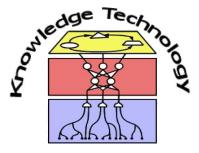
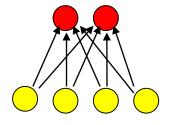
### **Neural Networks**

Lecture 3: Learning in Multilayer Networks

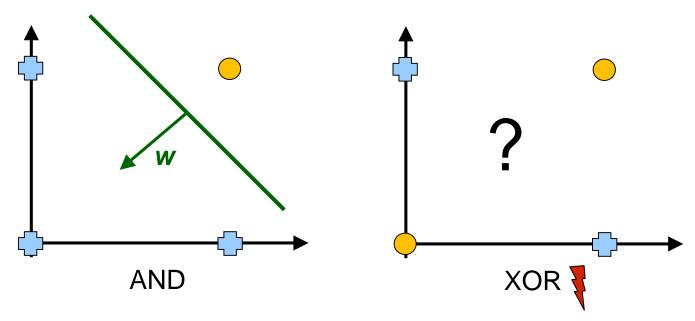


http://www.informatik.uni-hamburg.de/WTM/

### Revision: The Perceptron

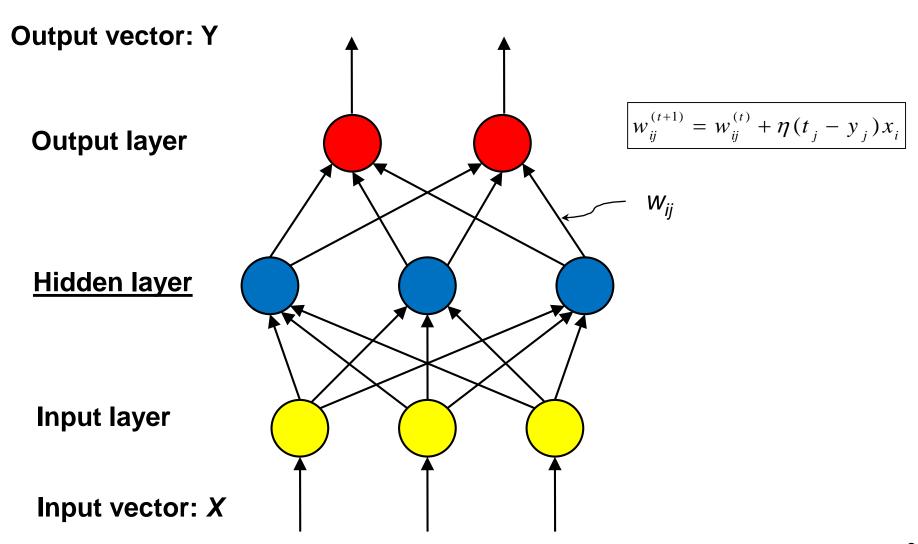


- The Perceptron is a linear classifier
- The update algorithm learns a straight line (decision boundary) that can separate the classes. It cannot learn the classes if the data is not linearly separable: (Minsky/Papert)

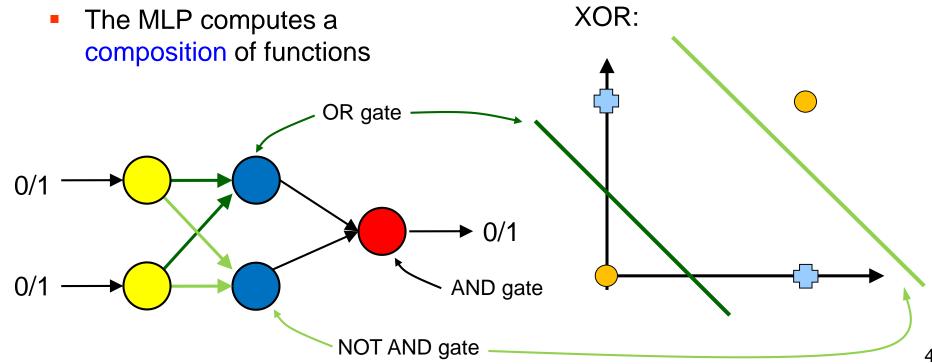


How can this fundamental limitation be overcome?

