proposed Approach Methodology

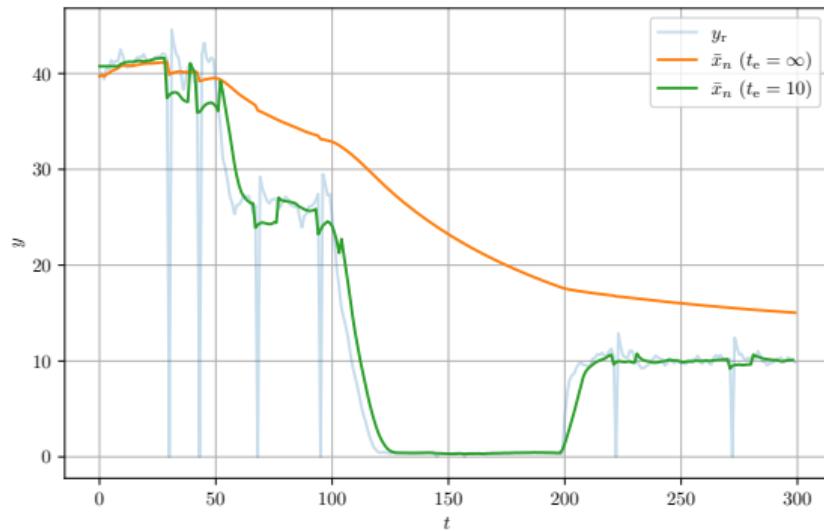
## 4 Results

# Welford Algorithm



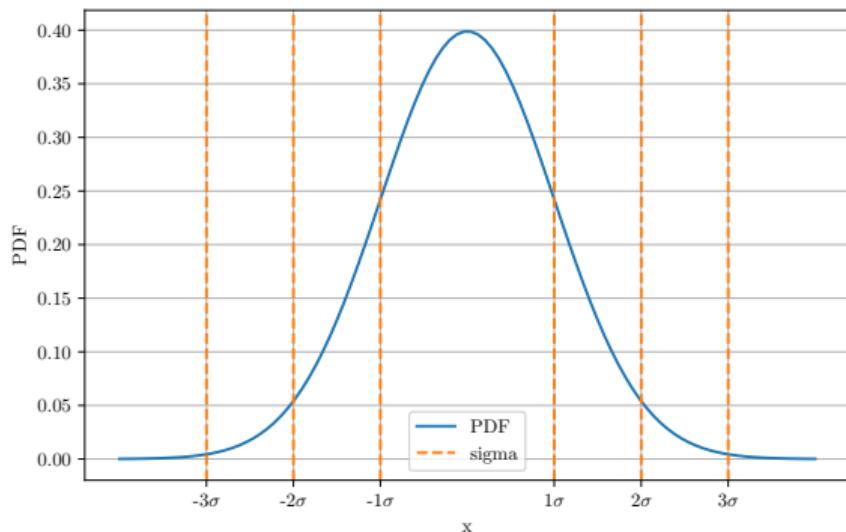
+ One-Pass Algorithm | - Adaptation Slows Down

