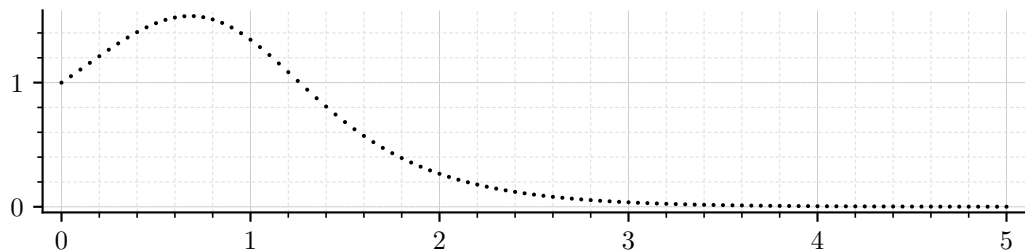
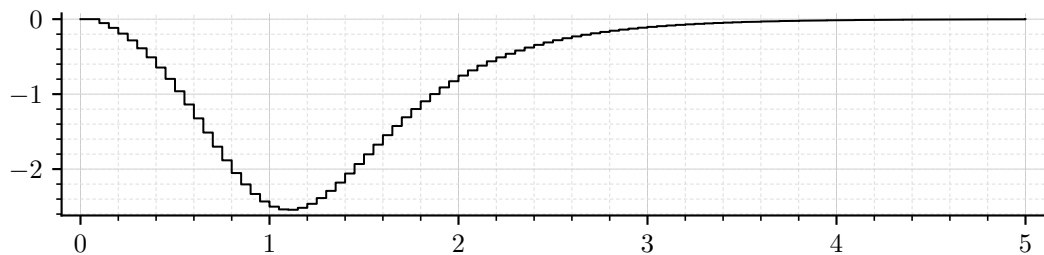


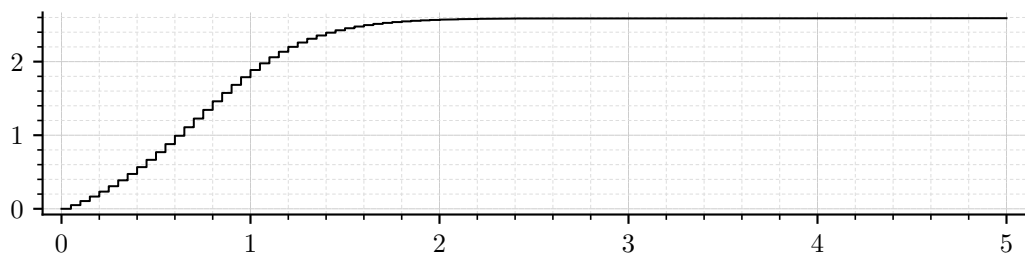
Výstup

• $x(t)$

Akčný zásah

— $u(t)$

Adaptovaný parameter

— $k(t)$