

How resource abundance and stochasticity affect animals' spatial needs

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Abstract

Animals' spatial needs are thought to be tightly linked to the amount of resources within their habitats, such that animals living in productive habitats generally require less space than those in resource-poor habitats. This hypothesis has widespread empirical support, but existing studies have focused primarily on responses to the *mean* amount of resources, while responses to the variance around the mean are still largely unknown. This is not a trivial oversight. Animals adjust to variable environmental conditions, so failing to account for the effects of resource unpredictability can result in a limited understanding of animals' spatial needs. In this study, we first review the literature of studies that estimate animals' spatial needs as a function of resource abundance. We then leverage this information to provide a unifying framework and hypotheses for the effect of mean *and* variance in resources on animals' space use. Next, we use simulated movement data to demonstrate how the combined effects of mean and variance in resource abundance interact to shape predictable patterns in animal space use. Finally, we use real-world tracking data on a lowland tapir (*Tapirus terrestris*) from the Brazilian Cerrado to show how this framework can be applied to better understand the movement ecology of free-ranging animals. Results from the simulations and empirical examples are presented using a fully transparent approach that allows researchers to apply the framework to their own data and inform area-based conservation efforts.

Introduction

The amount of resources an organism is able to access is a strong determinant of its odds of survival and reproduction. Resource limitations can cause individuals to experience a negative energetic balance, which can then result in lower fitness (Le Bot et al. 2019; Hou et al. 2020), changes to community structure (Burson et al. 2018; Ghislandi et al. 2018; Haney and Siepielski 2018; Riotte-Lambert and Matthiopoulos 2020), altered physiology (Wessling et al. 2018; Le Bot et al. 2019; Rocha et al. 2021; Dai Pra et al. 2022), lower chance of reproduction (Douglas and Pearce-Higgins 2014; Le Bot et al. 2019; Schmidt et al. 2020; Stefanescu et al. 2021), and even death (Foley et al. 2008; Berger et al. 2018). Thus, many organisms will adapt their behaviors in response to changes in local resource abundance to ensure their needs are met. Some species may respond to fluctuations in resource abundance by, if possible, switching to other food sources (Le Bot et al. 2019; Steinmetz et al. 2021), reducing energetic costs by reducing body heat (Schmidt et al. 2020), or entering hibernation or torpor (Boyles et al. 2020; Mohr et al. 2020; Fjelldal et al. 2021), but movement represents one of the most readily available traits that species can adjust, whether this be by modifying their home range (Lucherini and Lovari 1996; Relyea et al. 2000; Arechavala-Lopez et al. 2019; Bista et al. 2022; Bradsworth et al. 2022; Yu et al. 2022), migrating (Middleton et al. 2018; Geremia et al. 2019), dispersing (framework: Southwood 1977; amphibians: Cayuela et al. 2020; Wheat et al. 2017; birds: Pretorius et al. 2020; mammals: Singh et al. 2012), or moving nomadically (Nandintsetseg et al. 2019; Teitelbaum and Mueller 2019).

The relationship between animal movement and resource abundance has been of interest to biologists for over half a century. Burt (1943) considered the search for food as the primary driver for animal movement within an animal's home range. Three decades after, Southwood (1977) suggested that change in resource abundance is a strong determinant of how animals decide where to live and when to reproduce. Two years later, Harestad and Bunnel (1979) proposed that the simplest relationship between resource abundance and an

animal's home-range size is

$$H = C/R, \quad (1)$$

where H is the animal's **home-range size**, C is the animal's resource consumption, and R is the **resources** an animal can access. However, a species' spatial requirements depend strongly on its metabolic rate, diet, and body weight (Harvey and Clutton-Brock 1981, 1981; Gittleman and Harvey 1982; Lindstedt et al. 1986; Reiss 1988; Boratyński 2020; Noonan et al. 2020).

While many researchers have demonstrated that animals adapt their home ranges in response to resources abundance, few studies build upon others' previous work. Instead, results are reported as independent, *de-novo* findings. Consequently, we currently lack a unifying framework for quantifying the effects of resource abundance on animals' spatial needs. In addition, while much work has been done on estimating animals' responses to average resource abundance, there is little to no information on how they respond to unpredictable changes in resources.

In this paper, we refer to a location's average amount of resources as **resource abundance**, while use the phrase **resource stochasticity** to indicate the variability in resource abundance due to unpredictable causes. We argue that, on its own, a habitat's long-term resource abundance is not sufficient to assess the habitat's quality. For instance, a grassland with relatively low but constant forage availability will clearly require drastically different behaviors and adaptations from a desert location with equally scarce forage but rare, sudden, and strong pulses of resources. In the first scenario, an animal may require a large but constant home range as it moves between locations in search of food, while an animal in the second scenario may switch between dispersal as it searches for high-resource patches and short-term range residency until the local resources are depleted. Although it may be possible for both habitats to have the same long-term average resource abundance, the differences in resource unpredictability result in substantially different movement strategies being

selected for. Although it is generally expected that resource unpredictability will decrease animals' fitness and a landscape's energetic balance (Chevin et al. 2010), there is little empirical evidence to support this hypothesis (but see: Herfindal et al. 2005; Nilsen et al. 2005; Rizzuto et al. 2021).

Here, we illustrate how animals' spatial needs depend on the abundance and unpredictability of resources. First, we set the theoretical background necessary for the successive sections by introducing concepts and notations without assuming any previous knowledge of statistics or movement ecology. Next, we provide a review of the effects of resource *abundance* on animals' spatial needs while suggesting a unifying hypothesis. Afterwards, we provide a review of the effects of resource *stochasticity* on animals spatial needs while suggesting a second unifying hypothesis. Subsequently, we test the two hypotheses using quantitative, simulated responses to changes in resource abundance and unpredictability. Finally, we demonstrate how this framework can be used in practice to describe the movement ecology of a lowland tapir (*Tapirus terrestris*) from the Brazilian Cerrado (Medici et al. 2022). Results from the simulations and empirical example are presented using a fully transparent approach that allows researchers to replicate the work and apply the methods to their own tracking data.

Concepts and definitions

Resources as a random variable

In statistics, **random variables** indicate random (i.e., unknown) quantities and are indicated with capital letters (e.g., R). Known values, such as realizations of random variables (i.e., known observations or instances), are indicated with lower-case letters (e.g., r). Using this notation, we can write the statement “the probability of random variable R taking the value r ” as $P(R = r)$. Resource abundance is often unpredictable (and hard to quantify), since it depends on a variety of factors which cannot be accounted for easily, including cli-

mate, weather, competitive pressure, and individual- and species-specific energetics. Thus, we can let the random variable R indicate the resource abundance at a given point in space and time.

Probability distributions

Random variables are defined by specifying the **distribution** the variable is assumed to follow (e.g., Gaussian, Gamma, Poisson, Beroulli). Since the variable is random, it can take multiple possible values, each with different probabilities. The set or range of values which have non-zero probabilities in a distribution are referred to as the distribution's **support**.

There are many distributions we can assign to R , depending on how we quantify it. If R is the number of calories an animal is able to access from food in a given location, we can let R follow a distribution with support over all real numbers between 0 and infinity, which we can indicate with $R \in (0, \infty)$,¹ such as a Gamma or log-normal distribution. If R is a discrete variable, such as the number of prey in a location during a period of time, we can use a Poisson or negative binomial distribution. Alternatively, if we measure R using the Normalized Difference Vegetation Index (**NDVI**, see Pettorelli et al. 2011), we should use a distribution with support over the interval $[-1, 1]$, since NDVI can only take on values between -1 and 1 (extremes included).

Expected resource abundance, $\mathbb{E}(R)$

Since the exact value of R at a given time and location is unknown, comparing the magnitude in R between two locations or time periods requires a quantitative measure of what value we believe R will take, on average. The **expectation** of a random variable is the value one can *expect* the random variable to take, on average, in the long term. Thus, we can let $\mathbb{E}(R)$ indicate the expectation of the random variable R . When the mean changes over time, such as in strongly seasonal regions, we explicitly indicate that $\mathbb{E}(R)$ changes over time by writing

¹We use round parentheses rather than square brackets (i.e., $[0, \infty]$) because neither 0 nor infinity are included in the distribution's support set.

$\mathbb{E}(R)$ as a function of time, t : $\mu(t)$. We indicate the *estimated* average resource abundance over time by adding a caret on the symbol: $\hat{\mu}(t)$.

