

# RIOT Beginner Tutorial

## RIOT Summit

<https://github.com/riot-os/riot-course>

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1. Learn how to write and build a RIOT application



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4. Perform a firmware update

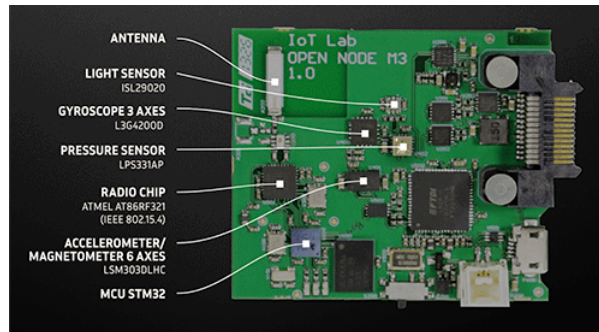
# Tutorial overview (1)

# Tutorial overview (2)

- No setup required, all activities are performed online in Jupyter Notebooks



- Run the RIOT applications on the [IoT-LAB](#) testbed
- Use [IoT-LAB M3](#) boards:

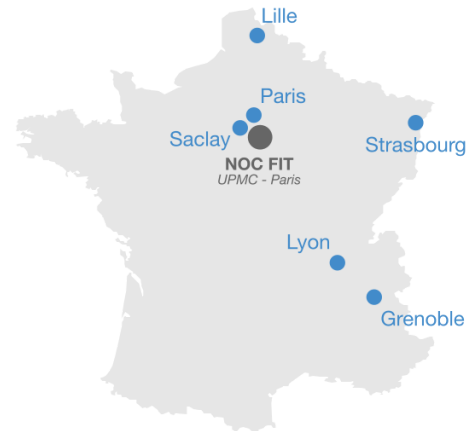
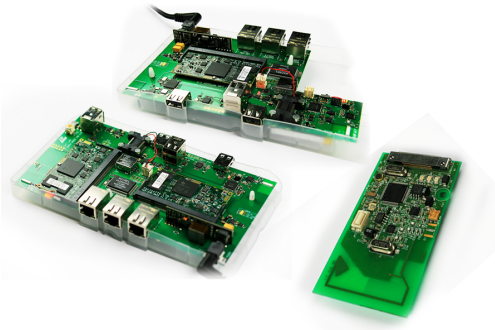


# About IoT-LAB

<https://www.iot-lab.info>

IoT-LAB is a large scale experimentation testbed

- Can be used for testing wireless communication networks on small devices
- Can be used for learning IoT programming and communication protocols
- Can be used for testing software platforms





# About the Jupyter Notebooks

- Available at <https://labs.iot-lab.info>



Welcome to the IoT-LAB JupyterHub!

Use your IoT-LAB credentials to login.

You can create an account [here](#).

Sign in

Username:

Password:

Sign In

- No setup required!
- Source code of the notebooks is available at <https://github.com/iot-lab/iot-lab-training>

**Short demo: in Jupyterlab, read the notebook `start.ipynb`\*\***

# RIOT Overview

# What is RIOT

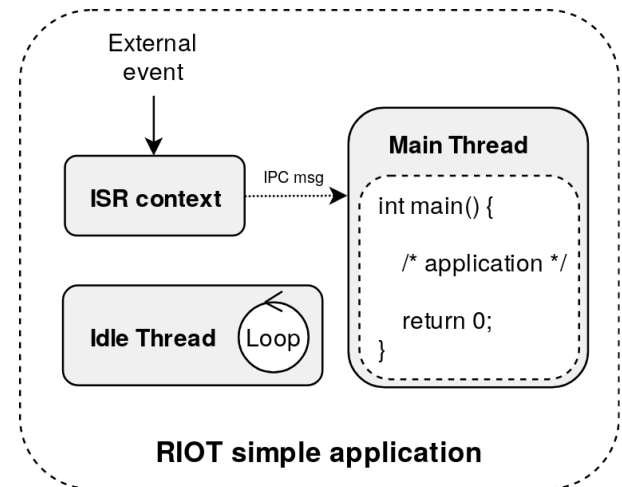


- **operating system** for microcontrollers
  - **microkernel architecture** ⇒ require very low resources
  - **real-time** and **multi-threaded**
  - comes with **in-house networking stacks**
- **open-source**: <https://github.com/RIOT-OS/RIOT>
  - free software platform
  - **world-wide community** of developers
- **easy to use** and **reuse**
  - Standard programming in C
  - Standard tooling
  - **API is independent** from the hardware



