Application of AC-OPF with SOCP Wind farm-related power distribution network access an ESS

Yue Zhao Industrial Engineering Ira A. Fulton Schools of Engineering



Motivation

- Understanding the AC-OPF and SOCP.
- Comparing Several Relaxation Methods with Julia and PowerModels.
- Finding the best bus to locate an ESS in a Wind farm-related power distribution network

Copyright © 2021 Arizona Board of Regents

Optimal Power Flow(OPF)

- The goal of an optimal power flow (OPF) is to determine the "best" way to operate a power system.
 Usually "best" = minimizing operating cost.
 - Find a Power Flow distribution
 - Satisfy system operating constraints such as node voltage constraints, branch current/power constraints, generator power constraints, etc.
 - Find an optimal value for a certain aspect of the index, such as the lowest generation cost or the lowest system network loss

Copyright © 2021 Arizona Board of Regents

AC Optimal Power Flow(OPF)

sets:

N-buses

R- reference buses

 E, E^R - branches, forward and reverse orientation

 G, G_i - generators and generators at bus i

 L, L_i - loads and loads at bus i

 S, S_i - shunts and shunts at bus I

data:

 S_k^{gl} , $S_k^{gu} \forall k \in G$ - generator complex power bounds $c_{2k}, c_{1k}, c_{0k} \forall k \in G$ - generator cost components v_i^l , $v_i^u \forall i \in N$ - voltage bounds $S_k^d \forall k \in L$ - load complex power consumption $Y_k^S \forall k \in S$ - bus shunt admittance $Y_{ij}, Y_{ij}^c, Y_{ji}^c \forall (i,j) \in E$ - branch pi-section parameters $T_{ij} \forall (i,j) \in E$ - branch complex transformation ratio $s_{ij}^u \forall (i,j) \in E$ - branch apparent power limit $i_{ij}^u \forall (i,j) \in E$ - branch current limit $\theta_{ij}^{\Delta l}, \theta_{ij}^{\Delta u} \forall (i,j) \in E$ - branch voltage angle difference bounds

AC Optimal Power Flow(OPF)

variables:

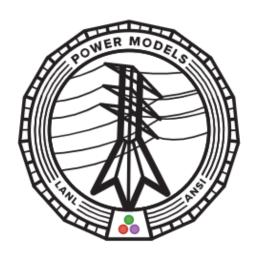
 $S_k^g \forall k \in G$ $V_i \forall i \in N$ $S_{ij} \forall (i,j) \in E \cup E^R$

minimize:

$$\sum_{k \in G} c_{2k} (R(S_k^g))^2 + c_{1k} (R(S_k^g))^2 + c_{0k}$$

subject to:

Implementing AC-OPF with Julia and PowerModels



PowerModels.jl

Take MATPOWER's case30.m as an example for testing

```
network_data = PowerModels.parse_file("D:/asu/IEE 598/Project/case30.m");|

ACP = instantiate_model(network_data, ACPPowerModel, PowerModels.build_opf);
result = optimize_model!(ACP, optimizer=CPLEX.Optimizer);
```

The solver does not support nonlinear problems (i.e., NLobjective and NLconstraint).

!! AC-OPF is Non-convex

(eg. $S_{ij} = V_{ij} I_{ij}$ is Non-convex)

Quick Comparison of Several Relaxation Methods with Julia and PowerModels

- Relaxation Methods
 - PowerModels.LPACCPowerModel The LPAC Cold-Start AC Power Flow Approximation
 - PowerModels.SOCWRPowerModel the Second-order cone relaxation
 - PowerModels. QCRMPowerModel the Recursive McCormik relaxations
 - PowerModels. QCLSPowerModel the "Quadratic-Convex" relaxation
- Comparison by solve time

```
solve time of LPACC is 0.054000139236450195
solve time of SOCWR is 0.03500008583068848
solve time of QCRM is 0.0820000171661377
solve time of QCLS is 0.07800006866455078
```

Second-Order Cone Programming(SOCP)