# The importance of the Neural Architecture - Solution: Multilayer Perceptron (MLP)

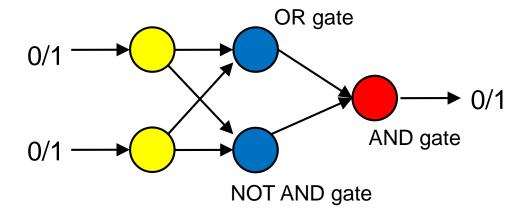


- Need to use two lines to separate the classes
- MLP below can solve this task.
- Each hidden unit describes one of the two lines:

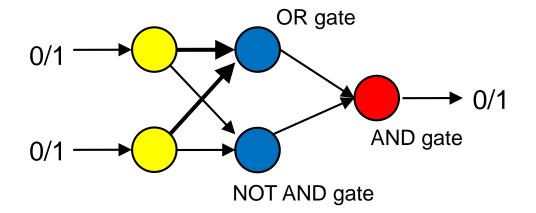


AND(OR(a,b), NAND(a,b))=XOR(a,b)

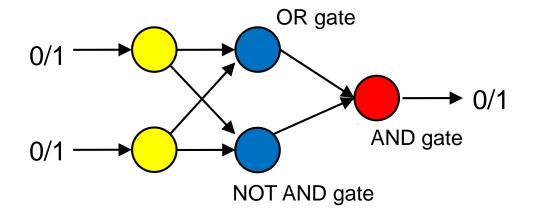
<b>x1</b>	<b>x2</b>		
0	0		
0	1		
1	0		
1	1		



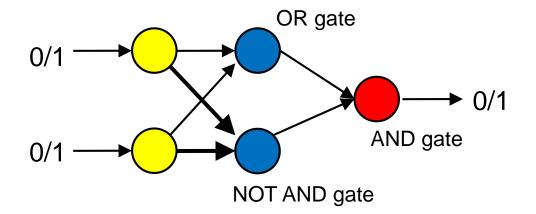
<b>x1</b>	<b>x2</b>	OR		
0	0	0		
0	1	1		
1	0	1		
1	1	1		



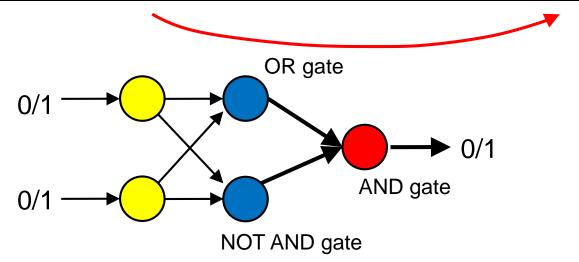
<b>x1</b>	<b>x2</b>	OR	AND	
0	0	0	0	
0	1	1	0	
1	0	1	0	
1	1	1	1	



<b>x1</b>	<b>x2</b>	OR	AND	NOT AND	
0	0	0	0	1	
0	1	1	0	1	
1	0	1	0	1	
1	1	1	1	0	



<b>x1</b>	<b>x2</b>	OR	AND	NOT AND	XOR
0	0	0	0	1	0
0	1	1	0	1	1
1	0	1	0	1	1
1	1	1	1	0	0



### Learning with hidden units

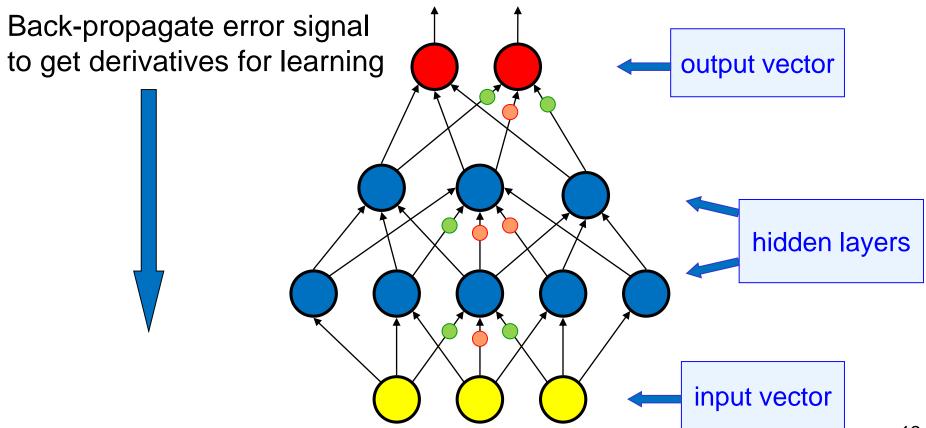
- Networks without hidden units very limited in input-output mappings
  - More layers of linear units do not help since still linear
- Need multiple layers of adaptive non-linear hidden units (→ universal approximator)
- How can we learn?
  - Need an efficient way of adapting all the weights, not just the last layer
  - No target labels in the hidden layers
  - Learning the weights going into hidden units is equivalent to learning features

