

Real-Time Outlier Detection with Dynamic Process Limits

Process Control 2023

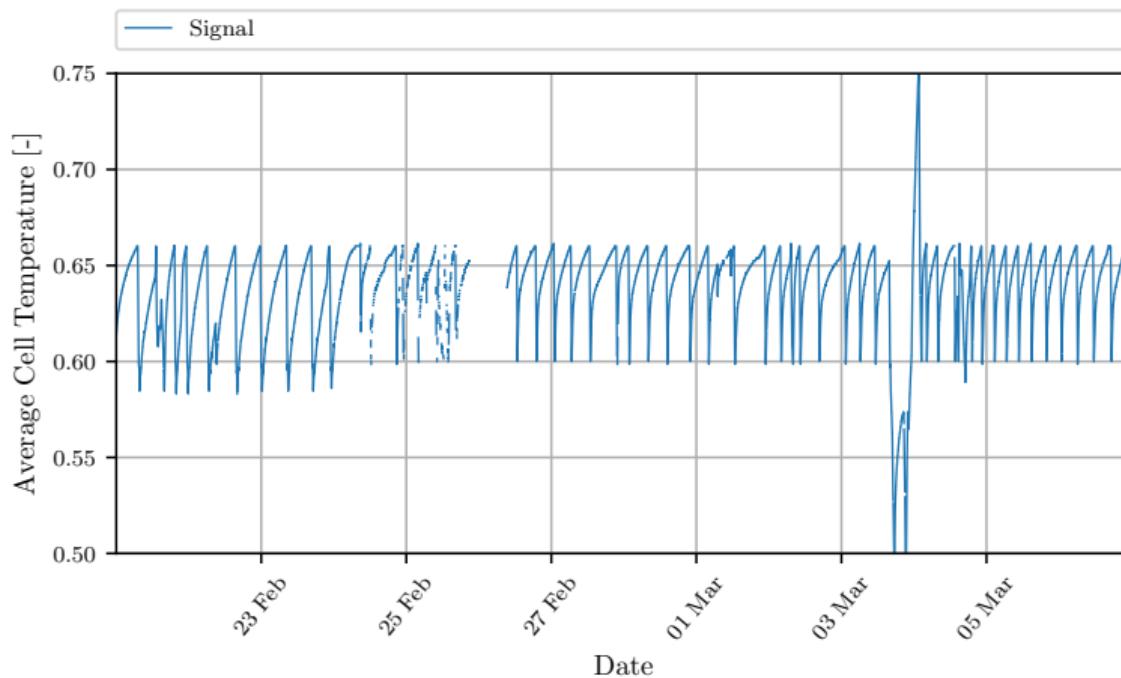
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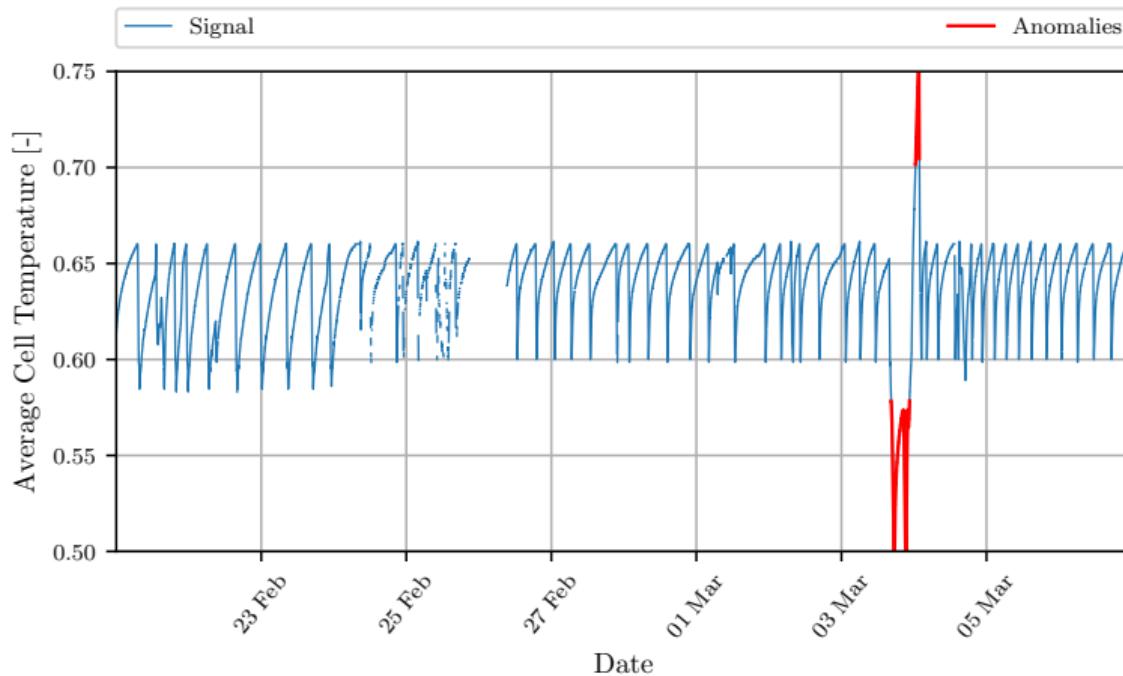


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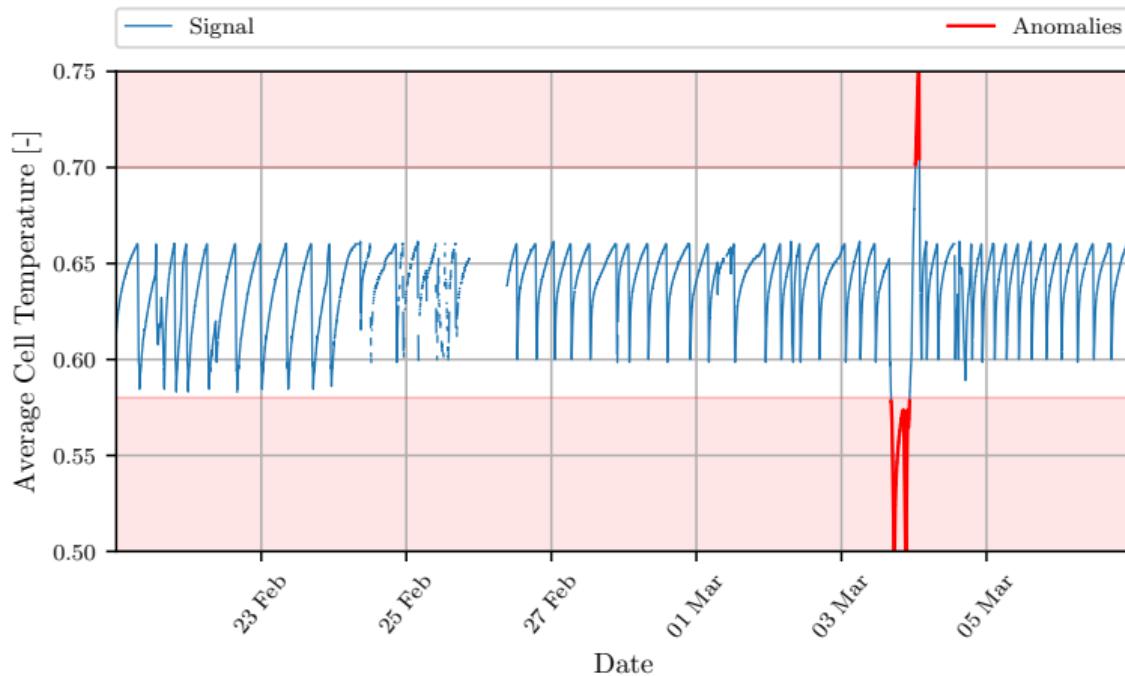
Real World Data