# General-Purpose OS for IoT

- **Real-Time** scheduler
  - $\Rightarrow$  fixed priorities preemption with  $O(1)$  operations
  - $\Rightarrow$  tickless scheduler, i.e. no periodic timer event
- **Multi-Threading** and IPC:
  - Separate thread contexts with separate thread memory stack
  - Minimal thread control block (TCB)
  - Thread synchronization using mutexes, semaphores and messaging
  - ISR context handles external events and notifies threads using IPC messages
  - *Note:* optional multi-threading



# A modular OS

Features are provided as modules ⇒ **only build what's required**

- System libraries: **xtimer**, **shell**, crypto, etc
- Sensors and actuators
- Display drivers, filesystems, etc
- Embedded interpreters: Javascript, LUA, uPython
- High-level network protocols: CoAP, MQTT-SN, etc
- External packages: lwIP, Openthread, u8g2, loramac, etc

Package	Overall Diff Size	Relative Diff Size
ccn-lite	517 lines	1.6 %
libfixmath	34 lines	0.2 %
lwip	767 lines	1.3 %
micro-ecc	14 lines	0.8 %
spiffs	284 lines	5.5 %
tweetnacl	33 lines	3.3 %
u8g2	421 lines	0.3 %

# Network stacks

**IP oriented stacks** ⇒ designed for Ethernet, WiFi, 802.15.4 networks

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- Other IPv6 stacks:
  - **lwIP**: full-featured network stack designed for low memory consumption
  - **emb6**: A fork of Contiki network stack that can be used without proto-threads

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- In-house Controller Area Network (**CAN**)

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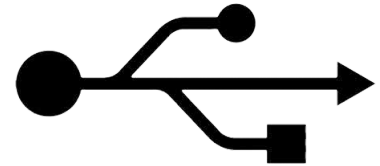
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- In-house Controller Area Network (**CAN**)
- BLE stack support: [NimBLE](#)
- **LoRaWAN** stack ⇒ Compliant with LoRaWAN 1.0.2
- **SigFox** support for ATA8520e modules



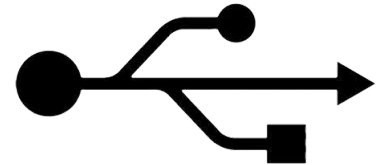
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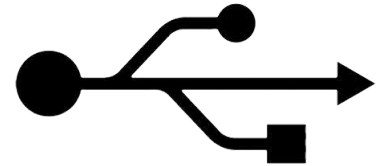


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<https://datatracker.ietf.org/wg/suit/about/>

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# Getting started

# Structure of a RIOT application

A minimal RIOT application consists in:

- A Makefile

```
APPLICATION = example  
  
BOARD ?= native  
  
RIOTBASE ?= $(CURDIR)/../../RIOT  
  
DEVELHELP ?= 1  
  
include $(RIOTBASE)/Makefile.include
```

- A C-file containing the main function

```
#include <stdio.h>  
  
int main(void)  
{  
    puts("My first RIOT application");  
    return 0;  
}
```

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  - From the application directory:

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$ cd <application_directory>  
$ make
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- From anywhere, by using the -C to specify the application directory:

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- Use the **BOARD** variable to specify the target at build time

```
$ make BOARD=<target> -C <application_directory>
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BOARD can be any board supported by RIOT

⇒ see the **RIOT/boards** directory for the complete list

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$ make BOARD=<target> -C <application_directory>
```

BOARD can be any board supported by RIOT

⇒ see the **RIOT/boards** directory for the complete list

- Use the **RIOTBASE** variable to specify the RIOT source base directory

# Run a RIOT application

This depends on the target board:

- Running on **native**: the RIOT application executed is a simple Linux process

```
$ make BOARD=native -C <application_dir>  
$ <application_dir>/bin/native/application.elf
```

- Running on **hardware**: the RIOT application must be *flashed* first on the board

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```

- Running on **hardware**: the RIOT application must be *flashed* first on the board

⇒ use the **flash** and **term** targets with make

- **flash**: build and write the firmware on the MCU flash memory
- **term**: opens a terminal client connected to the serial port of the target

