Take Our Daughters And Sons to Work Day

https://github.com/Mark-MDO47/TODAS_DaughtersAndSons.git

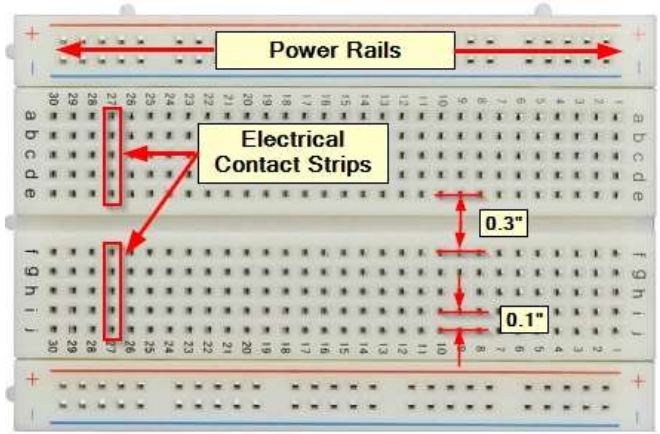
June 2024

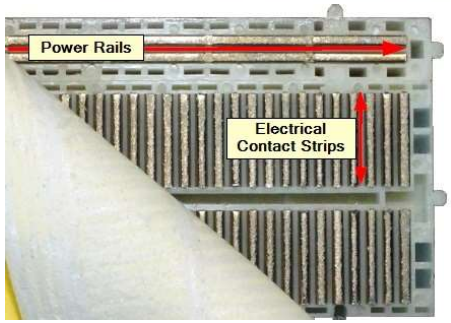
TODAS – Electricity, Arduinos, Fun

1. Water Flow - a way to think about Electricity
2. Arduino (computer on a chip), buttons, and LEDs
3. Sonar Control and big LED ring
4. Bananas and Sounds

- Resources

01 – Breadboards – how do they work?

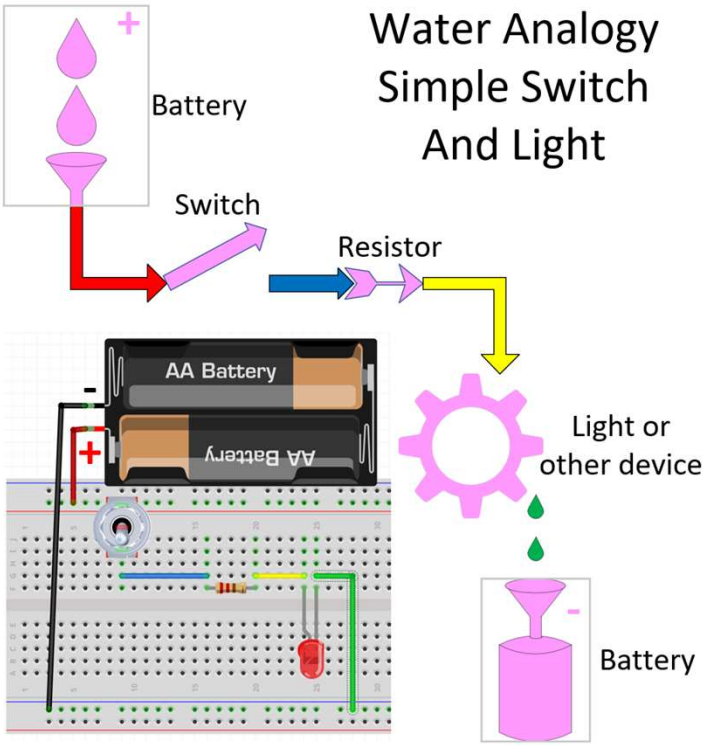




- Sides have power rails – length
- Center has contact strips – width

- Images from protosupplies.com

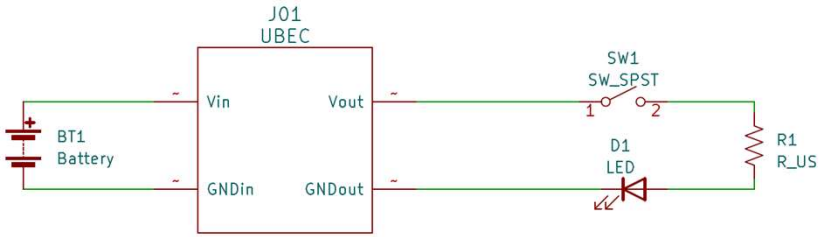
01 – Water Analogy – Simple Circuit



- Electrons in wires actually flow from negative to positive, but many electrical symbols are drawn as if the current flow is from positive to negative so let's get used to it!