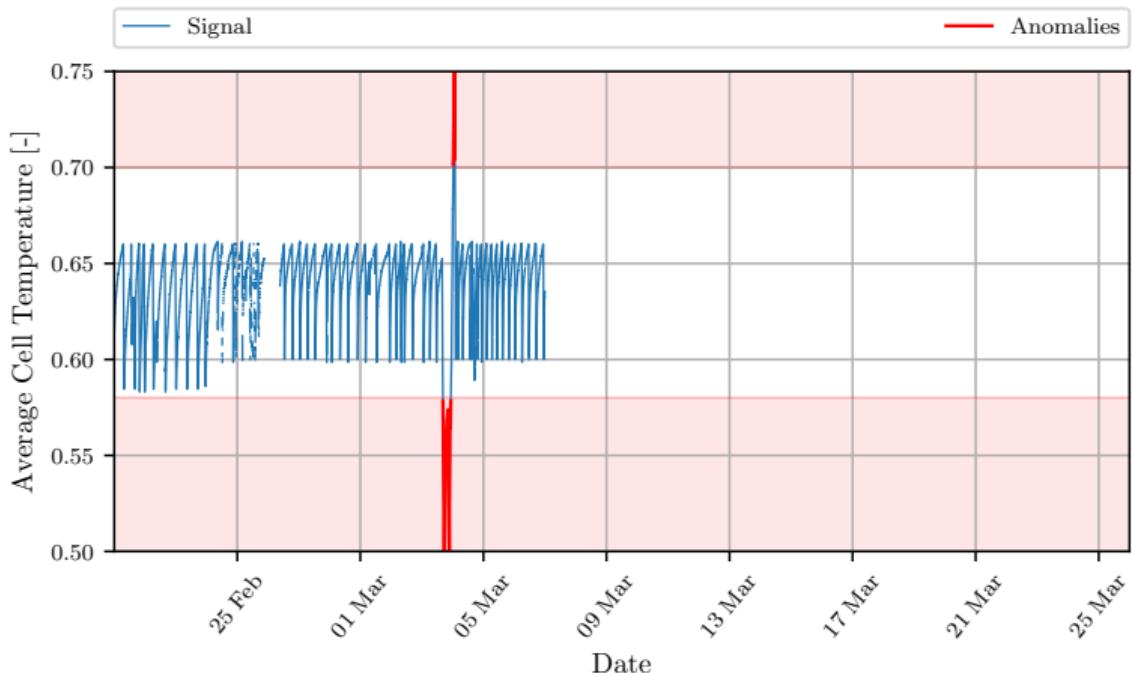
Data with Outliers



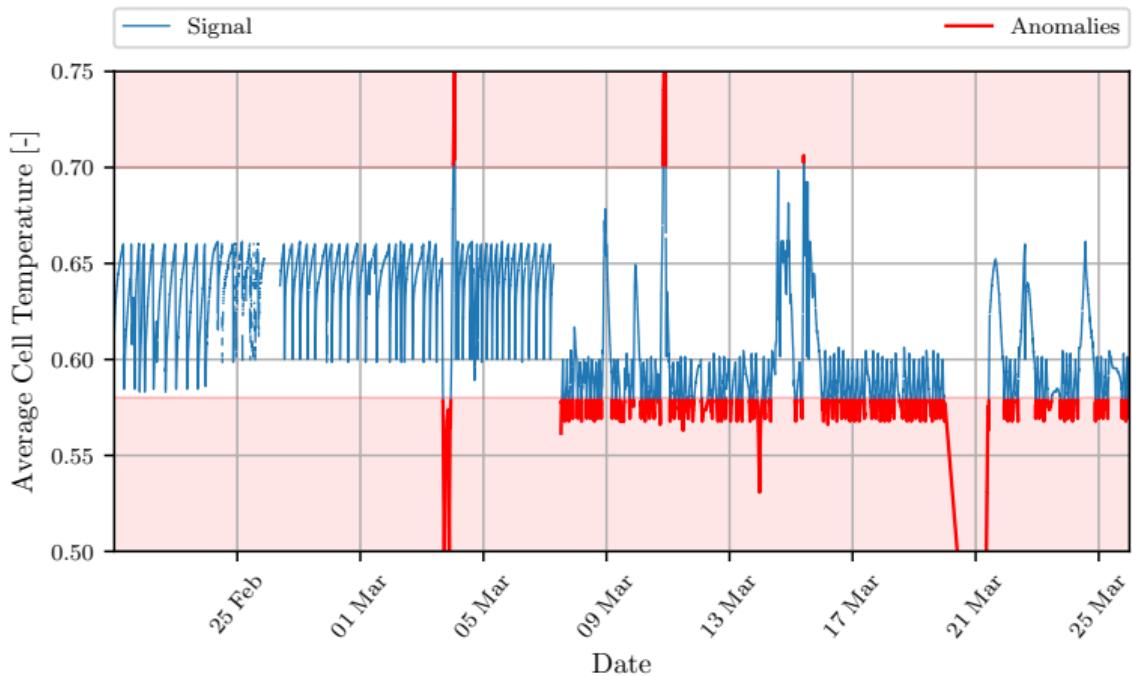
Static Threshold Limits



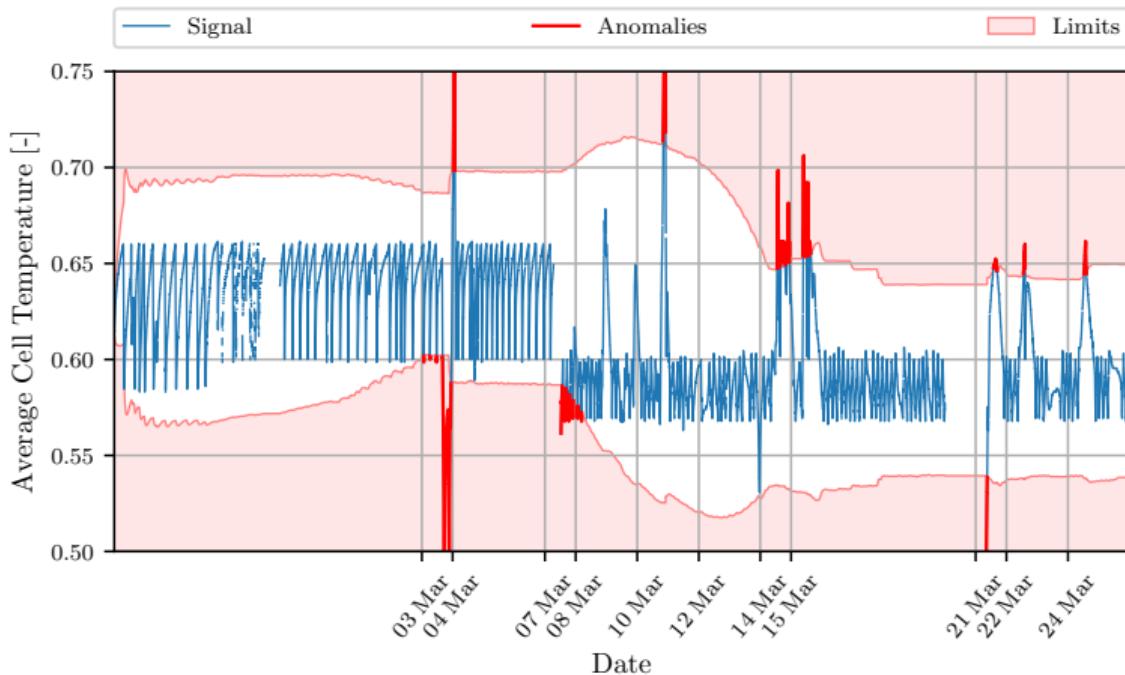
Static Threshold Limits



Comming Problem



Control Engineering Meets Artificial Intelligence



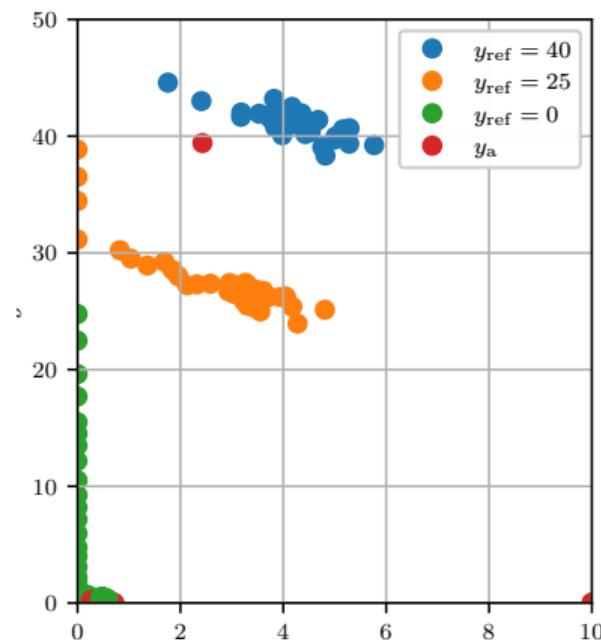
Goals

We need to design a detector that:

- adapts to unseen operation
- provides conservative process limits
- operates with existing infrastructure