### The concept behind backpropagation

- Instead of using desired activities to train the hidden units, use error derivatives for hidden activities
- Each hidden unit can affect many other "higher" hidden or output units
- From error derivatives for hidden activities, we can get error derivatives for the weights going into a hidden unit
- This learning rule is called backpropagation.
   It is a generalization of the delta rule (see last week)

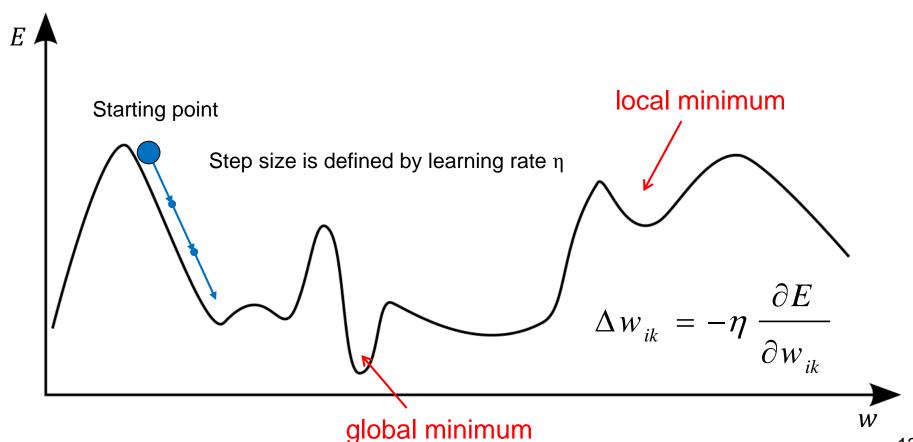
### Learning by back-propagating error derivatives

Compare outputs with correct answer to get error signal



### Gradient descent

 Backpropagation is a gradient descent method to find the minimum error on the error surface:



### **Error Terms**

- Need to differentiate the sigmoid function
- Gives us the following error terms (deltas)
  - For the outputs

$$\delta_k = (t_k - y_k) y_k (1 - y_k)$$

For the hidden nodes from the input activities a

$$\delta_{j} = a_{j} (1 - a_{j}) \sum_{k} w_{jk} \delta_{k}$$

### **Update Rules**

- This gives us the necessary update rules
  - For the weights connected to the outputs:

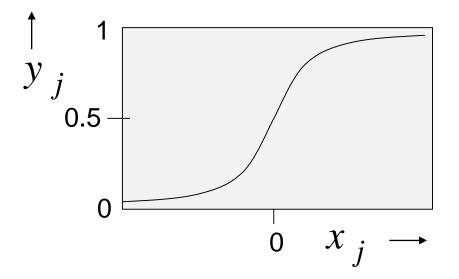
$$w_{jk} \leftarrow w_{jk} + \eta \delta_k a_j^{\text{hidden}}$$

For the weights connected to the hidden nodes:

$$v_{ij} \leftarrow v_{ij} + \eta \delta_{j} x_{i}$$

### Non-linear neurons with smooth derivatives

- For backpropagation, we need neurons that have well-behaved derivatives.
  - Typical: the logistic/sigmoid function
  - The output is a smooth function of the summed input



$$x_j = b_j + \sum_i y_i w_{ij}$$

$$y_{j} = \frac{1}{-x_{j}}$$

$$1 + e^{-x_{j}}$$

$$\frac{dy_j}{dx_j} = y_j (1 - y_j)$$

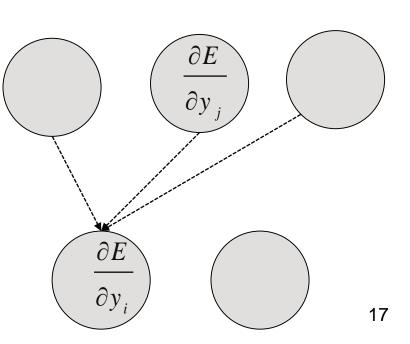
# Sketch of the backpropagation algorithm on a single training case

- 1. convert difference between each output and its target value into an error derivative
- 2. compute error derivatives in each hidden layer from error derivatives in the layer above
- 3. use error derivatives for activities to get error derivatives for the weights.

