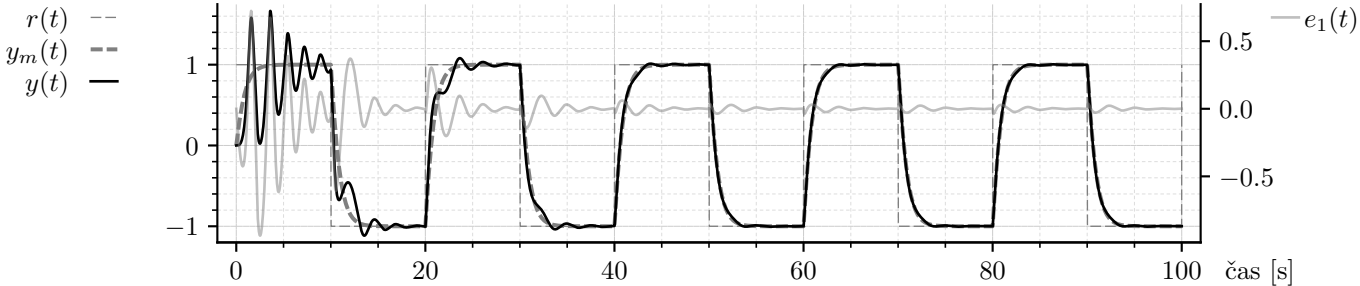


$r(t), y(t)$  $e_1(t)$  $u(t)$  $\Theta(t)$ 