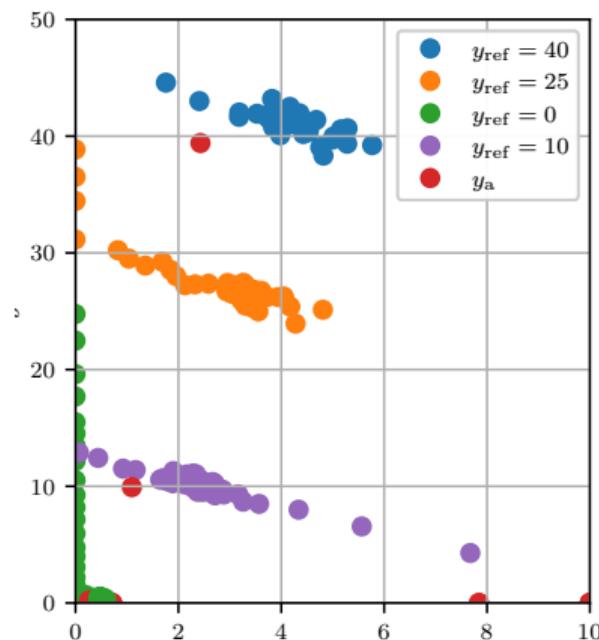
Challenges

- need for training data



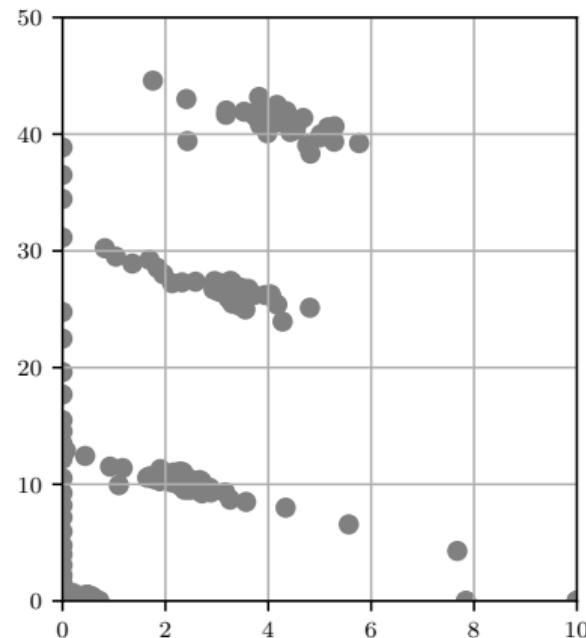
Challenges

- need for training data
- changes in operation regime



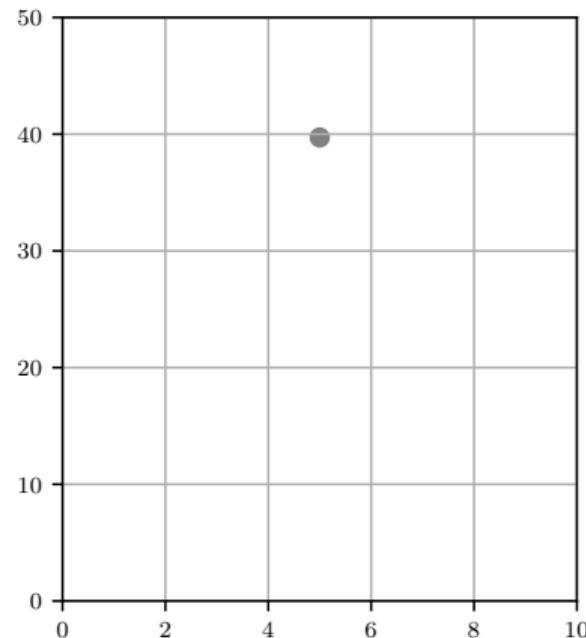
Challenges

- need for training data
- changes in operation regime
- unavailability of labels



Challenges

- need for training data
- changes in operation regime
- unavailability of labels
- no storage of historical data

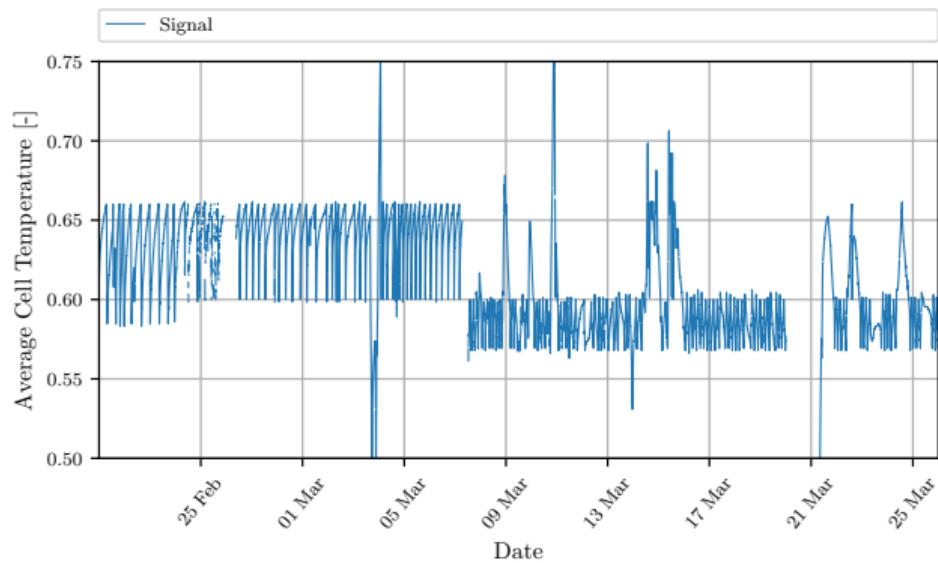


Proposed Solution

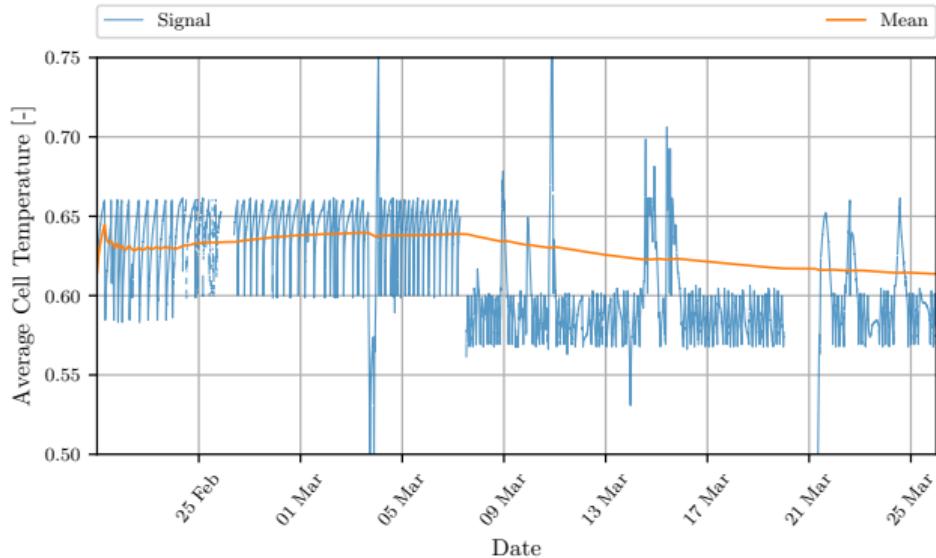
Real-Time Outlier Detection with Dynamic Process Limits combining:

- online learning
- invertible probabilistic model
- outlier detection
- self-supervised learning

Real Operation Data

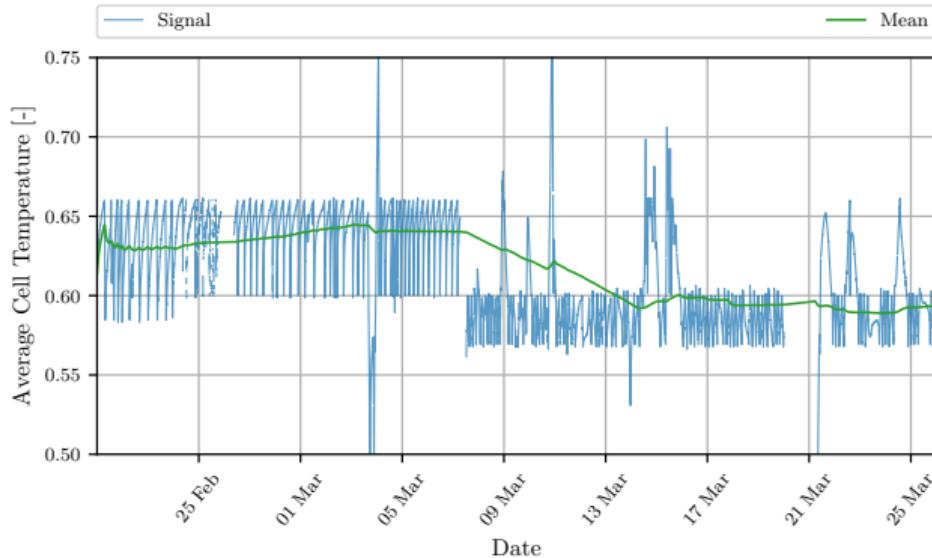


Online Learning via Welford Algorithm



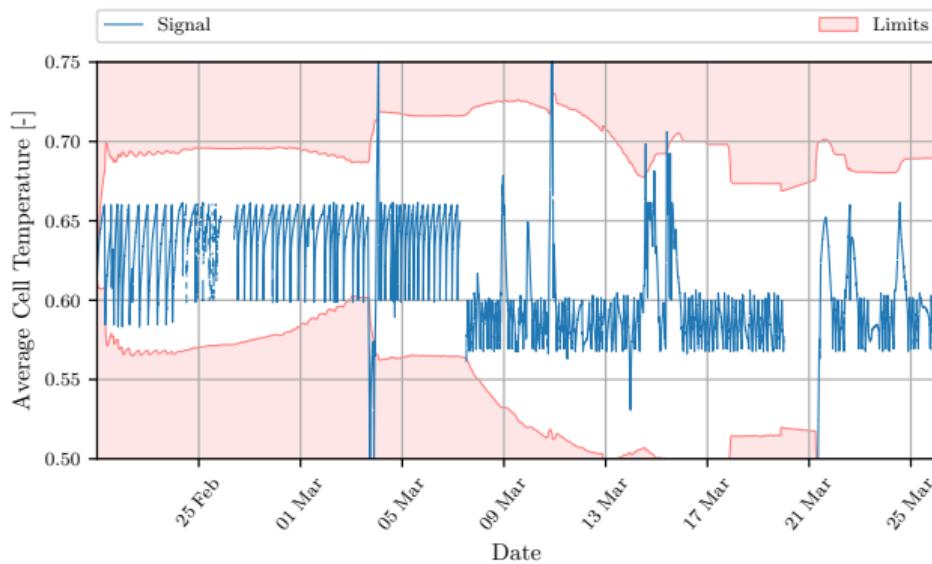
+ One-Pass Algorithm | - Adaptation Slows Down