$$E = \frac{1}{2} \sum_{j} (t_{j} - y_{j})^{2}$$

$$\partial E$$

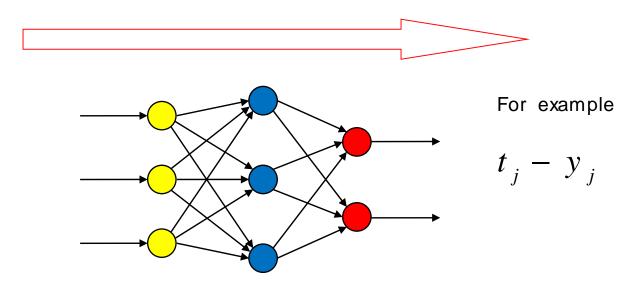
$$\frac{\partial E}{\partial y_j} = t_j - y_j$$



### **Training MLP**

### (1) Forward Pass

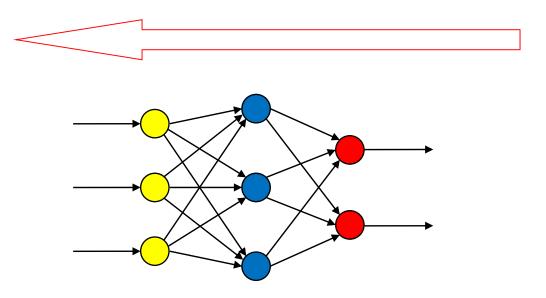
- Put the input values in the input layer
- Calculate the activations of the hidden nodes
- Calculate the activations of the output nodes
- Calculate the errors using the targets



### Training MLPs

#### (2) Backward Pass

- From output errors, update last layer of weights
- From these errors, update next layer
- Work backwards through the network
- Error is backpropagated through the network



### Training issues

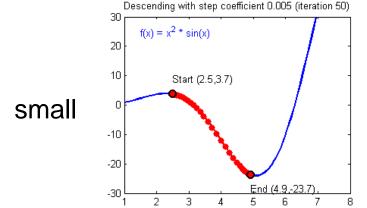
- How to update the weights?
  - After each training sample: Incremental/Online training
  - At the end of each epoch:
    - Batch training: Epoch ends when all training samples seen
    - Mini-batch training: Epoch ends when subset of training data seen
- How to choose the learning parameters?
  - Use a fixed learning rate
  - Adapt the learning rate?
  - Use steepest descent or not?
  - Add momentum?

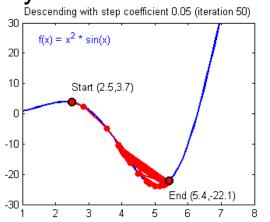
### Learning rate and momentum

- Tuning the learning rate
  - Too small: cannot escape local minima.
  - Too large: overshooting narrow valleys
- Momentum term

$$\Delta w_{jk}(t) = \eta \delta_k y_j + \left(\mu w_{jk}(t-1)\right)$$

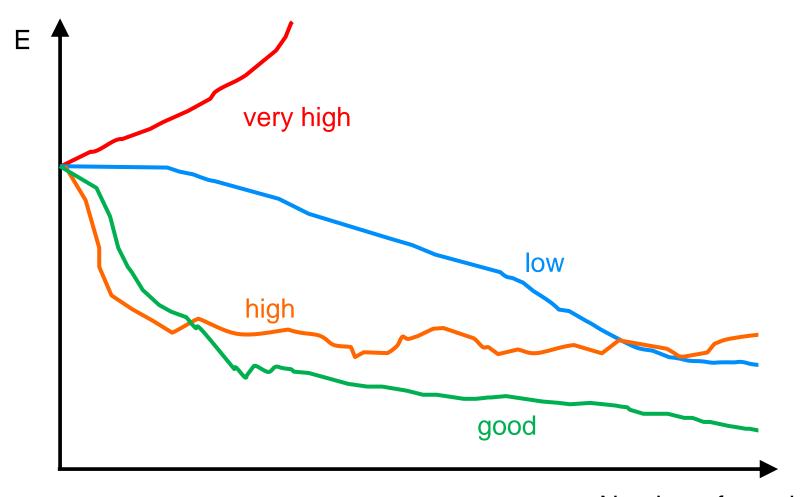
- Keep fraction of previous gradient
- Gradient keeps pointing in same direction: Increase step size
- Gradient keeps oscillating in valley: Slow down