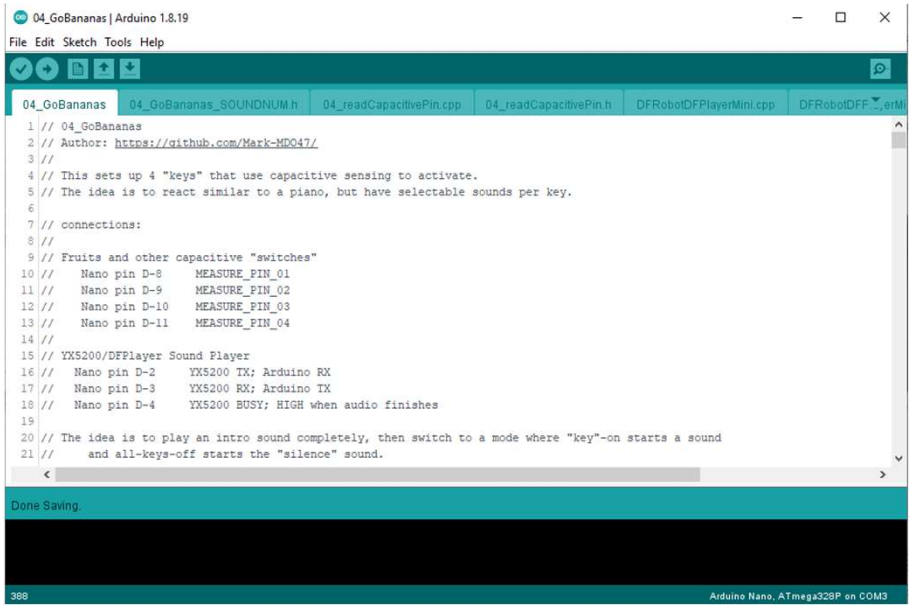
- "Pictorial" circuit is "Fritzing Diagram"
  - https://fritzing.org/ - 8 Euros

01 Simple Circuit Schematic



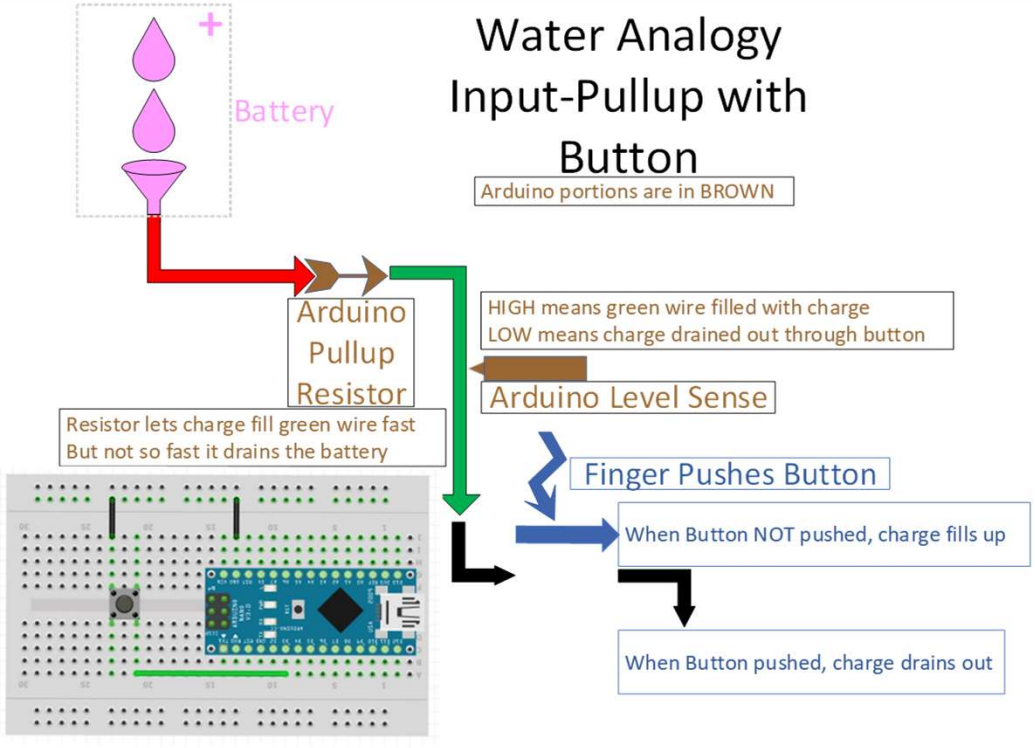
- The Universal Battery Eliminator Circuit produces 5 volts if the input is greater than or equal to about 6 volts.
- The resistor prevents sending too much current through the LED; that would burn it up.
- Schematic diagram is from KiCad
  - https://www.kicad.org/ - it's free!