The hypothesis that spatial needs decrease with resource abundance, $\mathbb{E}(R)$, is commonly accepted and well supported, but many studies assume a linear relationship (e.g., Harestad and Bunnel 1979; Relyea et al. 2000; McClintic et al. 2014; Rizzuto et al. 2021; Bista et al. 2022; Bradsworth et al. 2022). This is problematic because a linear relationship can lead to questionable estimates and problematic biases, such as negative or excessively small home ranges (e.g., figure 2 in the work of Bista et al. 2022). Conceptually, the relationship between spatial needs and $\mathbb{E}(R)$ must be nonlinear, since there are limits to how much space an animal is able to explore in its lifetime as well as the minimum amount of space it requires to survive (which is necessarily greater than zero). As $\mathbb{E}(R)$ increases, we expect animals' spatial requirements to decrease nonlinearly until they reach the smallest amount of space required to survive (e.g., Relyea et al. 2000; Herfindal et al. 2005; Nilsen et al. 2005).

Variance in resource abundance, $\mathbb{V}(R)$

In viewing resources as a random variable, we not only obtain a formal framework for describing $\mathbb{E}(R)$, but also the spread around $\mathbb{E}(R)$. A random variable's **variance** is a measure of its unpredictability (i.e., variability). We use the notation $\mathbb{V}(R)$ to indicate the variance in R after accounting for changes in $\mu(t)$ and $\widehat{\sigma^2}(t)$ to indicate its estimate over time. Consequently, while one may consider R to vary within years, we define $\mathbb{V}(R)$ as the variation in R after accounting for the fact that R is (predictably) lower during some seasons and higher in others. Additionally, we distinguish between two different sources of variation: We refer to known or expected spatiotemporal differences or changes as **heterogeneity**, which we consider as a change in $\mu(t)$. In contrast, we use the term **stochasticity** for unpredictable and unexpected variation (i.e., due to $\sigma^2(t)$). For example, the location of (high-yield) berry bushes in a valley and the time at which they produce fruit may be heterogeneous, but it becomes predictable once a bear visits all patches in the valley. In contrast, whether next

year will be a good or bad year for berries is stochastic because it depends on factors the bear cannot predict.

Simulating resource abundance

In this paper, we simulate R using a Gamma distribution with time-dependent mean $\mu(t)$ and time-dependent variance $\sigma^2(t)$, which we write as $R \sim \Gamma(\mu(t), \sigma^2(t))$. Although Gamma distributions are more often parameterized using parameters shape and scale (k, θ) or shape and rate $(\alpha, \beta = 1/\theta)$, we use $\mathbb{E}(R) = k\theta$ and $\mathbb{V}(R) = k\theta^2$ to facilitate visualizing the simulations. However, note that $\mathbb{E}(R)$ and $\mathbb{V}(R)$ are not independent because the variance depends strongly on the mean (and vice-versa): As the mean approaches zero (from the positive side, which we write as $\mathbb{E}(R) \rightarrow 0^+$) the variance also does: $\mathbb{E}(R) \rightarrow 0^+ \iff k\theta \rightarrow 0^+ \iff k\theta^2 = 0^+ \iff \mathbb{V}(R) = 0^+$. This assumption also holds biologically: In the example from above, a mean of zero kg of berries within the bear's habitat during winter implies the variance in berries is also zero.

Estimating resource abundance using NDVI

In this paper's empirical example, we estimate resource abundance using NDVI (for more information, see the relevant section later in the paper and Pettorelli et al. 2011). However, since there is no commonly used distribution with a support over the interval $[-1, 1]$ we scale NDVI to the interval $[0, 1]$ to use a Beta distribution by applying the **linear transformation**

$$\nu_{[0,1]} = \frac{\nu + 1}{2}, \quad (2)$$

where ν indicates the NDVI value (see Denny 2017 for more information on transforming response data). In this case, we can define R as following a Beta distribution with mean and variance that depend on time using the notation $B(\mu(t), \sigma^2(t))$. We use this parameterization here for ease of explanation, but note that Beta distributions are generally parameterized using the shape parameters α and β such that the mean is

$$\mathbb{E}(R) = \frac{\alpha}{\alpha + \beta} \quad (3)$$

while the variance is

$$\mathbb{V}(R) = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)}. \quad (4)$$

We can easily convert $\mu(t)$ and $\sigma^2(t)$ back to mean and variance in NDVI using the inverse of equation (2):

$$\nu = 2\nu_{[0,1]} - 1. \quad (5)$$

Consequently, we have

$$\mathbb{E}(\nu|t) = 2\mu(t) - 1. \quad (6)$$

and

$$\mathbb{V}(\nu|t) = 2^2\sigma^2(t) + 0 = 4\sigma^2(t). \quad (7)$$

Particular attention should be given when deciding what distribution to use and how to estimate means and variances in R . Improper models and simulations of resource abundance can fail to produce robust, sensible, and accurate estimates of R .

Effects of resource abundance, $\mathbb{E}(R)$

While animals' needs vary greatly between taxonomic groups, some needs are essential for most species for survival and reproduction. All heterotrophic organisms require sources of chemical energy (i.e., food), water, and various limiting nutrients to survive, grow, and reproduce (Harvey and Clutton-Brock 1981; Baldwin and Bywater 1984; Reich 2001). Failing

to acquire sufficient resources can result in lower fitness, behavioral changes, physiological changes or damage, inability to reproduce, and death. Motile organisms can move to new locations in search of resources, but they must also account for a higher metabolism and movement costs (Taylor et al. 1982).

An animal's spatial needs are often hypothesized to depend on resource abundance (Burt 1943), such that spatial needs are high when resources are scarce and low when resources are abundant, but, as noted above, the relationship is necessarily non-linear, as illustrated in figure 1 (also see: Lucherini and Lovari 1996; Herfindal et al. 2005; Nilsen et al. 2005; Simcharoen et al. 2014; Watson 2020; and contrast them to estimates based on linear models, e.g.: Relyea et al. 2000; Rizzuto et al. 2021; Bista et al. 2022). Low values of $\mathbb{E}(R)$ force animals to have larger home ranges (Lucherini and Lovari 1996; Relyea et al. 2000; Herfindal et al. 2005; Nilsen et al. 2005; Bista et al. 2022), migrate to better locations (Samarra et al. 2017; Middleton et al. 2018; Geremia et al. 2019), or move nomadically (Singh et al. 2012; Polansky et al. 2015; Nandintsetseg et al. 2019; Teitelbaum and Mueller 2019), although large-scale changes in behavior (such as species-wide shifts to dispersal, migration, or nomadism) are more likely to occur over evolutionary timescales than over an animal's lifespan.

Animals living in large groups will often require larger home ranges because they will have to share resources with conspecifics (Prox and Farine 2020), but larger home ranges can

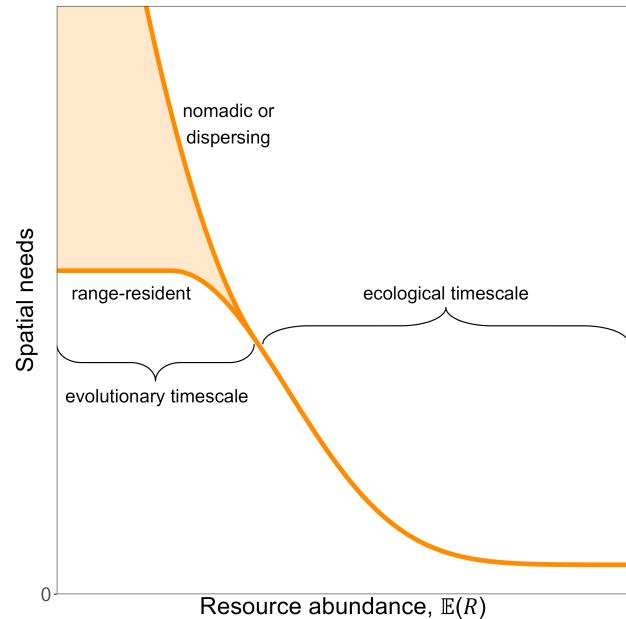


Figure 1: Hypothesized spatial needs of an animal as a function of resource abundance ($\mathbb{E}(R)$). We expect low values of $\mathbb{E}(R)$ to result in high spatial needs as animals are forced to explore large areas to collect the resources they require to survive, whether they be range-resident or nomadic. As $\mathbb{E}(R)$ increases, spatial needs should decrease nonlinearly until they reach the minimum amount of space required by the animal to survive. Note that the relationship between $\mathbb{E}(R)$ and spatial needs cannot be linear because it would require spatial needs to be negative for high values of $\mathbb{E}(R)$.

et al. 2005; Nilsen et al. 2005; Bista et al. 2022), migrate to better locations (Samarra et al. 2017; Middleton et al. 2018; Geremia et al. 2019), or move nomadically (Singh et al. 2012; Polansky et al. 2015; Nandintsetseg et al. 2019; Teitelbaum and Mueller 2019), although large-scale changes in behavior (such as species-wide shifts to dispersal, migration, or nomadism) are more likely to occur over evolutionary timescales than over an animal's lifespan.

be harder to defend and also result in higher rates of competition and movement costs (Grant 1993; Jetz et al. 2004; but also see Dickie et al. 2022). While competition may push animals to explore other areas and expand their home range (Jetz et al. 2004), strong and consistent competition paired with territorial defense may also prevent them from doing so (wolves: Rich et al. 2012; feral cats: Bengsen et al. 2016; Capuchin monkeys: Tórrez-Herrera et al. 2020). It is unclear when animals switch from range residency to migration or nomadism (or vice-versa), but understanding the connection between these types of movement is important for quantifying the effect of resource abundance on animal's spatial needs and when an animal may choose to migrate or disperse rather than remaining range-resident (mammals: Teitelbaum et al. 2015; moose: Singh et al. 2012; eagles: Wheat et al. 2017; Poessel et al. 2022; flamingos: Pretorius et al. 2020).

