QRAAT

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Abstract

This could eventually be our doc for QRAAT. For now, this just outlines configuration stuff for the prototype system. Build this doc with pdflatex (sudo apt-get install pdflatex).

Contents

1 Overview

1.1 Hardware

Along with the antenna, preamps, RMG receiver, batteries, and solar panels, a node in the QRAAT network consists of a router for the network, a field computer, and a network-addressible powerswitch. The last two are pictured together with the receiver in Figure 1.

Field computer. To run the software defined radio remotely, we require a headless system that can run on limited power and be able to withstand high temperatures. The ideal system would have no moving parts—fanless, solid-state memory instead of a harddrive—and draw only a few amps. However, in our tests with various solutions, we've concluded that a dual-core CPU is required at a minimum.[1] There are a number of products available that strike a comprimise between power consumption and processing power. The fit-PC3 suites our needs well.[2] The fit-PC3 has a dual-core, 32-bit AMD processor, 2 GBs of ram, and a 8GB solid state drive. Although it is designed to run any general-purpose desktop operating system, the fit-PC3 can easily be configured to run as a headless system. It even comes with a mini-rs232 console interface, although we don't make use of this in QRAAT. With our software running full-bore, the fit-PC3 draws 46 W.

Figure 1: Network powerswitch, field computer, and RMG receiver.

Powerswitch. A network-addressible powerswitch makes it possible to turn the equipment on and off remotely and, with certain products, monitor power levels. We've deemed this feature necessary for two reasons: one, an intermittent issue related to the RMG receiver's USRP[3] can be fixed by cycling the power; two, we need to be able to save energy. The powerswitch, field computer, and network router are connected via an ethernet switch. The field computer and RMG receiver are powered by the powerswitch. The computer's power is switched over the network by the server, and the the computer is set up to switch the receiver.

Again, there are various solutions for network power switching. Most of these input mains power, i.e. 120 V AC, and require us to mofidy them to work with our solar panels (12 V DC). The PingBrother EPIW104P[4] passive POE ethernet switch not only allows us to input the proper power, but provides an array of features uesful for our deployment of QRAAT. The EPIW104P can switch a 12 V DC relay instead of POE, and the ethernet ports can be used as a dumb switch. In addition, its http-based interface can be used to monitor the input voltage and power consumption. Our nominal hardware specification with the PingBrother powerswitch and fit-PC3 is as follows:

Network The network router and field computer are plugged into the powerswitch's ethernet switch. The powerswitch and computer are assigned static IP addresses in the subnet of the router. Static addresses are necessary because the QRAAT server must know how to reach the site; this information is not distributed when the node comes into the network. (See software overview section for details.)

Power The field computer's power is attached to the powerswitch's first relay on NC ("normally closed"). If power goes down and is then made availalbe, the field computer will be powered automatically. The

[1] One solution we tried was the net6501-70 from Soekris Engineering, which ships with a single 1.6 Ghz Atom core. The backend software was installed on top of the OpenWRT operating system, a stripped-down version of GNU/Linux meant for embedded systems. The Soekris board failed to process the radio signal at line-rate with the system running full-bore.

[2] For details, visit `fit-pc.com`.

[3] For details, visit `ettus.com`.

[4] For details, visit `pingbrother.com`.

RMG receiver is attached to the second relay on NO ("normally opened") so that it won't get power automatically.

Receiver The receiver has a two ports: one, a straight-through serial port for communication with the receiver's PIC interface, and two, a standard USB 2.0 port for data transfer from the USRP. The fit-PC3 doesn't have a straight-through serial interface, but an off-the-shelf a serial → USB converter is sufficient. The PIC uses a 9600,8n1 baud-rate/parity-bit scheme.

1.2 Software

We begin this section with an eagle eye view of the QRAAT dataflow. Each transmitter emits a periodic pulse on a specific radio frequency, e.g. 164.599 Mhz. The pulse is received and amplifed on four channels, then converted to a digital signal by the RMG receiver. The software-defined radio filters the signal and inputs it into a pulse detector. When the pulse detector is triggered, the signal region surrounding the pulse on all four channels is dumped to file. This kind of record is created for each pulse and each transmitter that the SDR is conifgured to listen to. These files are produced and store in memory locally on site; when the server requests them, they are tranferred over the network and removed from the field computer.