02 – Arduino IDE



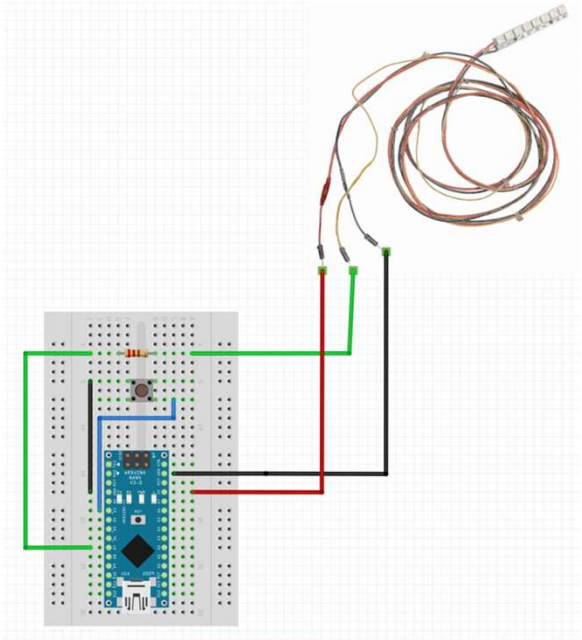
- IDE means Integrated Development Environment
- https://www.arduino.cc/en/software - it's free!

02 – Water Analogy Input-Pullup & Button



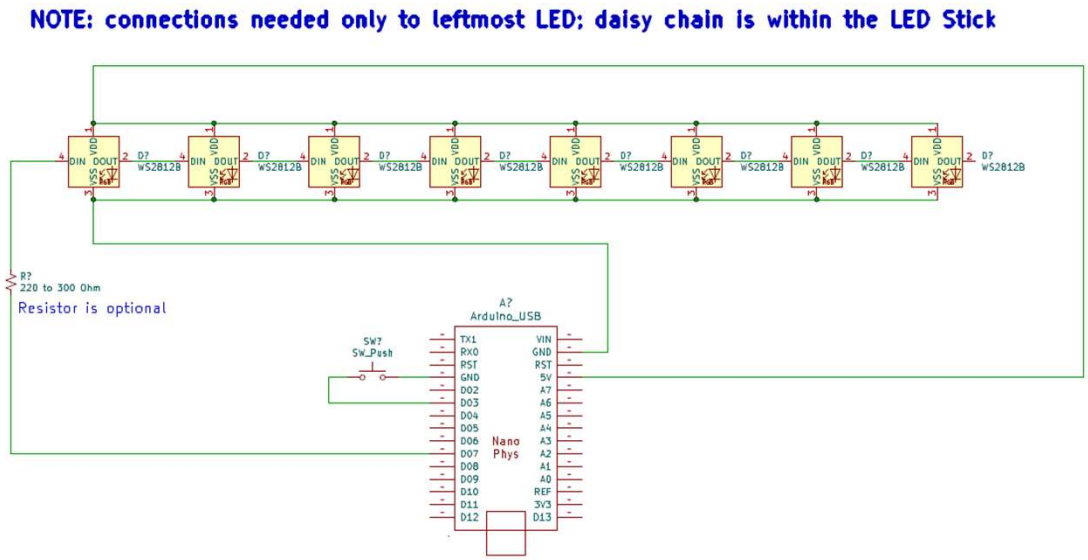
- Remember: electrons in wires actually flow from negative to positive, but often easier to understand by pretending positive to negative

02 – Arduino Moving Color Lights



- "Fritzing diagram" of color lights in motion!
  - LED is Light Emitting Diode
- Configure software for color choices
- Press button to stop, release to continue
- How does it work? SOFTWARE!
  - Pins can be input or output – you tell it which
  - Read the button
  - If not pressed – display next light
  - Short delay
- TLDR – WS2812B individually addressable color LEDs using FastLED library

02 - Arduino Moving Color Lights Schematic



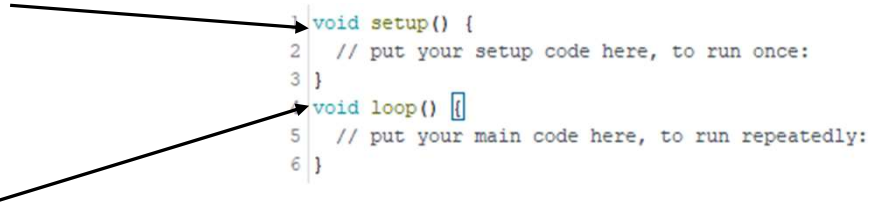
- The LED stick has eight small chips that control 3 LEDs each: Red, Green, and Blue.
- 3 LEDs are close together so they look like one color

02 – Arduino Inputs

- When button is pushed, Arduino input is LOW
- When button is not pushed, Arduino input is HIGH
- We want to do LED motion when button is NOT pushed
  - Assign name to the pin we use
  - Make the pin an input
  - If the state is HIGH (button not pushed) do the motion

02 - Arduino Code Structure – Empty Sketch

- Empty “sketch” has
  - setup() – called once at start
    - Initialize hardware
    - Initialize software
  - loop() – called repeatedly
    - Process events
    - Generate outputs