large

## Learning rate

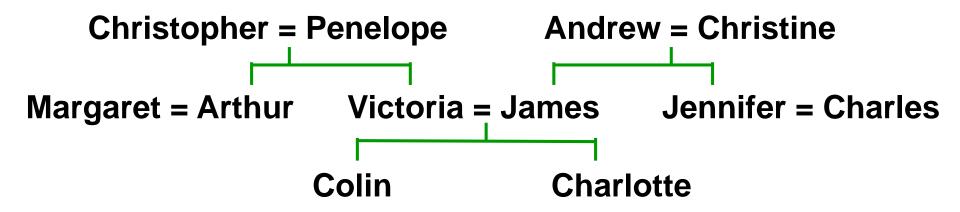


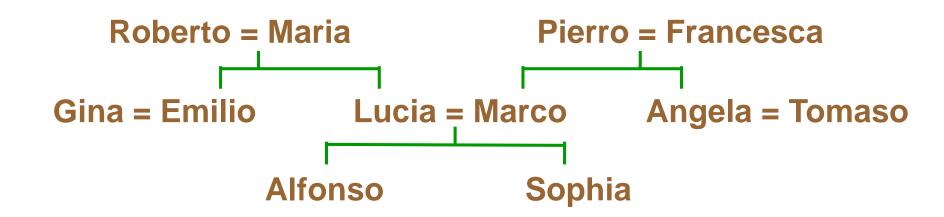
Number of epochs

## What can be learned with MLP and how to evaluate

- Supervised learning problems with input and output classes
- What problems:
- Classification problems (obvious supervised learning problem)
- Regression problems (obvious supervised learning problem)
- Prediction problems (obvious supervised learning problem)
- Symbolic knowledge relationships? (harder? not so obvious?)

### Example Problems: relational information





### Another way to express the same information

- Using the 12 relationships:
  - son, daughter, nephew, niece
  - father, mother, uncle, aunt
  - brother, sister, husband, wife
- Make a set of propositions
  - (colin has-father james)
  - (colin has-mother victoria)
  - (james has-wife victoria) this follows from the two above
  - (charlotte has-brother colin)
  - (victoria has-brother arthur)
  - (charlotte has-uncle arthur) this follows from the above

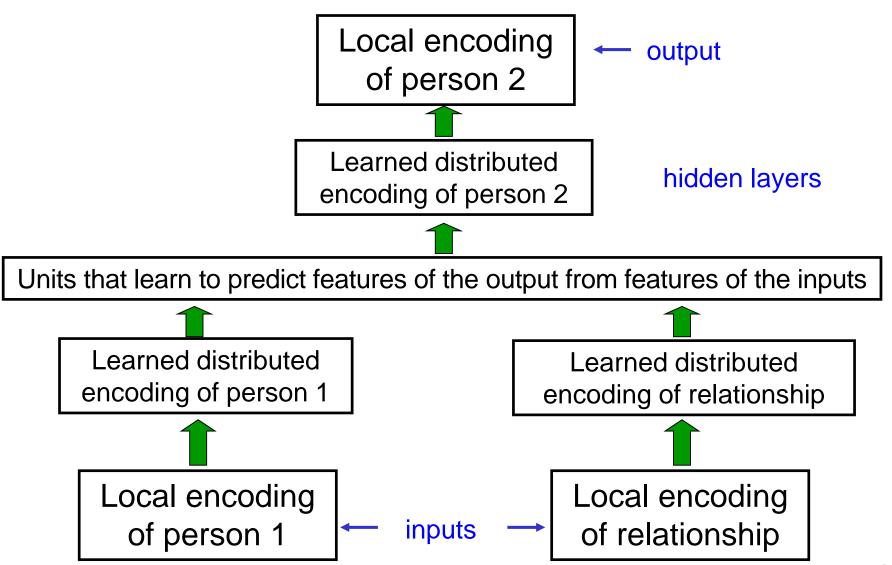
### A relational learning task

- Given a large set of triples that come from some family trees, figure out the regularities.
  - The obvious way to express the regularities is as symbolic rules

```
(x has-mother y) & (y has-husband z) => (x has-father z)
```

- Finding symbolic rules involves a difficult search through a very large discrete space of possibilities
- Can a neural network capture the same symbolic knowledge by searching through a continuous space of weights?