Consider the scenario where the average in resource abundance, $\mathbb{E}(R)$, changes over time but $\mathbb{V}(R) = \sigma^2 > 0$ is constant over time and space (see figure 2a). We can use the notation $R \sim \Gamma(\mu(t), \sigma^2(t))$ to indicate that R follows a Gamma distribution with a mean $\mu(t)$ that changes over time (i.e., it is a function of time) while the variance is constant (figure 2b). Since R is spatiotemporally random, an animal that moves in the landscape will not find the same R at different time points or throughout the habitat. However, if $\mu(t)$ changes repetitively and regularly over time (e.g. peaks each spring and is lowest in winter), an animal may learn to predict times of high or low R (Samarra et al. 2017; Abrahms et al. 2019; Geremia et al. 2019; e.g., Falcón-Cortés et al. 2021), but it will not be able to predict *where* R is high if $\mathbb{E}(R)$ does not vary predictably over space.

This model is somewhat simplistic, but its simplicity makes it easy to fit and conceptualize. Such a model may be appropriate in regions where variability does not change noticeably spatiotemporally, or when data availability is too low to produce appreciable measures of changes in variance. Examples of temporally homogeneous habitats include regions where productivity remains fairly predictable throughout the year (e.g., equatorial rain forests or highly homogeneous deserts). When productivity is approximately stable over long periods

of time, it may be possible to further simplify the model by assuming a constant mean, but this is likely rarely the case. Most often, $\mathbb{E}(R)$ will vary over time, and animals' behaviors will change in response. The need to account for $\mathbb{V}(R)$ is compounded by recent changes in climate, which exposes species to novel situations and increasingly common stochastic events (IPCC 2018; Noonan et al. 2018; Yao et al. 2022).

Effects of resource stochasticity,

$$\mathbb{V}(R)$$

Although the effect of R on animals' spatial needs is often recognized and accounted for in ecology (Burt 1943; Southwood 1977; Lucherini and Lovari 1996; Relyea et al. 2000; Nilsen et al. 2005; Williams-Guillen et al. 2006; Rickbeil et al. 2019), most of the focus has been on the effects of $\mathbb{E}(R)$, while $\mathbb{V}(R)$ has received far less attention (but see Nilsen et al. 2005; Di Stefano et al. 2011; Rizzuto et al. 2021; Seigle-Ferrand et al. 2021). However, $\mathbb{V}(R)$ can fluctuate both spatially and temporally due to many important drivers, including repetitive and predictable patterns as well as infrequent and unpredictable events. For example, berries are predictably scarce out of the growing season, but their abundance more stochastic when in spring and summer since the timing between plants can depend on many unpredictable factors, and an animal may explore a location only after competitors ate all the berries. Thus, while a bear cannot to expect

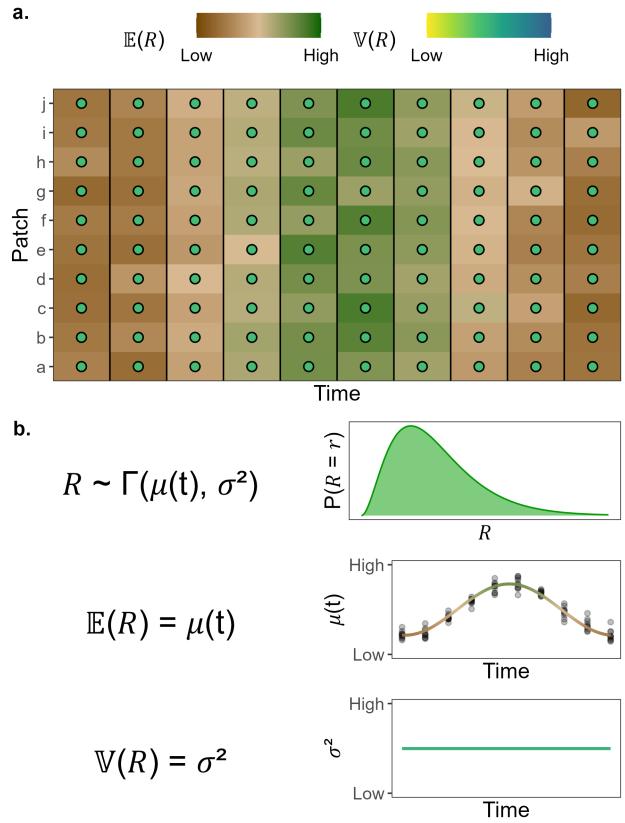


Figure 2: Fictitious example of variation in resources in a heterogeneous environment with constant variance (after accounting for changes in the mean). (a.) Resources (R , brown-green fill) vary over time and space with a constant the variance (dot color). (b.) Arbitrary definition of R as following a Gamma distribution with time-varying mean $\mu(t)$ and constant variance $\mathbb{V}(R) = \sigma^2$.

to find berries during growing season, it can expect the abundance in berries to be more stochastic. In contrast, other sources of stochasticity can be much less predictable, such as the arrival of new competitors (Alexander et al. 2015), the emergence of new diseases (Hollings et al. 2014), droughts (Foley et al. 2008; Haig et al. 2013), fires (Jolly et al. 2022), floods (Ramos Pereira et al. 2013), changes in climate and phenology (Inouye et al. 2000; Jonzén et al. 2006; Grant et al. 2017; Berger et al. 2018; Noonan et al. 2018; Woolway et al. 2020; Severson et al. 2021; Yao et al. 2022), and other extreme events (Logares and Nuñez 2012; Anderson et al. 2017).

Environmental variability can reduce a landscape's energetic balance (Chevin et al. 2010), which, in turn, decreases animals' fitness (Berger et al. 2018) and increases their spatial needs. While this is true for both predictable and unpredictable stochasticity, extreme and rare events are more likely to have a stronger effect. A few recent studies support these hypotheses (Chevin et al. 2010; Morellet et al. 2013; Nandintsetseg et al. 2019; Riotte-Lambert and Matthiopoulos 2020), but many of them are limited in geographic and taxonomic scales, so the extent to which these preliminary findings can be generalized is still very limited. Thus, there remains a need for developing a more complete understanding of how animals' spatial needs change with environmental stochasticity.

Similarly to the effect of $\mathbb{E}(R)$, we expect $\mathbb{V}(R)$ to have a nonlinear effect on animals' spatial needs. When $\mathbb{V}(R)$ is low enough that R is relatively predictable, we do not expect

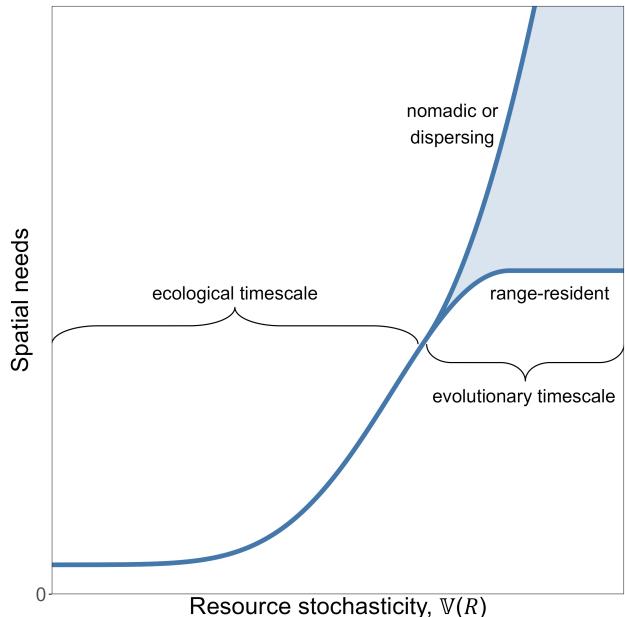


Figure 3: Hypothesized spatial needs of an animal as a function of resource stochasticity ($\mathbb{V}(R)$). We expect low values of $\mathbb{V}(R)$ to result in low spatial needs as animals are able to depend on somewhat predictable resources. As $\mathbb{V}(R)$ increases, spatial needs should increase nonlinearly, whether this results in an expansion of the home range (in the case of range-resident animals) or a switch to dispersal, nomadism, or migration. Note that the relationship between $\mathbb{V}(R)$ and spatial needs cannot be linear because it would require spatial needs to be negative for low values of $\mathbb{V}(R)$.

changes in $\mathbb{V}(R)$ to have a noticeable effect, but as resources become increasingly unpredictable, we expect spatial needs to increase progressively faster (figure 3) because (1) as $\mathbb{V}(R)$ increases the chances of finding low R increase superlinearly, (2) stochastic environments tend to be less productive (Chevin et al. 2010), and (3) the added movement required to search for food increases animals' energetic requirements. If resources remain highly unpredictable over long periods of time (e.g., multiple lifespans), animals may evolve or develop new behaviors (such as nomadism, dispersal, and migration) or adaptations (such as increased fat storage or food caching). If changes in $\sigma^2(t)$ are sufficiently predictable, animals may learn to anticipate and prepare for periods of greater stochasticity by pre-emptively caching food or migrating, or relying on alternative food sources during stochastic events (e.g., after the arrival of competitors).