Online Learning via Invertible Welford Algorithm



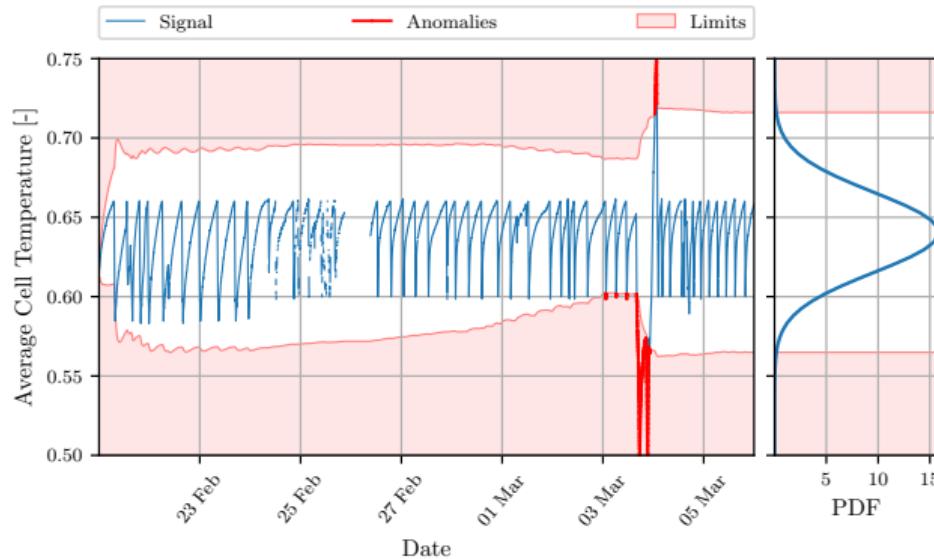
+ Constant Adaptation | - Memorizes Data Window

Dynamic Threshold Limits via Inversion



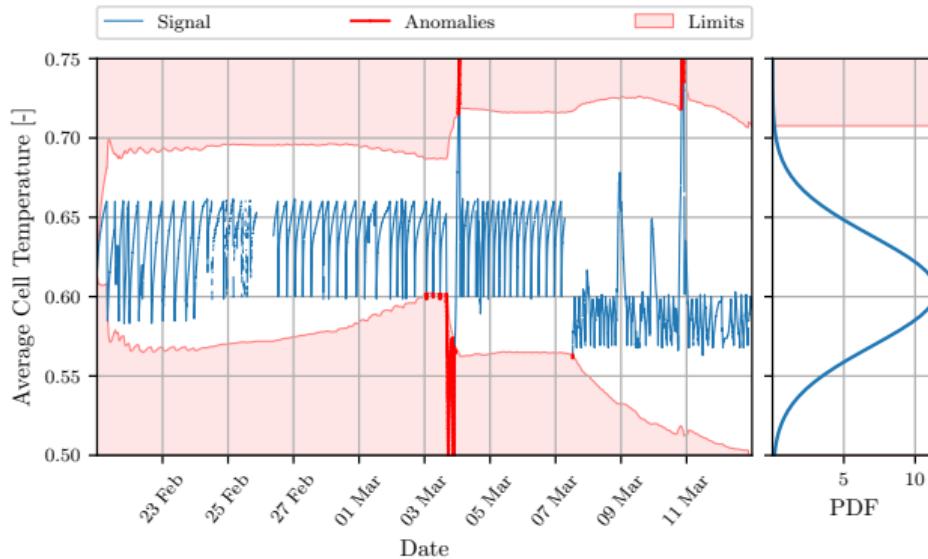
$$x_1 = F_X(1 - q; \bar{x}_n, s_n)^{-1}$$
$$x_u = F_X(q; \bar{x}_n, s_n)^{-1}$$

Distance-based Outlier Detection



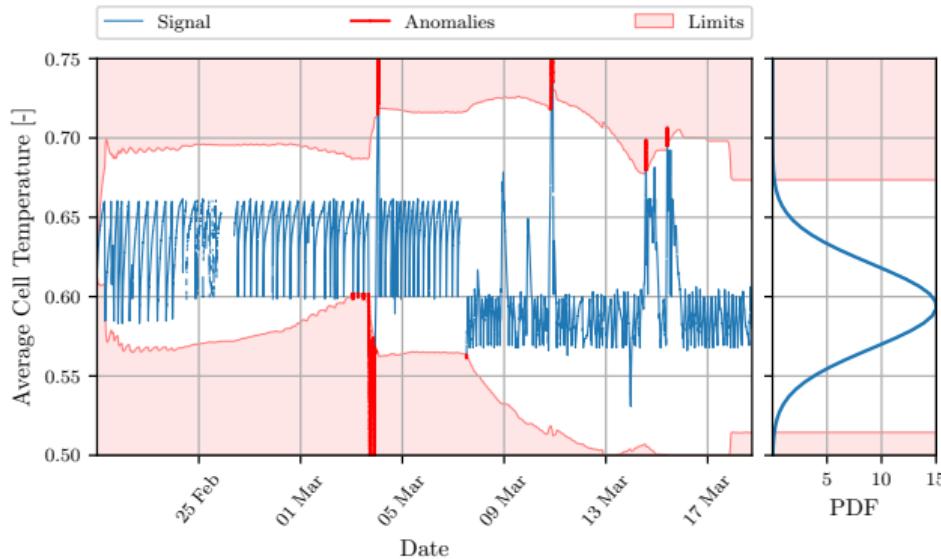
$$y_i = \begin{cases} 0 & \text{if } q \leq F_X(x_i; \bar{x}_n, s_n) \\ 1 & \text{if } q > F_X(x_i; \bar{x}_n, s_n) \end{cases}$$

Distance-based Outlier Detection



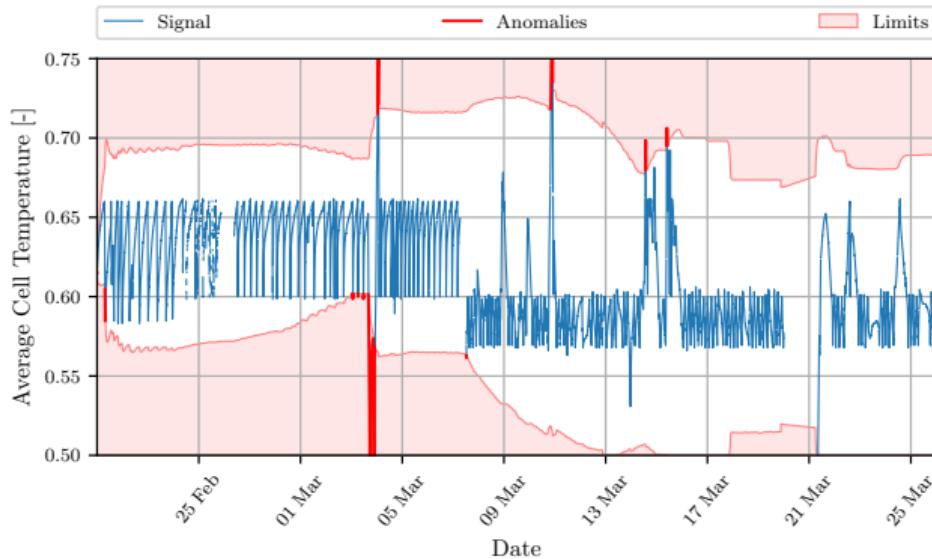
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Distance-based Outlier Detection