# Inverse Welford Algorithm



+ Constant Adaptation | - Memorizes Data Window

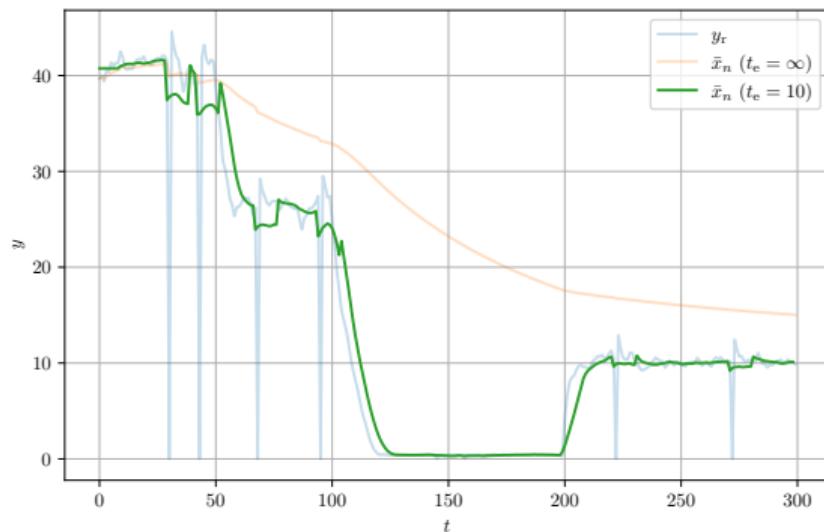
# Distance-based Outlier Detection



$$y_i = \begin{cases} 0 & \text{if } q \leq F_X(x_i; \bar{x}_n, s_n) \\ 1 & \text{if } q > F_X(x_i; \bar{x}_n, s_n) \end{cases} \quad (1a)$$

$$(1b)$$

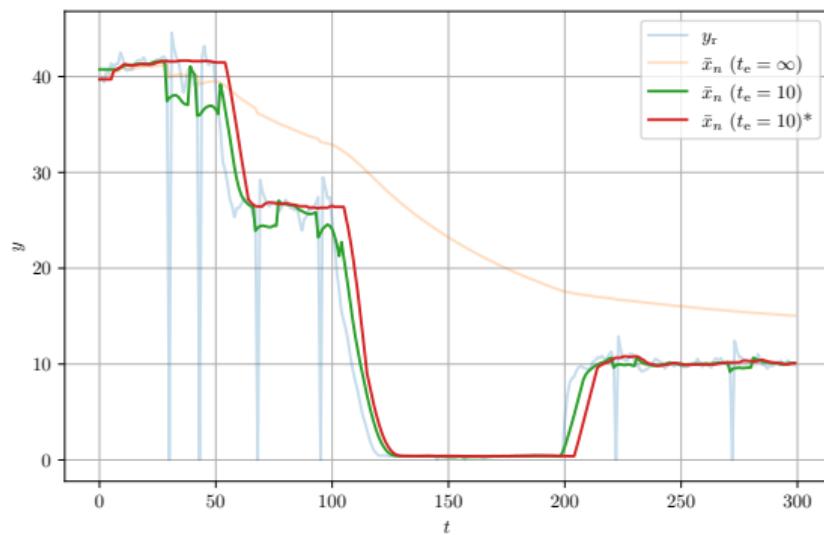
# Self-Supervised Learning



$$y_i = \begin{cases} 0 & \text{if } q \leq F_X(x_i; \bar{x}_n, s_n) \\ 1 & \text{if } q > F_X(x_i; \bar{x}_n, s_n) \end{cases} \quad (1a)$$