All this can be done in one command:

```
$ make BOARD=<target> -C <application_dir> flash term
```

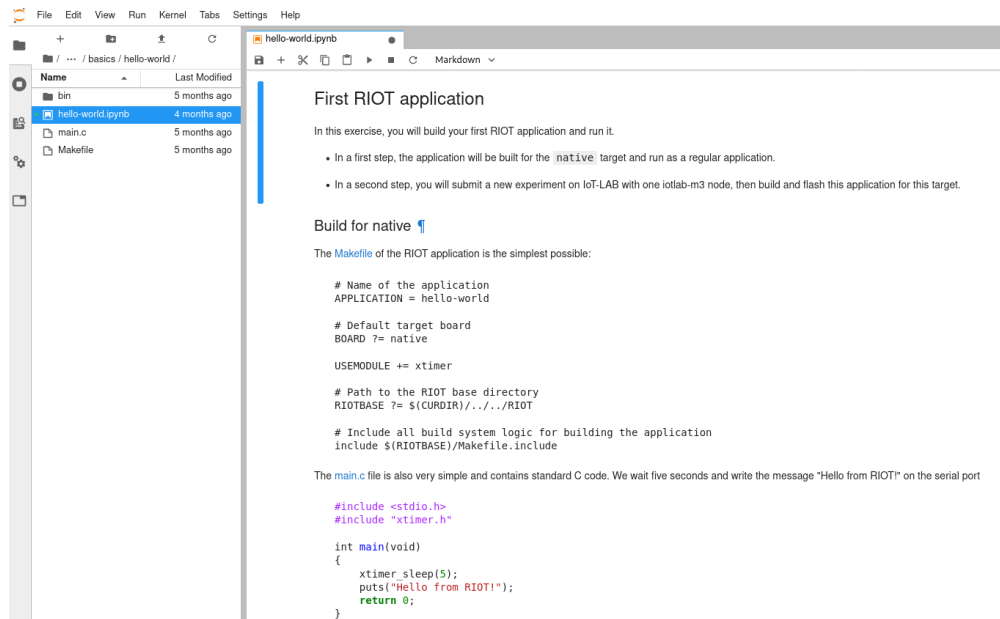
*Note:* the last command can also be used with **native** target



# Exercise: your first RIOT application

Let's build and run our first RIOT application !

In jupyterlab, open the notebook **riot/basics/hello-world/hello-world.ipynb** and follow the instructions.



File Edit View Run Kernel Tabs Settings Help

hello-world.ipynb

First RIOT application

In this exercise, you will build your first RIOT application and run it.

- In a first step, the application will be built for the `native` target and run as a regular application.
- In a second step, you will submit a new experiment on IoT-LAB with one iotlab-m3 node, then build and flash this application for this target.

Build for native

The `Makefile` of the RIOT application is the simplest possible:

```
# Name of the application
APPLICATION = hello-world

# Default target board
BOARD ?= native

USEMODULE += xtimer

# Path to the RIOT base directory
RIOTBASE ?= $(CURDIR)/../../RIOT

# Include all build system logic for building the application
include $(RIOTBASE)/Makefile.include
```

The `main.c` file is also very simple and contains standard C code. We wait five seconds and write the message "Hello from RIOT!" on the serial port

```
#include <stdio.h>
#include "xtimer.h"

int main(void)
{
    xtimer_sleep(5);
    puts("Hello from RIOT!");
    return 0;
}
```

# How to extend the application

⇒ by adding modules in the application Makefile or from the command line:

- Add extra modules with **USEMODULE**  
⇒ xtimer, fmt, shell, ps, etc
- Include external packages with **USEPKG**  
⇒ lwip, semtech-loramac, etc
- Use MCU peripherals drivers with **FEATURES\_REQUIRED:**  
⇒ `periph_gpio`, `periph_uart`, `periph_spi`, `periph_i2c`

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Example in a Makefile:

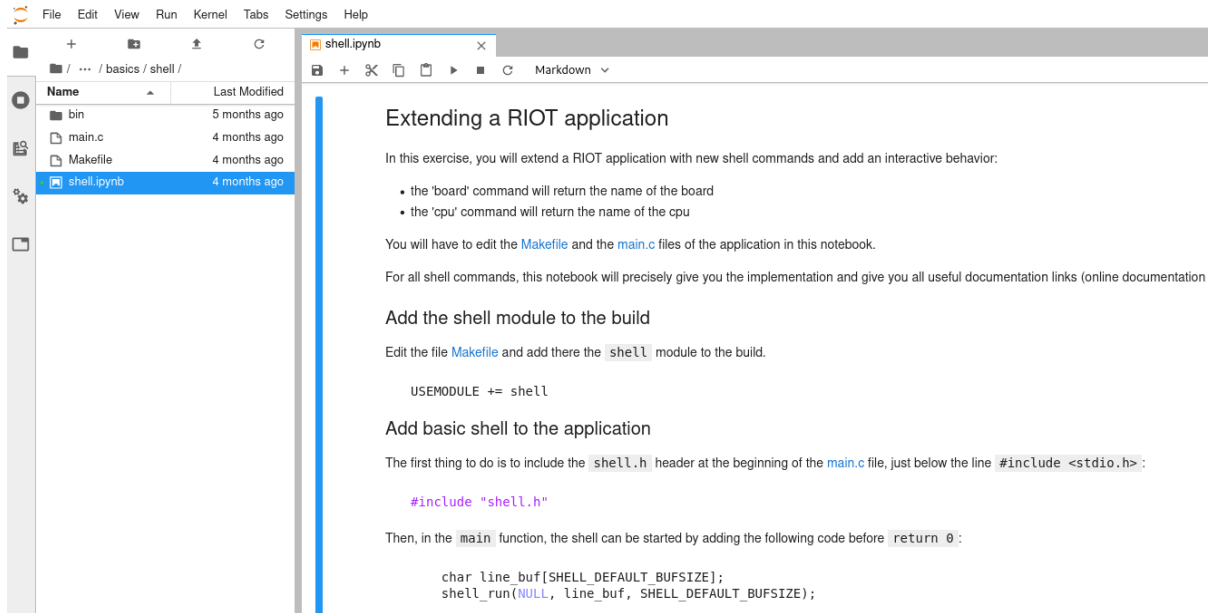
```
USEMODULE += xtimer shell  
  
USEPKG += semtech-loramac  
  
FEATURES_REQUIRED += periph_gpio
```

Example from the command line:

```
$ USEMODULE=xtimer make BOARD=b-l072z-lrwan1
```

# Exercise: write an application with a shell

Follow the instructions in the notebook **riot/basics/shell/shell.ipynb**



The screenshot shows a Jupyter Notebook interface with a file explorer on the left and a notebook cell on the right. The file explorer shows the directory structure: `/ ... / basics / shell /` with files `bin`, `main.c`, `Makefile`, and `shell.ipynb`. The notebook cell is titled "Extending a RIOT application" and contains the following text:

Extending a RIOT application

In this exercise, you will extend a RIOT application with new shell commands and add an interactive behavior:

- the 'board' command will return the name of the board
- the 'cpu' command will return the name of the cpu

You will have to edit the `Makefile` and the `main.c` files of the application in this notebook.

For all shell commands, this notebook will precisely give you the implementation and give you all useful documentation links (online documentation)

Add the shell module to the build

Edit the file `Makefile` and add there the `shell` module to the build.

```
USEMODULE += shell
```

Add basic shell to the application

The first thing to do is to include the `shell.h` header at the beginning of the `main.c` file, just below the line `#include <stdio.h>`:

```
#include "shell.h"
```

Then, in the `main` function, the shell can be started by adding the following code before `return 0`:

```
char line_buf[SHELL_DEFAULT_BUFSIZE];
shell_run(NULL, line_buf, SHELL_DEFAULT_BUFSIZE);
```

# Security basics for IoT

# Why is security difficult on low-end IoT devices ?

blablabla

# Exercise: compute a hash

Follow the instructions in the notebook [`riot/security/hash/hash.ipynb`](#)

# Exercise: sign and verify signature

Follow the instructions in the notebook `riot/security/signature/signature.ipynb`



# Exercise: encrypt and decrypt a message

Follow the instructions in the notebook [`riot/security/encyption/encyption.ipynb`](#)

# Exercise: secure communication using dtls

Follow the instructions in the notebook [`riot/security/dtls/dtls.ipynb`](#)

# Exercise: standard and secure firmware update

Follow the instructions in the notebook `riot/security/ota/ota.ipynb`

**All complete ? Well done!**