Like the scenario illustrated in figure 2, we can imagine an environment where both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ change over time. We can then define $\mathbb{V}(R)$ as a function of time using the same notation as we did for $\mathbb{E}(R)$, i.e., $\mathbb{V}(R|t) = \sigma^2(t)$ (figure 4). When both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ change over time, predicting R becomes more complex. Statistically, this is because $\sigma^2(t)$ decreases as we allow $\mu(t)$ to change more over time and explain a greater proportion of $\mathbb{V}(R)$. Biologically, this is important because some animals may perceive changes in R as a change in $\mathbb{E}(R)$, while others may perceive the change as a stochastic event. An animal's perception of changes in R will depend strongly on the animal's cognitive capacities, including its memory and lifespan (Foley et al. 2008; Fagan et al. 2013; Mueller et al. 2013; Abrahms et al. 2019; Falcón-Cortés et al. 2021). The ability to predict trends in $\mu(t)$ and $\sigma^2(t)$ requires animals have high cognitive capacity, since distinguishing between changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$ is not easy (Steixner-Kumar and Gläscher 2020), especially if $\mathbb{E}(R)$ and $\mathbb{V}(R)$ are not independent, as in the case of $R \sim \Gamma(\mu(t), \sigma^2(t))$.

Interactive effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$

In systems where both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ change substantially over time, animals may respond to changes in $\mathbb{V}(R)$ more when resources are scarce than when they are abundant. Consequently, models estimating the effects of R on animal's movement should account for not only the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ separately, but also their interactive effects. A highly unpredictable habitat may be very inhospitable if resources are poor, but $\mathbb{V}(R)$ may have little effect if resources are stochastic but always abundant. Thus, we expect $\mathbb{V}(R)$ to have a stronger effect on spatial needs when $\mathbb{E}(R)$ is low, and less of an effect when $\mathbb{E}(R)$ is high.

Rizzuto et al. (2021) found that the spatial needs of snowshoe hares (*Lepus americanus*) increased with average carbon to nitrogen ratio (C:N, a measure of N scarcity) in lowbush blueberry as well as the coefficient of variation (the standard deviation over the mean, $\frac{\mu(t)}{\sqrt{\sigma^2(t)}}$) in C:N. However, it is hard to determine how $\sigma^2(t)$ affected the hares' spatial needs since the coefficient of variation is a function of both $\mu(t)$ and $\sigma^2(t)$, so the effects of the two variables are confounded. Similarly, Mueller et al. (2011) suggested that ecosystem variability (measured as spatial semivariance in NDVI) causes ungulates to move more and be more likely to be nomadic, but it is hard to determine whether the higher semivariances in NDVI are due to an increase in $\mathbb{V}(R)$ or simply spatial changes in $\mathbb{E}(R)$ (e.g., increased seasonality, heterogeneity, or continentality). Likewise, Herfindal et al. (2005) found that the home ranges Canadian lynx (*Lynx canadensis*) decreased with seasonality, but this may

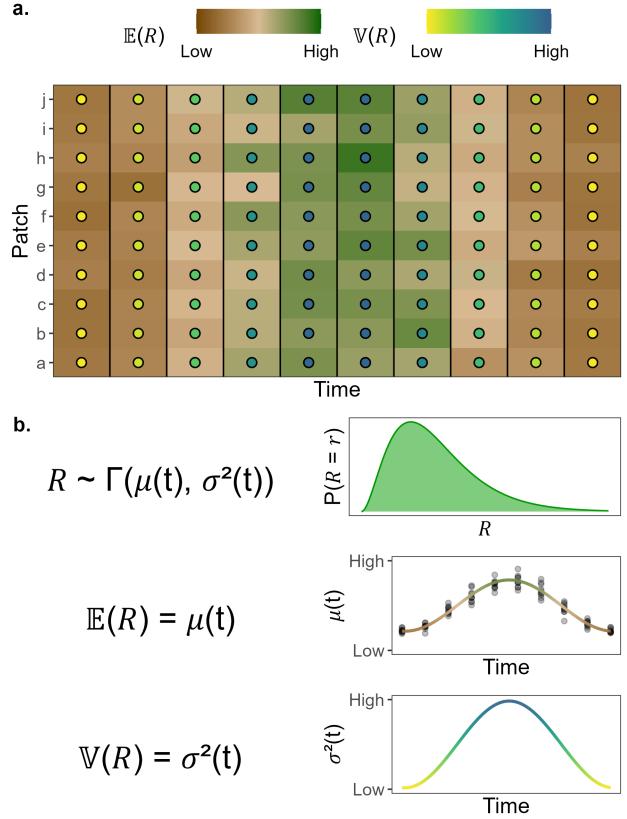


Figure 4: Fictitious example of variation in resources in a heterogeneous environment with changing variance (even after accounting for changes in the mean). (a.) Although resource abundance (R , brown-green fill) varies over time and space, the variance (dot color) is lowest at the beginning and end of the observational period and highest when $\mathbb{E}(R)$ peaks. (b.) Arbitrary definition of R as following a Gamma distribution with time-varying mean $\mu(t)$ and variance $\sigma^2(t)$.

be an artifact of a lower $\mu(t)$ in highly seasonal environments, rather than stochasticity in R . A subsequent analysis by Nilsen et al. (2005) of the lynx data of Herfindal et al. (2005) along with data on wolverines (*Gulo gulo*), bobcats (*Lynx rufus*), and coyotes (*Canis latrans*) found that carnivores respond differently to seasonality, which suggests that different species may have different perceptions of the changes in R over the seasons. Thus, it is important to disentangle the effects of spatiotemporal heterogeneity (i.e., changes in $\mathbb{E}(R)$, such as seasonal trends in $\mu(t)$) and stochasticity ($\mathbb{V}(R)$).

Nilsen et al. (2005) also show that the effect of $\mathbb{E}(R)$ on the home-range size of wolves (*Canis lupus*) and fishers (*Martes pennanti*) depends on seasonality (and vice-versa): Animals in habitats with high and low seasonality had opposite responses to $\mathbb{E}(R)$. Therefore, it may not be sufficient to account for the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$; models may also need a term for interaction between the two. This may be because animals respond strongly to $\sigma^2(t)$ when $\mu(t)$ is low, but they may not respond if $\mu(t)$ is sufficiently high. However, it does not explain why animals may respond to $\mathbb{E}(R)$ in opposite ways in different habitats.

Simulating animal responses to $\mathbb{E}(R)$ and $\mathbb{V}(R)$

To illustrate how $\mathbb{E}(R)$ and $\mathbb{V}(R)$ affect animals' spatial needs as well as the interaction effect of $\mathbb{E}(R)$ and $\mathbb{V}(R)$, we present the results from a series of quantitative simulations in figure 5 (for methodological details, see Appendix 1). The top row (constant $\mathbb{V}(R)$) shows how spatial needs vary for different trends in $\mu(t)$ while $\mathbb{V}(R)$ remains constant (like in figure 2). As $\mathbb{E}(R)$ increases at a constant slope (linear $\mu(t)$) the spatial needs decrease nonlinearly, with larger changes when $\mathbb{E}(R)$ is low, until home-range size approaches the minimum size required by the animal. As described in the section on the effects of resource abundance, the nonlinear decrease is because changes in $\mu(t)$ have a larger effect when $\mathbb{E}(R)$ is low (e.g., Lucherini and Lovari 1996; Herfindal et al. 2005; Nilsen et al. 2005).