Second-order cone

$$C_k = \left\{ \begin{bmatrix} u \\ t \end{bmatrix} \middle| u \in R^{k-1}, t \in R, ||u|| \le t \right\}$$

second-order cone constraint

$$||Ax + b|| \le c^T x + d \Leftrightarrow \begin{bmatrix} A \\ c^T \end{bmatrix} x + \begin{bmatrix} b \\ d \end{bmatrix} \in C_k$$

second-order cone constraint in AC-OPF

$$S_{ij} = V_{ij} I_{ij} \iff I_{ij} = \frac{P_{ij}^2 + Q_{ij}^2}{V_i} \iff \left\| \frac{P_{ij}^2}{Q_{ij}^2} \right\|_2 \le V_{ij} I_{ij} \iff \left\| \frac{2P_{ij}}{2Q_{ij}} \right\|_2 \le \tilde{I}_{ij} + \tilde{V}_j, \forall ij \in E$$

AC-OPF with the Second-order cone relaxation

$$\min f(p,q,P,Q,V,I)$$

$$s.t.$$

$$\begin{cases} p_j = \sum_{k \in \mathcal{S}(j)} P_{jk} - \sum_{i \in \pi(j)} \left(P_{ij} - \tilde{I}_{ij} r_{ij} \right) + g_j \tilde{V}_j, \forall j \in B \\ \\ q_j = \sum_{k \in \mathcal{S}(j)} Q_{jk} - \sum_{i \in \pi(j)} \left(Q_{ij} - \tilde{I}_{ij} x_{ij} \right) + b_j \tilde{V}_j, \forall j \in B \end{cases}$$

$$\tilde{V}_j = \tilde{V}_i - 2 \left(P_{ij} r_{ij} + Q_{ij} x_{ij} \right) + \tilde{I}_{ij} \left(r_{ij}^2 + x_{ij}^2 \right), \forall ij \in E$$

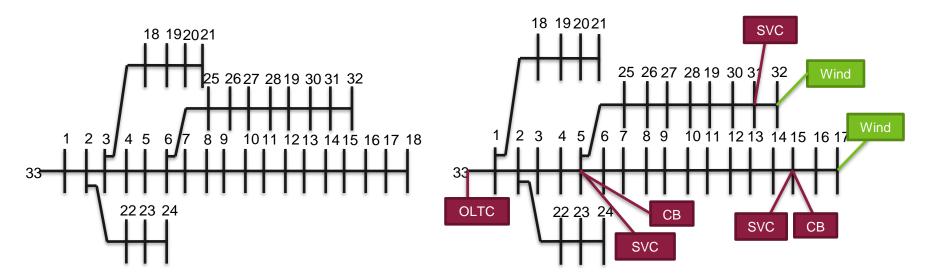
$$\left\| \begin{vmatrix} 2P_{ij} \\ 2Q_{ij} \\ \tilde{I}_{ij} - \tilde{V}_j \end{vmatrix} \right\|_2 \leq \tilde{I}_{ij} + \tilde{V}_j, \forall ij \in E$$

$$\underline{I}_{ij}^2 \leq \tilde{I}_{ij} \leq \tilde{I}_{ij}^2, \forall ij \in E$$

$$\underline{V}_j^2 \leq \tilde{V}_j \leq \tilde{V}_j^2, \forall ij \in B^+$$

Wind farm-related power distribution network with 33 buses

Take data from MATPOWER's case33bw



Add OLTC and Constraints

- On-Load Tap Changers (OLTC) regulates the voltage value on the low voltage side
- With the addition of OLTC, the substation bus node is converted into an adjustable variable.
- The following substitutions can be made:

$$\begin{cases} \sigma_{j,1,t}^{OLTC,IN} \geq \sigma_{j,2,t}^{OLTC,} \leq \sigma_{j,SR_{j,t}}^{OLTC,IN} \text{,} \forall t, \forall j \in B^{OLTC} \\ \sigma_{j,t}^{OLTC,IN} + \delta_{j,t}^{OLTC,DE} \leq 1 \text{,} \forall t, \forall j \in B^{OLTC} \end{cases} \\ \sum_{s} \sigma_{j,s,t}^{OLTC} - \sum_{s} \sigma_{j,s,t-1}^{OLTC} \geq \sigma_{j,t}^{OLTC,IN} - \delta_{j,t}^{OLTC,DE} SR_{j}, \forall t, \forall j \in B^{OLTC} \\ \sum_{s} \sigma_{j,s,t}^{OLTC} - \sum_{s} \sigma_{j,s,t-1}^{OLTC} \leq \delta_{j,t}^{OLTC,DE} SR_{j} - \delta_{j,t}^{OLTC,DE} \text{,} \forall t, \forall j \in B^{OLTC} \\ \sum_{s} (\sigma_{j,t}^{OLTC,IN} + \delta_{j,t}^{OLTC,DE}) \leq N_{j}^{OLTC,max} \text{,} \forall j \in B^{OLTC} \end{cases}$$