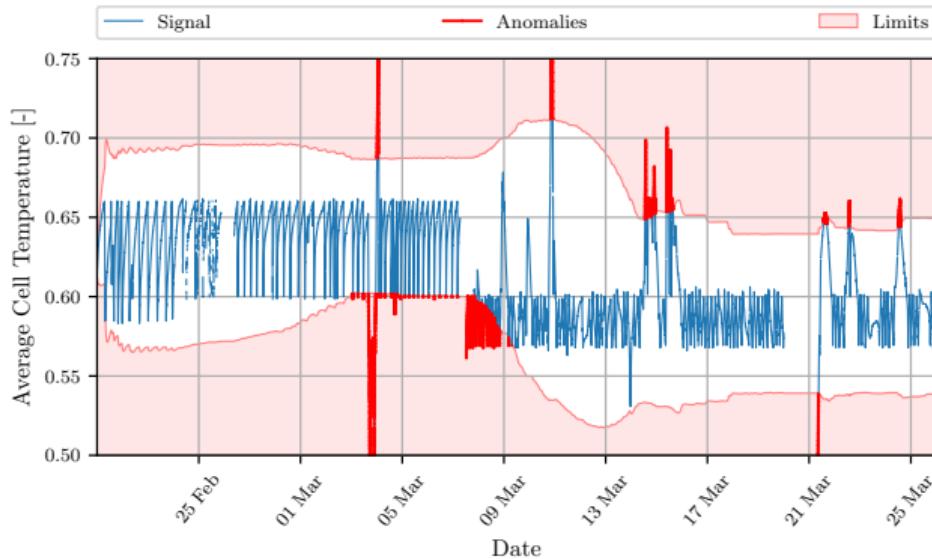
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Distance-based Outlier Detection



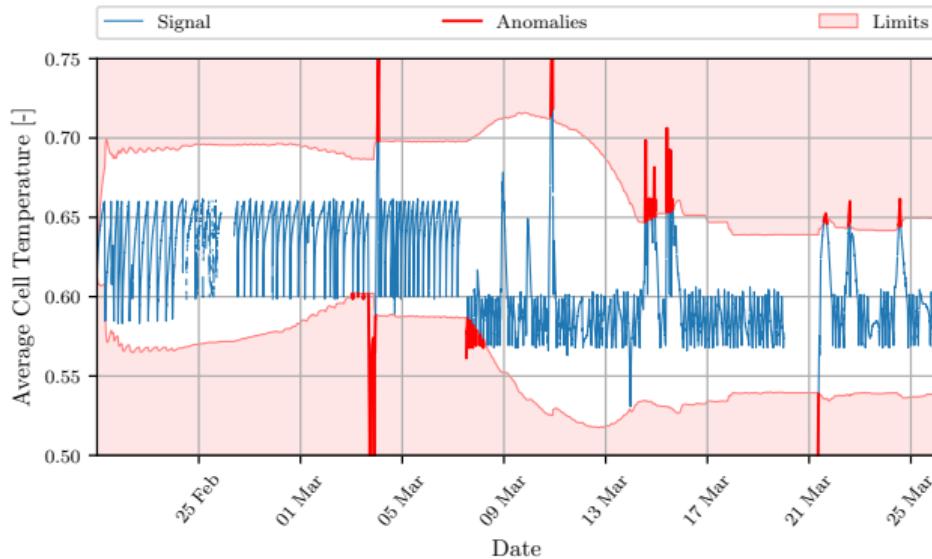
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Self-Supervised Learning



$$y_i = \begin{cases} 0 & \text{if } q \leq F_X(x_i; \bar{x}_n, s_n) \\ 1 & \text{if } q > F_X(x_i; \bar{x}_n, s_n) \end{cases}$$