In regions where the $\mu(t)$ changes over time (e.g., seasonal changes – see cyclical $\mathbb{E}(R)$ and Lai et al. 2017), animals should have access to sufficient space to fulfill their needs

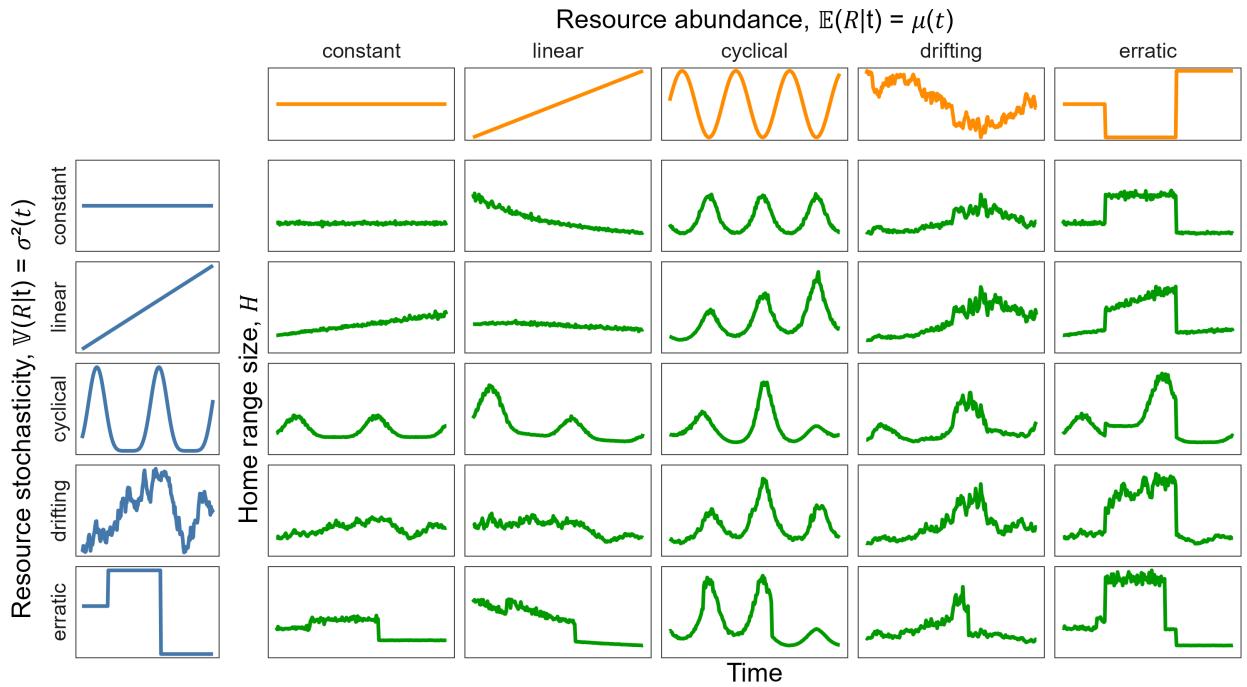


Figure 5: Simulated home range sizes, H , of an animal living in habitats where the mean and variance in resources are constant, linearly increasing, cyclical, drifting, or erratic over time. Note how H decreases nonlinearly as $\mu(t)$ increases and increases nonlinearly as $\sigma^2(t)$ increases. Additionally, the variance in H is higher when $\mu(t)$ is lower or $\sigma^2(t)$ is higher, and changes in $\sigma^2(t)$ have greater impacts when $\mu(t)$ is low.

Simulations were run such that animals followed the same $2^{10} = 1024$ tracks at each time point starting from the location $\langle 0, 0 \rangle$ until they reach satiety, after which they were allowed to return to $\langle 0, 0 \rangle$ over the same amount of time required to reach satiety. The animal's movement and utilization distribution were then estimated using an Ornstein-Uhlenbeck Foraging (OUF) model and Autocorrelated Kernel Density Estimation (AKDE), respectively, via the `ctmm` package (Fleming and Calabrese 2021). H was estimated using the UD's 0.95 quantile, but the effect is true for all quantiles since the UD was estimated via AKDE. Additional information is provided in Appendix 1.

during periods of scarcity, whether the space available is sufficiently large year-round or it changes seasonally with the expected changes in $\mu(t)$ (e.g., winter park closures). However, estimates of spatial requirements based on estimated changes in $\mu(t)$ should be interpreted carefully, since model error and unforeseeable decreases in $\mathbb{E}(R)$ (such as following fires or floods) may increase animals' spatial needs suddenly and unpredictably. Thus, it is best to include a "buffer" area so the available space is larger than the estimated spatial needs. This is particularly the case in environments where resource abundance changes unpredictably (drifting $\mu(t)$), since accurate long-term estimates and predictions of $\mu(t)$ may be hard to produce, if not impossible. In cases where $\mu(t)$ is highly unpredictable, animals should have enough space to collect resources during times of greatest predicted scarcity, particularly if the changes in resource abundance occur rapidly, often, or for long periods of time (erratic $\mu(t)$).

The leftmost column of figure 5 (constant $\mathbb{E}(R)$) illustrates the effects of $\mathbb{V}(R)$ on the simulated spatial needs while $\mathbb{E}(R)$ remains constant. Overall, both mean H and the variance around it increase with $\sigma^2(t)$ (most visible with constant $\mathbb{E}(R)$ and linear $\mathbb{V}(R)$). This is because, similarly to resource-poor periods, times of greater stochasticity require the animal to move over larger areas for longer periods of time. This results in a greater uncertainty in how much time and space the animal will require to reach satiety, or indeed whether an animal living in highly stochastic environments can even reach satiety within a finite amount of time.

The remaining panels in figure 5 illustrate how the effect of $\mathbb{V}(R)$ depends on $\mathbb{E}(R)$ (and vice-versa) as well as how complex the relationships can be. Since $\mathbb{E}(R)$ and $\mathbb{V}(R)$ have opposite effects on H , disentangling the effects can be particularly difficult when both parameters change in a correlated manner (e.g., linear $\mathbb{E}(R)$ and $\mathbb{V}(R)$). When both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ increase linearly, H initially increases since the effect of $\mathbb{V}(R)$ is stronger, but then decreases as the effect of $\mathbb{E}(R)$ begins to dominate. However, when $\mu(t)$ and $\sigma^2(t)$ follow fairly different trends (e.g., cyclical $\mathbb{E}(R)$ and linear $\mathbb{V}(R)$), it is easy to see how an increase

in $\mathbb{V}(R)$ amplifies the effects of $\mathbb{E}(R)$. In contrast, the effect of $\mathbb{V}(R)$ is stronger when $\mathbb{E}(R)$ is low (e.g., linear $\mathbb{E}(R)$ with cyclical $\mathbb{V}(R)$). Thus, H is largest when $\mathbb{E}(R)$ is low and $\mathbb{V}(R)$ is high, and it is smallest when $\mathbb{E}(R)$ is high and $\mathbb{V}(R)$ is low (see the panel with cyclical $\mathbb{E}(R)$ and $\mathbb{V}(R)$ as well as Lai et al. 2017).

Not all 25 scenarios depicted in figure 5 may be realistic, but the trends in $\mathbb{E}(R)$ and $\mathbb{V}(R)$, and their impacts on animal space use are useful examples that can be thought of as simplified scenarios. $\mathbb{E}(R)$ and $\mathbb{V}(R)$ may be assumed to be (approximately) constant in highly homogeneous environments. Although it is impossible for $\mu(t)$ and $\sigma^2(t)$ to increase linearly forever, these examples are useful to demonstrate that linear changes in $\mu(t)$ and $\sigma^2(t)$ affect H nonlinearly. Cyclical oscillations in $\mathbb{E}(R)$ and $\mathbb{V}(R)$ may occur in urban environments as human activity changes within and between days (Péron et al. 2017; Ikeda et al. 2022) and as temperatures fluctuate daily and seasonally (Geremia et al. 2019; Alston et al. 2020), while $\mathbb{E}(R)$ and $\mathbb{V}(R)$ may drift randomly in highly complex environments which are too hard to predict. Finally, erratic changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$ may occur in environments where changes are very sudden, such as areas prone to fires or floods, as well as habitats with drastic human alteration (e.g., a forest which is clear-cut with a subsequent artificial re-forestation). However, if stochastic changes are sufficiently small and frequent, animals may perceive them as continuous and smooth changes rather a series of small and sudden changes.

Although the temporal trends in figure 5 are complex and the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ can be hard to disentangle, two surprisingly simple relationships emerge when home-range size is shown as a function of either $E(R)$ or $V(R)$, rather than time. Both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ affect spatial needs precisely as we hypothesized (figure 6).

