

Practical

TIMER

tick value = $1/\text{frequency}$.

```
time delay = count * tick value.
```

Example,

```
f=16MHz  
t= 1/16M = 0.0625 &micro;s  
  
If Time delay = 2 sec, tick value = 0.0625 &micro;s  
then, count=?  
  
count = time delay / tick value  
count = 2/(0.0625x10-6) = 32x106.
```

PWM

```
DUTY CYCLE =  $\text{Ton}/(\text{Ton}+\text{Toff}) * 100$ 
```

```
Ton is ON Time  
Toff is OFF Time
```

PWM frequency

```
PWM frequency =  $\text{Timer Frequency}/(\text{Prescalar} * (\text{Duty Cycle} + 1))$ 
```

Example,

```
Timer freq = 16MHz, Prescaler = 16, Duty Cycle = 99;  
PWM freq = (16x10^6)/(16x(99+1)) = (16x10^6)/(1600) = 10kHz  
  
PWM time = 1/10x10^3 = 0.1ms = 100us.
```

DRIVERS/CMSIS/Device/ST/stm32f407xx.h contains data structures and addr mapping of all peripherals.
Which part of code uses which cmsis.....

APSR, Core registers, PSR are found in DRIVERS/CMSIS/INCLUDE/core_cm3.h

Read operation - set MSB to 1
Write operation - set MSB to 0

I2C

Start condition: The SDA line switches from HIGH to LOW level before SCL line switches from HIGH to LOW.

Stop condition: The SDA line switches from LOW to HIGH level before SCL line switches from LOW to HIGH.

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