

ABC Net

Idea is to approximate real valued weights W as a linear combination of binary weights.

$$W \approx \sum_{i=1}^M \alpha_i B_i \quad M \Rightarrow \# \text{ filters}$$

$$\min_{\alpha, B} J(\alpha, B) = \|W - B\alpha\|^2$$

$$\text{s.t. } B_{ij} \in \{-1, +1\}$$

$$B = [\text{vec}(B_1), \dots, \text{vec}(B_M)]$$

$$w = \text{vec}(W) \quad \alpha = [\alpha_1, \dots, \alpha_M]^T$$

$$B_i = F_{ui}(W) := \text{sign}(\bar{W} + u_i \text{std}(W)) \quad i=1:M$$

$$\bar{W} = W - \text{mean}(W)$$

$$u_i = -1 + (i-1) \frac{2}{M-1} \quad i=1:M$$

weights are observed to be symmetric & have a non-dense distribution close to a Gaussian.

as B_i 's are fixed

$$\min_{\alpha} J(\alpha) = \|W - B\alpha\|^2$$

B_i 's are fixed and are the basis/dictionary matrix.

$C \rightarrow$ cost function



Forward $\Rightarrow B_i = F_{u_i}(W)$

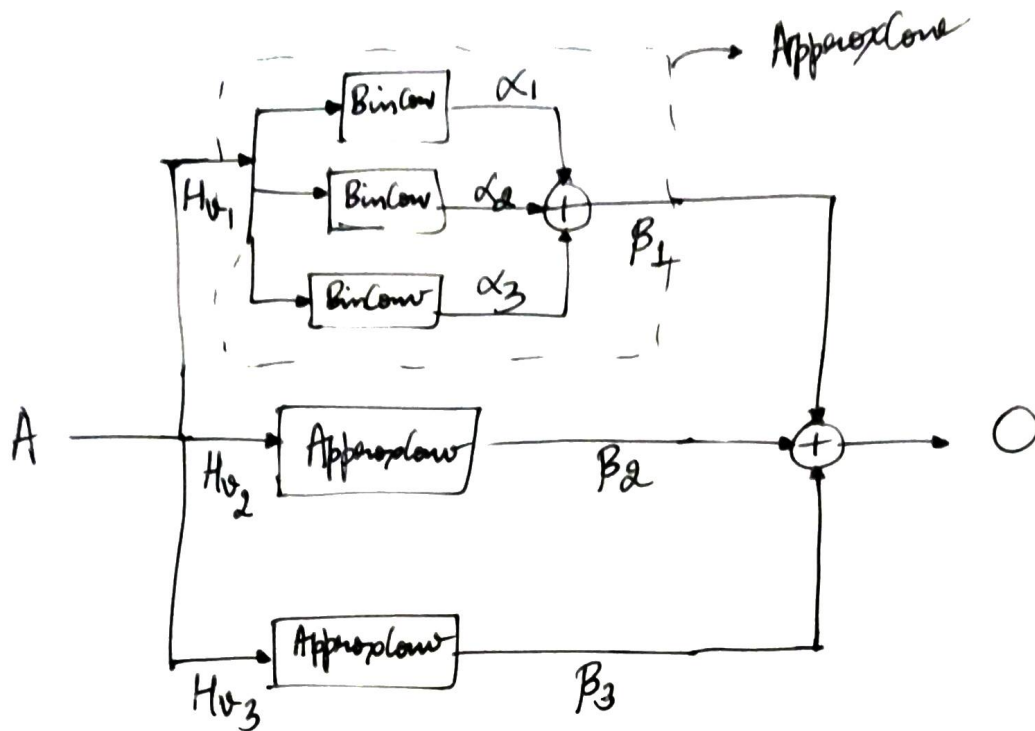
$$\alpha = \min_{\alpha} J(\alpha) = \|W - B\alpha\|^2$$

$$O = \sum_{m=1}^M \alpha_m \text{Conv}(B_m, A)$$

Backward $\Rightarrow \frac{\partial C}{\partial W} = \frac{\partial C}{\partial O} \left(\sum_{m=1}^M \alpha_m \frac{\partial O}{\partial B_m} \frac{\partial B_m}{\partial W} \right)$

Bengio's straight through estimator \leftarrow STE $\frac{\partial C}{\partial O} \left(\sum_{m=1}^M \alpha_m \frac{\partial O}{\partial B_m} \right)$
 $= \sum_{m=1}^M \alpha_m \frac{\partial C}{\partial B_m}$

STE is used to obtain gradient for a threshold operation. The threshold operation can't be differentiated. This can on average be approximated as i/p gradient = o/p gradient.



i/p A is $\{-1, +1\}$ everything
can be implemented as
XNOR and Bitcount.

H_{vi} are used to binarize A .

Follows DoReFa-Net paper and uses
bounded rectifier for H_{vi} .
Indicator func.

$$H_v(R) := 2 \mathbb{I}_{h_v(R) \geq 0.5} - 1$$

$$h_v(x) = \text{clip}(x + v, 0, 1)$$

↓
shift.

Forward $\Rightarrow A = H_v(R)$

Backward $\Rightarrow \frac{\partial C}{\partial R} \stackrel{\text{STE}}{=} \frac{\partial C}{\partial A} \circ \mathbb{I}_{0 \leq R - v \leq 1}$

• \Rightarrow Hadamard product.
Same as \odot

Binarization of ~~loss~~ is super-noisy and crude. To make this work Batch Normalization (BN) is used before every activation to have zero-mean and unit variance.

Real valued activation R is approximated as a linear combination of N binary activations

$$R \approx \sum_{i=1}^N \beta_i A_i.$$

$$A_i = H_{v_i}(R)$$

β_i 's and v_i 's are both trainable.

$$\begin{aligned} \text{Conv}(W, R) &\approx \text{Conv}\left(\sum_{m=1}^M \alpha_m B_m, \sum_{n=1}^N \beta_n A_n\right) \\ &= \sum_{m=1}^M \sum_{n=1}^N \alpha_m \beta_n \text{Conv}(B_m, A_n) \end{aligned}$$

Conv \rightarrow Pool (Map.) \rightarrow BN \rightarrow Act.

$$\begin{aligned} H_v(\text{BN}(R)) &= \begin{cases} +1, & aR + b \geq 0.5 - v \\ -1, & aR + b < 0.5 - v \end{cases} \\ &= \begin{cases} +1, & R \geq (0.5 - v - b)/a \\ -1, & R < (0.5 - v - b)/a \end{cases} \end{aligned}$$