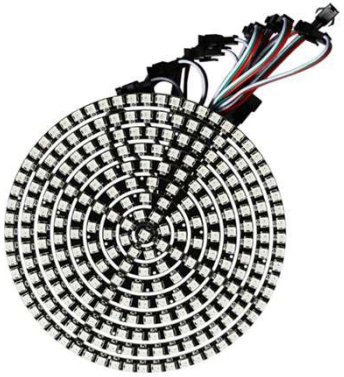


02 – Arduino Button Input Software

- this defines a name for pin D3 for the button
- Inside “setup()“ - pinMode sets that pin to be an input with “pullup”; HIGH unless connected to ground by pushing button
- ptrn_phase() is called from code inside “loop()”
  - Because current_phase is “static”, it remembers previous value from last time ptrn_phase() was called
  - The “if(HIGH” block does the motion if button NOT pushed
  - If button WAS pushed we return current_phase of -1 to signify stopping LED motion

```
#define BUTTON_PIN_STOP 3 // press to stop action; release to restart

  pinMode(BUTTON_PIN_STOP, INPUT_PULLUP); // digital INPUT_PULLUP means voltage HIGH unless grounded


////////////////////////////////////////////////////////////////////////////////////////////////////
// ptrn_phase() - determine the state of the phase of pattern generation
//     returns: long int with either value >= 0 phase to blink or value < 0 STOP
//

long int ptrn_phase() {
  static long int current_phase = -1;

  if (HIGH == digitalRead(BUTTON_PIN_STOP)) {
    current_phase += 1;
    current_phase %= gPatternsRepeat; // loop through the number of calls before repeat
    if (0 == current_phase) {
      step_color_value();
    }
  } else {
    current_phase = -1; // STOP
  }

  return(current_phase);
} // end ptrn_phase()
```

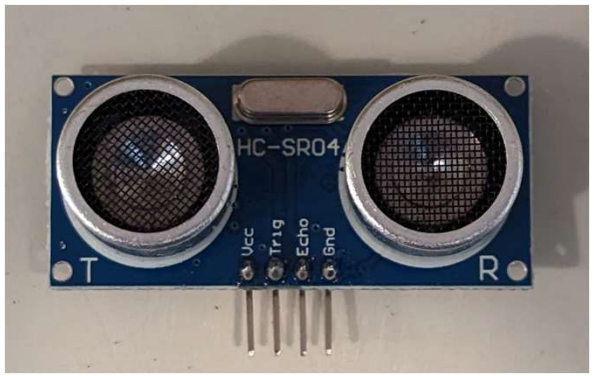
03 – Go Big with Ultrasonic Sonar Control

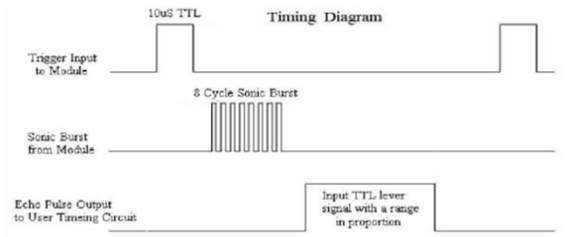


- 8 LEDs is fun – but 241 LEDs is MORE fun!
  - TLDR – WS2812B individually addressable color LEDs using FastLED Library
- Displays moving patterns we choose
- Disk is mostly wired; less soldering needed
- Needs more power than Arduino can give

- Pictures from amazon.com
  - TLDR - https://www.amazon.com/WESIRI-WS2812B-Individually-Addressable-Controller/dp/B083VWVP3J

03 – Ultrasonic Sonar Control





- Ultrasonic Sonar sensor detects distance
- Bounces ultrasonic sound off objects

- Set “Trig” HIGH then LOW to start sonic burst
- Measure time until “Echo” is HIGH
- Divide time by speed of sound to get distance

- TLDR diagram from the sparkfun.com HC-SR04 spec.

03 – Ultrasonic Sonar Detector Software

Include library, define names for pins

“my_ultra” is how I use the HC-SR04

Make a global “gUltraDistance” for debugging

“handle_ultra” returns a pattern number

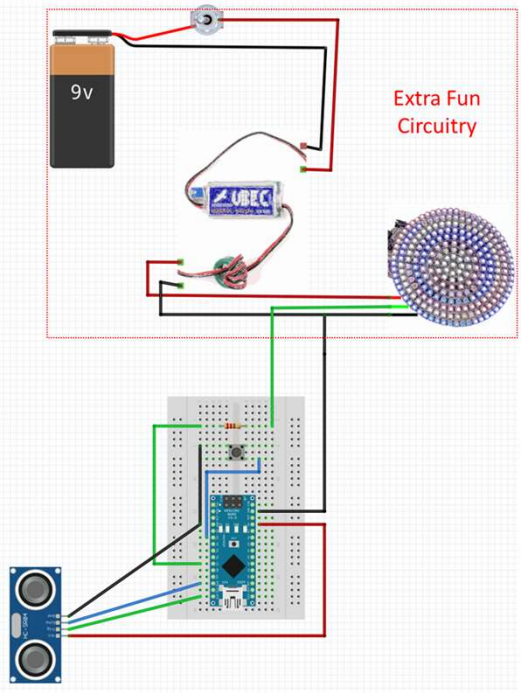
“my_ultra.read(CM)” gives distance in CM
stored in “gUltraDistance”

Use math to turn distance into “pattern”