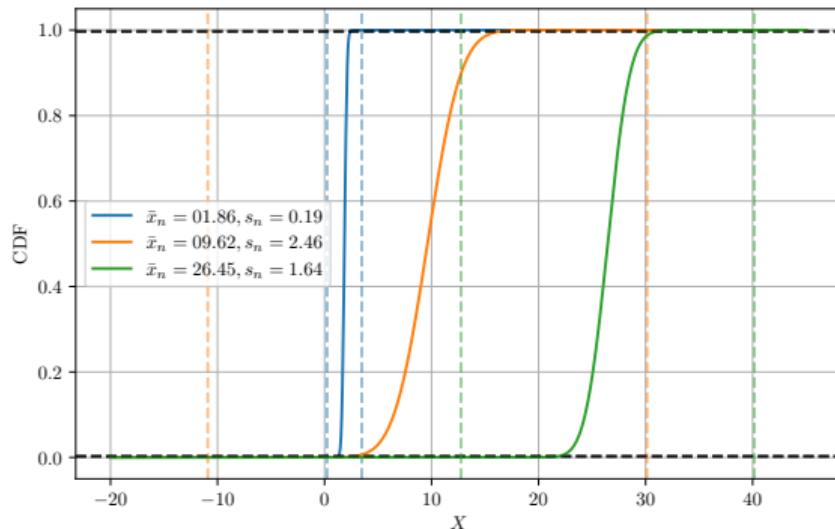
$$(1b)$$

# Self-Supervised Learning



$$\frac{\sum_{y \in Y} y}{n(Y)} > q \quad (3)$$

## Inversion of CDF



$$x_1 = F_X(1 - q; \bar{x}_n, s_n)^{-1}$$

$$x_u = F_X(q; \bar{x}_n, s_n)^{-1}$$