The backend software package is comprised of two elements: one, the software defined radio module, and two, a system for managing QRAAT's resources and collecting data. We now describe these in turn. This section refers to the software repository published on Github at `github.com/QRAAT`.

1.2.1 RMG module

The SDR pulse detector is implemented with a mixture of C++ and Python on top of GNU Radio.[5] In GNU Radio terms, the module is made up of a radio signal processing block with a suite of high-level applications that run it. The transmitters that the RMG module listen for are specified by a file called `tx.csv`. (See Appendix A for file format.) When the software starts, a signal filter and peak detector is instantiated for each frequency passed by `tx.csv`, up to 32. The pulse data files are stored in a directory structure that reflects the time and date it was created. For example:

```
/tmp/ramdisk/det_files/2013/03/22/15/20/03439743.det
```

The file name gives the second it was created with millisecond precision, i.e. `SSUUUUUU.det`.

1.2.2 Dataflow

Each QRAAT node has a state associated with it: *down*—computer should shutdown, *up*—computer should be on, but the RMG receiver should be off and not listening for transmitters, or *active*—the RMG receiver should be on and pulse detector should be running. The state is specified by a file on the server called `sitelist.csv`. (See Appendix A for file format.) Along with the state, the site list specifies the configuration information of each site. The parameters are:

1. *Name* - of the site,
2. *CompIP* - hostname or IP address of the remote computer,
3. *PowerIP* - hostname or IP address of the network addressible power source,
4. *CompOutlet* - outlet number of the computer,
5. *RxOutlet* - outlet number of the RMG receiver module,
6. *PowerType* - power source type, e.g. Netbooter, PingBrother, or WebPowerSwitch, and finally
7. *State*.

[5] `gnuradio.org`.

When a site's configuration information needs to be updated or the user wishes to change its state, the parameters *(PowerIP, RxOutlet, PowerType, State)* are transmitted to the site computer as a configuration file called `site.csv`.

Node. Although the node's *goal* state is specified by the server, the server cannot directly coerce its state; only the node can power on its RMG receiver and start the RMG module or power itself down. We've designed it this way so that the nodes can function independently of the server in case of network failure. In addition to controlling its own state, the node implements monitoring and error recovery by checking its state periodically. If the pulse detector crashes for any reason, the process is controlled by a monitor script that cycles the recevier's power and attempts to restart the module. If the process crashes a certain number of time before the system successfully reaches *active*, the node gives up. Each time the site's state is checked or transitioned, the *real* state, which we'll call *site status*, is reported to a file called `status.log`.

Server. There are three essential tasks that the server implements: one, pole the sites for status information, two, update the sites' configuration and goal state, and three, download and store pulse data. When a site is poled, the server collects network and site status. If the site is reachable, then the server reads the last line of `status.log`. Site status is reported as *(net_status, site_status)*. After a site is udpated (the `site.csv` file is transmitted to the field computer), the server instructs it to check its own state.

Finally, when the server fetches the pulse data files, it downloads all available files excluding those that were recently produced (within the last minute). This is to avoid attempting to download a file that is currrently being written. Note that this design critically depends on real time clock synchronization, which we achieve through the `ntpd`[6] daemon.

1.3 Usage

Dataflow and site management for the prototype system is implemented with shell scripts. The user-level programs are `rmg` and `rmg-node`. When invoked, they immediately set up environment variables specifying data, configuration files, etc.

rmg.[7] This program takes as arguments a task and a list of sites. Before performing the task, the status of the site is checked. Possible tasks are the following:

status — Just report site's current status as *(net_status, site_status)*.

update — Passive site update. Copy new `site.csv`.

up/down/start/stop — New goal state. Update `sitelist.csv` and copy new `site.csv`. Tell the site to check its new state.

on/off — Switch the field computer's power supply.

updatetx –file *FILE* — Update site's `tx.csv`.

cyclerx — Cycle the site's receiver power. This is needed sometimes.

fetch — Download `.det` files.

rmg-node. Control a site's state locally. This program is used for monitoring and is invoked by `rmg` when the user changes the site's goal state. It can also be safely called directly. As its argument, it accepts either a new state or `check`:

active — Check that RMG receiver is on and the SDR is running.

up — Check that the RMG receiver is off and the SDR is stopped.

down –delay *M* — Set a timer to shutdown. If M minutes have elapsed the next time state is checked, then poweroff the computer.