Return “pattern” (number) to caller

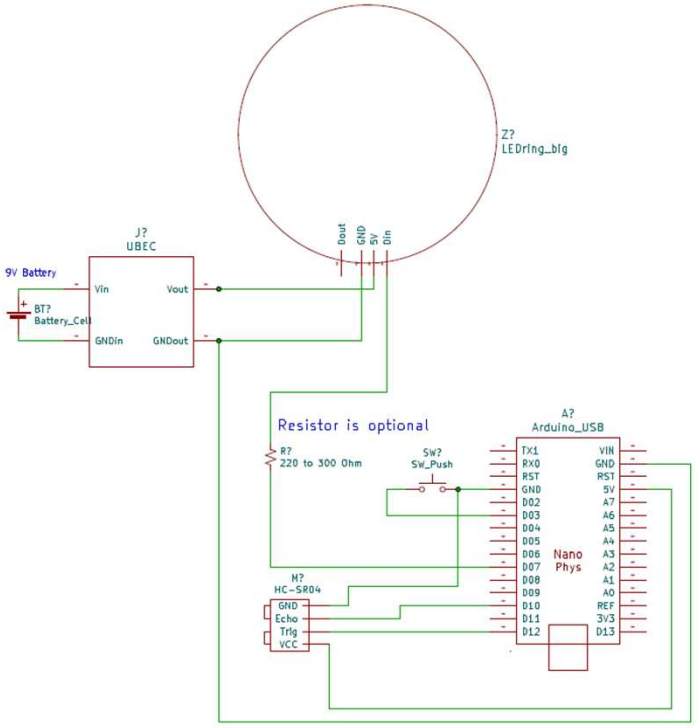
```
#include <FastLED.h>
#include <Ultrasonic.h>

// Ultrasonic HC_SR04 definitions
#define ULTRA_TRIG_PIN 12 // HC-SR04 Trigger digital pin
#define ULTRA_ECHO_PIN 10 // HC-SR04 Trigger echo pin
#define ULTRA_CM_PER_REGION 9 // HC-SR04 every this many CM is a different pattern
#define ULTRA_IGNORE_INITIAL_CM 3 // HC-SR04 ignore the first 3 CM since valid range starts at 2 CM

// instantiate my HC-SR04 data object
Ultrasonic my_ultra = Ultrasonic(ULTRA_TRIG_PIN, ULTRA_ECHO_PIN); // default timeout is 20 milliseconds

int gUltraDistance = 0; // latest measured distance in centimeters

////////////////////////////////////////////////////////////////////////////
// handle_ultra() - process HC-SR04 data.
//     returns: pattern number 0 <= num <= PATTERN_MAX_NUM
//

int handle_ultra() {
  int pattern; // integer pattern number from 0 thru 5 inclusive
  // get the range reading from the Ultrasonic sensor in centimeters
  int ultra_dist;

  gUltraDistance= (my_ultra.read(CM));
  ultra_dist = gUltraDistance - ULTRA_IGNORE_INITIAL_CM;
  if (ultra_dist < 0) ultra_dist = 0;
  pattern = ultra_dist / ULTRA_CM_PER_REGION;
  if (pattern > 5) pattern = 5;

  return(pattern);
} // end handle_ultra()
```

03 – Fritzing Diagram



- Replace 8-LED stick with 241-LED Disk
  - Separate power for 241-LED Disk
- Add new HC-SR04 Ultrasonic Sensor
- Button unused – can leave it
- We add the battery and UBEC because the 241 LEDs take a lot of power!

03 – Schematic Diagram



The button connected to pin D03 is not used for this project.

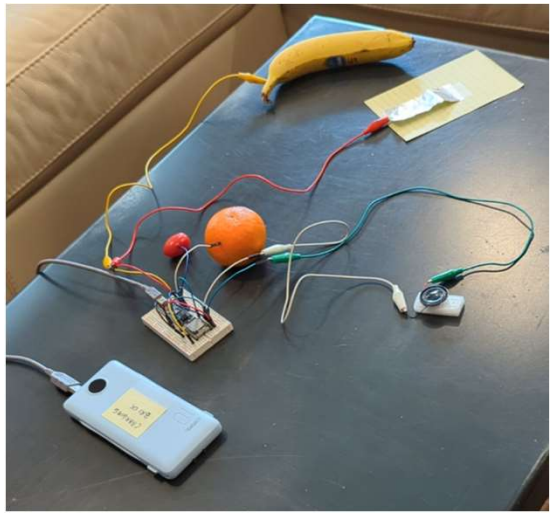
We leave it on the breadboard; no need to remove it.

We connect the UBEC ground to Arduino, LEDs, and HC-SR04.

