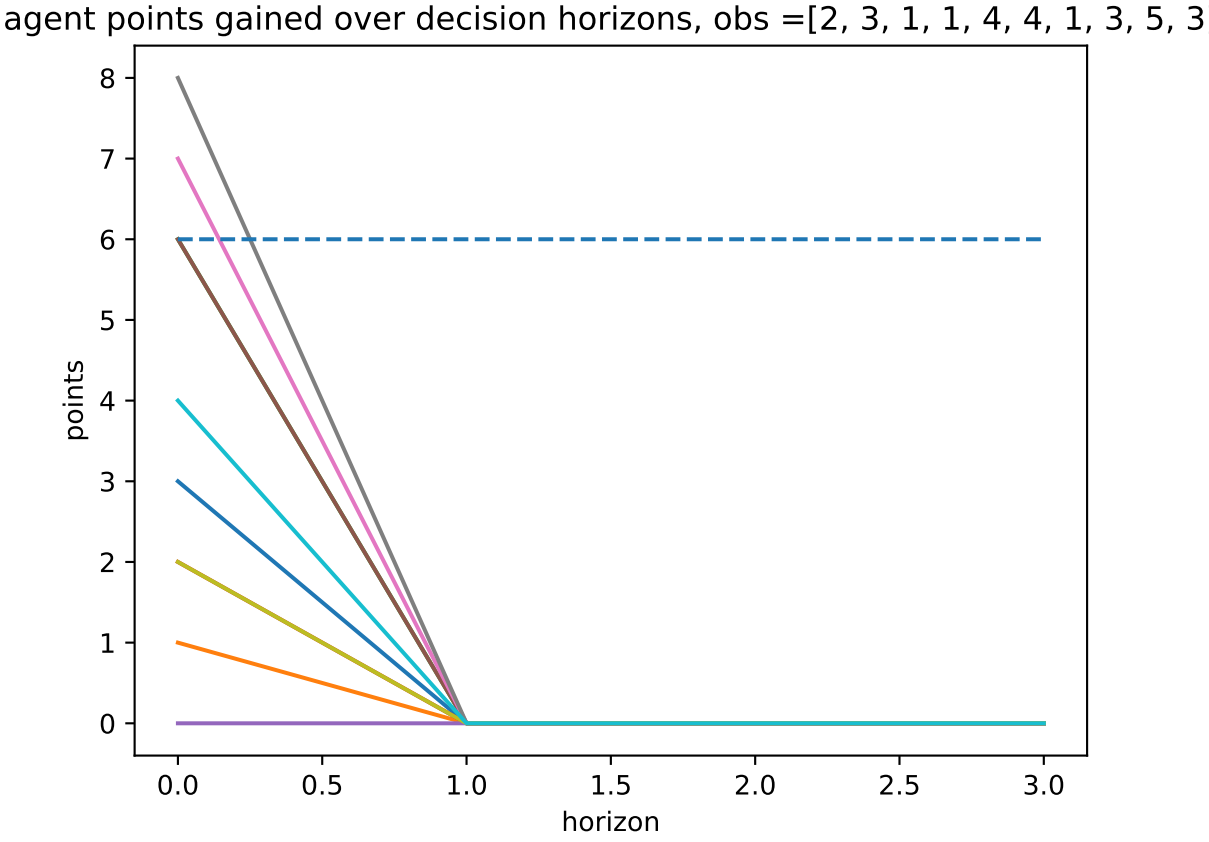
agent points gained over decision horizons, obs =[2, 3, 1, 1, 4, 4, 1, 3, 5, 3]
points
horizon
0
1
2
3
4
5
6
7
8
0.0
0.5
1.0
1.5
2.0
2.5
3.0