We believe the approximately linear effect of $\mathbb{V}(R)$ on H is mainly due to two factors. Firstly, H scales superlinearly with the standard deviation in R (as $\sqrt{\mathbb{V}(R)}$ is on the same scale as $\mathbb{E}(R)$; not shown), which would necessarily imply that H increases *sublinearly* with $\mathbb{V}(R)$. Secondly, the simulated animal's range residency with a consistent (albeit stochastic)

movement process within a homogeneous environment. Since real-world landscapes are heterogeneous in both $\mathbb{E}(R)$ and $\mathbb{V}(R)$, animals may choose to shift their home range to a new area following a stochastic event such as a fire or a flood. Thus, we hypothesize that our simulations may be underestimating animals' responses to spatiotemporal changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$, since the simulated animals cannot select for areas of higher $\mathbb{E}(R)$ or lower $\mathbb{V}(R)$. Additionally, the simulations also ignore the competition, movement costs, predation, and other factors may affect the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ on H . While these are definitely important effects that should be accounted for (Jetz et al. 2004), we believed that doing so was beyond the scope of this paper.

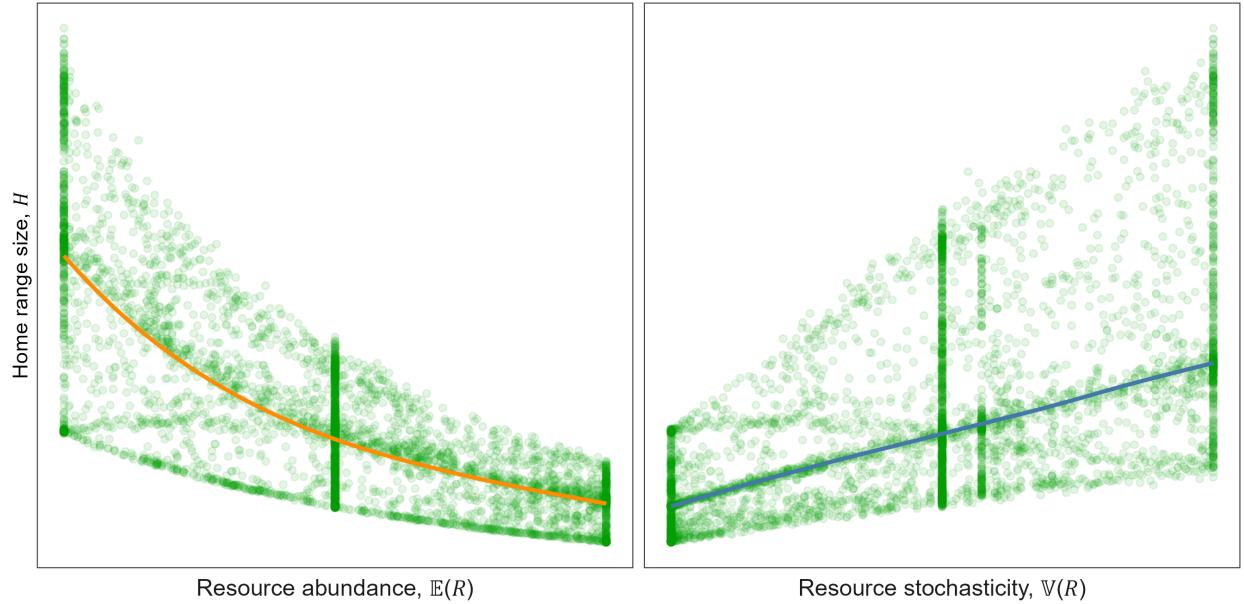


Figure 6: Effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ on simulated spatial requirements. The relationships were estimated using a Generalized Additive Model for Location and Scale (Rigby and Stasinopoulos 2005; Stasinopoulos and Rigby 2007) with a Gamma family of distributions. The model accounted for the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ and the interaction effects between the two on both $\mathbb{E}(H)$ and $\mathbb{V}(H)$. Note the nonlinear decrease in H as $\mathbb{E}(R)$ increases and the approximately nonlinear increase in H as $\mathbb{V}(R)$ increases. Additionally, note how the variance in spatial needs increases with mean spatial needs.

Applying this framework

The hypotheses we present here allow researchers to combine findings and generalize results to a single, common set of functional responses. We expect the two hypotheses we present here (figures 1 and 3) to be applicable to all animals, once differences in metabolic needs and diet are accounted for. In this subsection, we illustrate how researchers can test these

hypotheses using their own data to build on previous work rather than listing the results as *de novo* findings. Additionally, the analyses can be expanded to test whether members of the same population or species behave according to common functional responses to $\mathbb{E}(R)$ and $\mathbb{V}(R)$ while also quantifying any deviation from the hypothesized behavior. In the following sections, we illustrate how one can apply this framework to empirical data.

We start by providing examples and considerations on how one may model R , animals' spatial needs, and the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ on animals' spatial needs. Next, we provide an empirical example using tracking data on a lowland tapir (*Tapirus terrestris*) from the Brazilian Cerrado and NDVI as a proxy for R . Finally, we offer suggestions on how this approach can be used to inform conservation-related decisions, including assessing habitat quality and estimating animals spatial needs under different scenarios.

Modeling R

Location-scale models (Rigby and Stasinopoulos 2005; Stasinopoulos and Rigby 2007) are a class of statistical models that allow us to estimate changes in a random variable's mean (i.e. its location) and variance (which depends on its scale) while allowing the mean-variance relationship to vary. `mgcv` (Wood 2017) is a commonly used R package that allows one to fit Generalized Linear Models (GLMS, see Zuur 2009) and generalized additive models (GAMs, see Wood 2017), including location-scale GLMs and GAMs. Currently, the `mgcv` package allows one to fit location-scale models with a variety families of distributions, including Gaussian (i.e., normal), scaled t, gamma, Tweedie, and Gumbel.

The Gaussian location-scale family of distributions is very flexible, since the mean and variance parameters are assumed to be independent, and the response can be either positive or negative. However, the distribution's flexibility can also result in unreliable estimates for non-Gaussian responses, such as strictly positive data (e.g. available biomass), count data (e.g., number of prey), proportions (e.g., percentage of forested habitat), NDVI (Pettorelli et al. 2011), and extremes (such as daily maximum or minimum temperatures).

The Gamma location-scale family is best for strictly positive responses, such as areas (including home ranges), elemental compositions (e.g., carbon to nitrogen ratio, see Rizzuto et al. 2021), total biomass (e.g., kg of carbon per m²), or energetic intake (e.g., kcal/day). The Tweedie location-scale family is similar to the Gamma family, but it allows for zero data, so it is appropriate for data with a non-trivial amount of zeros, such as daily precipitation or prey density. In this paper, we estimate R by modeling NDVI using `mgcv` and a beta location-scale family. This family is not available in `mgcv` at the time of publication, but it should be available soon. If one is interested in families of distributions which are not available in `mgcv`, we suggest using the `brms` package (Bürkner 2017), which allows full control over all of a family's parameters via a fully Bayesian approach (as opposed to `mgcv`'s Empirical Bayes method – see Bürkner 2018).

Irrespectively of whether one uses a frequentist or Bayesian approach, it is important to model the mean and variance terms carefully. Since trends in both $\mathbb{E}(R)$ and $\mathbb{V}(R)$ can be nonlinear and non-monotonic, we suggest using a GAM rather than a GLM. However, the complexity of the spatiotemporal terms should be chosen carefully, particularly for the location terms. An excessively wiggly $\hat{\mu}(t)$ will cause $\sigma^2(t)$ to be under-estimated, while an excessively smooth $\hat{\mu}(t)$ will cause $\sigma^2(t)$ to be over-estimated. Although there is no error-proof system, choosing the complexity of the terms based on the animal's ability to detect change and adapt is a reasonable starting point. Additionally, using REstricted Marginal Likelihood (REML, a form of penalized maximum likelihood optimization, see Wood 2011) and setting the basis dimension (k) of the scale terms to be half or less than that of the mean terms should provide reasonably accurate results. We suggest starting with low values of k and adjusting k based on the trends in the residuals. Note that since R is likely spatiotemporally autocorrelated, it may be easy to overfit the model if R is measured at high frequencies and with a large sample size (but low effective sample size). Appendix 2 contains additional information on how NDVI was modeled for the empirical example, along with the continuous time models (Noonan et al. 2019a; Fleming and Calabrese 2021) and

autocorrelated kernel density estimation (Noonan et al. 2019b; Alston et al. 2022; Silva et al. 2022) used to quantify the tapir’s spatial needs.

Modeling the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$

As discussed in the previous section, the first step to modeling H is to choose an appropriate distribution. Since H is strictly positive and continuous, a Gamma distribution seems the most appropriate among the distributions currently offered by the `mgcv` package (Wood 2017). The Tweedie distribution may also be appropriate, if the mean-variance relationship of the Gamma distribution results in a poor fit.