That allows both LED and HC-SR04 to recognize the voltages from the Arduino

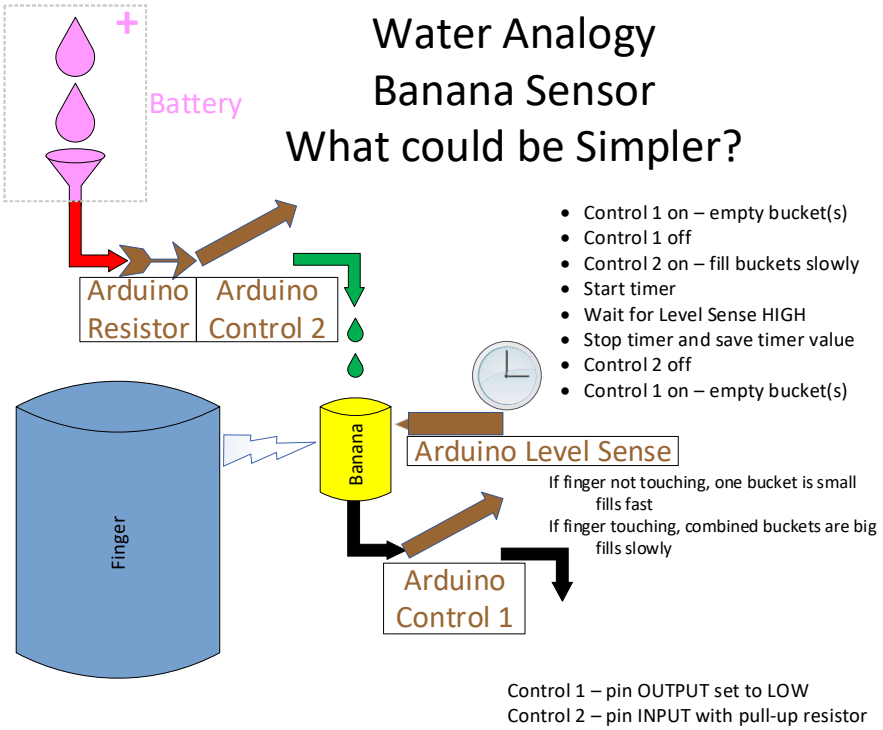
04 – Go Bananas!

- A Banana Piano! Several “key” fruit types…
  - Uses “capacitive sensing” – depends on how fast Arduino can charge it up
    - Touching banana makes it take longer to charge
- Digitized sounds are played when the “key” is pressed
- Only one sound at a time is played
- Sounds are “sampled” – digital storage format
- Video: https://youtu.be/EC1qHbE89JI



- TLDR – Image to the left by krakenimages.com on Freepik

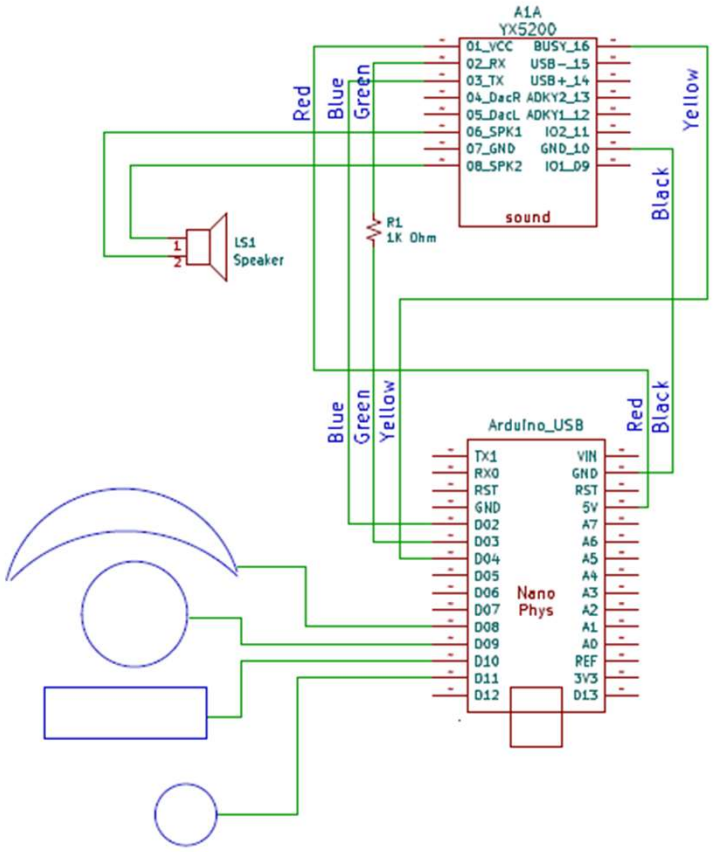
04 – Water Analogy - Banana Input



- Note that this is an analog of how it works
- The diagram shows the flow of the code
- The code uses tricks to be fast – makes code harder to understand
  - But that is all hidden in 04_readCapacitivePin.*

04 Bananas Schematic

- Bottom half has Arduino and fruits
  - Capacitive sensing of fruits
- Top half has sound module and speaker
  - UART serial interface
  - Universal Asynchronous Receiver / Transmitter