[6] Network time protocol (NTP).

[7] The name "rmg" is admittedly a bit of a misnomer, since it has nothing to do with "Rapid Multichannel Goniometers". It just stuck, I suppose.

check — Look up goal state in `site.csv` and transition as described above.

2 Dataflow specifications [REDO]

QRAAT has two main components: the remote field computers, which implement the initial signal detection, and the server, which collects data from the field computers for higher order processing. Here we outline the structure of these two components.

2.1 QRAAT node

Each field computer is configured to run the software defined radio. We are using fanless, low-power machines manufactured by fit-PC.[8] The fit-PC3 has a dual-core, 32-bit AMD processor, 2 GBs of ram, and 8 GBs solid-state persistent memory. They run stock Ubuntu Server 12.04. Along with the SDR implemented in GNU Radio, each is configured to run an ssh server, ntpdate, and other necessities.

The initial signal processing software outputs files corresponding to pulses with the extension `.det`. These are stored on a temporary file system in memory, located at /tmp/ramdisk/det_files. The pulse data files are stored in a directory structure according to the the minute in which they were recorded, for example:

```
/tmp/ramdisk/det_files/2013/03/22/15/20/03439743.det
```

The file name gives the second it was created with millisecond precision, i.e. `SSUUUUUU.det`. This is the last step on the field computers; these files are then collected by the server.

Each site has a user called *rmg* whose password—you guessed it—is *rmg*.

The QRAAT software is located in /home/rmg/QRAAT. We've set it up as a git repository that pulls from the RMG Server. To update the software, ssh to the site, switch to this directory, and type '`git pull`'. You will be prompted for the server's password.

The transmitter file is /home/rmg/tx.csv.

2.2 QRAAT server

Along with managing the field computers and collecting data, the server is responsible for callibration and triangulation. The `rmg` script allows us to power the computer and RMG module on and off, cycle the RMG module power, start and stop the software defined radio, update the field computer's transmitter file, and collect `.det`s. The server has a file called `sitelist.csv` that stores various parameters and the status of the RMG remotes:

1. *Name* - of the site,
2. *CompIP* - hostname or IP address of the remote computer,
3. *PowerIP* - hostname or IP address of the network addressible power source,
4. *CompOutlet* - outlet number of the computer,
5. *RxOutlet* - outlet number of the RMG receiver module,
6. *PowerType* - power source type, e.g. Netbooter, PingBrother, or WebPowerSwitch, and finally
7. *State* - is the site up, down, or active (SDR is running).

Following is a sample of a typical `sitelist.csv` file. Fields can be skipped if they aren't applicable to a particular site (e.g. site1 runs on the same machine as the server), but they must be deliniated by commas:

[8] For details, visit `fit-pc.com`.

```
name,comp_ip,power_ip,comp_outlet,rx_outlet,powertype,state
site0,10.0.0.55,10.0.0.56,1,2,pingbrother,active
site1,localhost,,,,,active
site2,10.2.1.55,10.2.1.56,1,2,netbooter,down
site10,10.10.1.55,10.10.1.56,1,2,webpowerswitch,up
```

`rmg` uses RSA encryption for ssh instead of prompting the user for a password each time. This is important since some of `rmg`'s routines, such as `rmg fetch`, make many ssh calls. The RMG remotes store the public part of the key and the server the private part.

We keep a copy of the software repository on the server from which the remote ocmputers pull; the server copy pulls directly from github.

3 Configuration instructions

3.1 Field computers

The field computers were configured by building and installing the software on one system, creating an image from its harddrive, and copying this image to the other sites. To create the image, we first installed a stock copy of Ubuntu Server 12.04 on a 7.5 GB partition, leaving 512 MB for swap. We configured no automatic updates, since these computers spend the majority of their time not connected to the internet. After booting the system and updating, the first thing to do is install the following packages via apt-get:

1. `git-core` - clone our software repository from github,
2. `openssh-server` - each field site needs to run an ssh daemon,
3. `minicom` - serial interface to RMG receiver module, and
4. `ntpdate` - remote computers will be clock synced to the server via `ntpd`.