Self-Supervised Learning – Faster Adaptation

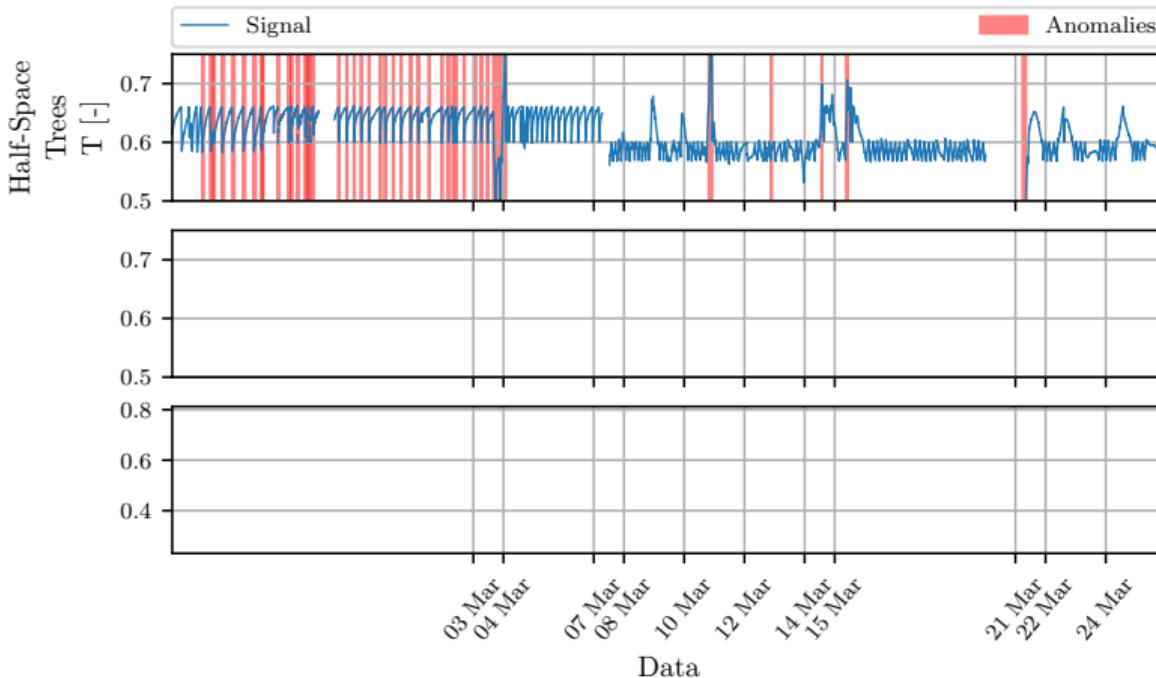


$$\frac{\sum_{y \in Y} y}{|Y|} > q$$

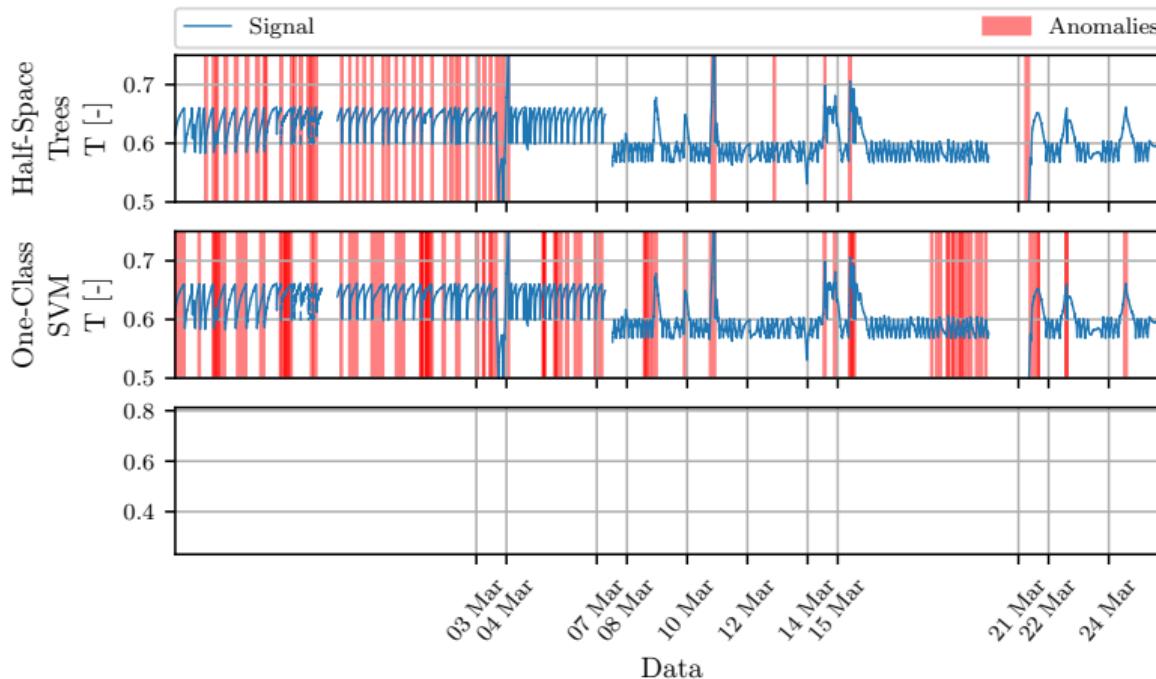
Battery Energy Storage System – BESS



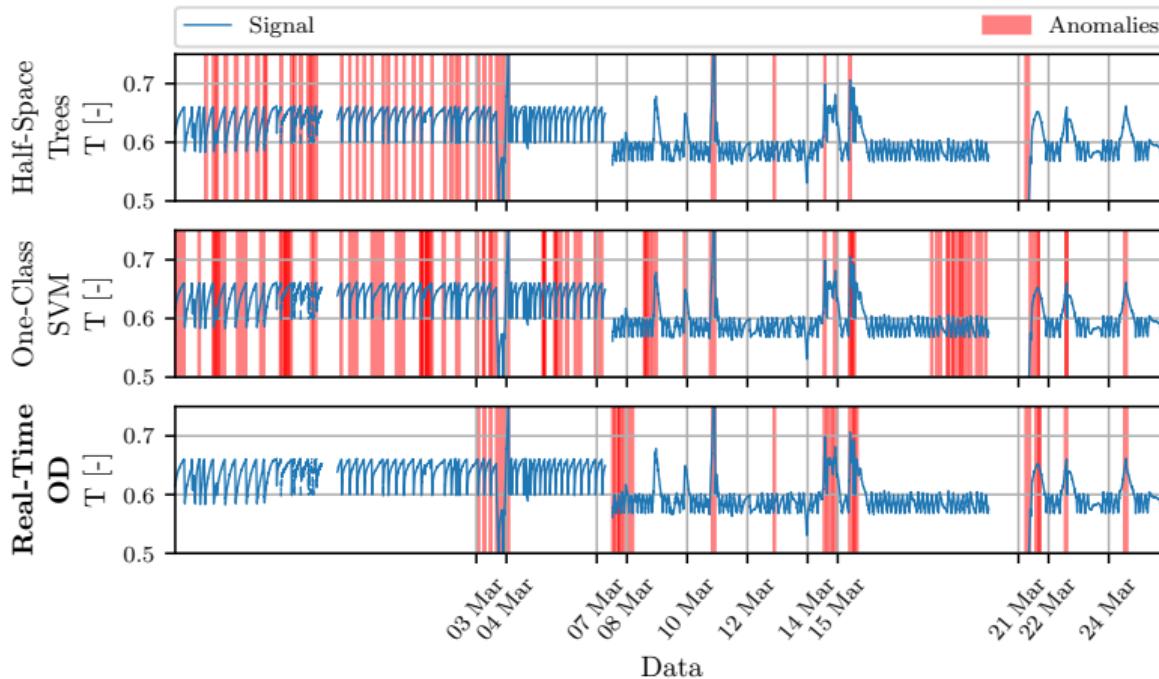
Case Study – BESS



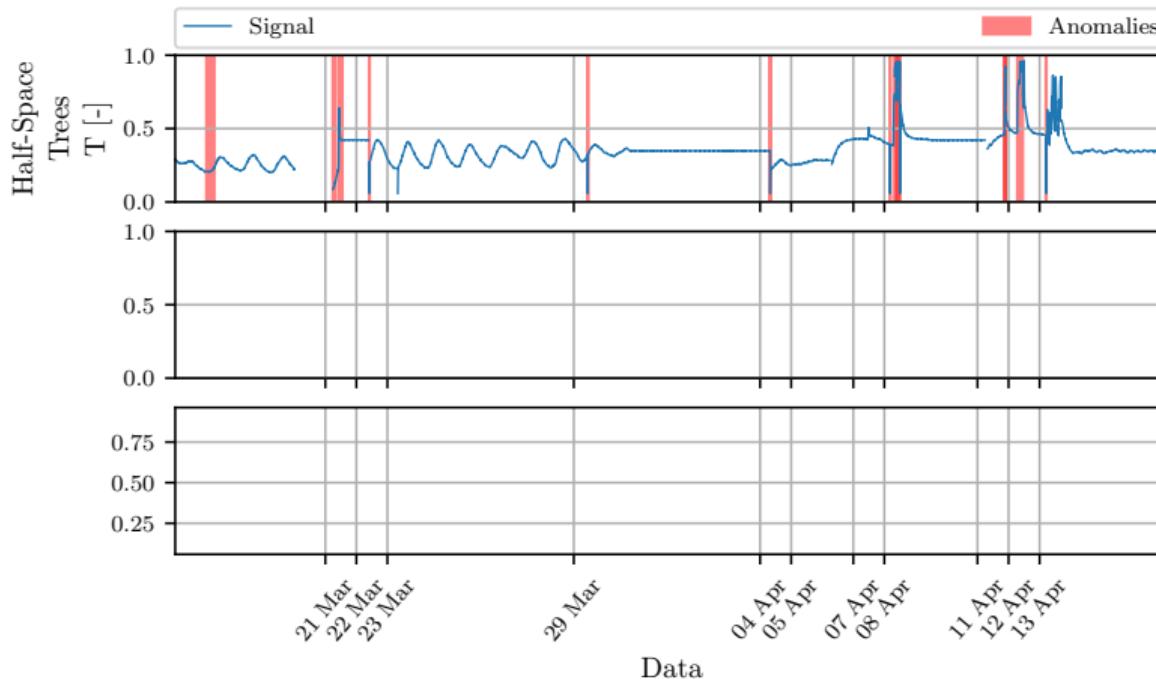
Case Study – BESS



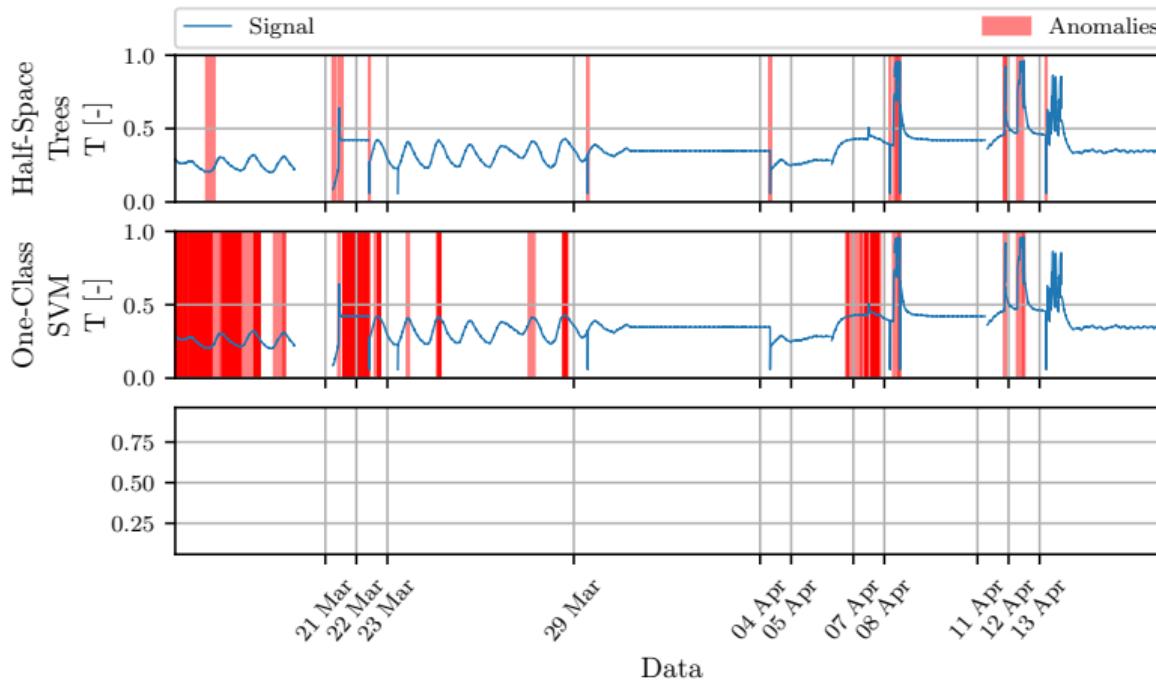
Case Study – BESS



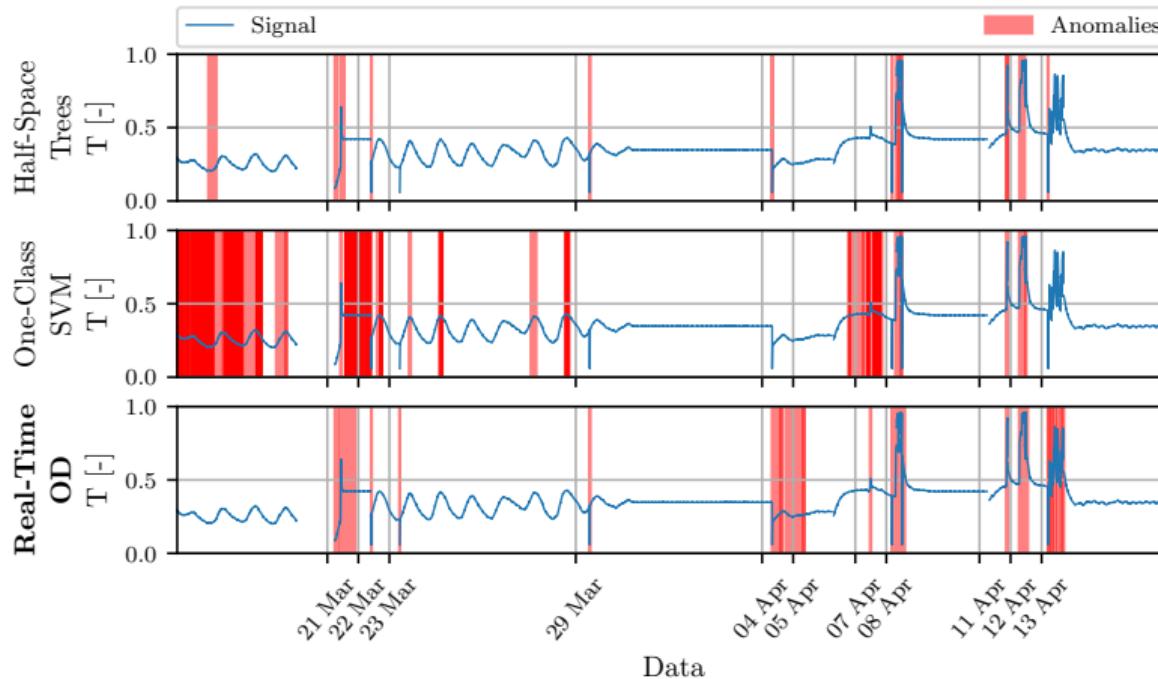
Case Study – Inverter



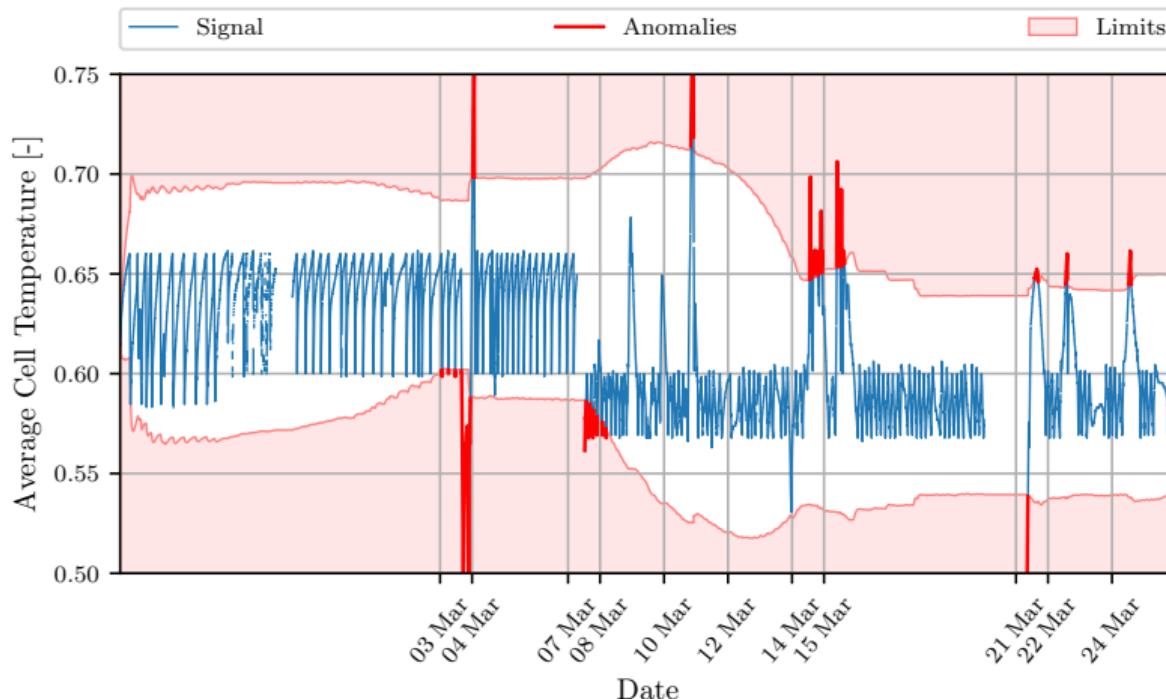
Case Study – Inverter



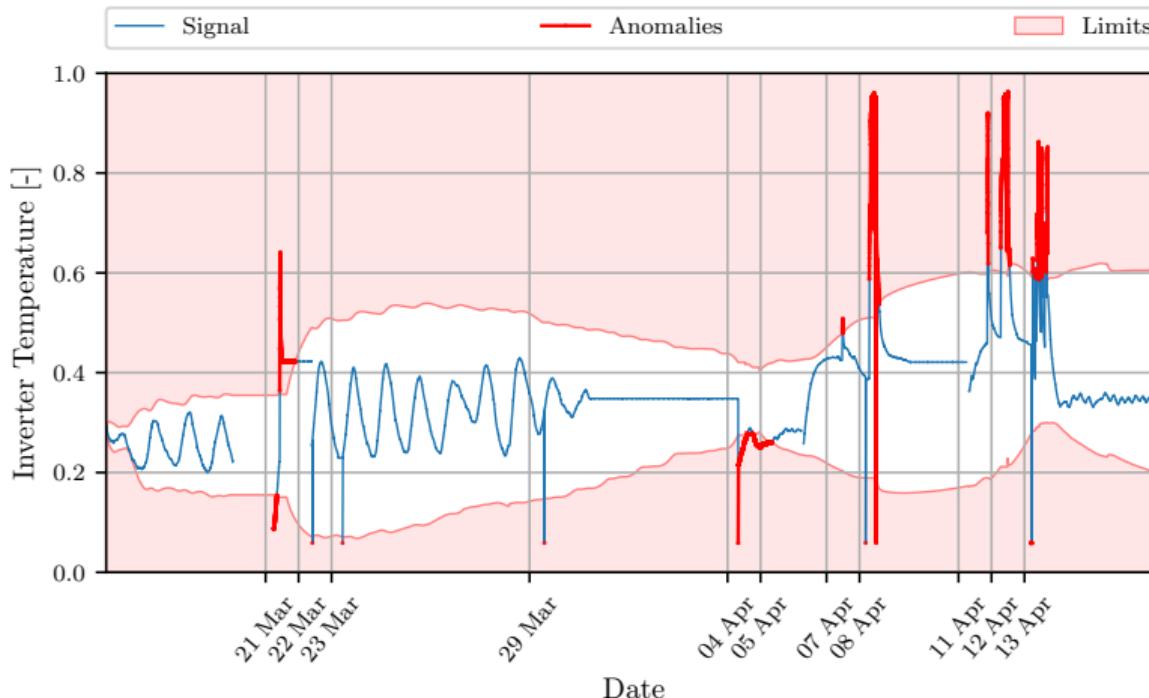
Case Study – Inverter



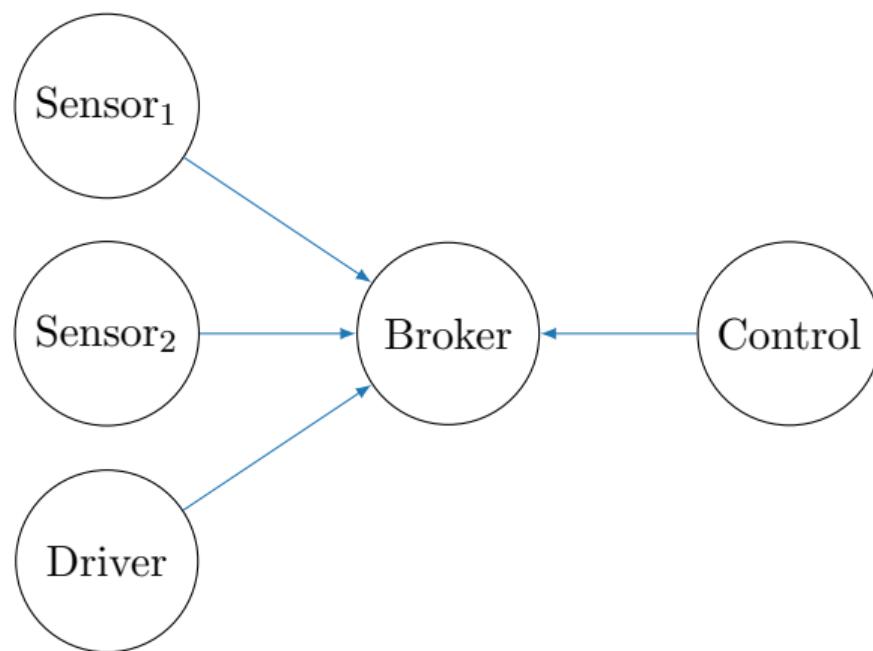
Dynamic Process Limits – BESS



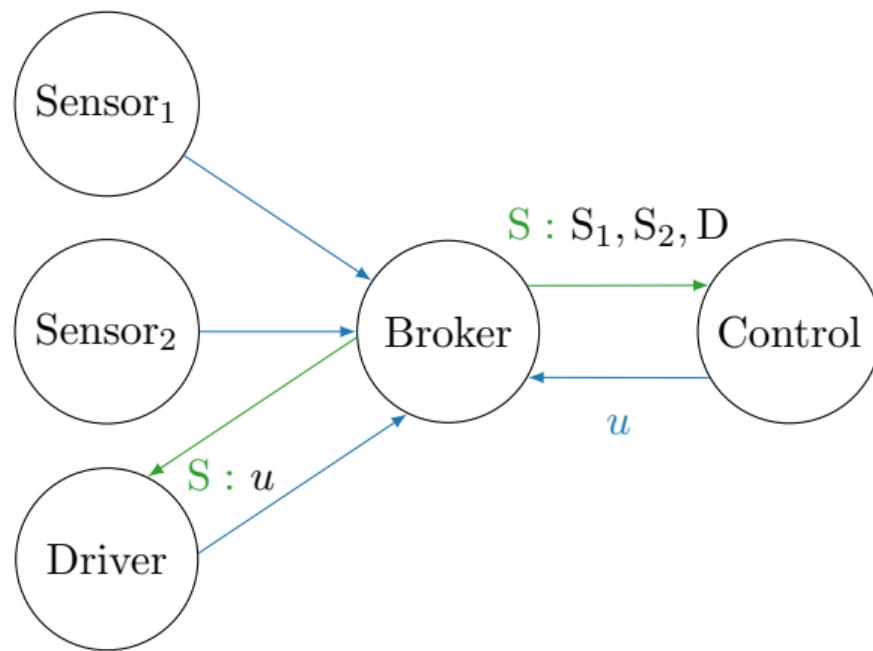
Dynamic Process Limits – Inverter



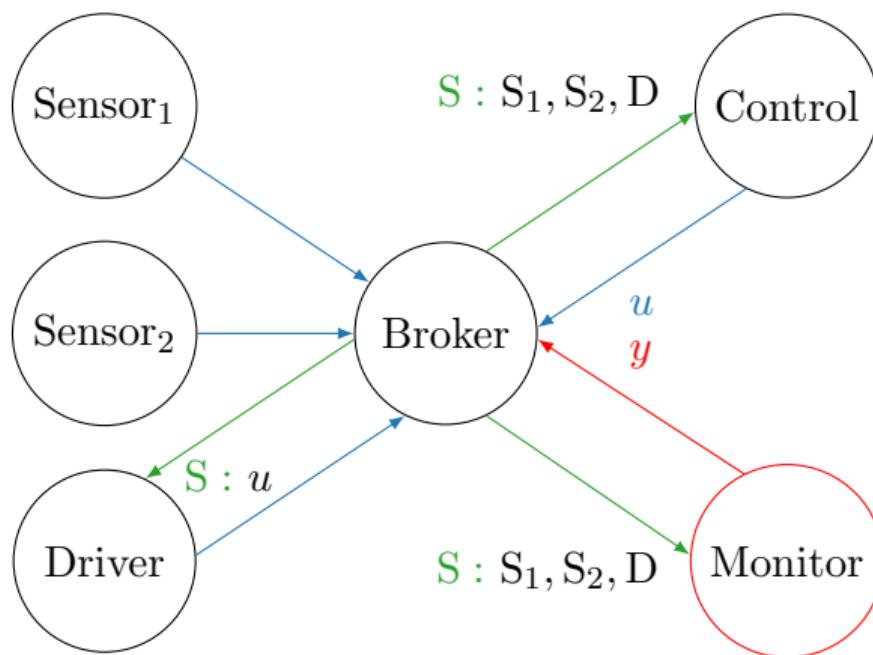
Utilize Existing Infrastructure



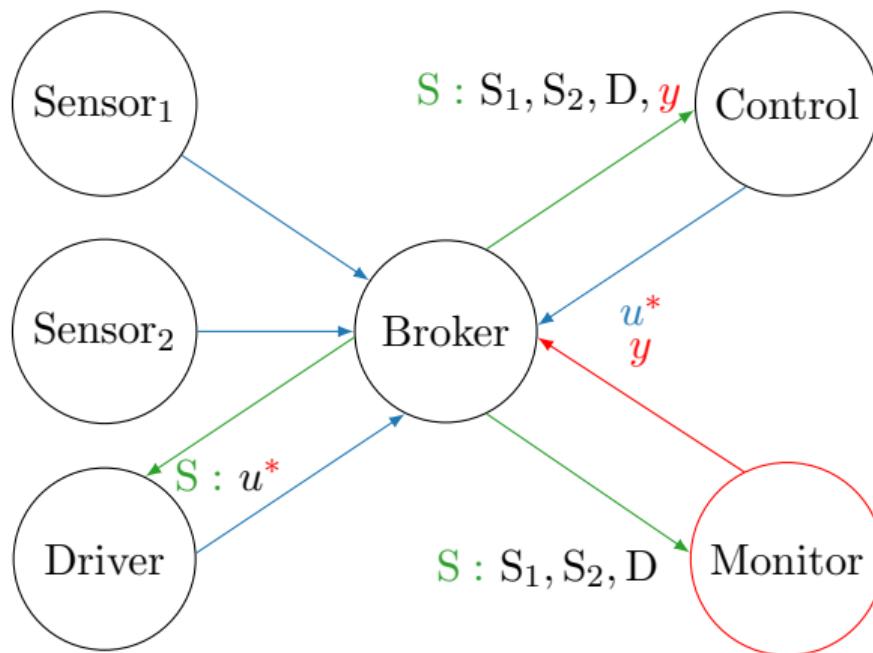
