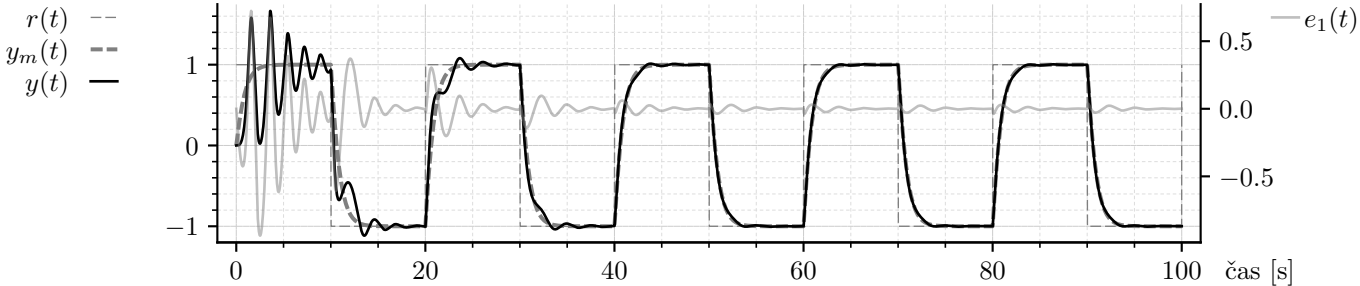


$r(t), y(t)$ $e_1(t)$  $u(t)$ $\Theta(t)$ 