3.1.1 Building and installing the software

Clone the online repository to get things going:

```
$ git clone github.com/QRAAT/QRAAT.git
```

The first thing to build is GNU Radio along with the UHD driver. For conveniance, we provide a copy of the gnuradio build script written by Marcus Leech. Type

```
$ QRAAT/build-gnuradio -v all
```

to start downloading and building. This may take a few hours; however, you'll only need to do this once. When the build finishes, it will output a couple post-install tasks. Make sure you do these. Next, building and installing the QRAAT software is essentially the same procedure, though it will take less than two minutes:

```
$ QRAAT/build-rmg -v install
```

Before testing your build, we need to setup communication with the RMG recevier's PIC interface. First we add a rule to udev[9] to set permissions for `/dev/ttyUSB0`, the serial interface for the RMG receiver. Create a new file:

```
$ sudo vi /etc/udev/rules.d/101-serial-usb.rules
```

[9] `udev` is a common domain on GNU/linux systems used to handle new devices when they're plugged in. For instance, when you installed GNU Radio, rules were installed for the USRP—a hardware component of the RMG receiver—and the UHD driver.

and type the following line:

```
KERNEL=="ttyUSB0", MODE="0666"
```

To verify that this worked, we'll try to communicate with the PIC via minicom. Open up the minicom configuration screen. Under *Serial port setup*, set *Serial Device* to `/dev/ttyUSB0`. Set *Bps/Par/Bits* to `9600 8N1`. Lastly, set *Hardware/Software Flow Control* to `No`. Restart minicom. See if you're able to communicate with it by typing "`?`".

3.1.2 Post-configuration

We don't want the RMG remotes to save their pulse data locally to disk; the files will be stored locally in memory. For this reason, we need to set up a ramdisk to be created at start up. Add the following line to the end of `/etc/fstab` (be careful!):

```
tmpfs   /tmp/ramdisk  tmpfs  nodev,nosuid,mode=1777,size=1024M   0   0
```

1 GB is reasonable since the field computers have 2 GBs of ram.

If linux shutsdown uncleanly, e.g. the site loses power, the GRUB bootloader will wait for user input before rebooting the operating system. This is bad for headless systems, so we need to configure GRUB to timeout in this situation. Add the following to /etc/default/grub:

```
GRUB_RECORDFAIL_TIMEOUT=2
```

Then type `sudo update-grub`.

Up until now, we've been using the field computer with a monitor, keyboard, and ethernet connection to the internet. The next thing we have to do is configure the network interface so that we can access it over ssh without a head. In /etc/network/interfaces, comment out the default ethernet interface and add a static IP address:

```
# auto eth0
# iface eth0 inet dhcp
auto eth0
iface eth0 inet static
  address 10.20.1.55
  netmask 255.0.0.0
```

To connect to the computer directly through an ethernet cable, just setup a static IP address on the host system in the same subnet. See the section on networking for details.

The next thing to do is change the system's hostname. This needs to be changed in two places: /etc/hostname and /etc/hosts.

Lastly, since we will be managing the power of this system remotely, we want to be able to shutdown and reboot the computer without typing in a sudo password. Type

```
$ sudo visudo
```

and add the following lines to the end of the sudoers file:

```
rmg ALL=NOPASSWD: /sbin/halt
rmg ALL=NOPASSWD: /sbin/reboot
rmg ALL=NOPASSWD: /sbin/poweroff
```

3.1.3 Creating an image

The preceeding configuration is time-consuming, though not difficult. For configuring many sites, it's best to create an image from a fully configured system and copy this to other sites. The simplest way to do this

is with a Ubuntu live-USB. Plug a monitor, keyboard, and mouse into the FitPC and boot a live copy of Ubuntu on a thumbdrive. Grab a terminal and make sure the harddrive is unmounted. ("`mount | grep "sda"`. Verify that /dev/sda is indeed the harddrive.) Plug in an external harddrive or thumbdrive that can fit the 8 GB file we're about to create. Change the directory to the external drive and run:

```
$ dd if=/dev/sda of=qraat.img bs=4K
```

To copy the image, boot another computer in the same way. Plug in the external drive, change to its directory, and type

```
$ dd if=qraat.img of=/dev/sda bs=4K
```

Both of these commands should take about 30 minutes. Once you've finished copying the image, you'll want to edit the hostname and network interfaces as described in the preceeding section.