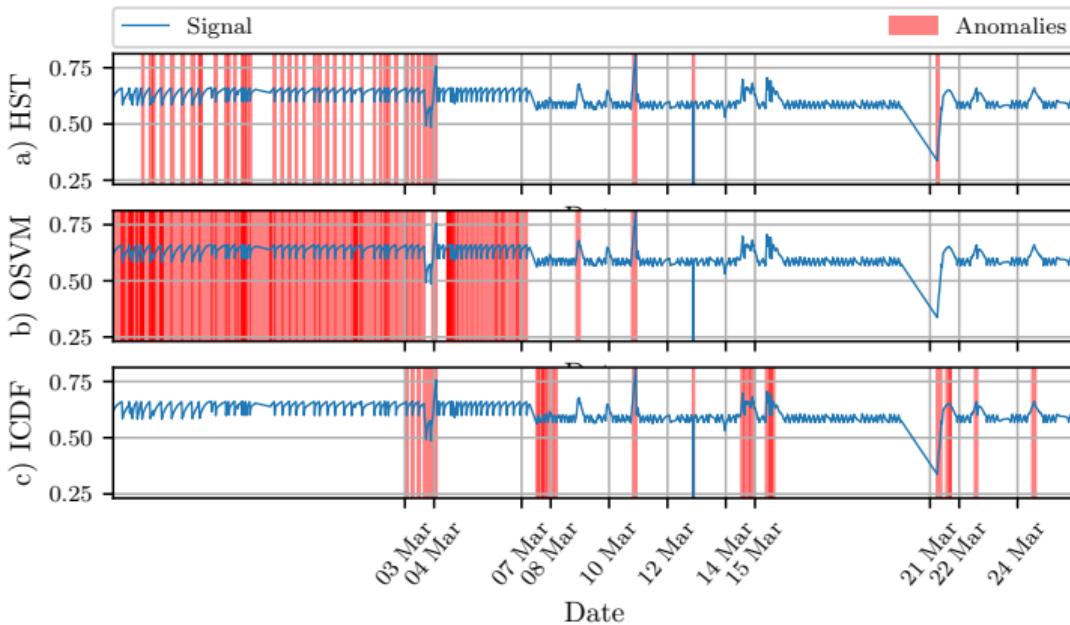
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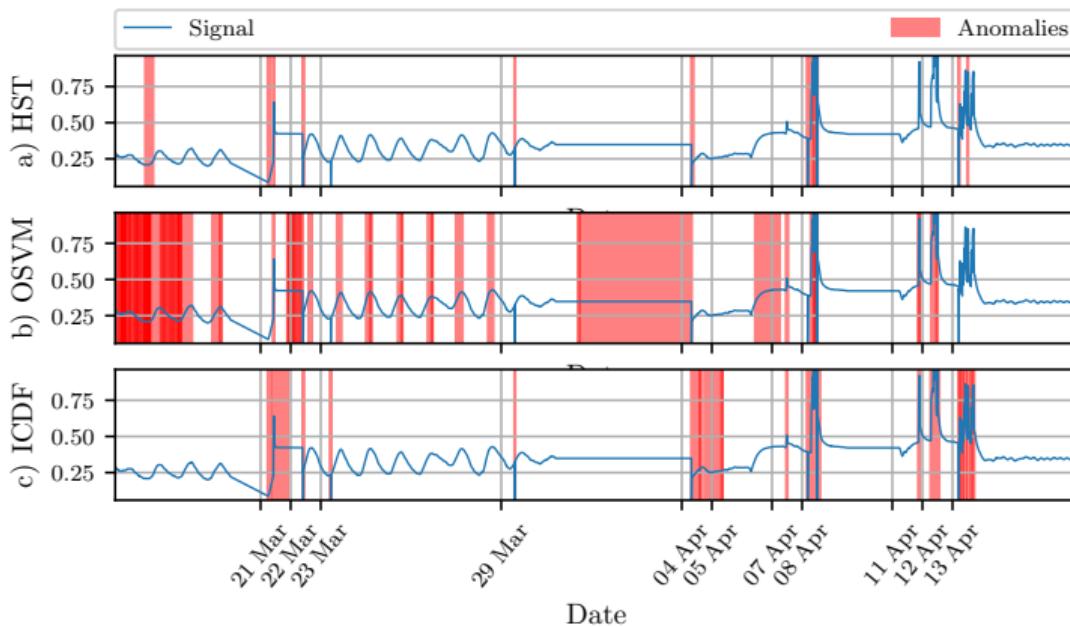
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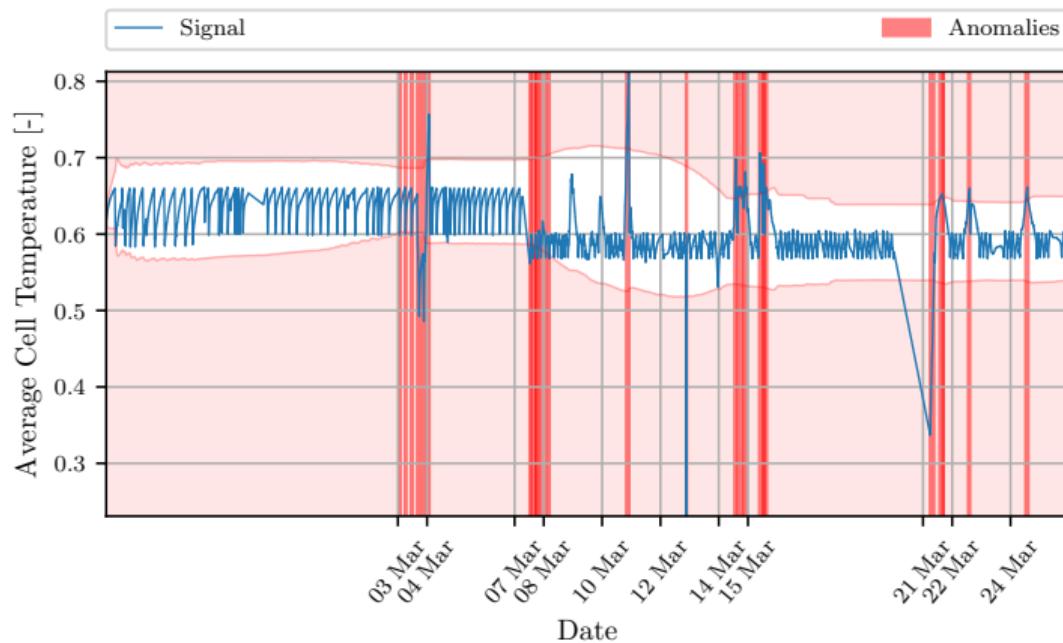
## ICDF-based Outlier Detection - BESS