### One possible structure of a neural net



### One way to see that it works

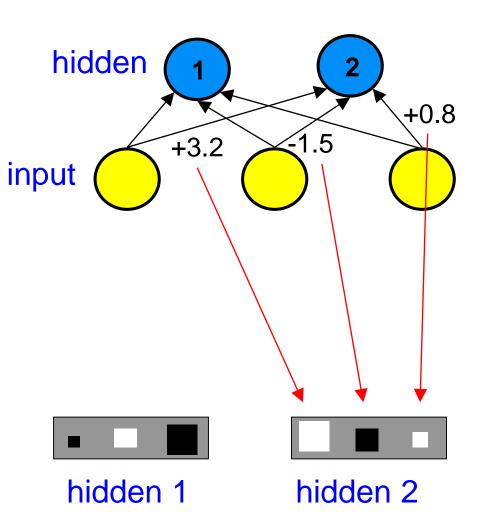
- Train the network on all but some of the triples that can be made using the 12 relationships
  - It needs to sweep through the training set many times adjusting the weights slightly each time.

Test the network

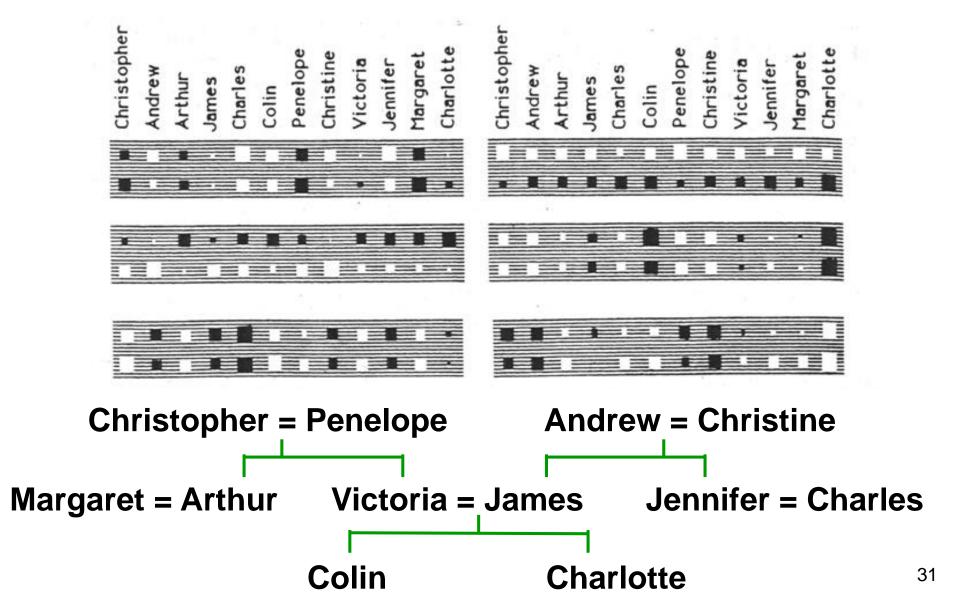
But what is the knowledge in a network ?

### How to interpret the weights of hidden units

- Obvious method is to show numerical weights for connections:
  - Try showing 25,000 weights this way…
- Its better to show weights as black or white boxes in the locations of the neurons that they come from
  - Better use of pixels
  - Easier to see patterns



# The weights of 24 input units (person) to 6 hidden units in second layer



### What the network learns

- Six hidden units connected to the input representation of person 1 learn to represent useful features for predicting answer.
  - Nationality, generation, branch of the family tree.
- Higher central layer learns how features predict other features.
  - For example:

```
Input person is of generation 3 and
```

relationship requires answer to be one generation up implies

Output person is of generation 2

### Why this is interesting

Debate in cognitive science between two rival theories about concept representation:

- Feature theory: Concept is a set of semantic features.
  - good for explaining similarities between concepts
- Structuralist theory: Concept meaning is in relationships to other concepts
  - conceptual knowledge best expressed as a relational graph

A neural net can use semantic features to implement the relational graph

- it learns the intuitively obvious consequences of the facts
- no explicit inference required (-> word2vec)

### Other prediction and classification examples

- We cannot identify phonemes perfectly in noisy speech
  - The acoustic input is often ambiguous: there are several different words that fit the acoustic signal equally well.
- People use their understanding of the meaning of the utterance to hear the right word.
  - We do this unconsciously and well
- Speech recognizers have to know which words are likely to come next
  - Can this be done without full understanding?

### The traditional standard "trigram" method

Count frequencies of all triples of words of text. Then use these frequencies to make bets on the next word in a b?