Add Reactive Power Regulator and Constraints

Capacitor Banks(CB)

$$\begin{cases} \sum_{s} \delta_{j,t}^{CB} \leq N_{j}^{CB,max} \\ -\delta_{j,t}^{CB} Y_{j}^{CB,max} \leq Y_{j,t}^{CB} \leq \delta_{j,t}^{CB} Y_{j}^{CB,max} \end{cases}, \forall t, \forall j \in B^{CB}$$

Static VAR compensation(SVC)

$$Q_{j}^{SVC,min} \le Q_{j,t}^{SVC} \le Q_{j}^{SVC,max}$$
, $\forall t, \forall j \in B^{SVC}$

Select which bus to add an ESS?

- Place the ESS on each bus in turn
- Add ESS constraints to the power system model
- The objective values are obtained by solving with the CPLEX solver.
- Find the minimum objective value and index its bus
- Get the best position for ESS

Select which bus to add an ESS?

Charging and discharging mode limitation

$$u_{j,t}^{discharge} + u_{j,t}^{charge} \le 1, \forall j \in B^{ESS}, \forall t$$

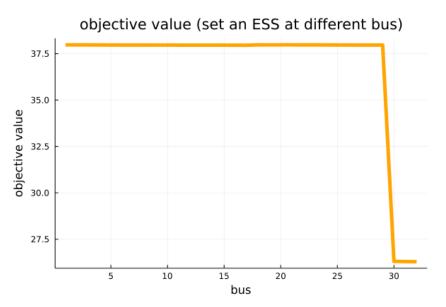
Power Limit

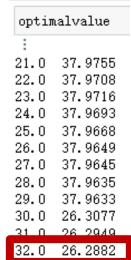
$$\begin{cases} u_{j,t}^{discharge} P_{j}^{discharge,min} \leq P_{j,t}^{discharge} \leq u_{j,t}^{discharge} P_{j}^{discharge,max} \\ u_{j,t}^{charge} P_{j}^{charge,min} \leq P_{j,t}^{charge} \leq u_{j,t}^{charge} P_{j}^{charge,max} \\ \forall t, \forall j \in B^{ESS} \end{cases}$$

Storage Limit

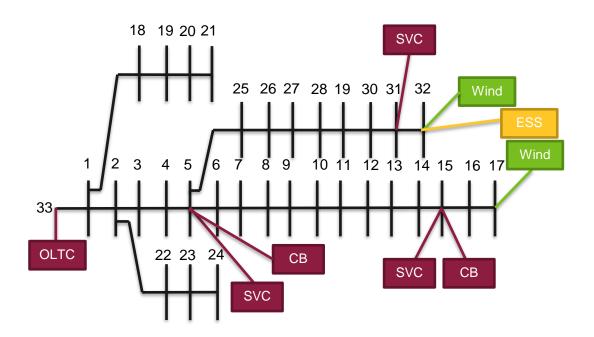
$$\begin{cases} E_{j+1}^{ESS} = E_{j,t}^{ESS} + \alpha_{j}^{charge} P_{j,t}^{charge} - \alpha_{j}^{discharge} P_{j,t}^{discharge} \\ E_{j}^{ESS,min} \leq E_{j,t}^{ESS} \leq E_{j}^{ESS,max} \end{cases}$$