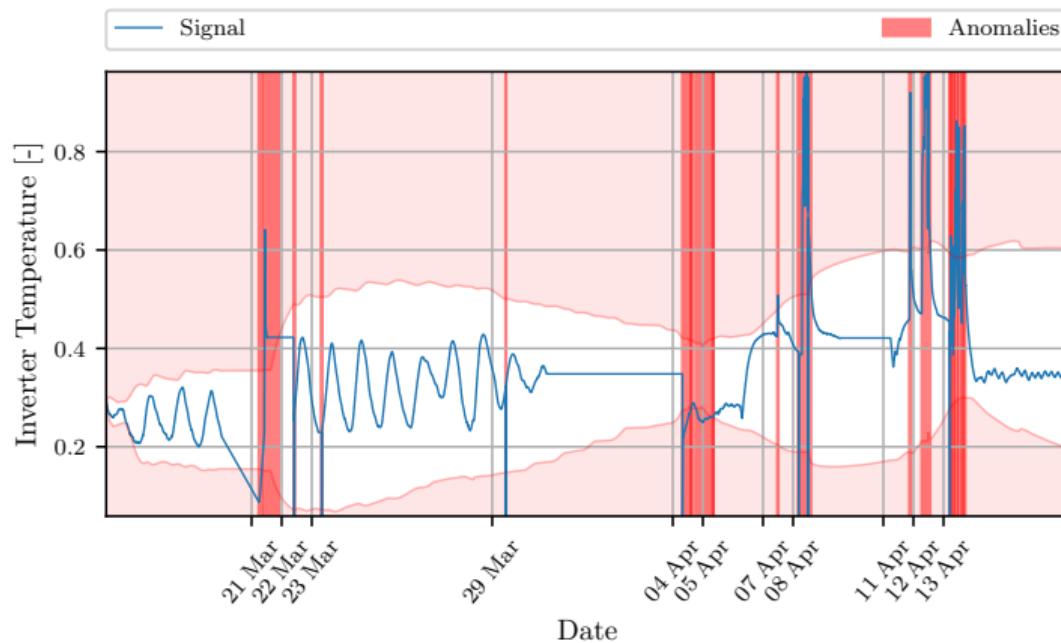
## ICDF-based Outlier Detection - Inverter