04 Bananas Software – customization

```
// "pin index" state:
//   -1 means nothing selected
//   0-3 (3 = NUM_MEASURE_PINS-1) represent pins MEASURE_PIN_01 to MEASURE_PIN_03,
//   any other value is invalid
int8_t gCurrentPinIndex = -1; // Index number of which PinIndex is current - nothing selected
int8_t gPrevPinIndex = -1; // previous PinIndex - nothing selected

// "pin index" to sound mapping
//    pin index goes from -1 to 3 (3 = NUM_MEASURE_PINS-1)
//    we add one to that number to go from 0 to 4
//       0 = Silence sound
//       1 through 4 = MEASURE_PIN_01 through MEASURE_PIN_04
uint16_t gPinIndex2SoundNum[1+NUM_MEASURE_PINS] = { SOUNDNUM_silence, SOUNDNUM_electric_piano_C, SOUNDNUM_organ_D, SOUN
```

```
////////////////////////////////////////////////////////////////////
// pin2soundnum(pinIndex) - convert pin index to sound number
//
// pinIndex to sound mapping
//    pinIndex goes from -1 to 3 (3 = NUM_MEASURE_PINS-1)
//    we add one to that number to go from 0 to 4
//       0 = Silence sound
//       1 through 4 = MEASURE_PIN_01 through MEASURE_PIN_04

uint16_t pin2soundnum(int8_t pinIndex) {
  uint16_t soundNum = SOUNDNUM_INVALID;
  if ((pinIndex >= -1) and (pinIndex < NUM_MEASURE_PINS)) {
    soundNum = gPinIndex2SoundNum[pinIndex+1];
  } else {
    Serial.print("ERROR pin2soundnum() - pinIndex="); Serial.pri
    soundNum = SOUNDNUM_INVALID; // not really needed
  }
  return(soundNum);
} // end pin2soundnum()
```

- Place sound numbers into array gPinIndex2SoundNum[]
- Calls to pin2soundnum() will convert PinIndex to sound number
- Most of routine is error checking (this is normal)

Only one line is needed to actually do translation

could just use gPinIndex2SoundNum[pinIndex+1] if wanted to skip error checking

04 Bananas Software – loop() - repeats

- Executes block every 50 milliseconds
- Gets active PinIndex
- If this is change in PinIndex: start sound
  - Could be “silence” sound
- Not a change, still holding: repeat sound
- No key pressed: repeat silence
- Extra credit: can you simplify the last if/else/endif ?
- Extra credit: can you write simple code to replace EVERY_N_MILLISECONDS(50) ? Do we even need this?

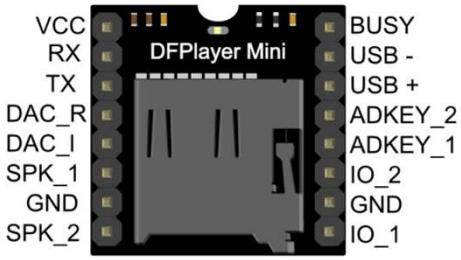
```
////////////////////////////////////////////////////////////////////////////////////////////////////
// loop()
void loop() {
  EVERY_N_MILLISECONDS( 50 ) {
    gCurrentPinIndex = handle_capacitive(); }
    if (gPrevPinIndex != gCurrentPinIndex) {
      // "key" (PinIndex) is different than before so start a new sound
      //    -1 will start the silent sound, otherwise the chosen key sound will start
      gPrevPinIndex = gCurrentPinIndex;
      DFstartSound(pin2soundnum(gCurrentPinIndex), SOUND_DEFAULT_VOL);
    } else if (DFcheckSoundDone()) {
      if (gCurrentPinIndex >= 0) {
        // PinIndex is not -1 so we are still holding a key down - restart sound
        gPrevPinIndex = gCurrentPinIndex;
        DFstartSound(pin2soundnum(gCurrentPinIndex), SOUND_DEFAULT_VOL);
      } else {
        // PinIndex is -1 so no key is held down - start silence sound
        gPrevPinIndex = -1;
        DFstartSound(pin2soundnum(gCurrentPinIndex), SOUND_DEFAULT_VOL);
    } // end if
  } // end EVERY_N_MILLISECONDS
} // end loop()
```

04 Bananas Software – setup() - one time

- Initialize serial debug interface
- Do capacitive sensing setup
- Initialize sound card interface
- Initialization complete
- Play intro sound then start

```
////////////////////////////////////////////////////////////////////////////////////////////////////
// setup()
void setup() {
  Serial.begin(115200);         // this serial communication is for general debug; set the USB serial por
  while (!Serial) {
    ; // wait for serial port to connect. Needed for native USB port only
  }
  Serial.println(""); // print a blank line in case there is some junk from power-on

  CapacitiveSetup();

  pinMode(DPIN_AUDIO_BUSY,  INPUT_PULLUP); // HIGH when audio stops
  mySoftwareSerial.begin(9600); // this is control to DFPlayer audio player
  // initialize the YX5200 DFPlayer audio player
  DFsetup();

  Serial.println("TODAS init complete...");

  // play the INTRO sound to completion, then allow normal loop() processing
  DFstartSound(SOUNDNUM_introduction, SOUND_DEFAULT_VOL);
  while (!DFcheckSoundDone()) {
    delay(10); // wait for the INTRO sound to finish
  } // end while
  Serial.println("Intro Sound Complete");
  gCurrentPinIndex = gPrevPinIndex = -1;
  DFstartSound(SOUNDNUM_silence, SOUND_DEFAULT_VOL);

} // end setup()
```