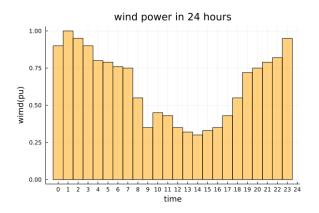
$$\forall j \in B^{ESS}, \forall t$$

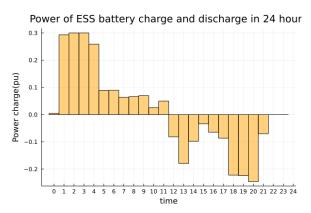


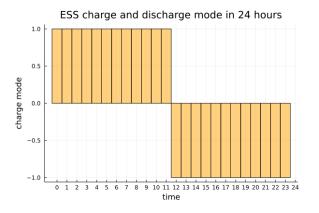


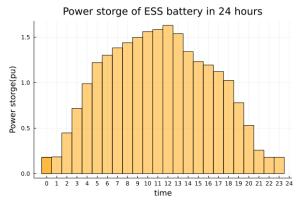
choose 32 bus to set an ESS

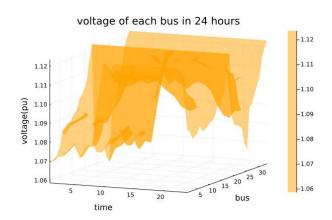


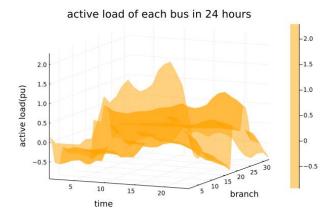


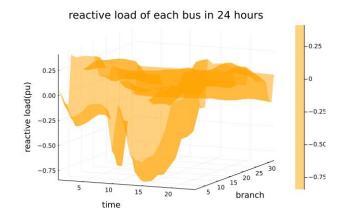












Future Research

- Considering a large scale grid
- Involving some geographical factors related to a real world case
- Adding more constraints to the model, like factors related to the electricity market

References

- [1]. Farivar, Masoud, and Steven H. Low. "Branch flow model: Relaxations and convexification—Part I." *IEEE Transactions on Power Systems* 28, no. 3 (2013): 2554-2564.
- [2]. Gao, Hongjun, Junyong Liu, Xiaodong Shen, and R. Xu. "Optimal power flow research in active distribution network and its application examples." In *Proceedings of the CSEE*, vol. 37, no. 6, pp. 1634-1644. 2017.
- [3]. Chertkov, Michael, Deepjyoti Deka, and Yury Dvorkin. "Optimal ensemble control of loads in distribution grids with network constraints." In 2018 Power Systems Computation Conference (PSCC), pp. 1-7. IEEE, 2018.
- [4]. Ponoćko, Jelena. Data Analytics-Based Demand Profiling and Advanced Demand Side Management for Flexible Operation of Sustainable Power Networks. Springer Nature, 2020.
- [5]. Carpentier, J. "Contribution to the economic dispatch problem." *Bulletin de la Societe Francoise des Electriciens* 3, no. 8 (1962): 431-447.
- [6]. Coffrin, Carleton, and Pascal Van Hentenryck. "A linear-programming approximation of AC power flows." *INFORMS Journal on Computing* 26, no. 4 (2014): 718-734.
- [7]. Jabr, Rabih A. "Radial distribution load flow using conic programming." *IEEE transactions on power systems* 21, no. 3 (2006): 1458-1459.

References

- [8]. Hijazi, Hassan, Carleton Coffrin, and Pascal Van Hentenryck. "Convex quadratic relaxations for mixed-integer nonlinear programs in power systems." *Mathematical Programming Computation* 9, no. 3 (2017): 321-367.
- [9]. Sundar, Kaarthik, Harsha Nagarajan, Sidhant Misra, Mowen Lu, Carleton Coffrin, and Russell Bent. "Optimization-based bound tightening using a strengthened QC-relaxation of the optimal power flow problem." arXiv preprint arXiv:1809.04565 (2018).
- [10]. CASE30. Description of case30. (n.d.). Retrieved November 18, 2021, from https://matpower.org/docs/ref/matpower6.0/case30.html.
- [11]. *CASE33BW*. Description of case33bw. (n.d.). Retrieved November 18, 2021, from https://matpower.org/docs/ref/matpower6.0/case33bw.html.
- [12]. The powermodels mathematical model. Mathematical Model · PowerModels. (n.d.). Retrieved November 18, 2021, from https://lanl-ansi.github.io/PowerModels.jl/stable/math-model/.