As with the simulated effects of $\mu(t)$ and $\sigma^2(t)$ on H (figure 6), a location-scale Gamma model is likely required. If there is not sufficient data to fit a location scale model (which is not the case here), a simple Gamma model may be sufficient, but we suggest selecting the best family of distributions using an information criterion such as the Akaike Information Criterion (Akaike 1974). While a GAM would allow the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ on H to be quite flexible, we suggest one use a GLM, instead, (unlike when modeling R) because we expect the relationship to be fairly simple and monotonic. Restricting the model to a GLM reduces the risk of issues that may arise due to limited sample size and temporal autocorrelation in $\mathbb{E}(R)$ and $\mathbb{V}(R)$. If one is interested in fitting a GAM but imposing shape constraints, such as monotonicity, we suggest fitting a shape-constrained GAM via the `scam` package (as we do here: see the section below, Appendix 2, and Pya 2022).

An empirical example: Lowland tapir in the Brazilian Cerrado

In this section, we use empirical tracking data on a lowland tapir (*Tapirus terrestris*) from the Brazilian Cerrado to show how this framework can be applied to better understand the movement ecology of free-ranging animals. We estimate $\mathbb{E}(R)$ and $\mathbb{V}(R)$ by modeling NDVI (Pettorelli et al. 2011) using a Beta location-scale GAM, after scaling NDVI to $[0, 1]$ using equation (2). Additional information regarding the modeling can be found in Appendix 2.

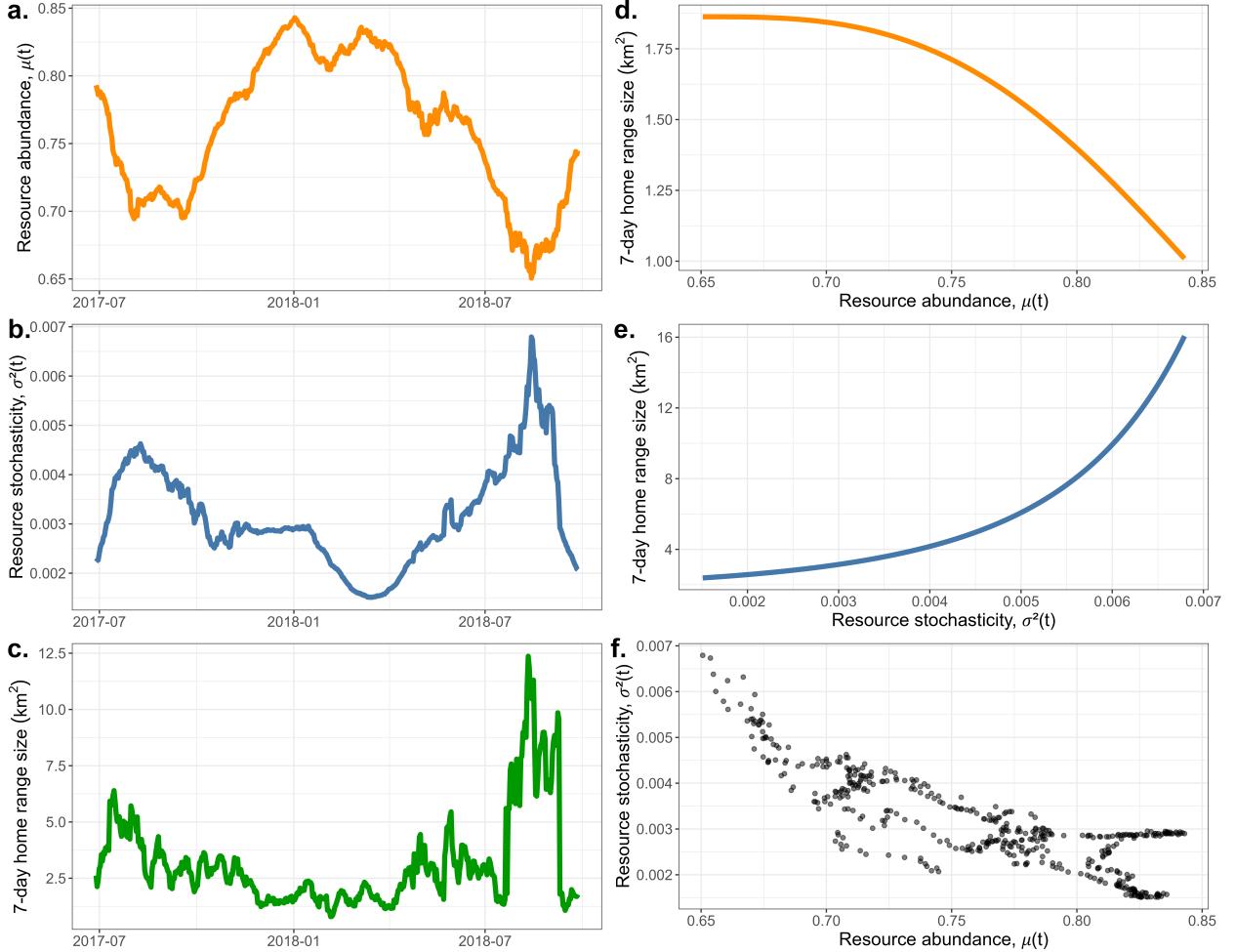


Figure 7: Seven-day home-range size of a tapir (*Tapirus terrestris*) in response to changes in mean and variance in resource abundance. (a.) Mean resource abundance, $\mu(t)$, estimated as the mean NDVI at the locations visited by the tapir. (b.) Variance in resource abundance, $\sigma^2(t)$, estimated as the average variance in NDVI at the locations visited by the tapir. (c.) Estimated seven-day home range based on the 95% utilization quantiles. (d., e.) estimated marginal effects of $\mu(t)$ and $\sigma^2(t)$ on home-range size. The model accounted for the marginal effects of $\mu(t)$ and $\sigma^2(t)$ and their interaction on mean spatial needs and the variance around them. (f.) The effect of $\mu(t)$ does not follow the data closely because $\mathbb{E}(R)$ and $\mathbb{V}(R)$ are highly correlated. Consequently, while estimating the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ via separate models would allow result in a closer fit, the estimated effects would be inappropriate because they do not disentangle the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$. See Appendix 2 for additional information. The tapir movement data corresponds to the individual named "Anna" from the Cerrado sample of Medici *et al.* (2022).

Figure 7 illustrates the tapir’s response to changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$. Panels **a** and **b** show the changes in mean and variance in NDVI, respectively, during the tracking period. Panel **c** shows the changes in the tapir’s spatial use over time. Note how the home-range size is larger during periods of lower NDVI (e.g., August 2017) and smallest during periods with high NDVI (January 2018). In contrast, when resources are scarce and highly unpredictable (August 2018), the tapir uses up to 5 times more space than when resources are abundant and predictable. Finally, panels **d** and **e** show the estimated (partial) effects of $\mu(t)$ and $\sigma^2(t)$ on the tapir’s space use. Again, the estimated effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ follow the simple relationships we hypothesized (figures 1 and 3) and supported with the simulated responses (figure 6).

Discussion

This paper presents a new unifying framework for describing the effects of resource abundance and stochasticity on animals’ spatial needs. The hypotheses and methods we present allow researchers to generalize the effects $\mathbb{E}(R)$ and $\mathbb{V}(R)$ have on animals’ spatial needs by building upon previous work rather than stating their results as *de novo* findings. Instead, one can test whether individuals follow these hypotheses, if members of the same population or species behave similarly, and if all members of the group have a common functional response (using hierarchical models, see Pedersen et al. 2019). Individuals and populations that were thought to have different behaviors and spatial needs due to differences in behavior may instead be simply responding to different conditions along the same functional response (e.g., Singh et al. 2012).