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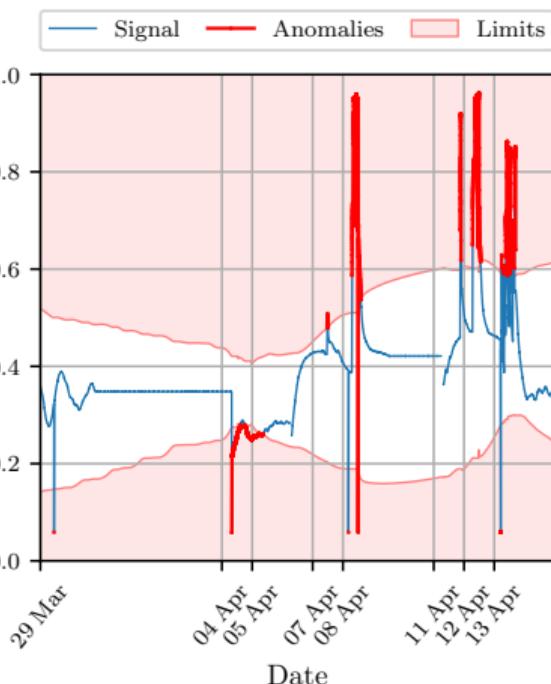


Utilize Existing Infrastructure



Summary

- outlier detection on streamed data
- adaptation to external conditions
- online self-learning approach
- dynamic process limits for individual signals
- integration with existing IT infrastructure



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Process Time Evaluation

Comparison of latency on univariate data.

Algorithm	BESS		Inverter	
	average [μ s \pm μ s]	max [ms]	average [μ s \pm μ s]	max [ms]
Half-Space Trees	220 \pm 200	10	220 \pm 200	11
One-Class SVM	8 \pm 7	1	9 \pm 9	2
Proposed	57 \pm 55	9	60 \pm 75	12

Online Anomaly Detection Workflow

Input: expiration period t_e , time constant t_c

Output: score y_i , threshold $x_{q,i}$

Initialisation :