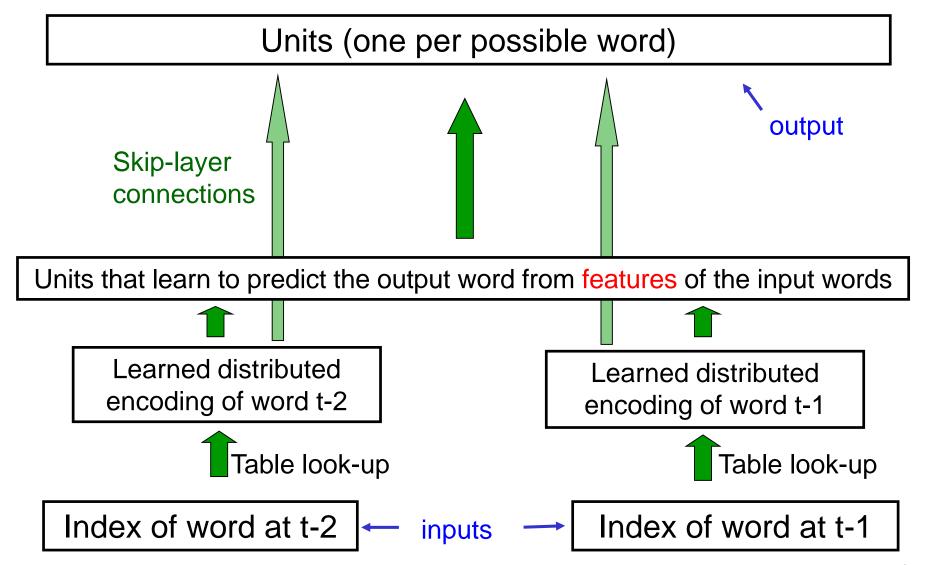
$$\frac{p(w_3 = c \mid w_2 = b, w_1 = a)}{p(w_3 = d \mid w_2 = b, w_1 = a)} = \frac{count (abc)}{count (abd)}$$

- Until recently this was state-of-the-art.
  - We cannot use a bigger context because there are too many quadgrams
  - We have to "back-off" to bigrams when the count for a trigram is zero.
    - The probability is not zero just because we did not see one.

### Why the trigram model is inefficient

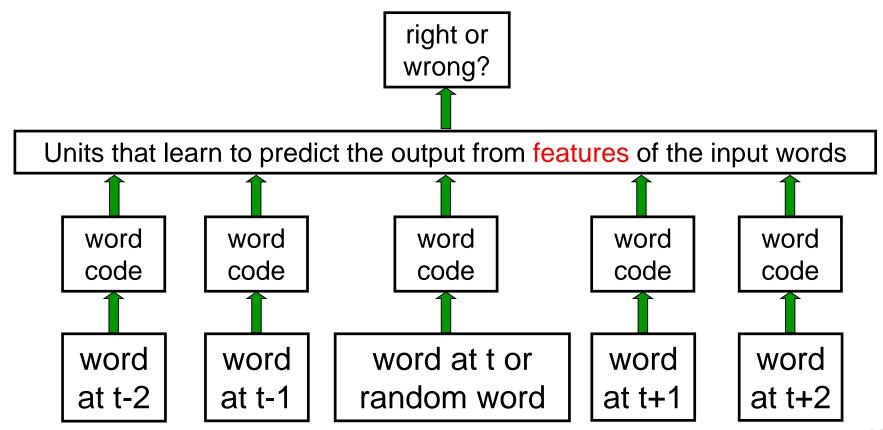
- Example sentence
   "the cat got squashed in the garden on friday"
- should to predict words in "the dog got flattened in the yard on monday"
- A trigram model does not understand the similarities between
  - cat/dog squashed/flattened garden/yard friday/monday
- Need to use features of previous words to predict features of next word
  - Using a feature representation and a learned model of how past features predict future ones, we can use many more words from the past history.