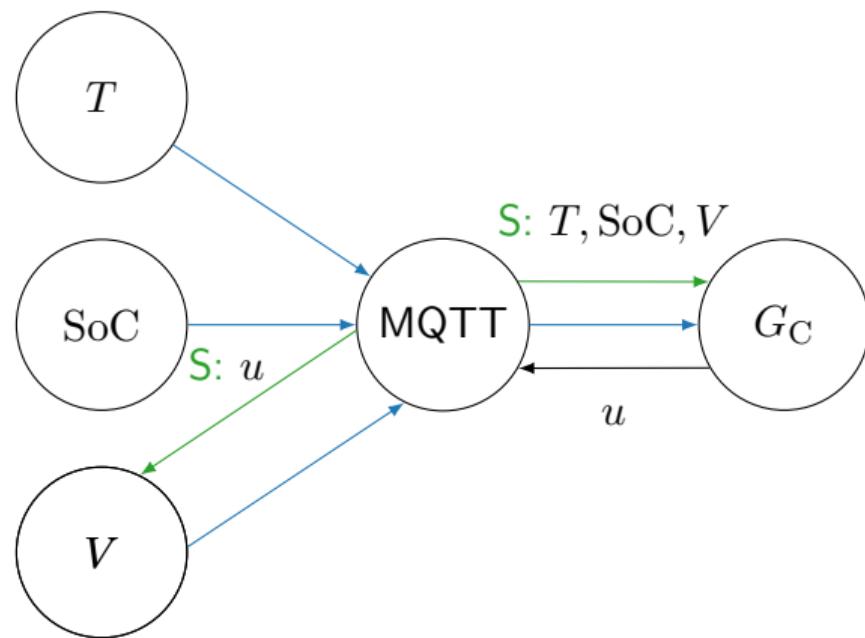
# Dynamic Process Limits



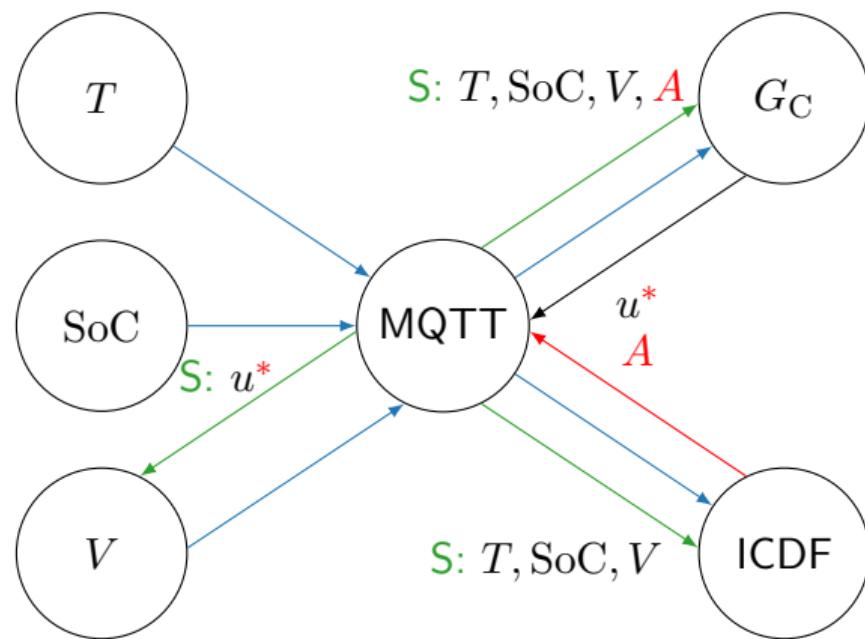
# Dynamic Process Limits



# Utilize Existing Infrastructure



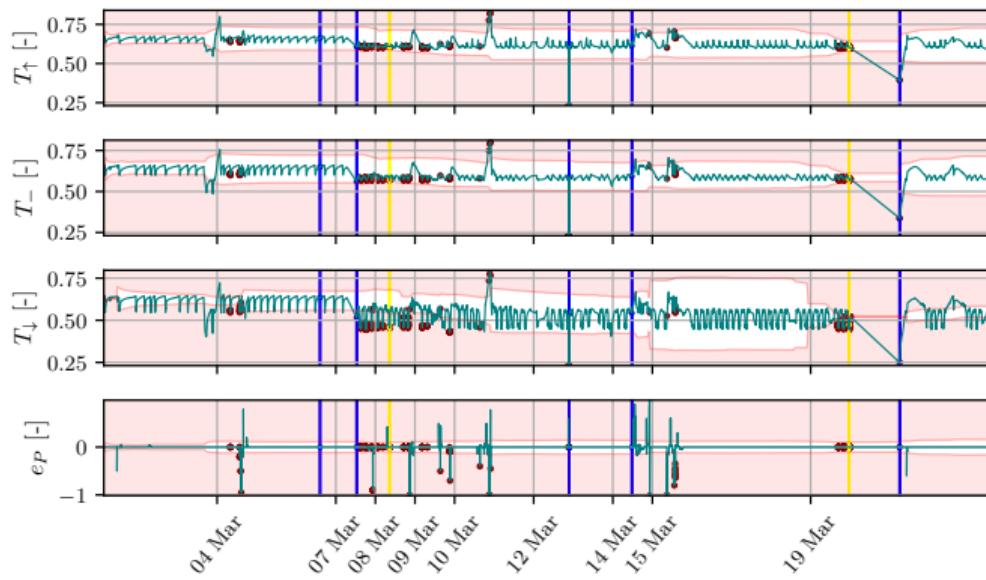
# Utilize Existing Infrastructure



## Summary

- Automated alerting without prior knowledge of process limits
- Assessment of environmental conditions and device aging
- Self-learning approach using streamed data
- Automated alerting threshold setup for multiple signals
- Seamless integration with existing IT infrastructure

## Follow-up research



1

<sup>1</sup> M. Wadinger and M. Kvasnica. Adaptable and interpretable framework for novelty detection in real-time iot systems. In Proceedings of the 62nd IEEE CDC, Singapore, 2023. under review.

# Online Anomaly Detection Workflow

**Input:** expiration period  $t_e$ , time constant  $t_c$

**Output:** score  $y_i$ , threshold  $x_{q,i}$

*Initialisation :*

- 1:  $i \leftarrow 1; n \leftarrow 1; q \leftarrow 0.9973; \bar{x} \leftarrow x_0; s^2 \leftarrow 1;$
- 2: compute  $F_X(x_0)$  ;

*LOOP Process*

3: **loop**

4:    $x_i \leftarrow \text{RECEIVE}();$

5:    $y_i \leftarrow \text{PREDICT}(x_i) ;$

6:    $x_{q,i} \leftarrow \text{GET}(q, \bar{x}, s^2);$

7:   **if** (1a) **or** (3) **then**

8:      $\bar{x}, s^2 \leftarrow \text{UPDATE}(x_i, \bar{x}, s^2, n);$

9:      $n \leftarrow n + 1;$

10:    **for**  $x_{i-t_e}$  **do**

11:       $\bar{x}, s^2 \leftarrow \text{REVERT}(x_{i-t_e}, \bar{x}, s^2, n);$

12:       $n \leftarrow n - 1;$

13:    **end for**

14:   **end if**

15:    $i \leftarrow i + 1;$

16: **end loop**