Animal adaptations to changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$

The spatiotemporal scale over which an event occurs is a main determinant of whether an animal will be able to predict the event and how it will respond to it (or fail to do so). Events which occur at the scale of the organism (i.e. approximately one or more times per

generation and on the spatial scale of the animal's spatial range, see Frankham and Brook 2004) are more likely to be perceived as a threat or boon worth preparing for (e.g., elephants, *Loxodonta* sp.: Foley et al. 2008; muskoxen, *Ovibos moschatus*: Berger et al. 2018; bison, *Bison bison*, and mule deer, *Odocoileus hemionus*: Geremia et al. 2019). Consequently, organisms with long generations (e.g., elephants) or large spatial ranges (e.g., migratory birds) are more likely to experience stochastic events and thus respond to and prepare for stochastic events by adjusting the timing of reproduction (framewokrk: Southwood 1977; red-backed fairywren, *Malurus melanocephalus*: Boersma et al. 2021) and torpor or hibernation (marmots, *Marmota flaviventris*: Inouye et al. 2000; ground squirrels *Urocitellus brunneus*: Goldberg and Conway 2021), storing large amounts of energy (Lindstedt and Boyce 1985) through fat storage (marmots: Armitage et al. 2003; bears, *Ursus* sp.: Nespolo et al. 2022) or resource caching (Post et al. 2006), moving long distances over short periods of time (Jetz et al. 2004; Hirt et al. 2017) including migration (Mueller et al. 2013; Geremia et al. 2019) or nomadism (Teitelbaum et al. 2015; Nandintsetseg et al. 2019; Teitelbaum and Mueller 2019), and developing more complex cognitive abilities over longer lifespans, generation times, and developmental periods (Brown et al. 2004), including the development of memory of such events (framework: Fagan et al. 2013; Riotte-Lambert and Matthiopoulos 2020; Steixner-Kumar and Gläscher 2020; bison and mule deer: Geremia et al. 2019; blue whales, *Balaenoptera musculus*: Abrahms et al. 2019; caribou *Rangifer tarandus*: Cavedon et al. 2022; elephants: Foley et al. 2008; Polansky et al. 2015; Rickbeil et al. 2019; elk, *Cervus canadensis*: Falcón-Cortés et al. 2021; roe deer, *Capreolus capreolus*: Ranc et al. 2022), which is required for migration (whooping cranes, *Grus americana*: Mueller et al. 2013; bison and mule deer: Geremia et al. 2019; mule deer: Merkle et al. 2019; blue whales: Abrahms et al. 2019; Middleton et al. 2018; elk: Rickbeil et al. 2019; but see: Cuadrado 2021; Stefanescu et al. 2021). However, adapting to changes in environmental cues rather than on memory alone (Büntgen et al. 2017; Rickbeil et al. 2019; ungulates: Severson et al. 2021; birds: Jonzén et al. 2006), can prevent animals from becoming trapped in sub-optimal

conditions (Abrahms et al. 2019).

In contrast, individuals with short lifespans are less likely to experience stochastic events and memory about them. However, the short generation time and high reproductive rate of *r-selected* species (*sensu* Pianka 1970; Brown et al. 2004) may promote other traits that increase survival following extreme events. Examples include higher population size, dispersal, higher genetic diversity, and complex group dynamics (e.g., Cuadrado 2021; Stefanescu et al. 2021). Events that occur over large spatiotemporal scales can thus promote slow changes through adaptation, natural selection, and evolution of the species rather than the individual (Gienapp et al. 2008; Logares and Nuñez 2012; Anderson et al. 2017; Grant et al. 2017), which are numerically more likely if the starting population is large and genetically diverse, as in the case of r-selected species (but see Leung 2022). Of course, an animal with a lifespan shorter than a year will be unable to experience the cyclical nature of the seasons, and an animal with a lifespan of a few weeks or days may not even experience substantial changes in weather other than lower temperatures at night than during the day and some weather stochasticity. Still, a population may respond to spatiotemporal cycles in $\mathbb{E}(R)$ and $\mathbb{V}(R)$ by adapting the group's reproduction timing and migration (e.g., painted lady butterflies: Cuadrado 2021; Stefanescu et al. 2021).

A population's fitness and chances of survival in a changing environment depend strongly on its adaptability and responsiveness to change (Riotte-Lambert and Matthiopoulos 2020), and its ability to recognize cues that precede extreme events or periods of scarcity or abundance can have appreciable effects on its members' chances of survival and reproduction. For example, ungulates' ability to time their yearly migrations on available forage biomass, snow fall, snow melt, and hunting pressure allow them to adapt to changes in both $\mathbb{E}(R)$ and $\mathbb{V}(R)$, while their spatial memory (Falcón-Cortés et al. 2021; Ranc et al. 2022) allows them to optimize their large-scale movement by reducing the amount of time and energy spent exploring. Similarly, the ability of trans-Saharan migrant birds to adapt their migration timing based on environmental cues allows them to account for differences in $\mu(t)$ between

years (Jonzén et al. 2006). However, relying too strongly on short-term changes rather than depending on long-term memory can also cause animals to fail to find crucial resources (cranes: Mueller et al. 2013; Foley et al. 2008; elephants: Polansky et al. 2015; whales: Abrahms et al. 2019). However, when anomalies occur repeatedly over time, animals may begin to shift their ranges (terrestrial animals: Chen et al. 2011; Büntgen et al. 2017; ungulates: Severson et al. 2021), including migratory animals (Jonzén et al. 2006). Range shifts can help species overcome changes in the long-term trends in $\mu(t)$ and $\sigma^2(t)$, including changes in phenology (Severson et al. 2021). However, they can also result in phenological mismatches (Lameris et al. 2018) and add pressure to the species that already live in the habitat (Wallingford et al. 2020; but see Shepard et al. 2022), including specialists and obligate symbionts that may be unable to shift their range since it is determined by their food sources' and associates' ability to move and adapt, too.

Applications for conservation

Technical advancements from the last few decades have allowed scientists to collect increasingly larger amounts of data at finer and finer scales (Nathan et al. 2022), but little attention has been paid to estimating the effects of environmental stochasticity on animal behavior. In these times of great change and climatic uncertainty (Abrahms 2021; Intergovernmental Panel On Climate Change 2023), it is increasingly important to recognize how environmental stochasticity affects animal behavior and shapes ecosystems. Accounting for changes in both resource abundance and resource stochasticity is crucial when assessing whether the quality of protected areas is sufficiently high to sustain biodiversity long term. Protecting areas with high resource abundance and low resource stochasticity will reduce animal's spatial requirements.

The designation of high-quality habitats is a central concern of many conservation initiatives. This framework allows consultants and conservation managers to quantify the quality of a habitat based on its resource abundance and stochasticity as well as the amount of

space animals would need in the habitat. With the methods presented in this paper, one can (1) assess the quality of current protected areas, (2) predict whether or not the areas will be able to sustain current populations in future decades, and (3) evaluate the quality of new potential conservation areas. In light of the UN’s objective to conserve 30% of global landmasses and waters by 2030 (IPBES 2019), the framework and methods presented here provide useful metrics for evaluating whether protected areas will have sufficient quality and long-term stability to support species under various possible climate change scenarios (Intergovernmental Panel On Climate Change 2023).

Ignoring the effects of recent and predicted increases in $\mathbb{V}(R)$, including an increase in the intensity and frequency of extreme events (Yao et al. 2022; Intergovernmental Panel On Climate Change 2023), has the potential to greatly hinder future conservation efforts. Since not accounting for an increase in $\sigma^2(t)$ will result in an under-estimation of animals’ spatial needs, protected areas which were designated based on the area’s $\mu(t)$ but not $\sigma^2(t)$ will likely be insufficient in both size and resources in the future, which may lead to decreases in the fitness and size of a population while also increasing the risk of population collapse and human-wildlife conflict (Mukuka et al. 2019). This is particularly the case in resource-poor, stochastic regions, where animals are forced to endure longer and more unpredictable searches, which results in a larger variance in spatial needs.

It is also worth noting that carnivores may be more susceptible to changes in $\mathbb{E}(R)$ and $\mathbb{V}(R)$, and that this susceptibility is likely amplified further at higher trophic levels. While primary consumers can rely on relatively predictable and static resources that can be estimated easily via remote sensing measures such as NDVI, the fine-scale location of secondary consumers’ resources may not correlate as strongly with measures of habitat productivity. In fact, primary consumers’ ability to move makes their location and abundance more stochastic than those of plants. Consequently, the abundance of primary producers may correlate with habitat productivity weakly or at a temporal lag (e.g., Geremia et al. 2019). Thus, primary consumers’ delayed responses to fluctuations in $\mathbb{E}(R)$ and $\mathbb{V}(R)$ may result in an

increase in secondary consumers' resource stochasticity, which would also be perceived with a delay. Similar hypotheses can be formulated for higher trophic levels but with amplified temporal lags, since each trophic level adds another layer of uncertainty and delayed response, which together increase the unpredictability on how carnivores indirectly respond to changes in primary productivity.

Conclusion

The work presented here provides a unifying framework for viewing animal movement as function of resource abundance and stochasticity. We provide realistic and flexible hypotheses of the effects of $\mathbb{E}(R)$ and $\mathbb{V}(R)$ on animals' spatial needs and movement behavior. We demonstrate that animals' spatial needs respond nonlinearly to both resource abundance and stochasticity, and we demonstrate the importance of accounting for $\mathbb{V}(R)$ besides $\mathbb{E}(R)$. We also provide a moving window approach that allows one to model animal movement continuously rather than imposing arbitrary thresholds between different periods or types of behaviors, including temporal changes in spatial needs and shifts between range-residency and nomadism. The methods presented here can be applied to assess the current and future quality of protected areas while also estimating the amount of space animals currently need and will need in the future under different climate change scenarios.

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