# Neural prediction: Bengio's neural net for predicting the next word



# Neural classification (Collobert and Weston network)

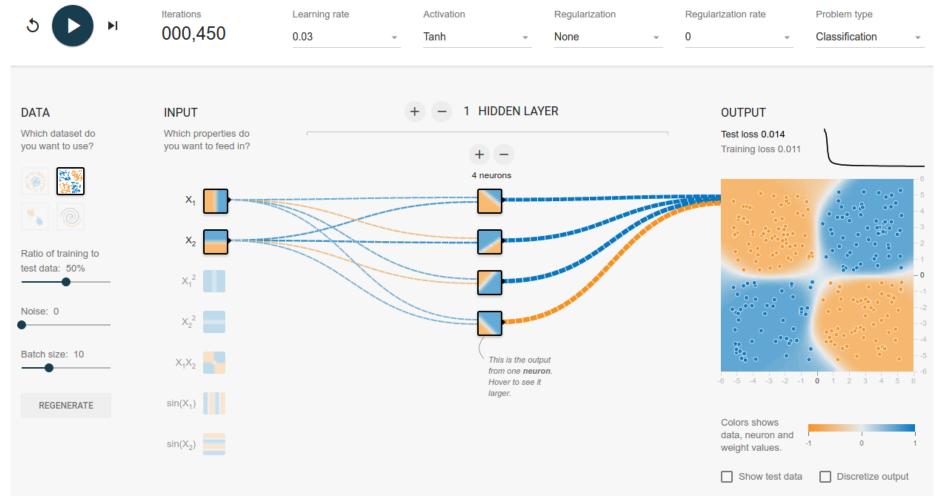
 Learn to judge if a word fits the 5-word context on either side of it. Train on ~600 million words.



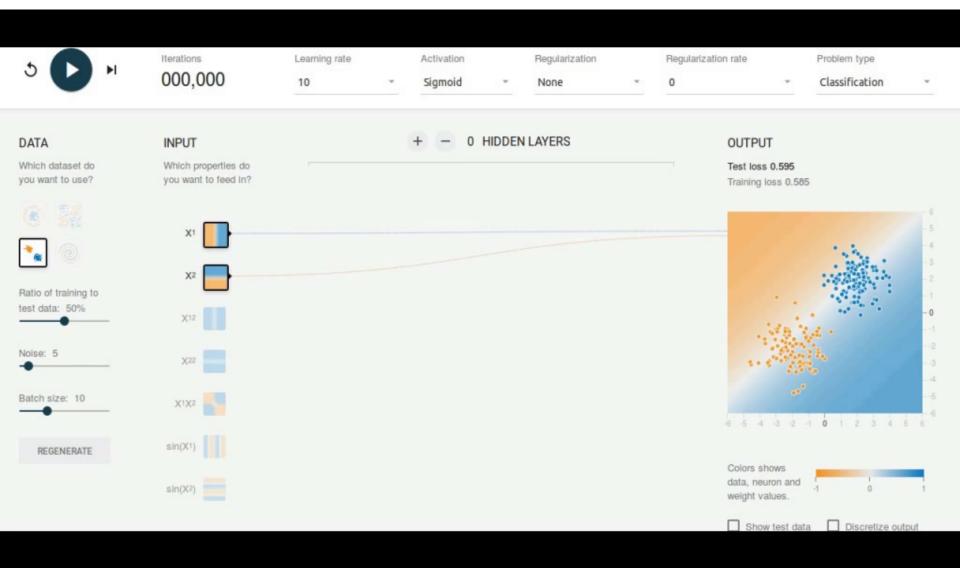
### Further success stories

- Backpropagation has been used for a large number of practical applications
  - Recognizing hand-written characters
  - Predicting the future price of stocks
  - Detecting credit card fraud
  - Recognizing speech
  - Predicting the next word in a sentence from the previous words
  - Understanding the effects of brain damage

# Try out your first neural network at a high level: playground.tensorflow.org



### **Demonstration**



### Universal Approximation Theorem

- The MLP is a universal approximator:
  - For every continuous, measurable function there is a Multilayer Perceptron (MLP) with 1 hidden layer and a finite number of units which approximates this function
- But careful:
  - We cannot guarantee an exact solution
  - We cannot guarantee that this theoretically existing network can in fact be *learned* with gradient descent

### Summary

- Multilayer Perceptrons are very effective in various classification, prediction, regression tasks.
- MLPs can be trained with gradient descent methods, e.g. the backpropagation algorithm
  - Suitable and derivable transfer functions are necessary.
  - Reasonable stopping criteria help to avoid overfitting.
  - Divergence during training can be avoided using momentum.
- MLPs also can be used to predict features of future events.
   Extension: Recurrent connections...

### **Further Reading**

- Recap:
  - Marsland (Chapter 3),
  - Goodfellow (Chapter 6.1 and 6.5)
  - Rojas (Chapters 6.1-7.3),
- Visual Proof of universal approximation theorem: <u>http://neuralnetworksanddeeplearning.com/chap4.html</u>
- http://playground.tensorflow.org/
- More in CommSy (Material > Literature and Background)