- 1: $i \leftarrow 1; n \leftarrow 1; q \leftarrow 0.9973; \bar{x} \leftarrow x_0; s^2 \leftarrow 1;$
- 2: compute $F_X(x_0)$;

LOOP Process

3: **loop**

4: $x_i \leftarrow \text{RECEIVE}();$

5: $y_i \leftarrow \text{PREDICT}(x_i) ;$

6: $x_{q,i} \leftarrow \text{GET}(q, \bar{x}, s^2);$

7: **if** (1a) **or** (3) **then**

8: $\bar{x}, s^2 \leftarrow \text{UPDATE}(x_i, \bar{x}, s^2, n);$

9: $n \leftarrow n + 1;$

10: **for** x_{i-t_e} **do**

11: $\bar{x}, s^2 \leftarrow \text{REVERT}(x_{i-t_e}, \bar{x}, s^2, n);$

12: $n \leftarrow n - 1;$

13: **end for**

14: **end if**

15: $i \leftarrow i + 1;$

16: **end loop**

Far Less False Positive Alarms

Recall, precision, and F1 evaluation on multivariate benchmark dataset.

Algorithm	Recall [%]	Precision [%]	F1 [%]
Half-Space Trees	33	36	34
One-Class SVM	57	37	44
Proposed	50	48	49

Follow-up research