04 – Digitized Sound Output

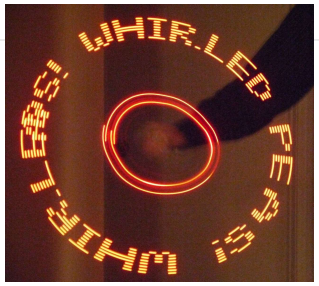


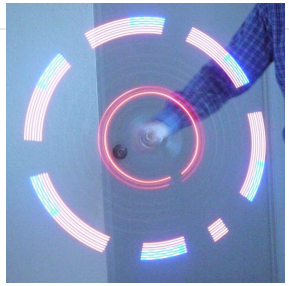
- DFPlayer (YX5200) accepts SD card with digitized audio
  - Plays SD card audio files by number
  - UART interface to Arduino
  - Direct mono speaker output
  - Line-out stereo output, usable for BlueTooth

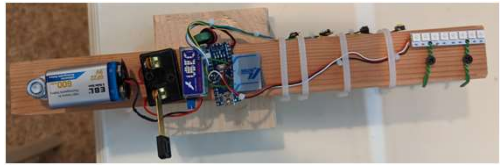
- Many tricks to using YX5200 https://github.com/Mark-MDO47/AudioPlayer-YX5200
- Espeak for robotic voice https://github.com/Mark-MDO47/RubberBandGun/tree/master/sounds
- Audacity for sound processing https://www.audacityteam.org/

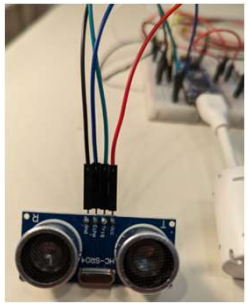
Resources – Arduino

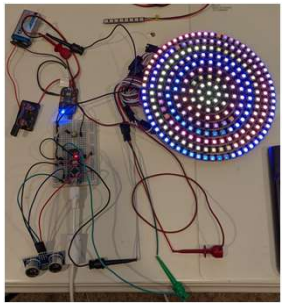
https://github.com/Mark-MDO47/ArduinoClass

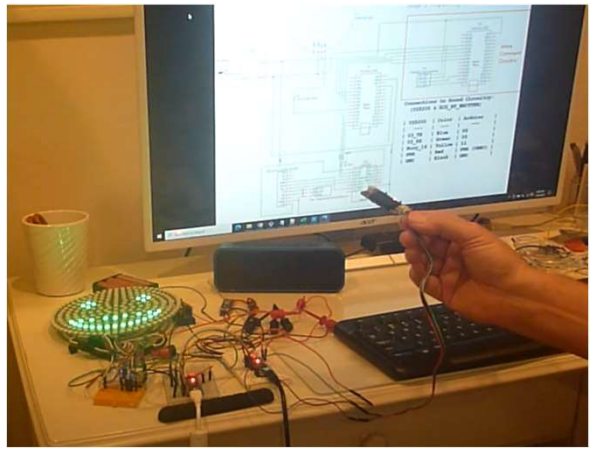


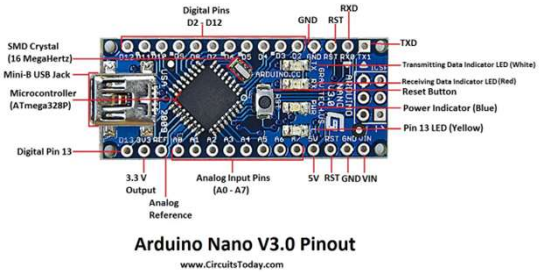






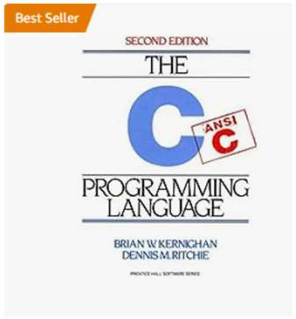


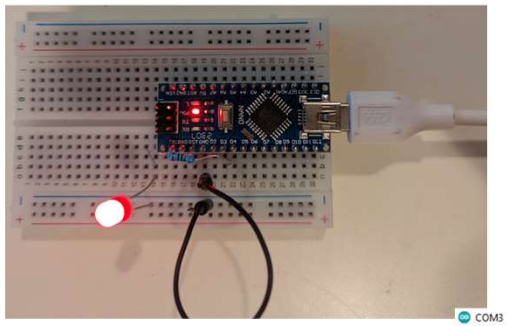




If you know a bit of programming…

Resources – C for Arduino





If you can use a programming refresher…

https://github.com/Mark-MDO47/CforArduinoClass