3.2 Networking

Here are the configuration steps that need to be taken as of this writing (27 March).

3.2.1 West campus prototype

We won't have networking for this implementation. As they are the ethernet interfaces of the RMG remotes are configured with a static IP address 10.<site_no>.1.55 and netmask 255.0.0.0. To connect to it, the simplest thing to do is create an interface in network manager. *Network Manager* → *Edit Connections...*, in the *Wired* tab, choose *Add*. In *IPv4 Settings*, choose *Method = Manual*. Add an address like 10.253.1.55 with netmask 255.0.0.0. You should be good to go.

In lue of networking, we're collecting the data on external harddrives at all three sites. We can use udev to setup automounting, Create a new udev rule file, like /etc/udev/rules.d/ 90-hd-backup.rules and add the following lines:

```
ACTION=="add", SUBSYSTEMS=="scsi", KERNEL=="sd[a-h]1", RUN+="/bin/mount /dev/%k /media/backup"
ACTION=="remove", SUBSYSTEMS=="scsi", KERNEL=="sd[b-h]1",RUN+="/bin/umount /dev/%k"
```

3.2.2 Quail Ridge

The ethernet interface needs to be configured to use the Qurinet router as its gateway. In /etc/network/interfaces, you'll find an interface that is commented out. Uncomment this and comment out the old one.

```
# Default interface in Quirinet
auto eth0
iface eth0 inet static
  address 10.20.1.55
  netmask 255.255.0.0
  gateway 10.20.1.1
```

The second part is to make sure the git repository is pointed to the right place. In /home/rmg/QRAAT/.git/config, you'll find a line that reads

```
url = christopher@10.253.1.55:work/QRAAT # change me!
```

Change this to the correct user and directory and you're set!

Appendices

A Configuration files

QRAAT metadata is stored in CSV-style files. Elements are seperated by commas and spaces are not allowed. The first row specifies the column parameters.

tx.csv. The transmitter file maps a name to frequency and also passes parameters to the pulse detector. These are described in detail in the backend software manual.

```
use,name,freq,type,pulse_width,rise_trigger,fall_trigger,filter_alpha
yes,robin1,164.42,Pulse,20,3.0,2.0,0.01
yes,robin1_heart,164.65,Continuous,,,,
no,noisy,164.5,Pulse,20,1.010,1.005,0.01
yes,test_tx,165.99,Pulse,25,3.00,1.15,.001
yes,mouse1,164.3,Pulse,25,3.0,2.0,0.01
```

sitelist.csv. The site list stores information about the nodes that is needed by the server.

```
name,comp_ip,power_ip,comp_outlet,rx_outlet,powertype,state
site0,10.0.0.55,10.0.0.56,1,2,webpowerswitch,down
site1,localhost,,,,,up
site2,10.2.1.55,10.2.1.56,1,2,netbooter,up
site10,10.10.1.55,10.10.1.56,2,3,pingbrother,up
site13,10.13.1.55,10.13.1.56,1,2,pingbrother,active
site20,10.20.1.55,10.20.1.56,1,2,pingbrother,down
site21,10.20.1.55,10.21.1.56,1,2,pingbrother,active
```

site.csv. Each field computer has a file that specifies its own configuration. This is necessary so that it can switch the receiver's power, as well as check its own goal state.

```
power_ip,rx_outlet,powertype,state
10.13.1.56,2,pingbrother,active
```

status.log. Each field computer keeps a log as a time stamp in seconds since the epoch and its status when checked.

```
timestamp,site_status
1366307941,up
1366312980,active
1366312996,up
1366313467,down(300)
1366313445,shutdown
1366323435,down(300)
1366323974,up
```